



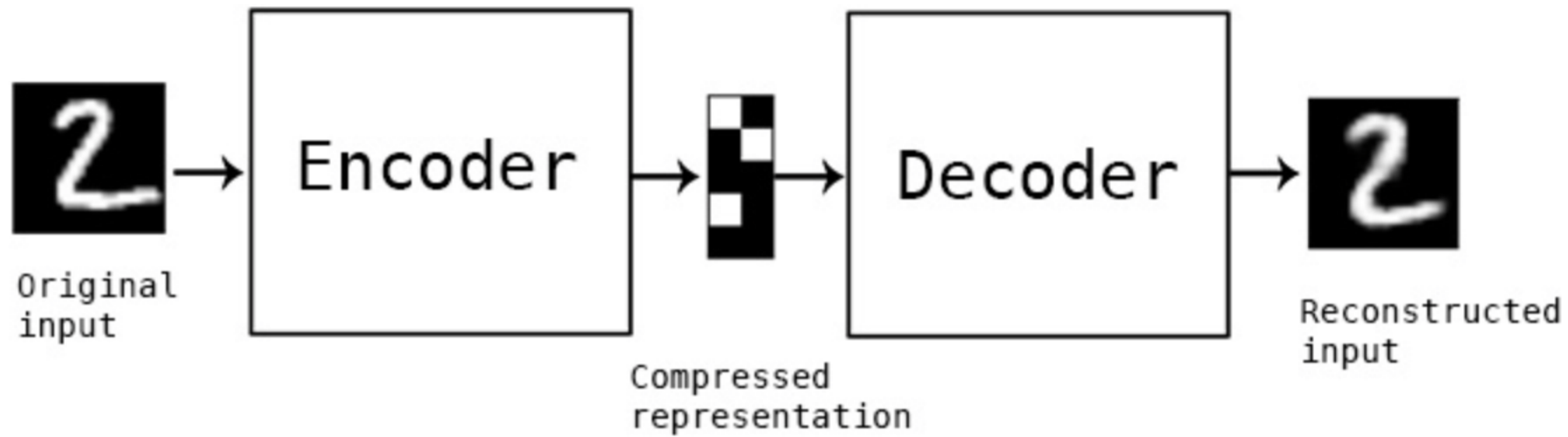
# Auto Encoder

# Variational Auto Encoder

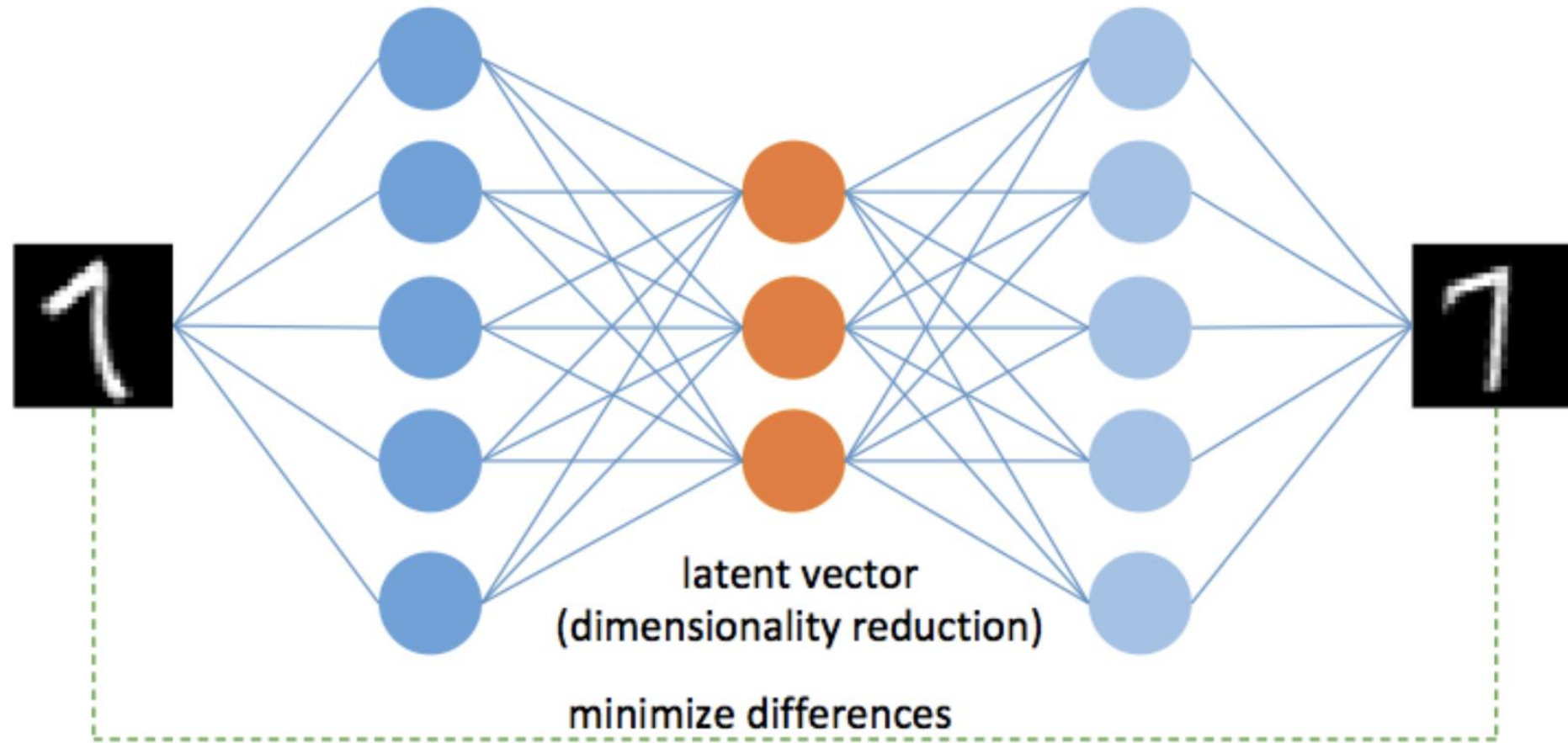
POSTECH A.I

Seungbeom Lee

# Autoencoder

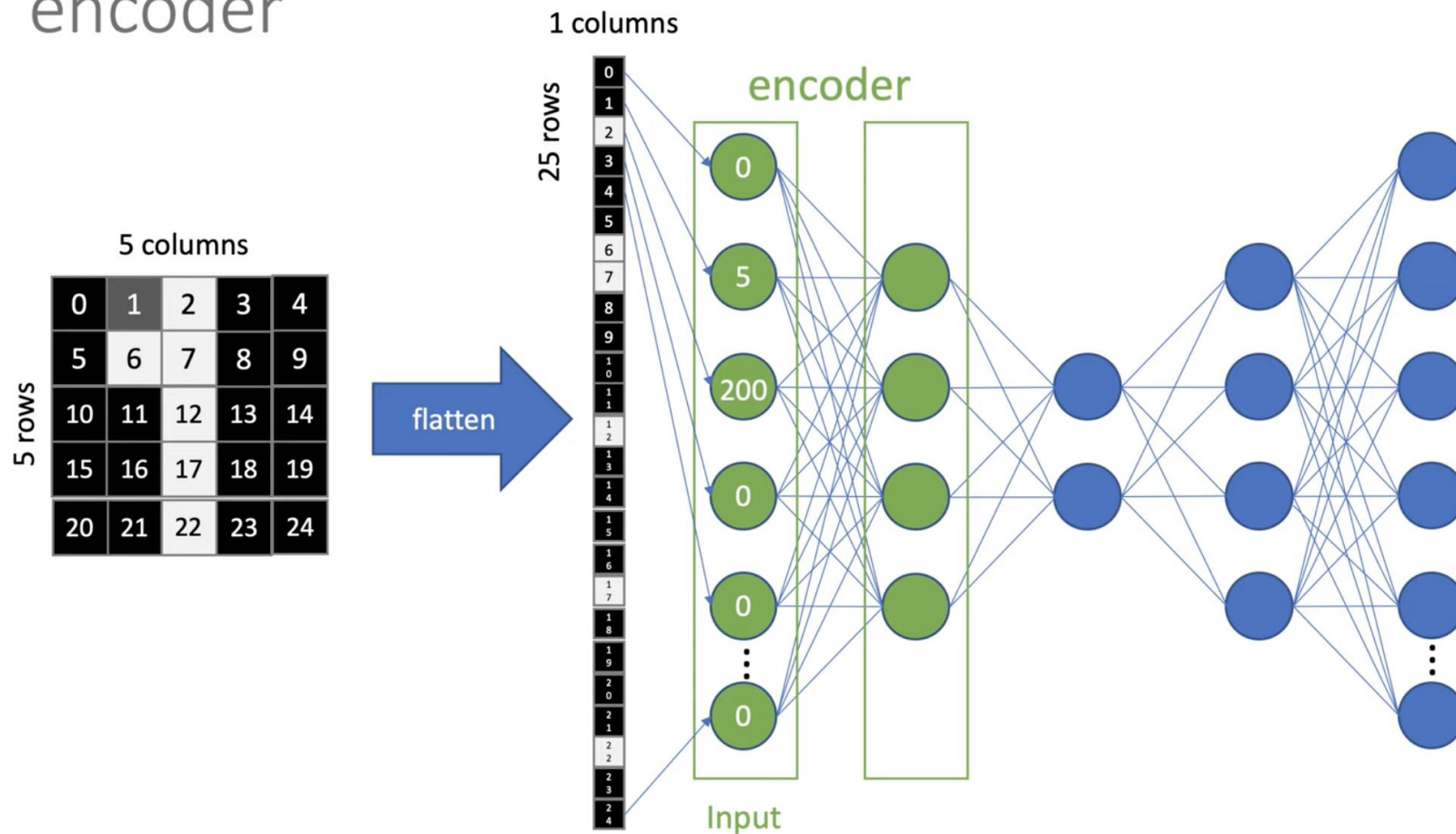


# Autoencoder

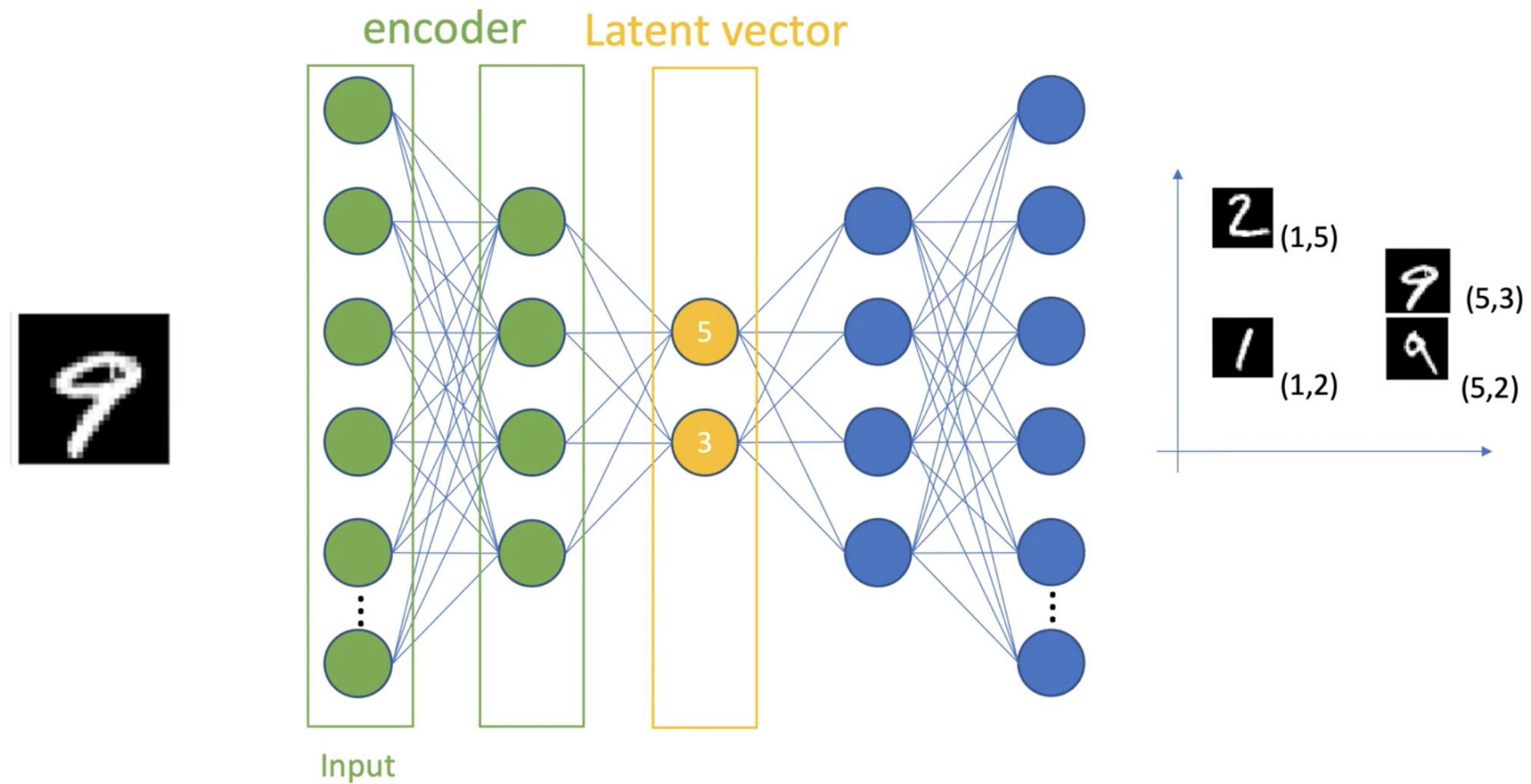


# Autoencoder

encoder

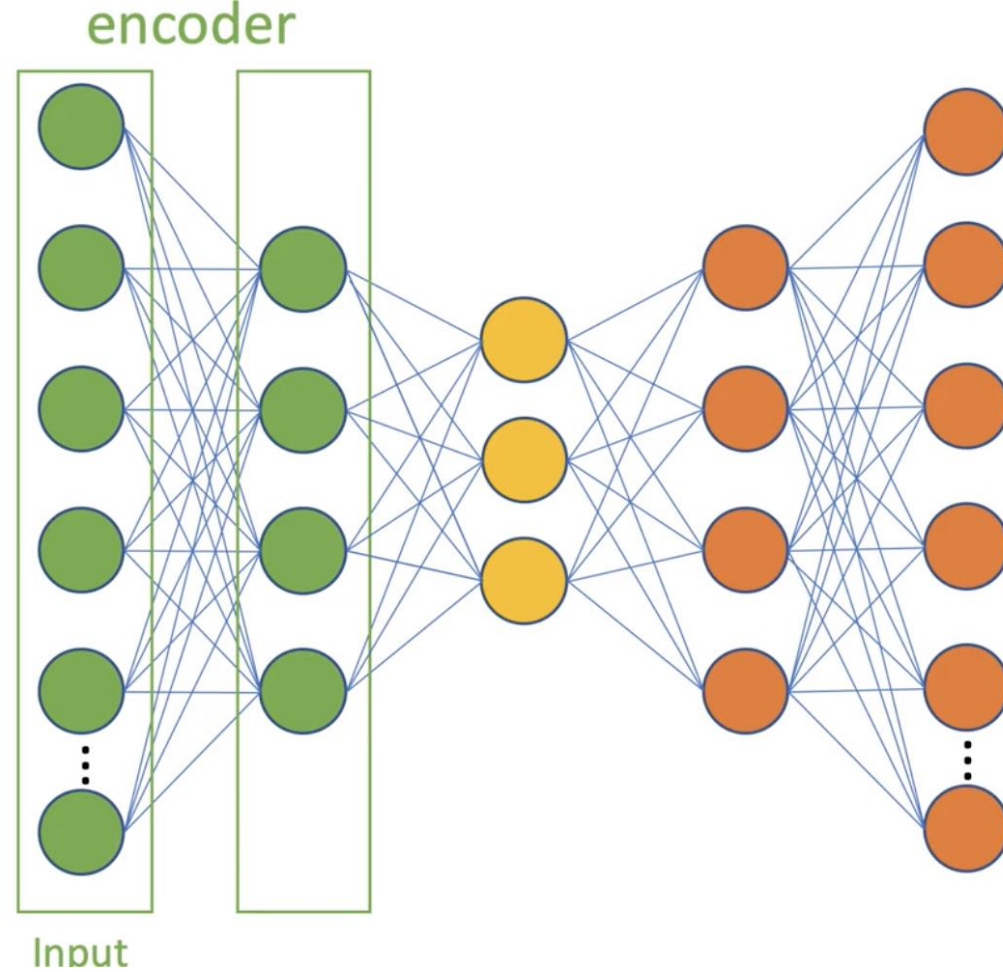


# Autoencoder

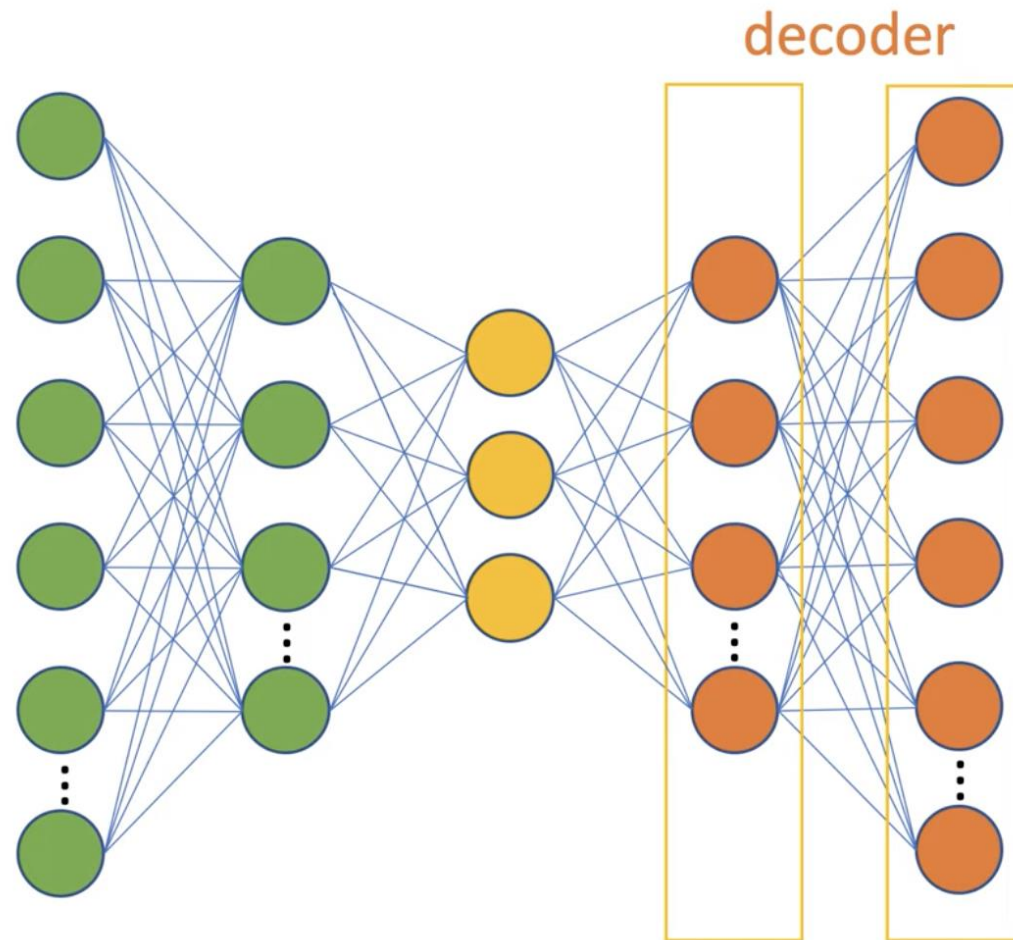


# Review the

Encoding  
dimension = 3



```
# MNIST input 28 rows * 28 columns = 784 pixels
input_img = Input(shape=(784,))
# encoder
encoder1 = Dense(128, activation='sigmoid')(input_img)
encoder2 = Dense(3, activation='sigmoid')(encoder1)
```



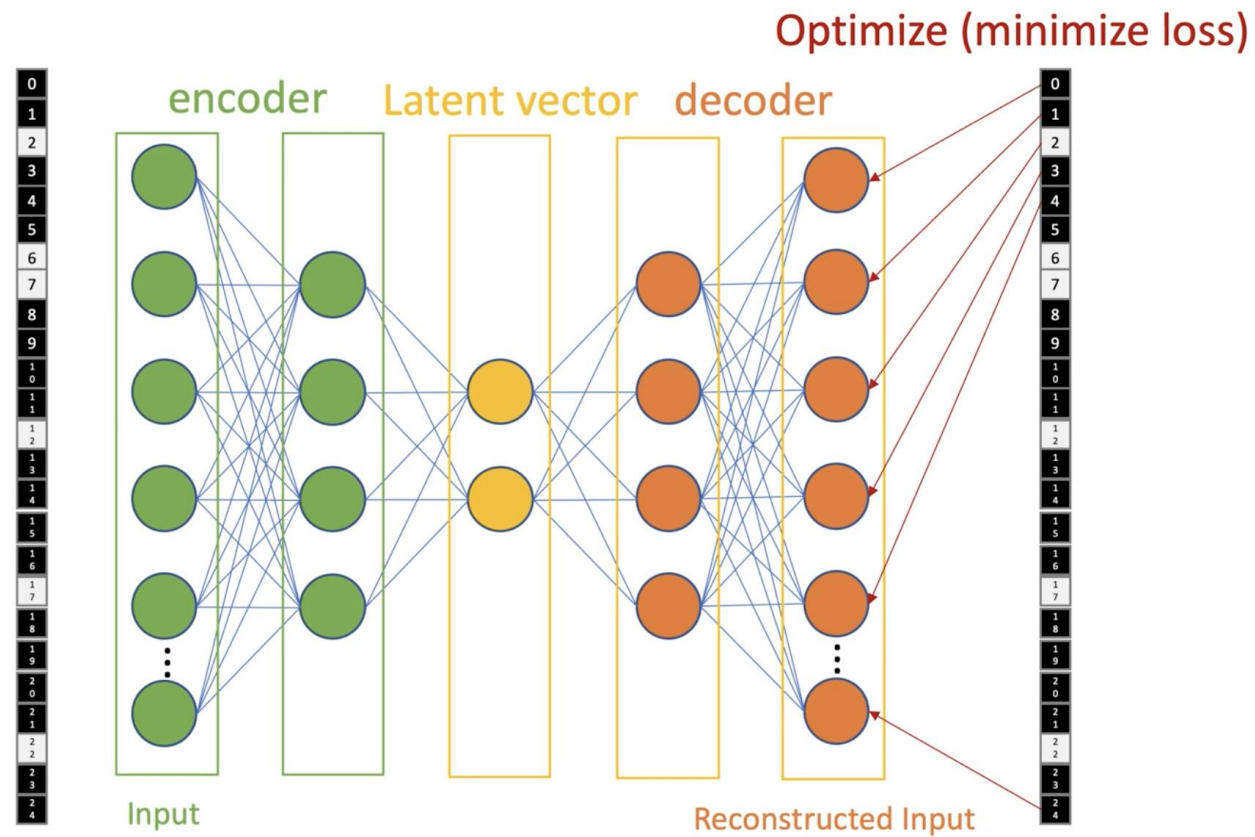
```
# decoder
```

```
decoder1 = Dense(128, activation='sigmoid')(encoder2)
```

```
decoder2 = Dense(784, activation='sigmoid')(decoder1)
```



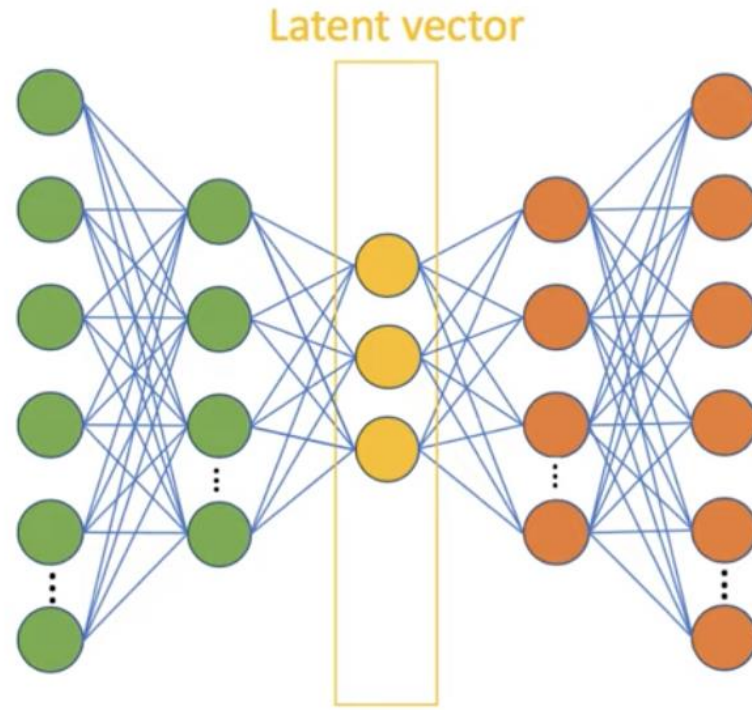
# decoder



```
autoencoder.compile(optimizer='adam', loss='binary_crossentropy')
```

```
autoencoder.fit(x_train, x_train,  
                epochs=5,  
                batch_size=32,  
                shuffle=True,  
                validation_data=(x_test, x_test))
```





```
# create encoder model
encoder = Model(inputs=input_img, outputs=encoder2)

# create decoder model
encoded_input = Input(shape=(3,))
decoder_layer1 = autoencoder.layers[-2]
decoder_layer2 = autoencoder.layers[-1]
decoder = Model(inputs=encoded_input, outputs=decoder_layer2(decoder_layer1(encoded_input)))
```

```
# get latent vector for visualization  
latent_vector = encoder.predict(x_test)
```

```
# get decoder output to visualize reconstructed image  
reconstructed_imgs = decoder.predict(latent_vector)
```

It just approximation f  
or the PCA



# Sequence to Sequence Autoencoder

만약 데이터가 연속적인 값이라면? 가능하다!

만약 LSTM encoder를 사용하여 입력 seq를 전체 seq 대한 정보가 들어있는 단일 벡터로 바꾸고 그 벡터를 n 번 반복. ( $n = \text{timestep}$ ) 그리고 이 일정한 seq를 target seq로 바꾸기 위해 LSTM decoder 실행

```
from keras.layers import Input, LSTM, RepeatVector
from keras.models import Model

inputs = Input(shape=(timesteps, input_dim))
encoded = LSTM(latent_dim)(inputs)

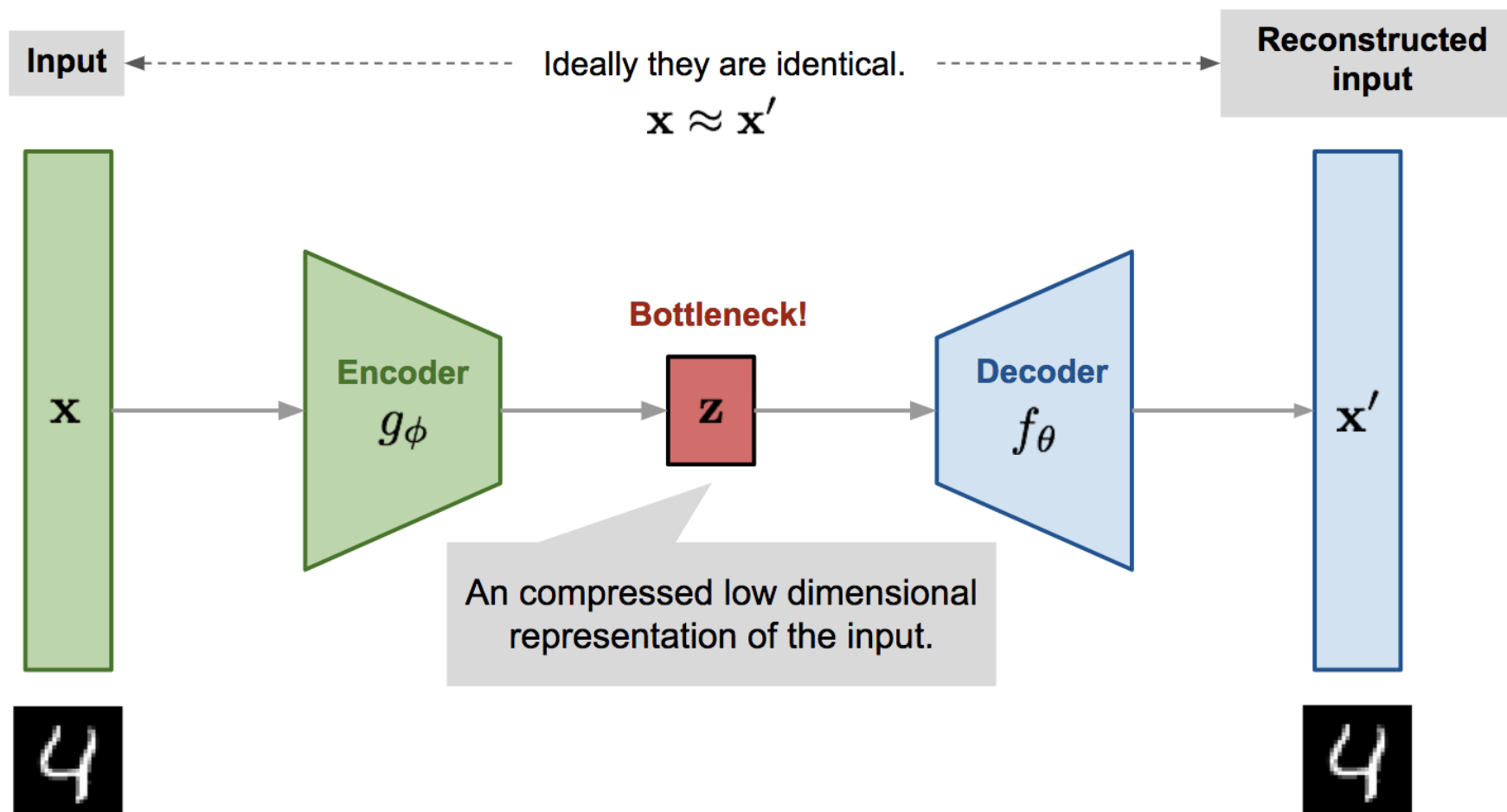
decoded = RepeatVector(timesteps)(encoded)
decoded = LSTM(input_dim, return_sequences=True)(decoded)

sequence_autoencoder = Model(inputs, decoded)
encoder = Model(inputs, encoded)
```

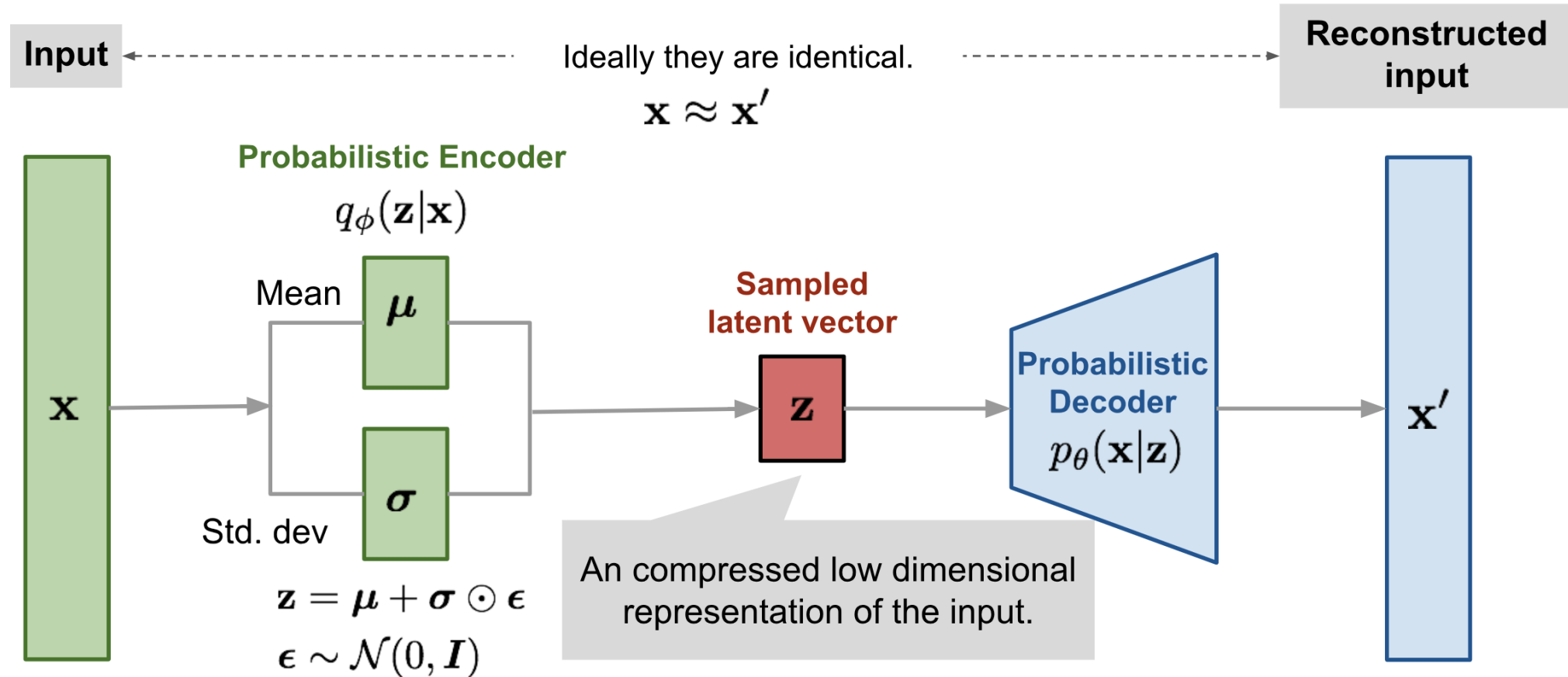
# Autoencoder

- Let's practice
  - Basic Autoencoder
  - Autoencoder with CNN
  - Image denoising

# Variational Auto Encoder



# Variational Auto Encoder





# Variational Autoencoders

Now equipped with our encoder and decoder networks, let's work out the (log) data likelihood:

$$\begin{aligned}\log p_{\theta}(x^{(i)}) &= \mathbf{E}_{z \sim q_{\phi}(z|x^{(i)})} [\log p_{\theta}(x^{(i)})] \quad (p_{\theta}(x^{(i)}) \text{ Does not depend on } z) \\ &= \mathbf{E}_z \left[ \log \frac{p_{\theta}(x^{(i)} | z) p_{\theta}(z)}{p_{\theta}(z | x^{(i)})} \right] \quad (\text{Bayes' Rule}) \\ &= \mathbf{E}_z \left[ \log \frac{p_{\theta}(x^{(i)} | z) p_{\theta}(z) q_{\phi}(z | x^{(i)})}{p_{\theta}(z | x^{(i)}) q_{\phi}(z | x^{(i)})} \right] \quad (\text{Multiply by constant}) \\ &= \mathbf{E}_z \left[ \log p_{\theta}(x^{(i)} | z) \right] - \mathbf{E}_z \left[ \log \frac{q_{\phi}(z | x^{(i)})}{p_{\theta}(z)} \right] + \mathbf{E}_z \left[ \log \frac{q_{\phi}(z | x^{(i)})}{p_{\theta}(z | x^{(i)})} \right] \quad (\text{Logarithms}) \\ &= \mathbf{E}_z \left[ \log p_{\theta}(x^{(i)} | z) \right] - D_{KL}(q_{\phi}(z | x^{(i)}) || p_{\theta}(z)) + D_{KL}(q_{\phi}(z | x^{(i)}) || p_{\theta}(z | x^{(i)}))\end{aligned}$$

We want to maximize the data likelihood

Decoder network gives  $p_{\theta}(x|z)$ , can compute estimate of this term through sampling. (Sampling differentiable through reparam. trick, see paper.)

This KL term (between Gaussians for encoder and  $z$  prior) has nice closed-form solution!

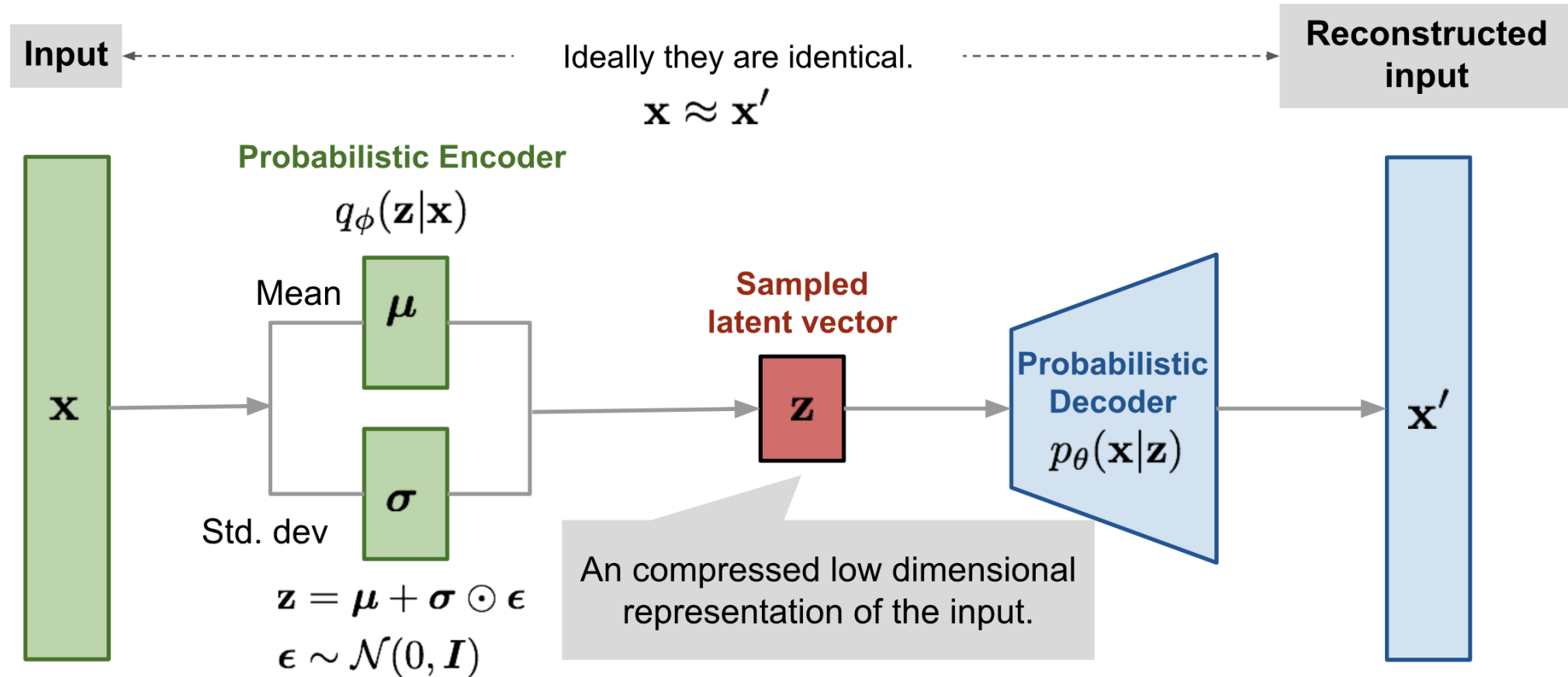
$p_{\theta}(z|x)$  intractable (saw earlier), can't compute this KL term :( But we know KL divergence always  $\geq 0$ .

# Variational Auto Encoder

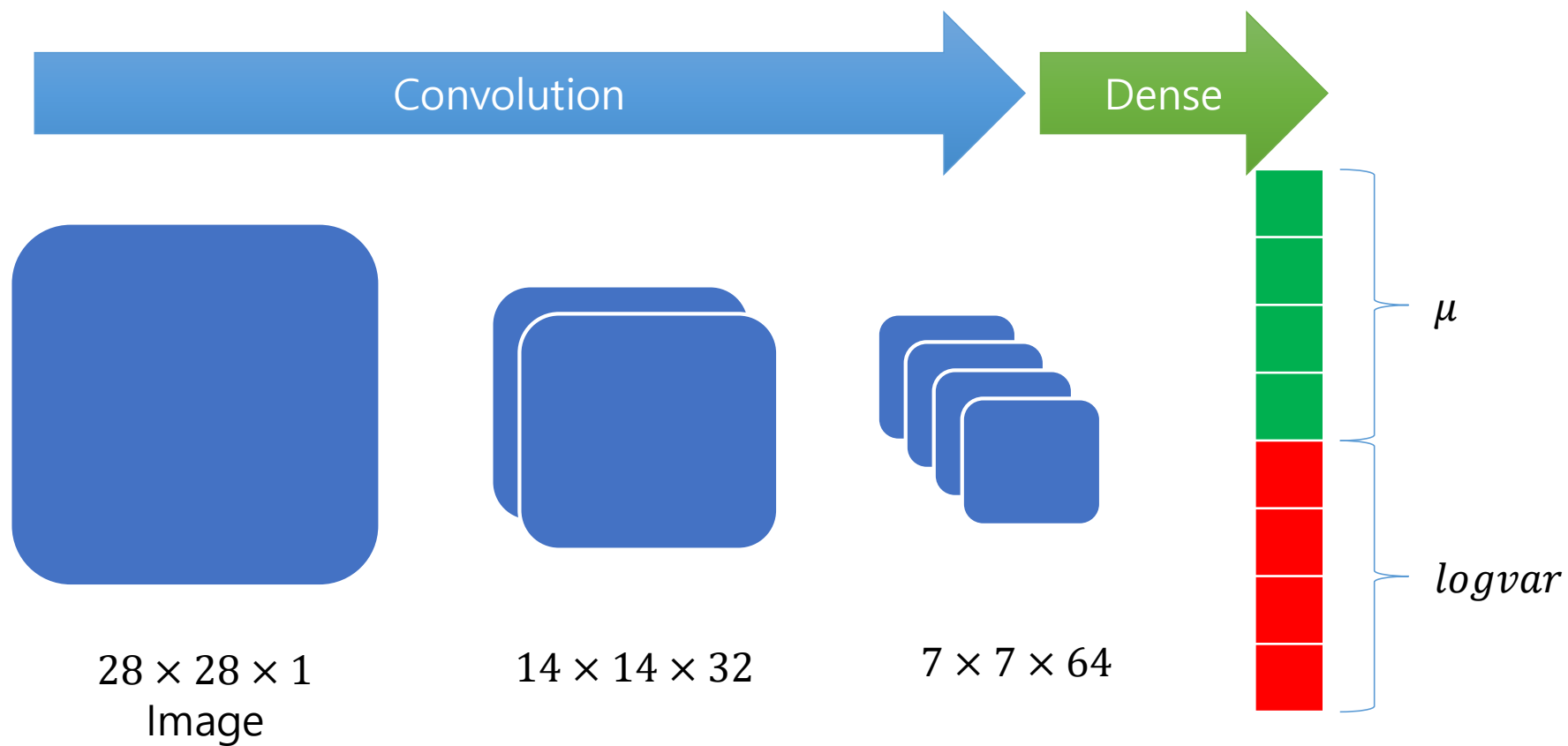
## Loss function (ELBO)

$$Loss = \frac{1}{L} \sum_{i=1}^L (\log(p_{\theta}(x|z^i))) + 0.5(\mu^2 + \sigma^2 - \log(\sigma^2) - 1)$$

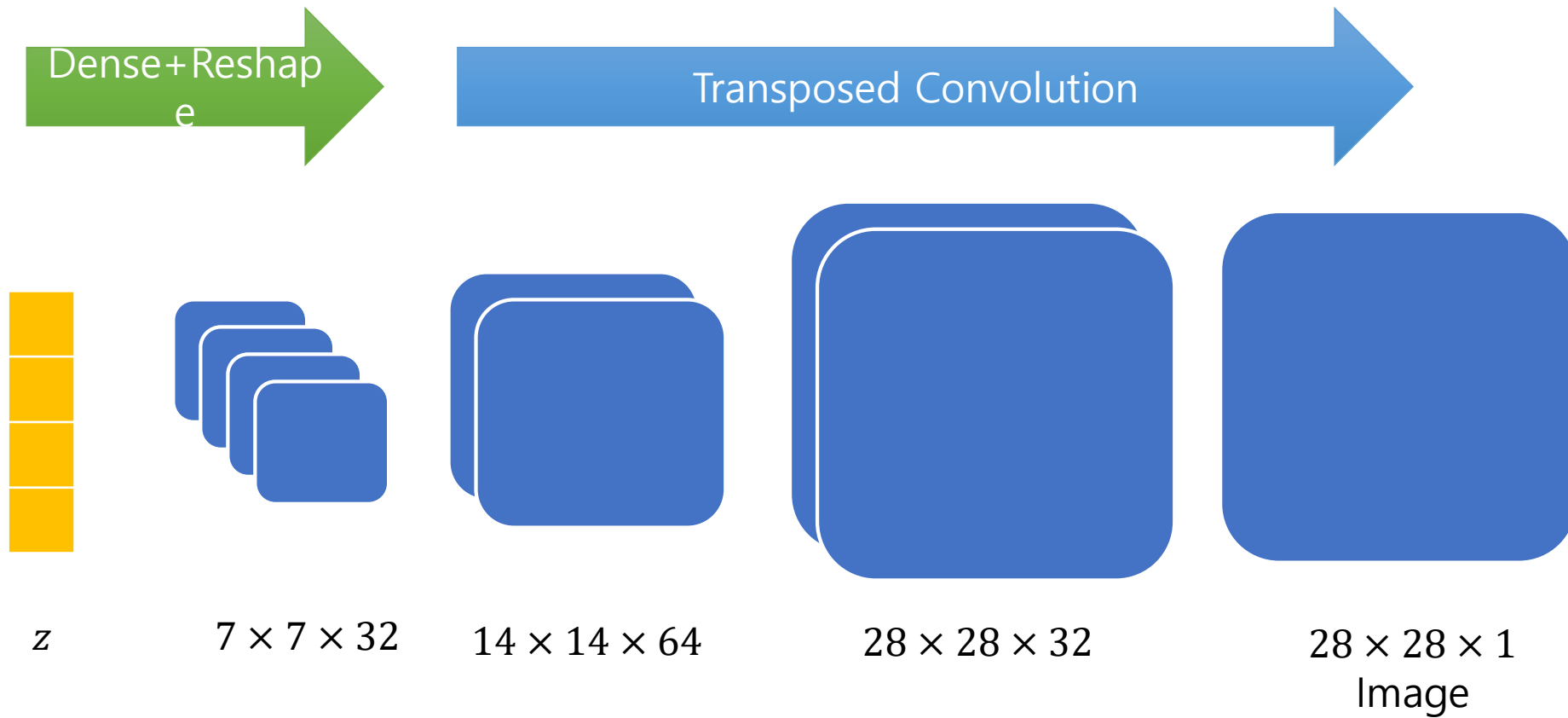
# Variational Auto Encoder



# Encoder structure



# Decoder structure



Thank You :)

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