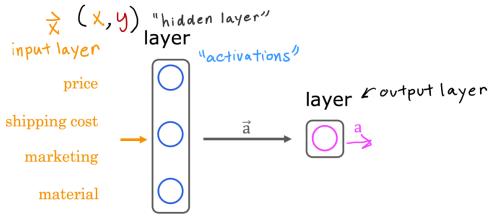
1. 1 point



Which of these are terms used to refer to components of an artificial neural network? (hint: three of these are correct)

- neurons
- layers
- axon
- activation function

 $\textbf{2.} \quad \text{True/False? Neural networks take inspiration from, but do not very accurately mimic, how neurons in a biological brain learn.}$ 

1 point

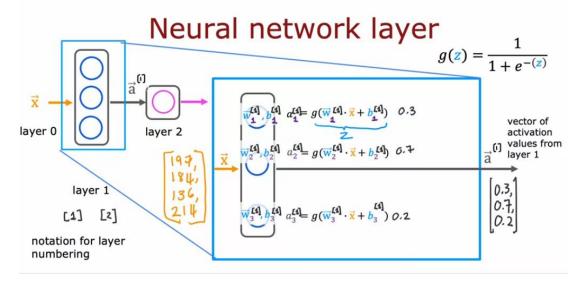
- True
- O False

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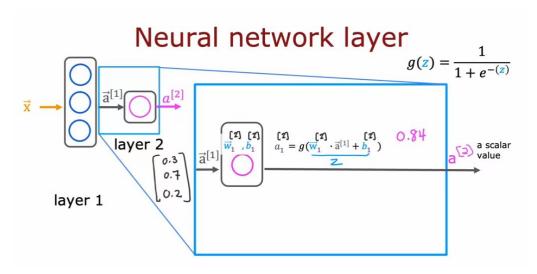
Windows'u Etkinleştir

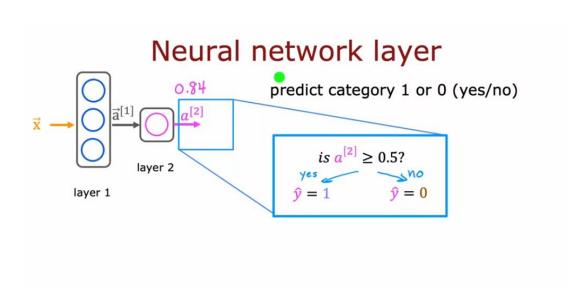
Windows'u etkinleştirmek için Ayarlar'a gidin.

Saban Kara, understand that submitting work that isn't my own may result in permanent failure of this course or deactivation of my Coursera account.

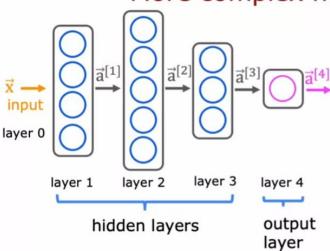


A üstü parantez sayı hangi katmana ait olduğunu gösterir.

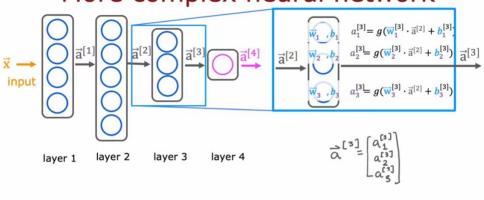


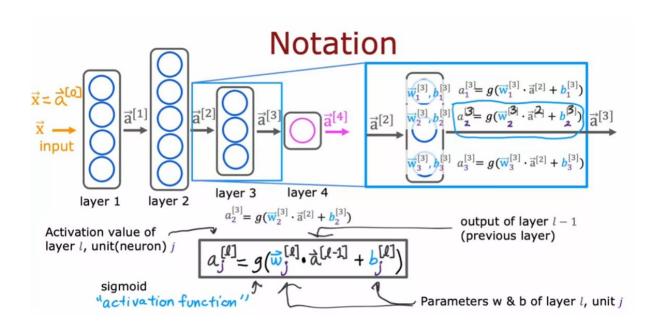


## More complex neural network

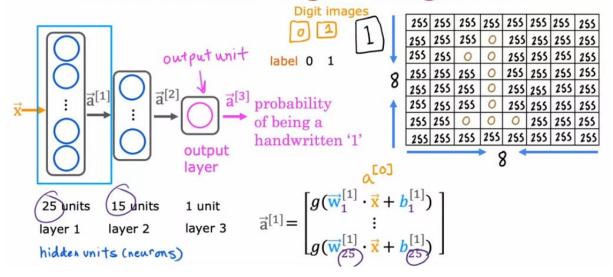


### More complex neural network

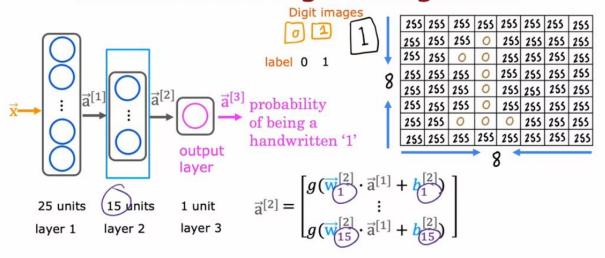




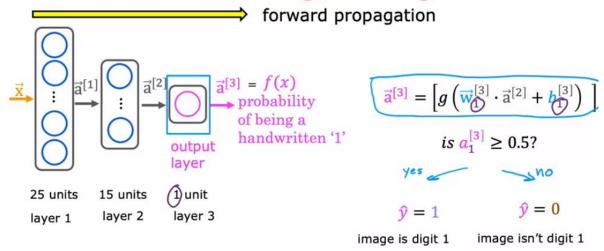
## Handwritten digit recognition



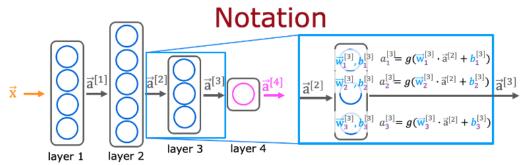
# Handwritten digit recognition



## Handwritten digit recognition



1.



$$a_j^{[l]} = g(\overrightarrow{\mathbf{w}}_j^{[l]} \cdot \overrightarrow{\mathbf{a}}^{[l-1]} + b_j^{[l]})$$

For a neural network, what is the expression for calculating the activation of the third neuron in layer 2? Note, this is different from the question that you saw in the lecture video.

$$\bigcap a_3^{[2]} = g(\vec{w}_3^{[2]} \cdot \vec{a}^{[2]} + b_3^{[2]})$$

$$O a_3^{[2]} = q(\vec{w}_2^{[3]} \cdot \vec{a}^{[2]} + b_2^{[3]} )$$

$$\bigcirc \ a_3^{[2]} = g(\vec{w}_2^{[3]} \cdot \vec{a}^{[1]} + b_2^{[3]})$$

## Handwritten digit recognition

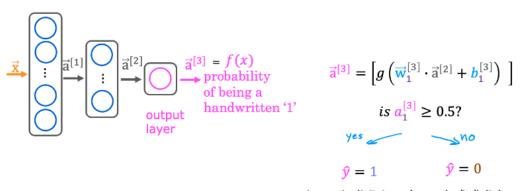


image is digit 1 image isn't digit 1

1 point

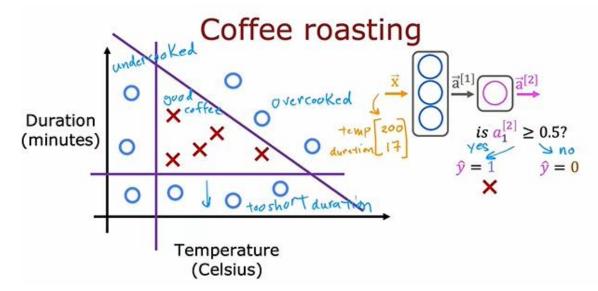
For the handwriting recognition task discussed in lecture, what is the output  $a_1^{[3]}$ ?

- A vector of several numbers, each of which is either exactly 0 or 1
- O A vector of several numbers that take values between 0 and 1
- A number that is either exactly 0 or 1, comprising the network's prediction
- The estimated probability that the input image is of a number 1, a number that ranges from 0 to 1.

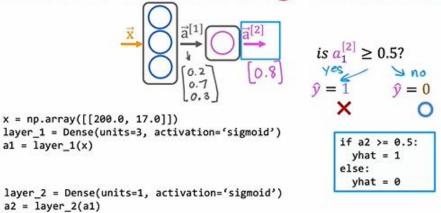
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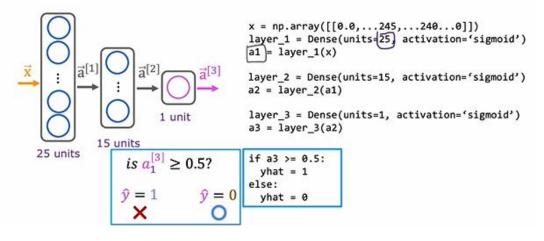
#### Inference in Code



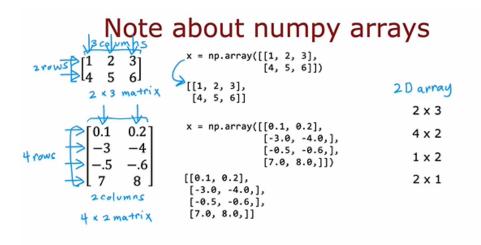
## Build the model using TensorFlow



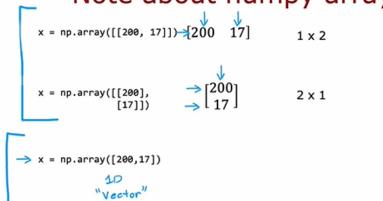
## Model for digit classification



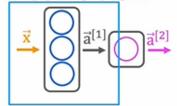
#### **Data in Tensorflow**



### Note about numpy arrays



### Activation vector



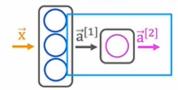
```
x = np.array([[200.0, 17.0]])
layer_1 = Dense(units=3, activation='sigmoid')
a1 = layer_1(x)

> [[0.2, 0.7, 0.3]] 1 x 3 matrix

tf.Tensor([[0.2 0.7 0.3]], shape=(1, 3), dtype=float32)

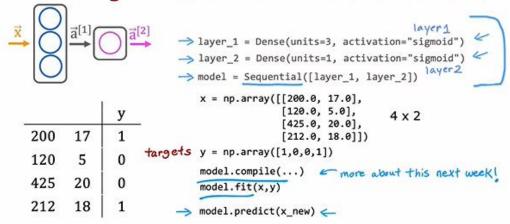
> a1.numpy()
array([[0.2, 0.7, 0.3]], dtype=float32)
```

## **Activation vector**

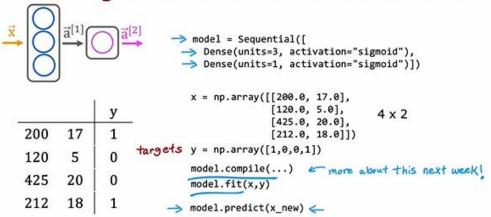


#### **Building a Neural Network**

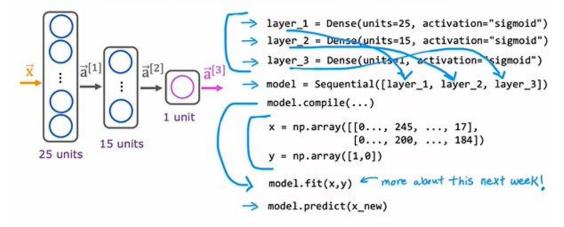
#### Building a neural network architecture



#### Building a neural network architecture



## Digit classification model



1 point

model = Sequential([

Dense(units=25, activation="sigmoid"),

Dense(units=15, activation="sigmoid"),

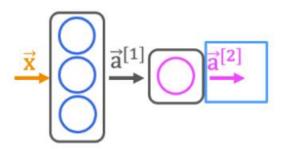
Dense(units=10, activation="sigmoid"),

Dense(units=1, activation="sigmoid")])

This code will define a neural network with how many layers?

- O 3
- 4
- O 25
- 0 5

2.



x = np.array([[200.0, 17.0]])
layer\_1 = Dense(units=3, activation='sigmoid')
a1 = layer\_1(x)

How do you define the second layer of a neural network that has 4 neurons and a sigmoid activation?

- O Dense(units=[4], activation=['sigmoid'])
- O Dense(units=4)
- Dense(units=4, activation='sigmoid')
- O Dense(layer=2, units=4, activation = 'sigmoid')

#### Forward prop in a single layer

## forward prop (coffee roasting model)

```
a_1^{[2]} = g(\vec{\mathbf{w}}_1^{[2]} \cdot \vec{\mathbf{a}}^{[1]} + b_1^{[2]})
                                                         → w2_1 = np.array([-7, 8, 9])
                                                         \rightarrow b2_1 = np.array([3])
                                                                                                             W<sub>1</sub> w<sub>2_1</sub>
                                                         \rightarrow z2_1 = np.dot(w2_1,a1)+b2_1
                                                         \rightarrow a2_1 = sigmoid(z2_1)
                                          10 arrays
x = np.array([200, 17])
                                                                              a_3^{[1]} = g(\vec{\mathbf{w}}_3^{[1]} \cdot \vec{\mathbf{x}} + b_3^{[1]})
a_1^{[1]} = g(\vec{\mathbf{w}}_1^{[1]} \cdot \vec{\mathbf{x}} + b_1^{[1]})
                                         a_2^{[1]} = g(\vec{\mathbf{w}}_2^{[1]} \cdot \vec{\mathbf{x}} + b_2^{[1]})
                                         w1_2 = np.array([-3, 4]) w1_3 = np.array([5, -6])
w1_1 = np.array([1, 2])
b1_1 = np.array([-1])
                                         b1_2 = np.array([1])
                                                                                   b1_3 = np.array([2])
z1_1 = np.dot(w1_1,x)+b1_1 z1_2 = np.dot(w1_2,x)+b1_2 z1_3 = np.dot(w1_3,x)+b1_3
                                                                                a1_3 = sigmoid(z1_3)
                                      Ga1_2 = sigmoid(z1_2)
a1_1 = sigmoid(z1_1)
                                       = np.array([a1_1, a1_2, a1_3])
```

#### Genearal implemantation of forward propagation

```
Forward prop in NumPy
                                                                  def sequential(x):
                                def dense(a_in,W,b):
                                3 units = W.shape[1] [0,0,0] &
                                                                 a1 = dense(x,W1,b1)
                                                                a2 = dense(a1, W2, b2)
                                  a_out = np.zeros(units)
                                                                    a3 = dense(a2,W3,b3)
                                  for j in range(units):0,1,2
                                                                    a4 = dense(a3, W4, b4)
                                   w = W[:,j]
                                                                    f_x = a4
                                    z = np.dot(w,a_in) + b[j]
                                   a_{out[j]} = g(z)
                                                                    return f x
                                  return a_out 🖹
                                                  Note: g() is defined outside of dense().
 b_1^{[l]} = -1 b_2^{[l]} = 1 b_3^{[l]} = 2
                                                 (see optional lab for details)
b = np.array([-1, 1, 2])
                                    capital W refers to a matrix
       \vec{a}^{[0]} = \vec{x}
a_{in} = np.array([-2, 4])
```

1 point

forward prop (coffee roasting model)

```
a_1^{[2]} = g(\vec{\mathbf{w}}_1^{[2]} \cdot \vec{\mathbf{a}}^{[1]} + b_1^{[2]})

≥ w2_1 = np.array([-7, 8, 9])
                                                           \rightarrow b2_1 = np.array([3])
                                                           > z2_1 = np.dot(w2_1,a1)+b2_1
                                                           \rightarrowa2_1 = sigmoid(z2_1)
x = np.array([200, 17])
                                            10 arrays
a_1^{[1]} = g(\overrightarrow{\mathbf{w}}_1^{[1]} \cdot \overrightarrow{\mathbf{x}} + b_1^{[1]})
                                           a_2^{[1]} = g(\vec{\mathbf{w}}_2^{[1]} \cdot \vec{\mathbf{x}} + b_2^{[1]})
                                                                                    a_3^{[1]} = g(\vec{\mathbf{w}}_3^{[1]} \cdot \vec{\mathbf{x}} + b_3^{[1]})
w1_1 = np.array([1, 2])
                                          w1_2 = np.array([-3, 4])
                                                                                     w1_3 = np.array([5, -6])
b1_1 = np.array([-1])
                                          b1_2 = np.array([1])
                                                                                     b1_3 = np.array([2])
z1_1 = np.dot(w1_1,x)+b1_1 z1_2 = np.dot(w1_2,x)+b1_2 z1_3 = 
                                                                                 √ a1_3 =
a1_1 = sigmoid(z1_1)
                                       a1_2 = sigmoid(z1_2)
                                      = np.array([a1_1, a1_2, a1_3])
```

 $According \ to \ the \ lecture, how \ do \ you \ calculate \ the \ activation \ of \ the \ third \ neuron \ in \ the \ first \ layer \ using \ NumPy?$ 

O layer\_1 = Dense(units=3, activation='sigmoid')

a\_1 = layer\_1(x)

O

z1\_3 = w1\_3 \* x + b

z1\_3 = np.dot(w1\_3, x) + b1\_3
a1\_3 = sigmoid(z1\_3)

a1\_3 = sigmoid(z1\_3)

2. 1point

```
Forward prop in NumPy

\vec{x}

\vec{w}_{2}^{[1]}, \vec{b}_{2}^{[1]}

\vec{w}_{3}^{[1]}, \vec{b}_{3}^{[1]}

\vec{w}_{1}^{[1]} = \begin{bmatrix} 1 \\ 2 \end{bmatrix} \quad \vec{w}_{2}^{[1]} = \begin{bmatrix} -3 \\ 4 \end{bmatrix} \quad \vec{w}_{3}^{[1]} = \begin{bmatrix} 5 \\ -6 \end{bmatrix}

\vec{w}

\vec{w}

\vec{w}

\vec{v}

\vec{v}
```

According to the lecture, when coding up the numpy array W, where would you place the w parameters for each neuron?

- O In the rows of W.
- In the columns of W.

3.

#### 1 point

## Forward prop in NumPy

```
\vec{x} \xrightarrow{W_{1}^{[1]},b_{1}^{[1]}} \vec{a}^{[l]} \xrightarrow{\vec{a}^{[l]}} 
\vec{w}_{1}^{[1]} = \begin{bmatrix} 1 \\ 2 \end{bmatrix} \vec{w}_{2}^{[1]} = \begin{bmatrix} -3 \\ 4 \end{bmatrix} \vec{w}_{3}^{[1]} = \begin{bmatrix} 5 \\ -6 \end{bmatrix} 
def dense(a_in,W,b, g): units = W.shape[1] a_out = np.zeros(units) for j in range(units): w = W[:,j] z = np.dot(w,a_in) + b[j] a_out[j] = g(z) return a_out 
\vec{b}_{1}^{[l]} = -1 \quad \vec{b}_{2}^{[l]} = 1 \quad \vec{b}_{3}^{[l]} = 2
\vec{b} = np.array([-1, 1, 2])
\vec{a}^{[0]} = \vec{x}
a_in = np.array([-2, 4])
```

For the code above in the "dense" function that defines a single layer of neurons, how many times does the code go through the "for loop"? Note that W has 2 rows and 3 columns.

- O 2 times
- O 6 times
- 3 times
- O 5 times

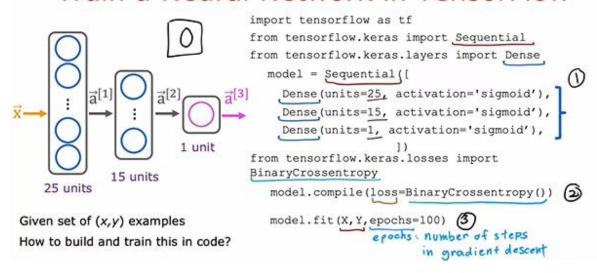
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#### **Tensorflow Implementation**

## Train a Neural Network in TensorFlow



#### **Training Details**

# Model Training Steps Tensor Flow

specify how to compute output given input x and parameters w,b (define model)

$$f_{\overrightarrow{\mathbf{w}},b}(\overrightarrow{\mathbf{x}}) = ?$$

(2) specify loss and cost

$$J(\overrightarrow{w},b) = \frac{1}{m} \sum_{i=1}^{m} L(f_{\overrightarrow{w},b}(\overrightarrow{x}^{(i)}), y^{(i)})$$

Train on data to minimize  $J(\overline{\mathbf{w}}, b)$ 

#### logistic regression

$$z = np.dot(w,x) + b$$

$$f_x = 1/(1+np.exp(-z))$$

#### logistic loss

#### neural network

#### binary cross entropy

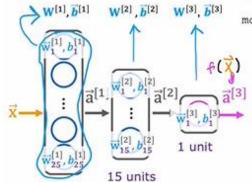
```
model.compile(
loss=BinaryCrossentropy())
model.fit(X,y,epochs=100)
```

### 1. Create the model

#### define the model

$$f(\vec{x}) = ?$$

25 units



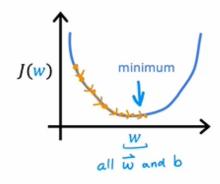
```
import tensorflow as tf
from tensorflow.keras import Sequential
from tensorflow.keras.layers import Dense
```

model = Sequential([
 Dense(units=25, activation='sigmoid'),
 Dense(units=15, activation='sigmoid'),
 Dense(units=1, activation='sigmoid'),
])

#### 2. Loss and cost functions

 $J(\mathbf{W}, \mathbf{B}) = \frac{1}{m} \sum_{i=1}^{m} L(f(\bar{\mathbf{x}}^{(i)}), y^{(i)})$ handwritten digit binary classification classification problem  $L(f(\overline{x}), y) = -y\log(f(\overline{x})) - (1 - y)\log(1 - f(\overline{x}))$  $W^{[1]}, W^{[2]}, W^{[3]} = \vec{b}^{[1]}, \vec{b}^{[2]}, \vec{b}^{[3]}$ Compare prediction vs. target 9 logistic loss also known as binary cross entropy from tensorflow.keras.losses import model.compile(loss= BinaryCrossentropy()) BinaryCrossentropy regression mean squared error (predicting numbers and not categories) from tensorflow.keras.losses import MeanSquaredError model.compile(loss= MeanSquaredError())

### Gradient descent



repeat {

$$w_j^{[l]} = w_j^{[l]} - \alpha \frac{\partial}{\partial w_j} J(\overrightarrow{w}, b)$$
$$b_j^{[l]} = b_j^{[l]} - \alpha \frac{\partial}{\partial bj} J(\overrightarrow{w}, b)$$

} Compute derivatives for gradient descent using "back propagation"

model.fit(X,y,epochs=100)