

Example 2: 32x32 Multiplier

(and why you want to use a DSP instead)

Digital Design Review: 32x32 Multiplier

- Longhand multiplication

$$\begin{array}{r} 1110 \\ \times 1001 \\ \hline 1110 \\ 0000 \\ 0000 \\ 1110 \\ \hline 1111110 \end{array}$$

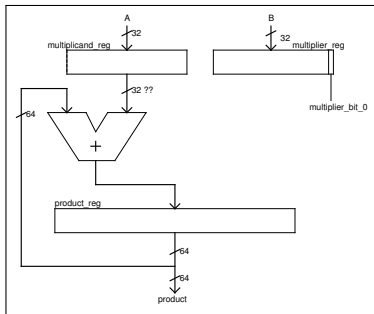
- Check first (LSB) bit of multiplier, if multiplier is a one, save a copy of multiplicand, else save all zeros.
- Check next bit of multiplier, if its a one, left-shift the multiplicand once and add it to the previously saved value. Else, add only zeros.
- Once all bits of the multiplicand are checked, and additions performed, the sum is the product.

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- Design constraints:
 - Synchronous (not combinatorial) using edge-triggered flip-flops
 - One clock, rising edge only, never gated
 - One reset, asynchronous, applied at power-up
 - One input to tell us to start, one output to indicate completion
- Now, ask, “what structures and paths do I need to implement the multiplication?”
 - Need storage for operands and product plus an adder
 - These will be flip-flops, not RAM. RAM makes no sense and is very expensive.
 - Then, what data paths will be needed between the blocks?

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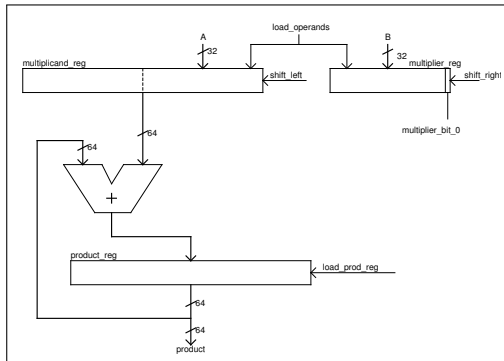
- First cut for storage and data paths
 - 32x32 multiplier must have a 64-bit output
 - Only looking at the LSB of the multiplier register
 - One clock, rising edge only, never gated
 - Clock and reset not shown. They are understood signals.



- What's missing, broken? What do we need now?

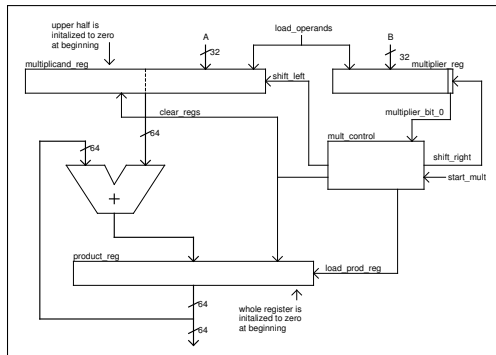
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- Clean up initial design - fix data paths, add some control stubs
 - Need 64-bit multiplicand register to shift left up-to 32 times
 - Need to be able to load the operand registers
 - Need to be able to load or hold value in product (free running clock)



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- Add remaining control signals
 - Upper 32 bits of multiplicand, product register needs to be cleared
 - Add "start" and "done" signals



- High-level block diagram is done! Time for a *noggin simulation*.
- Control is abstracted away into its own block.

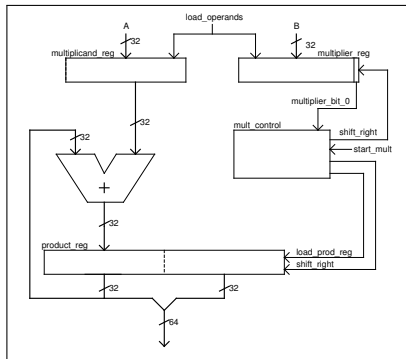
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- By now, you should see some optimizations that can be made.
- Approaching the design as we have exposes optimizations clearly.
- A "code first" approach will not reveal these optimizations.
- "Optimizing" your HDL code **will never create these optimizations**, as they are based in the structure of the hardware.
- "Optimizing" HDL code very often gives you exactly the same structure, only with more difficult to read code.

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■ First Optimization

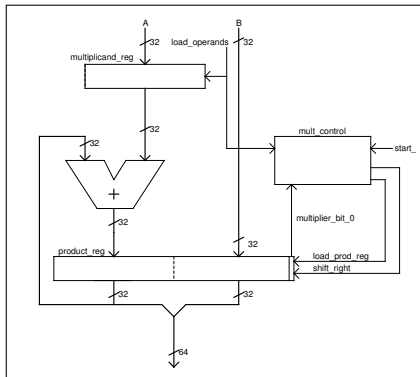
- The multiplicand register is filled with zeros as its shifted left. Half of it only holds zeros that the 64-bit ALU had to process.
- Consider: don't shift the multiplicand but shift the product right.
- Result: 32-bit multiplicand register and ALU. No synchronous reset required for the product or multiplicand register.



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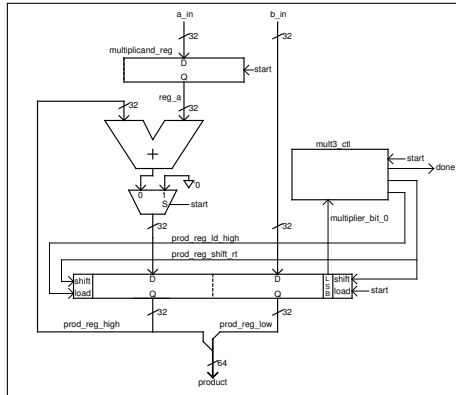
Final Optimization

- Any values in the lower half of the product register are discarded as it is shifted right. The wasted space is exactly the size of the multiplier.
- As wasted space in the product disappears, so does the multiplier.
- Lower half of the product register temporarily stores multiplier.
- Result: Removal of the 32-bit multiplier register and simpler control.



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- With an acceptable architecture we can create the control signals and tidy things up a bit. Fortunately, we have a simpler datapath to control.



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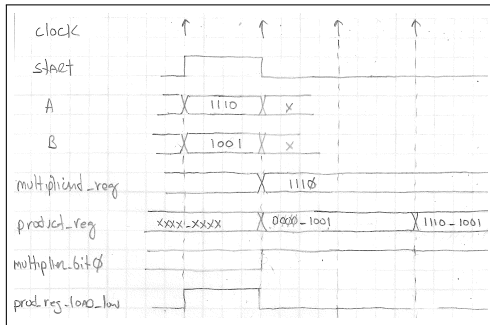
- Ground-rules for our control design
 - All control signals are synchronous to one clock (rising edge)
 - All control signals are created in synchronous state machines.
 - All control signals change state at rising clock edge.
 - All data movement happens at the rising clock edges.
 - Clock is never gated, we use enabled flip-flops.
- Use timing diagram and state machine diagrams to develop
- Start with either, go back and forth making sure they agree and that the signals are created at the correct time.

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- Why timing and state machine diagrams?
- Algorithms describe **what** things happen in a sequential manner. *Parallelism is hidden.*
- Timing Diagrams describe **when** things happen in a parallel manner. *Parallelism is exposed.*
- State Machine Diagrams separate parallel operations into easier to understand mini-machines.
- The visual nature of timing and state machines allow the use of visual pattern matching to observe commonality, see mistakes and to simplify our designs.

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- Timing and state machine diagrams are best worked out with paper and pencil or whiteboards.
- Producing these diagrams is another *eraser-intensive* exercise. Its hard work, and worth every minute.
- Time spent here is equal to 5x-10x time debugging HDL code.



- Some of this could become part of a future homework assignment

Questions?