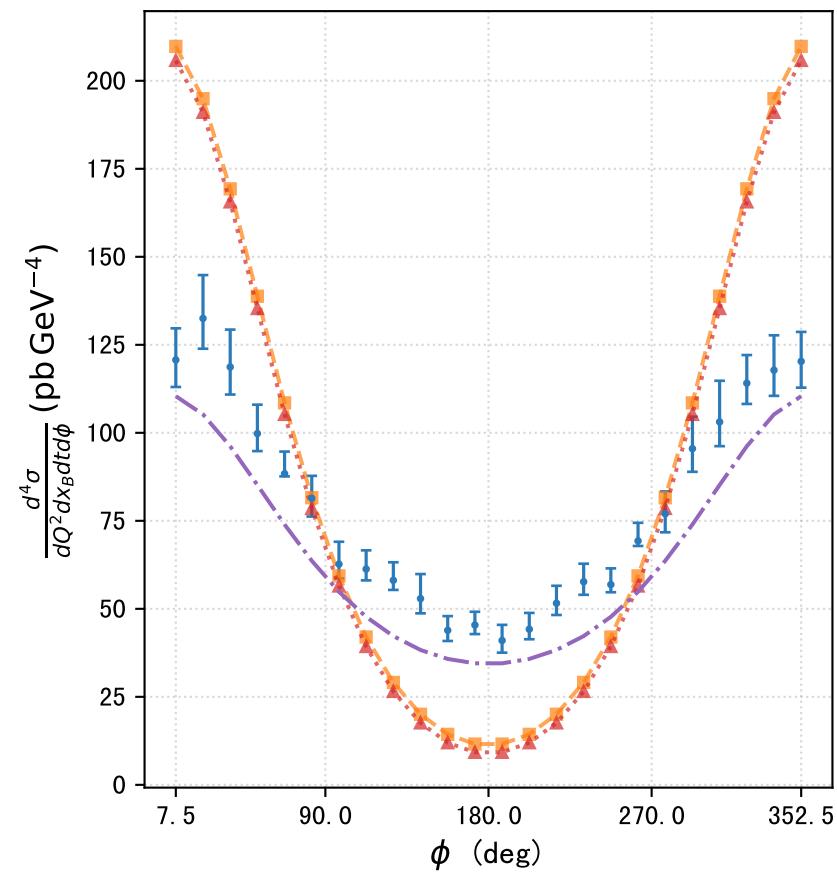
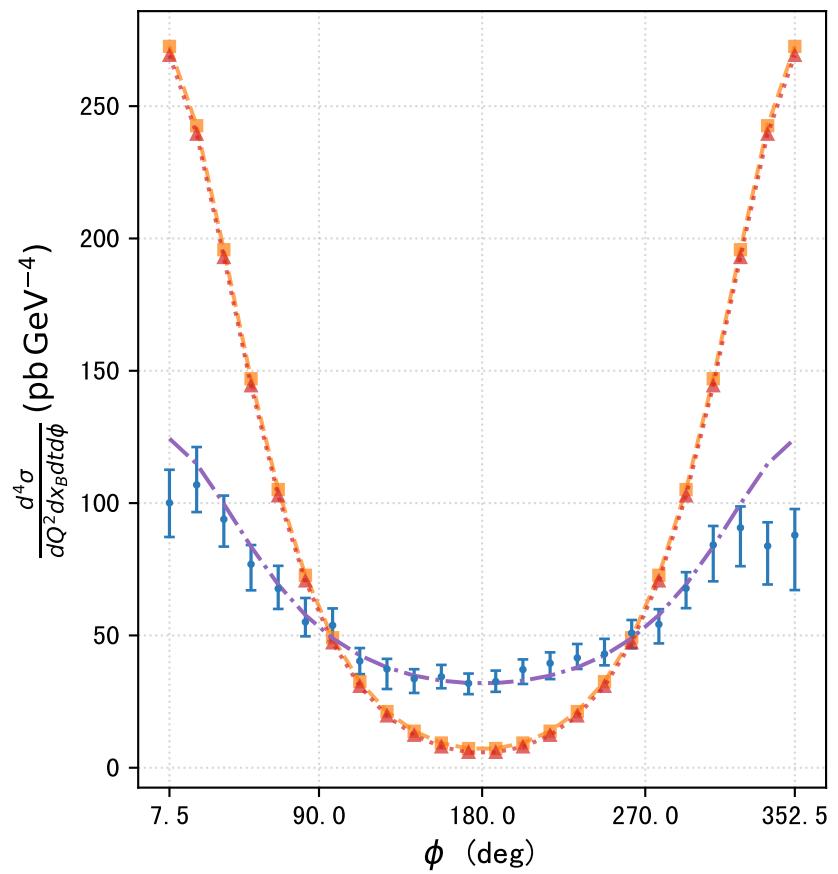


0p1    0p2    0p3    Experimental Data

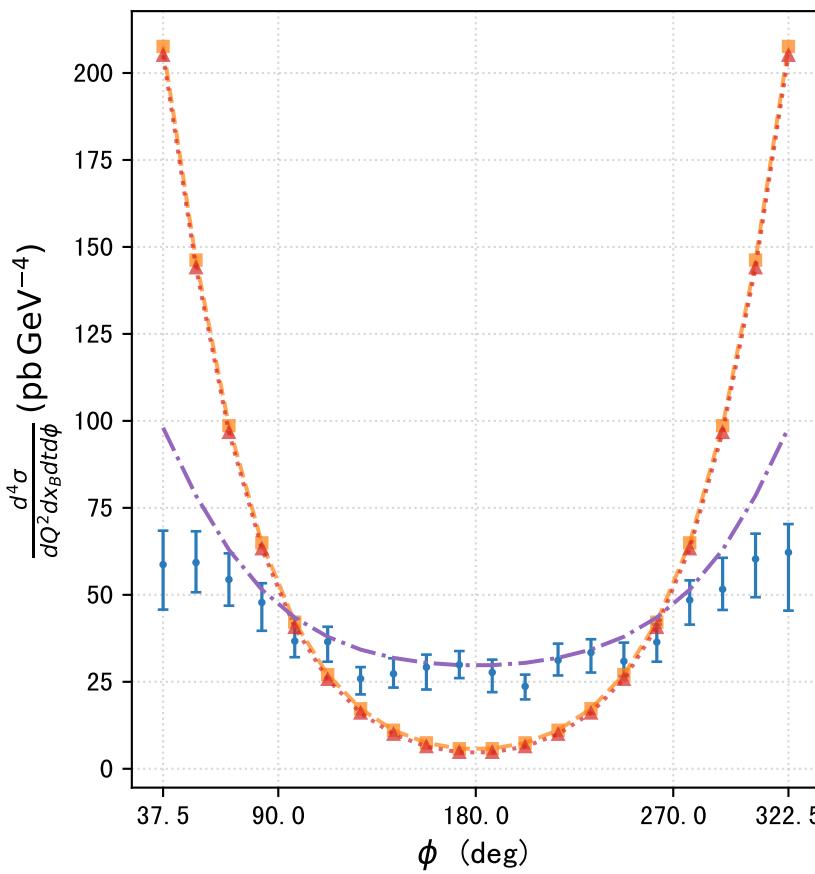
Kinematic Bin 1



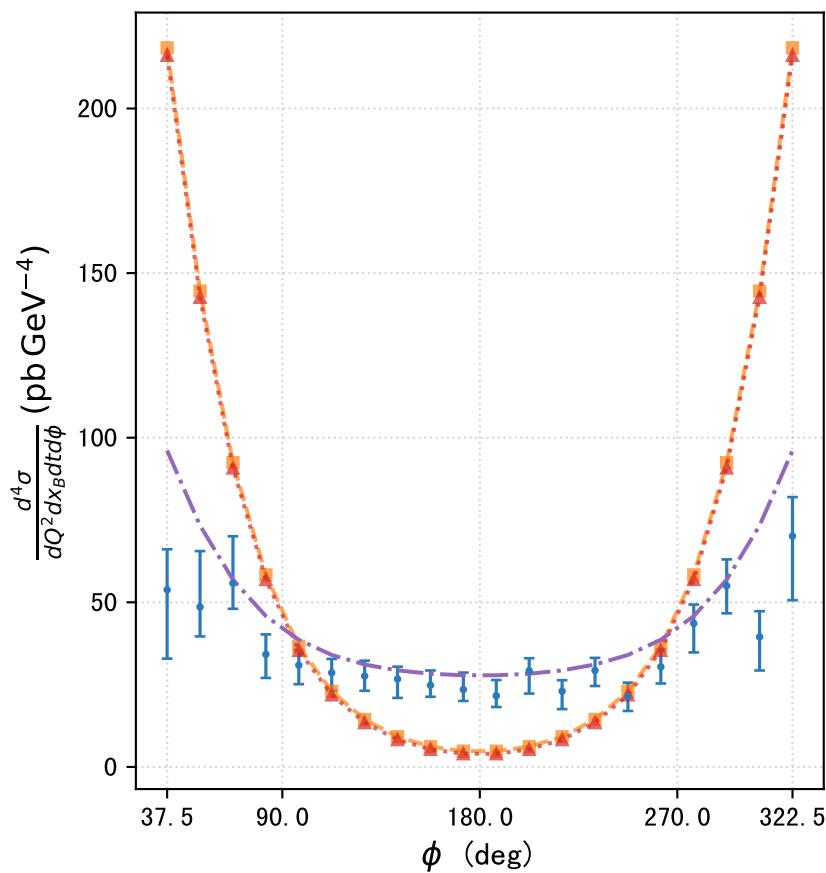
Kinematic Bin 2



Kinematic Bin 3



Kinematic Bin 4



Kinematic Bin 5

