

Lecture 13

Spectral Analysis of Time Series II

Readings: Cryer & Chan Ch 14; Brockwell & Davis Ch 4, Ch 10.1; Shumway & Stoffer Ch 1.5-1.6, Ch 4.4-Ch 4.6, Ch 4.8, Ch 5.5

MATH 8090 Time Series Analysis

November 9 & 11, 2021

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Whitney Huang
Clemson University

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- For odd $n = 2m + 1$, the inverse transform can be written

$$y_t - \bar{y} = \frac{2}{\sqrt{n}} \sum_{j=1}^m [d_{\cos}(\omega_j) \cos(2\pi\omega_j t) + d_{\sin}(\omega_j) \sin(2\pi\omega_j t)].$$

- Square and sum over t ; orthogonality of sines and cosines implies that

$$\begin{aligned} \sum_{t=1}^n (y_t - \bar{y})^2 &= 2 \sum_{j=1}^m [d_{\cos}(\omega_j)^2 + d_{\sin}(\omega_j)^2] \\ &= 2 \sum_{j=1}^m I(\omega_j) \end{aligned}$$

We have partitioned $\sum_{t=1}^n (y_t - \bar{y})^2$ into $2 \times \sum_{j=1}^m I(\omega_j)$. This leads to **Spectral ANOVA**

Source	df	SS	MS
ω_1	2	$2I(\omega_1)$	$I(\omega_1)$
ω_2	2	$2I(\omega_2)$	$I(\omega_2)$
\vdots	\vdots	\vdots	\vdots
ω_m	2	$2I(\omega_m)$	$I(\omega_m)$
Total	$2m = n - 1$	$\sum (y_t - \bar{y})^2$	

Toy example:

```
> x <- c(1, 2, 3, 2, 1) - mean(x)
> c1 <- cos(2 * pi * (1:5) * (1 / 5)); s1 <- sin(2 * pi * (1:5) * (1 / 5))
> c2 <- cos(2 * pi * (1:5) * (2 / 5)); s2 <- sin(2 * pi * (1:5) * (2 / 5))
> omega1 <- cbind(c1, s1); omega2 <- cbind(c2, s2)
> anova(lm(x ~ omega1 + omega2))
```

Warning in anova.lm(lm(x ~ omega1 + omega2)) :

ANOVA F-tests on an essentially perfect fit are unreliable

Analysis of Variance Table

Response: x

	Df	Sum Sq	Mean Sq	F value	Pr(>F)
omega1	2	2.74164	1.37082		
omega2	2	0.05836	0.02918		
Residuals	0	0.00000			

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Review: Nonparametric Spectral Estimation

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- **Periodogram:** $I(\omega_j) = |d(\omega_j)|^2$, where

$$d(\omega_j) = n^{-\frac{1}{2}} \sum_{t=1}^n y_t e^{-2\pi i \omega_j t}, \quad \omega_j = \frac{j}{n}, \quad j = 0, 1, \dots, n-1$$

- $\frac{I(\omega_j)}{\frac{1}{2}f(\omega_j)} \stackrel{\text{approx. i.i.d.}}{\sim} \chi_2^2, \quad j = 1, \dots, m = \frac{n-1}{2} \Rightarrow \mathbb{E}[I(\omega_j)] \approx f(\omega_j)$
(unbiased)
- But $\text{Var}[I(\omega_j)] \approx f^2(\omega_j)$ (inconsistent)

- Smooth the periodogram

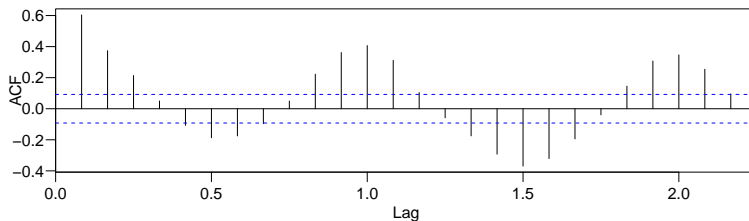
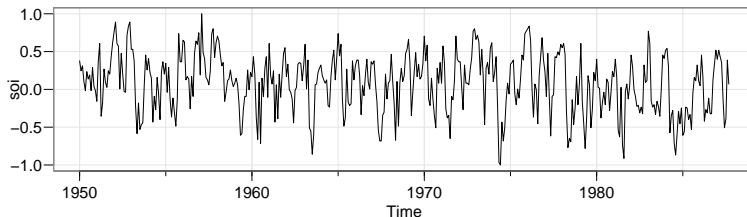
- **Averaged periodogram:** $\bar{f}(\omega_j) = \frac{1}{L} \sum_{k=-m}^m I(\omega_{j+k})$
- **Smoothed periodogram:** $\bar{f}(\omega_j) = \sum_{k=-m}^m W_m(k) I(\omega_{j+k})$

- Pointwise CI for $f(\omega_j)$:

$$\frac{\nu \bar{f}(\omega_j)}{\chi_\nu^2(1 - \alpha/2)} \leq f(\omega_j) \leq \frac{\nu \bar{f}(\omega_j)}{\chi_\nu^2(\alpha/2)}$$

Example: Southern Oscillation Index (SOI)

Southern Oscillation Index (SOI) for a period of 453 months
ranging over the years 1950-1987



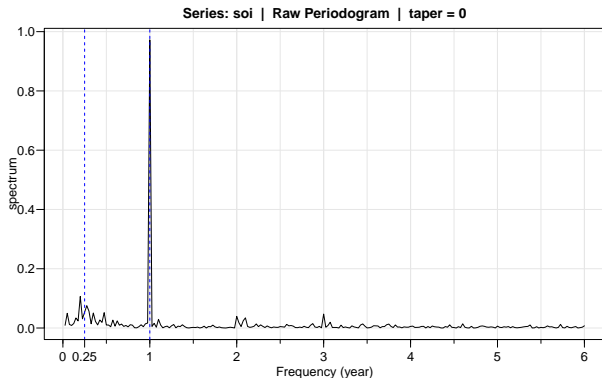
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SOI Example: Raw Periodogram



An approximate 95% confidence interval for $f(\omega)$:

ω	Period	Power	Lower	Upper
$\frac{1}{48}$	4 years	0.0537	0.0035	2.1222
$\frac{1}{12}$	1 year	0.9722	0.0632	38.4011

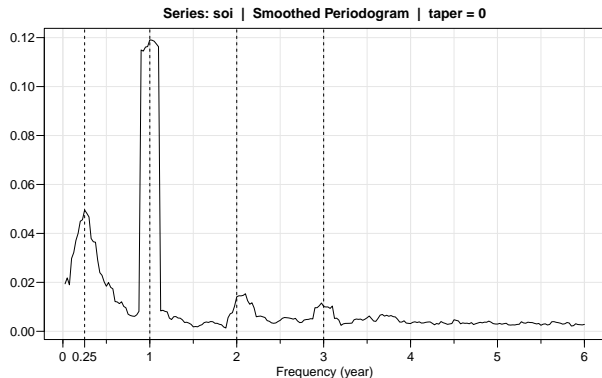
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SOI Example: Averaged Periodogram (Daniell with $m = 4$)



An approximate 95% confidence interval for $f(\omega)$:

ω	Period	Power	Lower	Upper
$\frac{1}{48}$	4 years	0.0495	0.0279	0.1113
$\frac{1}{12}$	1 year	0.1191	0.0670	0.2677

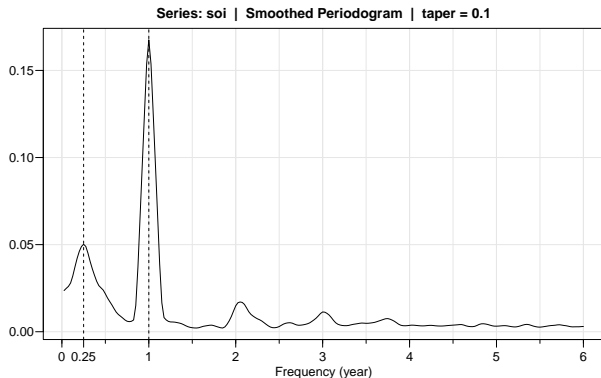
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SOI Example: Smoothed Periodogram (modified Daniell $c(3, 3)$)



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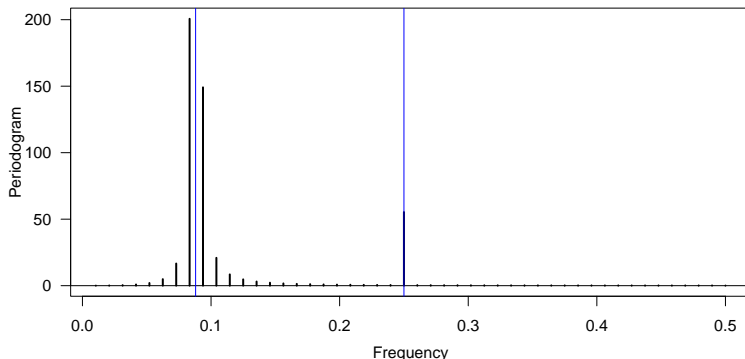
An approximate 95% confidence interval for $f(\omega)$:

ω	Period	Power	Lower	Upper
$\frac{1}{48}$	4 years	0.0502	0.0283	0.1129
$\frac{1}{12}$	1 year	0.1675	0.0943	0.3767

Spectral Leakage

Much of the previous discussion has assumed that the frequencies of interest are the **Fourier frequencies**, i.e., $\omega_j = \frac{j}{n}$. What happens if that is not the case?

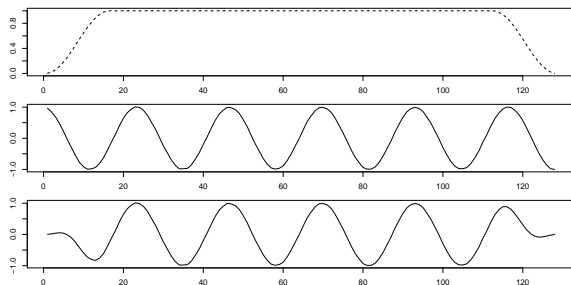
Example: $Y_t = 3 \cos(2\pi(0.088)t) + \sin(2\pi(\frac{24}{96})t)$, $t = 1, \dots, 96$



Power at non-Fourier frequencies will leak into the nearby Fourier frequencies

Tapering is one method used to alleviate the issue of **spectral leakage**, where power at non-Fourier frequencies leak into the nearby Fourier frequencies

Main idea: replace the original series by the tapered series, i.e., $\tilde{y}_t = h_t y_t$. Tapers h_t 's generally have a shape that enhances the center of the data relative to the extremities to reduce the end effects of computing a Fourier transform on a series of finite length



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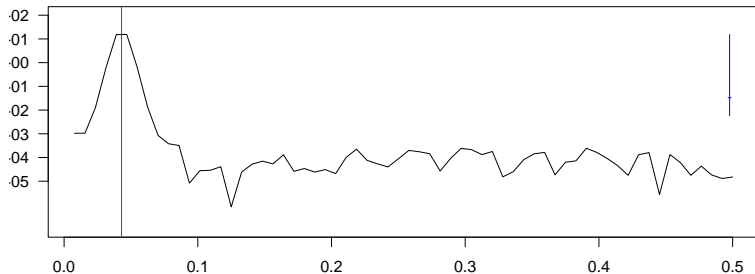
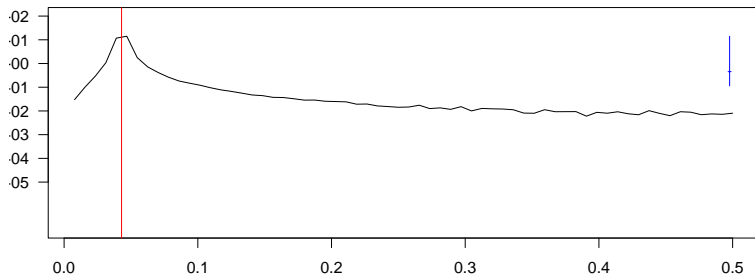
Tapering (Cont'd)

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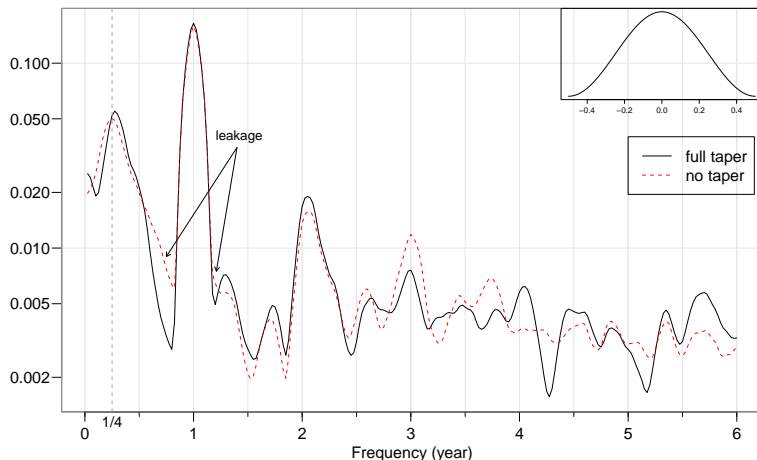
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SOI Example: Tapering



The tapered (with full tapering) spectrum does a better job in separating the yearly cycle $\omega = 1$ and the El Niño cycle $\omega = \frac{1}{4}$

Seasonally Adjusted SOI [Source: Peter Bloomfield's ST 730 Lecture Notes]

- The Southern Oscillation Index data provided by Shumway and Stoffer **is not seasonally adjusted**, which explains the substantial peaks in the periodogram at the annual frequency
- So the series is non-stationary, and has neither an autocovariance function nor a spectral density function
- A more sensible analysis uses the seasonally adjusted series. (Bloomfield did this by fitting a seasonal means model using data from 1876-2010.)

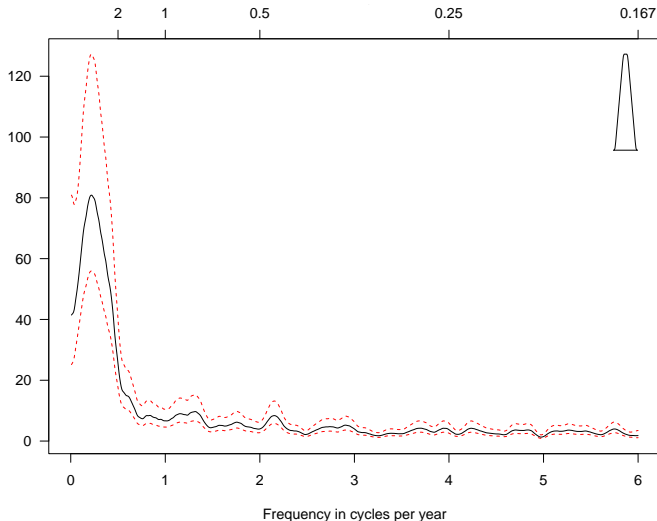
SOI Example from Bloomfield: Smoothed Periodogram

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Note that the peak at the annual frequency disappear due to the removal of the annual cycle

- **Parametric estimation**: estimate a model that is specified by a fixed number of parameters
- **Nonparametric estimation**: estimate a model that is specified by a number of parameters that can grow as the sample grows

Thus, the smoothed periodogram estimates we have considered are **nonparametric**: the estimates of the spectral density can be parameterized by estimated values at ω_j 's. As $n \uparrow$, the number of distinct frequency values increases

The time domain models we considered are **parametric**. For example, an $\text{ARMA}(p,q)$ process can be completely specified with $p + q + 1$ parameters

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The typical approach is to use the maximum likelihood parameter estimates $(\hat{\phi}_1, \dots, \hat{\phi}_p, \hat{\sigma}^2)$ for the parameters of an $AR(p)$, and then compute $\hat{f}(\omega)$ for this estimated AR model:

$$\hat{f}(\omega) = \frac{\hat{\sigma}^2}{|\hat{\phi}(e^{-2\pi i \omega})|^2}$$

For large n ,

$$\text{Var}(\hat{f}(\omega)) \approx \frac{2p}{n} f^2(\omega)$$

- The **bias** decreases as $p \uparrow$, the number of parameters increase, as one can model more complex spectra
- The **variance** increase linealy with p

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- Sometimes ARMA models are used instead
- Estimate the parameters of an ARMA(p, q) model and compute its spectral density:

$$\hat{f}(\omega) = \hat{\sigma}^2 \left| \frac{\hat{\theta}(e^{-2\pi i\omega})}{\hat{\phi}(e^{-2\pi i\omega})} \right|^2.$$

- However, it is more common to use large AR models, rather than ARMA models

- The main advantage of parametric spectral estimation over nonparametric is that it often gives better **frequency resolution** of a small number of peaks
- This is especially important if there is more than one peak at nearby frequencies
- The disadvantage of parametric spectral estimation is the inflexibility due to the use of the restricted class of ARMA models.

Given data y_1, y_2, \dots, y_n ,

- 1 Estimate the AR parameters $(\phi_1, \phi_2, \dots, \phi_p, \sigma^2)$ using maximum likelihood or Yule-Walker/least squares, choose a suitable model order p using AIC or BIC
- 2 Use the estimates $(\hat{\phi}_1, \hat{\phi}_2, \dots, \hat{\phi}_p, \hat{\sigma}^2)$ to compute the estimated spectral density:

$$\hat{f}(\omega) = \frac{\hat{\sigma}^2}{|\hat{\phi}(e^{-2\pi i \omega})|^2}$$

Example: AR(1) with $\phi = 0.8$

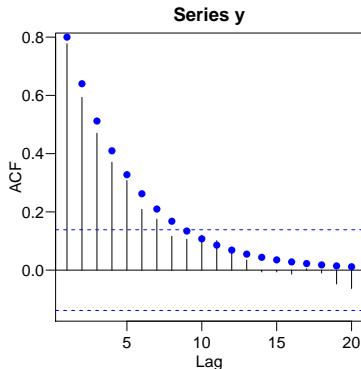
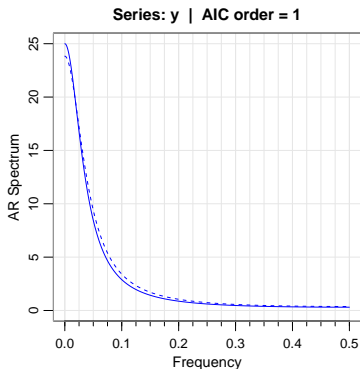
- 1 Use AIC to select p , the order of the AR model
- 2 Use the estimates $(\hat{\phi}_1, \hat{\phi}_2, \dots, \hat{\phi}_p, \hat{\sigma}^2)$ to compute the estimated spectral

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Example: ARMA(1, 1) with $\phi = 0.8$ and $\theta = 0.5$

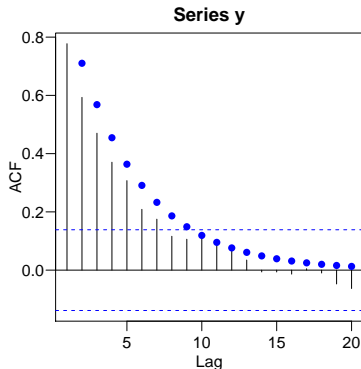
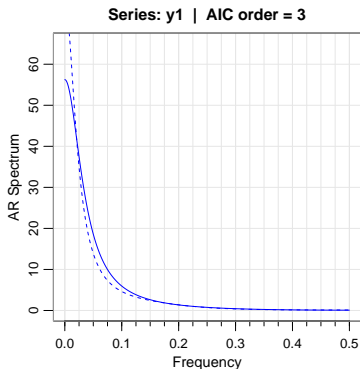
- 1 Use AIC to select p , the order of the AR model
- 2 Use the estimates $(\hat{\phi}_1, \hat{\phi}_2, \dots, \hat{\phi}_p, \hat{\sigma}^2)$ to compute the estimated spectral

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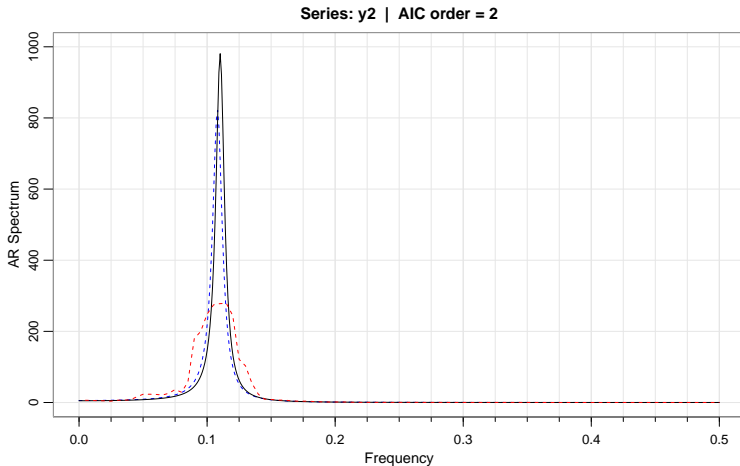
Example: AR(2) with $\phi_1 = 1.5$ and $\phi_2 = -0.95$

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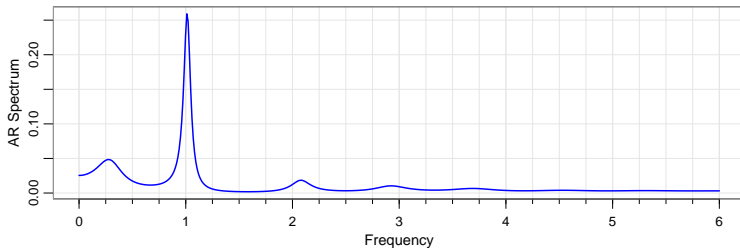
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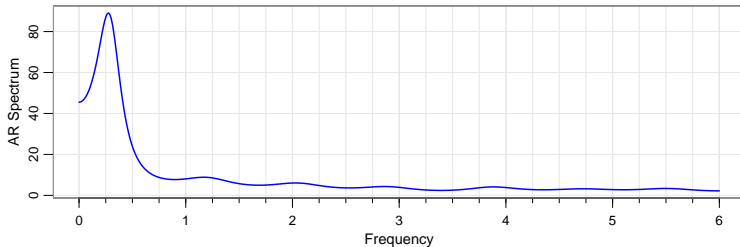


SOI Example

Series: soi | AIC order = 15



Series: soiAdj | AIC order = 14



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Consider a **lagged regression model** of the form

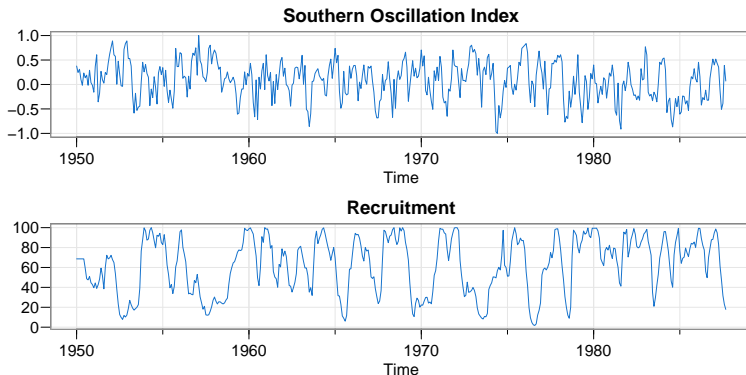
$$Y_t = \sum_{h=-\infty}^{\infty} \beta_h X_{t-h} + V_t,$$

where X_t is an observed **input time series**. Y_t is the observed **output time series**, and V_t is a **stationary** noise process.

Such a model is useful for

- Identifying the (best linear) relationship between two time series X_t and Y_t
- Forecasting one time series (likely Y_t) from the other (likely X_t). We may want to let $\beta_h = 0$ for $h < 0$

An Example of Lagged Regression Model



- We may wish to identify how the values of the recruitment series is related to the SOI
- We may wish to predict future values of recruitment from the SOI.

- **Time domain:** model the input series, extract the white time series driving it ("prewhitening"), regress with transformed output series
 - Cross-covariance function
 - Cross-correlation function
- **Frequency domain:** Calculate the input's spectral density, and the cross-spectral density between input and output, and find the **transfer function** relating them, in the frequency domain.
 - Cross spectrum
 - Coherence

Recall that the autocovariance function of a stationary process $\{Y_t\}$ is

$$\gamma_X(h) = \mathbb{E}[(X_{t+h} - \mu_X)(X_t - \mu_X)].$$

The **cross-covariance function** of two jointly stationary processes $\{Y_t\}$ and $\{X_t\}$ is

$$\gamma_{XY}(h) = \mathbb{E}[(X_{t+h} - \mu_X)(Y_t - \mu_Y)].$$

Note: Jointly stationary = constant means, autocovariances depending only on the lag h , and cross-covariance depends only on h

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The **cross-correlation function** of jointly stationary $\{X_t\}$ and $\{Y_t\}$ is

$$\rho_{XY}(h) = \frac{\gamma_{XY}(h)}{\sqrt{\gamma_X(0)\gamma_Y(0)}}.$$

Notice that $\rho_{XY}(h) = \rho_{YX}(-h)$ but $\rho_{XY}(h)$ is not necessarily equal to $\rho_{XY}(-h)$

Example: Suppose that $Y_t = \beta X_{t-\ell} + W_t$ for $\{X_t\}$ stationary and uncorrelated with $\{W_t\}$, and $\{W_t\}$ a zero mean white noise. Then $\{X_t\}$ and $\{Y_t\}$ are jointly stationary, with $\mu_Y = \beta\mu_X$,

$$\gamma_{XY}(h) = \beta\gamma_X(h + \ell).$$

- If $\ell > 0$, we say X_t leads Y_t
- If $\ell < 0$, we say X_t lags Y_t

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Sample Cross-Covariance and Sample Cross-Correlation

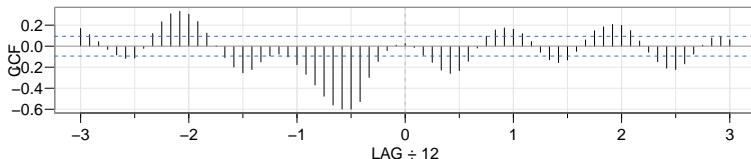
The sample cross-covariance is

$$\hat{\gamma}_{XY}(h) = \frac{1}{n} \sum_{i=1}^{n-h} (x_{t+h} - \bar{x})(y_t - \bar{y})$$

for $h \geq 0$. Then sample CCF is

$$\hat{\rho}_{XY}(h) = \frac{\hat{\gamma}_{XY}(h)}{\sqrt{\hat{\gamma}_X(0)\hat{\gamma}_Y(0)}}$$

SOI vs Recruitment



Example: CCF of SOI and recruitment has a peak at $h = -6$.
Thus, SOI leads recruitment by 6 months

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Suppose we wish to fit a lagged regression model of the form

$$Y_t = \beta(B)X_t + V_t = \sum_{j=0}^{\infty} \beta_j X_{t-j} + V_t,$$

where X_t is an observed input series, Y_t is the observed output series, and V_t is a stationary noise process, uncorrelated with X_t .

One approach (pioneered by [Box and Jenkins](#)) is to fit ARMA models for X_t and V_t , and then find a simple rational representation for $\beta(B)$. This is the [transfer function models](#)

$$Y_t = \beta(B)X_t + V_t = \sum_{j=0}^{\infty} \beta_j X_{t-j} + V_t,$$

For example:

$$X_t = \frac{\theta_X(B)}{\phi_X(B)} W_t,$$

$$V_t = \frac{\theta_V(B)}{\phi_V(B)} Z_t,$$

$$\beta(B) = \frac{\delta(B)}{\omega(B)} B^d$$

Notice the delay B^d , indicating that Y_t lags X_t by d steps

How do we choose all of these parameters?

- Fit $\theta_X(B)$, $\phi_X(B)$ to model the input series $\{X_t\}$
- **Prewhiten** the input series by applying the inverse operator $\phi_X(B)/\theta_X(B)$:

$$\tilde{Y}_t = \frac{\phi_X(B)}{\theta_X(B)} Y_t = \beta(B) W_t + \frac{\phi_X(B)}{\theta_X(B)} V_t$$

- Calculate the cross-correlation of \tilde{Y}_t with W_t ,

$$\gamma_{\tilde{Y}, W}(h) = \mathbb{E}[\tilde{Y}_{t+h} W_t] = \mathbb{E}\left[\sum_{j=0}^{\infty} \beta_j W_{t+h-j} W_t\right] = \sigma_W^2 \beta_h$$

to give an indication of the behavior of $\beta(B)$

- Estimate the coefficients of $\beta(B)$ and hence fit an ARMA model for the noise series V_t

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The prewhitening step inverts the linear filter $X_t = \frac{\theta_X(B)}{\phi_X(B)} W_t$.

Then the lagged regression is between the transformed Y_t and a white series W_t . This makes it easy to determine a suitable lag

Example: In the SOI/recruitment series, we treat SOI as an input, estimate an AR(1) model, prewhiten it, and consider the cross-correlation between the transformed recruitment series and the prewhitened SOI. This shows a large peak at lag -5 (corresponding to the SOI series leading the recruitment series)

This sequential estimation procedure ϕ_X, θ_X , then β , then ϕ_V, θ_V is rather ad hoc. State space methods (ARMAX model) offer an alternative, and they are also convenient for vector-valued input and output series

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To analyze lagged regression in the frequency domain, we'll need the notion of **coherence**, the analog of cross-correlation in the frequency domain

Define the **cross-spectrum** as the Fourier transform of the cross-correlation,

$$f_{XY}(\omega) = \sum_{h=-\infty}^{\infty} \gamma_{XY}(h) e^{-2\pi i \omega h},$$
$$\gamma_{XY}(h) = \int_{-\frac{1}{2}}^{\frac{1}{2}} f_{XY}(\omega) e^{2\pi i \omega h} d\omega,$$

provided that $\sum_{h=-\infty}^{\infty} |\gamma_{XY}(h)| < \infty$

Notice that $f_{XY}(\omega)$ is complex: $f_{XY}(\omega) = c_{XY}(\omega) - iq_{XY}(\omega)$.
Also, $\gamma_{YX}(h) = \gamma_{XY}(-h)$ implies $f_{YX}(\omega) = \overline{f_{XY}(\omega)}$

$$\Rightarrow c_{YX}(\omega) = c_{XY}(\omega) \quad \text{and} \quad q_{YX}(\omega) = -q_{XY}(\omega)$$

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- The **squared coherence** function is

$$\rho_{Y,X}^2(\omega) = \frac{|f_{YX}(\omega)|^2}{f_X(\omega)f_Y(\omega)}.$$

measures the strength of the relationship between X_t and Y_t at frequency ω

- $\rho_{Y,X}^2(\omega)$ is an analog of R^2 , it measures the fraction of variance in Y_t at frequency ω , $f_Y(\omega)$, explained by X_t
- $\rho_{Y,X}^2(\omega) = |\rho_{Y,X}(\omega)|^2$, where

$$\rho_{Y,X}(\omega) = \frac{f_{YX}(\omega)}{\sqrt{f_X(\omega)f_Y(\omega)}}$$

Estimating Squared Coherence

Recall that we estimated the spectral density using the smoothed squared modulus of the DFT of the series,

$$\begin{aligned}\bar{f}_X(\omega_j) &= \frac{1}{L} \sum_{k=-(L-1)/2}^{(L-1)/2} |d_X(\omega_j)|^2 \\ &= \frac{1}{L} \sum_{k=-(L-1)/2}^{(L-1)/2} d_X(\omega_{j+k}) \overline{d_X(\omega_{j+k})}.\end{aligned}$$

We can estimate the cross spectral density using the same sample estimate,

$$\bar{f}_{XY}(\omega_j) = \frac{1}{L} \sum_{k=-(L-1)/2}^{(L-1)/2} d_X(\omega_{j+k}) \overline{d_Y(\omega_{j+k})}$$

Also, we can estimate the squared coherence using these estimates,

$$\bar{\rho}_{Y,X}^2(\omega) = \frac{|\bar{f}_{YX}(\omega)|^2}{\bar{f}_X(\omega) \bar{f}_Y(\omega)}.$$

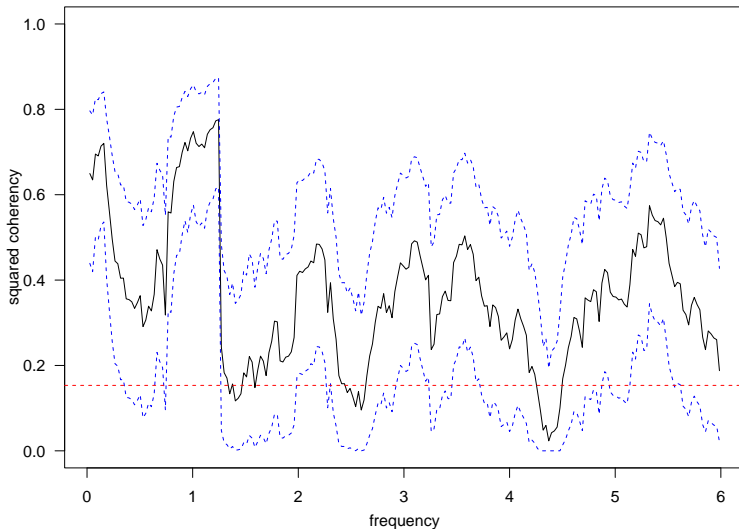
Estimating Squared Coherence: SOI and Recruitment Example

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Consider a lagged regression model of the form

$$Y_t = \sum_{j=-\infty}^{\infty} \beta_j X_{t-j} + V_t,$$

where X_t is an observed input series, Y_t is the observed output series, and V_t is a stationary noise process

We'd like to estimate the coefficients β_j that determine the relationship between the lagged values of the input series X_t and the output series Y_t

The projection theorem tells us that the coefficients that minimize the mean squared error,

$$\mathbb{E} \left[\left(Y_t - \sum_{j=-\infty}^{\infty} \beta_j X_{t-j} \right)^2 \right]$$

satisfy the orthogonality conditions

$$\mathbb{E} \left[\left(Y_t - \sum_{j=-\infty}^{\infty} \beta_j X_{t-j} \right) X_{t-k} \right] = 0, \quad k = 0, \pm 1, \pm 2, \dots$$

Taking the expectations inside leads to the normal equations

$$\sum_{j=-\infty}^{\infty} \beta_j \gamma_X(k-j) = \gamma_{YX}(k), \quad k = 0, \pm 1, \pm 2, \dots$$

We could solve these equations for the β_j using the sample autocovariance and sample cross-covariance. But it is more convenient to use estimates of the spectra and cross-spectrum because **convolution with $\{\beta_j\}$ in the time domain is equivalent to multiplication by the Fourier transform of $\{\beta_j\}$ in the frequency domain**

We replace the autocovariance and cross-covariance with the inverse Fourier transforms of the spectral density and cross-spectral density in the orthogonality conditions, i.e., replace

$$\sum_{j=-\infty}^{\infty} \beta_j \gamma_X(k-j) \quad k = 0, \pm 1, \pm 2, \dots$$

by

$$\int_{-\frac{1}{2}}^{\frac{1}{2}} \sum_{j=-\infty}^{\infty} \beta_j e^{2\pi i \omega(k-j)} f_X(\omega) d\omega$$

This gives, for $k = 0, \pm 1, \pm 2, \dots$,

$$\begin{aligned} \int_{-\frac{1}{2}}^{\frac{1}{2}} \sum_{j=-\infty}^{\infty} \beta_j e^{2\pi i \omega (k-j)} f_X(\omega) d\omega &= \int_{-\frac{1}{2}}^{\frac{1}{2}} e^{2\pi i \omega k} f_{YX}(\omega) d\omega, \\ \Rightarrow \int_{-\frac{1}{2}}^{\frac{1}{2}} e^{2\pi i \omega k} B(\omega) f_X(\omega) d\omega &= \int_{-\frac{1}{2}}^{\frac{1}{2}} e^{2\pi i \omega k} f_{YX}(\omega) d\omega, \end{aligned}$$

where $B(\omega) = \sum_{j=-\infty}^{\infty} e^{-2\pi i \omega j} \beta_j$ is the Fourier transform of the coefficient sequence β_j . Since the Fourier transform is unique, the orthogonality conditions are equivalent to

$$B(\omega) f_X(\omega) = f_{YX}(\omega).$$

Then we may take

$$\hat{B}(\omega_k) = \frac{\hat{f}_{YX}(\omega_k)}{\hat{f}_X(\omega_k)}$$

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Lagged Regression Models in the Frequency Domain

We can write the mean squared error at the solution as follows

$$\begin{aligned}\mathbb{E}\left[\left(Y_t - \sum_{j=-\infty}^{\infty} \beta_j X_{t-j}\right) Y_t\right] &= \gamma_Y(0) - \sum_{j=-\infty}^{\infty} \beta_j \gamma_{XY}(-j) \\&= \int_{-\frac{1}{2}}^{\frac{1}{2}} (f_Y(\omega) - B(\omega) f_{XY}(\omega)) d\omega \\&= \int_{-\frac{1}{2}}^{\frac{1}{2}} f_Y(\omega) \left(1 - \frac{f_{YX}(\omega) f_{XY}(\omega)}{f_X(\omega) f_Y(\omega)}\right) d\omega \\&= \int_{-\frac{1}{2}}^{\frac{1}{2}} f_Y(\omega) \left(1 - \frac{|f_{YX}(\omega)|^2}{f_X(\omega) f_Y(\omega)}\right) d\omega \\&= \int_{-\frac{1}{2}}^{\frac{1}{2}} f_Y(\omega) (1 - \rho_{Y,X}^2(\omega)) d\omega.\end{aligned}$$

$$\Rightarrow \text{MSE} = \int_{-\frac{1}{2}}^{\frac{1}{2}} f_Y(\omega) (1 - \rho_{Y,X}^2(\omega)) d\omega$$

$$\Rightarrow f_V(\omega) = (1 - \rho_{Y,X}^2(\omega)) f_Y(\omega)$$

Lagged Regression Models in the Frequency Domain

$$\text{Recall MSE} = \int_{-\frac{1}{2}}^{\frac{1}{2}} f_Y(\omega)(1 - \rho_{Y,X}^2(\omega)) d\omega.$$

Thus, $\rho_{Y,X}^2(\omega)$ indicates how the variance of $\{Y_t\}$ at a frequency ω is accounted for by $\{X_t\}$. Compare with the corresponding decomposition for random variables:

$$\mathbb{E}(Y - \beta X) = \sigma_Y^2(1 - \rho_{Y,X}^2)$$

We can estimate the β_j in the frequency domain:

$$\hat{B}(\omega_k) = \frac{\hat{f}_{YX}(\omega_k)}{\hat{f}_X(\omega_k)}.$$

We can approximate the inverse Fourier transform of $\hat{B}(\omega)$,

$$\hat{\beta}_j = \int_{-\frac{1}{2}}^{\frac{1}{2}} e^{2\pi i \omega j} \hat{B}(\omega) d\omega$$

via the sum,

$$\hat{\beta}_j = \frac{1}{M} \sum_{k=0}^{M-1} \hat{B}(\omega_k) e^{-2\pi i \omega_k j}.$$

Here is the approach:

- 1 Estimate the spectral density $f_X(\omega)$ and cross-spectral density $f_{YX}(\omega)$
- 2 Compute the transfer function $\hat{B}(\omega)$:

$$\hat{B}(\omega_k) = \frac{\hat{f}_{YX}(\omega_k)}{\hat{f}_X(\omega_k)}.$$

- 3 Take the inverse Fourier transform to obtain the impulse response function β_j :

$$\hat{\beta}_j = \frac{1}{M} \sum_{k=0}^{M-1} \hat{B}(\omega_j) e^{-2\pi i \omega_k j}.$$