

Extreme Value Analysis Part II: Multivariate and Spatial Extremes

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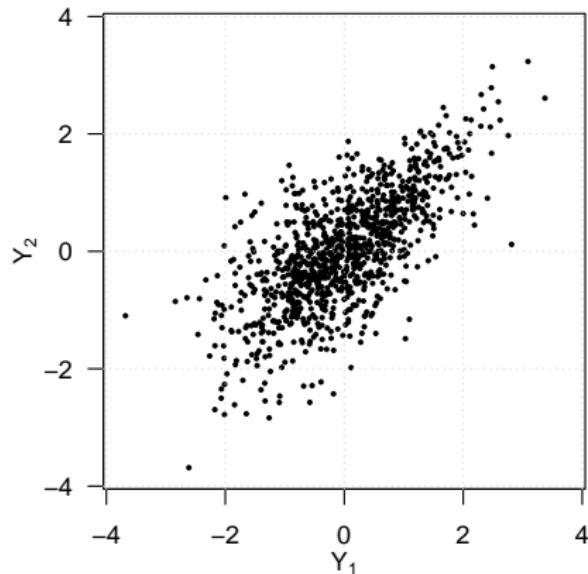
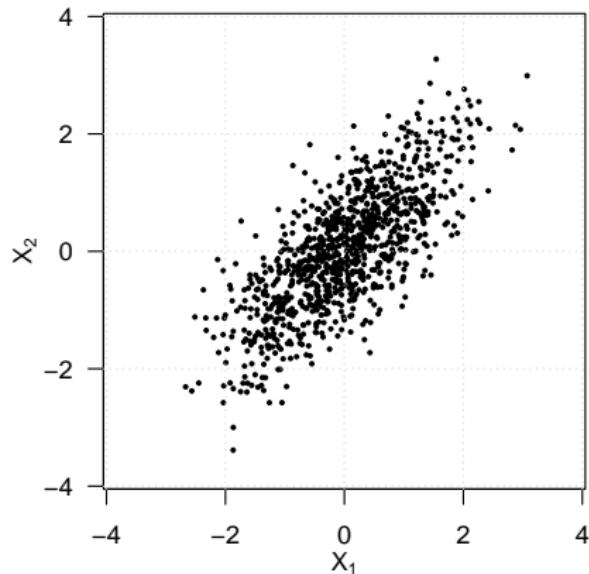
May 24, 2022



Today's Meeting Agenda

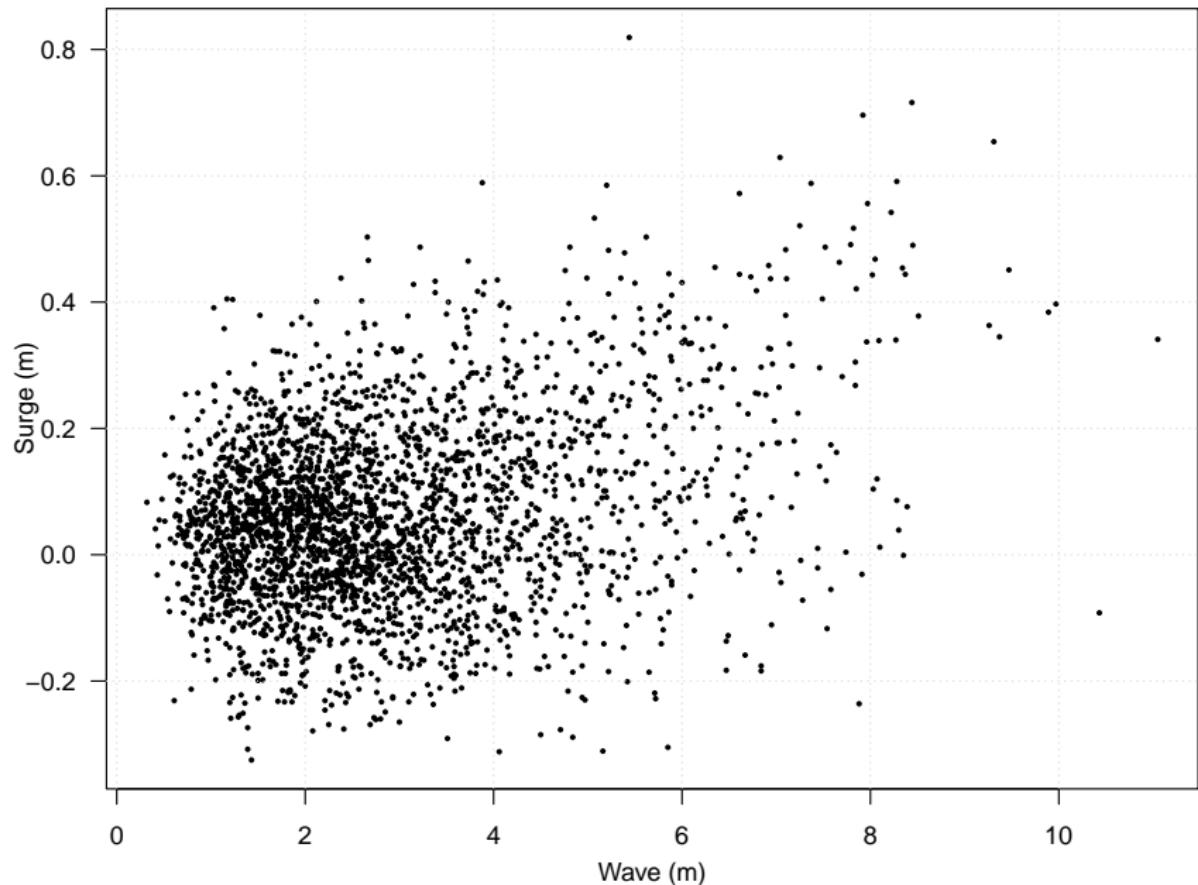
- ▶ Multivariate extremes
 - ▶ Describing tail dependence
 - ▶ Block Maxima Models
 - ▶ Threshold Exceedance Models
 - ▶ Conditional Extreme Value Models
- ▶ Spatial extremes
 - ▶ Weather vs. Climate
 - ▶ Bayesian Hierarchical Approaches
 - ▶ Max-Stable Process Models

Motivating Example

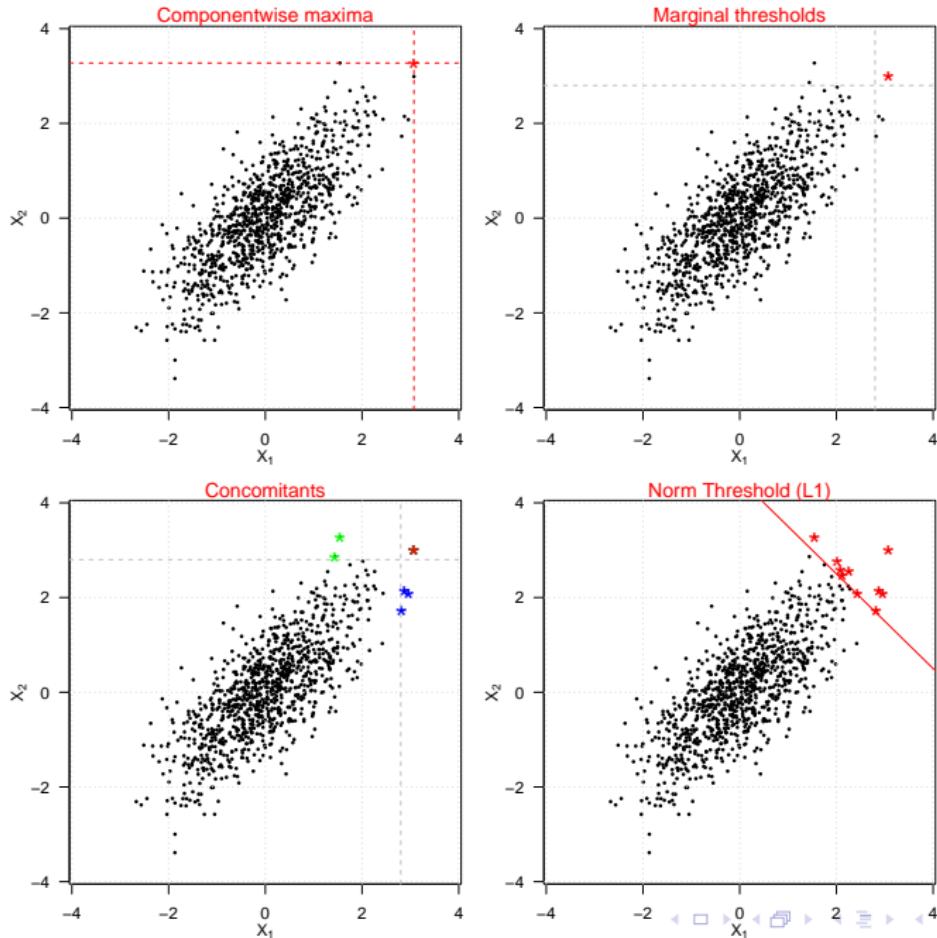


A central aim of multivariate extremes is to describe tail dependence

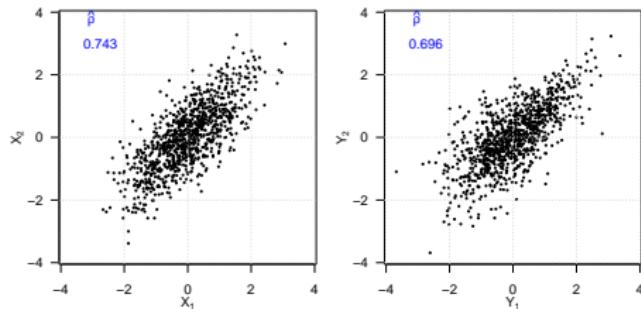
Example: Wave–Surge Data at Newlyn, UK



What is a Multivariate Extreme?

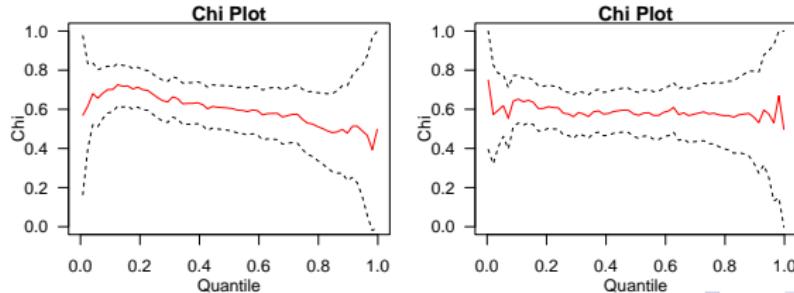


Measuring Tail Dependence



ρ measures “spread from center”, does not focus on extremes
Upper tail dependence parameter:

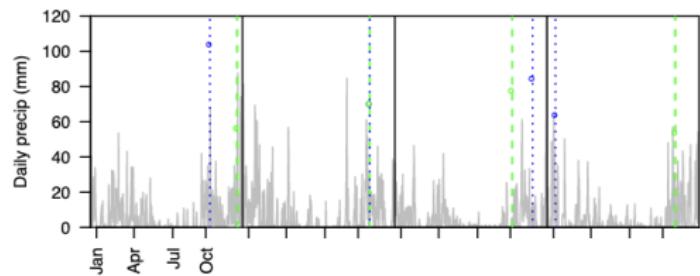
$$\chi = \lim_{u \rightarrow 1} \chi(u) = \mathbb{P}(F_{X_1}(X_1) > u | F_{X_2}(X_2) > u)$$



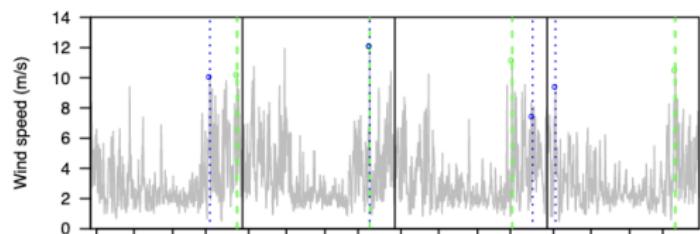
Componentwise Maxima

Let $\{\mathbf{X}_i = (X_{1,i}, \dots, X_{d,i})\} \in \mathbb{R}^d$ are i.i.d. random vectors. Let's first consider **componentwise maxima**:

$\mathbf{M}_n = (M_{1,n}, \dots, M_{d,n})^T$, where $M_{j,n} = \max_{i=1}^n X_{j,i}$



- ▶ Univariate GEV still apply in each margin
- ▶ Need to model the interdependence across $\{M_{j,n}\}_{j=1}^d$



- ▶ \mathbf{M}_n is not necessarily one the the original observations

Multivariate Extreme Value Theorem

Let $\mathbf{X}_1, \dots, \mathbf{X}_n \stackrel{\text{iid}}{\sim} \mathbf{F}$ where $\mathbf{X}_i \in \mathbb{R}^d$, if

$$\frac{\max_{i \leq i \leq n} \mathbf{X}_i - \mathbf{b}_n}{\mathbf{a}_n} = \left(\frac{\sqrt[n]{X_{1,i} - b_{1,n}}}{a_{1,n}}, \dots, \frac{\sqrt[n]{X_{d,i} - b_{d,n}}}{a_{d,n}} \right) \xrightarrow{d} \mathbf{G}$$

then \mathbf{G} must be a multivariate extreme value distribution

- ▶ Each marginal (approximately) follows a GEV distribution (i.e., $M_j \approx \text{GEV}(\mu_j, \sigma_j, \xi_j)$)
- ▶ No limiting parametric family exists for describing extremal dependence, i.e., the interdependence across $\{M_{j,n}\}_{j=1}^d$
- ▶ Marginals and dependence are typically handled separately \Rightarrow “Copula-like” approach

Multivariate GEV

- ▶ Transform each marginal to a common marginal distribution, e.g., unit Fréchet ($\text{GEV}(1, 1, 1)$)

$$\tilde{M}_j = \left[1 + \xi_j \left(\frac{M_j - \mu_j}{\sigma_j} \right) \right]^{\frac{1}{\xi_j}}$$

with $\tilde{G}(m) = \exp(m^{-1})$

- ▶ Then

$$\mathbb{P}(\tilde{M}_1 \leq \tilde{m}_1, \dots, \tilde{M}_d \leq \tilde{m}_d) = \exp(-V(\tilde{m}_1, \dots, \tilde{m}_d)),$$

where $V : \mathbb{R}_+^d \mapsto \mathbb{R}_+$ is the exponent measure that characterizes the extremal dependence

- ▶ In practice, modeling usually involves fitting a parametric family of V

Exponent Measure for Bivariate Extremes ($d = 2$)

$$\mathbb{P}(M_1 \leq m_1, M_2 \leq m_2) = \mathbb{P}(\tilde{M}_1 \leq \tilde{m}_1, \tilde{M}_2 \leq \tilde{m}_2) = \exp(-V(\tilde{m}_1, \tilde{m}_2)),$$

where

$$V(m_1, m_2) = 2 \int_0^1 \max\left(\frac{\omega}{m_1}, \frac{1-\omega}{m_2}\right) dH(\omega)$$

and H is a distribution on $[0, 1]$ satisfying the mean constraint:

$$\int_0^1 \omega dH(\omega) = \frac{1}{2}$$

Example: If H places mass 0.5 on $\omega = 0$ and 1, then we get

$$\mathbb{P}(\tilde{M}_1 \leq m_1, \tilde{M}_2 \leq m_2) = \exp\left\{-\left(m_1^{-1} + m_2^{-1}\right)\right\},$$

corresponding to independent of M_1 and M_2

The Logistic Model

$$G(m_1, m_2) = \exp \left\{ - \left(m_1^{-\frac{1}{\alpha}} + m_2^{-\frac{1}{\alpha}} \right)^{\alpha} \right\},$$

where m_1 and $m_2 > 0$, $\alpha \in (0, 1)$

- ▶ $\alpha \rightarrow 1$ corresponds to independent
- ▶ $\alpha \rightarrow 0$ corresponds to perfectly dependent
- ▶ This model is symmetric \Rightarrow the variables are exchangeable, that is, M_1 depends on M_2 to exactly the same degree that M_2 depends on M_1

The Bilogistic Model

$$G(m_1, m_2) = \exp \left\{ m_1 \gamma^{1-\alpha} + m_2 (1 - \gamma)^{1-\beta} \right\},$$

where $0 < \alpha < 1$, $0 < \beta < 1$, and γ is the solution of:

$$(1 - \alpha)m_1(1 - \gamma)^\beta = (1 - \beta)m_2\gamma^\alpha$$

- ▶ **Independence** is obtained when $\alpha = \beta \rightarrow 1$ and when one of α or β is fixed and the other approaches 1
- ▶ When $\alpha = \beta$ the model reduces to the logistic model
- ▶ The value of $\alpha - \beta$ determines the extent of **asymmetry** in the dependence structure

Parameter Estimation

Models (e.g., Logistic or Bilogistic) can be fitted by maximum likelihood estimation, either:

- ▶ two steps: marginal GEV components followed by dependence function, or
- ▶ one step that estimates marginals and dependence structure simultaneously

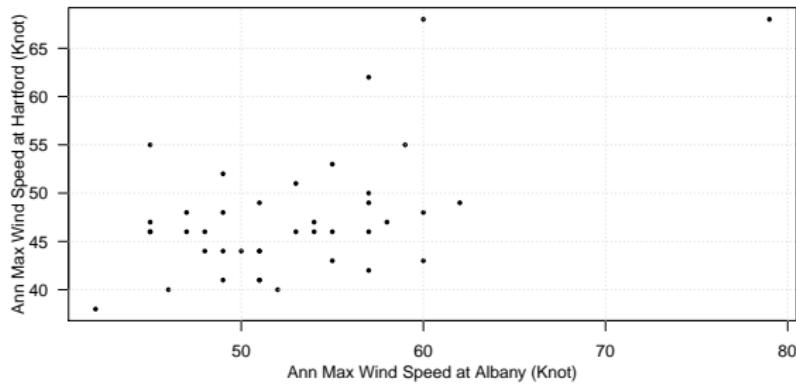
The probability density function is

$$g(m_1, m_2) = \{V_{m_1} V_{m_2} - V_{m_1 m_2}\} \exp(-V(m_1, m_2)),$$

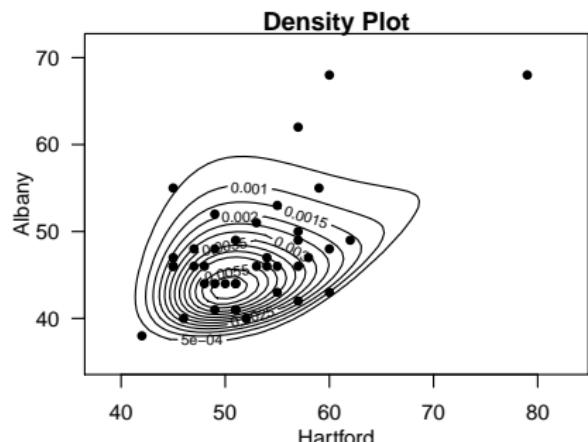
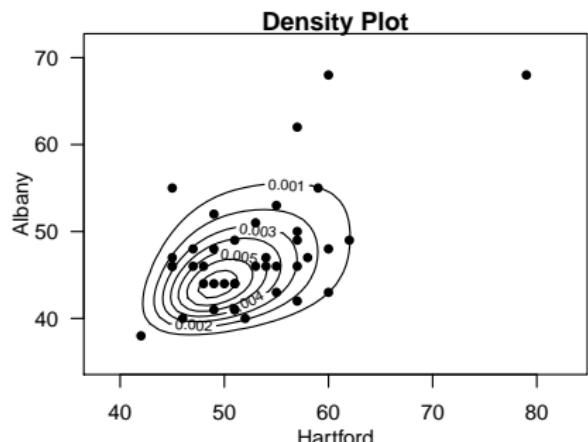
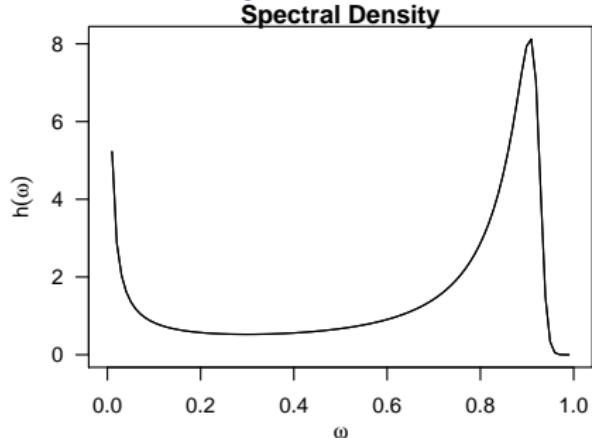
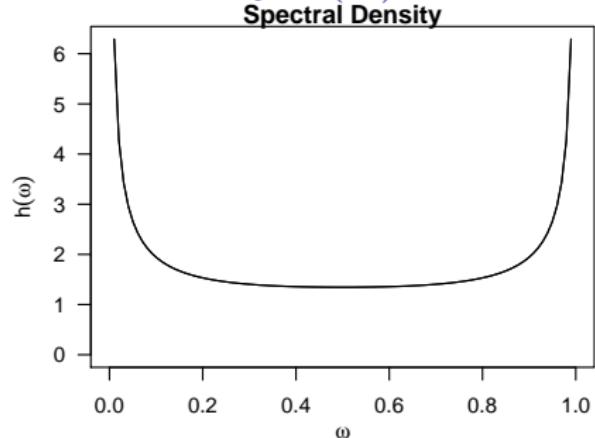
where V_{m_1} , V_{m_2} , and $V_{m_1 m_2}$ denote partial derivatives of V .

With the (transformed) data $(\tilde{m}_{1,i}, \tilde{m}_{2,i})_{i=1}^m$, one can maximize the log-likelihood $\ell(\theta) = \sum_{i=1}^m \log g(\tilde{m}_{1,i}, \tilde{m}_{2,i})$ to obtain maximum likelihood estimates and standard errors

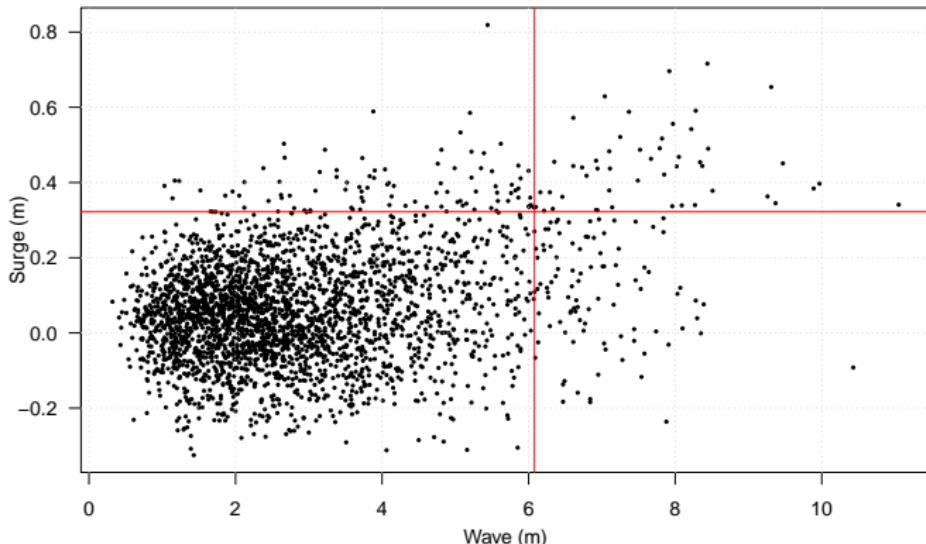
Annual Maximum Wind Speeds at Albany and Hartford



Spectral Density $h(\omega)$ and Bivariate Density Contour



Bivariate Threshold Excess Model

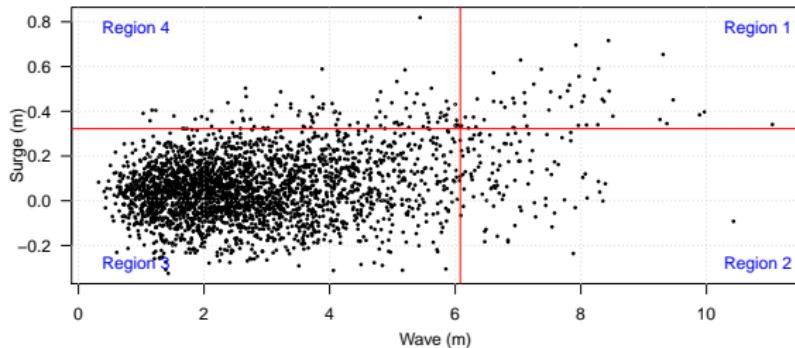


Main idea:

$$F(x_1, x_2) \approx G(x_1, x_2) = \exp(-V(\tilde{x}_1, \tilde{x}_2)), \quad x_1 > u_{x_1}, x_2 > u_{x_2},$$

where marginal transformation (from GPD to unit Fréchet) can be achieved by probability integral transformation

Likelihood Calculations



$$g(x_1, x_2) = \begin{cases} \frac{\partial^2 G}{\partial x_1 \partial x_2} |_{(\tilde{x}_1, \tilde{x}_2)} & \text{if } (x_1, x_2) \in \text{Region 1}; \\ \frac{\partial G}{\partial x_1} |_{(\tilde{x}_1, \tilde{u}_{x_2})} & \text{if } (x_1, x_2) \in \text{Region 2}; \\ \frac{\partial G}{\partial x_2} |_{(\tilde{u}_{x_1}, \tilde{x}_2)} & \text{if } (x_1, x_2) \in \text{Region 3}; \\ G(\tilde{u}_{x_1}, \tilde{u}_{x_2}) & \text{if } (x_1, x_2) \in \text{Region 4}. \end{cases}$$

Wave-Surge Analysis at Newlyn

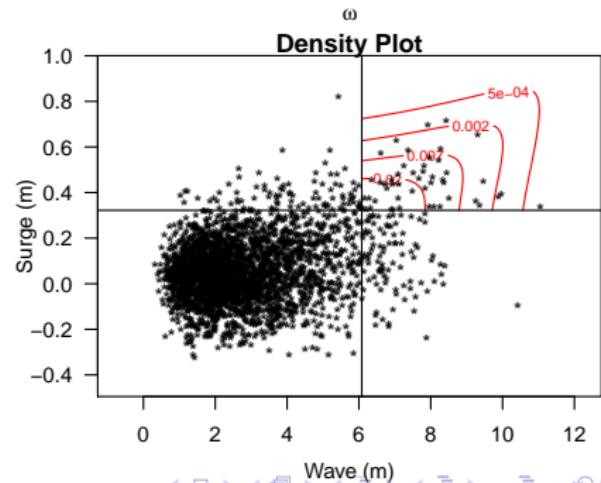
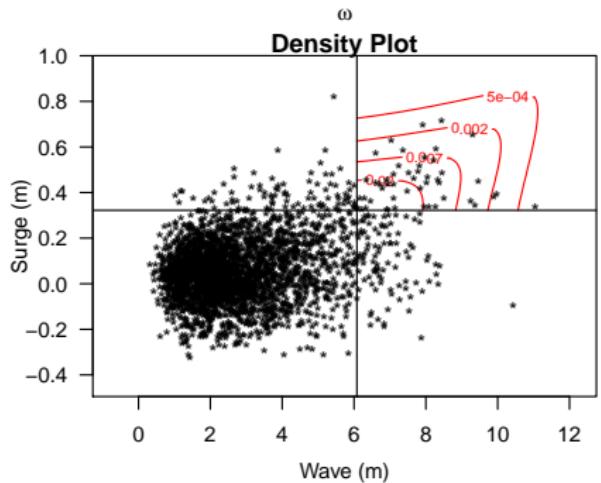
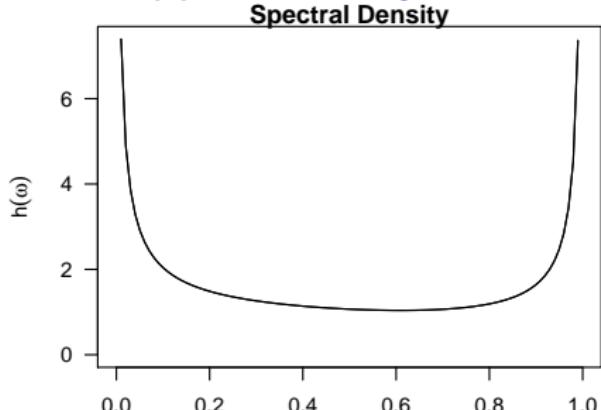
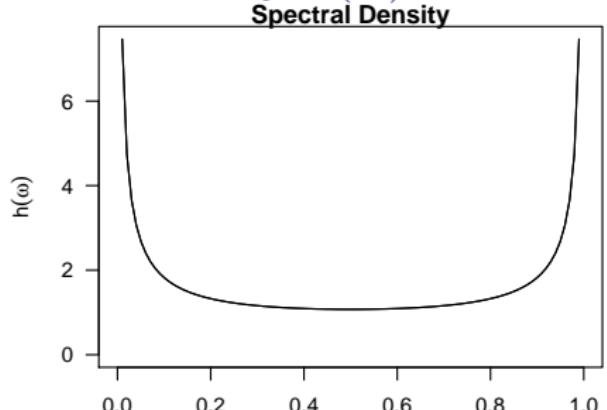
Marginal Parameter Estimates

Model	σ_{u_1}	ξ_1	σ_{u_2}	ξ_2
Logistic	1.26	-0.13	0.09	0.01
Bilogisitc	1.27	-0.14	0.09	0.01

Dependence Parameter Estimates

Model	log-lik.	α	β
Logistic	-1018.04	0.76	
Bilogisitc	-1017.90	0.79	0.73

Spectral Density $h(\omega)$ and Bivariate Upper Density Contour



Asymptotic Dependence and Independence

One key problem with using limit distributions for multivariate extremes is that they force one of two possibilities:

- ▶ **Asymptotic Dependence (AD):** extremes occur with a dependence structure which conforms to an extreme value distribution

$$\rightarrow \chi = \lim_{u \rightarrow 1} \mathbb{P}(F_{X_1}(X_1) > u | F_{X_2}(X_2) > u) > 0$$

- ▶ **Asymptotic Independence (AI):** extremes occur independently in the different margins

$$\rightarrow \chi = \lim_{u \rightarrow 1} \mathbb{P}(F_{X_1}(X_1) > u | F_{X_2}(X_2) > u) = 0$$

Often AI is suggested by the data, and yet quite strong dependence is still present at high levels (e.g., Gaussian copula with $\rho \neq 1$)

Conditional Extreme Value (CEV) Models [Heffernan & Tawn, 04]

Models the conditional distribution by assuming a **parametric** location-scale form after marginal transformation

► Marginal modeling:

1. Estimate marginal distributions of Y and X
2. Transform $(Y, X)^T$ to Laplace marginals $(\tilde{Y}, \tilde{X})^T$

► Dependence modeling:

Assume for large u ,

$$\left[\frac{\tilde{Y} - a(\tilde{X})}{b(\tilde{X})} \leq z | \tilde{X} > u \right] \sim G(z),$$

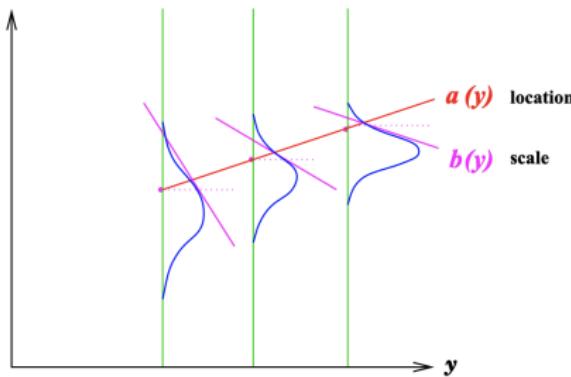
where $a(x) = \alpha x$ and $b(x) = x^\beta$, $\alpha \in [-1, 1]$, $\beta \in (-\infty, 1)$

A cartoon illustration of the CEV dependence modeling

Assume for large u ,

$$\left[\frac{\tilde{Y} - a(\tilde{X})}{b(\tilde{X})} \leq z | \tilde{X} > u \right] \sim G(z),$$

where $a(x) = \alpha x$ and $b(x) = x^\beta$, $\alpha \in [-1, 1]$, $\beta \in (-\infty, 1)$

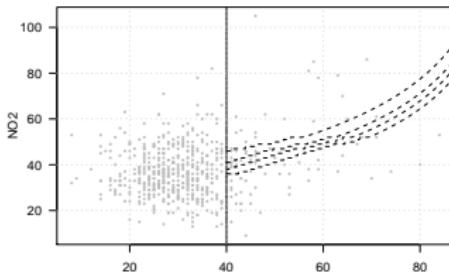
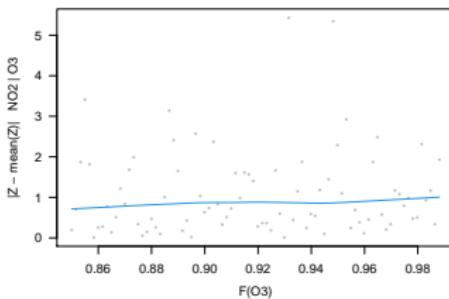
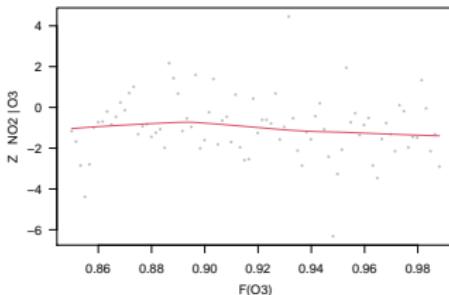


- ▶ $\tilde{Y} = \alpha \tilde{X} + \tilde{X}^\beta Z$,
 $\Rightarrow Z = \frac{\tilde{Y} - \alpha \tilde{X}}{\tilde{X}^\beta} \sim G$
- ▶ α and β are estimated by making a parametric assumption of \tilde{Y}
- ▶ G estimated nonparametrically

Source: Heffernan's slides given at the Interface 2008 Symposium

Modeling “Summer” O₃ and NO₂ [Heffernan & Tawn, 2004]

- ▶ Apr.-July, 1994-1998 daily maximum air pollution data from Leeds, U.K.
- ▶ Need to choose several thresholds: one for each marginal and a threshold for the dependence structure
- ▶ $\tilde{Y} = \alpha \tilde{X} + \tilde{X}^\beta Z$,
 $\Rightarrow Z = \frac{\tilde{Y} - \alpha \tilde{X}}{\tilde{X}^\beta} \sim G$
 $\hat{\alpha} = 0.77, \hat{\beta} = 0.188$

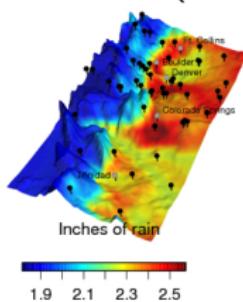
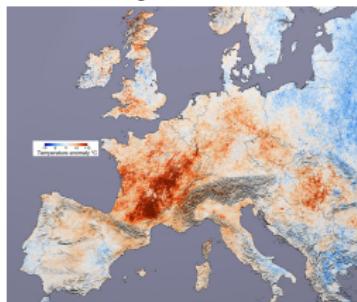


Summary of Multivariate Extreme Value Analysis

- ▶ Definition of a multivariate extreme is not obvious
- ▶ Tail dependence NOT summarized with correlations, we looked at the extremal coefficient
- ▶ Methodologies exist for both block maxima and threshold exceedance approaches
- ▶ Conditional extreme value models for asymptotic independence cases

Spatial Extremes: Why Spatial Matters?

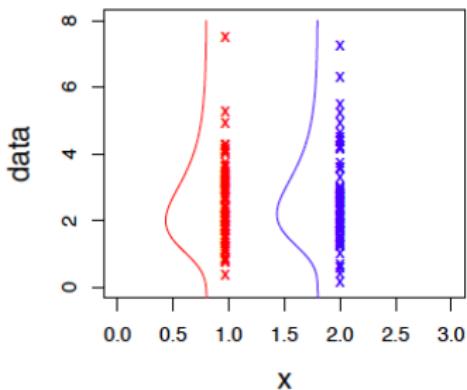
- ▶ Quantity of interest often has a (continuous) spatial domain



- ▶ "Everything is related to everything else, but near things are more related than distant things." – Waldo Tobler
- ▶ Spatial interpolation of:
 - ▶ **Climate (marginal)**: model how tail distributions vary in space, e.g., **return level maps**
 - ▶ **Weather (dependence)**: fill in extreme values in space

Main Objectives

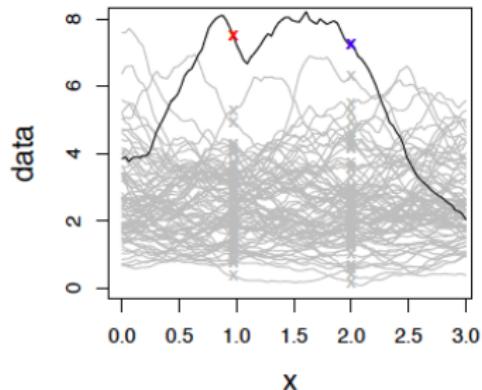
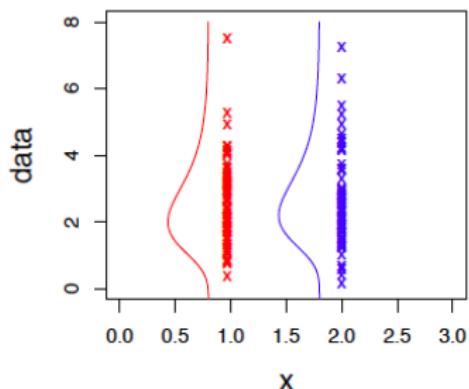
- ▶ Marginal modeling: model the site-wise behavior of extremes by using extreme value distribution (i.e. GEV, GPD)
- ▶ Dependence modeling: model the spatial dependence of the extreme values



Figures courtesy of Jenny Wadsworth

Main Objectives

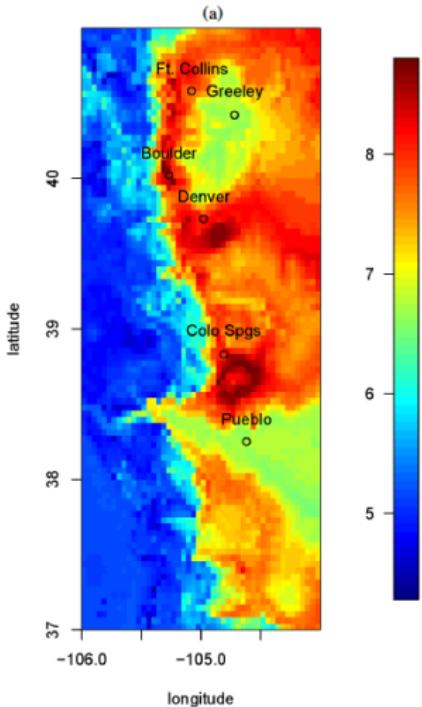
- ▶ Marginal modeling: model the site-wise behavior of extremes by using extreme value distribution (i.e. GEV, GPD)
- ▶ Dependence modeling: model the spatial dependence of the extreme values



Figures courtesy of Jenny Wadsworth

Estimating Return Level Maps

- ▶ $M(\mathbf{s}) \approx \text{GEV}(\mu(\mathbf{s}), \sigma(\mathbf{s}), \xi(\mathbf{s})), \mathbf{s} \in \mathcal{S}$
where $M(\mathbf{s}) = \max_{i=1}^n X_i(\mathbf{s})$. E.g.
 $X_i(\mathbf{s})$: daily cumulative precipitation
at site \mathbf{s}
- ▶ Have observations at $\mathbf{s}_1, \dots, \mathbf{s}_k$, could fit a GEV to each location **But ...**
- ▶ Need spatial models for $\mu(\mathbf{s}), \sigma(\mathbf{s}), \xi(\mathbf{s}), \mathbf{s} \in \mathcal{S}$
 - ▶ spatial interpolation to produce the **return level map**
 - ▶ borrowing strength over space



Source: Fig. 8 (a) of Cooley et al. 2007

Bayesian Hierarchical Approach [Cooley et al. 2007]

Model the spatial dependence of parameters of extreme value distribution

$$\left\{ \underbrace{\pi(\theta_1(s), \theta_2 | m(s))}_{\text{posterior}} \propto \underbrace{\pi(m(s) | \theta_1(s))}_{\text{data}} \underbrace{\pi(\theta_1(s) | \theta_2)}_{\text{process}} \underbrace{\pi(\theta_2)}_{\text{prior}} \right\}_{s \in \mathcal{D}}$$

- ▶ **Process level:** model each parameter across the spatial region as a Gaussian process to induce the spatial dependence
- ▶ **Data level:** marginals follow independent extreme value distribution given the parameters at the process level

The main purpose is to generate the return level map, e.g.
100 year **site-wise** precipitation event

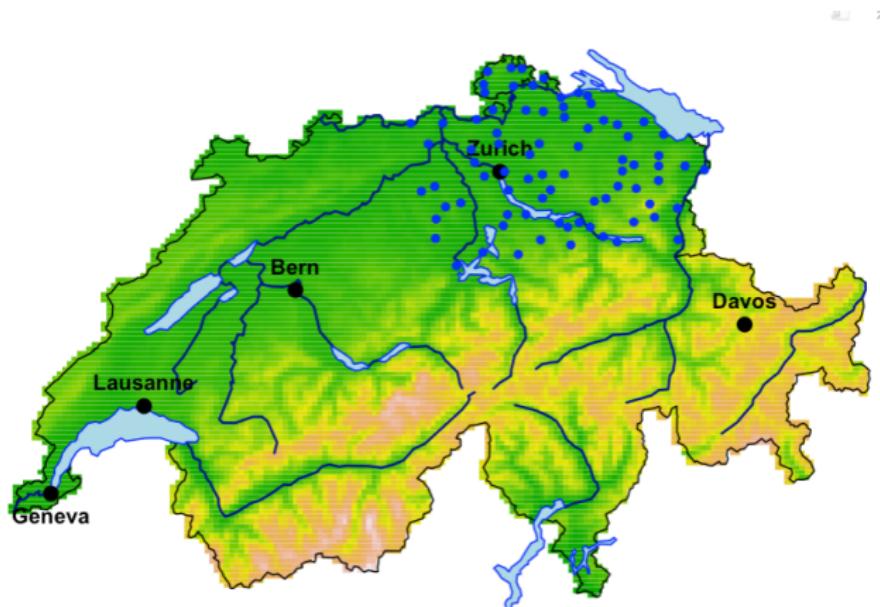
Hierarchical Approach Cont'd

- ▶ Data: $Y(\mathbf{s}_i) | (\mu(\mathbf{s}), \sigma(\mathbf{s}), \xi(\mathbf{s})) \stackrel{i.i.d.}{\sim} \text{GEV}(\mu(\mathbf{s}_i), \sigma(\mathbf{s}_i), \xi(\mathbf{s}_i))$, $\mathbf{s}_i \in \mathcal{S}$
- ▶ Latent processes: $(\mu(\mathbf{s}), \phi(\mathbf{s}) = \log(\sigma(\mathbf{s})), \xi(\mathbf{s}))$ are **Gaussian Processes GP($m(\cdot)$, $K_\theta(\cdot, \cdot)$)**
- ▶ Prior: need to specify the prior distributions of the parameters for mean and covariance functions to carry out Bayesian inference \Rightarrow can be difficult to specify

Estimating Switzerland Rainfall Return Level Map

[Davison, Padoan & Ribatet, 2012]

Summer (June–Aug.) annual maxima precipitation in Switzerland over the years 1962–2008



Let's give a try on using Bayesian hierarchical approach to produce, say, 20-year return level

R Implementation in SpatialExtremes

```
## Prior specification
```

```
```{r}
hyper <- list()
hyper$betaMeans <- list(loc = rep(0, 3), scale = rep(0, 3), shape = 0)
hyper$betaIcov <- list(loc = diag(rep(1/1000, 3)), scale = diag(rep(1 / 1000, 3)),
shape = 1 / 10)
hyper$sills <- list(loc = c(1, 12), scale = c(1, 1), shape = c(1, 0.04))
hyper$ranges <- list(loc = c(5, 3), scale = c(5, 3), shape = c(5, 3))
hyper$smooths <- list(loc = c(1, 1), scale = c(1, 1), shape = c(1, 1))
prop <- list(gev = c(3, 0.1, 0.3), ranges = c(1, 0.8, 1.2), smooths = rep(0, 3))
start <- list(sills = c(10, 10, 0.5), ranges = c(20, 10, 10), smooths = c(1, 1, 1),
beta = list(loc = c(25, 0, 0), scale = c(33, 0, 0), shape = 0.001))
```

```

```
### Running the Gibbs sampler
```

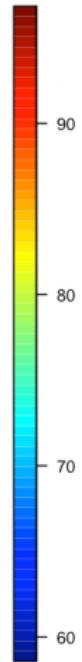
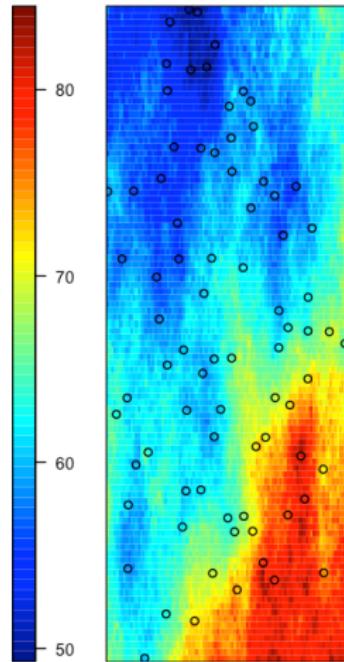
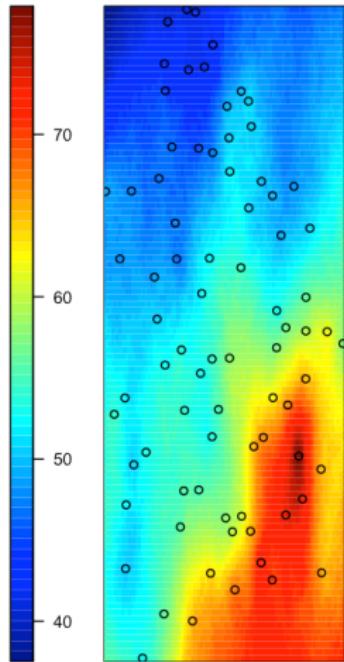
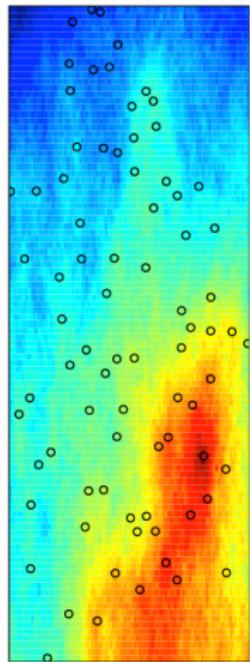
```
```{r}
loc.form <- scale.form <- y ~ lon + lat; shape.form <- y ~ 1
chain <- latent(rain, coord[, 1:2], "powexp", loc.form, scale.form, shape.form, hyper =
hyper,
 prop = prop,
start = start, n = 100, burn.in = 500, thin = 5)
chain
```

```

Summary of Bayesian Hierarchical Approach

- ▶ +: The latent variable approach is very flexible and can help in improving “weak” trend surfaces
- ▶ +: Easily extends to threshold exceedances
- ▶ -: It is however time consuming and no spatial dependence (on the data layer) is taken into account
- ▶ -: Quite difficult to define prior distributions and identifiability problems—typically sill and ranges.

Inference for 20-Year Return Level



Extremes of Stochastic Processes

So far the spatial dependence in extremes has been ignored, it is time to take it into account using max-stable processes

- ▶ Motivating example:

$$1 - \mathbb{P}(X_t(s) \leq h(s) \quad \forall s \in \mathcal{S}, \quad \forall t \in [a, b])$$

e.g. $X_t(s)$ be the sea level at location s at time t and $h(s)$ be the height of seawall at s

- ▶ Want: a limiting stochastic process $\{M(s)\}_{s \in \mathcal{S}}$ s.t.

$$\left\{ \frac{\max_{t=1}^n X_t(s) - b_n(s)}{a_n(s)} \right\}_{s \in \mathcal{S}} \xrightarrow{fdd} \{M(s)\}_{s \in \mathcal{S}}$$

It turns out that if such a $\{M(s)\}_{s \in \mathcal{S}}$ exists, it must be a max-stable process

Max-stable processes

A stochastic process $\{M(s)\}_{s \in \mathcal{S}}$ is **max-stable** if there exist functions $\{a_n(s)\}_{s \in \mathcal{S}} > 0$ and $\{b_n(s)\}_{s \in \mathcal{S}}$ such that

$$\left\{ \frac{\max_{i=1}^n M_i - b_n(s)}{a_n(s)} \right\}_{s \in \mathcal{S}} \stackrel{fdd}{=} \{M(s)\}_{s \in \mathcal{S}}, \quad n \geq 1$$

where M_1, \dots, M_n be the independent copies of $\{M(s)\}_{s \in \mathcal{S}}$

- ▶ $\{M(s)\}_{s \in \mathcal{S}}$: pointwise maxima over the spatial domain
- ▶ Any max-stable process, after marginal transformation, has its spectral representation (see next slide) \Rightarrow it is easier to specify/construct a max-stable process via the spectral representation

Spectral Representations for Max-Stable Processes [de Haan, 1984; Schlather, 2002]

Let $\{\zeta_i\}_{i \geq 1}$ be the points of Poisson process on $(0, \infty]$ with intensity $d\Lambda(\zeta) = \zeta^{-2} d\zeta$ and W_1, W_2, \dots be independent copies of a non-negative stochastic process $\{W(s)\}_{s \in \mathbb{R}^k}$ such that $\mathbb{E}[W(s)] = 1 \forall s \in \mathbb{R}^k$. Suppose $\{\zeta_i\}_{i \geq 1}$ independent of W_i 's.

Then

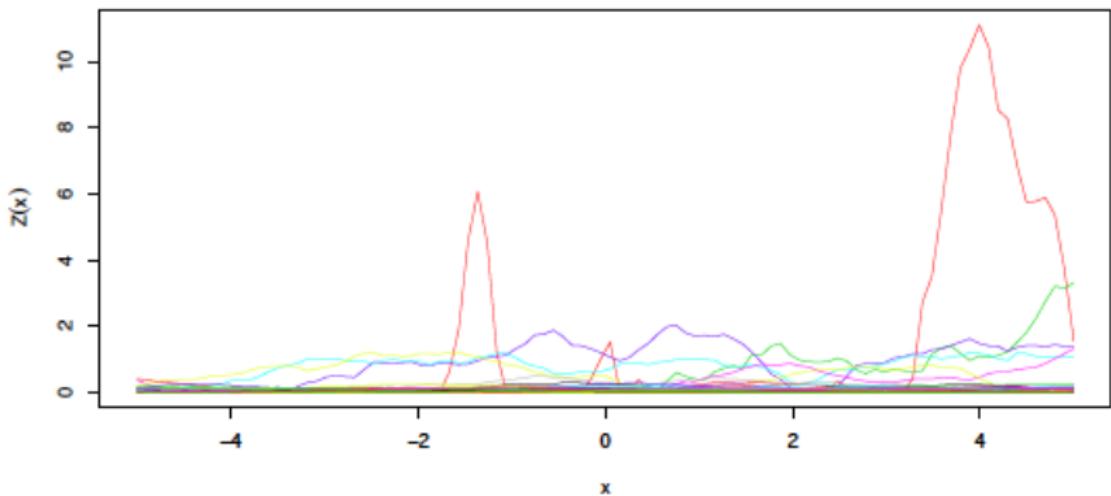
$$\left\{ \sqrt{\zeta_i} W_i(s) \right\}_{s \in \mathbb{R}^k}$$

is max-stable process with unit Fréchet marginals

e.g. Brown–Resnick model: $W(s) = \exp(\varepsilon(s) - \gamma(s))$, $s \in \mathbb{R}^k$, where $\{\varepsilon(s)\}$ is a Gaussian process with stationary increments and semivariogram γ

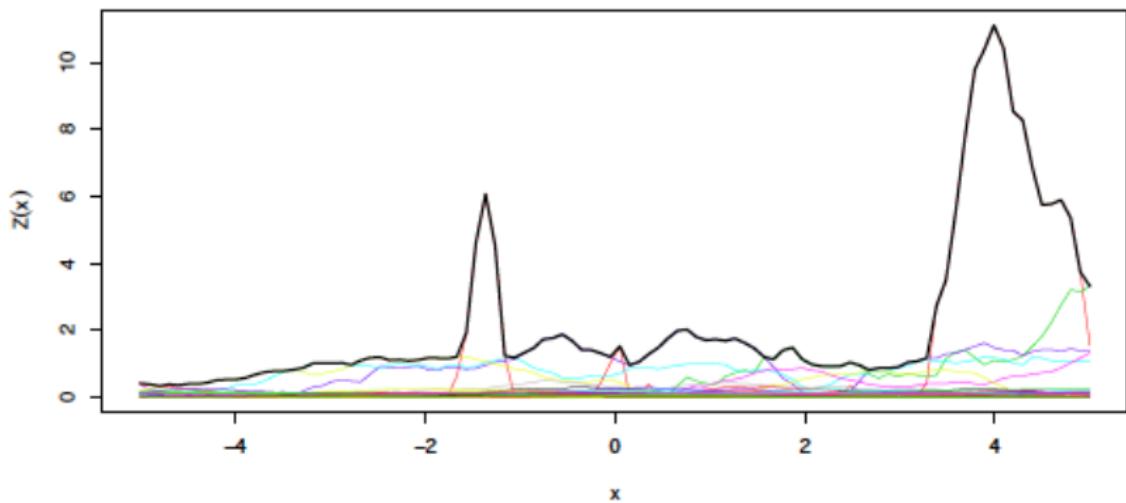
Schlather's Spectral Representation

$$\{\zeta_i W_i(s)\}_{s \in \mathbb{R}^k}$$



Schlather's Spectral Representation Cont'd

$$\left\{ \sqrt{\zeta_i} W_i(\mathbf{s}) \right\}_{\mathbf{s} \in \mathbb{R}^k}$$



Likelihood for a Max-Stable Process

Recall

$$\mathbb{P}(M_1 \leq m_1, \dots, M_d \leq m_d) = \exp\left(-\mathbb{E}\left[\max\left\{\frac{W(s_1)}{m_1}, \dots, \frac{W(s_d)}{m_d}\right\}\right]\right)$$

$\underbrace{\quad\quad\quad}_{V(m_1, \dots, m_d) \equiv V}$

joint density

$$\frac{\partial}{\partial m_1 \cdots \partial m_d} e^{-V} = e^{-V} \sum_{\pi \in \mathcal{P}_d} (-1)^{|\pi|} \prod_{j=1}^{|\pi|} \frac{\partial^{|\tau_j|}}{\partial m_{\tau_j}} V$$

where the cardinality of $\mathcal{P}_d = B_d$, the Bell number of order d

$$B_3 = 5$$

$$B_{10} = 115,975$$

$$B_{25} = 4,638,590,332,229,999,353!$$

Current Modeling Practice on Spatial Extremes

- ▶ Composite likelihood ([Lindsay, 1988](#)): pairwise likelihoods ([Padoan et al. \(2010\)](#)), Triplewise likelihoods ([Genton et al. \(2011\)](#), [Huser and Davison \(2013\)](#))
- ▶ Bayesian hierarchical approach for max-stable processes: [Reich and Shaby \(2012\)](#)
- ▶ Full likelihood by exploiting “temporal” information: [Wadsworth and Tawn \(2014\)](#), [Thibaud et al. \(2015\)](#)

Extremal Coefficient Function

The extremal coefficient is

$$\theta = \frac{\log \mathbb{P}(\max_{j=1}^d M(\mathbf{s}_j) \leq m)}{\log \mathbb{P}(M(\mathbf{s}) \leq m)} = V(1, \dots, 1).$$

$$1 \text{ (dependence)} \leq \theta \leq d \text{ (independence)}$$

- ▶ In a spatial context it is often more convenient to consider bivariate extremal coefficients and link to their pairwise spatial distances
- ▶ One can use F-madogram (Cooley, Naveau, & Poncet, 2006)

$$\nu_F(h) = \frac{1}{2} \mathbb{E} [|F(M(\mathbf{s})) - F(M(\mathbf{s}'))|]$$

to estimate

$$\theta(h) = \frac{1 - 2\nu_F(h)}{1 + 2\nu_F(h)}$$

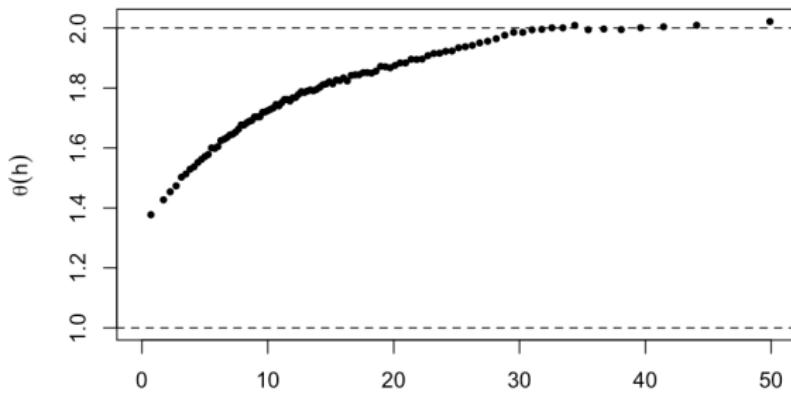
Fitting Max-Stable Processes using Pairwise Likelihood

Since the (full) likelihood is too expensive to compute, we consider pairwise log-likelihood

$$\ell_p(\theta; \mathbf{m}) = \sum_{t=1}^T \sum_{j=1}^{d-1} \sum_{k=j+1}^d w_{jk} \log g(m_t^{(j)}, m_t^{(k)}; \theta)$$

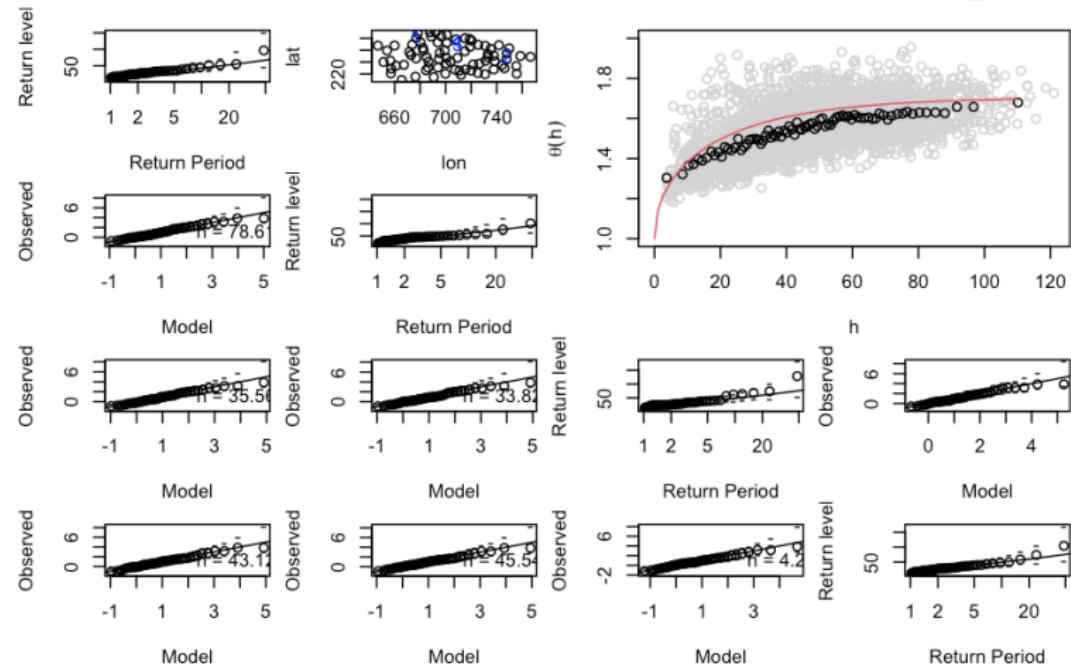
- ▶ g is the density of the associated bivariate GEV where spatial covariates can be added to define trend surfaces
- ▶ Maximize this gives the maximum composite likelihood estimator (MCLE)
- ▶ Inference can be performed under the composite likelihood framework

Summer Annual Maxima Temperature in Continental US, 1911-2010



Fitting Max-Stable Process Model!

```
```{r}
loc.form <- y ~ lon + lat + alt
scale.form <- y ~ lon + lat
shape.form <- y ~ 1
(fit <- fitmaxstab(rain, coord, "powexp", nugget=0, loc.form, scale.form, shape.form,
marg.cov = cbind(alt = alt)))
plot(fit)
````
```



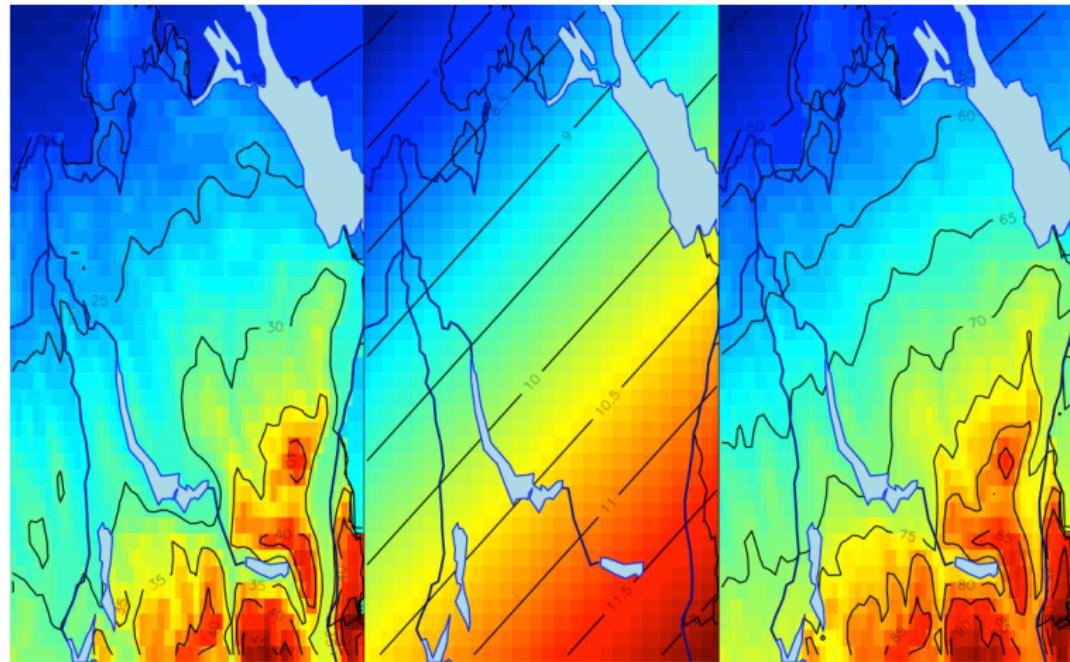
Model Selection

```
> M0 <- fitmaxstab(rain, coord, "powexp", nugget = 0, locCoeff4 = 0, loc.form, scale.form, shape.form,
+ marg.cov = cbind(alt = alt))
Computing appropriate starting values
Starting values are defined
Starting values are:
  range    smooth   locCoeff1   locCoeff2   locCoeff3   locCoeff4
27.257344723  0.974059614 29.764826111  0.037985247 -0.135302350  0.008372902
  scaleCoeff1  scaleCoeff2  scaleCoeff3  shapeCoeff1
10.529521199  0.013058818 -0.040111724  0.156381541
> M1 <- fitmaxstab(rain, coord, "powexp", nugget = 0,
+ loc.form, scale.form, shape.form, marg.cov = cbind(alt = alt))
Computing appropriate starting values
Starting values are defined
Starting values are:
  range    smooth   locCoeff1   locCoeff2   locCoeff3   locCoeff4
27.257344723  0.974059614 29.764826111  0.037985247 -0.135302350  0.008372902
  scaleCoeff1  scaleCoeff2  scaleCoeff3  shapeCoeff1
10.529521199  0.013058818 -0.040111724  0.156381541
> anova(M0, M1)
Eigenvalue(s): 161.12

Analysis of Variance Table
  MDf Deviance Df Chisq Pr(> sum lambda Chisq)
M0   9  2246053
M1  10  2232232  1 13821          < 2.2e-16 ***
---
Signif. codes:  0 ‘***’ 0.001 ‘**’ 0.01 ‘*’ 0.05 ‘.’ 0.1 ‘ ’ 1
```

Prediction

Spatial maps for μ , σ , and 20-year return level



Summary of Max-Stable Process Models

- ▶ +: Justified by extreme value theory
- ▶ +: Able to describe asymptotic dependence
- ▶ -: Describe everything that is asymptotically independent as exactly independent