

System Modeling

Finite State Machine

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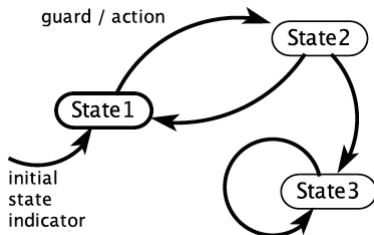
State Machine Models

- Summarize the behavior of an object or a subsystem in response to messages and events
- Shows how the object instance changes state depending on the messages that it receives
- Usually need a state diagram for the complex objects in the system

Finite State Machine

State Machine: Model of a system with discrete dynamics

Finite-State Machine (FSM): A state machine where the set *States* of possible states is finite

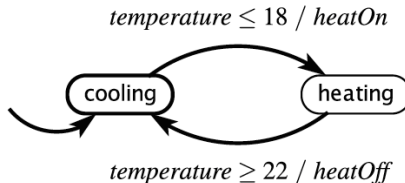


- State
- Initial State
- Transition
 - Self transition
 - Guard and Action

Example: FSM for Thermostat

input: *temperature* : \mathbb{R}

outputs: *heatOn*, *heatOff* : pure



Chattering: the heater would turn on and off rapidly when the temperature is close to the set-point temperature

Solution: **hysteresis** strategy, **dwel time**

Event-triggered vs. time-triggered transitions

Mathematical Notation of a State Machine

A finite state machine is represented as a five-tuple

$$(\textit{States}, \textit{Inputs}, \textit{Outputs}, \textit{update}, \textit{initialState})$$

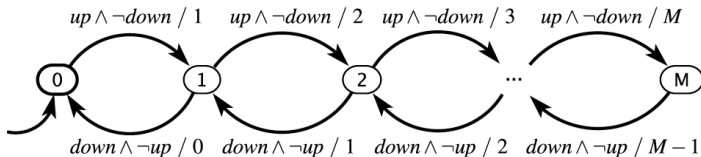
where,

- *States* is a finite set of states
- *Inputs* is a set of input valuations
- *Outputs* is a set of output valuations
- $\textit{update} : \textit{States} \times \textit{Inputs} \rightarrow \textit{States} \times \textit{Outputs}$ is an **update function**, mapping a state and an input valuation to a next state and an output valuation
- *initialState* is the initial state

Example: Garage Counter

inputs: $up, down$: pure

output: $count : \{0, \dots, M\}$



$States = \{0, 1, \dots, M\}$

$Inputs = (\{up, down\} \rightarrow \{present, absent\})$

$Outputs = (\{count\} \rightarrow \{0, 1, \dots, M, absent\})$

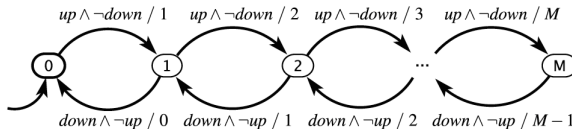
$initialState = 0$

Update function:

$$update(s, i) = \begin{cases} (s + 1, s + 1) & \text{if } s < M \wedge up \wedge \neg down \\ (s - 1, s - 1) & \text{if } s > 0 \wedge \neg up \wedge down \\ (s, absent) & \text{otherwise} \end{cases}$$

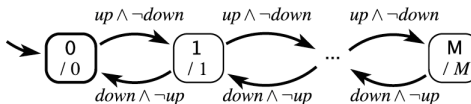
Mealy Machines and Moore Machines

inputs: $up, down$: pure
output: $count : \{0, \dots, M\}$



Mealy Machine: Produces outputs when a transition is taken

inputs: $up, down$: pure
output: $count : \{0, \dots, M\}$



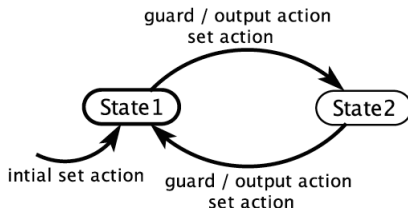
Moore Machine: Produces outputs when the machine is in a state

Extended State Machine

Augments the FSM Model with variables

Variables may be read and written while taking a transition

variable declaration(s)
input declaration(s)
output declaration(s)



The number of states. can be quite large, or even infinite
 n discrete states, m variables each of which can have one of p possible values

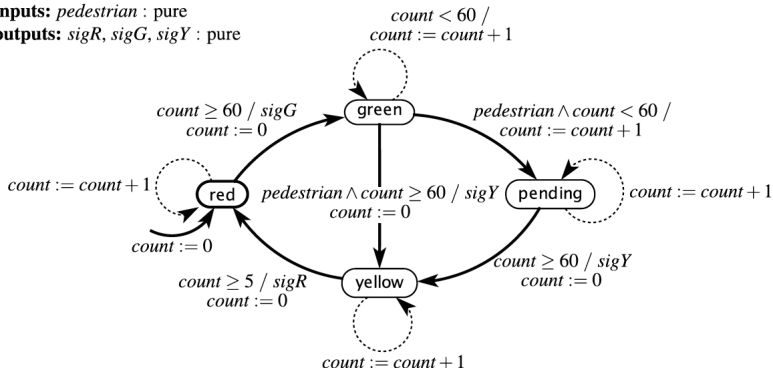
$$| \text{States} | = np^m$$

Example: ESM for Traffic Light

variable: $count: \{0, \dots, 60\}$

inputs: $pedestrian: \text{pure}$

outputs: $sigR, sigG, sigY: \text{pure}$



All states that can be reached from the initial state on some input sequence

May be smaller than the set of states

Traffic Light:

Total number of states = 244

Total number of reachable states = 189

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