MATH 8090: Stationary processes

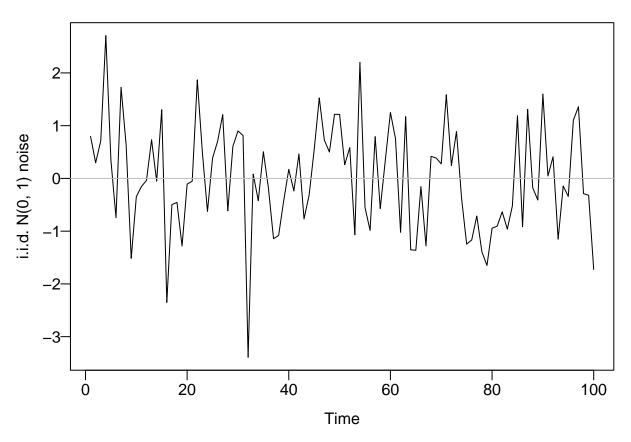
Whitney Huang, Clemson University

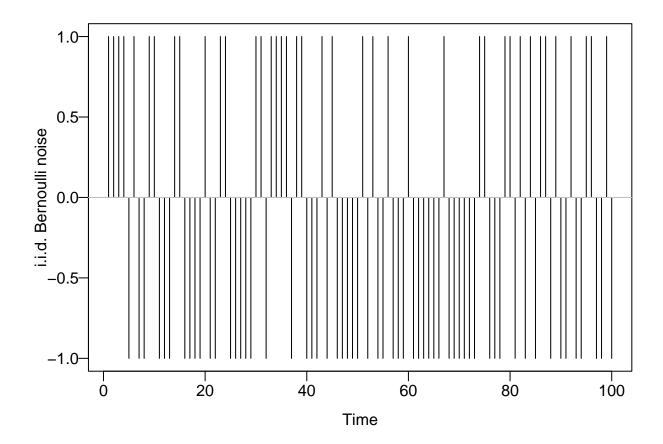
9/5-9/7/2023

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Examples of i.i.d. Noise



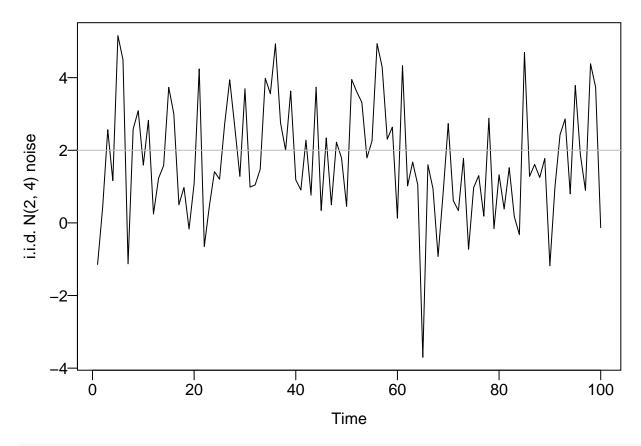


Examples realizations of white noise processes

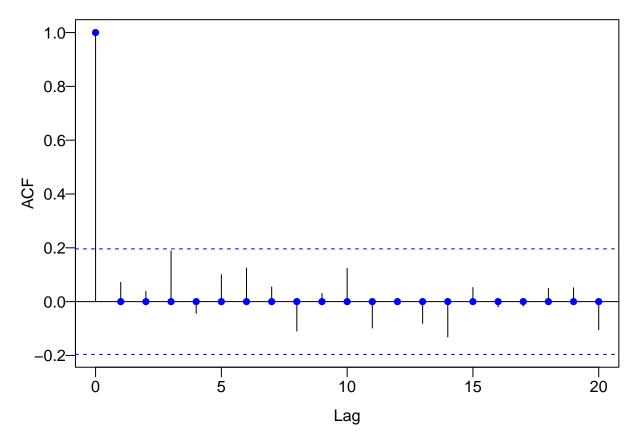
Note: here we do not require the sequence follow the same distribution.

```
T = 100
t <- 1:T
WN1 <- rnorm(n = T, mean = 2, sd = 2)

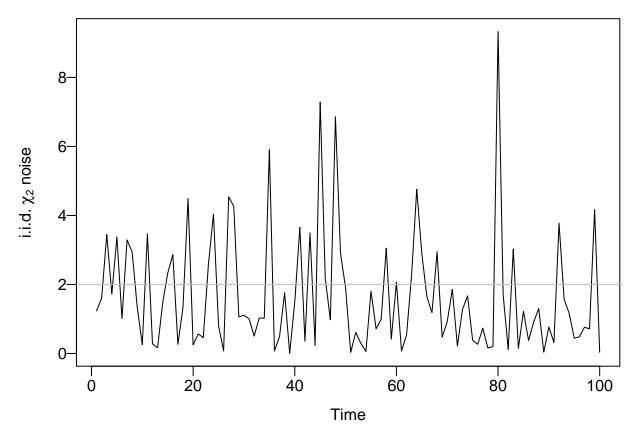
par(las = 1, mgp = c(2, 0.5, 0), mar = c(3.6, 3.6, 0.8, 0.6))
plot(t, WN1, type = "l", xlab = "Time", ylab = "i.i.d. N(2, 4) noise")
abline(h = 2, col = "gray")</pre>
```



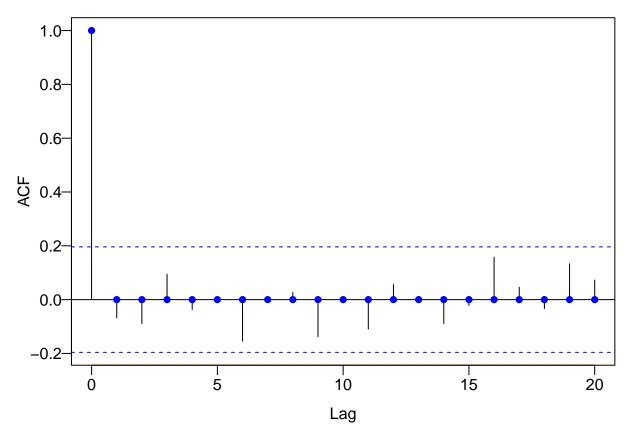
```
acf(WN1)
points(0:20, c(1, rep(0, 20)), pch = 16, col = "blue")
```



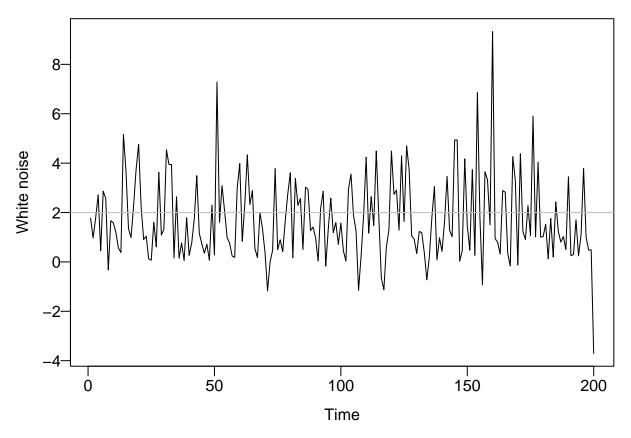
```
WN2 <- rchisq(n = T, df = 2)
plot(t, WN2, type = "l", xlab = "Time", ylab = expression(paste("i.i.d. ", chi[2], " noise")))
abline(h = 2, col = "gray")</pre>
```



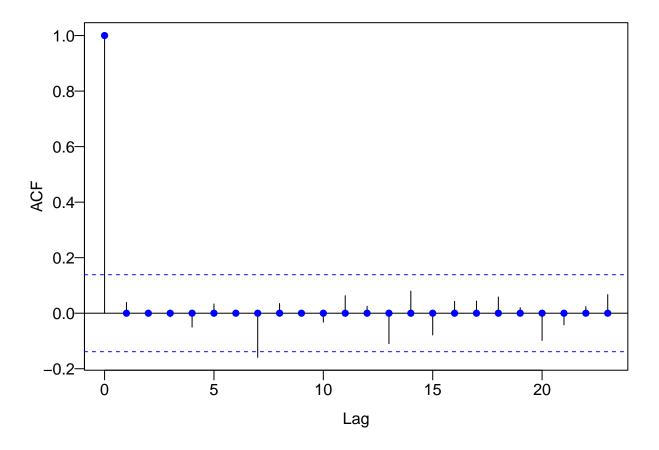
```
acf(WN2)
points(0:20, c(1, rep(0, 20)), pch = 16, col = "blue")
```



```
WN3 <- c(WN1, WN2)[sample(1:200)]
plot(1:200, WN3, type = "1", xlab = "Time", ylab = expression(paste("White noise")))
abline(h = 2, col = "gray")</pre>
```



```
acf(WN3)
points(0:23, c(1, rep(0, 23)), pch = 16, col = "blue")
```



MA(1) processes

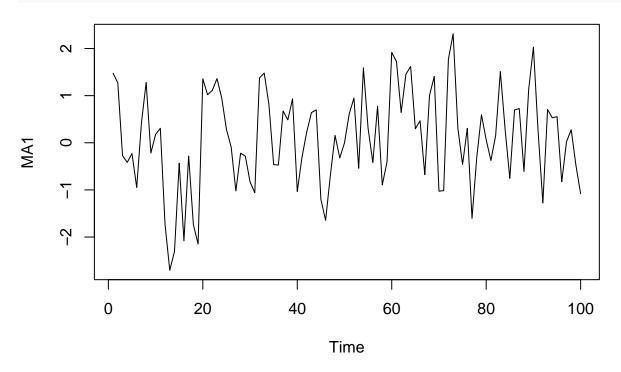
$$\eta_t = Z_t + \theta Z_{t-1},$$

where $Z \sim WN(0, \sigma^2)$.

```
library(animation)
T = 100
t <- 1:T
z <- rnorm(110)
theta <-c(0.25, 1, -1, -0.25)
saveLatex({
  par(las = 1, mgp = c(2, 0.5, 0), mar = c(3.6, 3.6, 0.8, 0.6),
      mfrow = c(2, 1)
  for (i in 1:4){
    MA1 \leftarrow filter(z, sides = 1, c(1, theta[i]))[-(1:10)]
    plot(t, MA1, type = "l", xlab = "Time", ylab = "MA(1)")
    abline(h = 0, col = "gray")
    legend("topleft", legend = theta[i], title = expression(theta),
           bty = "n")
    acf(MA1)
    points(0:20, c(1, theta[i] / (1 + theta[i]^2), rep(0, 19)),
           pch = 16, col = "blue")
  }
}, img.name = "MA1", ani.opts = "controls, width=0.95\\textwidth",
latex.filename = ifelse(interactive(), "MA1_realizations.tex", ""),
nmax = 4, ani.dev = "pdf", ani.type = "pdf", ani.width = 8,
```

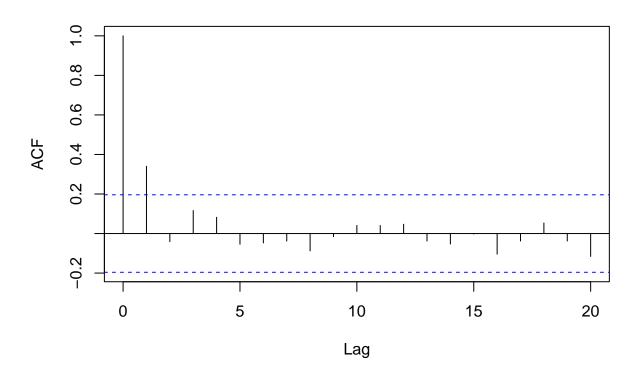
```
## \documentclass{article}
  \usepackage[papersize={8in,6in},margin=0.1in]{geometry}
##
               \usepackage{animate}
##
               \begin{document}
##
               \begin{figure}
##
               \begin{center}
               ##
               \end{center}
##
               \end{figure}
##
               \end{document}
##
##
```

```
##another way to simulate MA(1)
MA1 <- arima.sim(n = 100, list(ma = c(0.5)))
plot(MA1)</pre>
```



acf(MA1)

Series MA1



AR(1) processes

$$\eta_t = \phi \eta_{t-1} + Z_t,$$

where $|\rho| < 1$ is a constant and η_s and Z_t are uncorrelated for all $s < t \Rightarrow$ future noise is uncorrelated with the current value.

```
rho <- c(0.25, 0.9, -0.5)
saveLatex({
  par(las = 1, mgp = c(2, 0.5, 0), mar = c(3.6, 3.6, 0.8, 0.6),
      mfrow = c(2, 1)
 for (i in 1:3){
   AR1 \leftarrow arima.sim(n = 100, list(ar = c(rho[i])))
   plot(t, AR1, type = "l", xlab = "Time",
         ylab = paste("AR(1), rho = ", rho[i]))
    abline(h = 0, col = "gray")
   acf(AR1)
   points(0:20, c(1, rho[i]^(1:20)), pch = 16, col = "blue")
 }
}, img.name = "AR1", ani.opts = "controls, width=0.95\\textwidth",
latex.filename = ifelse(interactive(), "AR1_realizations.tex", ""),
nmax = 3, ani.dev = "pdf", ani.type = "pdf", ani.width = 8,
ani.height = 6,documentclass = paste("\\documentclass{article}",
                                      "\\usepackage[papersize={8in,6in},margin=0.1in]{geometry}",
                                      sep = "\n"))
```

- ## \documentclass{article}
- ## \usepackage[papersize={8in,6in},margin=0.1in]{geometry}

```
##
                    \usepackage{animate}
##
                    \begin{document}
##
                    \begin{figure}
                    \begin{center}
##
##
                    \animategraphics[controls, width=0.95\textwidth]{1}{AR1}{0}{2}
                    \end{center}
##
##
                    \end{figure}
                    \end{document}
##
##
```

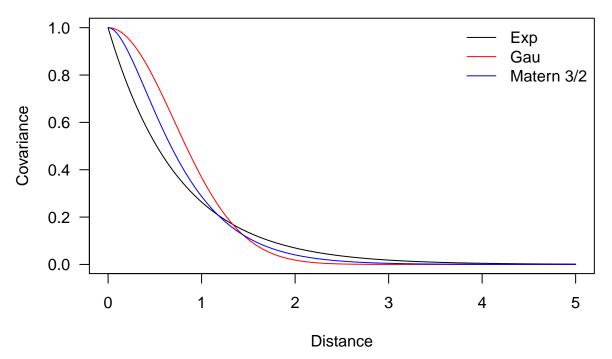
Random walk

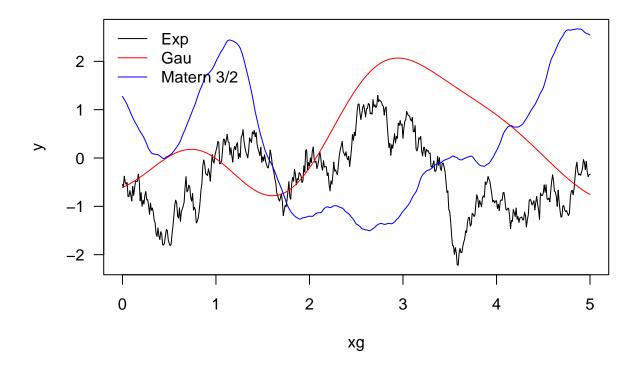
$$\eta_t = \sum_{s=1}^t Z_s.$$

```
saveLatex({
  par(las = 1, mgp = c(2, 0.5, 0), mar = c(3.6, 3.6, 0.8, 0.6))
  for (i in 1:5){
    z \leftarrow rnorm(500)
    plot(1:500, cumsum(z), type = "1", xlab = "Time",
         ylab = "Random Walk")
    abline(h = 0, col = "gray")
}, img.name = "RW", ani.opts = "controls, width=0.95\\textwidth",
latex.filename = ifelse(interactive(), "RW_realizations.tex", ""),
nmax = 5, ani.dev = "pdf", ani.type = "pdf", ani.width = 8,
ani.height = 4,documentclass = paste("\\documentclass{article}",
                                      "\\usepackage[papersize={8in,4in},margin=0.1in]{geometry}",
                                      sep = "\n"))
## \documentclass{article}
## \usepackage[papersize={8in,4in},margin=0.1in]{geometry}
##
                   \usepackage{animate}
##
                   \begin{document}
                   \begin{figure}
##
                   \begin{center}
##
                   \animategraphics[controls,width=0.95\textwidth]{1}{RW}{0}{4}
##
##
                   \end{center}
##
                   \end{figure}
                   \end{document}
##
##
```

Examples realizations of Gaussian process

```
library(fields)
# Commonly used covariance functions
cov.exp <- function(h, pars) pars[1] * exp(-h / pars[2])
cov.doubleExp <- function(h, pars) pars[1] * exp(-(h / pars[2])^2)
cov.Matern <- function(h, pars) Matern(h, phi = pars[1], range = pars[2], smoothness = pars[3])</pre>
```





ACF

 $Population\ ACF$

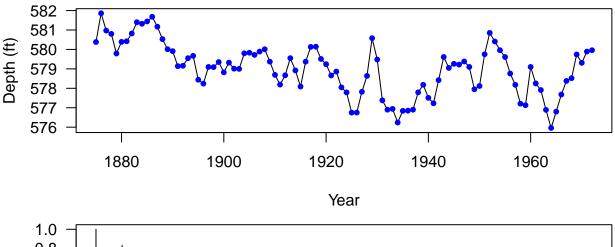
$$\rho(h) = \operatorname{Cor}(\eta_t, \eta_{t+h}) = \frac{\operatorname{E}\left[(\eta_t - \mu)(\eta_{t+h} - \mu)\right]}{\sqrt{\operatorname{Var}(\eta_t)\operatorname{Var}(\eta_{t+h})}}$$

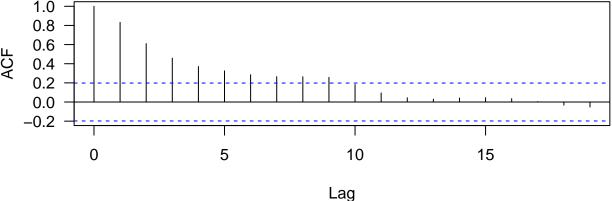
 $Sample\ ACF$

$$\hat{\rho}(h) = \frac{\hat{\gamma}(h)}{\hat{\gamma}(0)},$$

where $\hat{\gamma}(h) = \frac{1}{T} \sum_{t=1}^{T-|h|} (\eta_t - \bar{\eta})(\eta_{t+h} - \bar{\eta}).$

```
data(LakeHuron)
par(las = 1, mfrow = c(2, 1), mar = c(4, 4, 0.8, 0.6))
plot(LakeHuron, ylab = "Depth (ft)", xlab = "Year")
points(LakeHuron, cex = 0.8, col = "blue", pch = 16)
acf(LakeHuron)
```





Box test for temporal independence

Box and Pierce test Box and Pierce (1970)

We wish to test:

 $H_0:\{\eta_1,\eta_2,\cdots,\eta_T\}$ is an i.i.d. noise sequence

 $H_1: H_0$ is false

1. Under H_0 ,

$$\hat{\rho}(h) \stackrel{.}{\sim} \mathrm{N}(0, \frac{1}{T}) \stackrel{d}{=} \frac{1}{\sqrt{n}} \mathrm{N}(0, 1)$$

2. Hence

$$Q = T \sum_{i=1}^{k} \hat{\rho}^2(h) \stackrel{\cdot}{\sim} \chi_{df=k}^2$$

3. We reject H_0 if $Q > \chi_k^2(1-\alpha)$, the $1-\alpha$ quatile of the chi-squared distribution with k degrees of freedom

Ljung-Box Test

$$Q_{LB} = T(T-2) \sum_{h=1}^{k} \frac{\hat{\rho}^{2}(h)}{n-h} \stackrel{\cdot}{\sim} \chi_{k}^{2}.$$

The Ljung-Box test Ljung and Box (1978) can be more powerful than the Box and Pierce test

```
Box.test(rnorm(100), 20)
##
##
    Box-Pierce test
##
## data: rnorm(100)
## X-squared = 12.104, df = 20, p-value = 0.9125
Box.test(LakeHuron, 20)
##
##
    Box-Pierce test
##
## data: LakeHuron
## X-squared = 182.43, df = 20, p-value < 2.2e-16
Box.test(LakeHuron, 20, type = "Ljung")
##
##
   Box-Ljung test
##
## data: LakeHuron
## X-squared = 192.6, df = 20, p-value < 2.2e-16
```

References

Box, George EP, and David A Pierce. 1970. "Distribution of Residual Autocorrelations in Autoregressive-Integrated Moving Average Time Series Models." *Journal of the American Statistical Association* 65 (332): 1509–26.

Ljung, Greta M, and George EP Box. 1978. "On a Measure of Lack of Fit in Time Series Models." *Biometrika* 65 (2): 297–303.