HW1
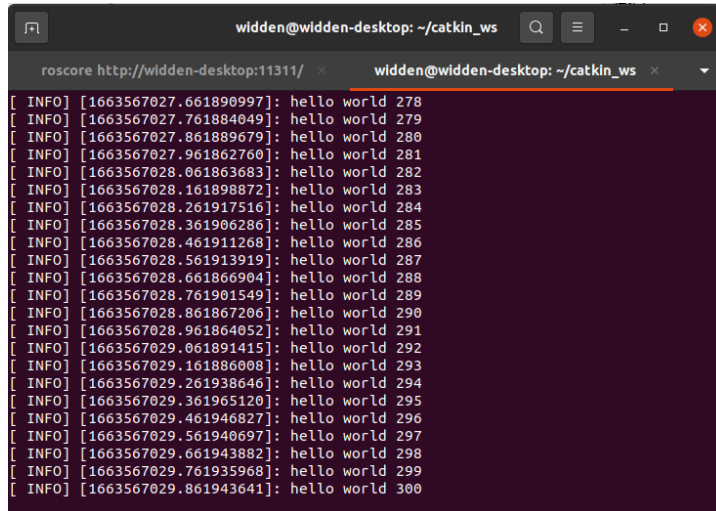
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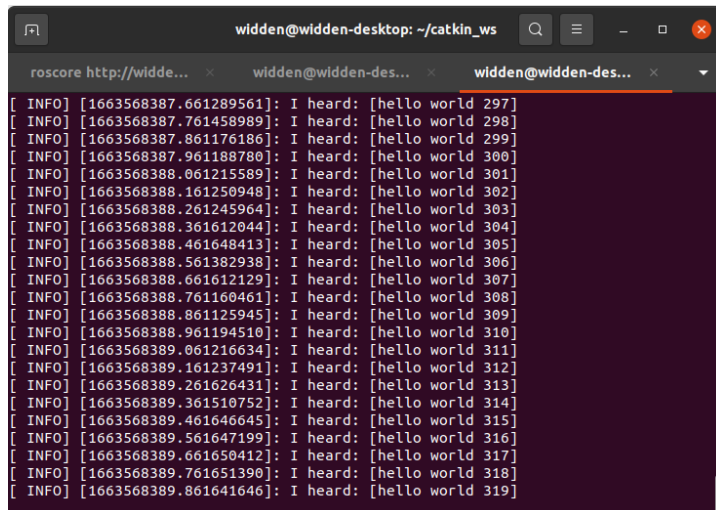
Part 1.ROS (I only use ROS)

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