

$$\begin{array}{c} ? \\ \{ \\ ???t[a_1(t),a_2(t)...a_9(t)] \end{array}$$

$$(1) \qquad u(x,t)=\sum_{j=1}^9 a_j(t)u_j(x),$$

$$u_1=\sqrt{2}sin(\frac{\pi y}{2})00,u_2=\frac{4}{\sqrt{3}}cos^2(\frac{\pi y}{2})cos(\gamma z)00,$$

$$u_3=\frac{2}{\sqrt{4\gamma^2+\pi^2}}02\gamma cos(\frac{\pi y}{2})cos(\gamma z)\pi sin(\frac{\pi y}{2})sin(\gamma z),u_4=00\frac{4}{\sqrt{3}}cos^2(\frac{\pi y}{2})cos(\alpha x),$$

$$u_5=002sin(\alpha x)sin(\frac{\pi y}{2}),u_6=\frac{4\sqrt{2}}{\sqrt{3(\alpha^2+\gamma^2)}}-\gamma cos(\alpha x)cos^2(\frac{\pi y}{2})sin(\gamma z)0\alpha sin(\alpha x)cos^2(\frac{\pi y}{2})cos(\gamma z),$$

$$u_7=\frac{2\sqrt{2}}{\sqrt{(\alpha^2+\gamma^2)}}\gamma sin(\alpha x)sin(\frac{\pi y}{2})sin(\gamma z)0\alpha cos(\alpha x)sin(\frac{\pi y}{2})cos(\gamma z),u_8=N_8\pi\alpha sin(\alpha x)sin(\frac{\pi y}{2})sin(\gamma z)2(\alpha^2+\gamma^2)cos(\alpha x)$$

$$u_9=\sqrt{2}sin(\frac{3\pi y}{2})00$$

$$\begin{array}{l} a(t)=\\ [a_1(t),a_2(t),...,a_8(t),a_9(t)]^T t+\\ \triangle ta(t+\\ \triangle t)\\ \overline{Re} \\ 678? \\ \begin{array}{c} ?? \\ ?? \\ ??y \end{array} \\ -0.5 \end{array}$$

$$(2) \qquad u_k=[u_{k1},u_{k2},...,u_{kn}],k=1...m$$

$$\frac{144\times 576}{82944}$$

$$(3) \qquad \overline{u}=\frac{1}{m}\sum_1^m u_m$$

$$\frac{u'_m}{\overline{uU}}=$$

$$U=u_1'u_2'u_3'\; u_m'=u_{11}'u_{12}'u_{13}'\cdots u_{1n}'u_{21}'u_{22}'u_{23}'\cdots u_{2n}'u_{31}'u_{32}'u_{33}'\cdots u_{3n}'u_{m1}'u_{m2}'u_{m3}'\cdots u_{mn}'$$

$$C=\frac{1}{m-1}U^TU=\frac{1}{m-1}\sum_{i=1}^m u_{i1}'^2\cdots \frac{1}{m-1}\sum_{i=1}^m u_{i2}'^2\cdots\cdots\cdots\frac{1}{m-1}\sum_{i=1}^m u_{i3}'^2\cdots\cdots\cdots\frac{1}{m-1}\sum_{i=1}^m u_{in}'^2$$

$$(4) \qquad TKE=\frac{1}{n}\sum_{i=1}^n\frac{1}{m-1}\sum_{j=1}^m u_{ij}'^2$$

$$\begin{array}{l} C^{n\times n}C \\ ??C \\ \Phi\Lambda\Phi^T\Phi U\Phi A \end{array}$$

$$A^{m\times n}=U^{m\times n}\Phi^{n\times n}$$

$$\overline{AU\Lambda U}$$

$$m-1A^TA=\frac{1}{m-1}(U\Phi)^T(U\Phi)=\frac{1}{m-1}(\Phi^TU^TU\Phi)=\Phi^TC\Phi=\Phi^T\Phi\Lambda\Phi^T\Phi=\Lambda=\lambda_1\lambda_2\lambda_3\;\lambda_n$$