GRACE forward modeling of Gulf of Alaska water balances

ABSTRACT. ...

3 INTRODUCTION

2

Data from the NASA/DLR Gravity Recovery and Climate Experiment (GRACE) have been fundamental tools for assessing mass variations of alpine and high latitude regions (Wouters and others, 2014). These regions are major participants in the global hydrological cycle due to their ability to store solid precipitation in glaciers and snowpacks, for release at a later time in response to seasonal and long term climatic variations. To date, most research has focused on the ice sheets, where the uniformity of land cover type minimizes the number of different geophysical signals that need to be partitioned in GRACE processing (Shepherd and others, 2012). In contrast, non-ice sheet (mountain glacier) regions usually exist within 10 a dispersed mixture of land and ocean cover types that often include complex fjords, coastal temperate 11 rainforests, lakes, rivers and seasonal snowpacks (Fig. ??). These complexities make it difficult to partition 12 the collection of hydrological and geophysical signals that GRACE observes. The problem is compounded 13 by the fact that many non-glacier surfaces have periodicity in their mass fluctuation that mimic those 14 of glaciers. For example, seasonal snowpacks and groundwater storage usually have semi-annual mass 15 periodicity related to seasonal temperature signals. For these reasons, most GRACE work applied to alpine 16 regions has focused on recovering the cumulative change in mass of the Canadian high Arctic (Gardner 17 and others, 2011; Lenaerts and others, 2013), high mountain Asia (Yi and Sun, 2014), Patagonia (Ivins 18 and others, 2011) and Alaska (Jacob and others, 2012; ?; ?) where glacier volume loss signals are assumed 19 to be the dominant driver of changes in hydrological storage. Nevertheless, there is an urgent need for 20 full utilization of the sub-annual components of the GRACE signal to inform studies of water resource 21 availability, impacts of freshwater discharge on ecosystem services, and predicting the likelihood of runoff-22 related hazards (O'Neel and others, 2015). 23 Progress toward the full utilization of GRACE data for assessing alpine and high latitude seasonal 24 hydrology is currently limited by the poor quality and low spatial resolution of existing global land 25 surface hydrology models. The Global Land Data Assimilation System (GLDAS, (?)) has been the primary 26

modeling/data assimilation framework used in previous studies to correct for terrestrial water storage in 27 studies of alpine hydrology. Within GLDAS are land surface hydrology models such as the Community 28 Land Model (?) and the Variable Infiltration Capacity model (?). At mid- to low latitudes, the accuracy 29 of such models is generally good (e.g. Werth and others, 2009). However at high elevation and latitude, 30 these models are limited in their capacity to fully account for changes in terrestrial snowpack, groundwater 31 32 storage, lake level fluctuations and precipitation. The primary problem is that such models do no have paramaterizations for glacier ice flow, and therefore any solid precipitation that is not removed in a given 33 season can accumulate indefinitely on high elevation grid cells. To account for this, all GRACE studies 34 to date have simply eliminated land surface hydrology corrections from those grid cells containing glacier 35 ice (e.g. Gardner and others, 2011; Jacob and others, 2012; ?). Due to the relatively coarse resolution of 36 the land surface hydrology models (generally 25 km), this correction procedure removes significant non-37 glacier areas from the analysis, leading to errors and mis-attribution of signal. An additional complication 38 relates to the periodicity of mass change signals relative to the period of GRACE processing. Aliasing 39 of daily, multi- and sub-daily cycling in hydrological signals occurs when these signals are averaged over 40 monthly time scales and then removed from fully processed GRACE solutions. Additional computations 41 are also necessary to properly compare hydrological observations collected at discrete points in time with 42 time-averaged monthly values acquired from multiple GRACE measurements over a particular region (??). 43 Inversion and forward modeling techniques have been developed to address some of the challenges in 44 GRACE signal recovery described above. In these approaches, best estimates of the mass variations in 45 the signal of interest are developed from independent models (?), datasets (?), or random algorithms 46 (Gardner and others, 2011; Colgan and others, 2013). The simulated signal is then forward modeled to 47 a degree and order that match GRACE resolution, and the observed and simulated GRACE signals are 48 compared. Joint inversion of GRACE together with GPS/ocean bottom pressure (?) and sea surface height 49 (Jensen and others, 2013) have been used to provide additional constraints that help minimize uncertainty 50 in attribution of the GRACE signal. All of these studies aim to better isolate the spatial and temporal 51 patterns in mass change of regions with complex hydrology. By forward modeling and using inversion or 52 Monte Carlo methods, they minimize uncertainties that result from smoothing and filtering when removing 53 signal from a fully processed GRACE solution. 54

Despite this progress in method development, there are several limitations to the above approaches. The first is that independent datasets used to initialize forward modeling studies have focused on glacier volume

loss (e.g.?), i.e. the long-term trend in the GRACE signal. Seasonal changes have been entirely attributed 57 to glacier seasonal mass balances, with limited consideration of the role of terrestrial snowpack and other 58 annually-varying components of the system. The second is that the random generation of a synthetic mass 59 change curve makes it impossible to understand partitioning of mass changes among various hydrological 60 61 systems. While the full signal may be well captured by such approaches, it returns a bulk measure of mass 62 change with no knowledge about the individual source contributors. The third problem is that the spatial resolution of existing inversion/forward modeling approaches is on the scale of large watersheds, limiting 63 our ability to use GRACE to understand processes at smaller spatial scales. 64 In this proposal we will make use a of suite of existing hydrological models that are designed specifically to 65

simulate the water balance of alpine regions, and are capable of being run at high resolution. We will provide evidence that existing land surface hydrology models are fundamentally ill-suited to remove hydrology 67 signals from alpine regions for GRACE simulations, because they have limited resolution, are incapable of 68 simulating basic glacier surface processes, and they lack information on large scale anthropogenic alteration 69 of hydrological systems. We will develop new approaches that can be incorporated into standard GRACE 70 processing procedures. We will show that it is possible to make significant improvements in our ability to 71 recover and partition the sources of mass changes from GRACE for major alpine regions across the globe. 72 Watersheds bordering the Gulf of Alaska (GOA) presently discharge approximately 850 km³ yr⁻¹ (Hill 73 and others, 2015) of freshwater to the ocean. Seasonal and multi-annual variations in these runoff volumes 74 have impacts on near shore ecosystems and ocean circulation patterns (O'Neel and others, 2015). Using a 75 fully distributed energy balance model at 1 km resolution, Beamer and others (2016) have shown that the 76 partitioning of GOA runoff between snow melt, glacier ice melt and rainfall during 2002-2014 was 63%, 77 17% and 20% respectively. 78

Data from the Gravity Recovery and Climate Experiment (GRACE) have been used to assess the hydrology of the GOA region. Early work focused on recovering the trends in mass from GRACE to assess Glacier Volume Loss (GVL) (Sasgen and others, 2012; Schrama and others, 2014; Harig and Simons, 2016; Reager and others, 2016).

There are numerous geophysical systems that contribute to the mass variability of the GOA region at magnitudes that can be measured by GRACE, including changes in glacier mass, terrestrial water storage and glacial isostatic adjustments. Most studies aim to use GRACE to isolate one of these systems as a

- 86 residual of GRACE processing after all other systems have been accounted for through observations or
- 87 models. Alternative approaches include
- 88 (Lenaerts and others, 2013)

89 METHODS

The GRACE mission has revolutionized our ability to monitor global water mass variability by mapping 90 the Earths gravity field each month with a spatial resolution of 300-400 km. Applying GRACE solutions 91 to high-resolution studies, however, poses significant challenges. Due to large increases in the GRACE 92 gravity errors at small spatial scales, the project spherical harmonic solutions must be filtered prior to 93 their application to geophysical research. GRACE mascon estimation, initially developed by the gravity 94 group at NASA Goddard Space Flight Center (GSFC) [Rowlands, 2005; Sabaka et al., 2010; Luthcke et 95 al., 2013], is quickly becoming the preferred method for time-variable gravity estimation (e.g. [Watkins et 96 al., 2015). The mascon approach optimizes the solution signal to noise ratio by introducing a geophysical-97 based regularization matrix in the normal equations, providing a great benefit to researchers who no longer need to design and apply a post-processing filter to the GRACE solutions. However, the mascons still 99 exhibit the same fundamental spatial resolution as the spherical harmonics within a mascon constraint 100 region. Attempts to overcome the resolution limits of GRACE have been made with the estimation and 101 application of 1x1 equal-angle gain factors using a combination of Terrestrial Water Storage (TWS) models 102 and filtered GRACE solutions [Landerer and Swenson, 2012]. The main deficiency in this approach is the 103 significant information loss that occurs when filtering GRACE solutions to their fundamental resolution. 104 Even though this scaled GRACE TWS product is distributed at 11 (Figure 1), it should only be analyzed 105 after combining a sufficient number of grid cells to form regions large enough to be resolved by GRACE. 106 These limitations in the spatial resolution of GRACE motivated the development of a forward modeling 107 approach. The conceptual benefit of forward modeling is simple: by accounting for as much of the known 108 mass variability in the Level 1B (i.e. the intersatellite range rate measurements) processing as possible, the 109 magnitude of the inter-satellite residuals and updates to the gravity field are minimized. This approach 110 reduces the well-known problem of temporal aliasing and limits the portion of the estimated gravity field 111 112 that is subject to the fundamental spatial resolution of the GRACE-determined solutions. In the case of a perfect forward model, the Level 1B processing would produce inter-satellite ranging measurement 113 residuals of zero (ignoring the effects of noise and systematic errors), and no updates to the gravity field 114 would be made. It is important to note that though GRACE solutions are limited in their ability to spatially 115

resolve signals, the Level 1B inter-satellite measurements are in fact sensitive to high temporal and spatial resolution variability, and unmodeled signals of sufficient magnitude at any resolution will manifest as non-zero updates to the mascons.

Since the beginning of the mission, GRACE Level 1B processing centers have relied on forward modeling 119 to remove the effects of ocean tides, atmospheric, and non-tidal ocean mass variability. Sabaka et al., 120 2010 demonstrated the benefit of also including a TWS model for the further reduction of the inter-121 satellite measurement residuals and the mitigation of signal leakage into or out of regions of hydrologic 122 variability. Luthcke et al. [2013] expanded this idea further with the implementation of a fully iterated 123 time-variable mascon solution, where each iterative solution defines the forward model for the subsequent 124 iteration, demonstrating a simultaneous increase in signal and decrease in residual magnitude until solution 125 convergence occurred. In addition to the typical forward models listed above, the current NASA GSFC 126 global mascon solution also models TWS from Global Land Data Assimilation (GLDAS)/Noah [Rodell 127 et al., 2004, ICE-6G glacial isostatic adjustment (GIA) [Peltier et al., 2015], and the largest co-seismic 128 events [Han et al., 2013]. Our proposal will leverage the Level 1B processing and global mascon estimation 129 capabilities at NASA GSFC, resulting in monthly estimates of 41,168 11 arc-degree equal-area cells in 130 terms of cm of equivalent water height. As previously discussed, the true resolution of the solution (300 131 km) is lower than that of the equal-area mascon grid (111 km), but the higher resolution mascon definition 132 allows for a more accurate representation of the land/ocean boundaries that define the constraint regions, 133 across which mascons are uncorrelated. 134

The forward model approach in the context of this study is as follows: GMELT datasets and models 135 of mass changes of the HMA (Figure 2) will define the high-resolution model in the HMA region while 136 the rest of the global model is the NASA GSFC GRACE mascon solution (all other previously described 137 components of the NASA GSFC forward model procedure are also included). Time series of mass changes 138 from GMELT will be combined into an ensemble product based on consensus across the HiMAT team. We 139 will explore the use of weighting factors to combine multiple overlapping estimates, or the testing of different 140 data/model combinations within our iterative framework. Next or best estimates will be expressed to at 141 least spherical harmonic degree and order 90, where the expansion size can be increased if it is determined 142 to be beneficial. Each new Level 1B processing produces a new global mascon solution, where the HMA 143 region mascons describe the long spatial wavelength GMELT error, which serves as feedback for the next 144 iterative construction of the GMELT water balances. Updated GMELT model output is iteratively applied 145

to new Level 1B forward model runs until the GRACE mascon updates are sufficiently close to zero, 146 indicating that the high-resolution GMELT model is in full agreement with the GRACE measurements. It 147 may prove to be more effective and efficient to circumvent the formation and inversion of normal equations 148 by directly analyzing the range-rate or range-acceleration residuals generated from the Level 1B processing 149 as described in recent studies [Loomis et al., 2015; Eicker and Springer, 2016]. We note that our iterative 150 151 procedure enables adjustment of parameters on individual modules of GMELT, or on weighting factors that combine the ensemble of mass change estimates. 152 NASA GSFC GRACE Level 1B processing applies a baseline orbit parameterization [Rowlands et al., 153 2002 that does not require the processing and reduction of GPS measurements, but instead uses the 154 GPS-determined Level 1B navigation files to define the initial orbit that is adjusted simultaneously with 155 the gravity from the inter-satellite measurements (also accounting for the Level 1B attitude quaternions 156 and accelerometer measurements). This allows for the rapid formation and inversion of normal equations 157 for the full duration of the GRACE mission. The ability to quickly process and invert new solutions is an 158 important practical consideration for the work proposed here, where a number of different GMELT outputs 159

161 ACKNOWLEDGEMENTS

will need to be analyzed and iterated.

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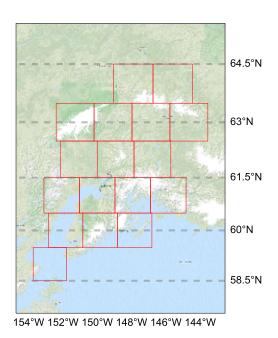


Fig. 1. Mascons of the western Gulf of Alaska.

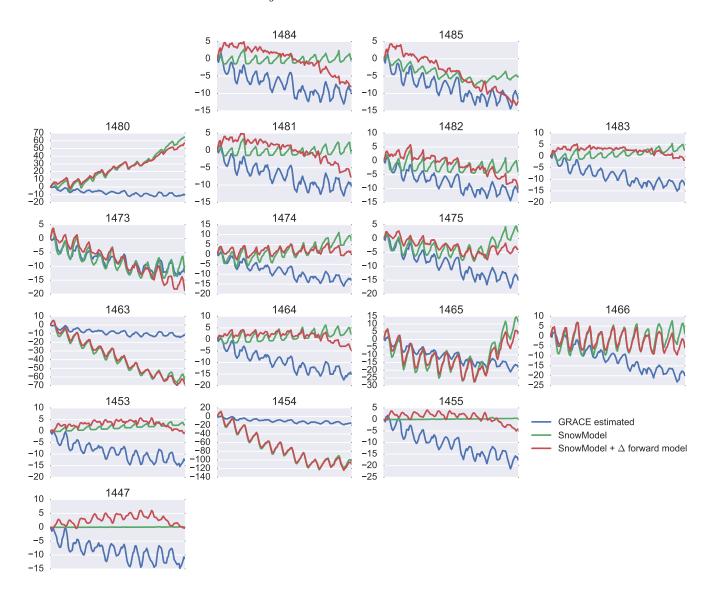


Fig. 2. Comparison of GRACE water balances prior to forward modeling (Luthcke and others, 2013), (blue); modeled water balances using SnowModel (Beamer and others, 2016) (green); and modeled water balance corrected by the forward modeling in this study (red). Subplots are arranged to approximately match the geographic layout of thier respective mascons in Fig. 1

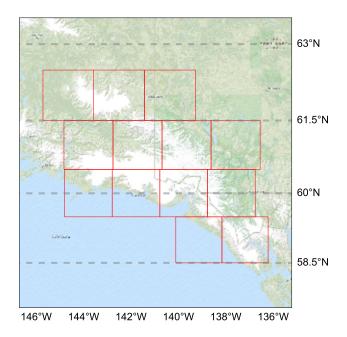


Fig. 3. Mascons of the western GOA

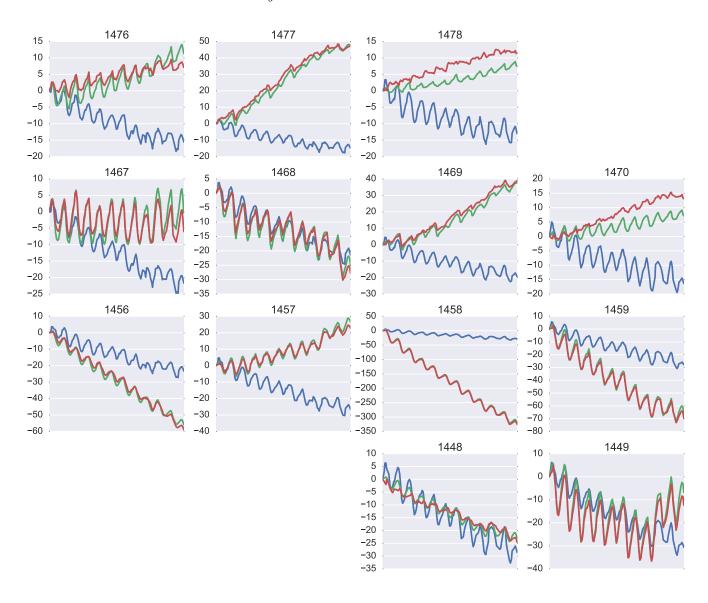
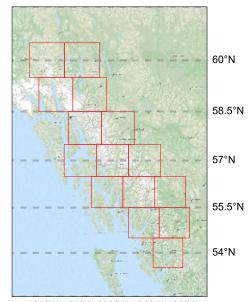


Fig. 4. Mascons of the western GOA



136°W 134°W 132°W 130°W 128°W

Fig. 5. Mascons of the western GOA

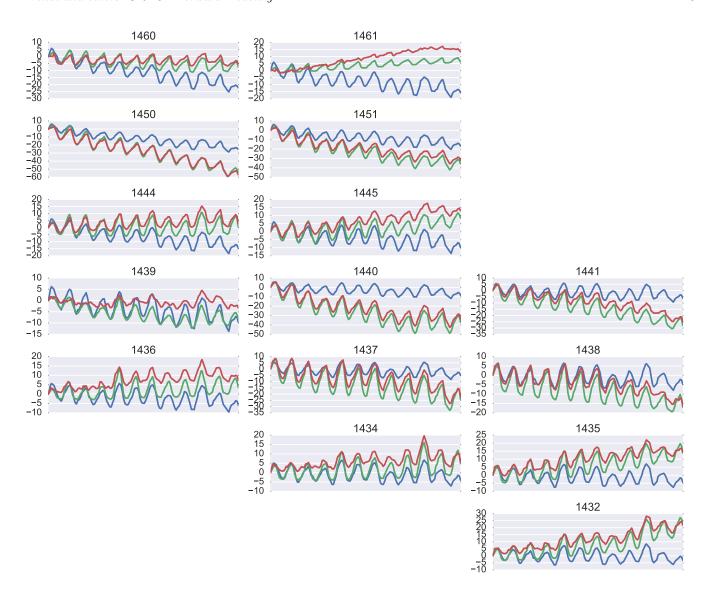


Fig. 6. Mascons of the western GOA