

Lecture 5

Multivariate Linear Regression

Readings: Johnson & Wichern 2007, Chapter 7; DSA 8020

Lectures 1-4 [\[Link\]](#); Zelterman, 2015, Chapter 9

DSA 8070 Multivariate Analysis

Motivation

Model and
Assumptions

Parameter Estimation

Inference and
Prediction

Motor Trend Car Road
Tests Data Analysis

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Example: Motor Trend Car Road Tests

```
> head(mtcars)
```

	mpg	cyl	disp	hp	drat	wt	qsec	vs	am	gear	carb
Mazda RX4	21.0	6	160	110	3.90	2.620	16.46	0	1	4	4
Mazda RX4 Wag	21.0	6	160	110	3.90	2.875	17.02	0	1	4	4
Datsun 710	22.8	4	108	93	3.85	2.320	18.61	1	1	4	1
Hornet 4 Drive	21.4	6	258	110	3.08	3.215	19.44	1	0	3	1
Hornet Sportabout	18.7	8	360	175	3.15	3.440	17.02	0	0	3	2
Valiant	18.1	6	225	105	2.76	3.460	20.22	1	0	3	1

Suppose we would like to study the (linear) relationship between mpg, disp, hp, wt (responses) and cyl, am, carb (predictors)

Multiple regression predicts one outcome; multivariate regression predicts several simultaneously

Why Multivariate Regression Instead of Separate Regressions?

- **Estimation:**

- Coefficient estimates are the same as running separate regressions

- **Inference:** The real gain comes from joint modeling

- Test hypotheses across multiple outcomes simultaneously
- Accounts for correlations among responses \Rightarrow more powerful and accurate tests

- **Examples:**

- Does a predictor affect all outcomes jointly?
- Multivariate analog of ANOVA (MANOVA)

The multiple linear regression model has the form:

$$y_i = \beta_0 + \sum_{j=1}^p \beta_j x_{ij} + \varepsilon_i, \quad i = 1, \dots, n,$$

where

- y_i is the **response** for the i -th observation
- x_{ij} is the j -th **predictor** for the i -th observation
- β_0 and β_j 's are the **regression intercept** and **slopes** for the response, respectively
- ε_i is the **error** term for the response of the i -th observation

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The Multivariate Linear Regression Model: Scalar Form

The multivariate (multiple) linear regression model has the form:

$$y_{ik} = \beta_{0k} + \sum_{j=1}^p \beta_{jk} x_{ij} + \varepsilon_{ik}, \quad i = 1, \dots, n, \quad k = 1, \dots, d,$$

where

- y_{ik} is the k -th **response** for the i -th observation
- x_{ij} is the j -th **predictor** for the i -th observation
- β_{0k} and β_{jk} 's are the **regression intercept** and **slopes** for k -th response, respectively
- ε_{ik} is the **error** term for the k -th response of the i -th observation

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The Multivariate Linear Regression Model: Assumptions

The assumptions of the model are:

- Relationship between $\{x_j\}_{j=1}^p$ and Y_k is **linear** for each $k \in \{1, \dots, d\}$
- $(\varepsilon_{i1}, \dots, \varepsilon_{id})^T \stackrel{i.i.d.}{\sim} N(\mathbf{0}, \Sigma)$ is an **unobserved random vector**
- $[Y_{ik} | x_{i1}, \dots, x_{ip}] \sim N(\beta_{0k} + \sum_{j=1}^p \beta_{jk} x_{ij}, \sigma_{kk})$ for each $k \in \{1, \dots, d\}$

The Multivariate Linear Regression Model: Matrix Form

The multivariate multiple linear regression model has the form

$$Y = XB + E,$$

where

- $Y = [y_1, \dots, y_d]$ is the $n \times d$ **response matrix**, where $y_k = (y_{1k}, \dots, y_{nk})^T$ is the k -th response vector
- $X = [1, x_1, \dots, x_p]$ is the $n \times (p + 1)$ **design matrix**
- $B = [\beta_1, \dots, \beta_d]$ is the $(p + 1) \times d$ **matrix of regression coefficients**
- $E = [\varepsilon_1, \dots, \varepsilon_d]$ is the $n \times d$ **error matrix**

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Matrix form writes the multivariate linear regression model for all $n \times d$ points simultaneously as

$$\mathbf{Y} = \mathbf{X}\mathbf{B} + \mathbf{E}$$

$$\begin{bmatrix} y_{11} & \cdots & y_{1d} \\ y_{21} & \cdots & y_{2d} \\ \vdots & \ddots & \vdots \\ y_{n1} & \cdots & y_{nd} \end{bmatrix} = \begin{bmatrix} 1 & \cdots & x_{1p} \\ 1 & \cdots & x_{2p} \\ \vdots & \ddots & \vdots \\ 1 & \cdots & x_{np} \end{bmatrix} \begin{bmatrix} \beta_{01} & \cdots & \beta_{0d} \\ \beta_{11} & \cdots & \beta_{1d} \\ \vdots & \ddots & \vdots \\ \beta_{p1} & \cdots & \beta_{pd} \end{bmatrix} + \begin{bmatrix} \varepsilon_{11} & \cdots & \varepsilon_{1d} \\ \varepsilon_{21} & \cdots & \varepsilon_{2d} \\ \vdots & \ddots & \vdots \\ \varepsilon_{n1} & \cdots & \varepsilon_{nd} \end{bmatrix}$$

Assuming that n subjects are **independent**, we have

$$\bullet \varepsilon_k \sim N(0, \sigma_{kk}), \quad k \in \{1, \dots, d\}$$

$$\bullet \varepsilon_i \stackrel{i.i.d.}{\sim} N(\mathbf{0}, \Sigma), \quad i = 1, \dots, n$$

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The **ordinary least squares** OLS estimate is

$$\operatorname{argmin}_{\mathbf{B} \in \mathbb{R}^{(p+1) \times d}} \|\mathbf{Y} - \mathbf{X}\mathbf{B}\|^2 = \operatorname{argmin}_{\mathbf{B} \in \mathbb{R}^{(p+1) \times d}} \sum_{i=1}^n \sum_{k=1}^d \left(y_{ik} - \beta_{0k} - \sum_{j=1}^p \beta_{jk} x_{ij} \right)^2,$$

where $\|\cdot\|$ denotes the Frobenius norm.

- $\text{OLS}(\mathbf{B}) = \|\mathbf{Y} - \mathbf{X}\mathbf{B}\|^2 = \text{tr}(\mathbf{Y}^T \mathbf{Y}) - 2\text{tr}(\mathbf{Y}^T \mathbf{X}\mathbf{B}) + \text{tr}(\mathbf{B}^T \mathbf{X}^T \mathbf{X} \mathbf{B})$
- $\frac{\partial \text{OLS}(\mathbf{B})}{\partial \mathbf{B}} = -2\mathbf{X}^T \mathbf{Y} + 2\mathbf{X}^T \mathbf{X} \mathbf{B}$

The OLS estimate has the form

$$\hat{\mathbf{B}} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{Y} \Rightarrow \hat{\beta}_k = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}_k, \quad k \in \{1, \dots, d\}$$

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Expected Value of Least Squares Coefficients

The expected value of the estimated coefficients is given by

$$\begin{aligned}\mathbb{E}(\hat{B}) &= \mathbb{E}[(X^T X)^{-1} X^T Y] \\ &= (X^T X)^{-1} X^T \mathbb{E}(Y) \\ &= (X^T X)^{-1} X^T X B \\ &= B\end{aligned}$$

$\Rightarrow \hat{B}$ is an unbiased estimator of B

- Fitted values are given by

$$\hat{Y} = X\hat{B},$$

$$\text{i.e., } \hat{y}_{ik} = \hat{\beta}_{0k} + \sum_{j=1}^p \hat{\beta}_{jk} x_{ij}, \quad i = 1, \dots, n, \quad k = 1, \dots, d$$

- Residuals are given by

$$\hat{E} = Y - \hat{Y},$$

$$\text{i.e., } \hat{e}_{ik} = y_{ik} - \hat{y}_{ik}, \quad i = 1, \dots, n, \quad k = 1, \dots, d$$

Just like in univariate linear regression we can write the fitted values as

$$\begin{aligned}\hat{Y} &= X\hat{B} \\ &= X(X^T X)^{-1} X^T Y \\ &= HY,\end{aligned}$$

where $H = X(X^T X)^{-1} X^T$ is the **hat matrix**

$\Rightarrow H$ projects y_k onto the column space of X for $k \in \{1, \dots, d\}$

Partitioning the Total Variation

We can partition the total covariation in $\{\mathbf{y}_i\}_{i=1}^n$ (SSCP_{Tot}) as

$$\begin{aligned}\text{SSCP}_{\text{tot}} &= \sum_{i=1}^n (\mathbf{y}_i - \bar{\mathbf{y}})^T (\mathbf{y}_i - \bar{\mathbf{y}}) \\&= \sum_{i=1}^n (\mathbf{y}_i - \hat{\mathbf{y}}_i + \hat{\mathbf{y}}_i - \bar{\mathbf{y}})(\mathbf{y}_i - \hat{\mathbf{y}}_i + \hat{\mathbf{y}}_i - \bar{\mathbf{y}})^T \\&= \underbrace{\sum_{i=1}^n (\hat{\mathbf{y}}_i - \bar{\mathbf{y}})(\hat{\mathbf{y}}_i - \bar{\mathbf{y}})^T}_{\text{SSCP}_{\text{Reg}}} + \underbrace{\sum_{i=1}^n (\mathbf{y}_i - \hat{\mathbf{y}}_i)(\mathbf{y}_i - \hat{\mathbf{y}}_i)^T}_{\text{SSCP}_{\text{Err}}} \\&\quad + \underbrace{2 \sum_{i=1}^n (\hat{\mathbf{y}}_i - \bar{\mathbf{y}})(\mathbf{y}_i - \hat{\mathbf{y}}_i)^T}_{=0} \\&= \text{SSCP}_{\text{Reg}} + \text{SSCP}_{\text{Err}}\end{aligned}$$

The corresponding **degrees of freedom** are $d(n-1)$ for SSCP_{Tot} ; dp for SSCP_{Reg} ; and $d(n-p-1)$ for SSCP_{Err}

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The estimated error covariance matrix is

$$\begin{aligned}\hat{\Sigma} &= \frac{\sum_{i=1}^n (\mathbf{y}_i - \hat{\mathbf{y}}_i)(\mathbf{y}_i - \hat{\mathbf{y}}_i)^T}{n - p - 1} \\ &= \frac{\text{SSCP}_{Err}}{n - p - 1}\end{aligned}$$

- $\hat{\Sigma}$ is an unbiased estimate of Σ
- The estimate $\hat{\Sigma}$ is the mean SSCP_{Err}

Sampling Distributions of \hat{B} , \hat{Y} , and \hat{E}

We would need to figure out the **sampling distributions** of estimator and predictor in order to drawn inference

Given the model assumptions, we have

$$\text{vec}(\hat{B}) \sim N(\text{vec}(B), \Sigma \otimes (X^T X)^{-1})$$

$$\text{vec}(\hat{Y}) \sim N(\text{vec}(XB), \Sigma \otimes H)$$

$$\text{vec}(\hat{E}) \sim N(0, \Sigma \otimes (I - H)),$$

where $\text{vec}(\cdot)$ is the vectorization operator and \otimes is the Kronecker product

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Inference about Multiple $\hat{\beta}_{jk}$

Assume that $q < p$ and want to test if a reduced model is sufficient:

$$H_0 : B_2 = \mathbf{0}_{p-q} \times d, \quad \text{versus} \quad H_a : B_2 \neq \mathbf{0}_{p-q} \times d,$$

where

$$B = \begin{bmatrix} B_1 \\ B_2 \end{bmatrix}$$

is the partitioned of the coefficient vector

We can compare the SSCP_{Err} for the **full model**:

$$y_{ik} = \beta_{0k} + \sum_{j=1}^p \beta_{jk} x_{ij} + \varepsilon_{ik}, \quad k = 1, \dots, d$$

and the **reduced model**:

$$y_{ik} = \beta_{0k} + \sum_{j=1}^q \beta_{jk} x_{ij} + \varepsilon_{ik}, \quad k = 1, \dots, d$$

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Some Test Statistics

Let $\tilde{E} = n\tilde{\Sigma}$ denote the SSCP_{Err} matrix from the **full model**,
and let $\tilde{H} = n(\tilde{\Sigma}_1 - \tilde{\Sigma})$ denote the hypothesis SSCP_{Err} matrix
Some test statistics for

$$H_0 : B_2 = \mathbf{0}_{p-q} \times d, \quad \text{versus} \quad H_a : B_2 \neq \mathbf{0}_{p-q} \times d :$$

- Wilks Lambda

$$\Lambda^* = \frac{|\tilde{E}|}{|\tilde{H} + \tilde{E}|}$$

Reject H_0 if Λ^* is “small”

- Hotelling-Lawley Trace

$$T_0^2 = \text{tr}(\tilde{H}\tilde{E}^{-1})$$

Reject H_0 if T_0^2 is “large”

- Pillai Trace

$$V = \text{tr}(\tilde{H}(\tilde{H} + \tilde{E})^{-1})$$

Reject H_0 if V is “large”

We would like to estimate the **expected value of the response** for a given predictor $\mathbf{x}_h = (1, x_{h1}, \dots, x_{hp})$.

Note that we have

$$\hat{\mathbf{y}}_h \sim N(\mathbf{B}^T \mathbf{x}_h, \mathbf{x}_h^T (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{x}_h \Sigma)$$

We can exploit the duality between interval estimation and hypothesis testing. That is, we can test

$$H_0 : \mathbb{E}(\mathbf{y}_h) = \mathbf{y}_h^* \text{ versus } H_a : \mathbb{E}(\mathbf{y}_h) \neq \mathbf{y}_h^*$$

The $100(1 - \alpha)\%$ confidence region is the collection of \mathbf{y}_h^* values that fail to reject H_0 at α level

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Test statistics:

$$T^2 = \left(\frac{\hat{B}^T \mathbf{x}_h - B^T \mathbf{x}_h}{\sqrt{\mathbf{x}_h^T (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{x}_h}} \right)^T \hat{\Sigma}^{-1} \left(\frac{\hat{B}^T \mathbf{x}_h - B^T \mathbf{x}_h}{\sqrt{\mathbf{x}_h^T (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{x}_h}} \right)$$
$$\stackrel{H_0}{\sim} \frac{d(n-p-1)}{n-p-d} F_{d, n-p-d}$$

Therefore, the $100(1 - \alpha)\%$ simultaneous **confidence interval** for y_{hk} is

$$\hat{y}_{hk} \pm \sqrt{\frac{d(n-p-1)}{n-p-d} F_{d, n-p-d}} \sqrt{\mathbf{x}_h^T (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{x}_h} \hat{\sigma}_{kk},$$

$$k \in \{1, \dots, d\}$$

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Here we want to predict the **observed value of response** for a given predictor

- **Note:** interested in actual \hat{y}_h instead of $\mathbb{E}(\hat{y}_h)$
- Given $\mathbf{x}_h = (1, x_{h1}, \dots, x_{hp})$, the fitted value is still $\hat{y}_h = \hat{\mathbf{B}}^T \mathbf{x}_h$

We can exploit the duality between interval estimation and hypothesis testing. That is, we can test

$$H_0 : \mathbf{y}_h = \mathbf{y}_h^* \text{ versus } H_a : \mathbf{y}_h \neq \mathbf{y}_h^*$$

The $100(1 - \alpha)\%$ prediction interval is the collection of \mathbf{y}_h^* values that fail to reject H_0 at α level

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Test statistics:

$$T^2 = \left(\frac{\hat{B}^T \mathbf{x}_h - B^T \mathbf{x}_h}{\sqrt{1 + \mathbf{x}_h^T (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{x}_h}} \right)^T \hat{\Sigma}^{-1} \left(\frac{\hat{B}^T \mathbf{x}_h - B^T \mathbf{x}_h}{\sqrt{1 + \mathbf{x}_h^T (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{x}_h}} \right)$$
$$\stackrel{H_0}{\sim} \frac{d(n-p-1)}{n-p-d} F_{d, n-p-d}$$

Therefore, the $100(1 - \alpha)\%$ simultaneous **prediction interval** for y_{hk} is

$$\hat{y}_{hk} \pm \sqrt{\frac{d(n-p-1)}{n-p-d} F_{d, n-p-d}} \sqrt{(1 + \mathbf{x}_h^T (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{x}_h) \hat{\sigma}_{kk}},$$

$$k \in \{1, \dots, d\}$$

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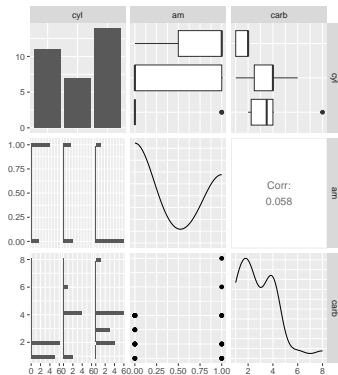
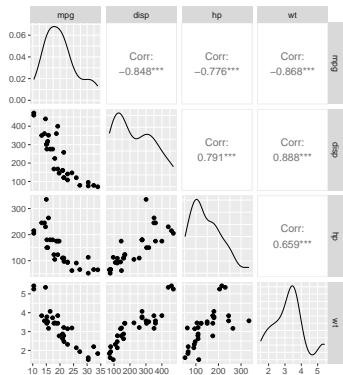
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Study the linear relationship between `mpg`, `disp`, `hp`, `wt` (responses) and `cyl`, `am`, `carb` (predictors) in the `mtcars` dataset



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- **Model:** `lm(Y ~ cyl + am + carb, data = mtcars)`
- **Key findings:**
 - `mpg`: decreases with more cylinders, increases with manual transmission
 - `disp`: strongly influenced by `cyl`
 - `hp`: influenced by `cyl8` and `carb`
 - `wt`: influenced by `cyl8`, `am`, `carb`
- **Note:** Multivariate regression produces the *same point estimates* as running separate regressions for each response

SSCP decomposition:

$$SSCP_{Tot} = SSCP_{Reg} + SSCP_{Err}$$

- Estimated error covariance matrix ($\hat{\Sigma}$)

	mpg	disp	hp	wt
mpg	7.8680094	-53.27166	-19.7015979	-0.6575443
disp	-53.2716607	2504.87095	425.1328988	18.1065416
hp	-19.7015979	425.13290	577.2703337	0.4662491
wt	-0.6575443	18.10654	0.4662491	0.2573503
	mpg	disp	hp	wt
mpg	1.0000000	-0.3794645	-0.29233405	-0.46209388
disp	-0.3794645	1.0000000	0.35354314	0.71314929
hp	-0.2923340	0.3535431	1.00000000	0.03825304
wt	-0.4620939	0.7131493	0.03825304	1.00000000

⇒ Captures residual dependencies among responses

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Do We Need “cyl”?

```
> mvlm0 <- lm(Y ~ am + carb, data = mtcars)
> anova(mvlm, mvlm0, test = "Wilks")
```

Analysis of Variance Table

Model 1: $Y \sim \text{cyl} + \text{am} + \text{carb}$

Model 2: $Y \sim \text{am} + \text{carb}$

	Res.Df	Df	Gen.var.	Wilks	approx F	num Df	Df
1	27		29.862				
2	29	2	43.692	0.16395	8.8181		8

	den Df	Pr(>F)
1		
2	48	2.525e-07 ***

Interpretation: cylinder count explains variation across responses

Default `predict()` lacks multivariate CI/PI, so we use an R function from Prof. Helwig at the University of Minnesota

```
> newdata <- data.frame(cyl = factor(6, levels = c(4, 6, 8)),  
+                        am = 1, carb = 4)  
> # confidence interval  
> pred.mlm(mvmlm, newdata)  
      mpg      disp      hp      wt  
fit 21.51824 159.2707 136.98500 2.631108  
lwr 16.65593  72.5141  95.33649 1.751736  
upr 26.38055 246.0273 178.63351 3.510479  
> # prediction interval  
> pred.mlm(mvmlm, newdata, interval = "prediction")  
      mpg      disp      hp      wt  
fit 21.518240 159.27070 136.98500 2.6311076  
lwr  9.680053 -51.95435  35.58397 0.4901152  
upr 33.356426 370.49576 238.38603 4.7720999
```

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In this lecture, we learned about Multivariate Linear Regression

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