IF2230 Deadlocks

Deadlocks

- The Deadlock Problem
- System Model
- Deadlock Characterization
- Methods for Handling Deadlocks
- Deadlock Prevention
- Deadlock Avoidance
- Deadlock Detection
- Recovery from Deadlock



Chapter Objectives

- To develop a description of deadlocks, which prevent sets of concurrent processes from completing their tasks
- To present a number of different methods for preventing or avoiding deadlocks in a computer system.



The Deadlock Problem

A set of blocked processes each holding a resource and waiting to acquire a resource held by another process in the set.

Example

- System has 2 tape drives.
- P_1 and P_2 each hold one tape drive and each needs another one.

Example

semaphores A and B, initialized to I

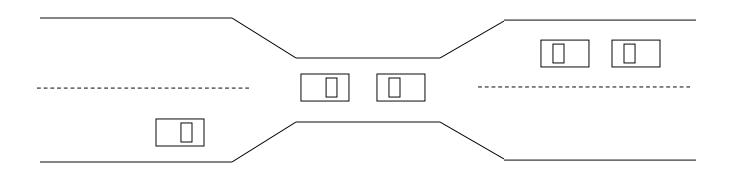
```
      P<sub>0</sub>
      P<sub>1</sub>

      wait (A);
      wait(B)

      wait (B);
      wait(A)
```



Bridge Crossing Example



- ▶ Traffic only in one direction.
- ▶ Each section of a bridge can be viewed as a resource.
- If a deadlock occurs, it can be resolved if one car backs up (preempt resources and rollback).
- Several cars may have to be backed up if a deadlock occurs.
- Starvation is possible.



System Model

- Resource types $R_1, R_2, ..., R_m$ CPU cycles, memory space, I/O devices
- \blacktriangleright Each resource type R_i has W_i instances.
- ▶ Each process utilizes a resource as follows:
 - request
 - use
 - release



Deadlock Characterization

Deadlock can arise if four conditions hold simultaneously.

- Mutual exclusion: only one process at a time can use a resource.
- ▶ Hold and wait: a process holding at least one resource is waiting to acquire additional resources held by other processes.
- No preemption: a resource can be released only voluntarily by the process holding it, after that process has completed its task.
- Circular wait: there exists a set $\{P_0, P_1, ..., P_0\}$ of waiting processes such that P_0 is waiting for a resource that is held by P_1, P_1 is waiting for a resource that is held by
 - P_1, \ldots, P_{p-1} is waiting for a resource that is held by P_n , and P_0 is waiting for a resource that is held by P_0 .



Resource-Allocation Graph

A set of vertices *V* and a set of edges *E*.

- V is partitioned into two types:
 - $P = \{P_1, P_2, ..., P_n\}$, the set consisting of all the processes in the system.
 - $R = \{R_1, R_2, ..., R_m\}$, the set consisting of all resource types in the system.
- ▶ request edge directed edge $P_1 \rightarrow R_i$
- ▶ assignment edge directed edge $R_j \rightarrow P_i$



Resource-Allocation Graph (Cont.)

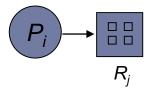
Process



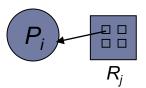
Resource Type with 4 instances



 \triangleright P_i requests instance of R_i

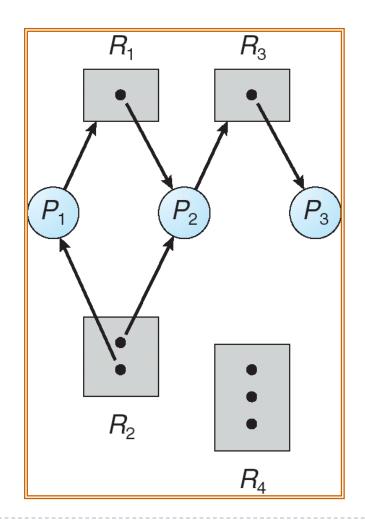


 \triangleright P_i is holding an instance of R_i



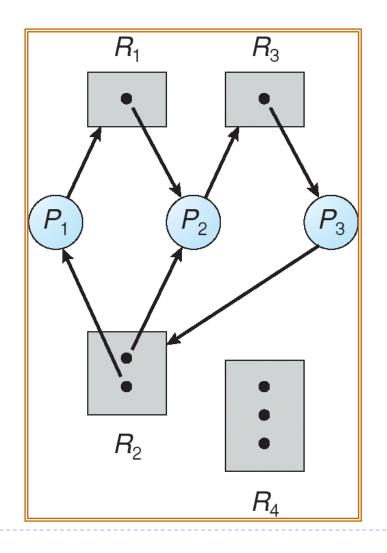


Example of a Resource Allocation Graph



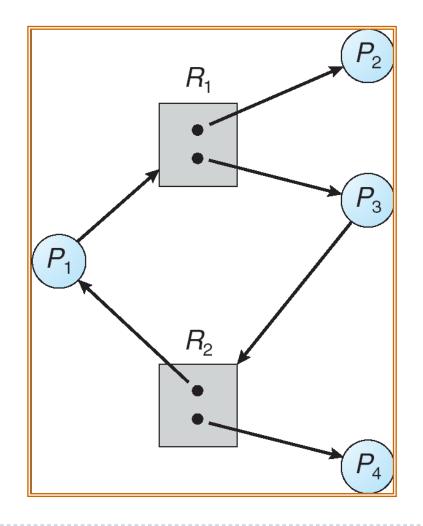


Resource Allocation Graph With A Deadlock





Resource Allocation Graph With A Cycle But No Deadlock





Basic Facts

- ▶ If graph contains no cycles \Rightarrow no deadlock.
- ▶ If graph contains a cycle \Rightarrow
 - if only one instance per resource type, then deadlock.
 - if several instances per resource type, possibility of deadlock.



Methods for Handling Deadlocks

- Ensure that the system will *never* enter a deadlock state.
- Allow the system to enter a deadlock state and then recover.
- Ignore the problem and pretend that deadlocks never occur in the system; used by most operating systems, including UNIX.



Deadlock Prevention

Restrain the ways request can be made.

- ▶ Mutual Exclusion not required for sharable resources; must hold for nonsharable resources.
- ▶ Hold and Wait must guarantee that whenever a process requests a resource, it does not hold any other resources.
 - Require process to request and be allocated all its resources before it begins execution, or allow process to request resources only when the process has none.
 - Low resource utilization; starvation possible.



Deadlock Prevention (Cont.)

No Preemption –

- If a process that is holding some resources requests another resource that cannot be immediately allocated to it, then all resources currently being held are released.
- Preempted resources are added to the list of resources for which the process is waiting.
- Process will be restarted only when it can regain its old resources, as well as the new ones that it is requesting.
- Circular Wait impose a total ordering of all resource types, and require that each process requests resources in an increasing order of enumeration.



Deadlock Avoidance

Requires that the system has some additional *a priori* information available.

- Simplest and most useful model requires that each process declare the maximum number of resources of each type that it may need.
- The deadlock-avoidance algorithm dynamically examines the resource-allocation state to ensure that there can never be a circular-wait condition.
- Resource-allocation state is defined by the number of available and allocated resources, and the maximum demands of the processes.



Safe State

- When a process requests an available resource, system must decide if immediate allocation leaves the system in a safe state.
- System is in safe state if there exists a safe sequence of all processes.
- Sequence $\{P_1, P_2, ..., P_n\}$ is safe if for each P_i , the resources that P_i can still request can be satisfied by currently available resources + resources held by all the P_i , with j < l.
 - If P_i resource needs are not immediately available, then P_i can wait until all P_i have finished.
 - When P_i is finished, P_i can obtain needed resources, execute, return allocated resources, and terminate.
 - When P_i terminates, P_{i+1} can obtain its needed resources, and so on.

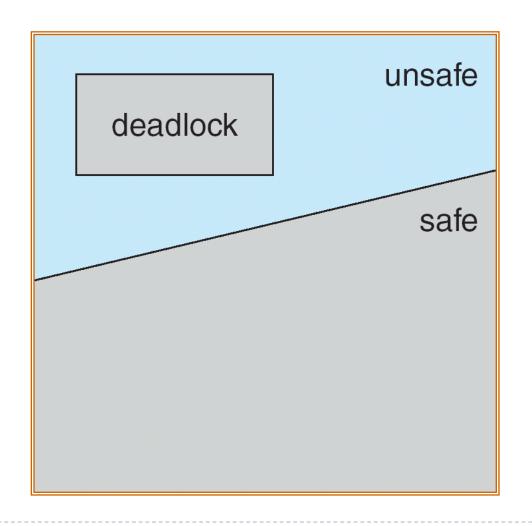


Basic Facts

- If a system is in safe state \Rightarrow no deadlocks.
- If a system is in unsafe state ⇒ possibility of deadlock.
- Avoidance ⇒ ensure that a system will never enter an unsafe state.



Safe, Unsafe, Deadlock State



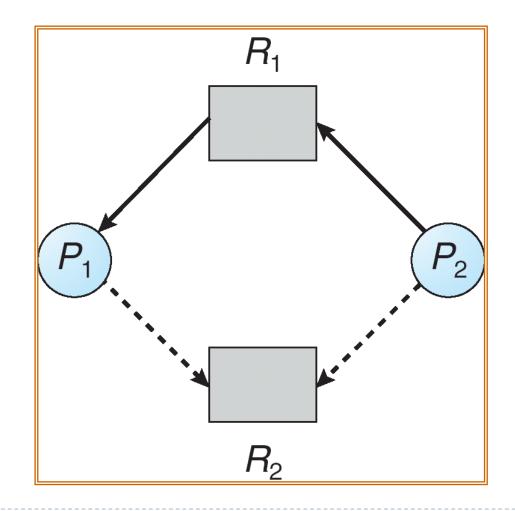


Resource-Allocation Graph Algorithm

- ▶ Claim edge $P_i \rightarrow R_j$ indicated that process P_j may request resource R_j ; represented by a dashed line.
- Claim edge converts to request edge when a process requests a resource.
- When a resource is released by a process, assignment edge reconverts to a claim edge.
- ▶ Resources must be claimed *a priori* in the system.



Resource-Allocation Graph For Deadlock Avoidance





Unsafe State In Resource-Allocation Graph



Banker's Algorithm

- Multiple instances.
- Each process must a priori claim maximum use.
- When a process requests a resource it may have to wait.
- When a process gets all its resources it must return them in a finite amount of time.



Data Structures for the Banker's Algorithm

Let n = number of processes, and m = number of resources types.

- Available: Vector of length m. If available [j] = k, there are k instances of resource type R_i available.
- Max: $n \times m$ matrix. If Max[i,j] = k, then process P_i may request at most k instances of resource type R_i .
- ▶ Allocation: $n \times m$ matrix. If Allocation[i,j] = k then P_i is currently allocated k instances of $R_{j.}$
- Need: $n \times m$ matrix. If Need[i,j] = k, then P_i may need k more instances of R_j to complete its task.

Need [i,j] = Max[i,j] - Allocation [i,j].



Safety Algorithm

I. Let Work and Finish be vectors of length m and n, respectively. Initialize:

```
Work = Available
Finish [i] = false for i - 1,3,...,n.
```

- 2. Find and *i* such that both:
 - (a) Finish [i] = false
 - (b) $Need_i \leq Work$

If no such *i* exists, go to step 4.

- 3. Work = Work + Allocation; Finish[i] = true go to step 2.
- 4. If Finish [i] == true for all i, then the system is in a safe state.



Resource-Request Algorithm for Process P_i

Request = request vector for process P_i . If Request_i [j] = k then process P_i wants k instances of resource type R_i .

- I. If $Request_i \leq Need_i$ go to step 2. Otherwise, raise error condition, since process has exceeded its maximum claim.
- 2. If $Request_i \leq Available$, go to step 3. Otherwise P_i must wait, since resources are not available.
- 3. Pretend to allocate requested resources to P_i by modifying the state as follows:

```
Available = Available - Request;;
Allocation; = Allocation; + Request;;
Need; = Need; - Request;;
```

- If safe \Rightarrow the resources are allocated to Pi.
- If unsafe ⇒ Pi must wait, and the old resource-allocation state is restored



Example of Banker's Algorithm

- ▶ 5 processes P_0 through P_4 ; 3 resource types A (10 instances), B (5 instances), and C (7 instances).
- \blacktriangleright Snapshot at time T_0 :

	<u>Allocation</u>	<u>Max</u>	<u>Available</u>
	ABC	ABC	ABC
P_0	010	753	3 3 2
P_{I}	200	3 2 2	
P_2	3 0 2	902	
P_3	2	2 2 2	
P_4	002	4 3 3	



Example (Cont.)

The content of the matrix. Need is defined to be Max
 Allocation.

The system is in a safe state since the sequence $< P_1, P_3, P_4, P_2, P_0>$ satisfies safety criteria.



Example P_1 Request (1,0,2) (Cont.)

► Check that Request \leq Available (that is, $(1,0,2) \leq (3,3,2)$ \Rightarrow true.

	<u>Allocation</u>	<u>Need</u>	<u>Available</u>
	ABC	ABC	ABC
P_0	010	7 4 3	230
P_{I}	302	020	
P_2	3 O I	600	
P_3	2	0 1 1	
P_4	002	4 3 I	

- Executing safety algorithm shows that sequence <PI, P3, P4, P0, P2> satisfies safety requirement.
- ▶ Can request for (3,3,0) by P4 be granted?
- ▶ Can request for (0,2,0) by P0 be granted?



Deadlock Detection

- Allow system to enter deadlock state
- Detection algorithm
- Recovery scheme

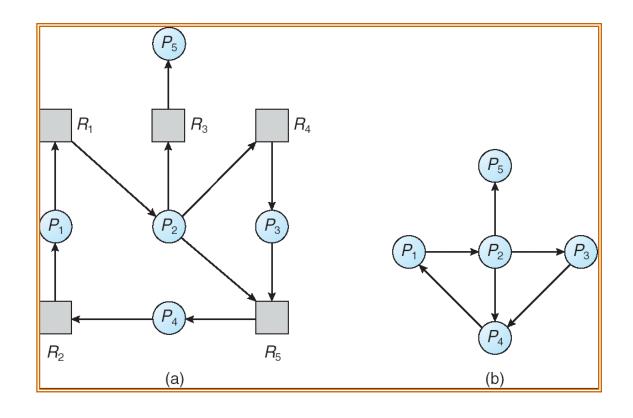


Single Instance of Each Resource Type

- Maintain wait-for graph
 - Nodes are processes.
 - ▶ $P_i \rightarrow P_j$ if P_i is waiting for P_j .
- Periodically invoke an algorithm that searches for a cycle in the graph.
- An algorithm to detect a cycle in a graph requires an order of n^2 operations, where n is the number of vertices in the graph.



Resource-Allocation Graph and Wait-for Graph



Resource-Allocation Graph Corresponding wait-for graph



Several Instances of a Resource Type

- Available: A vector of length m indicates the number of available resources of each type.
- Allocation: An n x m matrix defines the number of resources of each type currently allocated to each process.
- ▶ Request: An $n \times m$ matrix indicates the current request of each process. If Request $[i_j] = k$, then process P_i is requesting k more instances of resource type. R_j .



Detection Algorithm

- 1. Let Work and Finish be vectors of length m and n, respectively Initialize:
 - (a) Work = Available
 - (b) For i = 1, 2, ..., n, if $Allocation_i \neq 0$, then Finish[i] = false; otherwise, <math>Finish[i] = true.
- 2. Find an index i such that both:
 - (a) Finish[i] == false
 - (b) $Request_i \leq Work$

If no such i exists, go to step 4.



Detection Algorithm (Cont.)

- 3. Work = Work + Allocation; Finish[i] = true go to step 2.
- 4. If Finish[i] == false, for some i, $1 \le i \le n$, then the system is in deadlock state. Moreover, if Finish[i] == false, then P_i is deadlocked.

Algorithm requires an order of $O(m \times n^2)$ operations to detect whether the system is in deadlocked state.



Example of Detection Algorithm

- Five processes P_0 through P_4 ; three resource types A (7 instances), B (2 instances), and C (6 instances).
- \triangleright Snapshot at time T_0 :

	<u>Allocation</u>	Request	<u>Available</u>
	ABC	ABC	ABC
P_0	010	000	000
P_{I}	200	202	
P_2	3 0 3	000	
P_3	2	100	
P_4	002	002	

▶ Sequence $\langle P_0, P_2, P_3, P_1, P_4 \rangle$ will result in Finish[i] = true for all i.



Example (Cont.)

 \triangleright P_2 requests an additional instance of type C.

```
Request
A B C
P<sub>0</sub> 0 0 0
P<sub>1</sub> 2 0 1
P<sub>2</sub> 0 0 1
P<sub>3</sub> 1 0 0
P<sub>4</sub> 0 0 2
```

- State of system?
 - \triangleright Can reclaim resources held by process P_0 , but insufficient resources to fulfill other processes; requests.
 - ▶ Deadlock exists, consisting of processes P_1 , P_2 , P_3 , and P_4 .



Detection-Algorithm Usage

- When, and how often, to invoke depends on:
 - How often a deadlock is likely to occur?
 - How many processes will need to be rolled back?
 - one for each disjoint cycle
- If detection algorithm is invoked arbitrarily, there may be many cycles in the resource graph and so we would not be able to tell which of the many deadlocked processes "caused" the deadlock.



Recovery from Deadlock: Process Termination

- Abort all deadlocked processes.
- Abort one process at a time until the deadlock cycle is eliminated.
- In which order should we choose to abort?
 - Priority of the process.
 - How long process has computed, and how much longer to completion.
 - Resources the process has used.
 - Resources process needs to complete.
 - How many processes will need to be terminated.
 - Is process interactive or batch?



Recovery from Deadlock: Resource Preemption

- Selecting a victim minimize cost.
- ▶ Rollback return to some safe state, restart process for that state.
- Starvation same process may always be picked as victim, include number of rollback in cost factor.



End of Chapter 7