#### A Short Review of Matrix Algebra



Motivation

Some Useful Matrix

## Lecture 2

## A Short Review of Matrix Algebra

Reading: Zelterman, 2015 Chapter 4; Izenman, 2008 Chapter 3.1-3.2

DSA 8070 Multivariate Analysis

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## **Agenda**

A Short Review of Matrix Algebra



Motivation

**Basic Matrix Concepts** 

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Motivation

Basic Matrix Concepts

#### Data:

	crim	zn	indus	chas	nox	rm
1	0.00632	18	2.31	0	0.538	6.575
2	0.02731	0	7.07	0	0.469	6.421
3	0.02729	0	7.07	0	0.469	7.185
4	0.03237	0	2.18	0	0.458	6.998
5	0.06905	0	2.18	0	0.458	7.147
6	0.02985	0	2.18	0	0.458	6.430

$$\boldsymbol{X} = \begin{bmatrix} x_{11} & x_{12} & \cdots & x_{1p} \\ x_{21} & x_{22} & \cdots & x_{2p} \\ \vdots & \vdots & & \vdots \\ x_{n1} & x_{n2} & \cdots & x_{np} \end{bmatrix}$$

## **Summary Statistics:**

$$\bar{X} = \begin{bmatrix} \bar{x}_1 \\ \bar{x}_2 \\ \vdots \\ \bar{x}_p \end{bmatrix} = \begin{bmatrix} \frac{1}{n} \sum_{i=1}^n x_{i1} \\ \frac{1}{n} \sum_{i=1}^n x_{i2} \\ \vdots \\ \frac{1}{n} \sum_{i=1}^n x_{ip} \end{bmatrix} = \frac{1}{n} \boldsymbol{X}^T \mathbf{1} \text{ is the sample mean vector,}$$

and 
$$S = \begin{bmatrix} s_{11} & s_{12} & \cdots & s_{1p} \\ s_{21} & s_{22} & \cdots & s_{2p} \\ \vdots & \cdots & \cdots & \cdots \\ s_{p1} & s_{p2} & \cdots & s_{pp} \end{bmatrix} = \frac{1}{n-1} \boldsymbol{X}^T (I - \frac{1}{n} \boldsymbol{1} \boldsymbol{1}^T) \boldsymbol{X} \text{ is the }$$

sample covariance matrix

⇒ Many matrix algebra techniques will be applied to this matrix in multivariate analysis

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Basic Matrix Concepts

Fools/Facts

 A column array of p elements is called a vector of dimension p and is written as

$$\mathbf{a} = \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_p \end{bmatrix}$$

 $\Rightarrow$  Each observation in a multivariate dataset is a p-dimensional vector (e.g., exam scores in math, science, and writing).

The transpose of the column vector a is a row vector

$$\boldsymbol{a}^T = \begin{bmatrix} a_1 & a_2 & \cdots & a_p \end{bmatrix}$$

•  $L_{\mathbf{a}}^{-1}\mathbf{a} = \frac{\mathbf{a}}{\sqrt{\sum_{i=1}^{n} a_{i}^{2}}}$  is called a unit vector

## **Vectors in Multivariate Analysis**

Motivation

Some Useful Matrix

- Column vector (observation): Each observation  $\mathbf{x}_i \in \mathbb{R}^p$  is a  $p \times 1$  column; stacking rows yields the data matrix  $\mathbf{X} \in \mathbb{R}^{n \times p}$
- Transpose: Enables matrix operations such as inner products and summary statistics, e.g.,  $\mathbf{x}^{\mathsf{T}}\mathbf{y}$  (inner product),  $\mathbf{a}^{T}\mathbf{x}$  (linear combination),  $\bar{\mathbf{x}} = \frac{1}{n}\mathbf{X}^{T}\mathbf{1}$  (mean),  $\mathbf{X}^{T}\mathbf{X}$  (cross-product for covariance)
- Unit vector: normalize  $\mathbf x$  to  $\mathbf x/\|\mathbf x\|$  (length 1) to remove scale and compare directions



Motivation

Basic Matrix Concepts

Tools/Facts

• A matrix A is an array of elements  $a_{ij}$  with n rows and p columns:

$$\mathbf{A} = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1p} \\ a_{21} & a_{22} & \cdots & a_{2p} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{np} \end{bmatrix}$$

• The transpose  ${\bf A}^T$  has p rows and n columns. The j-th row of  ${\bf A}^T$  is the j-th column of  ${\bf A}$ 

$$\mathbf{A}^{T} = \begin{bmatrix} a_{11} & a_{21} & \cdots & a_{n1} \\ a_{12} & a_{22} & \cdots & a_{n2} \\ \vdots & \vdots & \ddots & \vdots \\ a_{1p} & a_{2p} & \cdots & a_{np} \end{bmatrix}$$

 Key matrices in multivariate analysis: data matrix X, covariance/correlation S, R, and eigen decomposition

$$\boldsymbol{\Sigma} = \mathbb{E} \Big[ (\boldsymbol{X} - \boldsymbol{\mu}) (\boldsymbol{X} - \boldsymbol{\mu})^T \Big]$$

$$= \begin{bmatrix} \sigma_{11} & \sigma_{12} & \cdots & \sigma_{1p} \\ \sigma_{21} & \sigma_{22} & \cdots & \sigma_{2p} \\ \vdots & \vdots & \vdots & \vdots \\ \sigma_{p1} & \sigma_{p2} & \cdots & \sigma_{pp} \end{bmatrix},$$
population covariance matrix

$$S = \mathbb{E} \left[ (\boldsymbol{X} - \boldsymbol{\mu}) (\boldsymbol{X} - \boldsymbol{\mu})^T \right] \qquad S = \frac{1}{n-1} \left( \boldsymbol{X} - \mathbf{1} \, \bar{\mathbf{x}}^T \right)^T \left( \boldsymbol{X} - \mathbf{1} \, \bar{\mathbf{x}}^T \right)$$

$$= \underbrace{\begin{bmatrix} \sigma_{11} & \sigma_{12} & \cdots & \sigma_{1p} \\ \sigma_{21} & \sigma_{22} & \cdots & \sigma_{2p} \\ \vdots & \vdots & \vdots & \vdots \\ \sigma_{p1} & \sigma_{p2} & \cdots & \sigma_{pp} \end{bmatrix}}_{\text{population covariance matrix}}, \qquad = \underbrace{\begin{bmatrix} s_{11} & s_{12} & \cdots & s_{1p} \\ s_{21} & s_{22} & \cdots & s_{2p} \\ \vdots & \cdots & \cdots & \vdots \\ s_{p1} & s_{p2} & \cdots & s_{pp} \end{bmatrix}}_{\text{sample covariance matrix}}$$

- Since  $\sigma_{jk} = \sigma_{kj}$  (likewise  $s_{jk} = s_{kj}$ ) for all  $j \neq k \Rightarrow \Sigma$  and Sare symmetric
- $\Sigma$  and S are also non-negative definite  $\Rightarrow$  Any linear combination of the variables has nonnegative variance

 An identity matrix, denoted by I, is a square matrix with 1's along the diagonal and 0's everywhere else. For example,

$$\mathbf{I}_{3\times3} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

 Consider two square matrices A and B of the same dimension. If

$$AB = BA = I$$

then  $\mathbf{B}$  is the inverse of  $\mathbf{A}$ , denoted by  $\mathbf{A}^{-1}$ .

 The inverse matrix is used in multivariate analysis for standardization (e.g., Mahalanobis distance).

- A square matrix Q is orthogonal if
  - $\mathbf{Q}\mathbf{Q}^T = \mathbf{Q}^T\mathbf{Q} = I$
- If  $\mathbf{Q}$  is orthogonal, its rows and columns have unit length (i.e.,  $L_{\mathbf{q}_j} = 1$ ) and are mutually perpendicular (i.e.,  $\mathbf{q}_j^T \mathbf{q}_k = 0$  for any  $j \neq k$ )
- Example:

$$\mathbf{Q} = \frac{1}{3} \begin{bmatrix} 2 & -2 & 1 \\ 1 & 2 & 2 \\ 2 & 1 & -2 \end{bmatrix}$$

 Orthogonal matrices are used in multivariate analysis for rotations and transformations • A square matrix A has an eigenvalue  $\lambda$  with corresponding eigenvector  $\mathbf{x} \neq 0$  if

$$\mathbf{A}\mathbf{x} = \lambda\mathbf{x}$$
.

The eigenvalues of  ${\bf A}$  are the solution to  $|{\bf A}-\lambda I|=0$ 

- A normalized eigenvector is denoted by  ${\bf e}$  with  ${\bf e}^T{\bf e}$  = 1
- A p × p matrix A has p pairs of eigenvalues and eigenvectors

$$\lambda_1, \mathbf{e}_1 \quad \lambda_2, \mathbf{e}_2 \quad \cdots \quad \lambda_p, \mathbf{e}_p$$

 Eigenvalues and eigenvectors will play an important role in DSA 8070. For example, principal components are based on the eigenvalues and eigenvectors of sample covariance matrices

• The spectral decomposition of a  $p \times p$  symmetric matrix **A** is  $\mathbf{A} = \lambda_1 \mathbf{e}_1 \mathbf{e}_1^T + \lambda_2 \mathbf{e}_2 \mathbf{e}_2^T + \dots + \lambda_p \mathbf{e}_p \mathbf{e}_p^T$ . Matrix form:

$$\underbrace{\begin{bmatrix} \mathbf{e}_1 & \mathbf{e}_2 & \cdots & \mathbf{e}_p \end{bmatrix}}_{P} \underbrace{\begin{bmatrix} \lambda_1 & 0 & \cdots & 0 \\ 0 & \lambda_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \lambda_p \end{bmatrix}}_{\Lambda} \underbrace{\begin{bmatrix} \mathbf{e}_1 & \mathbf{e}_2 & \cdots & \mathbf{e}_p \end{bmatrix}^T}_{P^T}$$

• In PCA, let **A** be the covariance matrix; sort  $\lambda_1 \ge \cdots \ge \lambda_p$ : eigenvectors  $\mathbf{e}_j \Rightarrow$  principal components, eigenvalues  $\lambda_j \Rightarrow$  variances



Motivation

Basic Matrix Concer

## **Determinant, Trace, and Rank**



Motivation

Basic Matrix Concepts

- The trace of a  $p \times p$  matrix **A** is the sum of its diagonal elements, i.e.,  $\operatorname{trace}(\mathbf{A}) = \sum_{i=1}^{p} a_{ii}$ .
- The trace of a square, symmetric matrix **A** is the sum of its eigenvalues, i.e.,  $\operatorname{trace}(\mathbf{A}) = \sum_{i=1}^{p} a_{ii} = \sum_{i=1}^{p} \lambda_i$
- The determinant of a square, symmetric matrix A is the product of its eigenvalues, i.e.,  $|\mathbf{A}| = \prod_{i=1}^{p} \lambda_i$
- The rank of a matrix A is the dimension of the vector space spanned by its rows (or equivalently, its columns). It is equal to the number of nonzero eigenvalues of A

# **Determinant, Trace, and Rank: Applications in Multivariate Analysis**



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Basic Matrix Concepts

- The determinant of the covariance matrix is used to measure the generalized variance of a multivariate distribution.
- The trace of the covariance matrix represents the total variance across all variables.
- The rank of a data matrix (or covariance matrix) indicates the effective dimensionality of the data, revealing linear dependence among variables

- For a  $p \times p$  symmetric matrix  $\mathbf{A}$  and a vector  $\mathbf{x} = \begin{bmatrix} x_1 & x_2 & \cdots & x_p \end{bmatrix}^T$  the quantity  $\mathbf{x}^T \mathbf{A} \mathbf{x} = \sum_{i=1}^p \sum_{j=1}^p a_{ij} x_i x_j$  is called a quadratic form
- If  $\mathbf{x}^T \mathbf{A} \mathbf{x} \ge 0$  for any vector  $\mathbf{x}$ , both  $\mathbf{A}$  and the quadratic form are said to be non-negative definite
  - $\Rightarrow$  all the eigenvalues of  $\mathbf{A}$  are non-negative
- If  $\mathbf{x}^T \mathbf{A} \mathbf{x} > 0$  for any vector  $\mathbf{x} \neq \mathbf{0}$ , both  $\mathbf{A}$  and the quadratic form are said to be positive definite
  - ⇒ all the eigenvalues of A are positive
- In multivariate analysis, the covariance matrix must be positive definite to ensure valid Mahalanobis distances, PCA, and multivariate normal distributions

• For  $\mathbf{x} = \begin{bmatrix} x_1 & x_2 & \cdots & x_p \end{bmatrix}^T$  and a  $p \times p$  positive definite matrix  $\mathbf{A}$ .

$$d^2 = \mathbf{x}^T \mathbf{A} \mathbf{x}$$

when  $\mathbf{x}\neq 0$ . Thus, a positive definite quadratic form can be interpreted as a squared distance of  $\mathbf{x}$  from the origin and vice versa

 $\bullet$  The squared distance from  ${\bf x}$  to a fixed point  $\mu$  is given by the quadratic form

$$(\mathbf{x} - \boldsymbol{\mu})^T A (\mathbf{x} - \boldsymbol{\mu})$$

 In multivariate analysis, such quadratic forms are used to define the Mahalanobis distance, construct confidence ellipsoids, and perform discriminant analysis  We can interpret distance in terms of eigenvalues and eigenvectors of A. any point x at constant distance c from the origin satisfies

$$\mathbf{x}^T \mathbf{A} \mathbf{x} = \mathbf{x}^T \left( \sum_{j=1}^p \lambda_j \mathbf{e}_j \mathbf{e}_j^T \right) \mathbf{x} = \sum_{j=1}^p \lambda_j (\mathbf{x}^T \mathbf{e}_j)^2 = c$$

- Note that the point  $\mathbf{x} = c\lambda_1^{-\frac{1}{2}}\mathbf{e}_1$  is at a distance c (in the direction of e1) from the origin because it satisfies  $\mathbf{x}^T \mathbf{A} \mathbf{x} = c^2$
- The same is true for points  $\mathbf{x} = c\lambda_i^{-\frac{1}{2}}\mathbf{e}_i, j = 2, \dots, p$ . Thus, all points at distance c lie on an ellipsoid with axes in the directions of the eigenvectors and with lengths proportional to  $\lambda_i^{-\frac{1}{2}}$



$$\mathbf{A} = \sum_{j=1}^{p} \lambda_j \mathbf{e}_j \mathbf{e}_j^T = \mathbf{P} \Lambda \mathbf{P}^T,$$

with  $\Lambda_{p \times p} = \mathrm{diag}(\lambda_j)$ , all  $\lambda_j > 0$ , and  $\mathbf{P}_{p \times p} = \begin{bmatrix} \mathbf{e}_1 & \mathbf{e}_2 & \cdots & \mathbf{e}_p \end{bmatrix}$  an orthonormal matrix of eigenvectors. Then

$$\mathbf{A}^{-1} = \mathbf{P}\Lambda^{-1}\mathbf{P}^T = \sum_{j=1}^p \frac{1}{\lambda_j} \mathbf{e}_j \mathbf{e}_j^T$$

ullet With  $\Lambda^{rac{1}{2}}=\mathrm{diag}(\lambda_j^{rac{1}{2}}),$  a square-root matrix is

$$\mathbf{A}^{\frac{1}{2}} = \mathbf{P}\Lambda^{\frac{1}{2}}\mathbf{P}^{T} = \sum_{j=1}^{p} \sqrt{\lambda_{j}}\mathbf{e}_{j}\mathbf{e}_{j}^{T}$$



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Partitioned mean vector:

$$\mathbb{E}[X] = \mathbb{E}\begin{bmatrix} X_1 \\ X_2 \end{bmatrix} = \begin{bmatrix} \mathbb{E}[X_1] \\ \mathbb{E}[X_2] \end{bmatrix} = \begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix}$$

Partitioned covariance matrix:

$$\Sigma = \begin{bmatrix} \operatorname{Var}(\boldsymbol{X}_1) & \operatorname{Cov}(\boldsymbol{X}_1, \boldsymbol{X}_2) \\ \operatorname{Cov}(\boldsymbol{X}_2, \boldsymbol{X}_1) & \operatorname{Var}(\boldsymbol{X}_2) \end{bmatrix} = \begin{bmatrix} \underline{\boldsymbol{\Sigma}_{11}} & \underline{\boldsymbol{\Sigma}_{12}} \\ \underline{\boldsymbol{\gamma}_{\times q}} & \underline{\boldsymbol{\gamma}_{\times (p-q)}} \\ \underline{\boldsymbol{\Sigma}_{21}} & \underline{\boldsymbol{\Sigma}_{22}} \\ \underline{\boldsymbol{\gamma}_{-q} \times \boldsymbol{\gamma}_{\times (p-q)}} \end{bmatrix}$$

- Data as a matrix X; each row is an observation, each column a variable
- Sample mean vector and covariance matrix are matrix expressions
- Eigenvalues/eigenvectors ⇒ PCA, factor analysis, canonical correlation
- Quadratic forms ⇒ Mahalanobis distance, hypothesis testina

In the next lecture, we will learn:

- Multivariate Normal Distribution
- Copula Models and Non-parametric Density Methods