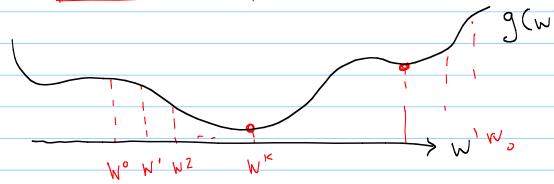
Note Title

Numerical Optimization

 $m \cdot h \quad d(\underline{m})$

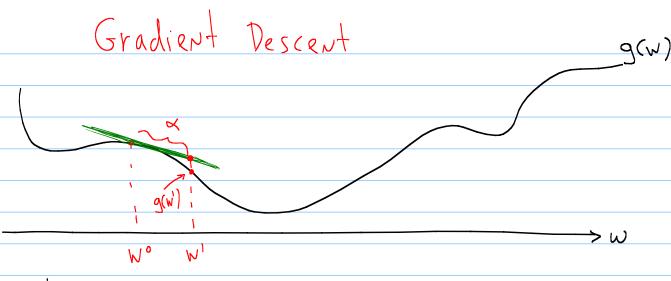
Tq(w) = 0 stationary point



How do you stop the tention?

• $\|\nabla q(\bar{w})\|_2^2 < \varepsilon$

le Norm Euch dean Non $\|x\|_{2}^{2} = \frac{1}{2} \times \frac{2}{1}$



· Linear approximation at W° is given by the 1st order Taylor approximation

$$h(\bar{w}) = g(\bar{w}^\circ) + Vg(\bar{w}^\circ)^T(\bar{w} - \bar{w}^\circ)$$

- · Downhill direction is given by Dg(wo) (finitede
- · Start & No

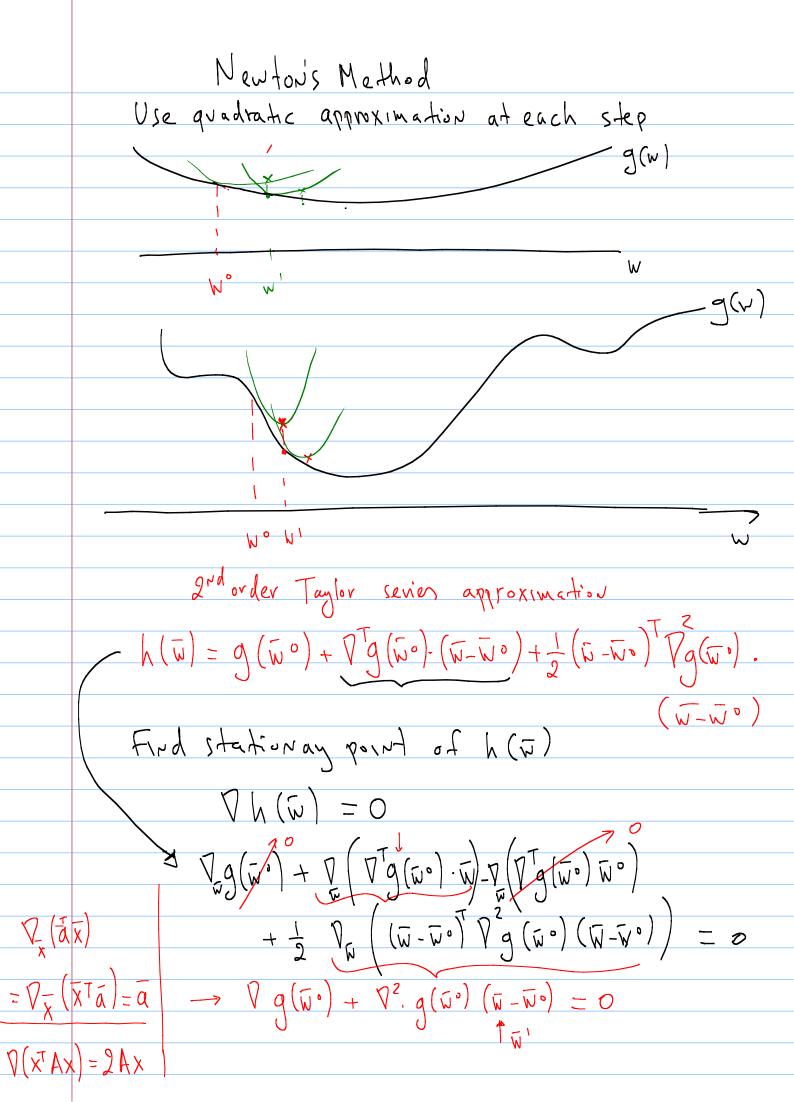
general form

$$W^{k} = W^{k-1} - X \sqrt{g(W^{k-1})}$$

$$g(W)$$

$$W^{\circ}$$

$$W^{\circ}$$



$$V_{g(\bar{w}^{\circ})} + V_{g(\bar{w}^{\circ})} W_{1} - V_{g(\bar{w}^{\circ})} \bar{w}^{\circ} = 0$$

$$V_{g(\bar{w}^{\circ})} W_{1} = V_{g(\bar{w}^{\circ})} \bar{w}^{\circ} - V_{$$