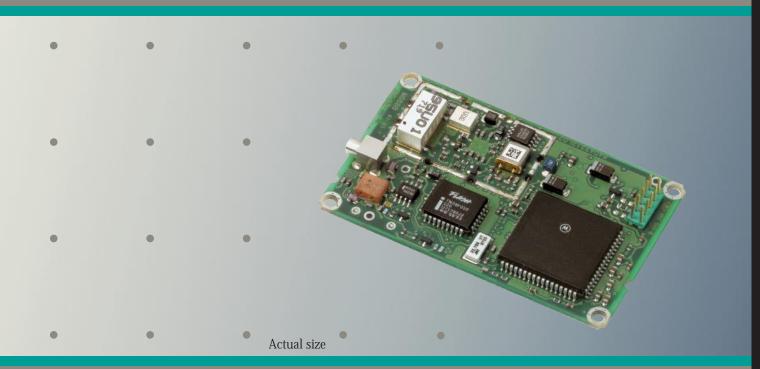


# **UT Plus Oncore**<sup>™</sup> **GPS Receiver**



There's only one name for quality and performance in GPS technology: Oncore. The Oncore family is a full line of GPS receivers developed and built by Motorola for the OEM and Systems Integrator marketplace.

The UT Plus Oncore is one of the newest members of the successful Oncore family, developed specifically for timing applications. The UT Plus Oncore adds more features at a lower cost, and is available in unlimited quantities. Continuing with the 8-channel design of the Oncore family, the UT Plus Oncore reflects Motorola's high standard for performance in timing and frequency stabilization. The UT Plus Oncore makes use of Motorola's Time RAIM (time receiver autonomous integrity monitoring) algorithm to ensure the validity and reliability of the GPS measurements. In addition, the UT Plus Oncore has industry leading immunity to unintentional jamming signals, an automatic site survey feature for greater convenience, and 100PPS output capability for rapid disciplining.

Measuring 2"  $\times$  3 1/4"  $\times$  1/2", the UT Plus Oncore is mechanically and electrically backwards compatible with the VP Oncore. To minimize software changes the I/O is a subset of the existing Oncore messages. The UT Plus Oncore also has very low power requirements and is well suited for embedding applications.

The Oncore family of GPS receivers incorporate Motorola GPS custom ICs (integrated circuits), Motorola MPUs (microprocessor units), and Motorola GPS receiver software. Add QS-9000 certification, reliability, responsive support and the long-term commitment you've come to expect from Motorola, and you understand why Oncore is the quality choice.





# **UT Plus Oncore**<sup>™</sup>

### General Characteristics

# **Performance Characteristics**

# **GPS Receiver**

	Receiver Architecture	<ul> <li>8 parallel channel</li> <li>L1 1575.42 MHz</li> <li>C/A code (1.023 MHz chip rate)</li> <li>Code plus carrier tracking (carrier aided tracking)</li> </ul>
	Tracking Capability	8 simultaneous satellite vehicles
	Dynamics	<ul> <li>Velocity: 1000 knots (515 m/s); &gt; 1000 knots at altitudes &lt; 60,000 ft</li> <li>Acceleration: 4 g</li> <li>Jerk: 5 m/s³</li> <li>Vibration: 7.7G per Military Standard 810E</li> </ul>
	Acquisition Time (Time To First Fix, TTFF) (Tested at -30 to +85°C)	<ul> <li>&lt; 20 s typical TTFF-hot (with current almanac, position, time and ephemeris)</li> <li>&lt; 50 s typical TTFF-warm (with current almanac, position and time)</li> <li>&lt; 300 s typical TTFF-cold</li> <li>&lt; 1.0 s internal reacquisition (typical)</li> </ul>
	Positioning Accuracy	• 100 m 2dRMS with SA as per DoD specification • Less than 25 m SEP without SA
	Timing Accuracy (1 Pulse Per Second, 1 PPS)	<ul> <li>Time RAIM algorithm</li> <li>&lt; 130 ns (1 sigma) with SA on</li> <li>In position hold mode, &lt; 50 ns (1 sigma) with SA on</li> </ul>
	Jamming Immunity	<ul> <li>Immune to the following CW jamming signal levels measured at the input to the Oncore Active Antenna when the receiver is in position-hold mode. Values are typical.</li> <li>-50 dBm @ 1570 MHz</li> <li>-79 dBm @ 1575.42 MHz</li> <li>-56 dBm @ 1580 MHz</li> </ul>
	Antenna	<ul> <li>Active micro strip patch antenna module</li> <li>Powered by receiver module (5-80 mA @ 5 Vdc)</li> </ul>
Г	Datum	• WGS-84
	Output Messages	<ul> <li>Latitude, longitude, height, velocity, heading, time (Motorola binary protocol)</li> <li>Software selectable output rate (continuous or poll)</li> <li>TTL interface (0 to 5 V)</li> </ul>
	Power Requirements	• 5 ± 0.25 Vdc; 50 mVp-p ripple (max.)
Ĺ	"Keep-Alive" BATT Power	• External 2.5 Vdc to 5.25 Vdc; 5 μA (typ.) @ 2.5 Vdc

## Serial **Communication**

## **Electrical Characteristics**

# **Physical** Characteristics

### **Environmental Characteristics**

### Miscellaneous

For more information contact your local distributor:

	-50 dBm @ 1570 MHz -79 dBm @ 1575.42 MHz -56 dBm @ 1580 MHz
Antenna	Active micro strip patch antenna module     Powered by receiver module (5-80 mA @ 5 Vdc)
Datum	• WGS-84
Output Messages	<ul> <li>Latitude, longitude, height, velocity, heading, time (Motorola binary protocol)</li> <li>Software selectable output rate (continuous or poll)</li> <li>TTL interface (0 to 5 V)</li> </ul>
Power Requirements	• $5 \pm 0.25$ Vdc; $50$ mVp-p ripple (max.)
"Keep-Alive" BATT Power	• External 2.5 Vdc to 5.25 Vdc; 5 μA (typ.) @ 2.5 Vdc
Power Consumption	• < 0.9 W @ 5 Vdc with active antenna drawing 20 mA
Dimensions	• 2.00 x 3.25 x 0.64 in. [50.8 x 82.6 x 16.3 mm]
Weight	• 1.8 oz. (51 g)
Connectors	Data/power: 10 pin (2x5) unshrouded header on 0.100 in. centers     RF: right angle OSX (subminiature snap-on)
Antenna to Receiver Interconnection	Single coaxial cable     Antenna sense circuit
Operating Temperature	• -40°C to +85°C
Humidity	• 95% noncondensing +30°C to +60°C
Altitude	• 60,000 ft. (18 km) (max.) • > 60,000 ft. (18 km) for velocities < 1000 knots
Standard Features	Time RAIM 100PPS output Automatic site survey Jamming protection
Optional Features	Lithium battery     Straight OSX RF connector



### **MOTOROLA**

4000 Commercial Avenue Northbrook, IL 60062 USA

In Europe call: In Asia call: 888.298.5217 +44.1628.763.260 +852.2966.4136 847.714.7325 fax +44.1628.637.059 fax +852.2966.4141 fax

Motorola is an Equal Employment Opportunity/Affirmative Action Employer. Motorola and A are registered trademarks of Motorola, Inc. O Copyright 1998 Motorola, Inc. 9.1.98