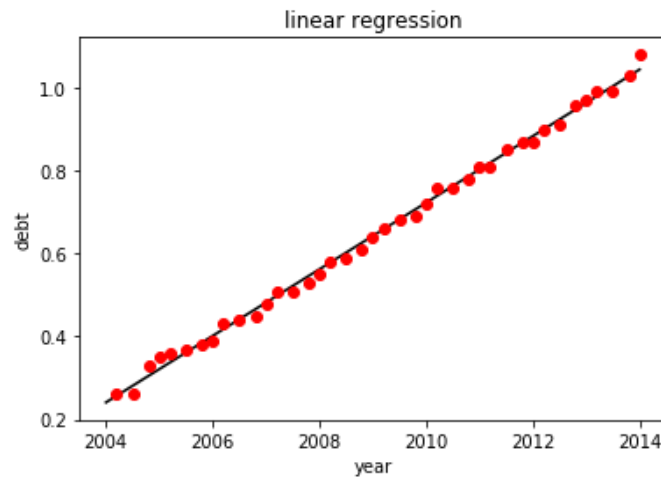


## HW2 Huaiyu Wang

3.1



Output: [3.93601056]

$w = 8.03244175 \times 10^{-2}$

$b = -1.60729045 \times 10^2$

In 2050, the student loan debt will be **3.93601056**

Code here:

```
import csv
```

```
from pylab import *
```

```
def main():
    rfile = 'student_debt.csv'
    csvfile = open(rfile, 'rt')
    data = csv.reader(csvfile, delimiter = ',')
    X = []
    Y = []
    for i, row in enumerate(data):
        X.append(float(row[0]))
        Y.append(float(row[1]))

    X = array(X)
    X_temp = X[:]
    Y = array(Y)
    one = ones((len(X)))
    X = row_stack((one,X))
    X = X.T
    Y = reshape(Y, (len(Y),1))
    weight = linearfit(X,Y)
    print (weight)
```

```
it = np.arange(2004, 2015, 1)
plt.ylabel('debt')
plt.xlabel('year')
plt.title('linear regression')
g = weight[1] * it + weight[0]
plt.plot(it, g, 'k')
plt.plot(X_temp, Y, 'ro')
plt.show()
plt.close()
print (weight[1] * 2050 + weight[0])
```

```
def linearfit(X, Y):
    W = dot(inv(dot(X.T, X)), dot(X.T, Y))
    return W
```

```
main()
```

HW2 Huaiyu Wang

$$\begin{aligned}
 3.3 \text{ (a)} \quad g(\bar{w}) &= \frac{p}{p+1} (\bar{x}^T \bar{w} - y_p)^2 \\
 &= \frac{p}{p+1} [(\bar{x}_p^T \bar{w})^T (\bar{x}_p^T \bar{w}) - 2y_p \bar{x}_p^T \bar{w} + y_p^2] \\
 &= \frac{p}{p+1} (\bar{w}^T \bar{x}_p \bar{x}_p^T \bar{w} - 2y_p \bar{x}_p^T \bar{w} + y_p^2) \\
 &= \frac{1}{2} \bar{w}^T \underbrace{\left( \sum_{p=1}^p 2 \bar{x}_p \bar{x}_p^T \right)}_{\bar{Q}} \bar{w} - \underbrace{\left( \sum_{p=1}^p 2 y_p \bar{x}_p^T \right)}_{\bar{r}^T} \bar{w} + \underbrace{\sum_{p=1}^p y_p^2}_d \\
 &= \frac{1}{2} \bar{w}^T \bar{Q} \bar{w} + \bar{r}^T \bar{w} + d
 \end{aligned}$$

1b) for any  $\bar{x}_p \bar{x}_p^T = A$ , has eigenvalue  $a$  with eigenvector  $\bar{v}$ .

$$\bar{x}_p \bar{x}_p^T \bar{v} = a \bar{v}$$

$$\bar{v}^T a \bar{v} = \bar{v}^T \bar{x}_p \bar{x}_p^T \bar{v} = (\bar{x}_p^T \bar{v})^T (\bar{x}_p^T \bar{v}) = \|\bar{x}_p^T \bar{v}\|^2 \geq 0.$$

$$a \bar{v}^T \bar{v} = a \|\bar{v}\|^2 \geq 0 \quad \therefore a \geq 0$$

$$\therefore \bar{Q} = \sum_{p=1}^p 2 \bar{x}_p \bar{x}_p^T$$

$\therefore \bar{Q}$  has all ~~non~~ nonnegative eigenvalues.

$$(c) \quad \nabla g(\bar{w}) = \frac{1}{2} (\bar{Q} + \bar{Q}^T) \bar{w} + \bar{r} \quad \bar{Q} = \sum_{p=1}^p 2 \bar{x}_p \bar{x}_p^T \text{ is symmetric}$$

$$\therefore \bar{Q} = \bar{Q}^T$$

$$\nabla g(\bar{w}) = \frac{1}{2} \bar{Q} \bar{w} + \bar{r}$$

$\nabla^2 g(\bar{w}) = \bar{Q}$  has all ~~non~~ nonnegative eigenvalues.

$\therefore g(\bar{w})$  is convex.

$$d) \nabla^2 g(\bar{w}^{k+1}) \bar{w}^k = \nabla^2 g(\bar{w}^{k+1}) \bar{w}^{k+1} - \nabla g(\bar{w}^{k+1})$$

$$\bar{Q} \bar{w}^k = \bar{Q} \bar{w}^{k+1} - (\bar{Q} \bar{w}^{k+1} + \bar{r}^T)$$

$$\bar{Q} \bar{w}^k = -\bar{r}$$

$$\left( \sum_{p=1}^P \bar{x}_p \bar{x}_p^T \right) \bar{w}^k = \left( \sum_{p=1}^P \bar{y}_p \bar{x}_p^T \right)^T$$

$$\left( \sum_{p=1}^P \bar{x}_p \bar{x}_p^T \right) \bar{w} = \sum_{p=1}^P \bar{x}_p \bar{y}_p$$

$$3.10 \quad a) \quad \delta(t) = \frac{1}{1+e^{-t}}$$

$$\delta^{-1}(\delta(t)) = \log\left(\frac{\frac{1}{1+e^{-t}}}{1 - \frac{1}{1+e^{-t}}}\right) = \log\left(\frac{\frac{1}{1+e^{-t}}}{\frac{e^{-t}}{1+e^{-t}}}\right)$$

$$= \log(e^t) = t$$

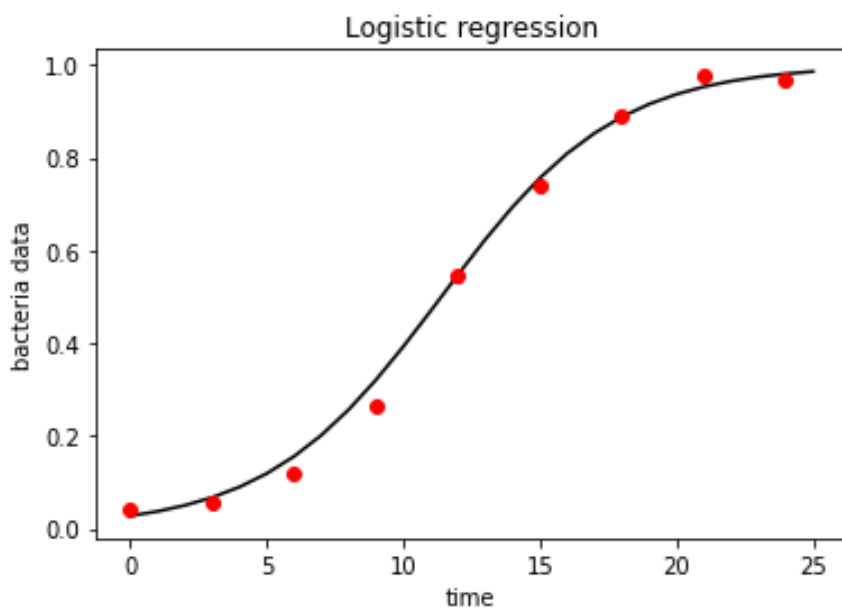
$$b) \quad \delta(b + x_p w) = y_p$$

$$\frac{1}{1 + e^{-(b + x_p w)}} = y_p$$

$$e^{-(b + x_p w)} = \frac{y_p - 1}{y_p}$$

$$b + x_p w = \log\left(\frac{y_p}{1 - y_p}\right) \quad p=1, \dots, P$$

(c)



Code here :

```
import csv
from pylab import *

def linearfit(X, Y):
    W = dot(inv(dot(X.T, X)), dot(X.T, Y))
    return W

def sigmoid(x):
    return 1 / (1 + exp(-x))

def main():
    rfile = 'bacteria_data.csv'
    csvfile = open(rfile, 'rt')
    data = csv.reader(csvfile, delimiter = ',')
    X = []
    Y = []
    for i, row in enumerate(data):
        X.append(float(row[0]))
        Y.append(float(row[1]))
    X = array(X)
    Y = array(Y)
    X1 = X[:]
    Y1 = Y[:]
    one = ones(len(X))
    X = column_stack((one, X))
    Y = Y.T
    Y = log(Y/(1-Y))
    w = linearfit(X, Y)

    it = np.arange(0, 26, 1)
    plt.ylabel('bacteria data')
    plt.xlabel('time')
    plt.title('Logistic regression')
    g = sigmoid(w[1] * it + w[0])
    plt.plot(it, g, 'k')
    plt.plot(X1, Y1, 'ro')
    plt.show()
    plt.close()
main()
```

$$3.11 \quad a, \quad \delta \alpha_i = \delta \alpha_i (1 - \delta \alpha_i)$$

$$\tilde{x}_p = \begin{pmatrix} 1 \\ \bar{x}_p \end{pmatrix} \quad \tilde{w} = \begin{pmatrix} b \\ \bar{w} \end{pmatrix} \quad \tilde{x}_p^T \cdot \tilde{w} = b + \bar{x}_p^T \bar{w}$$

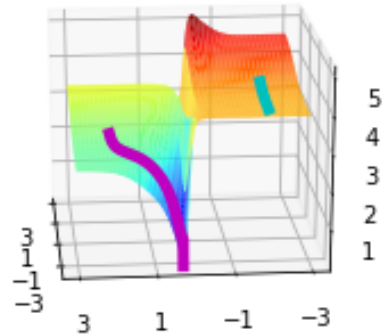
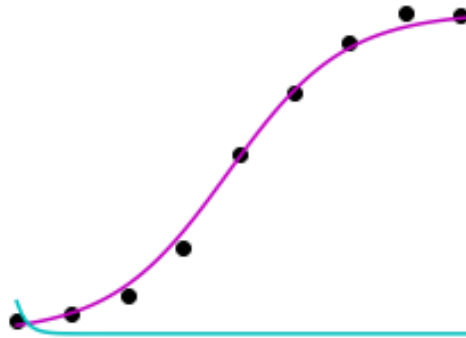
$$\nabla g(\tilde{w}) = 2 \sum_{p=1}^P (\delta(\tilde{x}_p^T \tilde{w}) - y_p) \cdot \nabla_{\tilde{w}} (\delta(\tilde{x}_p^T \tilde{w})) \cdot \nabla_{\tilde{w}} (\tilde{x}_p^T \tilde{w} + b)$$

$$\nabla g(\tilde{w}) = 2 \sum_{p=1}^P (\delta(\tilde{x}_p^T \tilde{w}) - y_p) \cdot \nabla_{\tilde{w}} \delta(\tilde{x}_p^T \tilde{w}) \cdot \nabla_{\tilde{w}} (\tilde{x}_p^T \tilde{w})$$

$$= 2 \sum_{p=1}^P (\delta(\tilde{x}_p^T \tilde{w}) - y_p) \cdot \nabla_{\tilde{w}} \delta(\tilde{x}_p^T \tilde{w}) \cdot \tilde{x}_p$$

$$= 2 \sum_{p=1}^P (\delta(\tilde{x}_p^T \tilde{w}) - y_p) \cdot \delta(\tilde{x}_p^T \tilde{w}) / (1 - \delta(\tilde{x}_p^T \tilde{w})) \tilde{x}_p$$

(b)



# YOUR CODE GOES HERE - compute gradient

```
grad=0
for p in range(0,np.shape(X)[0]):
    grad+=2*(s(np.dot(X[p].T,w))-y[p])*s(np.dot(X[p].T,w))*(1-
s(np.dot(X[p].T,w)))*X[p]
grad=np.asarray(grad)
grad.shape=(2,1)
```

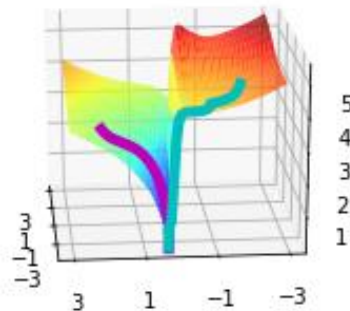
$$3.13(a) \quad g(b, \tilde{w}) = \sum_{p=1}^P (\sigma(b + \tilde{x}_p^T \tilde{w}) - y_p)^2 + \lambda \|\tilde{w}\|_2^2$$

$$\nabla_{\tilde{w}} (\lambda \|\tilde{w}\|_2^2) = 2\lambda \begin{pmatrix} 0 \\ \tilde{w} \end{pmatrix}$$

Substituting 3.11(a) .

$$\nabla g(\tilde{w}) = 2 \sum_{p=1}^P (\sigma(\tilde{x}_p^T \tilde{w}) - y_p) \sigma(\tilde{x}_p^T \tilde{w}) (1 - \sigma(\tilde{x}_p^T \tilde{w})) \tilde{x}_p + 2\lambda \begin{pmatrix} 0 \\ \tilde{w} \end{pmatrix}$$

(b)



Code here :

```
def gradient_descent(X,y,w0,lam):
    w_path = [] # container for weights learned at each iteration
    cost_path = [] # container for associated objective values at each
iteration
    w_path.append(w0)
    cost = compute_cost(w0)
    cost_path.append(cost)
    w= w0
    w1= np.array([0,0])
    w1.shape = (2,1)
    # start gradient descent loop
    max_its =20000
    alpha = 10**(-2)
    for k in range(max_its):
        # YOUR CODE GOES HERE - compute gradient
        grad=0
        for p in range(0,np.shape(X)[0]):
            grad+=2*(s(np.dot(X[p].T,w))-y[p])*s(np.dot(X[p].T,w))*(1-
s(np.dot(X[p].T,w)))*X[p]
        grad=np.asarray(grad)
        grad.shape=(2,1)
        w1[1]=w[1]
        grad=grad+0.05*w1

        # take gradient step
        w = w - alpha*grad

        # update path containers
        w_path.append(w)
        cost = compute_cost(w)
        cost_path.append(cost)

    # reshape containers for use in plotting in 3d
    w_path = np.asarray(w_path)
    w_path.shape = (np.shape(w_path)[0],2)

    cost_path = np.asarray(cost_path)
    cost_path.shape = (np.size(cost_path),1)

    return w_path,cost_path
```