

# Lecture 5

## Time Series Regression

Reading: Forecasting, Time Series, and Regression (4th edition) by Bowerman, O'Connell, and Koehler: Chapter 6

*MATH 4070: Regression and Time-Series Analysis*

Time Series Data

Trend Estimation

Estimating Seasonality

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# Agenda

Time Series Data

Trend Estimation

Estimating Seasonality

1 Time Series Data

2 Trend Estimation

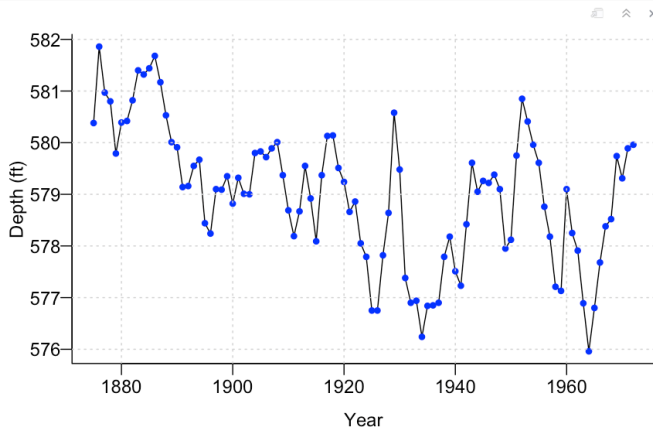
3 Estimating Seasonality

## Level of Lake Huron 1875–1972

Annual measurements of the level of Lake Huron in feet.

[Source: [Brockwell & Davis, 1991](#)]

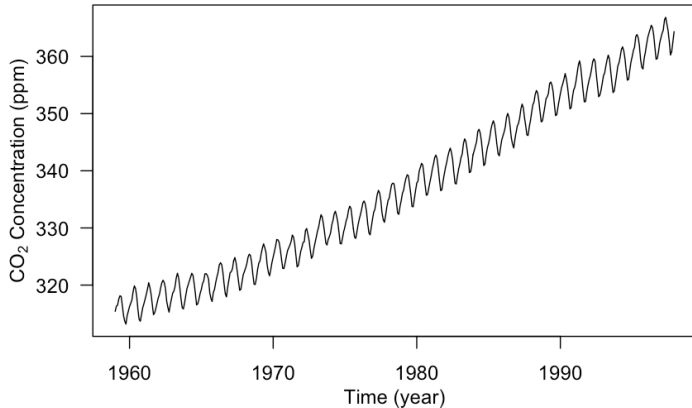
```
```{r}
par(mar = c(3.2, 3.2, 0.5, 0.5), mgp = c(2, 0.5, 0), bty = "L")
data(LakeHuron)
plot(LakeHuron, ylab = "Depth (ft)", xlab = "Year", las = 1)
points(LakeHuron, cex = 0.8, col = "blue", pch = 16)
grid()
```
```




# Mauna Loa Monthly Atmospheric CO<sub>2</sub> Concentration

[Source: Keeling & Whorf, Scripps Institution of Oceanography]

```
```{r}
data(co2)
par(mar = c(3.8, 4, 0.8, 0.6))
plot(co2, las = 1, xlab = "", ylab = "")
mtext("Time (year)", side = 1, line = 2)
mtext(expression(paste("CO"[2], " Concentration (ppm)")), side = 2, line = 2.5)
```
```



- A **time series** is a collection of observations  $\{y_t, t \in T\}$  taken sequentially in time ( $t$ ) with the index set  $T$ 
  - $T = \{0, 1, 2, \dots, T\} \subset \mathbb{Z} \Rightarrow$  **discrete-time time series**
  - $T = [0, T] \subset \mathbb{R} \Rightarrow$  **continuous-time time series**
- A discrete-time time series might be intrinsically discrete or might arise from a underlying continuous-time time series via
  - sampling (e.g., instantaneous wind speed)
  - aggregation (e.g., daily accumulated precipitation amount)
  - extrema (e.g., daily maximum temperature)
- We will focus on dealing with **discrete-time real-valued** ( $Y_t \in \mathbb{R}$ ) **time series** in this course

- Start with a **time series plot**, i.e., to plot  $y_t$  versus  $t$  
- Look at the following:
  - Are there abrupt changes?
  - Are there “outliers”?
  - Is there a need to transform the data?
- Examine the **trend**, **seasonal components**, and the “noise” term

## ● Trends ( $\mu_t$ )

- $\mu_t$  represents continuous changes, usually in the mean, over longer time scales. *"The essential idea of trend is that it shall be smooth."* - [Kendall, 1973]
- The form of the trend is typically unknown and needs to be estimated. Removing the trend yields a **detrended** series

## ● Seasonal or Periodic Components ( $s_t$ )

- $s_t$  repeats consistently over time, i.e.,  $s_t = s_{t+kd}$
- The form and period  $d$  of the seasonal component must be estimated to **deseasonalize** the series.

## ● The "Noise" Process ( $\eta_t$ )

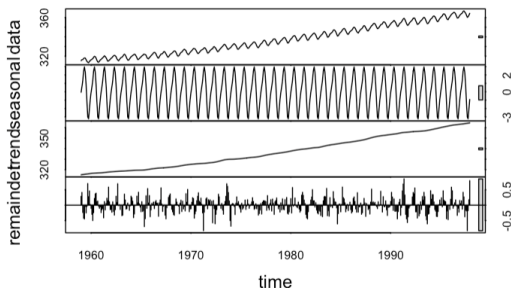
- $\eta_t$  represents the component that is neither trend nor seasonality
- Focus on finding plausible statistical models for this process

# Combining Trend, Seasonality, and Noise Together

There are two commonly used approaches

- Additive model:

$$Y_t = \mu_t + s_t + \eta_t, \quad t = 1, \dots, T$$



- Multiplicative model:

$$Y_t = \mu_t s_t \eta_t, \quad t = 1, \dots, T$$

If all  $\{y_t\}$  are positive then we obtain the additive model by taking logarithms:

$$\log Y_t = \log \mu_t + \log s_t + \log \eta_t, \quad t = 1, \dots, T$$

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# The (Additive) Decomposition Model

- The additive model for a time series  $\{Y_t\}$  is

$$Y_t = \mu_t + s_t + \eta_t,$$

where

- $\mu_t$  is the **trend** component
- $s_t$  is the **seasonal** component
- $\eta_t$  is the **random (noise)** component with  $\mathbb{E}(\eta_t) = 0$
- Standard procedure:
  - (1) Estimate/remove the trend and seasonal components
  - (2) Analyze the remainder, the residuals  $\hat{\eta}_t = y_t - \hat{\mu}_t - \hat{s}_t$
- We will focus on (1) for this week

Assuming  $s_t = 0$  (i.e., there is no “seasonal” variation), we have

$$Y_t = \mu_t + \eta_t,$$

with  $\mathbb{E}(\eta_t) = 0$

Methods for **estimating trends**

- Least squares regression
- Smoothing

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- The additive nonseasonal time series model for  $\{Y_t\}$  is

$$Y_t = \mu_t + \eta_t,$$

where the trend is assumed to be a linear combination of known covariate series  $\{x_{it}\}_{i=1}^p$

$$\mu_t = \beta_0 + \sum_{i=1}^p \beta_i x_{it}.$$

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- Here we want to **estimate**  $\beta = (\beta_0, \beta_1, \dots, \beta_p)^T$  from the data  $\{y_t, \{x_{it}\}_{i=1}^p\}_{t=1}^T$

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- You're likely quite familiar with this formulation already  $\Rightarrow$  **Regression Analysis**

## Some Examples of Covariate Series $\{x_{it}\}$

- **Simple linear regression model:**

$$\mu_t = \beta_0 + \beta_1 x_t,$$

for example, the temperature trend at time  $t$  could be a constant ( $\beta_0$ ) plus a multiple ( $\beta_1$ ) of the carbon dioxide level at time  $t$  ( $x_t$ )

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- **Polynomial regression model:**

$$\mu_t = \beta_0 + \sum_{i=1}^p \beta_i t^i$$

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- **Polynomial regression model:**

$$\mu_t = \beta_0 + \sum_{i=1}^p \beta_i t^i$$

- **Change point model:**

$$\mu_t = \begin{cases} \beta_0 & \text{if } t \leq t^*; \\ \beta_0 + \beta_1 & \text{if } t \geq t^*. \end{cases}$$



- Like in the linear regression setting, we can estimate the parameters via **ordinary least squares (OLS)**
- Specifically, we minimize the following objective function:

$$\ell_{ols} = \sum_{t=1}^T (y_t - \beta_0 - \sum_{k=1}^p x_{kt} \beta_k)^2.$$

- The estimates  $\beta = (\beta_0, \beta_1, \dots, \beta_p)^T$  minimizing the above objective function are called the **OLS estimates of  $\beta$**   $\Rightarrow$  they are easiest to express in **matrix form**

- Matrix representation:

$$\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\eta},$$

$$\text{where } \mathbf{Y} = \begin{bmatrix} Y_1 \\ \vdots \\ Y_T \end{bmatrix}, \mathbf{X} = \begin{bmatrix} 1 & x_{11} & x_{12} & \cdots & x_{1p} \\ 1 & x_{21} & x_{22} & \cdots & x_{2p} \\ 1 & \vdots & \cdots & \cdots & \vdots \\ 1 & x_{T1} & x_{T2} & \cdots & x_{Tp} \end{bmatrix}, \text{ and}$$

$$\boldsymbol{\eta} = \begin{bmatrix} \eta_1 \\ \vdots \\ \eta_T \end{bmatrix}$$

- Assuming  $\mathbf{X}^T \mathbf{X}$  is **invertible**, the OLS estimate of  $\boldsymbol{\beta}$  can be shown to be

$$\hat{\boldsymbol{\beta}} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{Y},$$

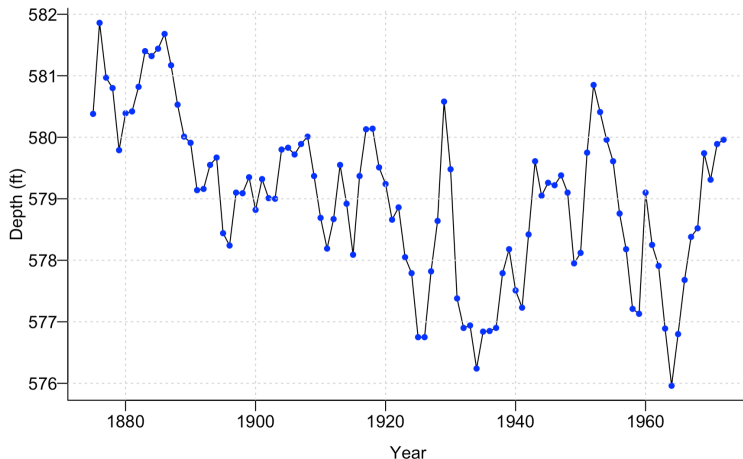
and the `lm` function in R calculates OLS estimates

Time Series Data

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Estimating Seasonality

# Lake Huron Example Revisited



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Let's **assume** there is a **linear trend in time**  $\Rightarrow$  we need to estimate the **intercept**  $\beta_0$  and **slope**  $\beta_1$

Call:

```
lm(formula = LakeHuron ~ yr)
```

Residuals:

| Min      | 1Q       | Median  | 3Q      | Max     |
|----------|----------|---------|---------|---------|
| -2.50997 | -0.72726 | 0.00083 | 0.74402 | 2.53565 |

Coefficients:

|             | Estimate   | Std. Error | t value | Pr(> t )     |
|-------------|------------|------------|---------|--------------|
| (Intercept) | 625.554918 | 7.764293   | 80.568  | < 2e-16 ***  |
| yr          | -0.024201  | 0.004036   | -5.996  | 3.55e-08 *** |

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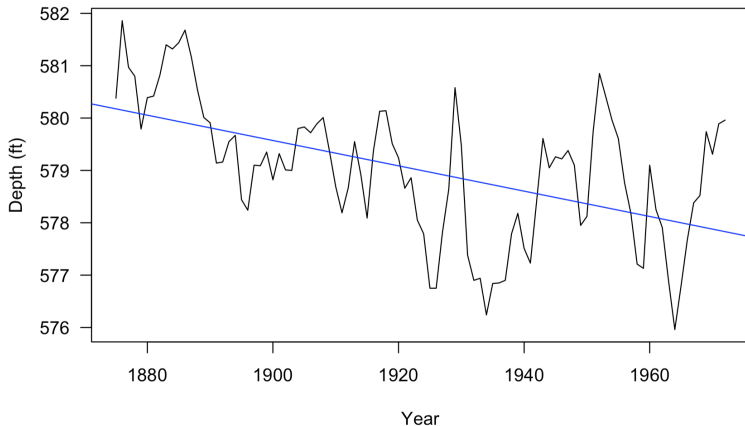
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Residual standard error: 1.13 on 96 degrees of freedom

Multiple R-squared: 0.2725, Adjusted R-squared: 0.2649

F-statistic: 35.95 on 1 and 96 DF, p-value: 3.545e-08

## Plot the (Estimated) Trend $\hat{\mu}_t = \hat{\beta}_0 + \hat{\beta}_1 t$



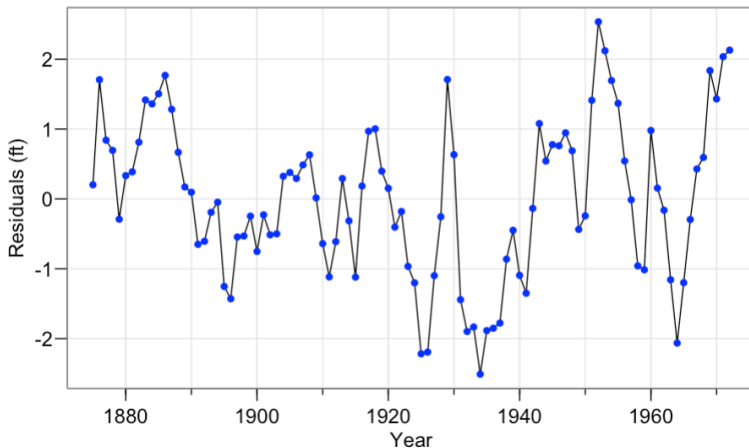
$\hat{\beta}_1 = -0.0242$  (ft/yr)  $\Rightarrow$  there seems to be a decreasing trend

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## Plot the Residuals $\{\hat{\eta}_t = y_t - \hat{\beta}_0 - \hat{\beta}_1 t\}$



$\{\hat{\eta}_t\}$  seems to exhibit some temporal dependence structure, should we worry about the results we have (recall OLS makes an i.i.d. assumption)?

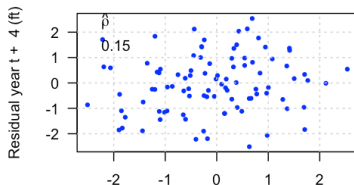
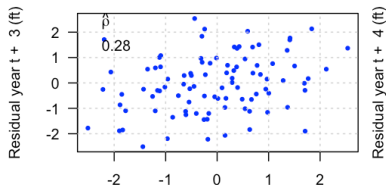
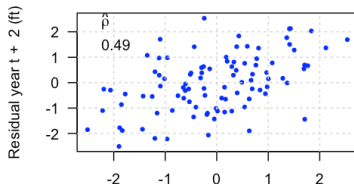
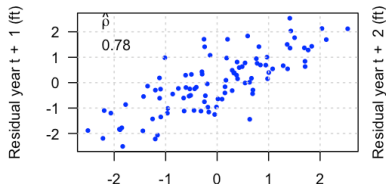
Time Series Data

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## Exploring the Dependence Structure of “Noise” $\{\eta_t\}$

$\{\eta_t\}$  exhibit a temporal dependence structure, meaning that the nearby (in time) values tend to be more alike than those that are far apart. To observe this, let's create a few time lag plots



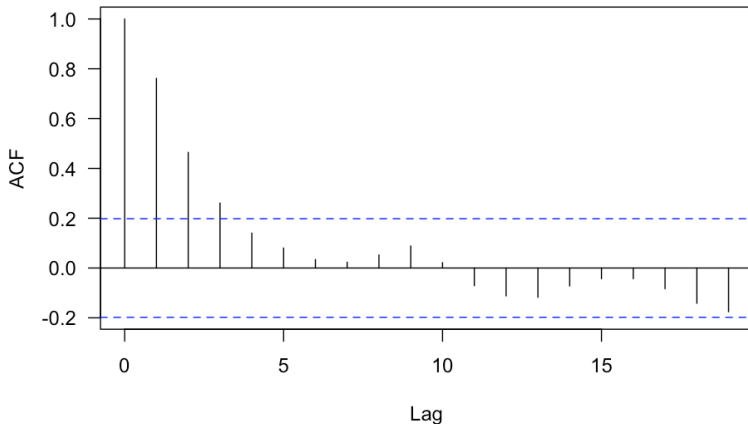
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## Further Exploration of the Temporal Dependence Structure

Let's plot the correlation as a function of the time lag



We will learn how to use this information to suggest an appropriate model

Time Series Data

Trend Estimation

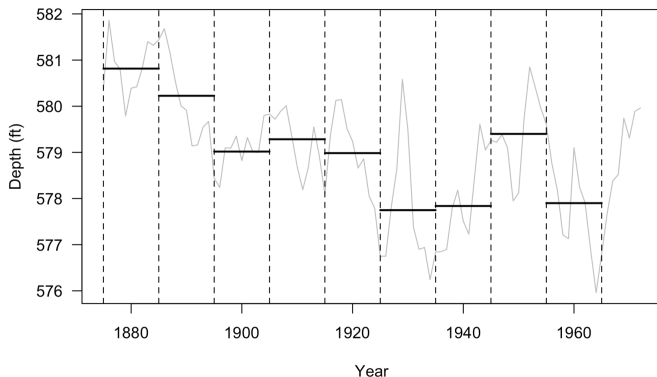
Estimating Seasonality



## Smoothing or Local Averaging

In some cases, we may relax the trend assumption using a 'non-parametric' approach.

We divide the time series into small blocks (each with 10 years of data) and average each block.

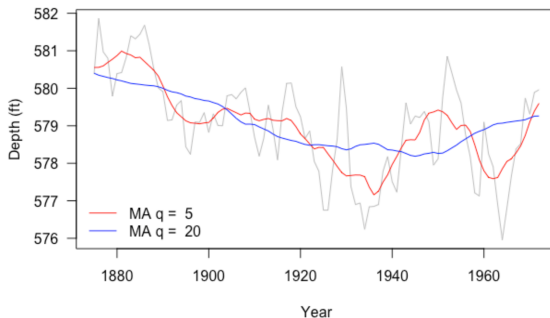


Doing this gives a very rough estimate of the trend. **Can we do better?**

## Moving Average Smoother

A **moving average smoother** estimates the trend at time  $t$  by averaging the current observation and the  $q$  nearest observations from either side. That is

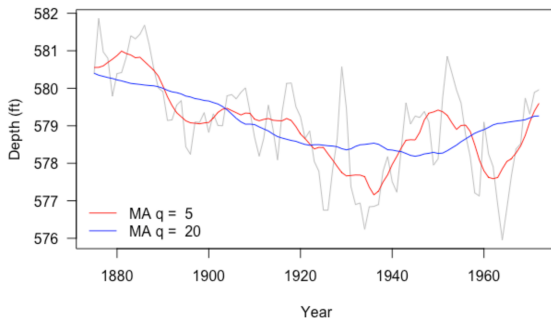
$$\hat{\mu}_t = \frac{1}{2q+1} \sum_{j=-q}^q y_{t-j}$$



## Moving Average Smoother

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$$\hat{\mu}_t = \frac{1}{2q+1} \sum_{j=-q}^q y_{t-j}$$



$q$  is the “smoothing” parameter, which controls the smoothness of the estimated trend  $\hat{\mu}_t$

- Let  $\alpha \in [0, 1]$  be some fixed constant, defined

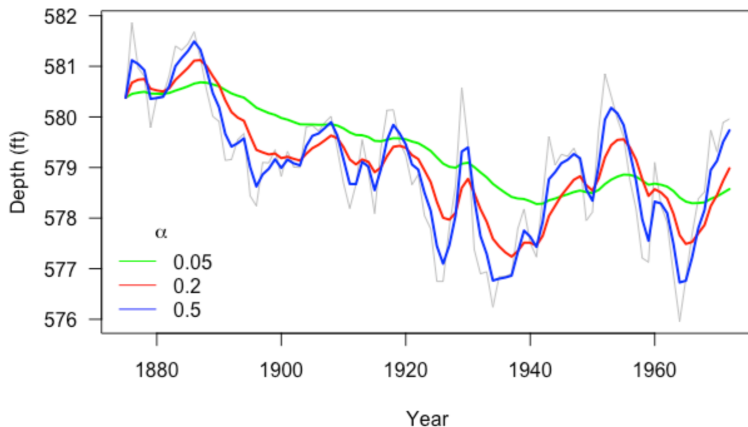
$$\hat{\mu}_t = \begin{cases} Y_1 & \text{if } t = 1; \\ \alpha Y_t + (1 - \alpha)\hat{\mu}_{t-1} & t = 2, \dots, T. \end{cases}$$

- For  $t = 2, \dots, T$ , we can rewrite  $\hat{\mu}_t$  as

$$\sum_{j=0}^{t-2} \alpha(1 - \alpha)^j Y_{t-j} + (1 - \alpha)^{t-1} Y_1.$$

$\Rightarrow$  it is a one-sided moving average filter with **exponentially decreasing weights**. One can alter  $\alpha$  to control the amounts of smoothing (see next slide for an example)

## $\alpha$ is the Smoothing Parameter for Exponential Smoothing



The smaller the  $\alpha$ , the smoother the resulting trend

Let's consider a situation where a time series consists of only a seasonal component (assuming the trend has been estimated/removed). In this scenario,

$$Y_t = s_t + \eta_t,$$

with  $\{s_t\}$  having period  $d$  (i.e.,  $s_{t+jd} = s_t$  for all integers  $j$  and  $t$ ),  $\sum_{t=1}^d s_t = 0$  and  $\mathbb{E}(\eta_t) = 0$

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Two methods to **estimate**  $\{s_t\}$

- Harmonic regression
- Seasonal mean model

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The simplest case is the **cosine wave**

$$\begin{aligned}s_t &= A \cos(2\pi\omega t + \phi) \\ &= \alpha_1 \cos(2\pi\omega t) + \alpha_2 \sin(2\pi\omega t),\end{aligned}$$

where

- $A$  is **amplitude**
- $\omega$  is **frequency**, in cycles per time unit
- $\phi$  is **phase**, determining the start point of the cosine function
- $\alpha_1 = A \cos(\phi)$ ,  $\alpha_2 = -A \sin(\phi)$ ,  $A = \sqrt{\alpha_1^2 + \alpha_2^2}$ ,  $\phi = \tan^{-1} \frac{-\alpha_2}{\alpha_1}$

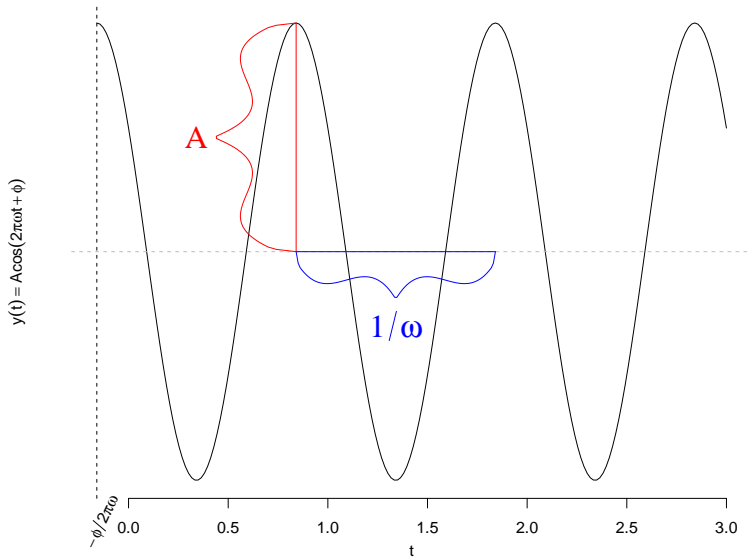
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# Graphical Illustration of the Cosine Wave



- A harmonic regression model has the form

$$s_t = \sum_{j=1}^k A_j \cos(2\pi\omega_j + \phi_j).$$

For each  $j = 1, \dots, k$ :

- $A_j > 0$  is the amplitude of the  $j$ -th cosine wave
  - $\omega_j$  controls the frequency of the  $j$ -th cosine wave (how often waves repeats)
  - $\phi_j \in [-\pi, \pi]$  is the phase of the  $j$ -th wave (where it starts)
- The above can be expressed as

$$\sum_{j=1}^k (\beta_{1j} \cos(2\pi f_j) + \beta_{2j} \sin(2\pi f_j)),$$

where  $\beta_{1j} = A_j \cos(\phi_j)$  and  $\beta_{2j} = A_j \sin(\phi_j) \Rightarrow$  **if  $\{\omega_j\}_{j=1}^k$  are known, we can use regression techniques to estimate the parameters  $\{\beta_{1j}, \beta_{2j}\}_{j=1}^k$**

# Monthly Average Temperature in Dubuque, IA [Cryer & Chan, 2008]

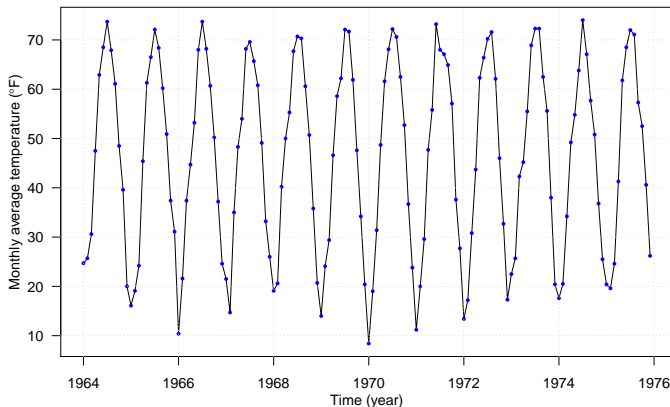
Time Series  
Regression



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Let's assume that there is no trend in this time series. In this context, our goal is to estimate  $s_t$ , the seasonal component.

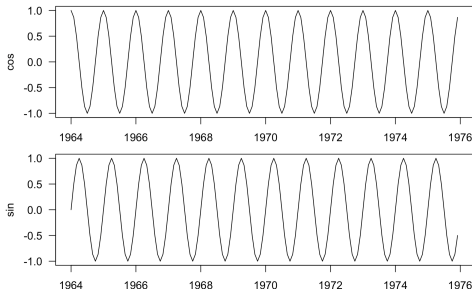
# Use a Harmonic Regression to Model Annual Cycles

**Model:**  $s_t = \beta_0 + \beta_1 \cos(2\pi t) + \beta_2 \sin(2\pi t)$

⇒ annual cycles can be modeled by a linear combination of **cos** and **sin** with 1-year period.

In R, we can easily create these harmonics using the `harmonic` function in the `TSA` package

```
harmonics <- harmonic(tempdub, 1)
```



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```
```{r}
harReg <- lm(tempdub ~ harmonics)
summary(harReg)
```

Call:

```
lm(formula = tempdub ~ harmonics)
```

Residuals:

Min	1Q	Median	3Q	Max
-11.1580	-2.2756	-0.1457	2.3754	11.2671

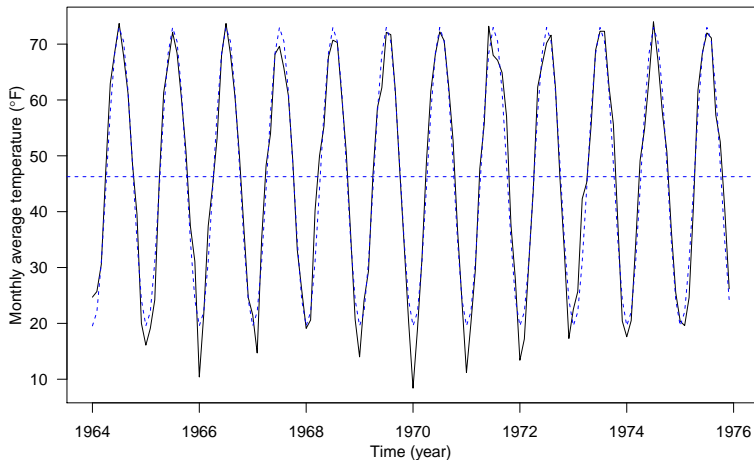
Coefficients:

	Estimate	Std. Error	t value	Pr(> t )
(Intercept)	46.2660	0.3088	149.816	< 2e-16 ***
harmonicscos(2*pi*t)	-26.7079	0.4367	-61.154	< 2e-16 ***
harmonicssin(2*pi*t)	-2.1697	0.4367	-4.968	1.93e-06 ***

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# The Harmonic Regression Model Fit



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- **Harmonics regression** assumes the seasonal pattern has a regular shape, i.e., the height of the peaks is the same as the depth of the troughs
- A less restrictive approach is to model  $\{s_t\}$  as

$$s_t = \begin{cases} \beta_1 & \text{for } t = 1, 1 + d, 1 + 2d, \dots & ; \\ \beta_2 & \text{for } t = 2, 2 + d, 2 + 2d, \dots & ; \\ \vdots & \vdots & ; \\ \beta_d & \text{for } t = d, 2d, 3d, \dots & . \end{cases}$$

- This is the **seasonal means** model, the parameters  $(\beta_1, \beta_2, \dots, \beta_d)^T$  can be estimated under the linear model framework (think about ANOVA)

## R Output

Call:

```
lm(formula = tempdub ~ month - 1)
```

Residuals:

Min	1Q	Median	3Q	Max
-8.2750	-2.2479	0.1125	1.8896	9.8250

Coefficients:

	Estimate	Std. Error	t value	Pr(> t )
monthJanuary	16.608	0.987	16.83	<2e-16 ***
monthFebruary	20.650	0.987	20.92	<2e-16 ***
monthMarch	32.475	0.987	32.90	<2e-16 ***
monthApril	46.525	0.987	47.14	<2e-16 ***
monthMay	58.092	0.987	58.86	<2e-16 ***
monthJune	67.500	0.987	68.39	<2e-16 ***
monthJuly	71.717	0.987	72.66	<2e-16 ***
monthAugust	69.333	0.987	70.25	<2e-16 ***
monthSeptember	61.025	0.987	61.83	<2e-16 ***
monthOctober	50.975	0.987	51.65	<2e-16 ***
monthNovember	36.650	0.987	37.13	<2e-16 ***
monthDecember	23.642	0.987	23.95	<2e-16 ***

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# The Seasonal Means Model Fit

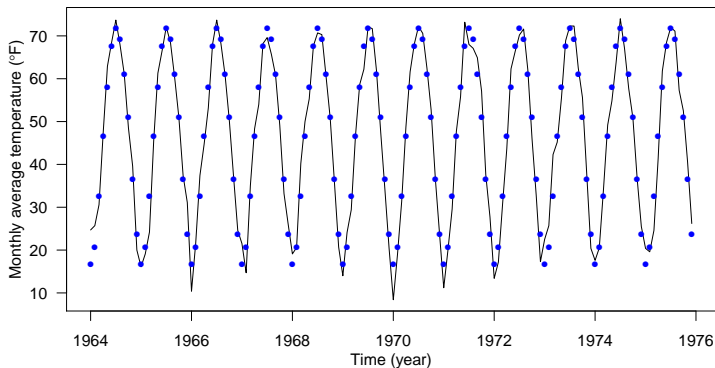
Time Series  
Regression



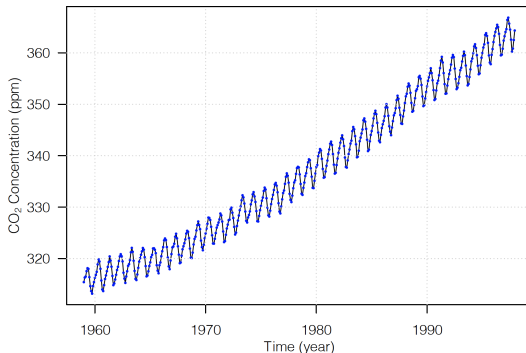
Time Series Data

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# Estimating the Trend and Seasonal variation Together



Let's perform a regression analysis to model both  $\mu_t$  (assuming a linear time trend) and  $s_t$  (using  $\cos$  and  $\sin$ )

```
```{r}
time <- as.numeric(time(co2))
harmonics <- harmonic(co2, 1)

lm_trendSeason <- lm(co2 ~ time + harmonics)
summary(lm_trendSeason)
```

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# The Regression Fit

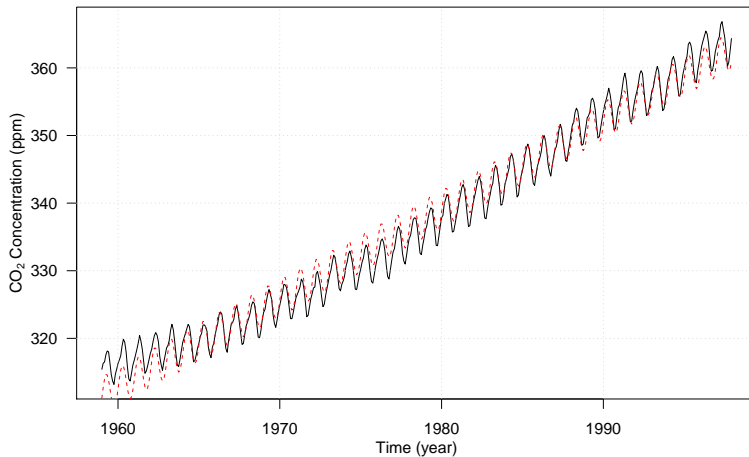
Time Series  
Regression



Time Series Data

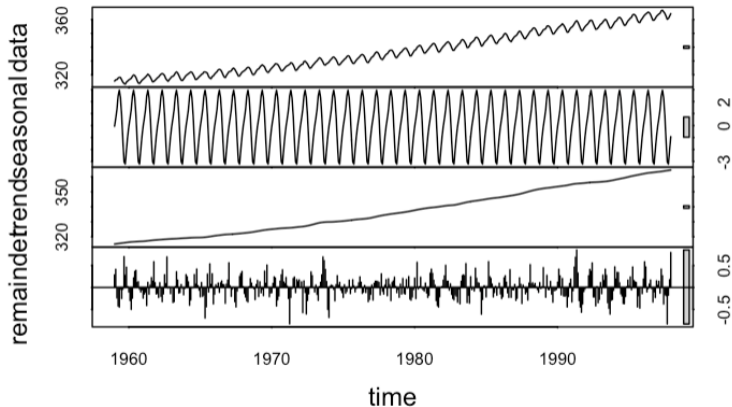
Trend Estimation

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# Seasonal and Trend decomposition using Loess [Cleveland, et. al., 1990]

```
``{r}  
# Seasonal and Trend decomposition using Loess (STL)  
par(mar = c(4, 3.6, 0.8, 0.6))  
stl <- stl(co2, s.window = "periodic")  
plot(stl, las = 1)  
``
```



Time Series Data

Trend Estimation

Estimating Seasonality

These slides cover:

- Main features of a time series: trend, seasonality, and “noise”
- Estimating trends using multiple linear regression and “nonparametric” smoothing
- Estimating seasonality using harmonic regression and the seasonal mean model

- Visualizing time series data: `plot` (for ts objects), `ts.plot`, `tsplot` (`astsa` package)
- Fitting time series regression: `lm`, `harmonic` (`TSA` package) for creating harmonic predictors, `filter` for smoothing
- Seasonal and trend decomposition: `stl`