Project 1: Taylor Series Numerical Methods for ODEs

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¹In alphabetical order

Outline

- Elementary
 - The Basic Problem That We Studied
 - Works with Matlab
- Our Results
 - Primary Results
 - Improved Method
- Others



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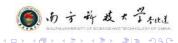


Initial Value Problem

$$\begin{cases} y'(x) = f(x,y) & a \le x \le b \\ y(x_0) = y_0 \end{cases}$$
 (1)

where y_0 is a known constant.

- If f(x,y) satisfies Lipschitz condition, y=y(x) has unique solution
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- Trapezoidal Method(TM)
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From Picard Method

$$\int_{x_{k}}^{x_{k+1}} y'(x) dx = \int_{x_{k}}^{x_{k+1}} f(x, y(x)) dx$$

$$i.e. \ y(x_{k+1}) - y(x_{k}) = \int_{x_{k}}^{x_{k+1}} f(x, y(x)) dx$$

- EM: Left rectangle replace right-hand integra
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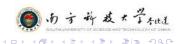
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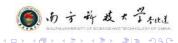
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Taylor Series Method

TSM needs more information of the points

• Iteration:
$$y_{k+1} = y_k + hy'_k + \frac{h^2}{2}y''_k + \dots + \frac{h^p}{p!}y_k^{(p)}$$

Way to get differentials

$$y' = f(x,y) \equiv f^{(0)}$$

$$y'' = \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial x} = \frac{\partial f^{(0)}}{\partial x} + \frac{\partial f^{(0)}}{\partial y} f \equiv f^{(1)}$$

$$y''' = \frac{\partial f^{(1)}}{\partial x} + \frac{\partial f^{(1)}}{\partial y} f \equiv f^{(2)}$$
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SM with Matlab

```
k = c(1,2) + subs(f,[x,y],[c(1,1),c(1,2)])*h;
           q = c(1,2) - subs(f,[x,y],[c(1,1),c(1,2)])*h;
           for i = 2:n
           if i==2
           c(i,1) = c(i-1,1) + h;
           w = c(i-1,1) - h;
           k1 = subs(f,[x,y],[w,q]);
           k2 = subs(f,[x,y],[c(i-1,1),c(i-1,2)]);
           k3 = subs(f,[x,y],[c(i,1),k]);
           c(i,2) = q + h*(k1+4*k2+k3)/3;
           else
           kk = c(i-1,2) + subs(f,[x,y],[c(i-1,1),c(i-1,2)])*h;
           c(i,1) = c(i-1,1) + h;
           kk1 = subs(f,[x,y],[c(i-2,1),c(i-2,2)]);
           kk2 = subs(f,[x,y],[c(i-1,1),c(i-1,2)]);
           kk3 = subs(f,[x,y],[c(i,1),kk]);
           c(i,2) = c(i-2,2) + h*(kk1+4*kk2+kk3)/3;
Figure:
```

TSM with Matlab

```
c(i) = \operatorname{diff}(c(i\text{-}1),x) + \operatorname{diff}(c(i\text{-}1),y) * c(1);
               end
               subsc = subs(c,[x,y],[x0,y0]);
               taylor = y0;
               for i = 1:n
               taylor = taylor + (subsc(i)*(x-x0) \land i) / factorial(i);
              end
Figure:
```



Comparison of Methods

$$\begin{cases} y'(x) = 2y \\ y(0) = 1 \end{cases}$$

Black:REM; Blue:Solution; Red:SM;Yellow:EM

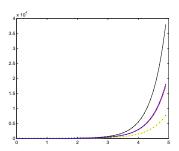


Figure:



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Primary Ideas

Fact

Appropriate Changes of Step Length Helps Accuracy; Areas Change Fast Deserved Small Steps, and vice versa

Corollary

Steps Are Anti-related with $\left|\frac{dy}{dx}\right| = |f(x,y)|$;

Fact

Steps could not be 0 or much huge;



Primary Ideas

Theorem

(Primary ZWL Method)
$$h_k = \frac{A}{|f(x_k, y_k)| + B} + C$$
, A B C are Parameters

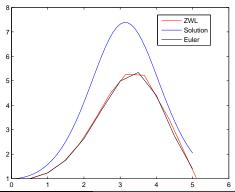
Fact

Primary ZWL Method Compare to Euler Method



Primary Ideas

$$\begin{cases} y'(x) = y \sin x \\ y(0) = 1 \end{cases}$$





Why?

•
$$\left(\frac{A}{|f(x_k,y_k)|+B}+C\right)f(x_k,y_k)\approx \left(\frac{A}{|f(x_k,y_k)|}\right)f(x_k,y_k)=A$$

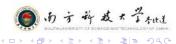
- Fixed Steps of y but not x;
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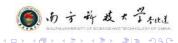
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Improved ZWL Method

Fact

Steps Length Rely on Curvature

Curvature Formula

$$\rho = \frac{|y''|}{\sqrt{1 + y'^2}^3}$$

Corollary

Steps Are Anti-related with Curvature

Theorem

$$h_k = \frac{A}{\frac{|y''(x_k)|}{f(x_k,y_k)^3} + B} + C$$
 where A B C are parameters.

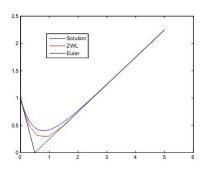
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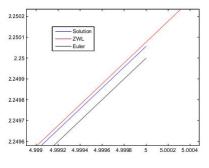


Comparison of ZWL Method and EM

$$\begin{cases} y'(x) = x - 2y \\ y(0) = 1 \end{cases}$$

Figure:









Convergence of ZWL Method

Proof.

Since we have

$$y_{k+1} = y_k + h_k f(x_k, y_k) = y_k + \left(\frac{A}{\frac{|y''(x_k)|}{f(x_k, y_k)^3} + B} + C\right) f(x_k, y_k)$$

For A B C are positive number, If we have $\frac{A}{B} + C < 1$, then

$$|y_{k+1}-y_k| \le L^k |y_1-y_0|$$

where, $0 < L \le 1$. Hence,

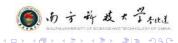
$$\lim_{k\to\infty}|y_{k+1}-y_k|=0$$

i.e. ZWL Method is Convergent.



Division of Work

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 Participate to discover the primary ZWL methods; Give Matlab codes of question b);
- Tao Luo: Give Matlab codes for Primary ZWL method and Taylor Series Method; Participate to discover the primary ZWL methods; Give the Matlab codes of question a)&c);
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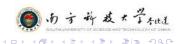
Codes List

- a.m
- airy.m
- b.m
- eular method.m
- eular PriZWL.m
- Simposonsrule.m
- ZWL.m



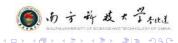
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For Further Reading Matlab codes for Ariy Equation

```
svms x v x0 v0 v1;
f = v^*x : n = 5 :
x0 = 4; %initial condition
y0 = 1;%initial condition
y1 = 2; %initial condition
c = f:
for i = 2:5
c(i) = diff(c(i-1),x) + diff(c(i-1),y)*c(1);
end
subs-c = subs(c,[x,y],[x0,y0]);
taylor = y0 + y1*(x-x0);
for i= 1:n
taylor = taylor + (subs-c(i)*(x-x0)\wedge(i+1))/factorial(i);
end
```

Figure: taylor

