### GROUP THEORY AND REPRESENTATION

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### 1. Group Theory

**Definition 1** (Group). A group is a set plus an operation, that map an ordered pair of group element (g, h) of G into another element  $g \cdot h \in G$ , satisfying the following properties:

- (1) operation is associative:  $g \cdot (h \cdot k) = (g \cdot h) \cdot k$  for  $g, h, k \in G$ ;
- (2) G contain an identity element e, that satisfies  $g \cdot e = e \cdot g = g$  for all  $g \in G$  and
- (3) Each element of G has an inverse, denoted by  $g^{-1}$ .

**Definition 2** (Order of the group). Order of the group G, or the cardinality of the group, is the number of elements in the set G, denoted by |G|

**Definition 3** (Abelian group). A group is called abelian if for all  $g, h \in G$ ,  $g \cdot h = h \cdot g$  (commutative)

Permutation group. We denote a set by X. All the bijections of X to itself form a group, which we denote  $\operatorname{Sym}(X)$ . If |X| = n, then  $|\operatorname{Sym}(X)| = n!$ . If |X| = |Y|, then  $\operatorname{Sym}(X) = \operatorname{Sym}(Y)$  and we denote it as  $\operatorname{Sym}(n)$  or  $S_n$  For example,  $S_3 = \{e, (1, 2), (2, 3), (1, 3), (1, 2, 3), (3, 2, 1)\}$ . We have  $|S_3| = 6$ . The permutation (3, 2, 1) means  $3 \to 2, 2 \to 1, 1 \to 3$  with 1, 2, 3 indicate the position in the set.

Linear transformation group. Denoting V as a vector space, we write GL(V) as the group of all linear transformation in V

**Definition 4** (Subgroup). Definition: H is a non empty subset of G and H is a group, then H is a subgroup of G

**Theorem 1.** The intersections of subgroups of G is also a subgroup of G.

*Proof.* Suppose H and L are subgroups of G. M is the intersections between H and L, then:

- (1) identity  $e \in M$ ;
- (2) if  $h_1, h_2 \in H$  and  $h_1 \cdot h_2 = e$ , If  $h_1 \in L$ , then inevitably  $h_2 \in L$ , therefore the intersections of H and L is closed under inverse;
- (3) similarly, if  $h_1, h_2 \in H$  and  $h_1, h_2 \in L$ , then  $h_1 \cdot h_2$  belong to both H and L are therefore in the intersections. M is closed under group operation.

**Definition 5** (Generator). For a set S, the intersections of all subgroups contain S is a subgroup. This intersections is denoted by  $\langle S \rangle$  and we say that it is generated by S.

For a group element g, we write that group that is generated by g as  $\langle g \rangle$ , the order of  $\langle g \rangle$  is also called the order of g.

**Theorem 2.** if a group G is finite, we must have  $g^n = e$  for  $g \in G$ . Since any  $g^a$  is a number in G

**Definition 6** (Cyclic group). If a group is generated by a single element, i.e.  $G = \langle g \rangle$  for  $g \in G$ 

**Definition 7.** A group is called normal (self-conjugate) if

$$gBg^{-1} = B \text{ for } g \in G \qquad (group \text{ automorphism})$$

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**Theorem 3** (Rearrangement theorem). for group G and a group element  $g' \in G$ , the set

$$\{g'g \mid g \in G\}$$

contain each group element once and only once.

*Proof.* It is equivalent to say that if  $g_1 \neq g_2$ , then  $g'g_1 \neq g'g_2$ . all group element in G are mapped to another distinct elements in G (rearrangement).

If 
$$g'g_1 = g'g_2$$
 but  $g_1 \neq g_2$ , then

$$g'^{-1}g'g_1 = g'^{-1}g'g_2$$

which appearnt conflict with the assumption

Multiplication. For S and T, both subset of group G, we define their produce:

$$ST = \{ st \mid s \in S, t \in T \}$$

and  $sT \equiv \{s\}T$  and  $Ts \equiv T\{s\}$  for  $s \in S$ .

**Definition 8** (Left cosets). For H a subgroup of G and  $g \in G$ , gH is called a left coset. Hg is called a right coset. The set  $\{gH \mid g \in G, H \text{ is subgroup of } G\}$  is written as  $G \setminus H$ 

For example, for  $S_3 = \{e, (12), (23), (13), (123), (132)\}$  and  $H = \{e, (123), (132)\}$ , We can work out the following relationship:

$$(123)(123) = (132) (132)(123) = e$$

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i.e., H is a subset of  $S_4$ . Applying element  $g \in \{(12), (23), (13)\}$  on H give the set  $\{(12), (23), (13)\}$ . Therefore, the left cosets of H is:

$$\{ \{e, (123), (132)\}, \{(12), (23), (13)\} \}$$

**Theorem 4.** The left cosets of the subgroup H of G partition G

*Proof.* This is equivalent to say that gH is either H itself, or share no comment elements with H. if  $g \in H$ , then gH = H. On the other hand, if  $g \notin H$  but  $gh \in H$  for an element  $h \in H$ , then, by the requirement of group  $h^{-1} \in H$ .  $ghh^{-1} = g \in H$  which conflict with the assumption. Therefore, we gH cannot share element with H: |gH| = |H|, so that left cosets of a subgroup partition the group.

As a result, the whole group can be written as:

$$G = H + g_1 H + g_2 H + \dots + g_n H$$

**Theorem 5** (Lagrange's theorem). For a finite group G and H is a subgroup of G, |H| can divide G.

**Definition 9** (Index of H in G). The number of left cosets of a subgroup H is called the index of H in G, denoted as [G:H].

If G is a finite group and  $g \in G$ . Then the order of  $\langle g \rangle$  divide |G|. This is because  $\langle g \rangle$  is a subgroup of G.

## 2. Representation Theory

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# 3. Crystal Structure

### Appendix A