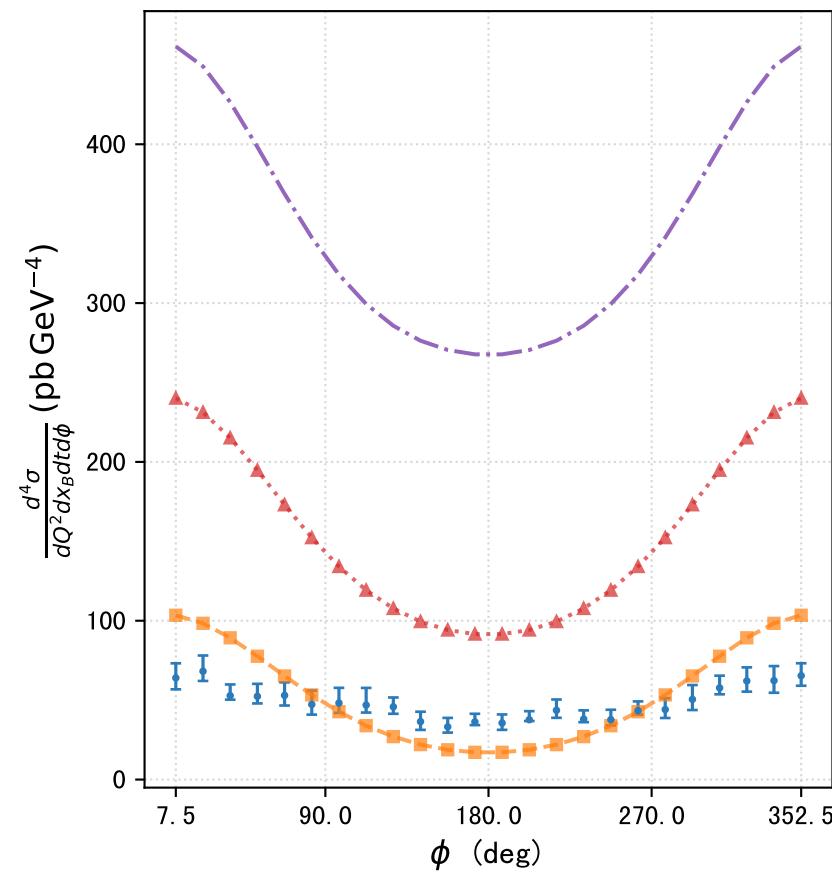
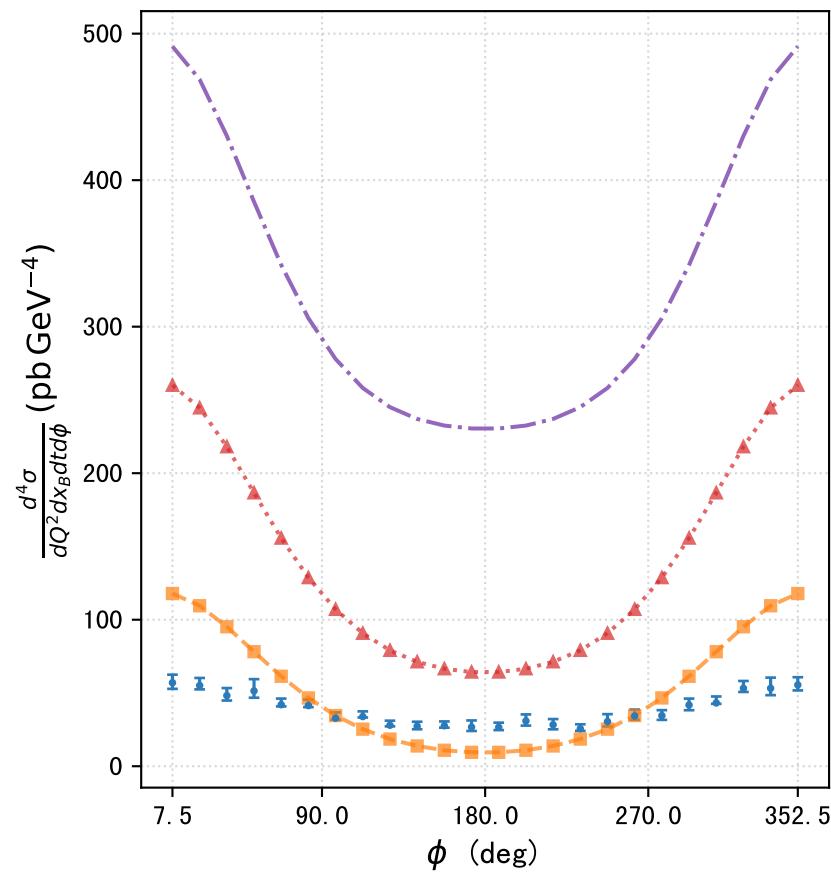


0p1 0p2 0p3 Experimental Data

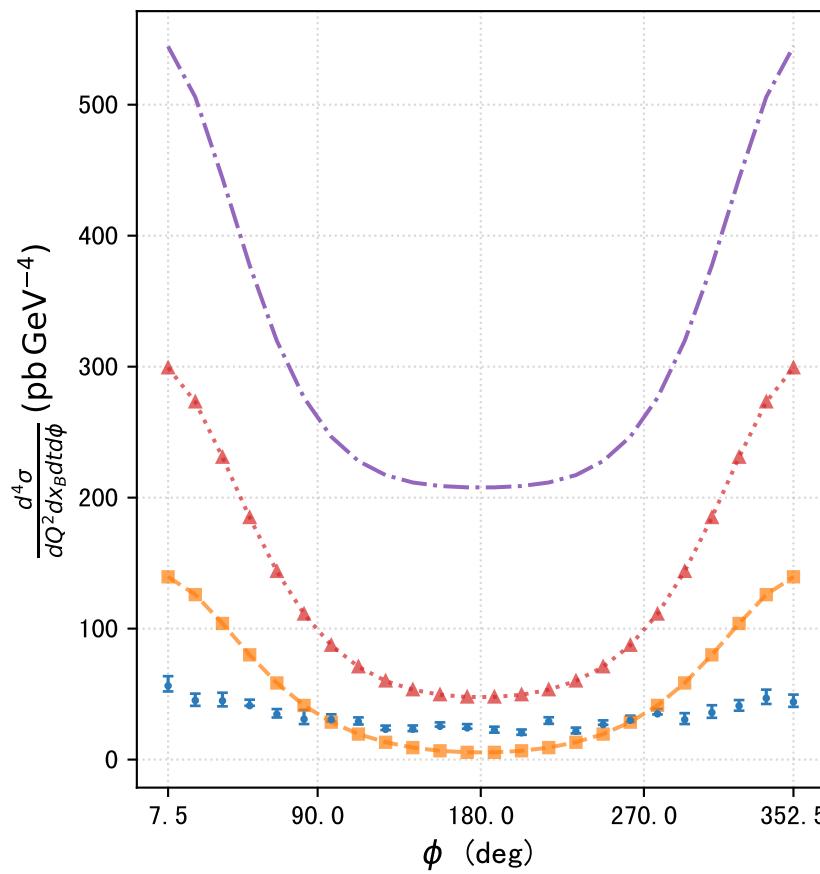
Kinematic Bin 1



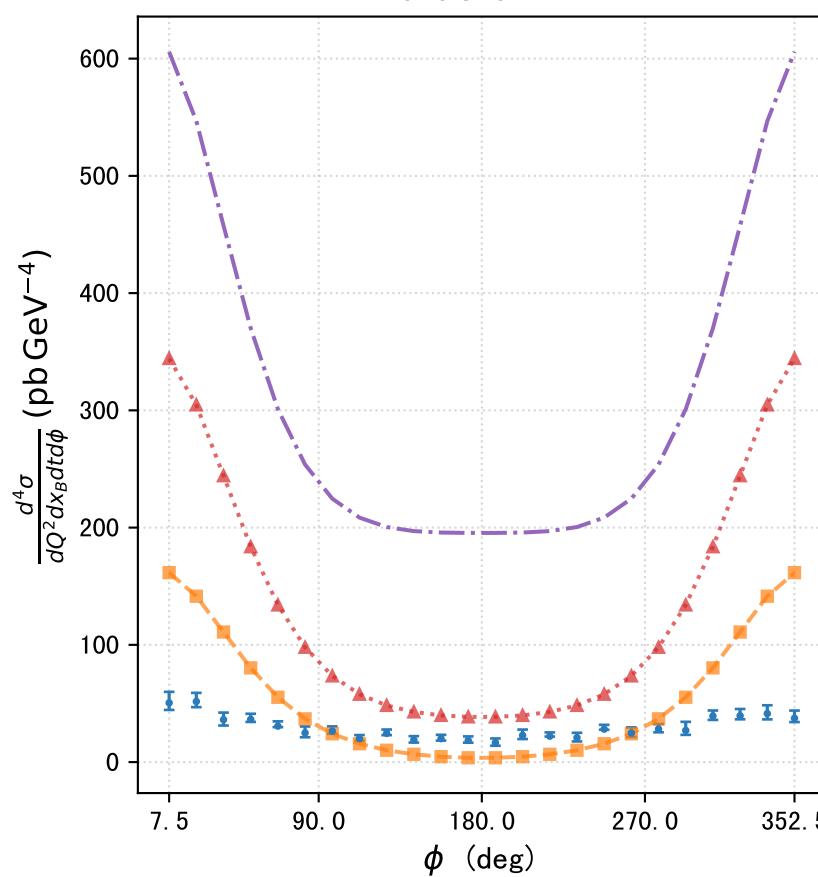
Kinematic Bin 2



Kinematic Bin 3



Kinematic Bin 4



Kinematic Bin 5

