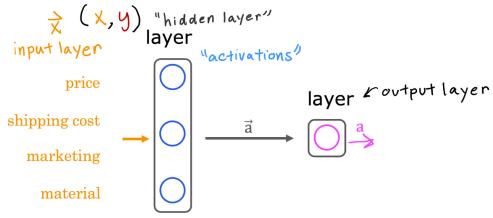
1. 1 point



Which of these are terms used to refer to components of an artificial neural network? (hint: three of these are correct)

- neurons
- layers
- axon
- activation function

 $\textbf{2.} \quad \text{True/False? Neural networks take inspiration from, but do not very accurately mimic, how neurons in a biological brain learn.}$



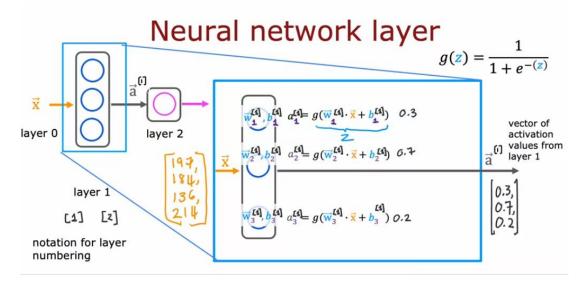
- True
- False

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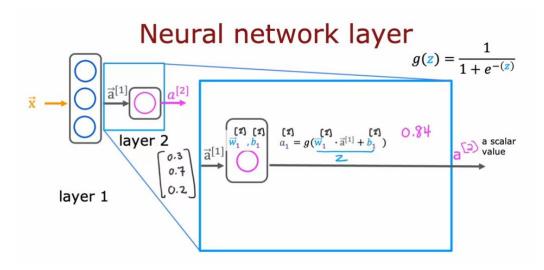
Windows'u Etkinleştir

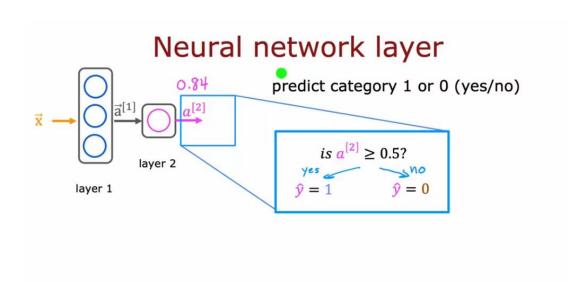
Windows'u etkinleştirmek için Ayarlar'a gidin.

\$\text{\$\text{\$\submitter{A}\text{}}}\$ I, \$\text{\$\text{\$\submitter{A}\text{}}}\$ and \$\text{\$\texitt{\$\text{\$\text{\$\text{\$\text{\$\tex{

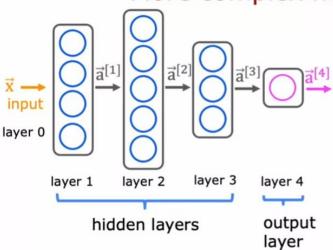


A üstü parantez sayı hangi katmana ait olduğunu gösterir.

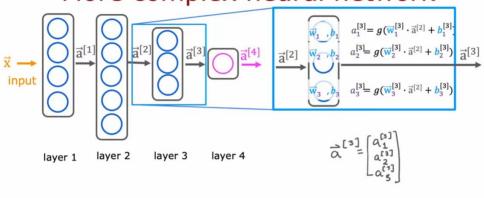


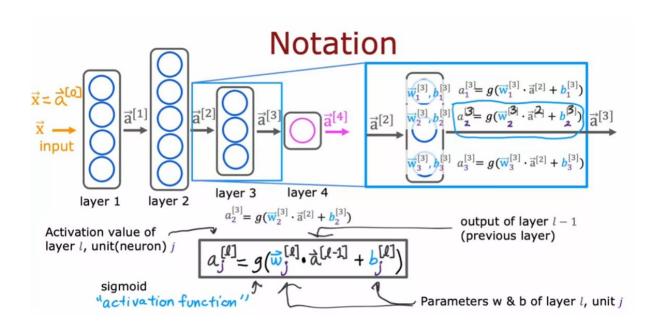


More complex neural network

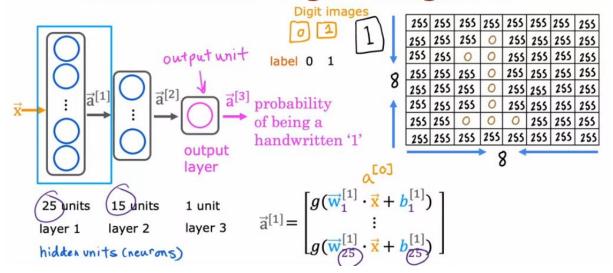


More complex neural network

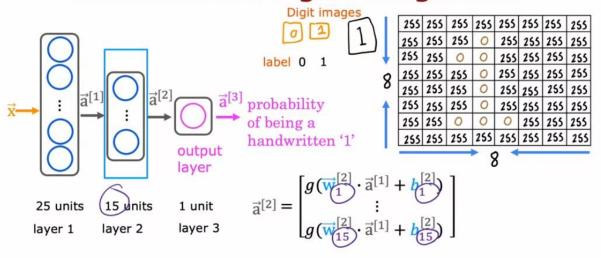




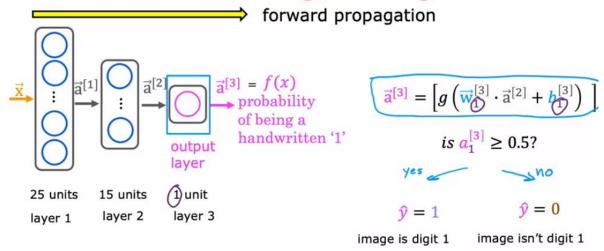
Handwritten digit recognition



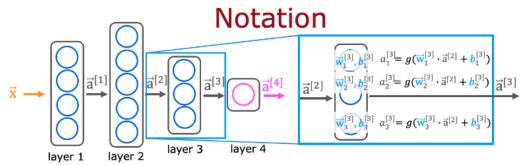
Handwritten digit recognition



Handwritten digit recognition



1.



$$a_j^{[l]} = g(\overrightarrow{\mathbf{w}}_j^{[l]} \cdot \overrightarrow{\mathbf{a}}^{[l-1]} + b_j^{[l]})$$

For a neural network, what is the expression for calculating the activation of the third neuron in layer 2? Note, this is different from the question that you saw in the lecture video.

$$\bigcap a_3^{[2]} = g(\vec{w}_3^{[2]} \cdot \vec{a}^{[2]} + b_3^{[2]})$$

$$\bigcap a_3^{[2]} = g(\vec{w}_2^{[3]} \cdot \vec{a}^{[2]} + b_2^{[3]})$$

$$\bigcirc \ a_3^{[2]} = g(\vec{w}_2^{[3]} \cdot \vec{a}^{[1]} + b_2^{[3]})$$

Handwritten digit recognition

 $\vec{a}^{[1]} \stackrel{\vec{a}^{[2]}}{\stackrel{\vec{a}^{[3]}}}{\stackrel{\vec{a}^{[3]}}{\stackrel{\vec{a}^{[3]}}}{\stackrel{\vec{a}^{[3]}}{\stackrel{\vec{a}^{[3]}}}{\stackrel{\vec{a}^{[3]}}}{\stackrel{\vec{a}^{[3]}}}{\stackrel{\vec{a}^{[3]}}{\stackrel{\vec{a}^{[3]}}}{\stackrel{\vec{a}^{[3]}}}{\stackrel{\vec{a}^{[3]}}}{\stackrel{\vec{a}^{[3]}}}{\stackrel{\vec{a}^{[3]}}}{\stackrel{\vec{a}^{[3]}}}{\stackrel{\vec{a}^{[3]}}}{\stackrel{\vec{a}^{[3]}}}{\stackrel{\vec{a}^{[3]}}}{\stackrel{\vec{a}^{[3]}}}{\stackrel{\vec{a}^{[3]}}}{\stackrel{\vec{a}^{[3]}}}{\stackrel{\vec{a}^{[3]}}}{\stackrel{\vec{a}^{[3]}}}{\stackrel{\vec{a}^{[3]}}}{\stackrel{\vec{a}^{[3]}}}}{\stackrel{\vec{a}^{[3]}}}{\stackrel{\vec{a}^{[3]}}}{\stackrel{\vec{a}^{[3]}}}{\stackrel{\vec{a}^{[3]}}}{\stackrel{\vec{a}^{[3]}}}{\stackrel{\vec{a}^{[3]}}}}{\stackrel{\vec{a}^{[3]}}}{\stackrel{\vec{a}^{[3]}}}}{\stackrel{\vec{a}^{[3]}}}{\stackrel{\vec{a}^{[3]}}}}{\stackrel{\vec{a}^{[3]}}}{\stackrel{\vec{a}^{[3]}}}}{\stackrel{\vec{a}^{[3]}}}{\stackrel{\vec{a}^{[3]}}}}{\stackrel{\vec{$

image is digit 1 image isn't digit 1

1 point

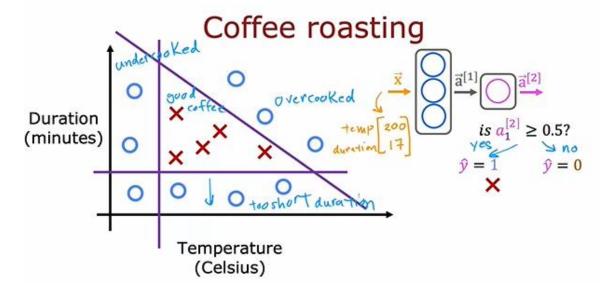
For the handwriting recognition task discussed in lecture, what is the output $a_1^{[3]}$?

- A vector of several numbers, each of which is either exactly 0 or 1
- O A vector of several numbers that take values between 0 and 1
- A number that is either exactly 0 or 1, comprising the network's prediction
- The estimated probability that the input image is of a number 1, a number that ranges from 0 to 1.

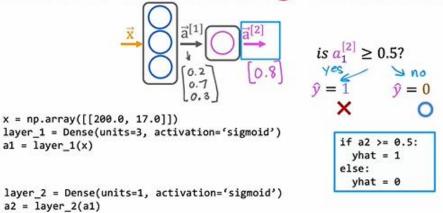
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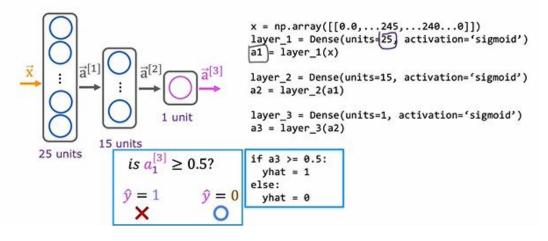
Inference in Code



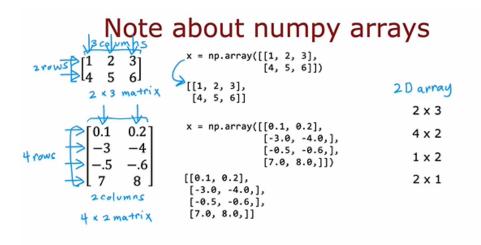
Build the model using TensorFlow



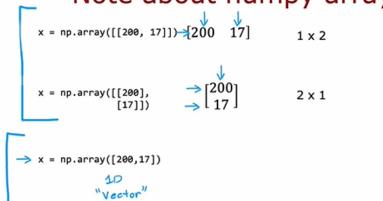
Model for digit classification



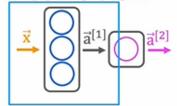
Data in Tensorflow



Note about numpy arrays



Activation vector



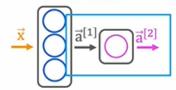
```
x = np.array([[200.0, 17.0]])
layer_1 = Dense(units=3, activation='sigmoid')
a1 = layer_1(x)

> [[0.2, 0.7, 0.3]] 1 x 3 matrix

tf.Tensor([[0.2 0.7 0.3]], shape=(1, 3), dtype=float32)

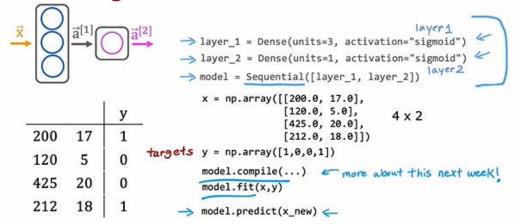
> a1.numpy()
array([[0.2, 0.7, 0.3]], dtype=float32)
```

Activation vector

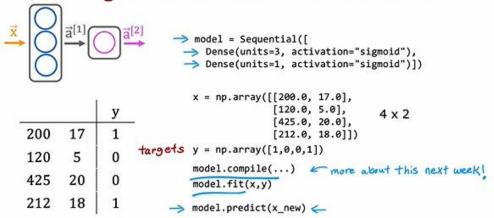


Building a Neural Network

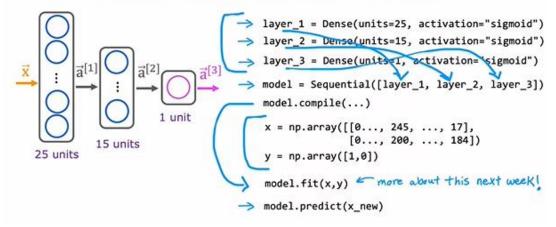
Building a neural network architecture



Building a neural network architecture



Digit classification model



model = Sequential([

Dense(units=25, activation="sigmoid"),

Dense(units=15, activation="sigmoid"),

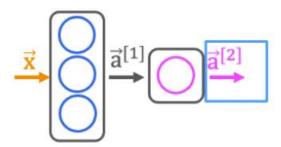
Dense(units=10, activation="sigmoid"),

Dense(units=1, activation="sigmoid")])

This code will define a neural network with how many layers?

- O 3
- 4
- O 25
- 0 5

2.



x = np.array([[200.0, 17.0]])
layer_1 = Dense(units=3, activation='sigmoid')
a1 = layer_1(x)

How do you define the second layer of a neural network that has 4 neurons and a sigmoid activation?

- O Dense(units=[4], activation=['sigmoid'])
- O Dense(units=4)
- Dense(units=4, activation='sigmoid')
- O Dense(layer=2, units=4, activation = 'sigmoid')

1 point

Forward prop in a single layer

forward prop (coffee roasting model)

```
a_1^{[2]} = g(\vec{\mathbf{w}}_1^{[2]} \cdot \vec{\mathbf{a}}^{[1]} + b_1^{[2]})
                                                          \rightarrow w2_1 = np.array([-7, 8, 9])
                                                          \rightarrow b2_1 = np.array([3])
                                                                                                               W<sub>1</sub> w<sub>2_1</sub>
                                                          \rightarrow z2_1 = np.dot(w2_1,a1)+b2_1
                                                          \rightarrow a2_1 = sigmoid(z2_1)
                                           10 arrays
x = np.array([200, 17])
                                                                               a_3^{[1]} = g(\vec{\mathbf{w}}_3^{[1]} \cdot \vec{\mathbf{x}} + b_3^{[1]})
a_1^{[1]} = g(\vec{\mathbf{w}}_1^{[1]} \cdot \vec{\mathbf{x}} + b_1^{[1]})
                                          a_2^{[1]} = g(\vec{\mathbf{w}}_2^{[1]} \cdot \vec{\mathbf{x}} + b_2^{[1]})
                                          w1_2 = np.array([-3, 4]) w1_3 = np.array([5, -6])
w1_1 = np.array([1, 2])
b1_1 = np.array([-1])
                                          b1_2 = np.array([1])
                                                                                    b1_3 = np.array([2])
z1_1 = np.dot(w1_1,x)+b1_1 z1_2 = np.dot(w1_2,x)+b1_2 z1_3 = np.dot(w1_3,x)+b1_3
                                                                                 a1_3 = sigmoid(z1_3)
                                       Ga1_2 = sigmoid(z1_2)
a1_1 = sigmoid(z1_1)
                                       = np.array([a1_1, a1_2, a1_3])
```

Genearal implemantation of forward propagation

```
Forward prop in NumPy
                                                                  def sequential(x):
                                def dense(a_in,W,b):
                                3 units = W.shape[1] [0,0,0] &
                                                                 a1 = dense(x,W1,b1)
                                                               a2 = dense(a1,W2,b2)
                                  a_out = np.zeros(units)
                                                                    a3 = dense(a2,W3,b3)
                                  for j in range(units):0,1,2
                                                                    a4 = dense(a3, W4, b4)
                                   w = W[:,j]
                                                                    f_x = a4
                                    z = np.dot(w,a_in) + b[j]
                                   a_{out[j]} = g(z)
                                                                    return f x
                                  return a_out 🖹
                                                 Note: g() is defined outside of dense().
 b_1^{[l]} = -1 b_2^{[l]} = 1 b_3^{[l]} = 2
                                                 (see optional lab for details)
b = np.array([-1, 1, 2])
                                    capital W refers to a matrix
       \vec{a}^{[0]} = \vec{x}
a_{in} = np.array([-2, 4])
```

1 point

forward prop (coffee roasting model)

```
a_1^{[2]} = g(\vec{\mathbf{w}}_1^{[2]} \cdot \vec{\mathbf{a}}^{[1]} + b_1^{[2]})
                                                            \rightarrow w2_1 = np.array([-7, 8, 9])
                                                           \rightarrow b2_1 = np.array([3])
                                                           \rightarrow z2_1 = np.dot(w2_1,a1)+b2_1
                                                           \rightarrowa2_1 = sigmoid(z2_1)
x = np.array([200, 17])
                                            10 arrays
a_1^{[1]} = g(\vec{\mathbf{w}}_1^{[1]} \cdot \vec{\mathbf{x}} + b_1^{[1]})
                                           a_2^{[1]} = g(\vec{\mathbf{w}}_2^{[1]} \cdot \vec{\mathbf{x}} + b_2^{[1]})
                                                                                    a_2^{[1]} = g(\vec{\mathbf{w}}_2^{[1]} \cdot \vec{\mathbf{x}} + b_2^{[1]})
w1_1 = np.array([1, 2])
                                          w1_2 = np.array([-3, 4])
                                                                                      w1_3 = np.array([5, -6])
b1_1 = np.array([-1])
                                          b1_2 = np.array([1])
                                                                                      b1_3 = np.array([2])
z1_1 = np.dot(w1_1,x)+b1_1 z1_2 = np.dot(w1_2,x)+b1_2 z1_3 = 

    a1_3 =

a1_1 = sigmoid(z1_1)
                                       a1_2 = sigmoid(z1_2)
                                      = np.array([a1_1, a1_2, a1_3])
```

According to the lecture, how do you calculate the activation of the third neuron in the first layer using NumPy?

O layer_1 = Dense(units=3, activation='sigmoid') a_1 = layer_1(x)

z1_3 = w1_3 * x + b a1_3 = sigmoid(z1_3)

z1_3 = np.dot(w1_3, x) + b1_3
a1_3 = sigmoid(z1_3)

2. 1point

```
Forward prop in NumPy

\vec{x}

\vec{w}_{1}^{(1)}, \vec{b}_{1}^{(1)}

\vec{w}_{2}^{(1)}, \vec{b}_{2}^{(1)}

\vec{w}_{1}^{(1)}, \vec{b}_{1}^{(1)}

\vec{w}_{1}^{(1)} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}

\vec{w}_{2}^{(1)} = \begin{bmatrix} -3 \\ 4 \end{bmatrix}

\vec{w}_{3}^{(1)} = \begin{bmatrix} 5 \\ -6 \end{bmatrix}

We np.array([

\begin{bmatrix} 1 \\ 1 \\ -3 \end{bmatrix}, \begin{bmatrix} 5 \\ 5 \\ 2 \end{bmatrix}, \begin{bmatrix} 4 \\ 4 \end{bmatrix}, \begin{bmatrix} -6 \end{bmatrix}])

\vec{w} = \vec{w}_{1}^{(1)} = \vec{w}_{2}^{(1)} = \vec{w}_{3}^{(1)} = \vec{w}_{3}^
```

According to the lecture, when coding up the numpy array W, where would you place the w parameters for each neuron?

- O In the rows of W.
- In the columns of W.

3.

1 point

Forward prop in NumPy

```
\vec{x} = \begin{bmatrix} \vec{x} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ \vec{y} & \vec{y} & \vec{y} & \vec{y} \end{bmatrix} & \text{def dense}(a_in, w, b, g): \\ & \vec{w}_1^{[1]} = \begin{bmatrix} 1 \\ 2 \end{bmatrix} & \vec{w}_2^{[1]} = \begin{bmatrix} -3 \\ 4 \end{bmatrix} & \vec{w}_3^{[1]} = \begin{bmatrix} 5 \\ -6 \end{bmatrix} & \text{a_out} = np.zeros(units) \\ & \text{for j in range}(units): \\ & \vec{w} = w[:,j] & \text{for j in range}(units): \\ & \vec{w} = w[:,j] & \text{z = np.dot}(w,a_in) + b[j] & \text{a_out}[j] = g(z) \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} & \vec{y} \\ & \vec{y} & \vec{y} & \vec{y} & \vec{y} &
```

For the code above in the "dense" function that defines a single layer of neurons, how many times does the code go through the "for loop"? Note that W has 2 rows and 3 columns.

- O 2 times
- O 6 times
- 3 times
- 5 times

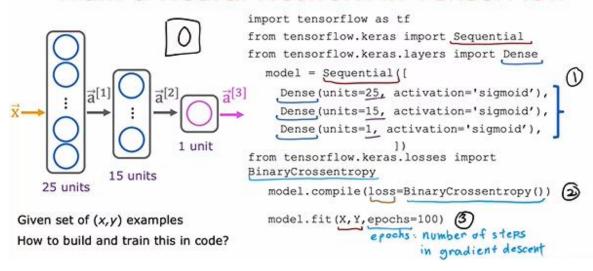
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Tensorflow Implementation

Train a Neural Network in TensorFlow



Training Details

Model Training Steps Tensor Flow

specify how to compute output given input x and parameters w,b (define model)

$$f_{\overrightarrow{\mathbf{w}},b}(\overrightarrow{\mathbf{x}}) = ?$$

(2) specify loss and cost

$$J(\overrightarrow{\mathbf{w}},b) = \frac{1}{m} \sum_{i=1}^{m} L(f_{\overrightarrow{\mathbf{w}},b}(\overrightarrow{\mathbf{x}}^{(i)}), y^{(i)})$$

Train on data to minimize $J(\overline{\mathbf{w}}, b)$

logistic regression

$$z = np.dot(w,x) + b$$

$$f_x = 1/(1+np.exp(-z))$$

logistic loss

neural network

binary cross entropy

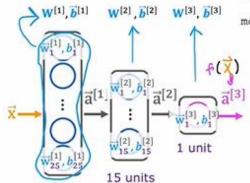
```
model.compile(
loss=BinaryCrossentropy())
model.fit(X,y,epochs=100)
```

1. Create the model

define the model

$$f(\vec{x}) = ?$$

25 units



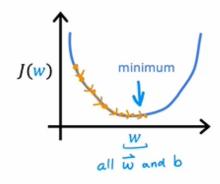
import tensorflow as tf
from tensorflow.keras import Sequential
from tensorflow.keras.layers import Dense

model = Sequential([
 Dense(units=25, activation='sigmoid'),
 Dense(units=15, activation='sigmoid'),
 Dense(units=1, activation='sigmoid'),
])

Loss and cost functions

 $J(\mathbf{W}, \mathbf{B}) = \frac{1}{m} \sum_{i=1}^{m} L(f(\mathbf{x}^{(i)}), \mathbf{y}^{(i)})$ handwritten digit binary classification classification problem $L(f(\overline{x}), y) = -y\log(f(\overline{x})) - (1 - y)\log(1 - f(\overline{x}))$ $W^{[1]}, W^{[2]}, W^{[3]} = \vec{b}^{[1]}, \vec{b}^{[2]}, \vec{b}^{[3]}$ Compare prediction vs. target 9 logistic loss also Known as binary cross entropy from tensorflow.keras.losses import model.compile(loss= BinaryCrossentropy()) BinaryCrossentropy K Keras regression mean squared error (predicting numbers and not categories) from tensorflow.keras.losses import MeanSquaredError model.compile(loss= MeanSquaredError())

Gradient descent



repeat {

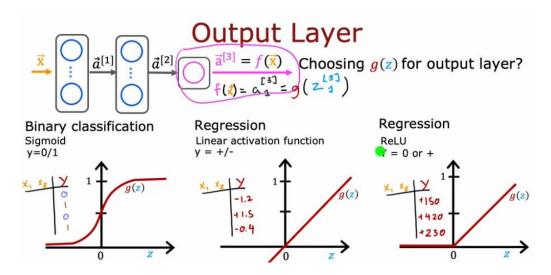
$$w_j^{[l]} = w_j^{[l]} - \alpha \frac{\partial}{\partial w_j} J(\overrightarrow{w}, b)$$

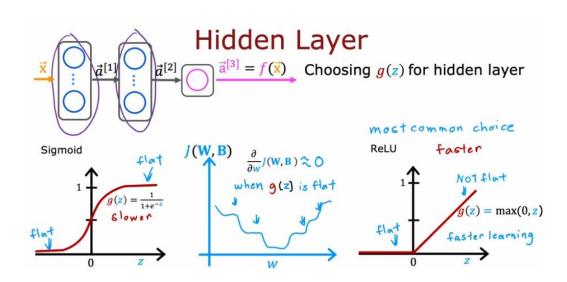
$$b_j^{[l]} = b_j^{[l]} - \alpha \frac{\partial}{\partial bj} J(\overrightarrow{w}, b)$$

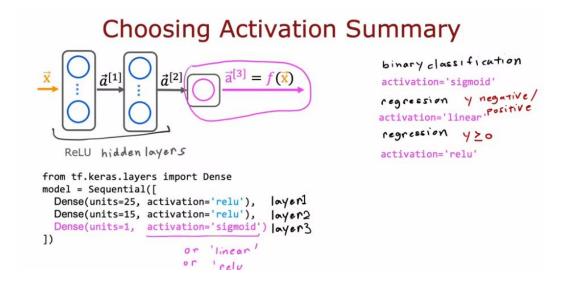
} Compute derivatives for gradient descent using "backpropagation"

model.fit(X,y,epochs=100)

Choosing activation function

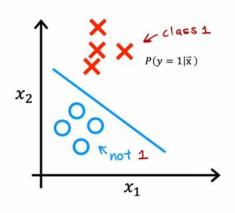


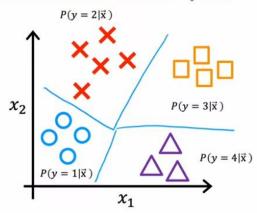




Multiclass

Multiclass classification example





Softmax

Logistic regression (2 possible output values) $z = \vec{w} \cdot \vec{x} + b$

$$a_1 = g(z) = \frac{0.11}{1+e^{-z}} = P(y=1|\vec{x})$$

Softmax regression (N possible outputs) y=1,2,3,...,N

$$z_{j} = \overrightarrow{w}_{j} \cdot \overrightarrow{x} + b_{j} \quad j = 1, ..., N$$

$$w_{1}, w_{2}, ..., w_{N}$$

$$a_{j} = \frac{b_{1}}{\sum_{k=1}^{N} e^{z_{k}}} = P(y = j | \overrightarrow{x})$$

note: a1+ a2+ ... + aN = 1

Softmax regression (4 possible outputs) y=1,2,3,4

$$\mathbf{x} \ z_1 = \ \overrightarrow{\mathbf{w}}_1 \cdot \overrightarrow{\mathbf{x}} + b_1$$

$$a_{1} = \frac{e^{z_{1}}}{e^{z_{1}} + e^{z_{2}} + e^{z_{3}} + e^{z_{4}}}$$

$$= P(y = 1|\vec{x}) \bigcirc .30$$

$$\bigcirc z_2 = \vec{w}_2 \cdot \vec{x} + b$$

$$a_2 = \frac{e^{z_2}}{e^{z_1} + e^{z_2} + e^{z_3} + e^{z_4}}$$

$$z_3 = \vec{\mathbf{w}}_3 \cdot \vec{\mathbf{x}} + b$$

$$a_3 = \frac{e^{z_3}}{e^{z_1} + e^{z_2} + e^{z_3} + e^{z_4}}$$

$$\cdot \vec{\mathbf{v}} + \mathbf{h}$$

$$a_4 = \frac{e^{z_4}}{e^{z_1} + e^{z_2} + e^{z_3} + e^{z_4}}$$
$$= P(y = 4|\vec{x}) \ 0.35$$

Logistic regression

 $z = \overrightarrow{w} \cdot \overrightarrow{x} + b$ $a_1 = g(z) = \frac{1}{1 + e^{-z}} = P(y = 1 | \overrightarrow{x})$ $a_2 = 1 - a_1 = P(y = 0 | \overrightarrow{x})$ $\log s = -y \log a_1 - (1 - y) \log(1 - a_1)$ $|f|_{y=1} = 0$

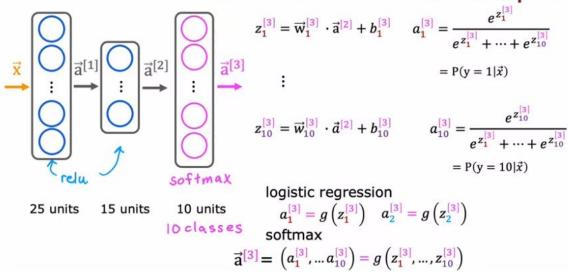
 $J(\vec{w}, b) = \text{average loss}$

Cost Softmax regression

 $a_{1} = \frac{e^{z_{1}} + e^{z_{2}} + \dots + e^{z_{N}}}{e^{z_{1}} + e^{z_{2}} + \dots + e^{z_{N}}} = P(y = N | \vec{x})$ \vdots $a_{N} = \frac{e^{z_{N}}}{e^{z_{1}} + e^{z_{2}} + \dots + e^{z_{N}}} = P(y = N | \vec{x})$ Crossentropy loss $loss(a_{1}, \dots, a_{N}, y) = \begin{cases} -\log a_{1} & \text{if } y = 1 \\ -\log a_{2} & \text{if } y = 2 \end{cases}$ \vdots $-\log a_{N} & \text{if } y = N \end{cases}$

Neural Network with Softmax output

Neural Network with Softmax output



MNIST with softmax specify the model from tensorflow.keras import Sequential $f_{\overrightarrow{\mathbf{w}},b}(\overrightarrow{\mathbf{x}}) = ?$ from tensorflow.keras.layers import Dense model = Sequential([Dense(units=25, activation='relu'), Dense (units=15, activation='relu'), Dense (units=10, activation='softmax') specify loss and cost $L(f_{\overrightarrow{\mathbf{w}},b}(\overrightarrow{\mathbf{x}}), \mathbf{y})$ from tensorflow.keras.losses import SparseCategoricalCrossentropy. model.compile(loss= SparseCategoricalCrossentropy()) Train on data to model.fit(X,Y,epochs=100) minimize $I(\vec{w}, b)$ Note: better (recommended) version later. Don't use the version shown here!

Improved implementation of softmax

Numerical Roundoff Errors

```
More numerically accurate implementation of logistic loss: | + 1 | 10,000 | - 10,000
                                                              model = Sequential([
Logistic regression:
                                                                   Dense(units=25, activation='relu'),
      Dense (units=15, activation='relu'), 'inear'
Original loss
loss = -y \log(a) - (1-y)\log(1-a) \quad model.compile(loss=BinaryCrossEntropy())
model.compile(loss=BinaryCrossEntropy(from_logits=True))
model.compile(loss=BinaryCrossEntropy(from_logits=True))
model.compile(loss=BinaryCrossEntropy(from_logits=True))
model.compile(loss=BinaryCrossEntropy(from_logits=True))
Original loss
```

More numerically accurate implementation of softmax

Softmax regression

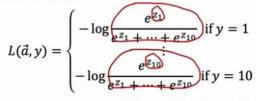
$$(a_{1},...,a_{10}) = g(z_{1},...,z_{10})$$

$$Loss = L(\vec{a},y) = \begin{cases} -\log(\vec{a}) & \text{if } y = 1 \\ -\log(\vec{a}_{10}) & \text{if } y = 10 \end{cases}$$

```
model = Sequential([
                                                                     Dense (units=25, activation='relu'),
                                                                     Dense (units=15, activation='relu'),
Loss = L(\vec{a}, y) = \begin{cases} -\log(\vec{a}) & \text{if } y = 1 \\ \vdots & \text{Dense (units=10, activation='relu'),} \\ \vdots & \vdots & \vdots \\ -\log(\vec{a}_{10}) & \text{if } y = 10 \end{cases}
```

model.compile(loss=SparseCategoricalCrossEntropy())

More Accurate





model.compile(loss=SparseCategoricalCrossEntropy(from logits=True))

MNIST (more numerically accurate)

logistic regression (more numerically accurate)

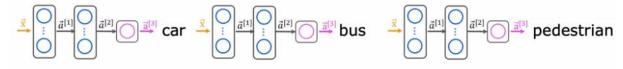
Classification with multiple outputs

Multi-label Classification



Is there a car? yesIs there a bus? yesIs there a pedestrian yes yes

Multi-label Classification



Alternatively, train one neural network with three outputs

$$\vec{a}^{[3]} = \begin{bmatrix} a_1^{[3]} \\ a_2^{[3]} \\ a_3^{[3]} \end{bmatrix}$$

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$$\vec{a}^{[3]} = \begin{bmatrix} a_1^{[3]} \\ a_2^{[3]} \\ a_3^{[3]} \end{bmatrix}$$

$$\vec{a}^{[3]} = \begin{bmatrix} a_1^{[3]} \\ a_2^{[3]} \\ a_3^{[3]} \end{bmatrix}$$

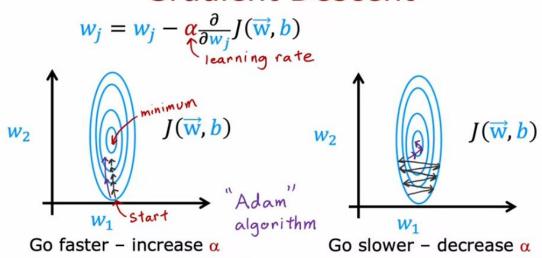
$$\vec{a}^{[3]} = \begin{bmatrix} a_1^{[3]} \\ a_2^{[3]} \\ a_3^{[3]} \end{bmatrix}$$

$$\vec{a}^{[3]} = \begin{bmatrix} a_1^{[3]} \\ a_2^{[3]} \\ a_3^{[3]} \end{bmatrix}$$

$$\vec{a}^{[3]} = \begin{bmatrix} a_1^{[3]} \\ a_2^{[3]} \\ a_3^{[3]} \end{bmatrix}$$

Advanced Optimization

Gradient Descent



Adam Algorithm Intuition

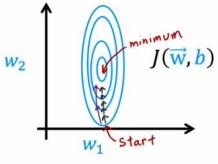
Adam: Adaptive Moment estimation not just one &

$$w_{1} = w_{1} - \underbrace{\alpha_{1} \frac{\partial}{\partial w_{1}}}_{\exists w_{1}} J(\overrightarrow{w}, b)$$

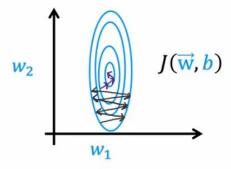
$$\vdots$$

$$w_{10} = w_{10} - \underbrace{\alpha_{10} \frac{\partial}{\partial w_{10}}}_{\exists w_{10}} J(\overrightarrow{w}, b)$$

$$b = b - \underbrace{\alpha_{11} \frac{\partial}{\partial b}}_{\exists w_{10}} J(\overrightarrow{w}, b)$$



If w_j (or b) keeps moving in same direction, increase α_j .



If w_j (or b) keeps oscillating, reduce α_j .

MNIST Adam

model

compile

```
d=10-3=0.001
```

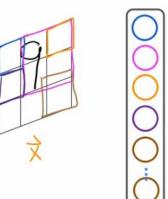
```
model.compile(optimizer=tf.keras.optimizers.Adam(learning_rate=1e-3),
    loss=tf.keras.losses.SparseCategoricalCrossentropy(from_logits=True))
```

fit

```
model.fit(X,Y,epochs=100)
```

Additional Layer Types

Convolutional Layer



Each Neuron only looks at part of the previous layer's inputs.

Why?

- · Faster computation
- Need less training data (less prone to overfitting)

Convolutional Neural Network

