

Q-Learning for Maze Navigation in Webots

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Problem and Dataset

- **Problem:** Navigating unknown mazes using reinforcement learning (Q-learning) in a simulated environment (Webots).
- **Goal:** Duplicate the method from a primary paper on Q-learning maze navigation.
- **Dataset/Simulation:** Webots provides the maze environment; the robot learns through exploration and reinforcement.

Primary paper that I will replicate

Weiss, Tobias, et al.

"Q-Learning for MAZE-Navigation of a TurtleBot." *Artificial Intelligence and Soft Computing*, 2023

- Focus on simulation and real-world environments.

Related Works Survey

1. Ioannou, Alexandros, et al.

"Deepbots: A Webots-Based Deep Reinforcement Learning Framework for Robotics." *Artificial Intelligence and Soft Computing*, 2021.

- Provides an abstraction for RL tasks in Webots.

2. Spryn, Mitchell.

"Solving A Maze With Q Learning." 2021.

- Simple Python Q-learning implementation for maze-solving.

Method

- Replicating the Q-learning algorithm:
 - **State:** Maze grid, robot position.
 - **Action:** Move (left, right, up, down).
 - **Reward:** Positive for reaching the goal, negative for hitting walls.
- Using Webots for simulation and testing.

Timeline

- **October 1 - October 15:** Literature review and initial setup in Webots.
- **October 16 - November 1:** Implementation of Q-learning and maze environment in Webots.
- **November 2 - November 10:** Testing and tweaking the algorithm.
- **November 11 - November 16:** Final evaluation and write-up.

Expected Learning Outcomes

- Understanding how Q-learning adapts to unknown environments.
- Gaining practical experience with Webots for simulating robot navigation tasks.
- Implementing and testing reinforcement learning models in a real-world simulation environment.

References

1. Weiss, Tobias, et al. "From Simulated to Real Environments: Q-Learning for MAZE-Navigation of a TurtleBot." *Artificial Intelligence and Soft Computing*, 2023.
2. Ioannou, Alexandros, et al. "Deepbots: A Webots-Based Deep Reinforcement Learning Framework for Robotics." *Artificial Intelligence and Soft Computing*, 2021.
3. Spryn, Mitchell. "Solving A Maze With Q Learning." 2021.