



Hochschule
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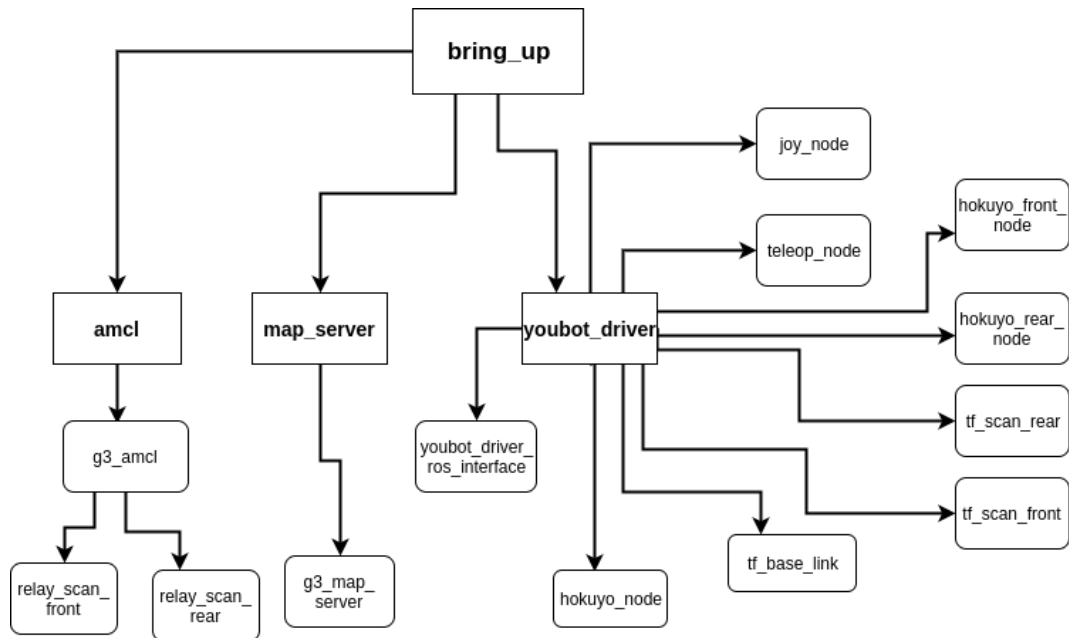
Software Development Project

Basic Navigation Test Analysis

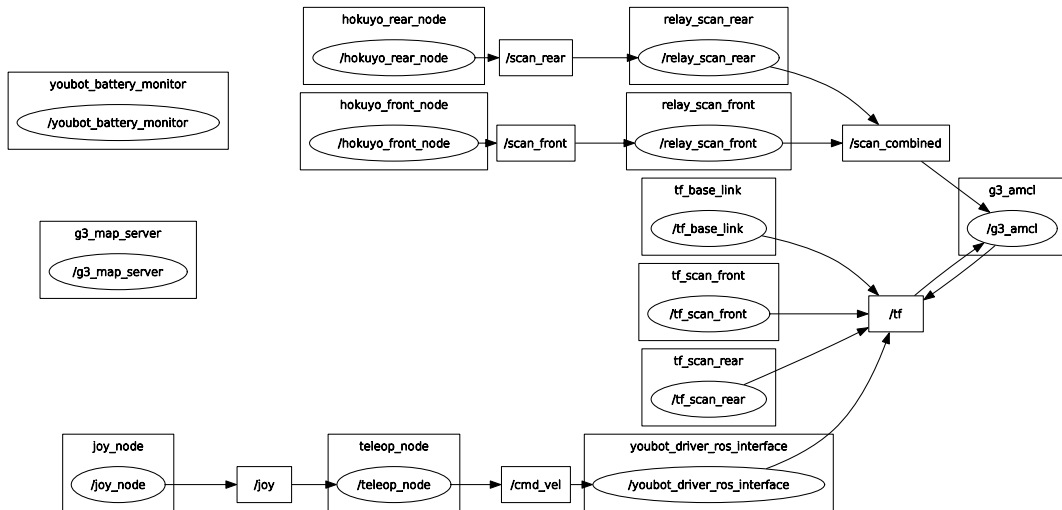
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Launch Files



RQT graph



Frames description

- map
 - map is a world fixed frame
 - discrete
 - useful as a long-term global reference, but discrete jumps in position estimators make it a poor reference frame for local sensing and acting
- odom
 - pose of a mobile platform in the odom frame can drift over time, without any bounds
 - continuous
 - useful as an accurate

