FED-3DA: A DYNAMIC AND PERSONALIZED FEDERATED LEARNING FRAMEWORK

Hui Wang^{1*}, Jie Sun¹, Tianyu Wo², Xudong Liu¹

¹ SKLSDE, School of Computer Science and Engineering, Beihang University, Beijing, China ² SKLSDE, School of Software, Beihang University, Beijing, China

ABSTRACT

In federated learning, the non-IID data generated from heterogeneous clients may reduce the global model efficiency. Previous studies use personalization as a common approach to adapt the global model to these clients (called the local model). However, client's data distribution may change dynamically with its location or environment, which can degrade the performance of the local model, leading to a new Dynamic Personalized Federated Learning (DPFL) problem. This paper proposes a novel approach to reduce the impact of the dynamic distribution on the local model based on metalearning and distribution distance measurement named Fed-3DA. It calculates the distribution distance periodically to perceive the distribution change on the client and adjust the local model preferences from a global meta-model through the distribution representation. Our experiments on public datasets show that Fed-3DA can effectively reduce the performance fluctuation of the local model in DPFL scenarios.

Index Terms— Dynamic personalized federated learning, non-IID data, Meta-learning, Distribution distance

1. INTRODUCTION

Federated Learning (FL) [1] is a distributed machine learning paradigm that implements cooperative learning among devices while protecting data privacy. FL typically involves one coordinator and multiple client devices. The global model training is an iterative process managed by the coordinator. At each training iteration, the coordinator sends the current state of the global model to the distributed devices. The devices then train the global model on their local data through stochastic gradient descent and generate local parameters, which are finally aggregated into the global model by the coordinator.

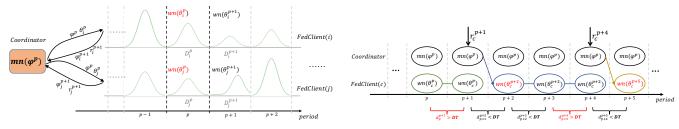
The IID sampling of the training data is important to ensure that the stochastic gradient is an unbiased estimate of the full gradient. Nonetheless, in most scenarios, the data is likely to be non-IID across devices. To address this problem, related works (e.g., [2, 3]) propose personalization-based approaches that allow each device to use a local model with personalized information for inference. However, these approaches cannot adapt to dynamic scenarios, where the data distribution of

each device may experience random drift due to changes in location or environment. More specifically, since the personalized working models are strongly correlated to the training data, their performance will decline dramatically when the data distribution changes during inference. We demonstrate this phenomenon through experiments in section 3.2.

Towards this problem, a straightforward idea is to update the personalized working models regularly to adapt to the data distribution change. However, this is also a challenging task. The reason is twofold. First, in most cases, labeling the data during model inference is expensive (e.g., it may need user interactions), and we can not assume enough data for the model update. Second, even though the data can be labeled in real-time, updating the model is computationally complex for existing approaches since it generally means training the personalized working models from scratch with the new data.

To solve the DPFL problem, we propose a new approach named Federated Dynamic Data Distribution Adaptive method (Fed-3DA). Fed-3DA can automatically detect the data distribution drift during the inference stage without relying on real-time labels and update the working models efficiently without the need for re-training. To achieve the first goal, Fed-3DA divides the timeline into fixed-length periods, and generates a low-dimensional feature vector (i.e., distribution representation vector) to represent the data distributions of each client in any period. Fed-3DA periodically calculates the data distribution distance of any two consecutive periods through optimal transport strategy [4] in order to detect the distribution drift. Towards the second goal, we use a global meta-model to establish the relationship between distribution representation vectors and working models at the training stage and share the distribution information among clients. Therefore, when the client data distribution drifts, Fed-3DA can update the corresponding working model by submitting the new distribution representation vector to the meta-model.

Contribution. (1) We define the DPFL problem and propose Fed-3DA to improve the performance of the local model. In addition to the *Accuracy*, the *MPV* and *LAT* (see section 3.1) are also proposed to evaluate the stability of the local model. (2) The experiments based on public datasets show that Fed-3DA can effectively reduce the performance jitter of the local model in DPFL scenarios.



(a) Training of models meta-network (mn) and work-network (wn)

(b) Update of model work-network (wn) weight

Fig. 1. Overview of proposed Fed-3DA.

2. METHOD

2.1. Problem Formulation

In DPFL, client c is equipped with its own data distribution \mathcal{P}^p_c in period p. The data of client c in period p is denoted as D^p_c , where $D^p_c = \{(x^{p(i)}_c, y^{p(i)}_c)\}_{i=1}^{S^p_c} \sim \mathcal{P}^p_c$, and S^p_c refers to the size of D^p_c . To simplify the problem, we assume all the clients have the same period size, i.e., $S^p_c \triangleq \{S^{p_i}_{c_i} = S^{p_j}_{c_j} \mid c_i, c_j \in [C]; p_i, p_j \in [P]\}$. C and P represent the total number of clients and periods. Let $\mathcal{L}^p_c(x^p_c, y^p_c; \theta^p_c)$ denote the loss function of client c in period p, and $\mathcal{L}^p(\theta^p) = \frac{1}{C} \sum_{c=1}^C \mathcal{L}^p_c(x^p_c, y^p_c; \theta^p_c)$ denote the average loss of clients in period p. θ^p denotes all the local model parameters $\{\theta^p_c\}_{c=1}^C$ in period p. The goal of the DPFL problem is to optimize

$$\arg\min_{\Theta}\mathcal{L}(\Theta) = \arg\min_{\Theta}\frac{1}{P}\sum_{p=1}^{P}\mathcal{L}^{p}(\theta^{p}), \tag{1}$$
 where Θ denotes the set of local model parameters, i.e., $\Theta =$

where Θ denotes the set of local model parameters, i.e., $\Theta = \{\theta_c^p\}_c^p, c \in [C], p \in [P].$

2.2. Distribution Distance between Different Datasets

Data D_c^p consists of a set of entries composed of features and labels (f, l). f and l represent the data feature vector that belong to the feature space \mathcal{FS} and the label vector that belong to the label space \mathcal{LS} .

$$D_c^p = \left\{ \left(f_c^{p(i)}, \ l_c^{p(i)} \right) \in \mathcal{FS} \times \mathcal{LS} \right\}_{i=1}^{\mathit{PS}},$$
 where PS represents the period size. Given two feature-label

where PS represents the period size. Given two feature-label pairs datasets D_1 =(f_1 , l_1) and D_2 =(f_2 , l_2), according to [5], the distance of them can be calculated with:

the distance of them can be calculated with:
$$d_{ot} = \left(d_f\left(f_1,f_2\right)^p + d_l\left(l_1,l_2\right)^p\right)^{1/p},\; p \geq 1\;.$$

 d_{ot} contains the feature distance d_f and label distance d_l . Moreover, d_l can be converted into d_f based on the definition:

$$\begin{array}{l} d_l \left(l_1, l_2 \right) = d_f \left(\frac{1}{N_1} \sum_{f \in \mathcal{U}_D(l_1)} f, \ \frac{1}{N_2} \sum_{f \in \mathcal{U}_D(l_2)} f \right), \\ \text{where } \mathcal{U}_D(l^*) &= \{ f | (f, \ l^*) \in D \}, \ N_1 &= |\mathcal{U}_D(l_1)|, \\ N_2 &= |\mathcal{U}_D(l_2)|. \ \text{On this basis, we can define the distribution distance between the data of two periods } D_c^m &= \{ (f_c^{m(i)}, l_c^{m(i)}) \}_{i=1}^{PS}, \ \text{and } D_c^n &= \{ (f_c^{n(i)}, l_c^{n(i)}) \}_{i=1}^{PS}. \end{array}$$

$$distance(D_{c}^{m}, D_{c}^{n}) = d_{f}(f_{c}^{m}, f_{c}^{n}) + d_{l}(l_{c}^{m}, l_{c}^{n}),$$
 (2)

where $d_f(f_c^m, f_c^n) = \sum_{i=1}^{PS} (f_c^{m(i)} - f_c^{n(i)})^2$. Since the samples are unlabeled, we ignore the d_l term in the inference.

2.3. Federated-3DA

Fed-3DA deploys a global meta-model (meta-network) on the coordinator and a work model (work-network) on each client, both of which are deep neural networks. The meta-network receives the distribution representation from each client and uses it to produce the weights for the corresponding work-network. On the other side, work-network is responsible for processing client data. We divide the training stage into continuous periods and vary the data distribution among different periods. The data in period p is denoted as D^p , which is generated by sampling from the available dataset. To estimate the data distribution in each period, we generate a feature vector r to represent the distribution of D^p . Vector r consists of the low-dimensional features extracted from the samples in D^p using t-SNE algorithm [6], as shown in **figure 2**.

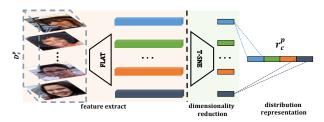


Fig. 2. Distribution representation of data D_c^p .

We restrict the distribution of D^p to $\mathcal{P}_{[iid]}$, $\mathcal{P}_{[0.5]}$, $\mathcal{P}_{[0.7]}$, $\mathcal{P}_{[0.8]}$, $\mathcal{P}_{[0.9]}$, $\mathcal{P}_{[0.4,0.4]}$, $\mathcal{P}_{[0.5,0.5]}$, and $\mathcal{P}_{[0.1,0.8]}$. $\mathcal{P}_{[iid]}$ denotes the D^p generated by random sampling from the training or test dataset. $\mathcal{P}_{[0.5]}$ indicates that 50% of the samples in D^p have the same label, and the rest are random. $\mathcal{P}_{[0.1,0.8]}$ indicates that 10% of the samples in D^p have label A and 80% have label B, while A and B are randomly selected. The sampling of D^p is shown in **figure 3**.



Fig. 3. The sampling of data D^p .

In each training period, we randomize the distribution

 \mathcal{P}_c^p and generate data \mathcal{D}_c^p for the client. The meta-network receives the distribution representation r_c^p from client and outputs the weights θ_c^p for the work-network (step 4 in algorithm 1). Fed-3DA uses the parameter update rule $\Delta \varphi = \alpha \Delta \theta \mathcal{L}_c$ to link the training of meta-network and work-network on the client side (step 6 in algorithm 2). $\Delta \theta$ is the change in local work model parameters after several client training rounds, which benefits the convergence of the meta-network The coordinator optimizes the *meta-network* by synchronously aggregating the gradients $\Delta \varphi$ from the clients (step 6 in algorithm 1). After multiple training rounds, we can build a mapping between the distribution representations and their corresponding personalized work models on meta*network*. The training of Fed-3DA is shown in **figure 1(a)**. In the inference stage, when the amount of data processed reaches period size, the client calculates the distribution distance $d_{p-1}^p = distance(D_c^p, D_c^{p-1})$ with the previous period. We set a hyper-parameter DT as the distribution distance threshold for us to identify the distribution drift. If $d_{n-1}^p >$ DT, then the local data distribution is considered as changed. The client then uploads the current distribution representation r_c^p to the *meta-network* and downloads the updated work-network weights θ_c^{p+1} for the next period (see **figure** 1(b)).

Algorithm 1 Fed-3DA (meta-network)

Input: FE: federated training rounds, C: client number. **Output**: meta-network weights φ , work-network weights θ .

Initialize the meta-network, with φ^{-1} random clients' data

Initialize the *meta-network* with φ^1 , random clients' data $\{D_c^1\}_{c=1}^C$.

```
1: generate the distribution representation \{r_c^1\}_{c=1}^C for \{D_c^1\}_{c=1}^C 2: for fe=1,...,FE do
3: for c=1,...,C do
4: \theta_c^{fe}=meta-network(\varphi^{fe},r_c^{fe})
5: \varphi_c^{fe+1},r_c^{fe+1}\leftarrow \mathbf{FedClientTrain}(\varphi^{fe},\theta_c^{fe})
6: \varphi^{fe+1}\leftarrow \frac{1}{C}\sum_{c=1}^C \varphi_c^{fe+1}
7: while receive r_c^p from client c do
8: return \theta_c^{p+1}=meta-network(\varphi^{fe},r_c^p)
```

2.4. Theoretical Analysis

In Fed-3DA, a multi-task learning is formed among the clients [8]. Let $f(\cdot; \varphi^p)$ denote the *meta-network* parameterized by φ^p , $w(\cdot; \theta^p_c)$ denote the *work-network* parameterized by θ^p_c . Given the distribution representation r^p_c , the *meta-network* outputs the weights θ^p_c for the *work-network*, i.e., $\theta^p = f(r^p_1...r^p_c; \varphi^p)$, $\theta^p = \{\theta^p_c\}_{c=1}^C$. Equation (1) can be adjusted to obtain the optimal expression of the DPFL problem:

$$\arg \min_{r_1^p, ..., r_c^p, \varphi^p} \frac{1}{P} \sum_{p=1}^P \mathcal{L}^p(f(r_1^p, ..., r_c^p; \varphi^p))$$
(3)

We denote by $\widehat{ER}(\varphi,r)$ the empirical loss of the *metanetwork* over all the P periods $\widehat{ER}(\varphi,r)=\frac{1}{PC}\sum_{p=1}^{P}\sum_{c=1}^{C}$

Algorithm 2 Fed-3DA (work-network)

Input: LE: client training rounds, DT: distribution distance threshold, α : federated learning rate, η : client learning rate, PS: period size, φ^{fe} : copy of meta-network weights, θ^{fe}_c : work-network weights, \mathcal{L}_c : loss function. **Output**: φ^{fe+1} , distribution representation r_c^{fe+1} and $\hat{y}_c^{p(i)}$.

```
1: FedClientTrain(\varphi^{fe}, \theta_c^{fe}):
  2: set \hat{\theta} = \theta_c^{fe}
  3: for le = 1, ..., LE do
               for b in batchs(D_c^{fe}) do
 4: For D in Datchs(D_c^c) do

5: \theta_c^{fe} \leftarrow \theta_c^{fe} - \eta \mathcal{L}_c
6: \varphi^{fe+1} \leftarrow \varphi^{fe} - \alpha(\hat{\theta} - \theta_c^{fe}) \mathcal{L}_c
7: random \mathcal{P}_c^{fe+1} and generate D_c^{fe+1} = \{(x_c^i, y_c^i)\}_{i=1}^{PS}
8: generate the distribution representation r_c^{fe+1} for D_c^{fe+1}
  9: return \varphi^{fe+1}, r_c^{fe+1}
10: while receive (x_c^{p(i)}, *) do
               if i>PS & distance(D_c^p, D_c^{p-1})>DT then
11:
12:
                      generate the distribution representation r_c^p for D_c^p
                     \begin{array}{l} \theta_c^{p+1} = \textit{meta-network}(\varphi^{fe}, r_c^p) \text{ and } p +\!\!\!+ \\ y_c^{p(i)} = \textit{work-network}(\theta_c^{p+1}, x_c^{p(i)}) \text{ and } i +\!\!\!\!+ \end{array}
13:
14:
15:
                     y_c^{p(i)} = \textit{work-network}(\theta_c^p, x_c^{p(i)}) and i++
16:
```

 $\begin{array}{l} \mathcal{L}^p_c(x^p_c,y^p_c;f(r^p_c;\varphi^p)) \ \ \text{and by} \ \ ER(\varphi,r) \ \ \text{the expected loss} \\ ER(\varphi,r) = \frac{1}{PC} \sum_{p=1}^P \sum_{c=1}^C \mathbb{E}_{(x,y)\sim\mathcal{P}^p_c}[\mathcal{L}^p_c(x,y;f(r^p_c;\varphi^p))]. \end{array}$

Theorem 1. Let the space of the meta-network parameter and clients' distribution representation be bounded in a minimum enclosing ball of radius R_e , and the dimension of them are N and E. Let Lip_l , Lip_{φ} and Lip_r be the Lipschitz constant of functions $\mathcal{L}^p_c(x,y)$, $f(*;\varphi)$ and f(r;*). For all p, ε, δ with $p \in [P]$ and $0 < \varepsilon, \delta < 1$, if the period size S satisfies $S \ge \mathbb{Q}(\frac{CE+N}{C\varepsilon^2}(\log R_e Lip_l(Lip_{\varphi} + Lip_r) - \log(\varepsilon\delta)))$, we have with probability at least I- δ , any φ , r will satisfy $|\widehat{ER}(\varphi,r) - ER(\varphi,r)| \le \varepsilon$.

Proof. The detailed proof is omitted due to space limitations. The full proof can be found in appendix [9].

3. EXPERIMENTS

Dataset and Metric: We evaluate Fed-3DA using three image classification datasets: CIFAR10, CIFAR100 [10], and Fashion-MNIST [11]. We report the *Accuracy*, *MPV*, and *LAT*, of which the latter two are defined in **equations (4)** and **(5)**. **Baseline:** (a) Local, local training on each client without sharing the gradient. (b) FedAvg [1], a global model trained through the gradient sharing between the clients. (c) pFedHN [12], a personalized FL approach based on *Hypernetwork* that outperforms *Per-FedAvg* [13], *FedPer* [14], *pFedMe* [15].

3.1. MPV and LAT Metrics

We define "multi-period variance" (MPV) to measure the fluctuation of the client test accuracy. MPV_n^i represents the

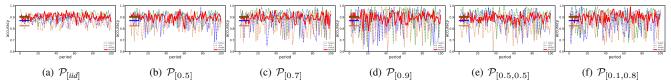


Fig. 4. Accuracy evaluated on the Fashion-MNIST. The validation accuracy is marked with a short line (FedAvg: 90.7%, Fed-3DA: 89.9%, Local: 87.1%, pFedHN: 82.5%). The distribution distance threshold (DT) comes from the maximum between the heterogeneous datasets. For more details, see appendix [9].

clients' test accuracy fluctuation in the i^{th} n period. VACC denotes the model validation accuracy. $TACC_c^p$ represents the test accuracy of client c in period p.

$$MPV_n^i = \frac{1}{n} \sum_{p=(i-1)n+1}^{in} \frac{1}{C} \sum_{c=1}^{C} (TACC_c^p - VACC)^2$$
 (4)

We define "accuracy threshold" (AT) as 90% of the model validation accuracy and calculate the proportion of clients, whose test accuracy is lower than the threshold, in all periods (denoted as LAT). LAT_n^i represents the proportion of the clients that meet the above definition in the i^{th} n period. VACC denotes the model validation accuracy.

$$LAT_{n}^{i} = \frac{1}{nC} \sum_{p=(i-1)n+1}^{in} f(p; i, n); where$$

$$f(p; i, n) = \begin{cases} 1, & 0 \le \frac{(VACC - TACC_{c}^{p})}{VACC} \le AT \\ 0, & else \end{cases}$$
(5)

3.2. Test Accuracy Fluctuation on non-IID Data

We optimize the global model based on the algorithm Fe-dAvg [1], the validation accuracy obtained on the CIFAR10 and Fashion-MNIST are: 57.67% and 90.7%. We generate the D^p for testing by random sample from the test set. The test accuracy is shown in **figure 5**. Under the IID distribution (**subfigure a**), the accuracy fluctuates the least. Under the non-IID condition (**subfigure b-f**), the more extreme the distribution type, the greater the accuracy fluctuation.

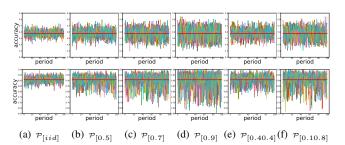


Fig. 5. *Test accuracy fluctuation*. The validation accuracy is marked with the red line (CIFAR10: first row, Fashion-MNIST: second row, ten clients, period size of 1K).

3.3. Model Adaptability under the Dynamic Distribution

We compare the Fed-3DA with other FL approaches, the results of *MPV* and *LAT* are presented in **table 1**. The test accuracy fluctuations on dataset Fashion-MNIST are shown in **figure 4**. The baselines: local, FedAvg and pFedHN, perform poorly on most tasks, showing the importance of the DPFL. Fed-3DA achieves significant 4.6%-20.1% and 5.3%-26.4% improvements over competing approaches in metrics *MPV* and *LAT* under the different distributions. These results demonstrate that Fed-3DA can effectively control the performance decline and reduce the model volatility.

Table 1. MPV and LAT evaluation.

Approach	CIFAR10		CIFAR100		Fashion-MNIST	
••	MPV_{100}^{1}	LAT_{100}^1	MPV_{100}^1	LAT_{100}^1	MPV_{100}^1	LAT_{100}^1
Local _[iid]	3.16 ± 0.52	$ 20 \pm 2 $	1.58 ± 0.63	31 ± 1	1.11 ± 0.57	1 ± 1
Local [0.5]	5.71 ± 1.91	$ 27 \pm 2 $	9.49 ± 6.44	49 ± 1	5.33 ± 2.26	9 ± 1
Local [0.7]	11.23 ± 3.74	32 ± 1	9.48 ± 1.41	54 ± 2	5.42 ± 0.30	13 ± 1
Local [0.8]	12.25 ± 1.95	$ 33 \pm 2 $	20.71 ± 10.40	55 ± 3	9.57 ± 5.78	16 ± 1
Local [0.9]	18.48 ± 7.29	33 ± 1	20.93 ± 10.74	57 ± 1	10.77 ± 2.07	18 ± 2
Local [0.4,0.4]	4.70 ± 2.10	31 ± 1	8.43 ± 2.29	49 ± 2	3.82 ± 0.94	10 ± 1
Local [0.5,0.5]	10.34 ± 5.42	34 ± 1	10.63 ± 3.36	49 ± 2	4.54 ± 2.73	15 ± 1
Local [0.1,0.8]	17.29 ± 3.65	34 ± 2	16.46 ± 8.75	57 ± 3	8.95 ± 3.48	15 ± 1
$FedAvg _{[iid]}$	2.56 ± 0.74	17 ± 6	3.07 ± 1.69	33 ± 3	0.78 ± 0.28	1 ± 1
FedAvg _[0.5]	6.19 ± 1.67	27 ± 5	9.73 ± 0.89	45 ± 2	3.74 ± 2.68	7 ± 1
FedAvg _[0.7]	10.97 ± 3.82	31 ± 7	9.30 ± 3.23	48 ± 1	3.42 ± 0.62	14 ± 1
FedAvg _[0.8]	15.00 ± 1.31	33 ± 5	13.91 ± 7.89	52 ± 3	3.21 ± 1.46	14 ± 1
FedAvg [0.9]	18.13 ± 3.77	33 ± 6	20.87 ± 3.23	52 ± 2	9.32 ± 4.73	19 ± 2
FedAvg [0.4,0.4]	9.59 ± 1.11	26 ± 5	7.00 ± 1.12	45 ± 2	2.64 ± 0.79	6 ± 1
FedAvg [0.5,0.5]	9.80 ± 2.99	29 ± 5	12.40 ± 5.21	47 ± 2	5.83 ± 0.66	12 ± 1
FedAvg [0.1,0.8]	13.97 ± 3.72	32 ± 6	15.61 ± 6.49	50 ± 2	9.23 ± 7.18	19 ± 1
$pFedHN _{[iid]}$	3.50 ± 1.94	30 ± 3	1.66 ± 0.17	39 ± 1	4.08 ± 0.39	8 ± 2
pFedHN _[0.5]	18.01 ± 3.01	60 ± 1	6.62 ± 4.13	69 ± 1	8.50 ± 3.21	16 ± 2
pFedHN [0.7]	31.67 ± 16.85	65 ± 2	10.78 ± 1.61	77 ± 1	8.83 ± 2.75	21 ± 1
pFedHN _[0.8]	50.77 ± 19.15	65 ± 2	37.97 ± 10.02	78 ± 1	32.40 ± 10.21	20 ± 2
pFedHN _[0.9]	69.14 ± 28.95	65 ± 3	49.23 ± 12.70	78 ± 1	26.00 ± 6.75	25 ± 2
pFedHN [0.4,0.4]	26.16 ± 5.42	51 ± 1	6.61 ± 2.31	68 ± 2	8.30 ± 2.54	16 ± 1
pFedHN [0.5,0.5]	39.83 ± 2.86	51 ± 3	20.67 ± 2.24	70 ± 2	15.01 ± 2.31	19 ± 1
pFedHN [0.1.0.8]	77.64 ± 50.21	64 ± 1	35.55 ± 31.95	74 ± 1	20.21 ± 5.47	22 ± 1
$Fed-3DA _{[iid]}$	2.05 ± 0.20	5 ± 1	1.51 ± 0.62	20 ± 1	0.78 ± 0.19	1 ± 1
Fed-3DA _[0.5]	5.56 ± 0.80	16 ± 1	6.84 ± 1.31	36 ± 1	$\textbf{2.13} \pm \textbf{0.48}$	7 ± 1
Fed-3DA _[0.7]	8.01 ± 0.41	21 ± 1	$\textbf{8.82} \pm \textbf{4.43}$	41 ± 3	$\textbf{2.83} \pm \textbf{1.63}$	13 ± 1
Fed-3DA [0.8]	12.10 ± 4.86	25 ± 2	$\textbf{13.51} \pm \textbf{2.48}$	43 ± 2	3.11 ± 1.29	14 ± 1
Fed-3DA [0.9]	18.07 ± 9.64	27 ± 1	$\textbf{20.34} \pm \textbf{3.49}$	45 ± 2	6.77 ± 4.39	18 ± 1
Fed-3DA $_{[0,4,0,4]}$	4.41 ± 1.26	17 ± 1	$\textbf{6.53} \pm \textbf{5.12}$	36 ± 1	$\textbf{2.20} \pm \textbf{1.07}$	6 ± 2
Fed-3DA $[0.5, 0.5]$	9.49 ± 1.12	21 ± 1	$\textbf{10.46} \pm \textbf{8.69}$	37 ± 2	$\textbf{3.94} \pm \textbf{0.72}$	11 ± 1
$\frac{\text{Fed-3DA} _{[0.1,0.8]}}{}$	12.67 ± 6.05	25 ± 1	$\textbf{15.46} \pm \textbf{5.72}$	$\textbf{44}\pm \textbf{1}$	$\textbf{4.01} \pm \textbf{3.63}$	15 ± 1

4. CONCLUSION

We formulate the DPFL problem and propose a new method named Fed-3DA, which can automatically detect the data distribution drift during the inference stage without relying on real-time labels. Besides, Fed-3DA can update the working models efficiently during run-time. Based on experiments, we show that Fed-3DA outperforms the baseline approaches.

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