Climarkplus Package

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Abstract

A reimplimentation in R of some of the concepts and methods of R. Stern's Climate package in Instat extended to allow for more general modelling

1 Design

1.1 intro

The package is not a port of the Climate package for Instat and Genstat, written by R. Stern, however, in some ways it is quite similar

The major difference is that fitting is done using a generalized linear model on the unbinned data rather than to estimated probabilities. Modifications to the basic Markov model can be made (e.g. a time term) and evaluated.

Other differences include the fact that R does not have many of the limitations of Instat. and the "spreadsheet model", in which everything is more or less a matrix, is only partially used. Columns are referred to by name, not number.

2 Example

2.1 Data Set

We will work with a dataset of 83 years of data from the Zaza, Rawanda station. This has been put into R form using functions from Helen Greatrex.

- > data(zaza)
- > head(zaza)

	Date	Inputfile	Station	Year	Day	Month	Rain	TMax	TMin
1	1930-10-01	Zaza mod1.txt	Zaza	1930	01	10	0	NA	NA
2	1930-10-02	Zaza mod1.txt	Zaza	1930	02	10	8	NA	NA
3	1930-10-03	Zaza mod1.txt	Zaza	1930	03	10	43	NA	NA
4	1930-10-04	Zaza mod1.txt	Zaza	1930	04	10	0	NA	NA
5	1930-10-05	Zaza mod1.txt	Zaza	1930	05	10	0	NA	NA
6	1930-10-06	Zaza mod1.txt	Zaza	1930	06	10	45	NA	NA

> tail(zaza)

```
Date
                     Inputfile Station Year Day Month Rain TMax TMin
29732 2012-02-24 Zaza mod1.txt
                                   Zaza 2012
                                             24
                                                        0.0
                                                    02
29733 2012-02-25 Zaza mod1.txt
                                   Zaza 2012
                                              25
                                                    02
                                                        0.0
                                                               NA
                                                                    NA
29734 2012-02-26 Zaza mod1.txt
                                   Zaza 2012
                                              26
                                                    02
                                                        0.0
                                                                    NA
                                                               NA
29735 2012-02-27 Zaza mod1.txt
                                   Zaza 2012
                                              27
                                                    02
                                                        1.4
                                                               NA
                                                                    NA
29736 2012-02-28 Zaza mod1.txt
                                   Zaza 2012
                                              28
                                                    02
                                                        0.0
                                                               NA
                                                                    NA
29737 2012-02-29 Zaza mod1.txt
                                   Zaza 2012
                                              29
                                                    02
                                                        0.0
                                                               NA
                                                                    NA
```

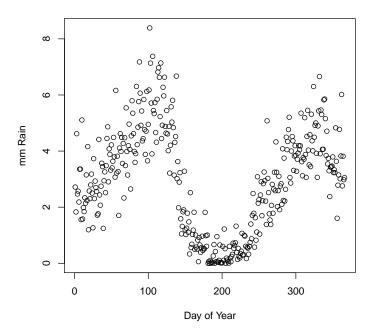
It is useful to have a dataset with day of year (consistent in that March 1 is day 61 for non leap years as well as leap years). The function <code>convert_data</code> does this.

- > zaza_doy=convert_data(zaza)
- > head(zaza_doy)

```
Station
                Date Rain DOY
1
     Zaza 1930-10-01
                         0 275
2
     Zaza 1930-10-02
                         8 276
3
     Zaza 1930-10-03
                        43 277
4
     Zaza 1930-10-04
                         0 278
     Zaza 1930-10-05
5
                         0 279
     Zaza 1930-10-06
                        45 280
```

We can plot the average rain over the year (more on the details of this later)

```
> plot(sapply(split(zaza_doy$Rain,zaza_doy$DOY),mean,na.rm=T),
```



Note the rainfall has two peaks, but does not fall to 0 in Dec/Jan.

2.2 Markov Model

The first thing we do is to add the Markov lags, up to order=2.

- > zaza_wm=add_markov(zaza_doy)
- > #load("zaza_wm")
- > head(zaza_wm)

	${\tt Station}$	Date	Rain	DOY	wet_or_dry	lag_1	lag_2
1	Zaza	1930-10-01	0	275	d	<na></na>	<na></na>
2	Zaza	1930-10-02	8	276	W	d	<na></na>
3	Zaza	1930-10-03	43	277	W	W	wd
4	Zaza	1930-10-04	0	278	d	W	ww
5	Zaza	1930-10-05	0	279	d	d	dw
6	Zaza	1930-10-06	45	280	W	d	dd

Note there are three new columns. "d" means a dry day and "w" means any day in which the amount of rain is more than some threshold (default 0.12 mm). Lag_n is the pattern of wet and dry days over the previous n days.

2.3 Philosophy of Model

The basic idea of the package is to model and analyze rainfall. To determine the amount of rainfall on a given day we use two steps.

- 1. Get the probability that there will be rain.
- 2. Get the distribution of the amount of rain on rainy days

2.3.1 Probability of Rain

We use a markov model of order k of the probability of rain, that is the chance of rain will depend on the pattern of wet and dry days over the previous k days. The order can be chosen (standard is an order of two, e.g in the given model)

If the order is k, then there are 2^k possible patterns of wet, w, and dry, d, days. For k=2 we have ww, dw, wd, dd. Note for every pattern there is a column in the model called P(w|pattern) For each day (the rows 1–366) we have the probability applicable to that day. There is no restriction on where these values come from. They can be fitted values from raw data, however there are other possibities.

2.3.2 Amount of rain

We use a markov model of order k for both the mean of the rain. Hence, the mean ammount of rain will depend of the pattern of wet and dry days over the previous k days. (It is assumed that the amount of rain follows a Gamma distribution with a constant shape) The order can be chosen (standard is an order of 1, or 0 (do not take into account any pattern))

If the order is k, then there are 2^k possible patterns of wet, w, and dry, d, days. For k=1 we have w, d Note for every pattern there is a column in the model called <(r|pattern>). For each day (the rows 1–366) we have the mean. There is no restriction on where these values come from. Note we also have the < rain > column This is the unconditional mean of the rain amount.

Note though there is a day of year dependence in the model there is (as yet) no year dependence.

2.3.3 Obtaining Values: shape, offset

Each column, whether probability or amount is said to be a "curve". As indicated, the model does not know where the curve came from. However, it is often usefull to break the curve down into two parts. a "shape" and an "offset". The shape is any general curve, the offset is a single number applied to the shape to get the final curve. So

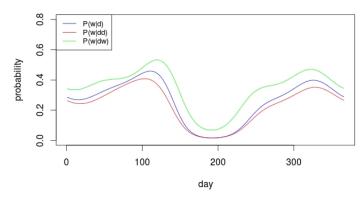
$$(curve) = \text{shape} + \text{offset}$$
 (1)

(We do not attempt to make a canonical offset for the shape. We need the weighted sum of squares fit to a constant to be zero, but in practice the weighting is not known)

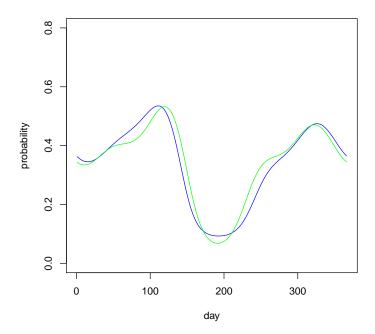
The motivation here, is that it is often noted that higher order curves (eg P(w|dw)) are often very similar to lower order curves (eg P(w|d)) but with an offset. Thus, it makes sense to estimate the higher order curve by estimating only this offset, rather than the large number of parameters needed to directly estimate the higher order curve.

An example can help here. We look at the same site that was used to produce the above model.

Compare P(w|d) to P(w|dd) and P(w|dw)



The blue line is the probability of rain given that the previous day was dry, P(w|d). This can be broken down into P(w|dd), the red line, and P(w|dw), the green line. We note that the green line has much the same shape as the blue line but with a substantial offset.



Here we see P(w|d) (the blue line) shifted to match P(w|dw) (the green line). It seems that we can use the shifted blue line rather than the green line. Given that we have much more confidence in the shifted blue line (more data, fewer coefficients) that the green line, we may prefer to use the shifted blue line.

3 Parameter Files

On way of creating a model is to start with a set of raw probabilities, raw_probs , derived from a dataset associated (usually) with a station. Then each curve P(w|lag) can be a fitted version of the corresponding data in the dataset, or a (possibly shifted) fitted version of some other data from the dataset.

The model is described by a parameter (*.pl) file. An example of the start of such a file is given.

```
<order> = 2
<dd> = dd

<dd_fit_order>= choose
<dd_offset> = NO
...

Every line has the form
<key> = value
```

When read in you get a list, with list[key] = value with value a string.

The first parameter, order, gives the order of the wet/dry part of the model. For each of the 2^{order} values for the lag, there are three parameters. The first lag is the column of the raw dataset used; the second lag_fit_order is the number of harmonics used to fit the raw data (if this value is choose then the fit order is determined automatically); the third lag_offset is the dataset from which the offset is to be determined, if the value is NO then there is no offset.

The part of the parameter file which deals with the amount of rain on wet days is similar, although in this case we have lag for the mean and standard deviation.

```
<rain_order>= 1
<rw>=w
<rw_fit_order>=4
<rw_offset> = NO
```

This is the "standard" parameter file, order_2_0.pl. It describes an order 2 model for the probability of rain, and an order zero model for the amount of rain.

If we want an order 1 model for the amount of rain, we change only the rain section (last three line) to

```
<rain_order>= 1
<rw>=w
<rw_fit_order>=4
<rw_offset> = NO
<rd>=d
```

```
<rd_fit_order>=4
<rd_offset> = NO
```

We can get a mixed markov model by changing what is used to estimate higher order lags.

```
<order> = 2
<dd> = d
<dd_fit_order>= 4
<dd_offset> = NO
<dw> = d
<dw_fit_order>= 4
<dw_offset> = NO
<wd>= wd
<wd_fit_order>= 4
<wd_offset> = NO
<wd>= wd
<wd_offset> = NO
<ww = ww
<ww_fit_order>= 4
<ww_offset> = NO
<ww = ww
<ww_fit_order>= 4
<ww_offset> = NO
<rain_order>= 0
<ro_fit_order>= 4
```

Note that the curves for the order two lags dd and dw are both derived from the order 1 curve lag d. However, the curves for the order 2 lags wd and ww are derived from order two curves. In other words we only use order 2 lags if the first day is wet.

We can add offsets if desired. Let us change the offset for the curve for lag dw.

```
<dw> = d
<dw_fit_order>= 4
<dw_offset> = dw
```

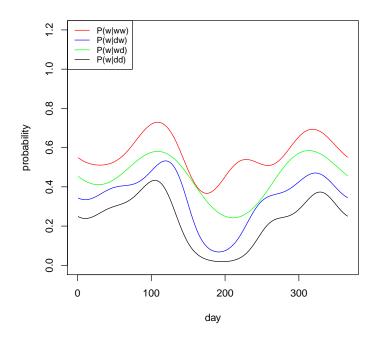
Note that we still derive the curve from the first order lag, but now we add an offset derived from the second order lag.

We can illustrate this by using the above data set. (here we are looking a only the probability of rain)

First we show a second order model

> mod=make_approx_model_pl(zaza_pbs,"/home/william/Reading/rstudio/Climarkplus/inst/paramete
> plot_model(mod,"Second Order Model")

Second Order Model

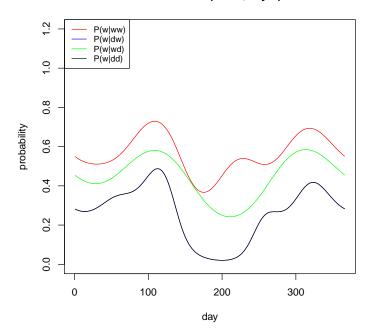


As we have noted above, the wd, and ww, lines are not close in shape to the w line, but the dd and dw lines are close in shape to the d line. So we can try a mixed model, going to order 2 lags if the previous day was wet, but using only order 1 if the previous day was dry

 $[\]verb|> mod=make_approx_model_pl(zaza_pbs,"/home/william/Reading/rstudio/climate/trunk/inst/parametric parametric parametri$

> plot_model(mod, "Mixed Model (wet 2, dry 1) ")

Mixed Model (wet 2, dry 1)

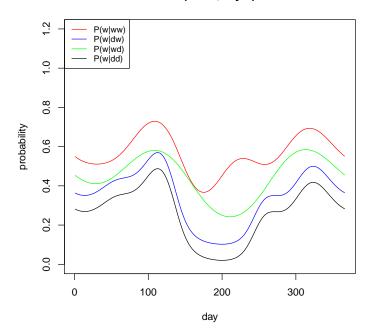


Note that P(w|dw) and P(w|dd) are identical. The latter obscures the former.

We note from above that the d line can be used for dd but while the dw line is similar in shape to dd there is an obvious offset. We can include this offset.

- > plot_model(mod,"Mixed Model (wet 2, dry 1) dw offset")

Mixed Model (wet 2, dry 1) dw offset



Note that the dw line is now visible. It has the same shape as the dd (and hence d) line, but not the same offset.

3.1 Fitting

There are two functions that do the true fitting: fit_rainy for the probability of rain; and fit_amount for the amount of rain. Both functions take the same parameters

wms This is the raw data. It must have column DOY and it must have columns for the needed Markov lags

filename The name of the parameter file used to guide the fit. Standard parameter files can be founc in inst/parameter

others This is a vector of names of other predictors that should be used in the fit (no interactions). Anything in others should also be a column in the raw data.

other_model_string This can be anything you want. It is a string that is added verbatim to the fitting string. This can be used e.g. to study interactions. However, if this is used the fit object produced probably cannot be used to construct a model for synthesis

The output of both functions is a fit_object. This is a list of two items. The first is a list of information, the second is the fit, an R object.

An example

```
> fit_object_1=fit_rainy(zaza_wm,filename="/home/william/Reading/rstudio/Climarkplus/inst/pa
> fit_object_1[[1]]
```

[[1]]

```
order
                            dd
                                   dd_fit_order
                                                        dd_offset
                                                                                 dw
          "2"
                          "dd"
                                       "choose"
                                                             "NO"
                                                                               "dw"
dw_fit_order
                    dw_offset
                                             wd
                                                    wd_fit_order
                                                                         wd_offset
                                                         "choose"
    "choose"
                          "NO"
                                            "wd"
                                                                               "NO"
                 ww_fit_order
                                      ww_offset
                                                      rain_order
                                                                      r0_fit_order
           WW
         "ww"
                      "choose"
                                            "NO"
                                                              "0"
                                                                                "4"
```

r0_sd_fit_order "4"

[[2]]

[1] "end"

> summary(fit_object_1[[2]])

Call:

glm(formula = fit_string, family = "binomial", data = wms)

Deviance Residuals:

Min 1Q Median 3Q Max -1.616 -0.919 -0.365 1.035 2.862

Coefficients:

Estimate Std. Error z value Pr(>|z|)ULAGSdd:cos(DOY * 0 * 2 * pi/366) -1.488320.02926 -50.87 < 2e-16 *** ULAGSdw:cos(DOY * 0 * 2 * pi/366) -0.748920.06142 -12.19 < 2e-16 *** ULAGSwd:cos(DOY * 0 * 2 * pi/366) -0.220480.04840 -4.56 5.2e-06 *** ULAGSww:cos(DOY * 0 * 2 * pi/366)0.26700 0.05441 4.91 9.2e-07 *** ULAGSdd:cos(DOY * 1 * 2 * pi/366)1.13404 0.04582 24.75 < 2e-16 *** ULAGSdw:cos(DOY * 1 * 2 * pi/366)6.05 1.4e-09 *** 0.64009 0.10575 ULAGSwd:cos(DOY * 1 * 2 * pi/366)0.34052 0.08043 4.23 2.3e-05 *** ULAGSww:cos(DOY * 1 * 2 * pi/366)2.53 0.01131 * 0.23568 0.09304 ULAGSdd:sin(DOY * 1 * 2 * pi/366)10.77 < 2e-16 *** 0.39057 0.03628 ULAGSdw:sin(DOY * 1 * 2 * pi/366)0.23388 0.05558 4.21 2.6e-05 *** ULAGSwd:sin(DOY * 1 * 2 * pi/366)3.04 0.00234 ** 0.15623 0.05135 ULAGSww:sin(DOY * 1 * 2 * pi/366)0.07820 0.05172 1.51 0.13054 ULAGSdd:cos(DOY * 2 * 2 * pi/366) -0.84844-19.72 < 2e-16 *** 0.04301 ULAGSdw:cos(DOY * 2 * 2 * pi/366) -0.603590.08805 -6.86 7.1e-12 *** ULAGSwd:cos(DOY * 2 * 2 * pi/366) -0.30668-4.43 9.4e-06 *** 0.06923 ULAGSww:cos(DOY * 2 * 2 * pi/366) -0.31485-4.01 5.9e-05 *** 0.07842

```
ULAGSdd:sin(DOY * 2 * 2 * pi/366) -0.43209
                                              0.03829
                                                       -11.29
                                                               < 2e-16 ***
ULAGSdw:sin(DOY * 2 * 2 * pi/366) -0.37117
                                                        -5.43
                                              0.06830
                                                              5.5e-08 ***
ULAGSwd:sin(DOY * 2 * 2 * pi/366) -0.40672
                                              0.06036
                                                        -6.74 1.6e-11 ***
ULAGSww:sin(DOY * 2 * 2 * pi/366) -0.24445
                                              0.06400
                                                        -3.82 0.00013 ***
ULAGSdd:cos(DOY * 3 * 2 * pi/366)
                                  0.33172
                                              0.04113
                                                         8.06 7.3e-16 ***
ULAGSdw:cos(DOY * 3 * 2 * pi/366)
                                 0.29888
                                              0.07109
                                                         4.20 2.6e-05 ***
ULAGSwd:cos(DOY * 3 * 2 * pi/366)
                                  0.00489
                                              0.06047
                                                         0.08 0.93560
ULAGSww:cos(DOY * 3 * 2 * pi/366)
                                                         1.83 0.06651 .
                                   0.11722
                                              0.06388
ULAGSdd:sin(DOY * 3 * 2 * pi/366)
                                  0.02232
                                              0.03894
                                                         0.57 0.56647
ULAGSdw:sin(DOY * 3 * 2 * pi/366) 0.06524
                                                         0.95 0.34149
                                              0.06858
ULAGSwd:sin(DOY * 3 * 2 * pi/366) -0.08162
                                                        -1.34 0.17877
                                              0.06070
ULAGSww:sin(DOY * 3 * 2 * pi/366) -0.24936
                                              0.06087
                                                        -4.10 4.2e-05 ***
ULAGSdd:cos(DOY * 4 * 2 * pi/366) -0.14488
                                              0.03870
                                                        -3.74 0.00018 ***
ULAGSdw:cos(DOY * 4 * 2 * pi/366) -0.22765
                                              0.06077
                                                        -3.75 0.00018 ***
ULAGSwd:cos(DOY * 4 * 2 * pi/366) -0.07142
                                              0.05568
                                                        -1.28 0.19956
ULAGSww:cos(DOY * 4 * 2 * pi/366) -0.09873
                                              0.05513
                                                        -1.79
                                                               0.07331 .
                                                        -2.03 0.04280 *
ULAGSdd:sin(DOY * 4 * 2 * pi/366) -0.07877
                                              0.03889
ULAGSdw:sin(DOY * 4 * 2 * pi/366) -0.05261
                                              0.06062
                                                        -0.87 0.38541
ULAGSwd:sin(DOY * 4 * 2 * pi/366) -0.06239
                                              0.05553
                                                        -1.12 0.26122
ULAGSww:sin(DOY * 4 * 2 * pi/366) 0.11769
                                              0.05409
                                                         2.18 0.02956 *
```

Signif. codes: 0 âĂŸ***âĂŹ 0.001 âĂŸ**âĂŹ 0.01 âĂŸ*âĂŹ 0.05 âĂŸ.âĂŹ 0.1 âĂŸ âĂŹ 1

(Dispersion parameter for binomial family taken to be 1)

```
Null deviance: 30758 on 22187 degrees of freedom
Residual deviance: 23633 on 22151 degrees of freedom
(7550 observations deleted due to missingness)
```

AIC: 23705

Number of Fisher Scoring iterations: 6

We see that the first member of the information list is the contents of the parameter file. The fit is the second member, summary gives the coefficients in a nice form. Note that the coefficients are Fourier Coefficients for the levels of ULAGS. ULAGS is a new column added to the raw data. It is similar to lags_n (n the order of the Markov fit) but some lags may be combined (not in this example though)

We can experiment with adding something to the others parameter. First make a column of the Julian Day and add it to zaza_wm

```
2
     Zaza 1930-10-02
                         8 276
                                               d <NA> -14336
                                        W
3
     Zaza 1930-10-03
                        43 277
                                                    wd -14335
                                        W
                                               W
4
     Zaza 1930-10-04
                         0 278
                                        d
                                                    ww -14334
     Zaza 1930-10-05
5
                         0 279
                                         d
                                               d
                                                    dw -14333
     Zaza 1930-10-06
                       45 280
                                         W
                                                    dd -14332
```

We can now add Julian as a predictor

```
 > fit_object_1a=fit_rainy(zaza_wm,filename="/home/william/Reading/rstudio/Climarkplus/inst/policy of the property of the pr
```

Call.

```
glm(formula = fit_string, family = "binomial", data = wms)
```

Deviance Residuals:

```
Min 1Q Median 3Q Max
-1.655 -0.917 -0.366 1.034 2.871
```

Coefficients:

```
Estimate Std. Error z value Pr(>|z|)
Julian
                                  4.75e-06
                                             2.03e-06
                                                         2.34 0.01904 *
ULAGSdd:cos(DOY * 0 * 2 * pi/366) -1.48e+00
                                             2.96e-02 -49.91 < 2e-16 ***
                                             6.15e-02 -12.04 < 2e-16 ***
ULAGSdw:cos(DOY * 0 * 2 * pi/366) -7.41e-01
ULAGSwd:cos(DOY * 0 * 2 * pi/366) -2.12e-01
                                                       -4.37 1.3e-05 ***
                                             4.85e-02
ULAGSww:cos(DOY * 0 * 2 * pi/366) 2.73e-01
                                             5.45e-02
                                                         5.02 5.2e-07 ***
ULAGSdd:cos(DOY * 1 * 2 * pi/366)
                                 1.13e+00
                                             4.58e-02
                                                        24.77 < 2e-16 ***
ULAGSdw:cos(DOY * 1 * 2 * pi/366) 6.41e-01
                                             1.06e-01
                                                         6.06 1.4e-09 ***
ULAGSwd:cos(DOY * 1 * 2 * pi/366)
                                                         4.24 2.2e-05 ***
                                  3.41e-01
                                             8.04e-02
ULAGSww:cos(DOY * 1 * 2 * pi/366) 2.41e-01
                                             9.31e-02
                                                         2.59 0.00964 **
ULAGSdd:sin(DOY * 1 * 2 * pi/366) 3.91e-01
                                             3.63e-02
                                                        10.76 < 2e-16 ***
ULAGSdw:sin(DOY * 1 * 2 * pi/366)
                                                         4.26 2.0e-05 ***
                                  2.37e-01
                                             5.56e-02
ULAGSwd:sin(DOY * 1 * 2 * pi/366)
                                  1.59e-01
                                             5.14e-02
                                                         3.10 0.00194 **
ULAGSww:sin(DOY * 1 * 2 * pi/366) 8.29e-02
                                             5.18e-02
                                                         1.60 0.10908
ULAGSdd:cos(DOY * 2 * 2 * pi/366) -8.49e-01
                                             4.30e-02 -19.74 < 2e-16 ***
ULAGSdw:cos(DOY * 2 * 2 * pi/366) -6.04e-01
                                                        -6.86 7.0e-12 ***
                                             8.81e-02
ULAGSwd:cos(DOY * 2 * 2 * pi/366) -3.07e-01
                                             6.92e-02
                                                        -4.43 9.3e-06 ***
ULAGSww:cos(DOY * 2 * 2 * pi/366) -3.18e-01
                                             7.84e-02
                                                       -4.05 5.1e-05 ***
ULAGSdd:sin(DOY * 2 * 2 * pi/366) -4.31e-01
                                             3.83e-02
                                                       -11.26 < 2e-16 ***
ULAGSdw:sin(DOY * 2 * 2 * pi/366) -3.74e-01
                                                        -5.47 4.6e-08 ***
                                             6.83e-02
ULAGSwd:sin(DOY * 2 * 2 * pi/366) -4.09e-01
                                             6.04e-02
                                                        -6.77 1.3e-11 ***
ULAGSww:sin(DOY * 2 * 2 * pi/366) -2.45e-01
                                             6.40e-02
                                                        -3.83 0.00013 ***
ULAGSdd:cos(DOY * 3 * 2 * pi/366)
                                 3.29e-01
                                             4.11e-02
                                                         8.01 1.2e-15 ***
ULAGSdw:cos(DOY * 3 * 2 * pi/366)
                                 2.98e-01
                                                         4.20 2.7e-05 ***
                                             7.11e-02
ULAGSwd:cos(DOY * 3 * 2 * pi/366) 4.47e-03
                                             6.05e-02
                                                         0.07 0.94103
ULAGSww:cos(DOY * 3 * 2 * pi/366) 1.22e-01
                                                         1.91 0.05567 .
                                             6.39e-02
ULAGSdd:sin(DOY * 3 * 2 * pi/366) 2.10e-02
                                             3.89e-02
                                                         0.54 0.58930
ULAGSdw:sin(DOY * 3 * 2 * pi/366) 6.62e-02
                                                         0.96 0.33484
                                             6.86e-02
```

```
ULAGSwd:sin(DOY * 3 * 2 * pi/366) -8.11e-02
                                                6.07e-02
                                                           -1.34 0.18184
ULAGSww:sin(DOY * 3 * 2 * pi/366) -2.50e-01
                                                6.09e-02
                                                           -4.11 4.0e-05 ***
ULAGSdd:cos(DOY * 4 * 2 * pi/366) -1.44e-01
                                                3.87e-02
                                                           -3.72 0.00020 ***
ULAGSdw:cos(DOY * 4 * 2 * pi/366) -2.27e-01
                                                6.08e-02
                                                           -3.74 0.00019 ***
ULAGSwd:cos(DOY * 4 * 2 * pi/366) -7.11e-02
                                                5.57e-02
                                                           -1.28 0.20180
ULAGSww:cos(DOY * 4 * 2 * pi/366) -1.02e-01
                                                5.51e-02
                                                           -1.85 0.06502 .
ULAGSdd:sin(DOY * 4 * 2 * pi/366) -7.75e-02
                                                3.89e-02
                                                           -1.99 0.04621 *
ULAGSdw:sin(DOY * 4 * 2 * pi/366) -5.24e-02
                                                           -0.86 0.38767
                                                6.06e-02
ULAGSwd:sin(DOY * 4 * 2 * pi/366) -6.20e-02
                                                5.55e-02
                                                           -1.12 0.26408
ULAGSww:sin(DOY * 4 * 2 * pi/366) 1.15e-01
                                                5.41e-02
                                                            2.13 0.03331 *
Signif. codes: 0 âĂŸ***âĂŹ 0.001 âĂŸ**âĂŹ 0.01 âĂŸ*âĂŹ 0.05 âĂŸ.âĂŹ 0.1 âĂŸ âĂŹ 1
(Dispersion parameter for binomial family taken to be 1)
    Null deviance: 30758 on 22187 degrees of freedom
Residual deviance: 23627 on 22150 degrees of freedom
  (7550 observations deleted due to missingness)
AIC: 23701
Number of Fisher Scoring iterations: 6
   We note that the coefficient of "Julian" is significant at the 5% level. Fur-
thermore, looking at the coefficient (4.75e-06) and the mininum and maximum
values of Julian, we note that the net change over time is about 0.15. This is
in logit space, the net change in probability is about .03, about a 6% change in
probability.
   We can also add something to the other_model_string parameter. Lets
look at the interactions of Julian with the lags
> fit_object_1b=fit_rainy(zaza_wm,filename="/home/william/Reading/rstudio/Climarkplus/inst/p
> summary(fit_object_1b[[2]])
Call:
glm(formula = fit_string, family = "binomial", data = wms)
Deviance Residuals:
   Min
            1Q Median
                             3Q
                                    Max
-1.636 -0.916 -0.365
                          1.033
                                  2.873
Coefficients:
                                    Estimate Std. Error z value Pr(>|z|)
Julian
                                    6.00e-06
                                                3.33e-06
                                                            1.80 0.07175 .
ULAGSdd:cos(DOY * 0 * 2 * pi/366) -1.47e+00
                                                3.02e-02
                                                         -48.91 < 2e-16 ***
```

6.19e-02 -11.82 < 2e-16 ***

-4.25 2.1e-05 ***

4.78 1.7e-06 ***

4.90e-02

5.47e-02

ULAGSdw:cos(DOY * 0 * 2 * pi/366) -7.32e-01

ULAGSwd:cos(DOY * 0 * 2 * pi/366) -2.08e-01

ULAGSww:cos(DOY * 0 * 2 * pi/366) 2.62e-01

```
ULAGSdd:cos(DOY * 1 * 2 * pi/366)
                                  1.13e+00
                                              4.58e-02
                                                        24.77 < 2e-16 ***
ULAGSdw:cos(DOY * 1 * 2 * pi/366)
                                  6.43e-01
                                              1.06e-01
                                                         6.07 1.3e-09 ***
ULAGSwd:cos(DOY * 1 * 2 * pi/366)
                                              8.05e-02
                                                         4.25 2.2e-05 ***
                                  3.42e-01
                                             9.32e-02
ULAGSww:cos(DOY * 1 * 2 * pi/366)
                                  2.31e-01
                                                         2.48 0.01306 *
ULAGSdd:sin(DOY * 1 * 2 * pi/366)
                                  3.91e-01
                                              3.63e-02
                                                        10.76
                                                               < 2e-16 ***
ULAGSdw:sin(DOY * 1 * 2 * pi/366) 2.41e-01
                                              5.57e-02
                                                         4.32 1.5e-05 ***
ULAGSwd:sin(DOY * 1 * 2 * pi/366)
                                  1.61e-01
                                              5.14e-02
                                                         3.12 0.00180 **
ULAGSww:sin(DOY * 1 * 2 * pi/366) 7.41e-02
                                              5.19e-02
                                                         1.43
                                                               0.15339
ULAGSdd:cos(DOY * 2 * 2 * pi/366) -8.49e-01
                                              4.30e-02 -19.75
                                                               < 2e-16 ***
ULAGSdw:cos(DOY * 2 * 2 * pi/366) -6.05e-01
                                                        -6.86 6.8e-12 ***
                                              8.81e-02
ULAGSwd:cos(DOY * 2 * 2 * pi/366) -3.07e-01
                                              6.93e-02
                                                        -4.43 9.3e-06 ***
ULAGSww:cos(DOY * 2 * 2 * pi/366) -3.12e-01
                                              7.85e-02
                                                        -3.98 6.9e-05 ***
ULAGSdd:sin(DOY * 2 * 2 * pi/366) -4.31e-01
                                              3.83e-02 -11.25 < 2e-16 ***
ULAGSdw:sin(DOY * 2 * 2 * pi/366) -3.77e-01
                                              6.84e-02
                                                        -5.50 3.7e-08 ***
ULAGSwd:sin(DOY * 2 * 2 * pi/366) -4.10e-01
                                              6.04e-02
                                                        -6.78 1.2e-11 ***
ULAGSww:sin(DOY * 2 * 2 * pi/366) -2.44e-01
                                              6.40e-02
                                                        -3.81
                                                               0.00014 ***
ULAGSdd:cos(DOY * 3 * 2 * pi/366) 3.29e-01
                                              4.12e-02
                                                         7.99 1.4e-15 ***
ULAGSdw:cos(DOY * 3 * 2 * pi/366) 2.98e-01
                                              7.11e-02
                                                         4.19 2.8e-05 ***
ULAGSwd:cos(DOY * 3 * 2 * pi/366) 4.29e-03
                                              6.05e-02
                                                         0.07 0.94347
ULAGSww:cos(DOY * 3 * 2 * pi/366)
                                  1.13e-01
                                              6.41e-02
                                                         1.76 0.07817 .
ULAGSdd:sin(DOY * 3 * 2 * pi/366) 2.07e-02
                                              3.90e-02
                                                         0.53 0.59566
ULAGSdw:sin(DOY * 3 * 2 * pi/366) 6.73e-02
                                              6.87e-02
                                                         0.98 0.32722
ULAGSwd:sin(DOY * 3 * 2 * pi/366) -8.09e-02
                                              6.07e-02
                                                        -1.33 0.18313
ULAGSww:sin(DOY * 3 * 2 * pi/366) -2.49e-01
                                              6.09e-02
                                                        -4.09 4.3e-05 ***
ULAGSdd:cos(DOY * 4 * 2 * pi/366) -1.44e-01
                                              3.87e-02
                                                        -3.71 0.00021 ***
ULAGSdw:cos(DOY * 4 * 2 * pi/366) -2.27e-01
                                              6.08e-02
                                                        -3.73 0.00019 ***
ULAGSwd:cos(DOY * 4 * 2 * pi/366) -7.09e-02
                                                        -1.27 0.20273
                                              5.57e-02
ULAGSww:cos(DOY * 4 * 2 * pi/366) -9.61e-02
                                              5.52e-02
                                                        -1.74 0.08158 .
ULAGSdd:sin(DOY * 4 * 2 * pi/366) -7.72e-02
                                              3.89e-02
                                                        -1.98 0.04719 *
                                                        -0.86 0.39048
ULAGSdw:sin(DOY * 4 * 2 * pi/366) -5.21e-02
                                              6.07e-02
ULAGSwd:sin(DOY * 4 * 2 * pi/366) -6.19e-02
                                              5.56e-02
                                                        -1.11 0.26532
ULAGSww:sin(DOY * 4 * 2 * pi/366) 1.20e-01
                                                         2.22 0.02673 *
                                              5.41e-02
ULAGSdw: Julian
                                   4.45e-06
                                              5.65e-06
                                                         0.79 0.43123
                                             5.57e-06
ULAGSwd: Julian
                                   8.40e-07
                                                         0.15 0.88010
ULAGSww:Julian
                                  -1.01e-05
                                              5.40e-06
                                                        -1.87 0.06103 .
```

Signif. codes: 0 âĂŸ***âĂŹ 0.001 âĂŸ**âĂŹ 0.01 âĂŸ*âĂŹ 0.05 âĂŸ.âĂŹ 0.1 âĂŸ âĂŹ 1

(Dispersion parameter for binomial family taken to be 1)

Null deviance: 30758 on 22187 degrees of freedom Residual deviance: 23621 on 22147 degrees of freedom (7550 observations deleted due to missingness)

AIC: 23701

Number of Fisher Scoring iterations: 6

There is no significant interaction of Julian with any of the lags. (Note that fit_object_1b is not suitable for making a model)

We can also fit the amounts. Note that we use Gamma regression (we used logistic regression for tt fit_rainy). As well we only fit on days wich are rainy

```
> fit_object_2=fit_amounts(zaza_wm,filename="/home/william/Reading/rstudio/Climarkplus/inst,
> summary(fit_object_2[[2]])
```

Call:

```
glm(formula = fit_string, family = "Gamma", data = subdata)
```

Deviance Residuals:

```
Min 1Q Median 3Q Max -2.419 -1.231 -0.480 0.354 4.160
```

Coefficients:

```
Estimate Std. Error t value Pr(>|t|)
cos(DOY * 0 * 2 * pi/366)
                          0.117709
                                      0.002399
                                                  49.07 < 2e-16 ***
cos(DOY * 1 * 2 * pi/366) -0.000910
                                      0.004038
                                                  -0.23
                                                           0.822
sin(DOY * 1 * 2 * pi/366) -0.010436
                                      0.002451
                                                  -4.26
                                                        2.1e-05 ***
cos(DOY * 2 * 2 * pi/366)
                           0.002683
                                      0.003394
                                                          0.429
                                                  0.79
sin(DOY * 2 * 2 * pi/366)
                           0.007182
                                      0.003032
                                                   2.37
                                                           0.018 *
cos(DOY * 3 * 2 * pi/366)
                           0.003651
                                      0.002824
                                                   1.29
                                                           0.196
sin(DOY * 3 * 2 * pi/366)
                           0.000197
                                      0.002871
                                                  0.07
                                                           0.945
cos(DOY * 4 * 2 * pi/366) -0.003776
                                      0.002528
                                                 -1.49
                                                           0.135
sin(DOY * 4 * 2 * pi/366)
                           0.000227
                                      0.002546
                                                   0.09
                                                           0.929
```

Signif. codes: 0 âĂŸ***âĂŹ 0.001 âĂŸ**âĂŹ 0.01 âĂŸ*âĂŹ 0.05 âĂŸ.âĂŹ 0.1 âĂŸ âĂŹ 1

(Dispersion parameter for Gamma family taken to be 1.3)

Null deviance: NaN on 7623 degrees of freedom Residual deviance: 10476 on 7614 degrees of freedom AIC: 48266

Number of Fisher Scoring iterations: 7

Note that as we are using a rain order of 0, there is no interaction of the Fourier coefficients and any lag.

3.2 The model

Central to the package is the model data set. There are functions to create models (e.g. from known data).

We can create a model from the fit objects produced above.

```
> zaza_mod=make_model_from_fit_objects(fit_object_1,fit_object_2)
> head(zaza_mod)
```

```
info P(w|ww) P(w|dw) P(w|wd) P(w|dd) <rain>
                                         0.55
                                                             0.43
                                                                       0.26
1
                      \langle order \rangle = 2
                                                   0.34
                                                                                 8.4
2
                < rain_order > = 0
                                         0.55
                                                   0.34
                                                             0.43
                                                                       0.26
                                                                                 8.4
3
  \langle shape \rangle = 0.856151042431432
                                         0.54
                                                   0.34
                                                             0.42
                                                                       0.26
                                                                                 8.4
4
                                         0.54
                                                   0.34
                                                             0.42
                                                                       0.26
                                                                                 8.3
5
                                         0.54
                                                   0.34
                                                             0.41
                                                                       0.26
                                                                                 8.3
6
                                                                       0.25
                                         0.54
                                                   0.34
                                                             0.41
                                                                                 8.3
```

[Note that the model can and probably will change] The data set has 366 rows, only the first 6 are shown. The first column contains some information about the model. The <rain> column contains the mean of the Gamma distribution of the amount of rate. The shape is constant and is given in the firt column. Columns of the form P(w|lag) are the Markov probabilities of rain.

3.3 Simple Fitting For Model Choice

We count for each day of year:the number of "w" days following two "d" days; the number of "w" days following a "d" then a "w" day etc. Dividing by e.g. the number of times we have two consecutive "d" days give the estimated probability. The function make_all_probs does this, for all lags up to order (default 2). As well, for each day of year, we determine the mean and standard deviation of the rain of a "w" day both unconditional, and conditioned on lags up to max_mean_rain_order (default 1)

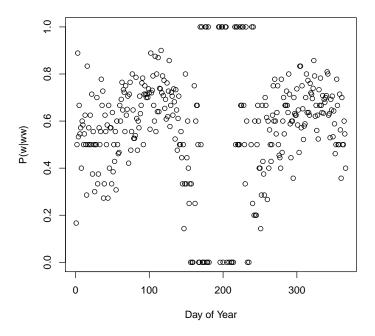
> zaza_pbs=make_all_probs(zaza_wm)

> head(zaza_pbs)

```
P(w) < rain > sd(rain) # days # wet days <math>P(w|w) P(w|d) # w # d P(w|ww) P(w|dw)
1 0.29
           9.4
                                                   0.30
                     16.0
                                62
                                             18
                                                           0.27 20 41
                                                                            0.17
                                                                                     0.38
                                                   0.50
                                                           0.27 18 44
                                                                                     0.43
  0.34
           5.4
                      7.9
                                62
                                             21
                                                                            0.50
3 0.52
           8.9
                     13.0
                                62
                                             32
                                                   0.71
                                                           0.41 21 41
                                                                            0.89
                                                                                     0.56
4 0.27
           9.0
                      8.2
                                62
                                             17
                                                   0.38
                                                           0.17 32 30
                                                                            0.53
                                                                                     0.33
5 0.39
           6.6
                      7.1
                                62
                                             24
                                                   0.65
                                                           0.29 17 45
                                                                            0.67
                                                                                     0.35
  0.40
           5.4
                      7.9
                                62
                                             25
                                                   0.58
                                                           0.29 24 38
                                                                            0.55
                                                                                     0.33
  P(w|wd) P(w|dd) #ww #dw #wd #dd < (r|w)>
                                                  \langle (r|d) \rangle sd\langle (r|d) #rw #rd
     0.50
                                    25
                                             2.0
                                                     12.7
                                                                2.4
                                                                        19.5
                                                                                6
               0.20
                      12
                           16
                                 8
1
                                                                                    11
2
     0.55
               0.20
                       6
                           14
                                11
                                     30
                                             4.3
                                                      6.2
                                                                5.3
                                                                         9.6
                                                                                9
                                                                                    12
3
     0.58
               0.38
                       9
                            9
                                     32
                                                                        13.2
                                                                               15
                                                                                    17
                                12
                                             7.7
                                                     10.1
                                                               13.1
4
     0.24
               0.12
                      15
                            6
                                17
                                     24
                                             9.7
                                                      7.4
                                                                9.3
                                                                         4.8
                                                                               12
                                                                                     5
5
     0.60
                                    25
               0.24
                      12
                           20
                                 5
                                             3.8
                                                      9.0
                                                                3.7
                                                                         8.5
                                                                                    13
                                                                               11
6
     0.62
               0.28
                      11
                            6
                                13
                                     32
                                             3.2
                                                      8.2
                                                                3.8
                                                                        10.6
                                                                               14
                                                                                    11
```

As we can see from a plot, the probabilities are all over the map. In this form they will not help use to choose a good model

> plot(zaza_pbs[,"P(w|ww)"],xlab="Day of Year",ylab="P(w|ww)")

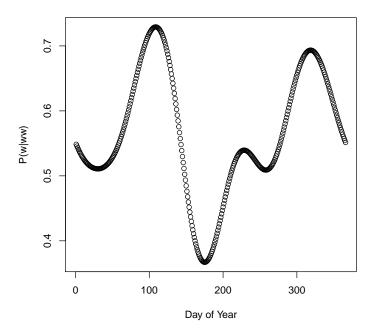


We need to smooth the probabilities. We fit a Fourier series (this has the advantage that we can make things periodic with period 1 year). The order of the fit can be determined before hand or determined interactively or automatically. The function used is make_approx_model_pl.

> zaza_approx = make_approx_model_pl(zaza_pbs,"/home/william/Reading/rstudio/climate/trunk

When fitting to obtain the approximate model , we weight each estimate by the number of observations used to obtain the estimate. So estimates based on only a single day (e.g. two consecutive "w" days during the dry season) are not given much weight.

> plot(zaza_approx[,"P(w|ww)"],xlab="Day of Year",ylab="P(w|ww)")



And things look much smoother.

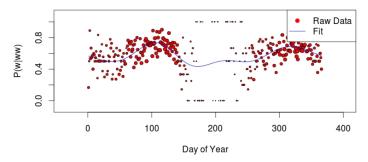
3.4 Interactive

We can also do the fitting interactively. At the console, enter the command

> zaza_mod = make_model_general(zaza_pbs,inter=TRUE)

We see a graph

Data fitted by Fourier series: order= 4



The red circles represent data points. The are of each circle is proportional to the weighting the data point has in the fit. The smallest circles are data point calculated from a single line of the raw data (so for probabilities are 0 or 1).

The blue line represents the fitted curve. It will change when we change the order of the Fourier fit.

On the console you will see:

enter

a: use this fit

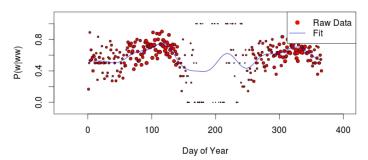
b: use previous order

f: add one to order

k: set order to k

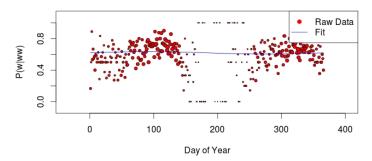
To enter a value you must type the value into the console and then press return. Entering a number changes the fit order to that number. Try entering 8. You get:

Data fitted by Fourier series: order= 8



The fit does not look that much better, especially when considering how much more wavy the line is. Try entering 1. You get:

Data fitted by Fourier series: order= 1



Clearly we are now underfitting. Enter 4, to get back to the first graph, then enter a to accept this fit. You will then have 5 more graphs to fit. Play around with the a,b and f keys or enter numbers. Repeatedly pressing a will use the default.

3.5 Synthetic Data

Once we have a model, we can use it to synthesize data. The command is

- > #load("zaza_synth")
- > zaza_synth=synth_data_set_mod(zaza_mod,num_years=83)
- > head(zaza_synth)

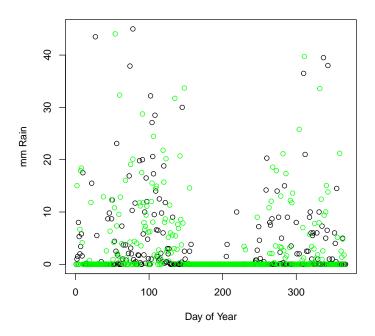
```
Date Rain DOY
  Station
    synth 1970-01-01
                       0.0
    synth 1970-01-02 15.0
                             2
    synth 1970-01-03
                             3
4
    synth 1970-01-04
                             4
                       0.0
5
    synth 1970-01-05
                             5
6
    synth 1970-01-06
                       6.7
                             6
```

The data will start from year 1970 by default. The number of years produced is limited by your patience (and by the address space of your machine, 200,000 years for a 32 bit machine; you need to have a **LOT** of patience to reach the limit if you have a 64 bit machine). As a rule of thumb 1000 years takes about a minute (your mileage will vary).

Let's compare the synthetic and the real data. Clearly we cannot expect day by day comparisons to be equal, indeed, compare the rain in 1931, to the first year of rain in the synthetic data.

```
> plot(zaza$Rain[93:459],xlab="Day of Year",ylab="mm Rain")
```

> points(zaza_synth\$Rain[1:366],col="green")



The exact values are different, but the pattern is similar. We now take advantage of the r function $x_split=split(x,y)$ where x and y are in the same dataframe. What this gives is a list indexed by the values of y. Each element contains every value of x with the given value of y. So zaza_split=split(zaza_doyRain, zaza_doyDOY) is a list of 366 vectors.

tt zaza_split[["120"]] is a vector of all rainfall on Day of Year 120. So mean(zaza_split[["120"]],na.rm=TRUE) is the mean rainfall on day 120 (the last arg means ignore NA's). We take further advantage by using the r function sapply(list, function,args) which applies function to every element of list, passing args to function. So sapply(zaza_split,mean,na.rm=TRUE) is a vector of the average rainfalls. Comparing

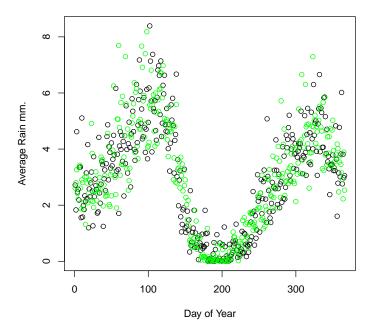
```
> zaza_split=split(zaza_doy$Rain,zaza_doy$DOY)
```

> synth_split=split(zaza_synth\$Rain,zaza_synth\$DOY)

> plot(sapply(zaza_split,mean,na.rm=TRUE),xlab="Day of Year",

⁺ ylab="Average Rain mm.")

> points(sapply(synth_split,mean,na.rm=TRUE),col="green")



The fit looks good on the mean, but we note that the variablity for the simulated data seems a bit lower that that of the real data.

3.6 Yearly Stats

If we split our real or synthetic data set by mod_year then we get a list of datasets, each covering a specific year. We can then find things such a the average spell length (over years), the maximum dry spell for each year etc. There is a simple function to split by mod_year adding the year it if it does not exist. The function add_spell_info calculates and adds the length of wet and dry spells. This should be applied before splitting if spells should cross year boundaries. Note that we need to add the Markov stuff before adding spell info.

```
> synth_wm= add_markov(zaza_synth)
> synth_spell= add_spell_info(synth_wm)
> zaza_spell=add_spell_info(zaza_wm)
> synth_split=split_by_year(synth_spell,year_begins_in_july=TRUE)
> zaza_split=split_by_year(zaza_spell,year_begins_in_july=TRUE)
> length(synth_split)

[1] 84
> head(synth_split[["1981"]])
```

```
Date Rain DOY wet_or_dry lag_1 lag_2 first_DOY spell_length
     Station
3835
       synth 1980-07-01
                             0 183
                                                         dd
                                                                   165
                                                                                   57
                                              d
                                                    d
3836
       synth 1980-07-02
                             0 184
                                              d
                                                    d
                                                         dd
                                                                   165
                                                                                   57
                             0 185
                                              d
                                                         dd
                                                                                   57
3837
       synth 1980-07-03
                                                    d
                                                                   165
3838
       synth 1980-07-04
                             0 186
                                              d
                                                    d
                                                         dd
                                                                   165
                                                                                   57
       synth 1980-07-05
                                              d
                                                                                   57
3839
                             0 187
                                                    d
                                                         dd
                                                                   165
3840
       synth 1980-07-06
                             0 188
                                                         dd
                                                                   165
                                                                                   57
     mod_year month day
3835
         1981
                   7
                        1
          1981
                        2
3836
                   7
3837
         1981
                   7
                        3
                   7
3838
         1981
                        4
3839
          1981
                   7
                        5
         1981
3840
```

> nrow(synth_split[["1981"]])

[1] 365

> length(zaza_split)

[1] 82

> head(zaza_split[["1951"]])

	Station		Date	Rain	DOY	wet_or_dry	lag_1	lag_2	Julian	first_DOY
7214	Zaza	1950-	-07-01	0	183	d	d	dd	-7124	151
7215	Zaza	1950-	-07-02	0	184	d	d	dd	-7123	151
7216	Zaza	1950-	-07-03	0	185	d	d	dd	-7122	151
7217	Zaza	1950-	-07-04	0	186	d	d	dd	-7121	151
7218	Zaza	1950-	-07-05	0	187	d	d	dd	-7120	151
7219	Zaza	1950-	-07-06	0	188	d	d	dd	-7119	151
	spell_le	ength	mod_ye	ear mo	onth	day				
7214		89	19	951	7	1				
7215		89	19	951	7	2				
7216		89	19	951	7	3				
7217		89	19	951	7	4				
7218		89	19	951	7	5				
7219		89	19	951	7	6				

> nrow(zaza_split[["1951"]])

[1] 365

So synth_split consists of 84 data sets (there is a partial year at the beginning and end) and zaza_split consists of 82 data sets (there are no partial years.)

3.6.1 Spell Lengths

We can look at the average dry spell length. For this we use the data that has not been spit into years. First we take only dry spells. To do this, take only rows of zaza_spell that correspond to a dry day.

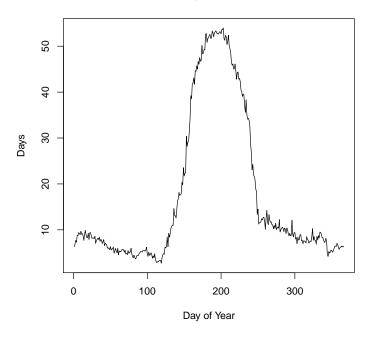
```
> zaza_dry=zaza_spell[(zaza_spell$wet_or_dry=="d"),]
> head(zaza_dry)
```

	Station D	ate	Rain	DOY	wet_or_dry	lag 1	lag 2	Julian	first DOY
1	Zaza 1930-10			275	d	<na></na>	•	-14337	275
4	Zaza 1930-10			278	d	W		-14334	278
5	Zaza 1930-10	-05	0	279	d	d		-14333	278
7	Zaza 1930-10	-07	0	281	d	W		-14331	
8	Zaza 1930-10	-08	0	282	d	d	dw	-14330	281
9	Zaza 1930-10	-09	0	283	d	d	dd	-14329	281
	spell_length								
1	1								
4	2								
5	2								
7	4								
8	4								
9	4								

Now we split the spell lengths by day of year, then take the mean (ignoring NA's). Plot this

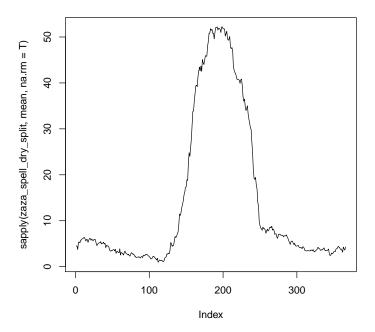
```
> dry_spell_split=split(zaza_dry$spell_length,zaza_dry$DOY)
> plot(sapply(dry_spell_split,mean,rm.na=T),type="l",xlab="Day of Year",
+ ylab="Days",main="Mean Length of Dry Spell")
```

Mean Length of Dry Spell



Note this is the average length of a dry spell, given that there is a dry spell. This may or may not be what you want. If you want the mean dry spell length, taking the dry spell length of a wet day to be 0 then this can be done by adding another column.

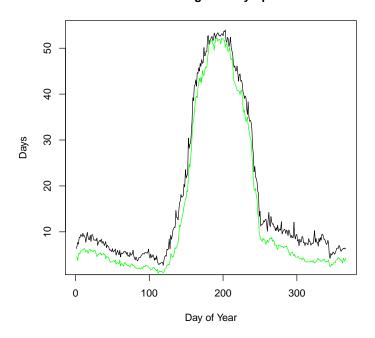
- > zaza_spell\$dry_spell_length=zaza_spell\$spell_length
- > zaza_spell\$dry_spell_length[zaza_spell\$wet_or_dry == "w"]=0
- > zaza_spell\$dry_spell_length[is.na(zaza_spell\$wet_or_dry)]=NA
- > zaza_spell_dry_split=split(zaza_spell\$dry_spell_length,zaza_spell\$DOY)
- > plot(sapply(zaza_spell_dry_split,mean,na.rm=T),type="1")



This looks similar. Plot them together for comparison. (note the use of the lines function which adds lines to a graph)

```
> plot(sapply(dry_spell_split,mean,rm.na=T),type="l",xlab="Day of Year",
+ ylab="Days",main="Mean Length of Dry Spell")
> lines(sapply(zaza_spell_dry_split,mean,na.rm=T),col="green")
```

Mean Length of Dry Spell

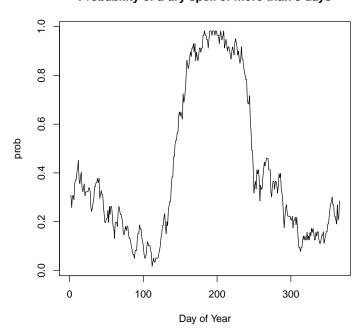


Assume that we know our crop can withstand dry spells of up to 5 days. Then we are interested in the probability of a dry spell of more than 5 days.

```
> zaza_dry_spell_over_5=zaza_spell[zaza_spell$wet_or_dry=="d" & zaza_spell$spell_length > 5
> zaza_dry_spell_over_5_split=split(zaza_dry_spell_over_5,zaza_dry_spell_over_5$DOY)
> num_of_dry_spells_over_5=sapply(zaza_dry_spell_over_5_split,nrow)
```

- > zaza_spell_good=zaza_spell[!is.na(zaza_spell\$wet_or_dry),]
- > zaza_spell_good_split=split(zaza_spell_good,zaza_spell_good\$DOY)
- > num_good_days=sapply(zaza_spell_good_split,nrow)
- > prob_of_dry_spell_over_5=num_of_dry_spells_over_5/num_good_days
- > plot(prob_of_dry_spell_over_5, type="l", xlab="Day of Year", ylab="prob",
- + main="Probability of a dry spell of more than 5 days")

Probability of a dry spell of more than 5 days



Naturally, all the above can be done with synthetic data as well. (Indeed, this is the whole point. Get your model from 20 years of real data, but get your probabilities from 100 or 1000 years of synthesized data. In some cases, the actual value can be obtained from the model by clever analysis (e.g. Markov model's and spell probabilities). However, R is cheap and fast; Statisticians capable of doing the analyses are expensive and slow. And what happens when you modify your model?)

3.6.2 First Day of Growing Season

Two common definitions of the "First Day of the Growing Season" are:

- 1. The first day of a period of n rainy days on which there is more than k millimetres of rain in total
- 2. As (1.) but additionally, there is no dry spell of k days in the next j days

The second definition may be defined as the time of successful planting (young seedlings may be injured or killed by a dry spell of k days) The function fdgs can calculate either of these for a year of data. So if we apply it to every year of data to find the distribution of the "First Day of the Growing Season" (we start our search in July if the growing season occurs in "winter"). So:

```
> first_days=sapply(zaza_split,fdgs)
```

> first_days_succ=sapply(zaza_split,fdgs,type=2)

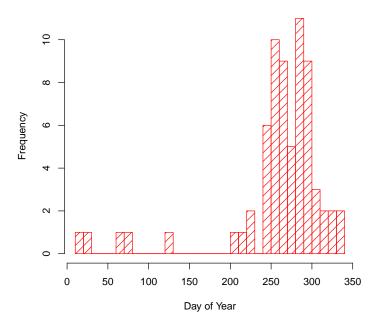
and we can do the same thing with synthetic data

- > first_days_synth=sapply(synth_split,fdgs)
- > first_days_succ_synth=sapply(synth_split,fdgs,type=2)

In this case a histogram is best for viewing a comparison.

- > hist(first_days,breaks=25,col="red",density=10,
- + xlab="Day of Year", main="First Day of Growing Season")

First Day of Growing Season

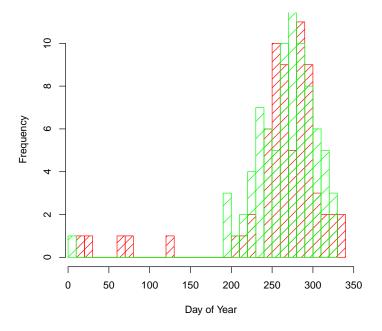


We can compare

this with the calculations from the synthetic data (note for adding information to a histogram, use the add=T) parameter.

- > hist(first_days,breaks=25,col="red",density=10,
- + xlab="Day of Year", main="First Day of Growing Season")
- $\verb| > hist(first_days_synth,breaks=25,col="green",density=5,add=T)| \\$





Again, this is similar but not identical.

Another question we might ask is: "In how many of the 82 years was planting by definition 1. successful?" To answer this we can compare, first_days and first_days_succ. We need to be careful to allow for NA's and for modding by 366.

- > diff=(first_days_succ-first_days) %% 366
- > diff_no_na=diff[!is.na(diff)]
- > diff_good=diff_no_na[diff_no_na==0]
- > length(diff_good)/length(diff_no_na)

[1] 0.51

This suggests that the default values do not work well for this site. Perhaps a more drought tolerant crop would work better, or wait for more rain before saying the growing season has started.