
Computer Graphics

- BRDFs & Texturing -

Hendrik Lensch

Overview

- **Last time**
 - Radiance
 - Light sources
 - Rendering Equation & Formal Solutions
- **Today**
 - Bidirectional Reflectance Distribution Function (BRDF)
 - Reflection models
 - Projection onto spherical basis functions
 - Shading
- **Next lecture**
 - Varying (reflection) properties over object surface: texturing

Reflection Equation - Reflectance

- **Reflection equation**

$$L_o(\underline{x}, \underline{\omega}_o) = \int_{\Omega_+} f_r(\underline{\omega}_i, \underline{x}, \underline{\omega}_o) L_i(\underline{x}, \underline{\omega}_i) \cos \theta_i d\omega_i$$

入射光照角度

- **BRDF**

- Ratio of reflected radiance to incident irradiance

$$f_r(\omega_o, x, \omega_i) = \frac{dL_o(x, \omega_o)}{dE_i(x, \omega_i)}$$

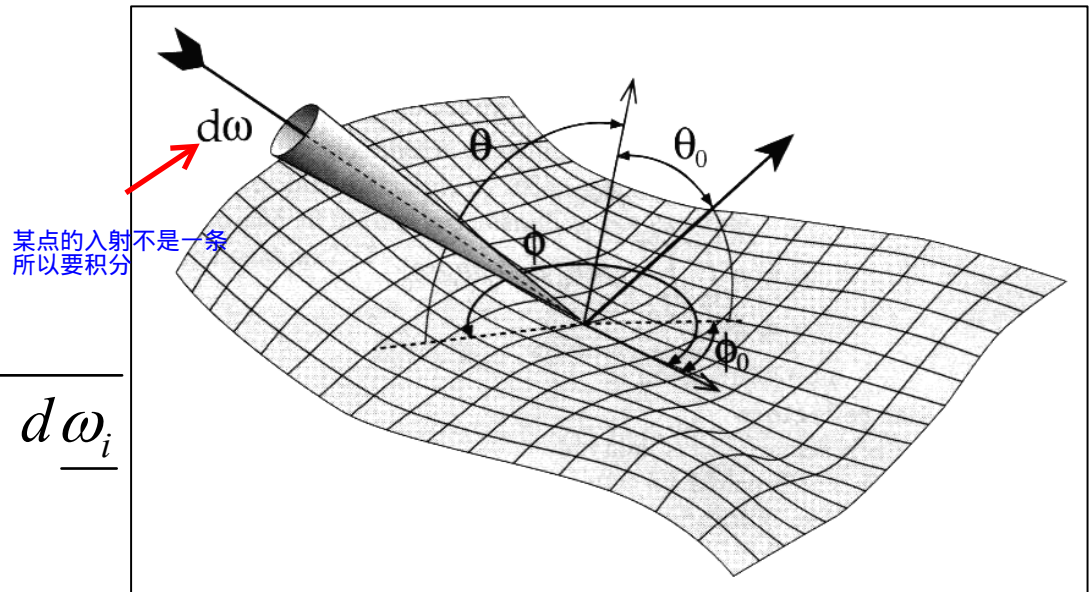
用x, 入射Wi 出射Wo 求 Fr对 L (x , W0) 做积分
对 E (x , Wi) 做积分

Fr为入射反射比

Bidirectional Reflectance Distribution Function

- **BRDF describes surface reflection for light incident from direction (θ_i, φ_i) observed from direction (θ_o, φ_o)**
- **Bidirectional**
 - Depends on two directions and position (6-D function)
- **Distribution function**
 - Can be infinite
- **Unit [1/sr]**

$$\begin{aligned} f_r(\underline{\omega}_o, \underline{x}, \underline{\omega}_i) &= \frac{dL_o(\underline{x}, \underline{\omega}_o)}{dE_i(\underline{x}, \underline{\omega}_i)} \\ &= \frac{dL_o(\underline{x}, \underline{\omega}_o)}{dL_i(\underline{x}, \underline{\omega}_i) \cos \theta_i d\omega_i} \end{aligned}$$



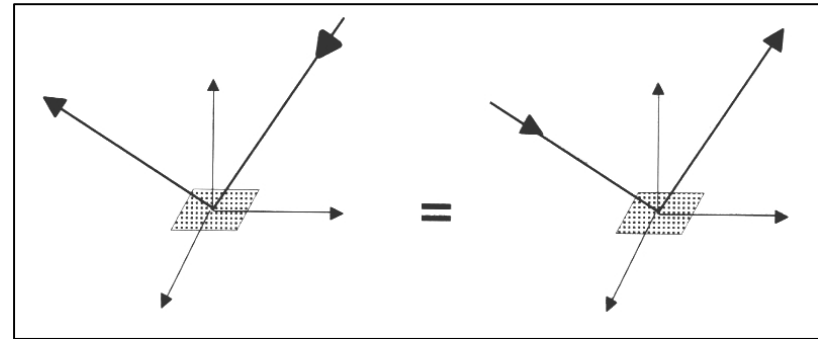
BRDF Properties

- **Helmholtz reciprocity principle**

- BRDF remains unchanged if incident and reflected directions are interchanged

$$f_r(\omega_o, \omega_i) = f_r(\omega_i, \omega_o)$$

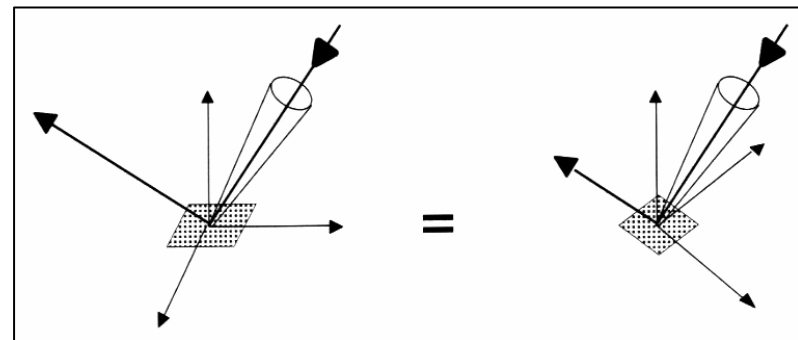
能量守恒，入射等于出射



- **Smooth surface: isotropic BRDF**

- reflectivity independent of rotation around surface normal
- BRDF has only 3 instead of 4 directional degrees of freedom

$$f_r(\underline{x}, \theta_i, \theta_o, \varphi_o - \varphi_i)$$



BRDF Properties

- **Characteristics**

- BRDF units [sr^{-1}]
 - Not intuitive
- Range of values:
 - From 0 (absorption) to ∞ (reflection, δ -function)
- Energy conservation law
 - No self-emission
 - Possible absorption

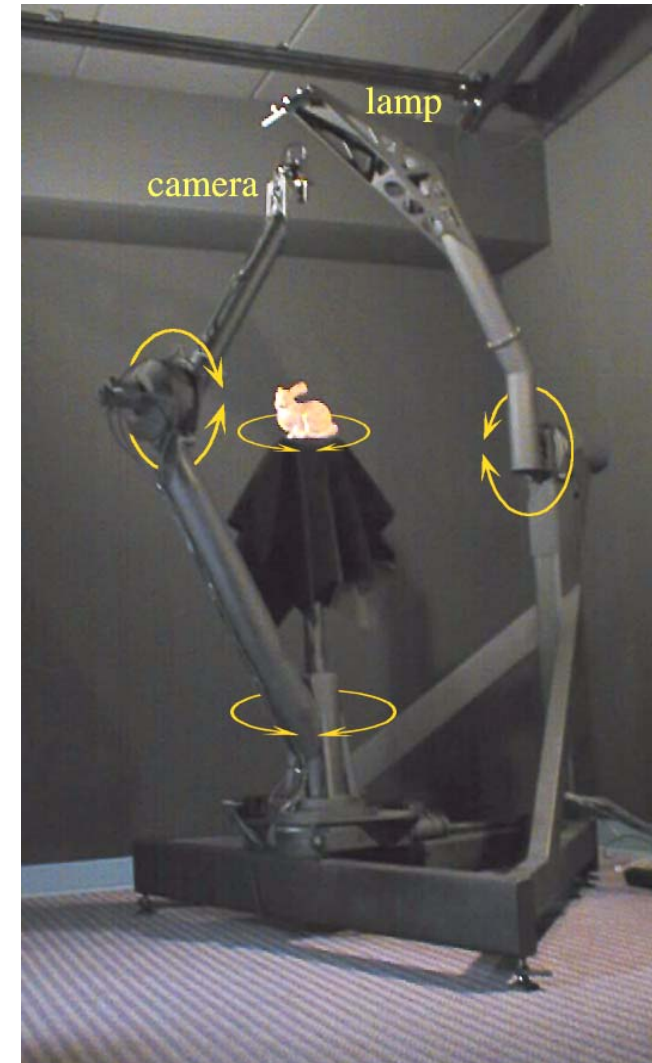
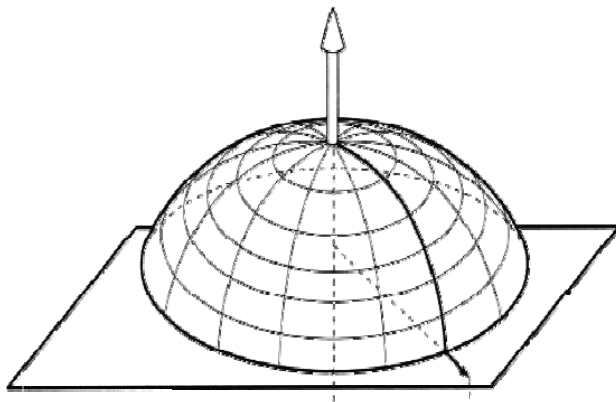
可能出射小于入射

$$\int_{\Omega} f_r(\underline{\omega}_o, \underline{x}, \underline{\omega}_i) \cos \theta_o d\omega_o \leq 1 \quad \forall \theta, \varphi$$

- Reflection only at the point of entry ($x_i = x_o$)
 - No subsurface scattering

BRDF Measurement

- **Gonio-Reflectometer**
- **BRDF measurement**
 - point light source position (θ, φ)
 - light detector position (θ_o, φ_o)
- **4 directional degrees of freedom**
- **BRDF representation**
 - m incident direction samples (θ, φ)
 - n outgoing direction samples (θ_o, φ_o)
 - $m*n$ reflectance values (large!!!)



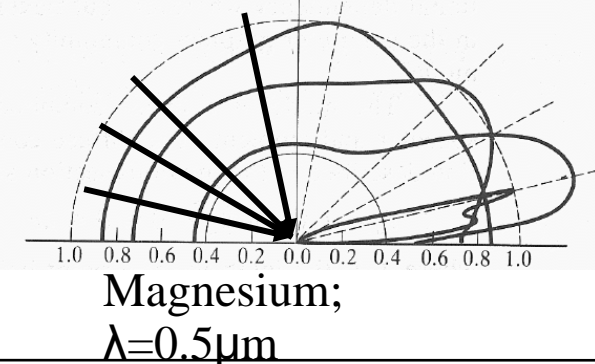
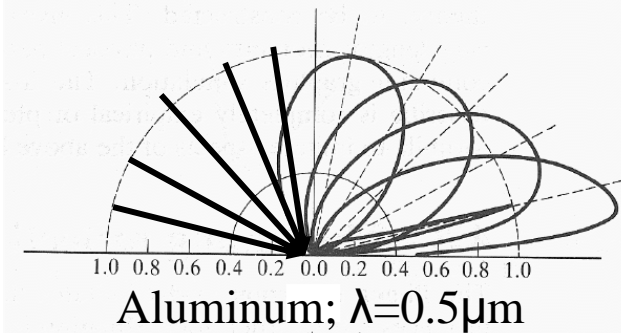
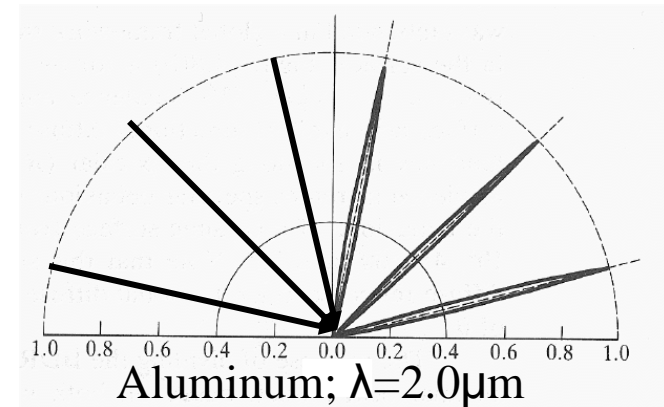
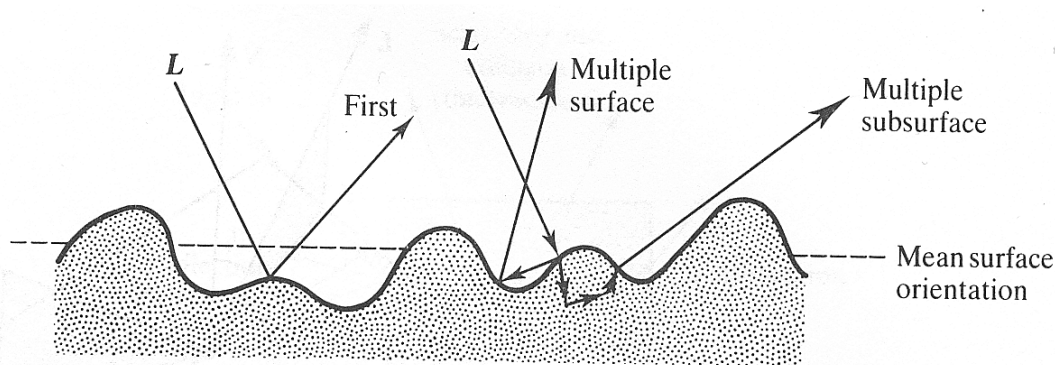
Stanford light gantry

Reflectance

- **Reflectance may vary with**
 - Illumination angle
 - Viewing angle
 - Wavelength
 - (Polarization, ...)
- **Variations due to**
 - Absorption
 - Surface micro-geometry
 - Index of refraction / dielectric constant
 - Scattering

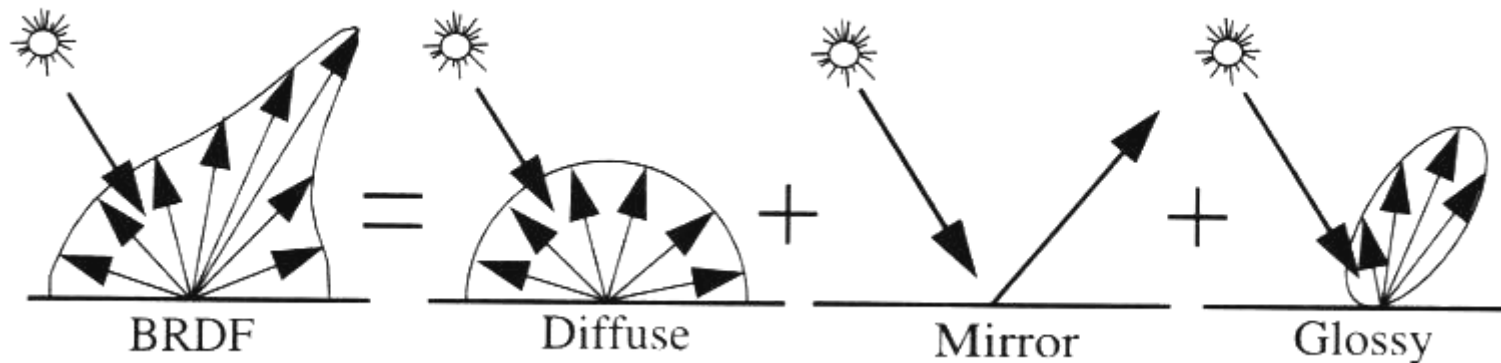
光照可能受很多因素影响

散射



BRDF Modeling

- **Phenomenological approach**
 - Description of visual surface appearance
- **Ideal specular reflection**
 - Reflection law
 - Mirror
- **Glossy reflection**
 - Directional diffuse
 - Shiny surfaces
- **Ideal diffuse reflection**
 - Lambert's law
 - Matte surfaces



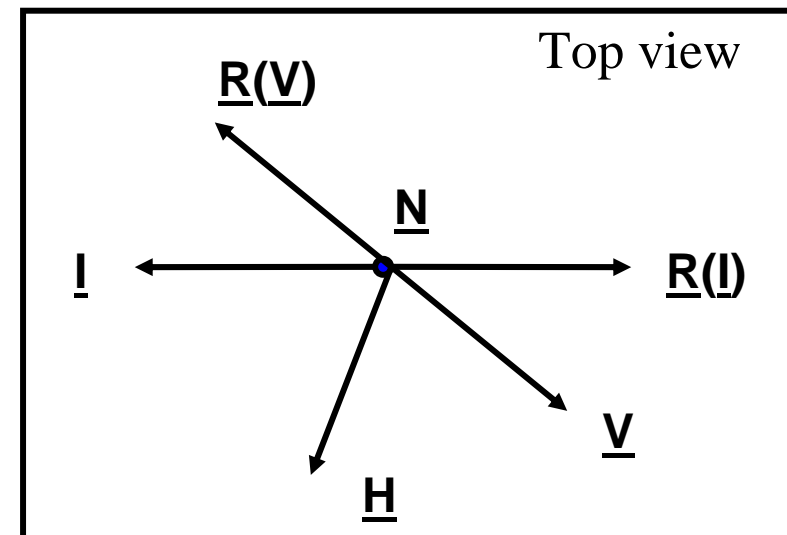
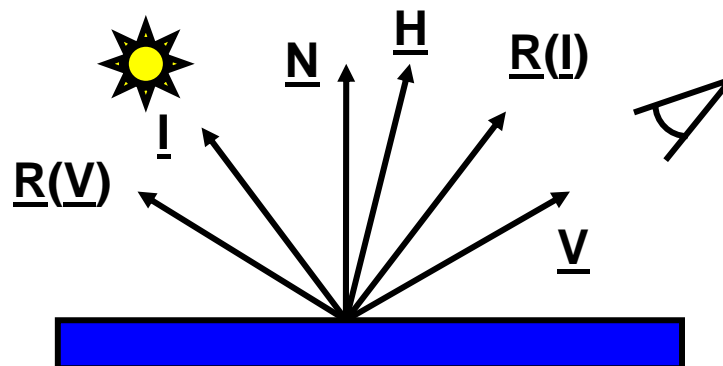
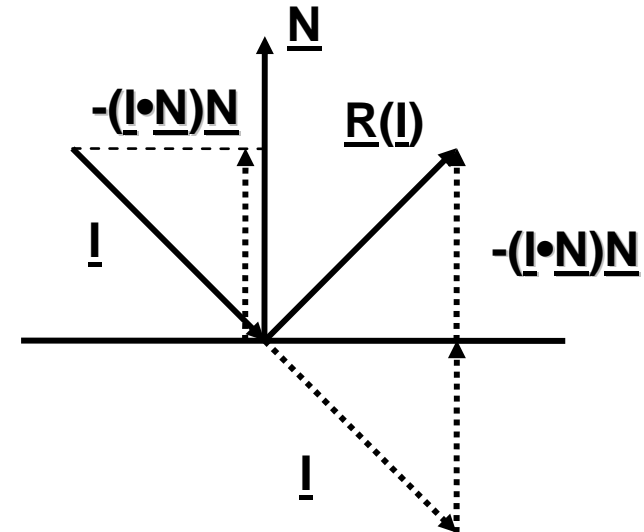
Reflection Geometry

- **Direction vectors (normalize):**

- \underline{N} : surface normal
- \underline{I} : vector to the light source
- \underline{V} : viewpoint direction vector
- \underline{H} : halfway vector

$$\underline{H} = (\underline{I} + \underline{V}) / |\underline{I} + \underline{V}|$$
 归一化
- $\underline{R(I)}$: reflection vector

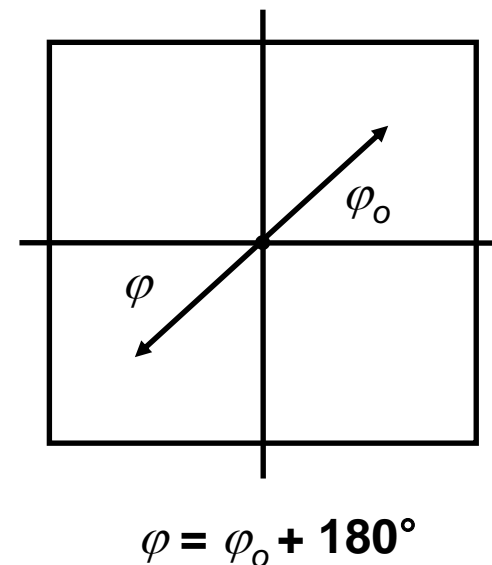
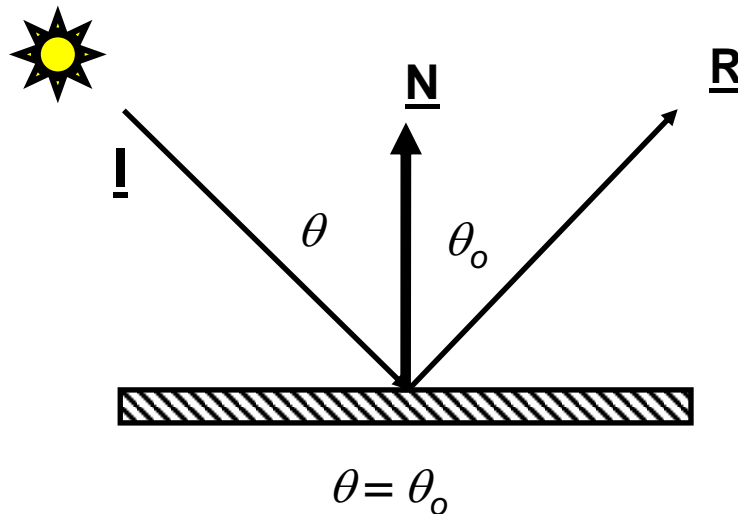
$$\underline{R(I)} = \underline{I} - 2(\underline{I} \cdot \underline{N})\underline{N}$$
- Tangential surface: local plane



Ideal Specular Reflection

- Angle of reflectance equal to angle of incidence
- Reflected vector in a plane with incident ray and surface normal vector

$$\underline{R} + (-\underline{I}) = 2 \cos\theta \underline{N} = -2(\underline{I} \cdot \underline{N}) \underline{N}$$
$$\underline{R}(\underline{I}) = \underline{I} - 2(\underline{I} \cdot \underline{N}) \underline{N}$$



Mirror BRDF

- **Dirac Delta function $\delta(x)$**

- $\delta(x)$: zero everywhere except at $x=0$
- Unit integral iff integration domain contains zero (zero otherwise)

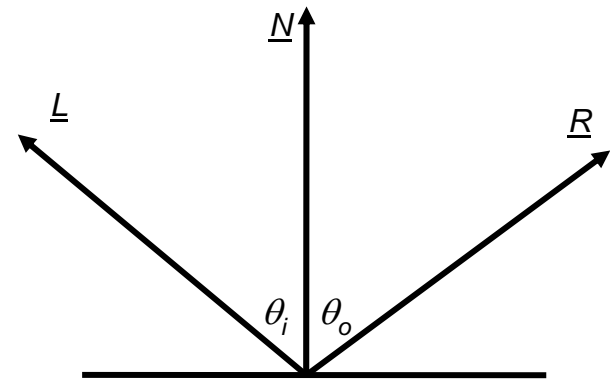
$$f_{r,m}(\omega_o, x, \omega_i) = \rho_s(\theta_i) \cdot \frac{\delta(\cos \theta_i - \cos \theta_o)}{\cos \theta_i} \cdot \delta(\varphi_i - \varphi_o \pm \pi)$$

$$L_o(x, \omega_o) = \int_{\Omega_+} f_{r,m}(\omega_o, x, \omega_i) L_i(\theta_i, \varphi_i) \cos \theta_i d\omega_i = \rho_s(\theta_i) L_i(\theta_o, \varphi_o \pm \pi)$$

- **Specular reflectance ρ_s**

- Ratio of reflected radiance in specular direction and incoming radiance
- Dimensionless quantity between 0 and 1

$$\rho_s(\theta_i) = \frac{\Phi_o(\theta_o)}{\Phi_i(\theta_i)}$$



Diffuse Reflection

- Light equally likely to be reflected in any output direction (independent of input direction)
- Constant BRDF

$$f_{r,d}(\underline{\omega}_o, \underline{x}, \underline{\omega}_i) = k_d = \text{const}$$

$$L_o(\underline{x}, \underline{\omega}_o) = \int k_d L_i(\underline{x}, \underline{\omega}_i) \cos \theta_i d\Omega_i = k_d \int L_i(\underline{x}, \underline{\omega}_i) \cos \theta_i d\Omega_i = k_d E$$

– k_d : diffuse coefficient, material property [1/sr]

Kd是一个定值，是材质的扩散系数



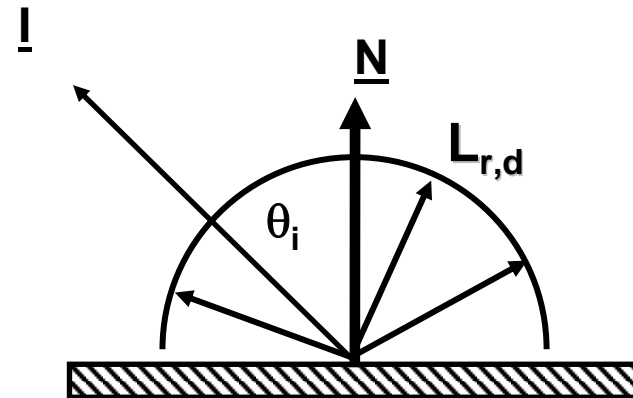
Lambertian Diffuse Reflection

- **Radiosity** $B = \int_{\Omega} L_o(\underline{x}, \underline{\omega}_o) \cos \theta_o d\underline{\omega}_o = L_o \int_{\Omega} \cos \theta_o d\underline{\omega}_o = \pi L_o$

- **Diffuse Reflectance** $\rho_d = \frac{B}{E} = \pi k_d$

- **Lambert's Cosine Law** $B = \rho_d E = \rho_d E_i \cos \theta_i$

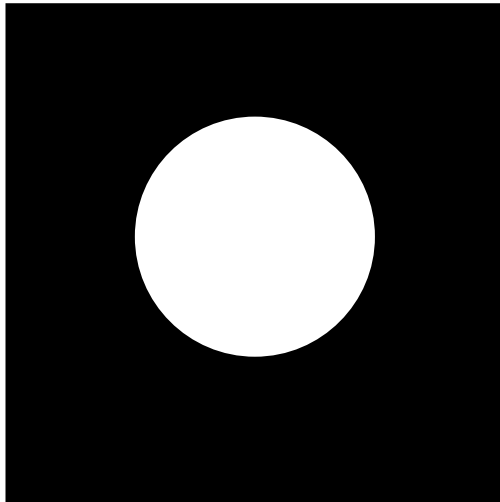
- **For each light source**
 - $L_{r,d} = k_d L_i \cos \theta_i = k_d L_i (\underline{l} \cdot \underline{N})$



Lambertian Objects

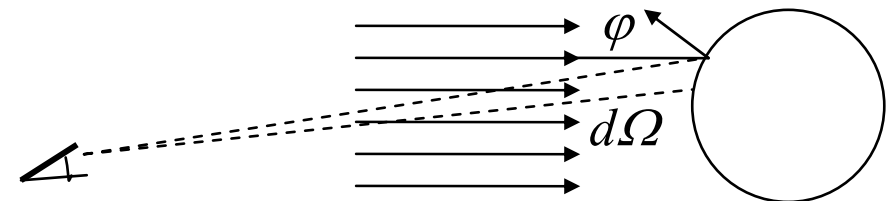
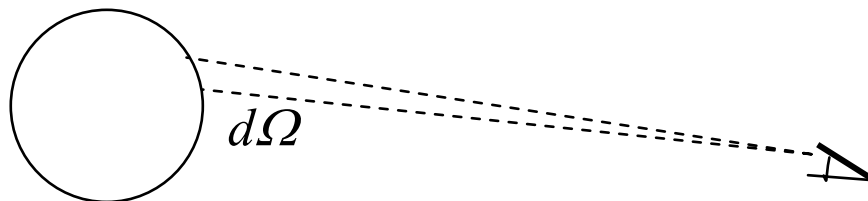
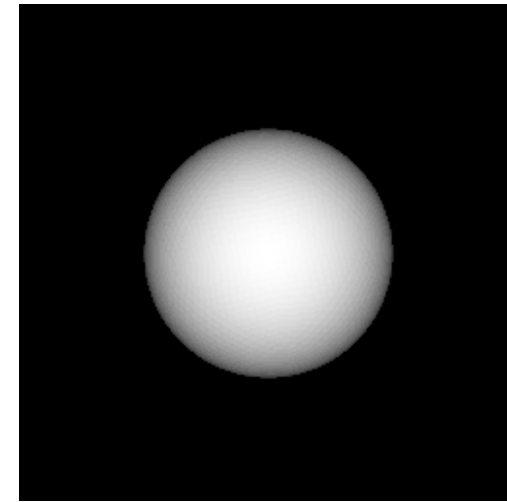
Self-Luminous
spherical Lambertian Light Source

$$\Phi_0 \propto L_0 \cdot d\Omega$$



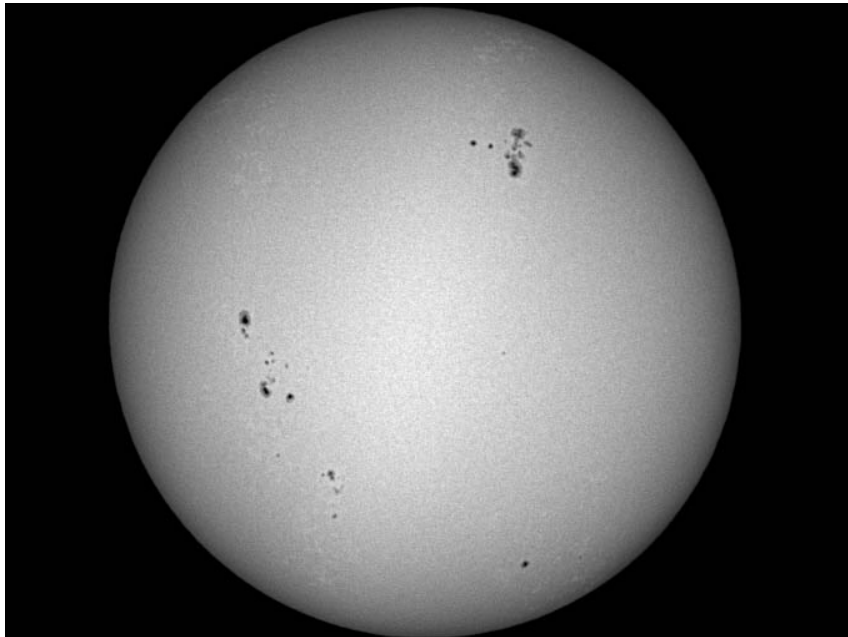
Eye-light illuminated
Spherical Lambertian Reflector

$$\Phi_1 \propto L_0 \cdot \cos \varphi \cdot d\Omega$$



Lambertian Objects II

The Sun



- Absorption in photosphere
- Path length through photosphere longer from the Sun's rim

The Moon



- Surface covered with fine dust
- Dust on TV visible best from slanted viewing angle

⇒ Neither the Sun nor the Moon are Lambertian

“Diffuse” Reflection

- **Theoretical explanation**
 - Multiple scattering
- **Experimental realization**
 - Pressed magnesium oxide powder
 - Almost never valid at high angles of incidence

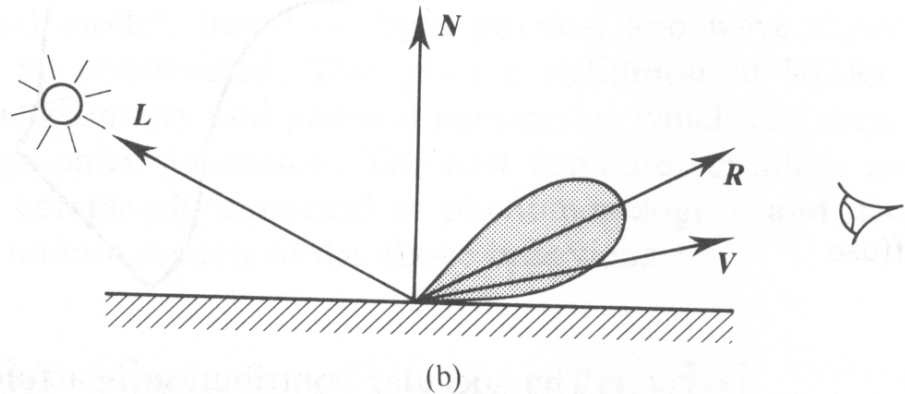
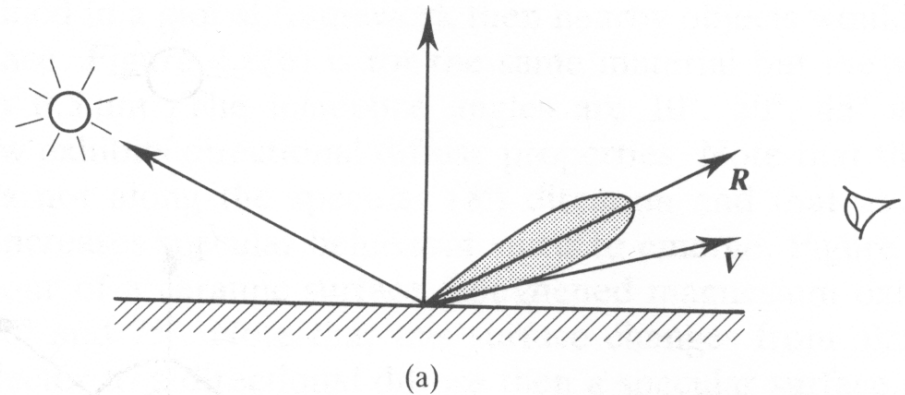
Paint manufacturers attempt to create ideal diffuse paints

Glossy Reflection



Glossy Reflection

- **Due to surface roughness**
- **Empirical models**
 - Phong
 - Blinn-Phong
- **Physical models**
 - Blinn
 - Cook & Torrance



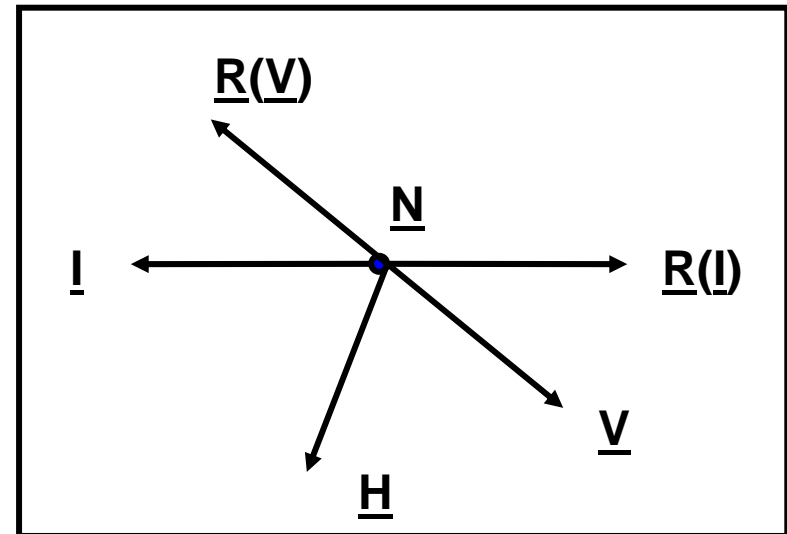
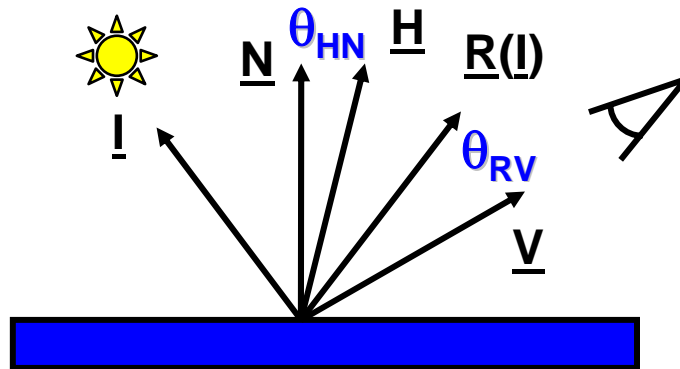
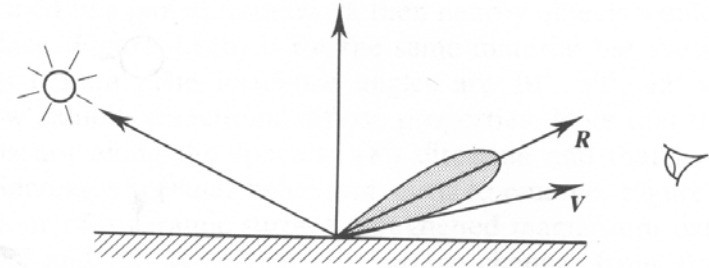
Phong Reflection Model

- Cosine power lobe

$$f_r(\omega_o, x, \omega_i) = k_s (\underline{R}(\underline{I}) \cdot \underline{V})^{k_e}$$

$$- L_{r,s} = L_i k_s \cos^{k_e} \theta_{RV}$$

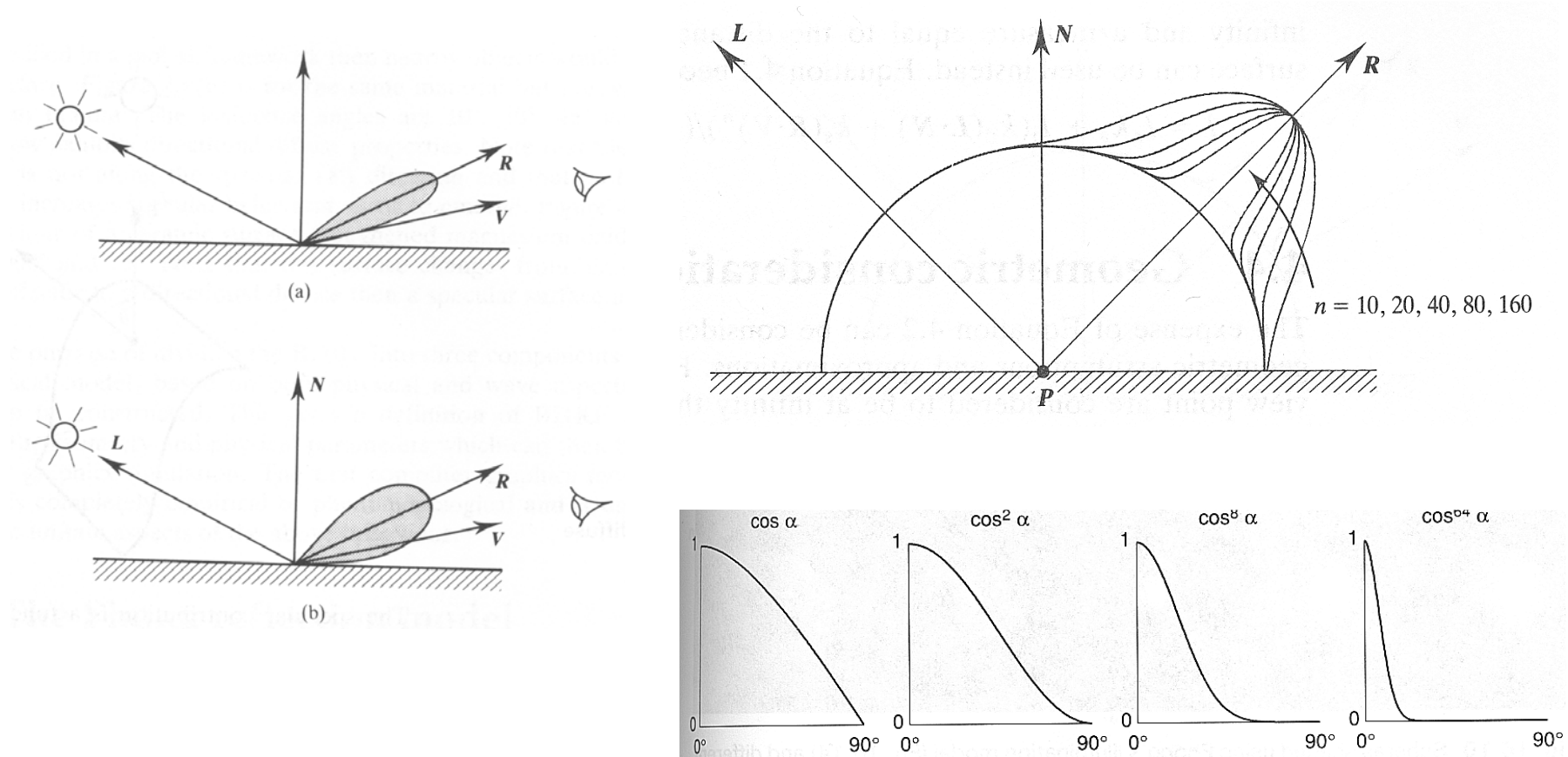
- Dot product & power
- Not energy conserving/reciprocal
- Plastic-like appearance



Phong Exponent k_e

$$f_r(\omega_o, x, \omega_i) = k_s (\underline{R(I)} \cdot \underline{V})^{k_e}$$

- **Determines size of highlight**

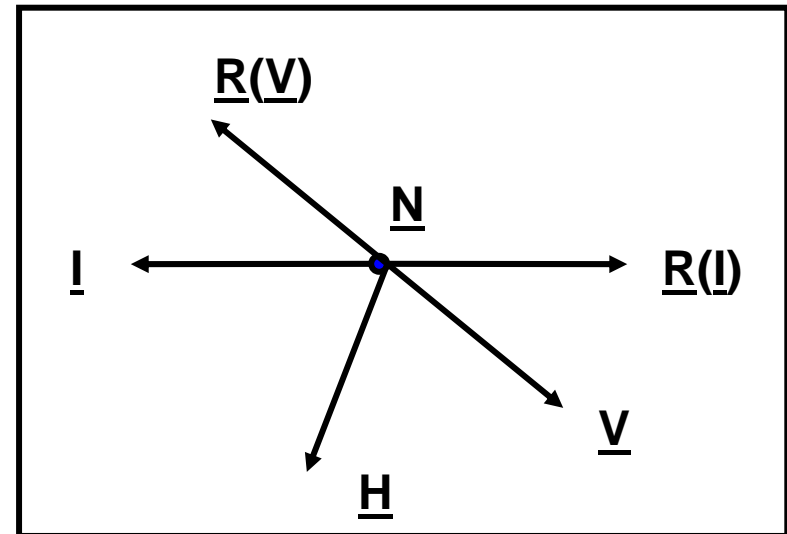
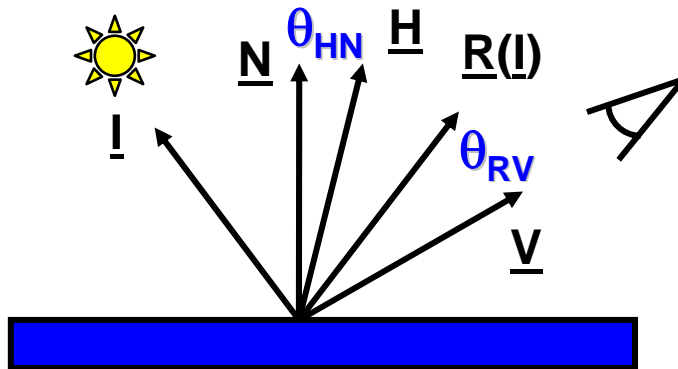
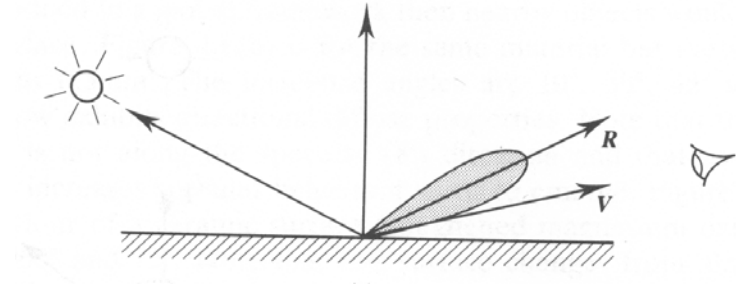


Blinn-Phong Reflection Model

- Blinn-Phong reflection model

$$f_r(\omega_o, x, \omega_i) = k_s (H \cdot N)^{k_e}$$

- $L_{r,s} = L_i k_s \cos^{k_e} \theta_{HN}$
- $\theta_{RV} \Rightarrow \theta_{HN}$
- Light source, viewer far away
- \underline{I} , \underline{R} constant: \underline{H} constant
 θ_{HN} less expensive to compute



Phong Illumination Model

- **Extended light sources: l point light sources**

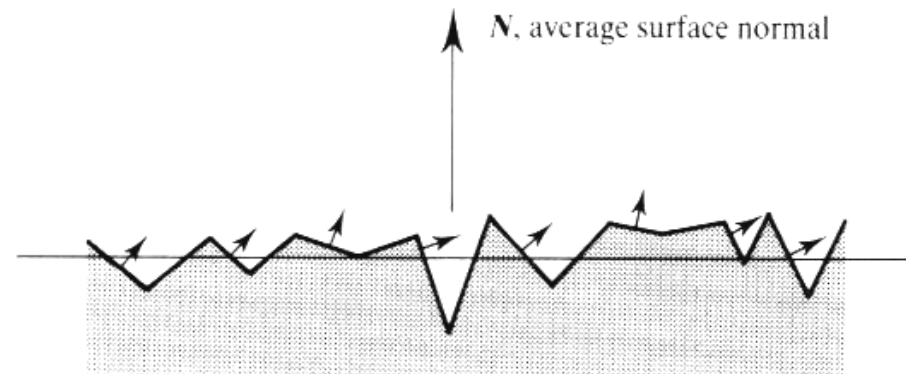
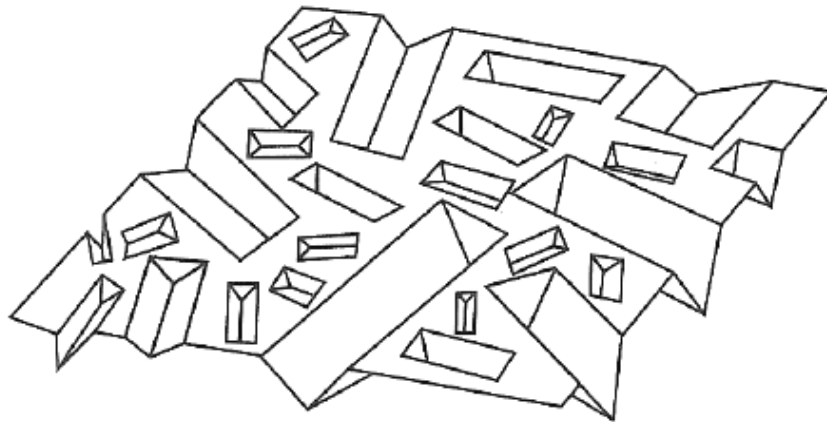
$$L_r = k_a L_{i,a} + k_d \sum_l L_l (I_l \cdot N) + k_s \sum_l L_l (R(I_l) \cdot V)^{k_e} \quad (\text{Phong})$$

$$L_r = k_a L_{i,a} + k_d \sum_l L_l (I_l \cdot N) + k_s \sum_l L_l (H_l \cdot N)^{k_e} \quad (\text{Blinn})$$

- **Color of specular reflection equal to light source**
- **Heuristic model**
 - Contradicts physics
 - Purely local illumination
 - Only direct light from the light sources
 - No further reflection on other surfaces
 - Constant ambient term
- **Often: light sources & viewer assumed to be far away**

Microfacet Model

- **Isotropic microfacet collection**
- **Microfacets assumed as perfectly smooth reflectors**
- **BRDF**
 - Distribution of microfacets
 - Often probabilistic distribution of orientation or V-groove assumption
 - Planar reflection properties
 - Self-masking, shadowing

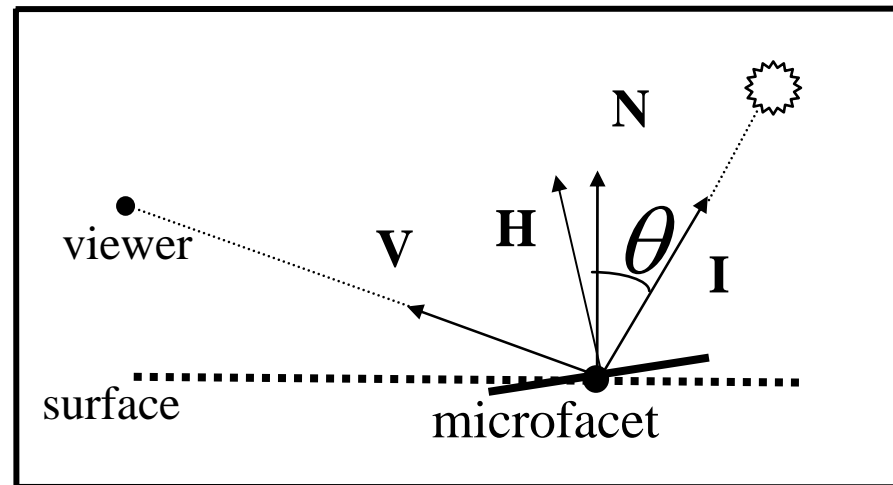


Ward Reflection Model

- **BRDF**

$$f_r = \frac{\rho_d}{\pi} + \rho_s \frac{1}{\sqrt{(I \cdot N)(V \cdot N)}} \cdot \frac{\exp(-\tan^2 \angle(H, N) / \sigma^2)}{4\pi\sigma^2}$$

- σ standard deviation (RMS) of surface slope
- Simple expansion to anisotropic model (σ_x, σ_y)
- Empirical, not physics-based
- Inspired by notion of reflecting microfacets
- Convincing results
- Good match to measured data



Physics-inspired BRDFs

- **Notion of reflecting microfacet**
- **Specular reflectivity of the form**

$$f_r = \frac{D \cdot G \cdot F_\lambda(\lambda, \theta_i)}{\pi \underline{N} \cdot \underline{V}}$$

- D : statistical microfacet distribution
 - G : geometric attenuation, self-shadowing
 - F : Fresnel term, wavelength, angle dependency of reflection along mirror direction
 - $\underline{N} \cdot \underline{V}$: flaring effect at low angle of incidence
-
- **Cook-Torrance model**
 - F : wavelength- and angle-dependent reflection
 - Metal surfaces

Cook-Torrance Reflection Model

- **Cook-Torrance reflectance model** is based on the *microfacet* model. The BRDF is defined as the sum of a diffuse and specular components:

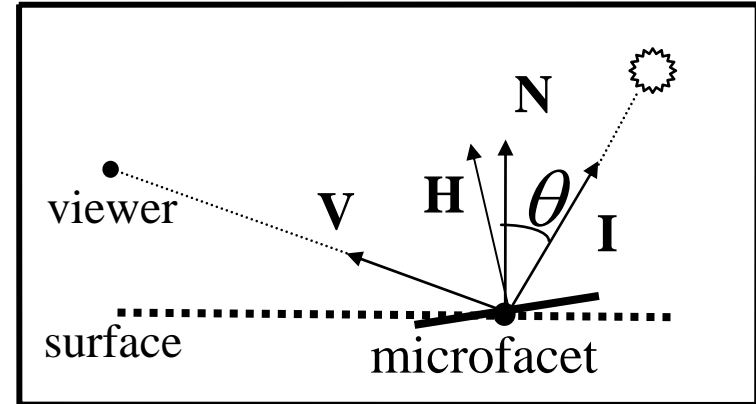
$$f_r = k_d \rho_d + k_s \rho_s; \quad k_d + k_s \leq 1$$

where k_s and k_d are the specular and diffuse coefficients.

- Derivation of the specular component ρ_s is based on a **physically derived** theoretical reflectance model

Cook-Torrance Specular Term

$$\rho_s = \frac{F_\lambda DG}{\pi(\underline{N} \cdot \underline{V})(\underline{N} \cdot \underline{I})}$$



- **D : Distribution function of microfacet orientations**
- **G : Geometrical attenuation factor**
 - represents self-masking and shadowing effects of microfacets
- **F_λ : Fresnel term**
 - computed by Fresnel equation
 - relates incident light to reflected light for each planar microfacet
- **$\underline{N} \cdot \underline{V}$: Proportional to visible surface area**
- **$\underline{N} \cdot \underline{I}$: Proportional to illuminated surface area**

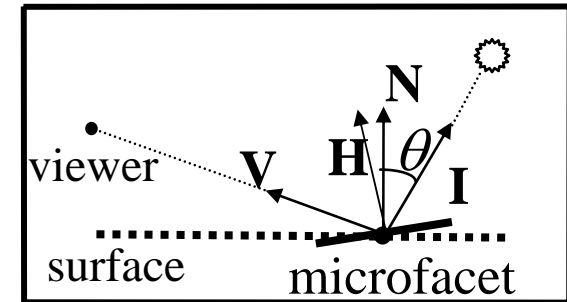
$$F_\lambda \approx (1 + (\underline{V} \cdot \underline{N}))^\lambda$$

Microfacet Distribution Functions

- **Isotropic Distributions** $D(\underline{\omega}) \Rightarrow D(\alpha) \quad \alpha = \mathbf{N} \cdot \mathbf{H}$

- α : angle to average normal of surface
- Characterized by half-angle β

$$D(\beta) = \frac{1}{2}$$



- **Blinn**

$$D(\alpha) = \cos^{\frac{\ln 2}{\ln \cos \beta} \alpha} \alpha$$

- **Torrance-Sparrow**

$$D(\alpha) = e^{-\left(\frac{\sqrt{2}}{\beta} \alpha\right)^2}$$

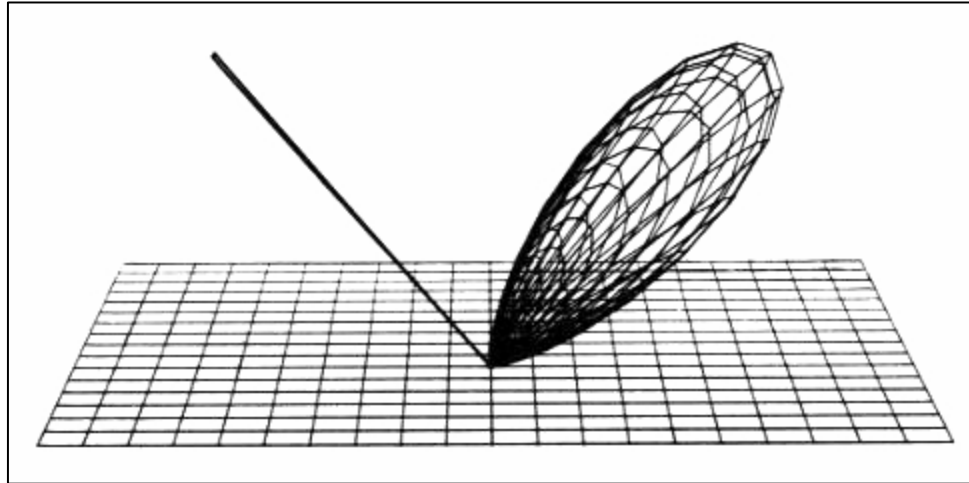
- **Beckmann**

- m : average slope of the microfacets
- Used by Cook-Torrance

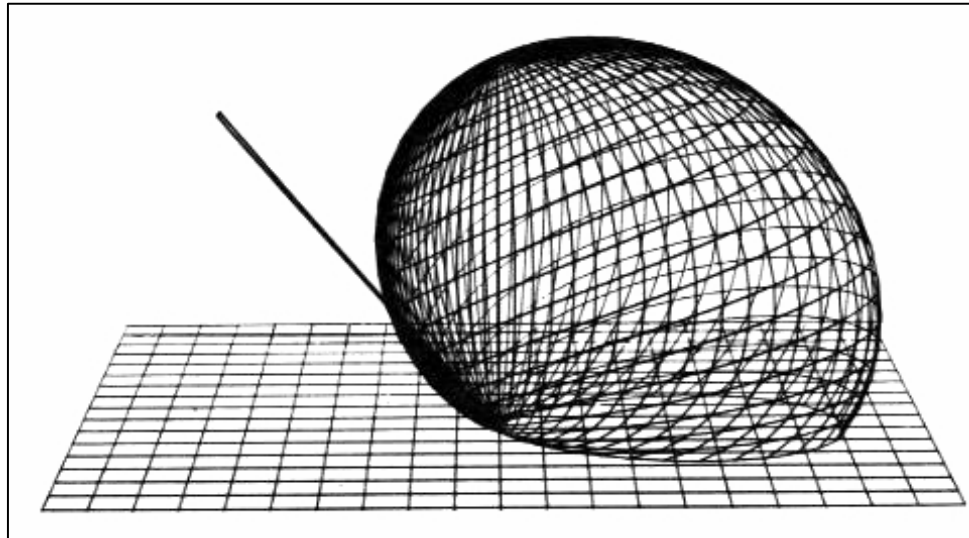
$$D(\alpha) = \frac{1}{4m^2 \cos^4 \alpha} e^{-[\tan \alpha / m]^2}$$

Beckman Microfacet Distribution Function

$m=0.2$



$m=0.6$



Geometric Attenuation Factor

- **V-shaped grooves**
- Fully illuminated and visible

$$G = 1$$

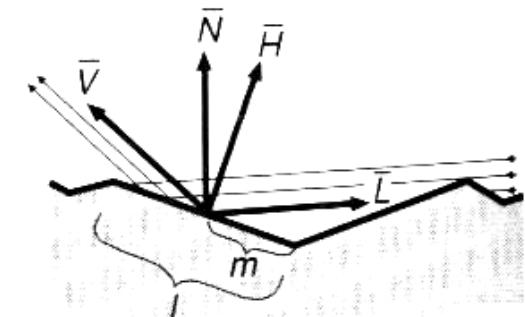
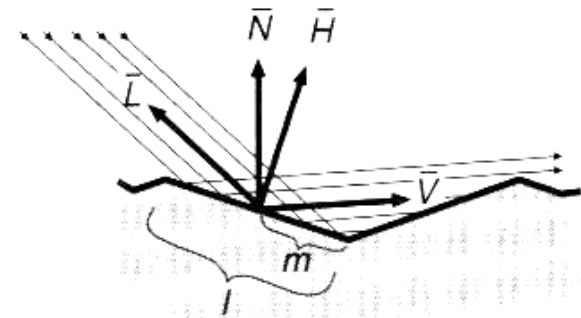
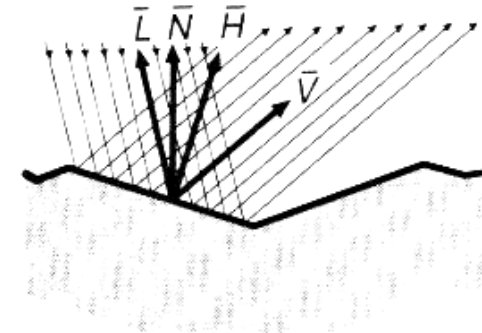
- Partial masking of reflected light

$$G = \frac{2(\underline{N} \cdot \underline{H})(\underline{N} \cdot \underline{V})}{(\underline{V} \cdot \underline{H})}$$

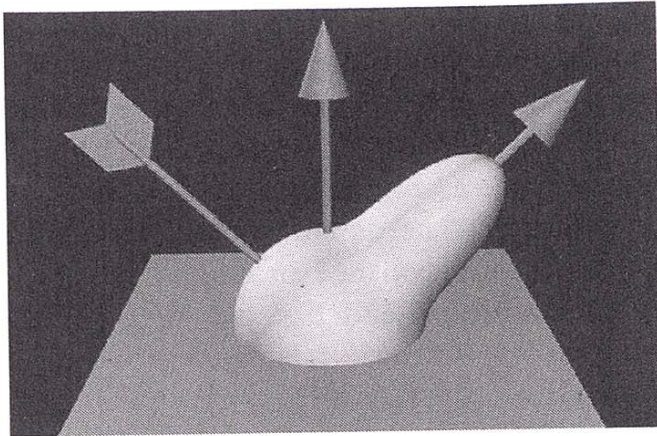
- Partial shadowing of incident light

$$G = \frac{2(\underline{N} \cdot \underline{H})(\underline{N} \cdot \underline{I})}{(\underline{V} \cdot \underline{H})}$$

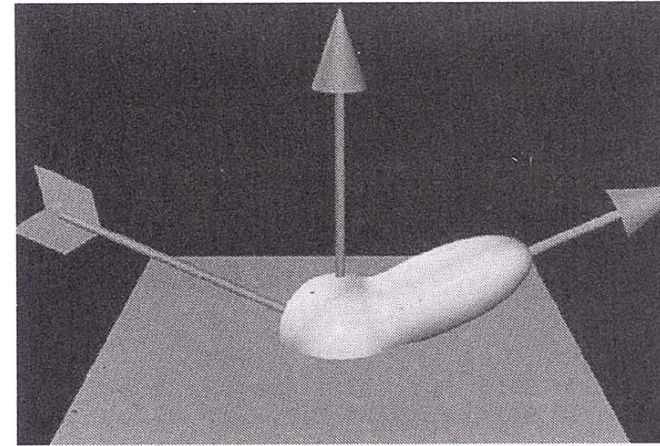
$$G = \min \left\{ 1, \frac{2(\underline{N} \cdot \underline{H})(\underline{N} \cdot \underline{V})}{(\underline{V} \cdot \underline{H})}, \frac{2(\underline{N} \cdot \underline{H})(\underline{N} \cdot \underline{I})}{(\underline{V} \cdot \underline{H})} \right\}$$



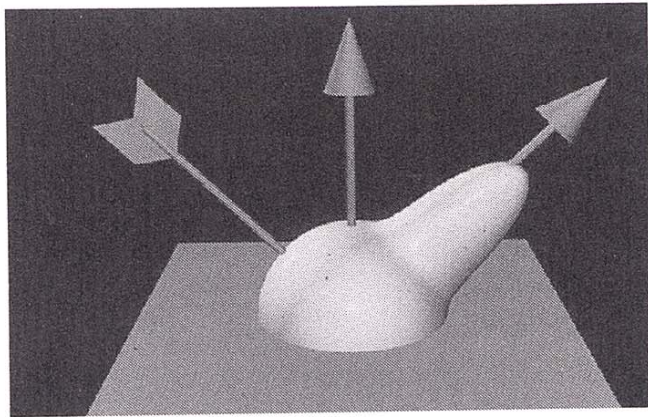
Comparison Phong vs. Torrance



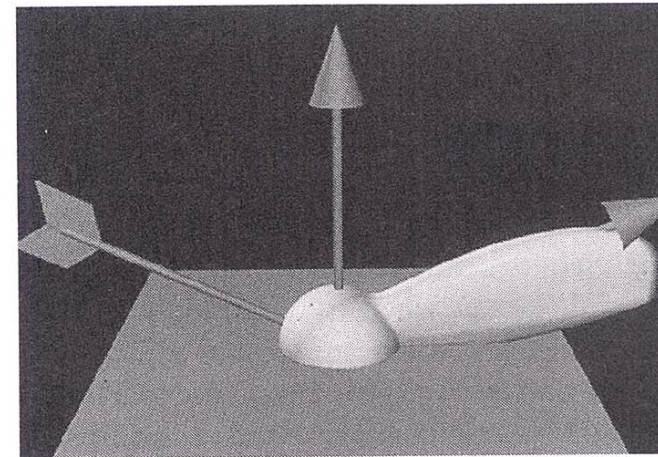
(a)



(b)



(c)

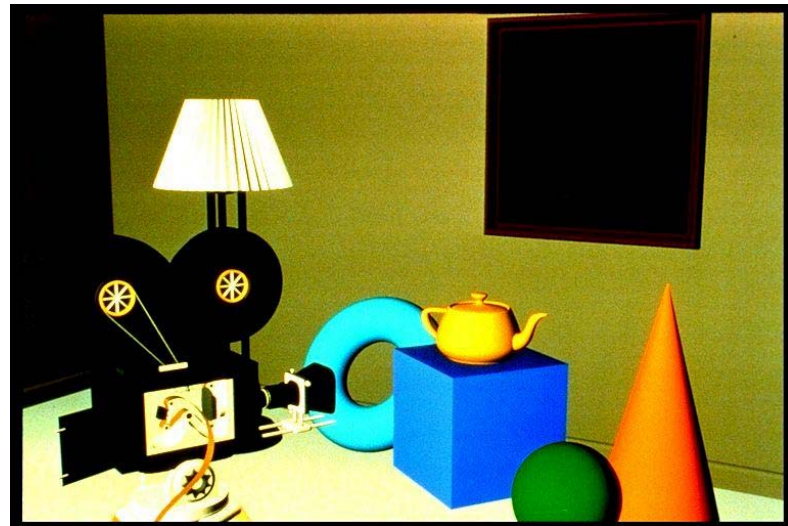
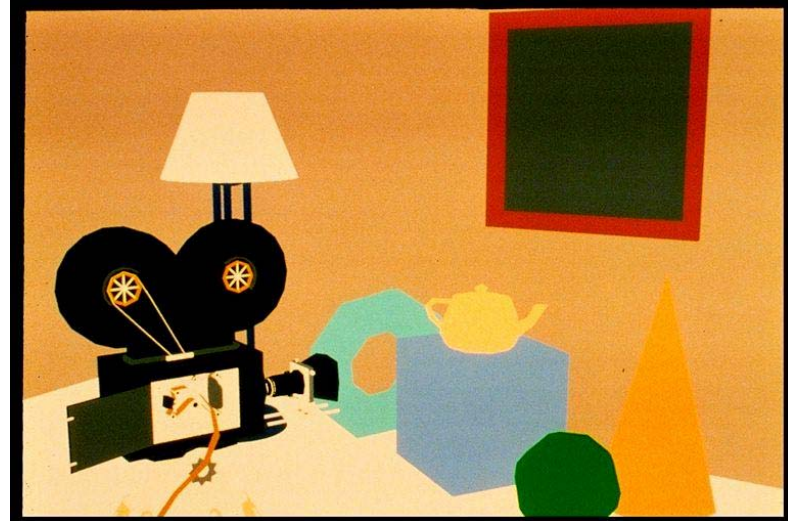


(d)

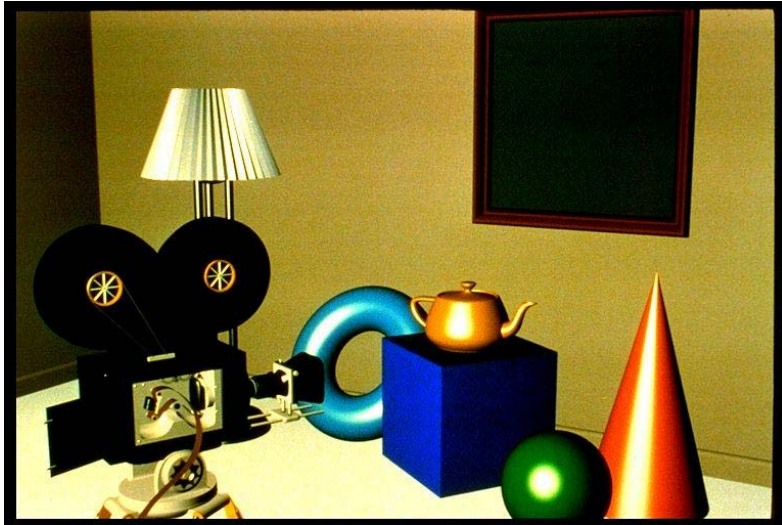
Texturing

Simple Illumination

- No illumination
- Constant colors
- Parallel light
- Diffuse reflection



Standard Illumination



- **Parallel light**
- **Specular reflection**



- **Multiple local light sources**
- **Different BRDFs**

Object properties constant over surface

Texturing

Locally varying
object characteristics

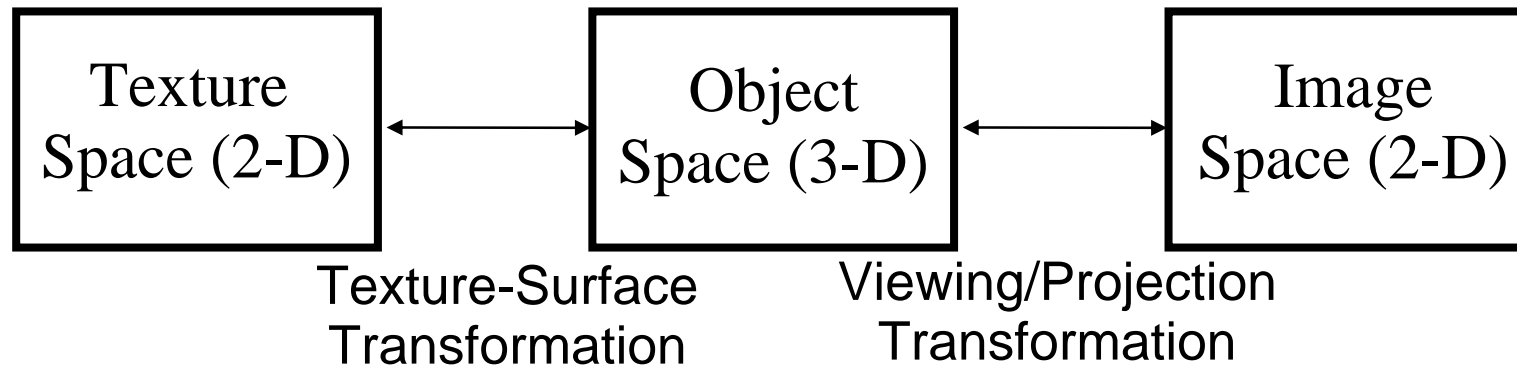
- 2D Image Textures
- Shadows
- Bump-Mapping
- Reflection textures



Texture-modulated Quantities

- **Modulation of object surface properties**
- **Reflectance**
 - Color (RGB), diffuse reflection coefficient k_d
 - Specular reflection coefficient k_s
- **Opacity (α)**
- **Normal vector**
 - $N(P) = N(P + t N)$ or $N = N + dN$
 - „Bump mapping“ or „Normal mapping“
- **Geometry**
 - $P = P + dP$
 - „Displacement mapping“
- **Distant illumination**
 - “Environment mapping“, “Reflection mapping“

Texture Mapping Transformations



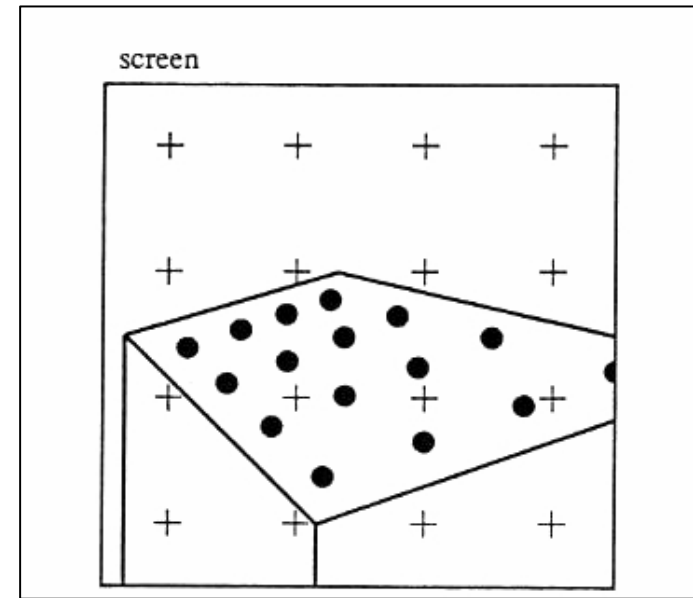
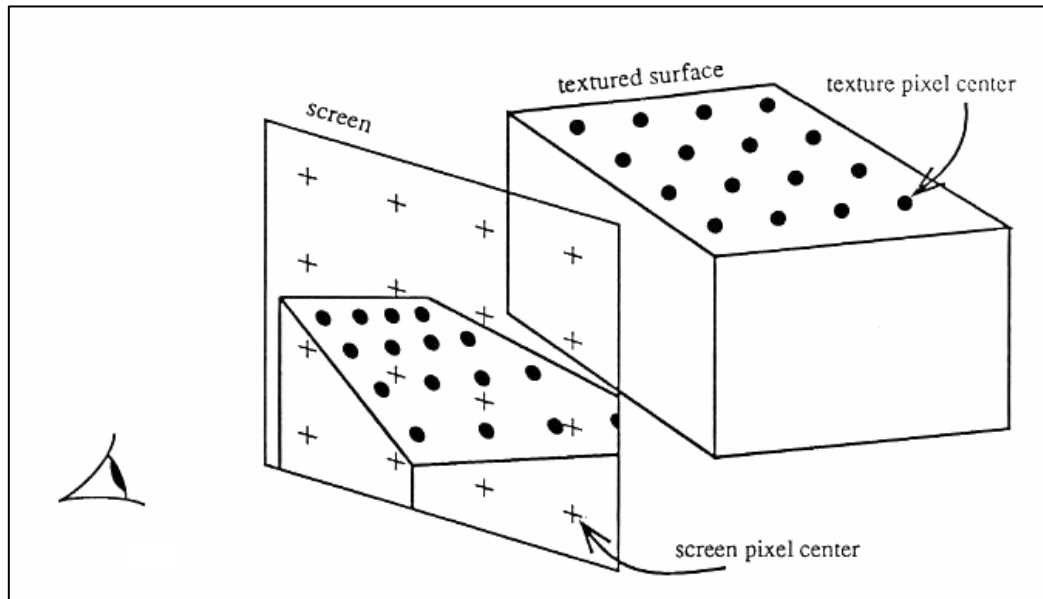
The texture is mapped onto a surface in 3-D object space, which is then mapped to the screen by the viewing projection. These two mappings are composed to find the overall 2-D texture space to 2-D image space mapping, and the intermediate 3-D space is often forgotten. This simplification suggests texture mapping's close ties with image warping and geometric distortion.

Texture space (u, v)

Object space (x_o, y_o, z_o)

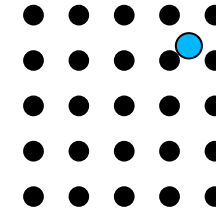
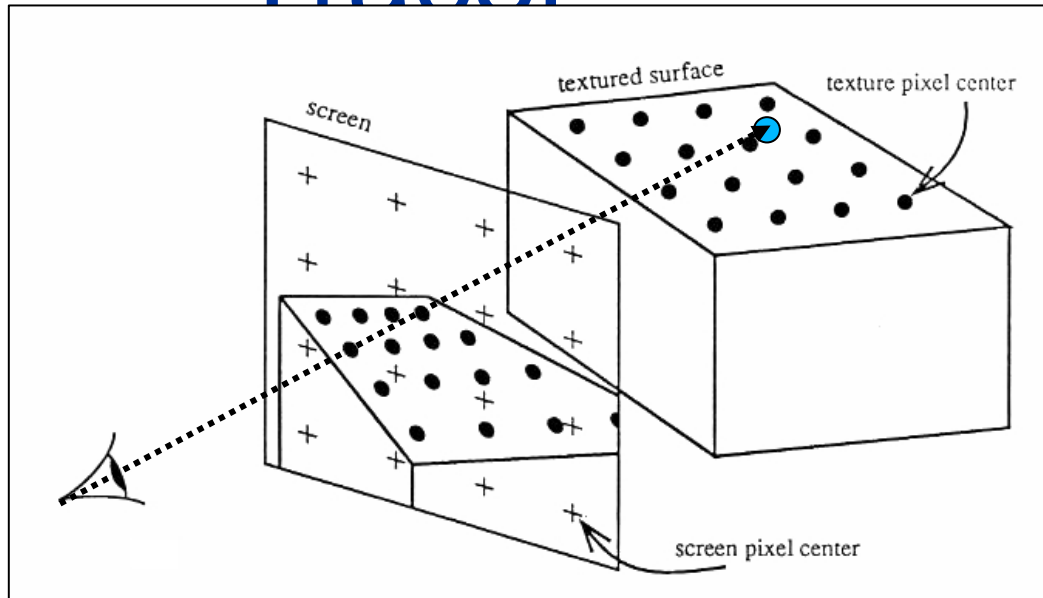
Screen space (x, y)

2D Texturing



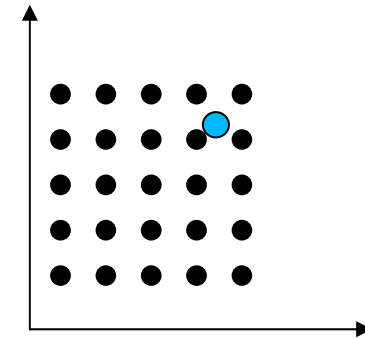
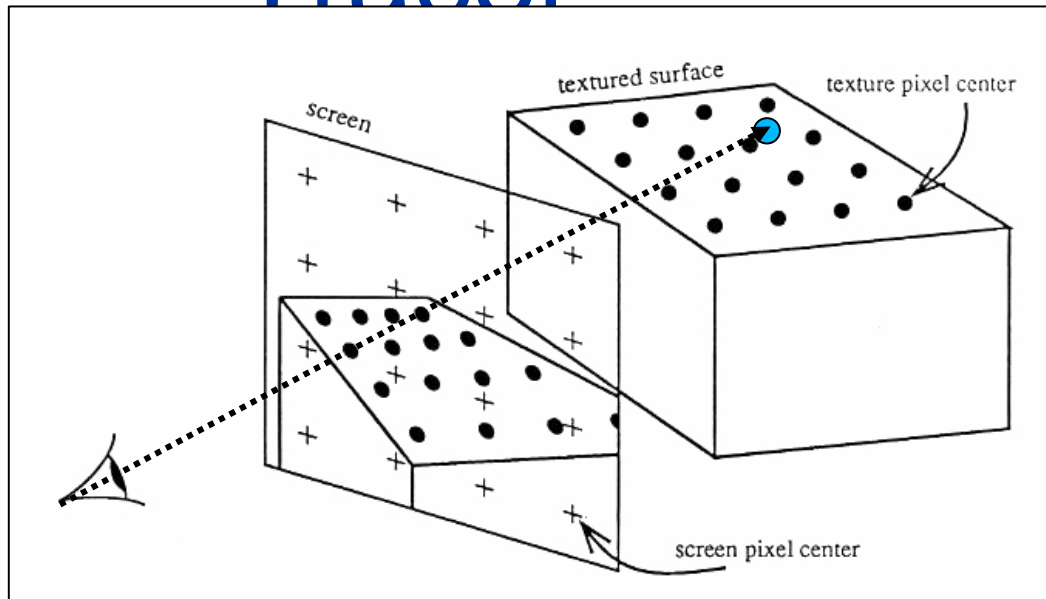
- 2D texture mapped onto object
- Object projected onto 2D screen
- 2D→2D: warping operation
- Uniform sampling ?
- Hole-filling/blending ?

Texture Mapping in a Ray Tracer



- **approximation:**
 - ray hits surface
 - surface location corresponds to coordinate inside a texture

Texture Mapping in a Ray Tracer



- **approximation:**
 - ray hits surface
 - surface location corresponds to coordinate inside a texture

Interpolation 1D



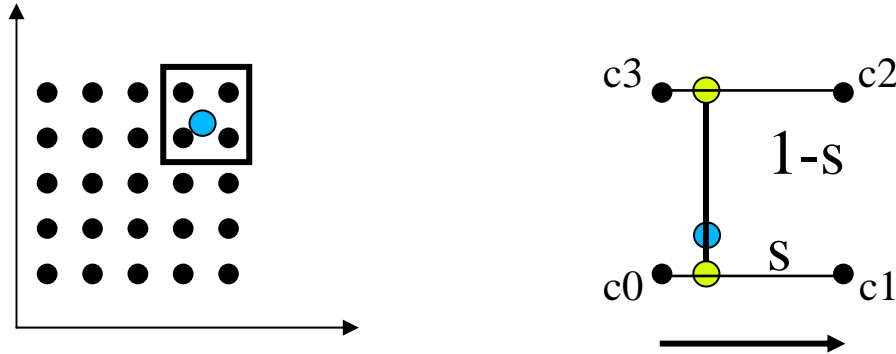
- **How to interpolate the color of the pixel?**

Interpolation 1D



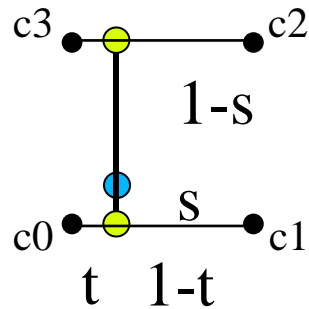
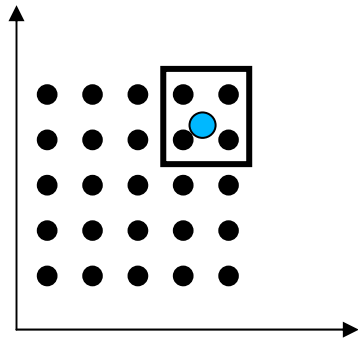
- **How to interpolate the color of the pixel?**

Interpolation 2D



- **How to interpolate the color of the pixel?**

Interpolation 2D



- How to interpolate the color of the pixel?
- 1D: $i0 = (1-t)c0 + tc1$
 $i1 = (1-t)c3 + tc2$
- 2D: $c = (1-s) i0 + s i1$