

Game-Theoretic Approach to Planning and Synthesis

Linear-Time Temporal Logic ¹

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ERC Advanced Grant

WhiteMech:

White-box Self Programming Mechanisms



SAPIENZA
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¹Thanks to Alessandro Abate and Tom Melham (University of Oxford) for providing help with part of these slides.



- given a system (e.g., a physical device, a hardware circuit, or software code), a **model** represents an **abstraction** of it
- models are *contextual*
- many *levels of abstraction* are possible: many models of a system can be made
- abstraction/refinement (choice of right model) ought to be part of the *modelling effort*
- formal verification asserts properties of a *model*, not of the underlying *system*

Definition

A *transition system* is a tuple $\langle S, \rightarrow, I, \text{Prop}, L \rangle$ consisting of

- S set of *states*,
- $\rightarrow \subseteq S \times S$ *transition relation*,
- $I \subseteq S$ set of *initial states*,
- Prop set of *atomic propositions* (alphabet), and
- $L : S \rightarrow 2^{\text{Prop}}$ *labelling function*.

A TS is also known as *Kripke structure*.



Clarke, Grumberg, Peled - Model Checking. - MIT Press 1999

Definition

A *transition system* is a tuple $\langle S, Act, \rightarrow, I, Prop, L \rangle$ consisting of

- S set of *states*,
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- $\rightarrow \subseteq S \times Act \times S$ *transition relation*,
- $I \subseteq S$ set of *initial states*,
- $Prop$ set of *atomic propositions* (alphabet), and
- $L : S \rightarrow 2^{Prop}$ *labelling function*.

- different modelling choice
- *action enabled* TS are closely related to Moore machines
- we will use action enabled TS only when strictly needed



Baier, Katoen - Principles of Model Checking. - MIT Press 2008



- We also write $s \rightarrow s'$ instead of $(s, s') \in \rightarrow$.
- We consider exclusively transition relations such that each state has an outgoing transition, that is

$$\forall s \in S : \exists s' \in S : s \rightarrow s'$$

known as *non-blocking* condition, as absence of *terminal* states.

- In this course we consider *finite* TS, namely S has finite cardinality.



System description: A traffic light can be red, green, amber or black (not working). The traffic light might stop working at any time. After it has been repaired, it turns red. Initially, the light is red.



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how many different states do we need to model the traffic light?

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$$S = \{1, 2, 3, 4, 5\}$$

- 1 red
- 2 amber and red
- 3 green
- 4 amber
- 5 black

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what are the transitions?

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$$\rightarrow = \{(1, 2), (2, 3), (3, 4), (4, 1), (1, 5), (2, 5), (3, 5), (4, 5), (5, 1)\}$$

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what are the initial states?

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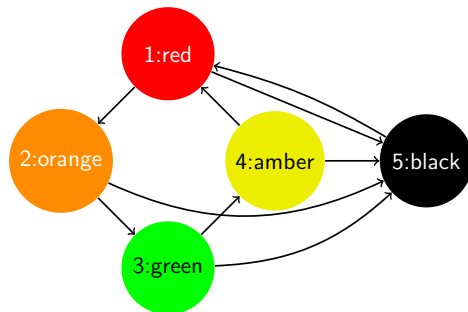
$$\begin{aligned} S &= \{1, 2, 3, 4, 5\} \\ \rightarrow &= \{(1, 2), (2, 3), (3, 4), (4, 1), (1, 5), (2, 5), (3, 5), (4, 5), (5, 1)\} \\ I &= \{1\} \\ \text{Prop} &= \{r, a, g, b\} \end{aligned}$$

how is the labelling function defined?

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Definition

Consider the transition system $\langle S, \rightarrow, I, \text{Prop}, L \rangle$

- A **finite path** is a finite state sequence $s_0 s_1 \dots s_n$ for some $n \geq 0$ such that $s_i \rightarrow s_{i+1}$ for all $0 \leq i < n$
- An **infinite path** is an infinite state sequence $s_0 s_1 \dots$ such that $s_i \rightarrow s_{i+1}$ for all $i \geq 0$
- A path is **initial** if $s_0 \in I$
- A **path** is an initial infinite path, contained in $\text{Paths}(TS)$
- A **trace** is the “output” of a path: $L(s_0)L(s_1)\dots$

- let $\pi = s_0 s_1 \dots$ be an infinite path (applies to finite paths too)
- for $j \geq 0$, the j th state of π , s_j is denoted by $\pi[j]$ (initial state is indexed by 0)
- for $j \geq 0$, the j th prefix of π , $s_0 s_1 \dots s_j$ is denoted by $\pi[..j]$

$$\overbrace{s_0 s_1 \dots s_{j-1} s_j}^{\pi[..j]} s_{j+1} \dots$$

- for $j \geq 0$, the j th suffix of π , $s_j s_{j+1} \dots$ is denoted by $\pi[j..]$

$$s_0 s_1 \dots s_{j-1} \overbrace{s_j s_{j+1} \dots}^{\pi[j..]}$$

- the set of infinite path π with $\pi[0] = s$ is denoted by $Paths(s)$

A standard language for talking about **infinite state sequences**.



Amir Pnueli - The Temporal Logic of Programs. - FOCS'77

\top truth constant

p primitive propositions

$\neg\phi$ classical negation

$\phi \vee \psi$ classical disjunction

$\phi \wedge \psi$ classical conjunction

A standard language for talking about **infinite state sequences**.



Amir Pnueli - The Temporal Logic of Programs. - FOCS'77

\top	truth constant	$\bigcirc\phi$	in the next state. . .
p	primitive propositions	$\Diamond\phi$	will eventually be the case
$\neg\phi$	classical negation	$\Box\phi$	is always the case
$\phi \vee \psi$	classical disjunction	$\phi U \psi$	ϕ until ψ
$\phi \wedge \psi$	classical conjunction	$\phi R \psi$	ϕ release ψ

A standard language for talking about **infinite state sequences**.



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$\phi \wedge \psi$	classical conjunction	$\phi \mathbf{R} \psi$	ϕ release ψ

Minimal syntax

$$\varphi := p \mid \neg\varphi \mid \varphi \wedge \varphi \mid \bigcirc\varphi \mid \varphi \mathbf{U} \varphi$$

you may encounter the following notations:

$X\varphi$: $\bigcirc\varphi$

$F\varphi$: $\diamond\varphi$

$G\varphi$: $\square\varphi$

past operators are possible (though not strictly necessary)

Eventually I will graduate

$\Diamond \text{degree}$

The plane will never crash

$\Box \neg \text{crash}$

I will eat pizza infinitely often

$\Box \Diamond \text{eatPizza}$

... and they all lived happily ever after

$\Diamond \Box \text{happy}$

We are not friends until you apologise

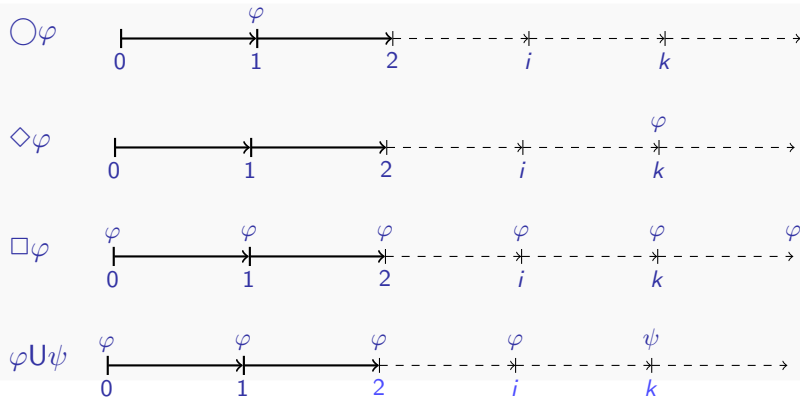
$(\neg \text{friends}) \text{U} \text{youApologise}$

Every time it is requested, a document will be printed

$\Box (\text{print_req} \rightarrow \Diamond \text{print})$

The two processes are never active at the same time

$\Box \neg (\text{proc}_1 \wedge \text{proc}_2)$



LTL formulas are evaluated on **infinite** traces, that is, obtained from an infinite path.

The language defined by an LTL formula φ is $\mathcal{L}(\varphi) = \{w \in \Sigma^\omega : w \models \varphi\}$.



how to express
“the light is infinitely often red”
by an LTL formula?



how to express
“the light is infinitely often red”
by an LTL formula?

$\square \lozenge \text{red}$

how to express
“the light is infinitely often red”
by an LTL formula?

$\square \diamond \text{red}$

how to express
“once green, the light cannot become immediately red”
by an LTL formula?

how to express
“the light is infinitely often red”
by an LTL formula?

$\Box \Diamond \text{red}$

how to express
“once green, the light cannot become immediately red”
by an LTL formula?

$\Box (\text{green} \rightarrow \neg \bigcirc \text{red})$

Question: How do you express in LTL

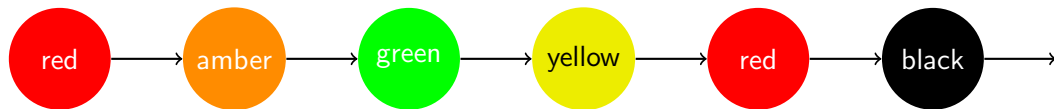
“once green, the light cannot become red immediately after”?

Question: How do you express in LTL

“once green, the light cannot become red immediately after”?

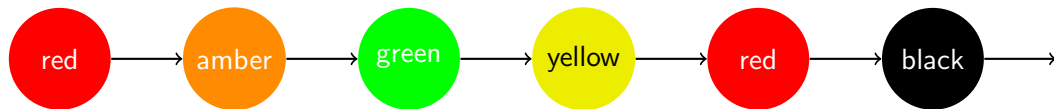
Answer: $\Box(\text{green} \rightarrow \neg \bigcirc \text{red})$.

back to the traffic light model, consider the following path:



question: $\pi \models \text{red}$?

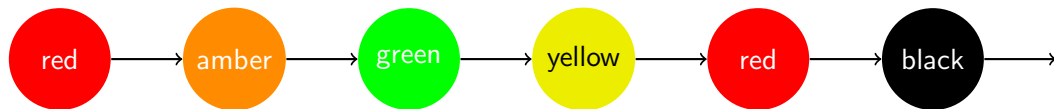
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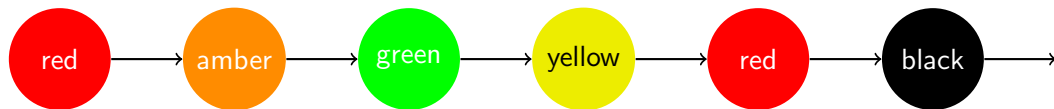
answer: yes

back to the traffic light model, consider the following path:



question: $\pi \models \bigcirc \bigcirc \text{red}$?

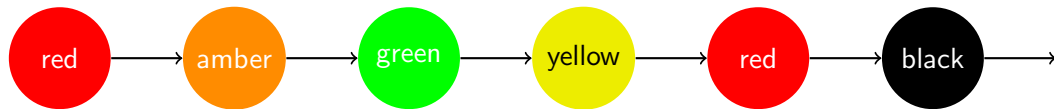
back to the traffic light model, consider the following path:



question: $\pi \models \bigcirc \bigcirc \text{red}$?

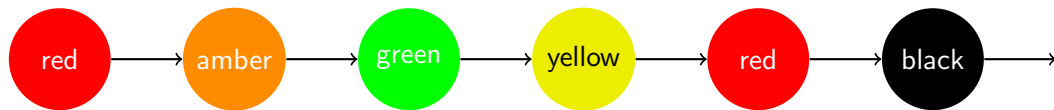
answer: no

back to the traffic light model, consider the following path:



question: $\pi \models \text{redUgreen?}$

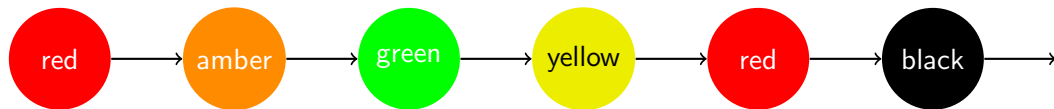
back to the traffic light model, consider the following path:



question: $\pi \models \text{red} \mathbf{U} \text{green}$?

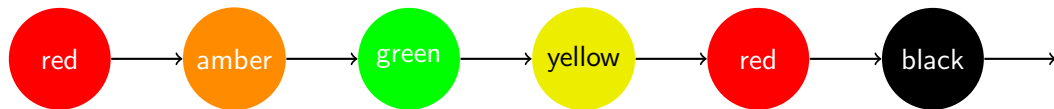
answer: yes, because $L(2) = \{\text{red}, \text{yellow}\}$

back to the traffic light model, consider the following path:



question: $\pi \models \diamond black$?

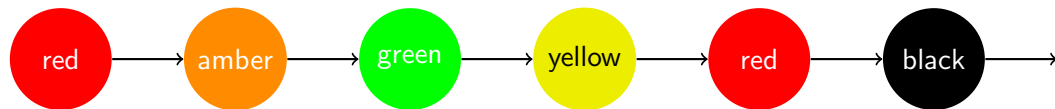
back to the traffic light model, consider the following path:



question: $\pi \models \Diamond black$?

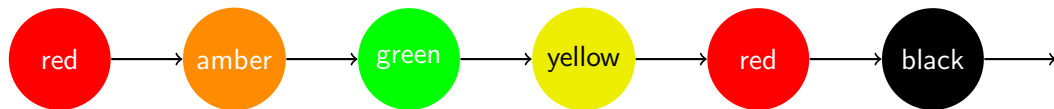
answer: yes

back to the traffic light model, consider the following path:



question: $\pi \models \square \neg \text{red}$?

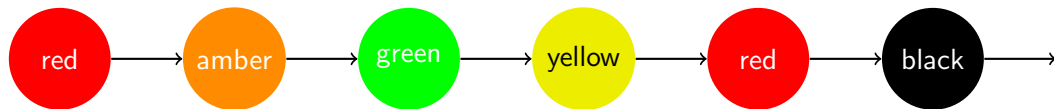
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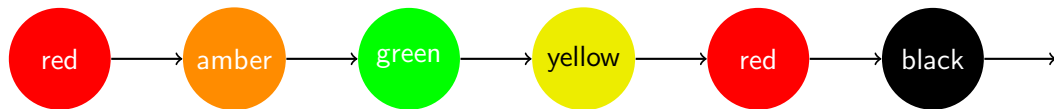
answer: no

back to the traffic light model, consider the following path:



question: $\pi \models (\Diamond \text{black})U(\bigcirc \text{red})$?

back to the traffic light model, consider the following path:



question: $\pi \models (\Diamond \text{black})U(\bigcirc \text{red})$?

answer: yes

Describe temporal modalities recursively

- $\varphi \mathbf{U} \psi \equiv \psi \vee (\varphi \wedge \bigcirc \varphi \mathbf{U} \psi)$

$\varphi \mathbf{U} \psi$ is a “solution” of $\Psi = \psi \vee (\varphi \wedge \bigcirc \Psi)$

- $\diamond \psi \equiv \psi \vee \bigcirc \diamond \psi$

$\diamond \psi$ is a solution of $\Psi = \psi \vee \bigcirc \Psi$

- also $\Box \psi \equiv \neg \diamond \neg \psi \equiv \psi \wedge \bigcirc \Box \psi$

$\Box \psi$ is a solution of $\Psi = \psi \wedge \bigcirc \Psi$



Define the **Release** operator **R** in a way that the following holds:

$$\varphi R \psi \equiv \neg(\neg\varphi U \neg\psi)$$

it also holds that

$$\varphi U \psi \equiv \neg(\neg\varphi R \neg\psi)$$

(Release is **dual** of Until)

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PNF

Positive Normal Form for LTL: for $a \in AP$

$$\varphi ::= \text{true} \mid \text{false} \mid a \mid \neg a \mid \varphi \wedge \varphi \mid \varphi \vee \varphi \mid \bigcirc \varphi \mid \varphi U \varphi \mid \varphi R \varphi$$

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Theorem

Each LTL formula φ admits an equivalent in PNF sometimes denoted $\text{pnf}(\varphi)$



question: what class of LTL formulas capture **invariants**?

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answer: $\Box\varphi$, where $\varphi ::= \text{true} \mid a \mid \varphi \wedge \varphi \mid \neg\varphi$

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answer: $\Box\varphi$, where $\varphi ::= \text{true} \mid a \mid \varphi \wedge \varphi \mid \neg\varphi$

example: $\Box\neg\text{red}$



question: how is the class of **safety properties** characterized?



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example: “every red light is immediately preceded by amber”

question: how can we express this property in LTL?

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example: “every red light is immediately preceded by amber”

question: how can we express this property in LTL?

answer: $\neg \text{red} \wedge \square(\bigcirc \text{red} \rightarrow \text{amber})$



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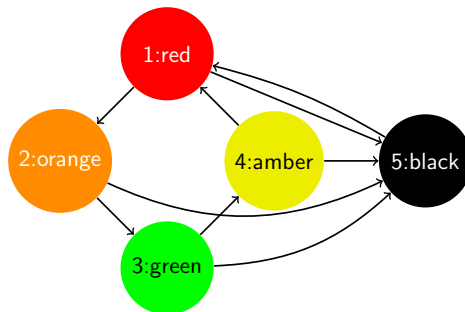
answer: “something good eventually happens”

example: “the light is infinitely often red”

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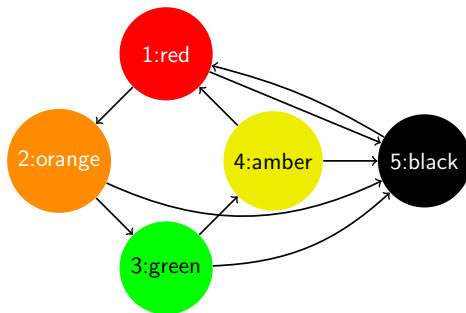
answer: $\Box\Diamond\text{red}$

consider traffic lights model



question: is $\psi := \Box(black \rightarrow \Diamond red)$ a liveness property?

consider traffic lights model



question: is $\psi := \Box(\text{black} \rightarrow \Diamond \text{red})$ a liveness property?

answer: yes

does it hold $TS \models \psi$?

unconditional fairness: “every transition is infinitely often taken”

$$\Box \Diamond \Psi$$

strong fairness: “if a transition is infinitely often enabled, then it is infinitely often taken”

$$\Box \Diamond \Phi \rightarrow \Box \Diamond \Psi$$

weak fairness: “if a transition is continuously enabled from a certain point in time, then it is infinitely often taken”

$$\Diamond \Box \Phi \rightarrow \Box \Diamond \Psi$$

consider LTL constraint *fair*;

$$\text{FairPaths}(s) = \{\pi \in \text{Paths}(s) \mid \pi \models \text{fair}\}$$

$$\text{FairPaths}(TS) = \{\pi \in \text{Paths}(TS) \mid \pi \models \text{fair}\}$$

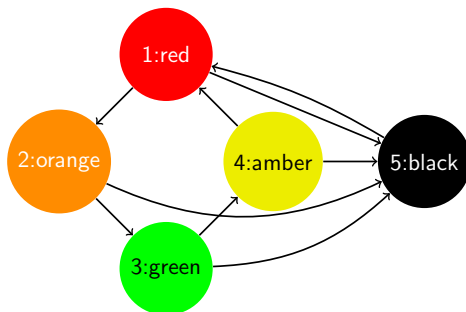
consider LTL specification φ ;

$$s \models_{\text{fair}} \varphi \text{ iff } \pi \models \varphi, \forall \pi \in \text{FairPaths}(s)$$

$$TS \models_{\text{fair}} \varphi \text{ iff } \pi \models \varphi, \forall \pi \in \text{FairPaths}(TS)$$

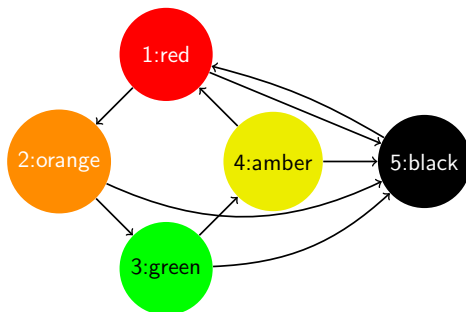
fairness constraints are easily embedded with LTL verification:

$$TS \models_{\text{fair}} \varphi \Leftrightarrow TS \models (\text{fair} \rightarrow \varphi)$$



question: “is the traffic light infinitely often orange (amber and red)” under the strong fairness condition (if a transition is infinitely often enabled then it is infinitely often taken)?

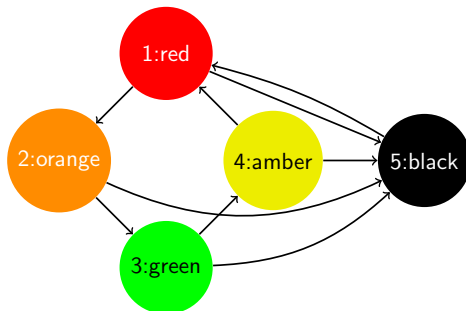
express this in LTL:



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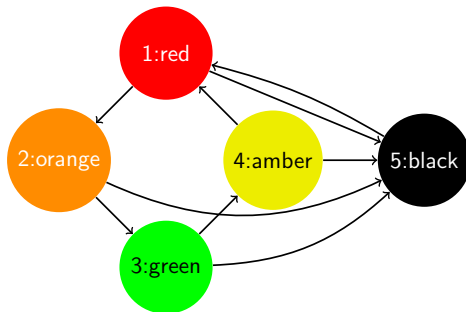


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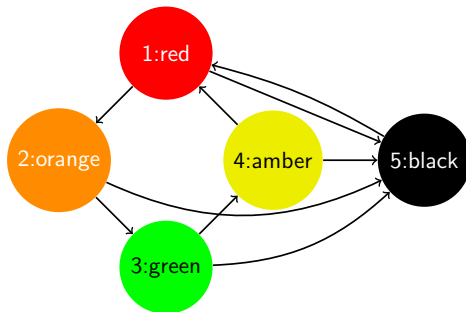
express this in LTL:

$$(\Box\Diamond\text{red}) \rightarrow \Box\Diamond(\text{red} \wedge \bigcirc(\text{red} \wedge \text{amber}))$$



question: “is the traffic light infinitely often orange” under the weak fairness condition (if a transition is continuously enabled from a certain point in time then it is infinitely often taken)?

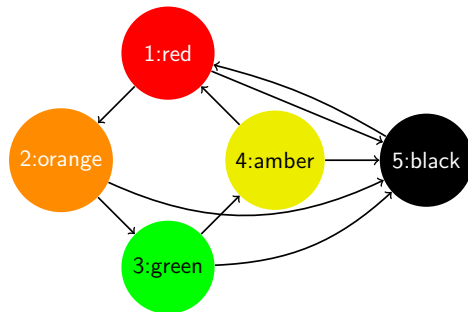
express this in LTL:



question: “is the traffic light infinitely often orange” under the weak fairness condition (if a transition is continuously enabled from a certain point in time then it is infinitely often taken)?

answer: yes

express this in LTL:



question: “is the traffic light infinitely often orange” under the weak fairness condition (if a transition is continuously enabled from a certain point in time then it is infinitely often taken)?

answer: yes

express this in LTL:

$$(\Diamond \Box \text{red}) \rightarrow \Box \Diamond (\text{red} \wedge \bigcirc (\text{red} \vee \text{amber}))$$

(semantics of negation)

argue why $(TS \not\models \varphi) \not\equiv (TS \models \neg\varphi)$

(semantics of negation)

argue why $(TS \not\models \varphi) \not\equiv (TS \models \neg\varphi)$

and why instead $TS \models \neg\varphi \rightarrow TS \not\models \varphi$



Model Checking

Verifying that a system *satisfies* a given (temporal) specification.

Synthesis

Producing a system that *satisfies* a given (temporal) specification by construction.

Industry-strength approach to **automated verification**.

Idea: view the state transition graph of a program P as a model M_P , and express correctness criteria as logic formula ϕ

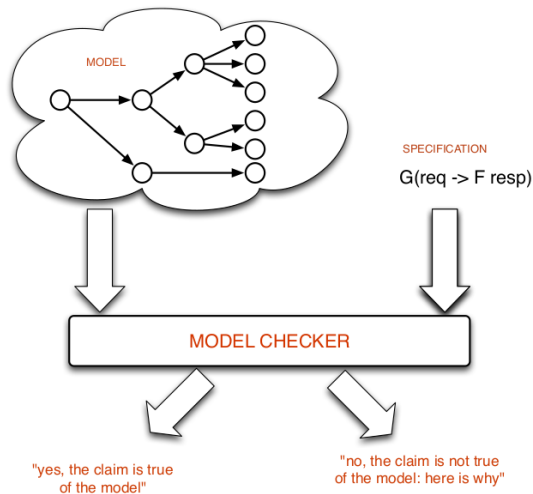
Verification then *reduces* to a model checking problem: $M_P \models \phi$

Most widely used **logical specification** languages: LTL and CTL ;



Clarke and Emerson - Design and Synthesis of Synchronization Skeletons
Using Branching-Time Temporal Logic. - LP'81

Can be (reasonably) efficiently automated, leading to many tools (SPIN, SMV, PRISM, MOCHA, MCMAS, EVE, ...).



Agents are powerful models in many areas of Computer Science.

Three characteristics

- **Capabilities**: actions and constraints
- **Knowledge**: information about environment
- **Goal**: specification of a task/objective to fulfill



Appears in many areas

Robotics

Software Engineering

Process Management

Knowledge Representation

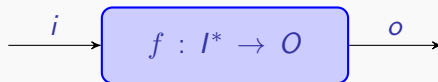
Planning

Multi-Agent Systems

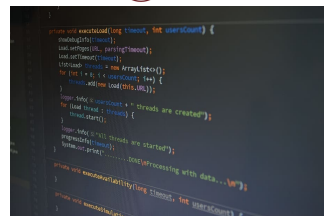
Sequential decision making

Reinforcement learning

Process



Function f sends **outputs** according to the history of **inputs**.



 Abadi, Lamport, Wolper - Realizable and Unrealizable Specifications of Reactive Systems. - ICALP'89

- **Adhere** to capabilities: actions always fulfill constraints
- **Depend** on knowledge: react on the stream of inputs
- **Fulfill** the specification

An agent satisfying these properties is **correct**.

Temporal specification setting

$$f \rightsquigarrow \mathcal{T}_f = \langle Q, I, O, \delta, \tau \rangle$$

Finite-state machines are expressive enough to **implement** agents correctly in a large class of **temporal specifications**.

Instead of writing programs, we write **specifications** and run an **automatic synthesis** procedure that in turns **produces** the program.

Reactive Synthesis

- **Self-programming** mechanism.
- **Specifying** a problem is usually simpler than **solving** it.
- Aim: **correct-by-construction**.



 Pnueli and Rosner - On the Synthesis of a Reactive Module. - POPL'89

 Finkbeiner - Synthesis of Reactive Systems. - DSSE'16

Synthesis problems as games

Agent vs environment	\Leftrightarrow	Two-Player Game
Temporal specification	\Leftrightarrow	Winning Condition
Correct program	\Leftrightarrow	Winning Strategy

Solving synthesis = winning a game

Synthesizing a **correct** program reduces to winning a suitably defined formal game.

Solution techniques: Logic, Games, and Automata.

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Stay tuned!