

# Matching, Graphs and Matroids

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# Introduction to Graphs and Bipartite Graphs

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- Example:  $L = \{u\}, R = \{v\}, E = \{(u, v)\}$
- No edges exist between vertices within the same set.

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- Goal: Find a matching of maximum size—i.e., the largest possible set of such edges.

# Introduction to Network Flow

- A **flow network** is a directed graph  $G = (V, E)$  with:
  - A **source** node  $s$  and a **sink** node  $t$
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- A **flow** assigns a value  $f(u, v)$  to each edge such that:
  - Capacity constraint:  $0 \leq f(u, v) \leq c(u, v)$
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- The **maximum flow problem** seeks the greatest total flow from  $s$  to  $t$

# Reducing Bipartite Matching to Flow

- Given bipartite graph  $G = (L \cup R, E)$ , construct a flow network:
  - Add source  $s$  and sink  $t$
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- Assign capacity 1 to all edges
- Solve max-flow from  $s$  to  $t$

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- This method solves bipartite matching in polynomial time using flow algorithms (e.g., Edmonds–Karp)

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- A **maximum matching** is a matching of the largest possible size.
- Unlike bipartite graphs, non-bipartite graphs may contain **odd cycles**, which require special handling.

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- **Edmonds' Blossom Algorithm** (1965) was the first polynomial-time algorithm for finding maximum matchings in general graphs.
- It works by:
  - Searching for **augmenting paths**
  - **Shrinking** blossoms (odd-length cycles) into single vertices
  - Recursively finding matchings in the contracted graph

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- Repeat until no more augmenting paths exist

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- Formally, a matroid is a pair  $M = (E, \mathcal{I})$  where:
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- The sets in  $\mathcal{I}$  must satisfy specific axioms.

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- **(I3) Exchange:** If  $A, B \in \mathcal{I}$  and  $|A| < |B|$ , then there exists  $e \in B \setminus A$  such that  $A \cup \{e\} \in \mathcal{I}$

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# Examples of Matroids

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- **Linear Matroid:**  $E$  is a set of vectors, and a set is independent if the vectors are linearly independent

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- That is, we can select at most  $r_i$  elements from each group  $E_i$

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- Idea: Model the matching problem as an intersection of two matroids on the ground set  $E$
- This allows us to use polynomial-time algorithms for matroid intersection

# Two Partition Matroids from Matching Constraints

We define two matroids over the edge set  $E$  in a bipartite graph  $G = (L \cup R, E)$ :

- **Matroid**  $\mathcal{M}_L = (E, \mathcal{I}_L)$ :
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  - Partition  $E$  by vertex in  $L$ : edges incident to  $u \in L$  form a part
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  - Each part has capacity 1  $\rightarrow$  at most one edge per  $v \in R$
- Both  $\mathcal{M}_L$  and  $\mathcal{M}_R$  are partition matroids.



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- Thus, **maximum bipartite matching** = **maximum-size common independent set** in  $\mathcal{M}_L$  and  $\mathcal{M}_R$
- We can solve it using **matroid intersection algorithms**

# Lawler's Algorithm for Matroid Intersection

- Given two matroids  $\mathcal{M}_1 = (E, \mathcal{I}_1)$  and  $\mathcal{M}_2 = (E, \mathcal{I}_2)$  over the same ground set  $E$

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- Runs in polynomial time using independence oracles for both matroids

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- Conceptually unifies matching and matroid theory!

# Conclusion

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- These concepts are not only theoretically rich, but also practically powerful in solving real-world discrete optimization problems.