Knowledge Representation and Reasoning

Introduction to Probabilistic Reasoning System

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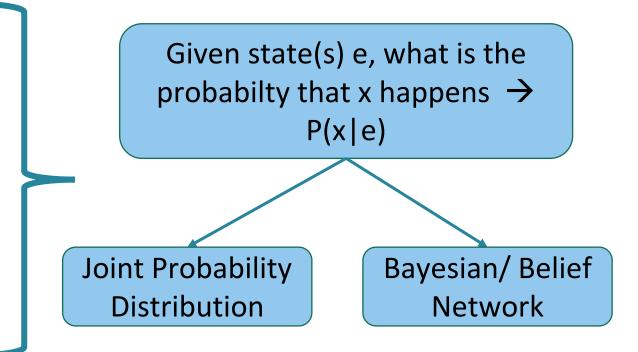
Inteligensi Artifisial (Artificial Intelligence)

Probabilistic Reasoning System (PRS)

Agent in real world need to handle uncertainty

Logical Agents handle uncertainty by disjunction \rightarrow cannot tell us how likely the difference conditions are

Probability theory provides a quantitative way of encoding likelihood



Joint Probability Distribution

Random variables

- Function: discrete domain \rightarrow [0, 1]
- Sums to 1 over the domain
 - Raining is a propositional random variable
 - Raining(true) = 0.2
 - P(Raining = true) = 0.2
 - Raining(false) = 0.8
 - P(Raining = false) = 0.8

Joint distribution

Probability assignment to all combinations of values of random variables

Inference using Joint Probability Distribution

	toothache		¬ toothache	
	catch	¬ catch	catch	¬ catch
cavity	.108	.012	.072	.008
¬ cavity	.016	.064	.144	.576

- For any proposition ϕ , sum the atomic events where it is true: $P(\phi) = \sum_{\omega:\omega \neq \phi} P(\omega)$
- P(toothache) = 0.108 + 0.012 + 0.016 + 0.064 = 0.2
- P(cavity) = 0.108 + 0.012 + 0.072 + 0.008 = 0.2
- P(cavity U toothache) = ?
- $P(\neg cavity \mid toothache)$ = $P(\neg cavity \cap toothache) / P(toothache)$ = (0.016+0.064) / (0.108 + 0.012 + 0.016 + 0.064)= 0.4

Inference using Joint Probability Distribution

	toothache		¬ toothache	
	catch	¬ catch	catch	¬ catch
cavity	.108	.012	.072	.008
¬ cavity	.016	.064	.144	.576

- If you have n binary propositional variables → requires 2ⁿ numbers to build Joint Probability Distribution
- → Bayesian Network (We want to exploit independences in the domain)

Bayes' Rule:

$$P(A \mid B) = P(A \cap B) / P(B)$$

= $P(B \mid A) P(A) / P(B)$

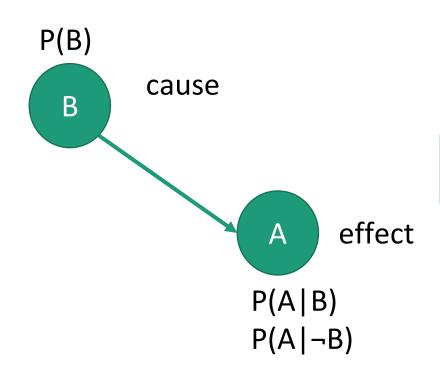
Conditioning:

$$P(A) = P(A \mid B) P(B) + P(A \mid \neg B) P(\neg B)$$
$$= P(A \cap B) + P(A \cap \neg B)$$

Structure of Bayesian Network

Nodes (variable)

Directed arc



Should be **Directed Acyclic Graph (DAG)**

Numerical Parameters

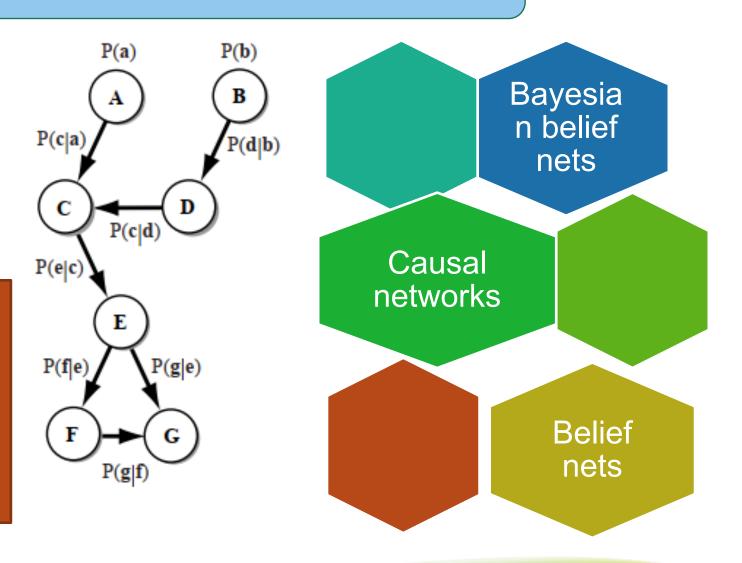
- Prior probability
- Probability conditional tables

Structure of Bayesian Network

Representation of causal dependencies graphically (Hart et al.,2001)

BN have capability probabilistic reasoning like full joint probability distribution. It can answer any question about the domain.

-- How we exploit Independence?



Independence

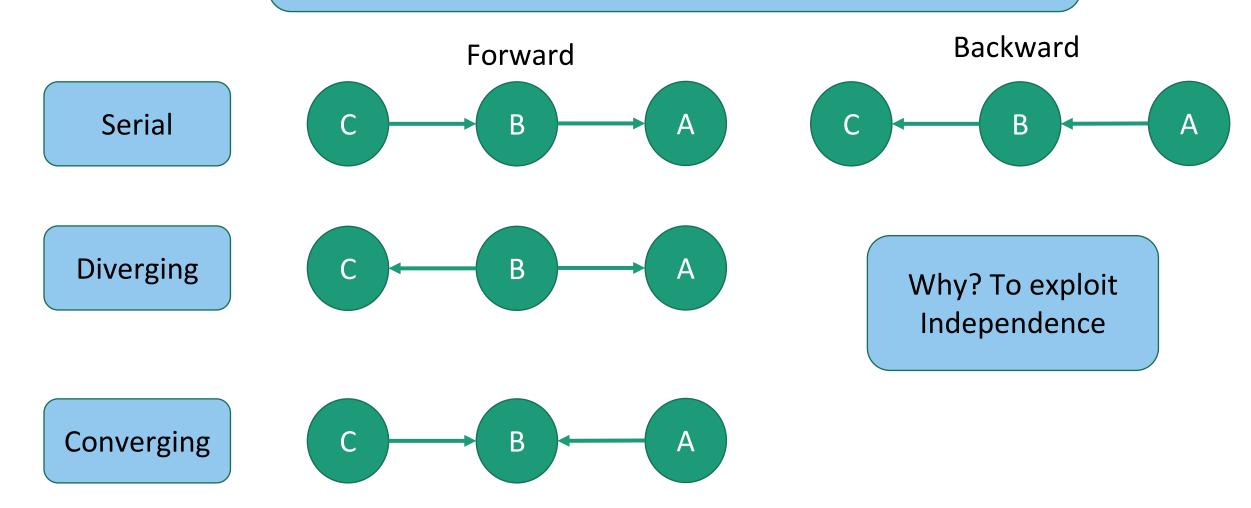
- A and B are independent iff
 - $P(A \cap B) = P(A) \cdot P(B)$
 - P(A | B) = P(A)
 - $P(B \mid A) = P(B)$
- Independence is essential for efficient probabilistic reasoning
- A and B are conditionally independent given C iff
 - P(A | B, C) = P(A | C)
 - P(B | A, C) = P(B | C)
 - $P(A \cap B \mid C) = P(A \mid C) \cdot P(B \mid C)$

Example of Independence

- X is late (X)
- Traffic Jam (T)
- Y is late (Y)
- None of these propositions are independent of one other
- X and Y are conditionally independent given T



Types of Connections in Bayesian Network



Independence in Connection

Serial **Diverging** Converging Knowing C will tell us about A, but if we know B, knowing C will tell us nothing about A (C and A conditionally independent or d-separated)

Knowing C will tell us nothing about A without knowing B, but if we see evidence about B, C and A becomes dependent

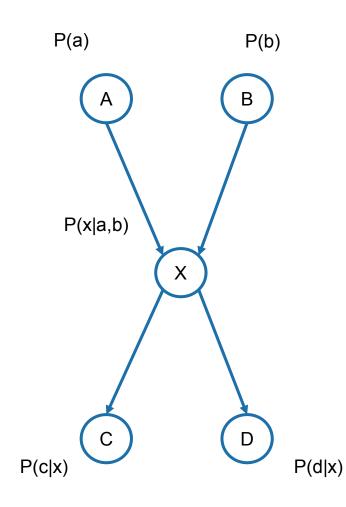
Reduction Number of Probabilities

In a domain with N binary propositional variables (2 possibilities value), one needs 2^N numbers to specify the joint probability distribution. N=5: need 32 probabilities

Independence and conditional independence relationships among variables can greatly reduce the number of probabilities that need to be specified in order to define the full joint distribution (Russel & Norvig, 2013)

For 5 binary variables with causal networks: need 2+2+8+4+4=20 probabilities (or 10 with complements).

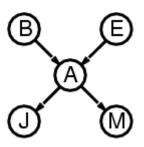
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Bayesian Network as Joint Probability Distribution (chain rule)

The full joint distribution is defined as the product of the local conditional distributions:

$$P(X_1, ..., X_n) = \prod_{i=1}^n P(X_i | Parents(X_i))$$

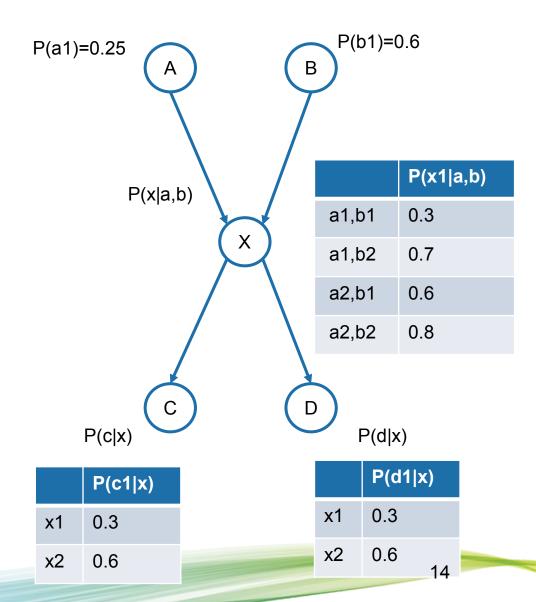


e.g.,
$$P(j \land m \land a \land \neg b \land \neg e)$$

$$= P(j \mid a) P(m \mid a) P(a \mid \neg b, \neg e) P(\neg b) P(\neg e)$$

Example

- We can determine the value of any entry in the joint probability.
- P(a2,b1,x2,c2,d1)
 =P(a2)P(b1)P(x2|a2,b1)P(c2|x2)P(d1|x2)
 =0.75*0.6*0.4*0.4*0.6
 =0.0432



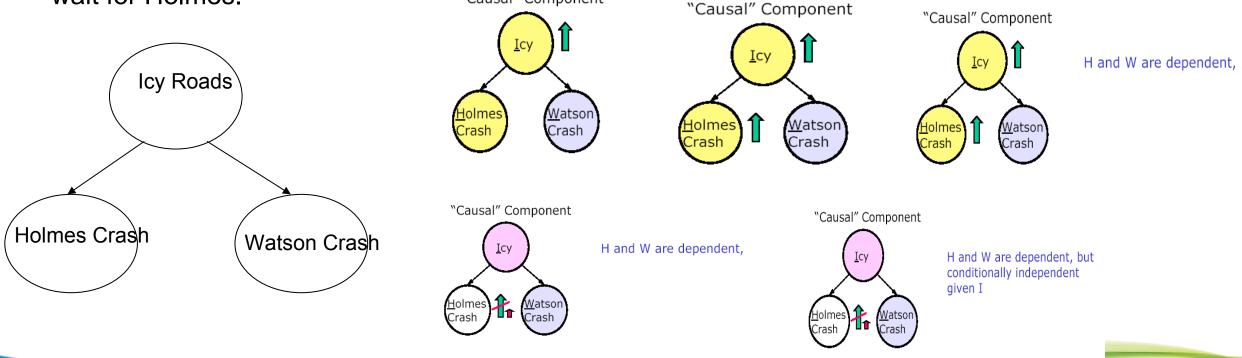
Example of Bayesian Network

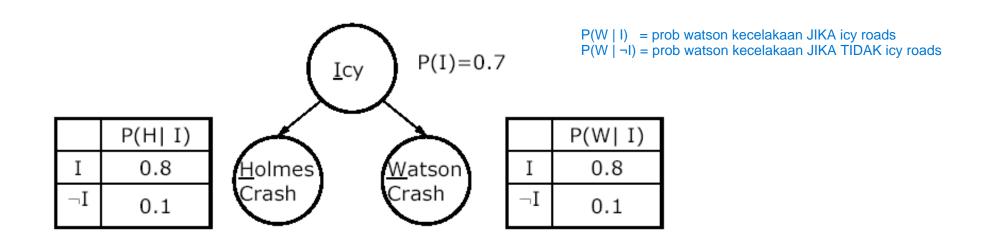
Icy Roads

Inspector Smith is waiting for Holmes and Watson, who are driving (separately) to meet him. It is winter. His secretary tells him that Watson has had an accident. He says, "It must be that the roads are icy. I bet that Holmes will have an accident too. I should go to lunch." But, his secretary says, "No, the roads are not icy, look at the window." So, he says, "I guess I better

"Causal" Component

wait for Holmes."

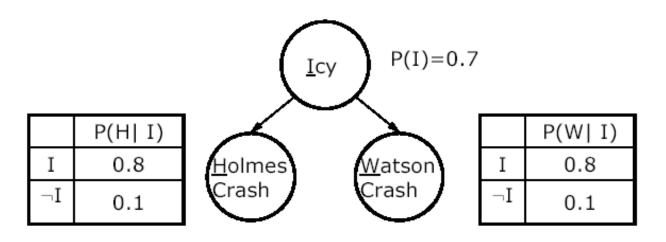




Probability that Watson Crashes:

$$P(W) = P(W|I) P(I) + P(W|\neg I) P(\neg I)$$

= 0.8 · 0.7 + 0.1 · 0.3
= 0.56 + 0.03
= 0.59

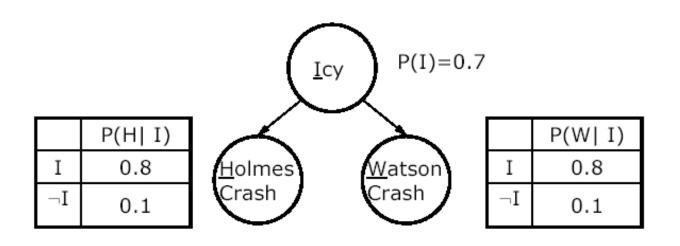


Probability of Icy given Watson (Bayes' Rule):

$$P(I | W) = P(W | I) P(I) / P(W)$$

= 0.8 · 0.7 / 0.59
= 0.95

We started with P(I) = 0.7; knowing that Watson crashed raised the probability to 0.95



Probability of Holmes given Watson:

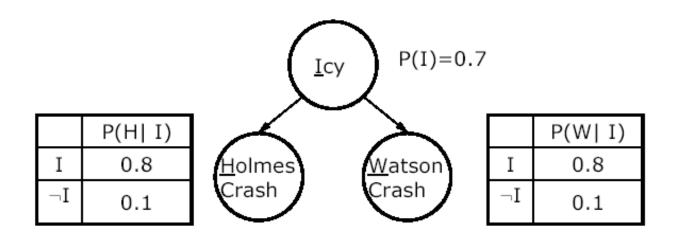
$$P(H|W) = P(H|W,I)P(I|W) + P(H|W,\neg I) P(\neg I|W)$$

$$= P(H|I)P(I|W) + P(H|\neg I) P(\neg I|W)$$

$$= 0.8 \cdot 0.95 + 0.1 \cdot 0.05$$

$$= 0.765$$

We started with P(H) = 0.59; knowing that Watson crashed raised the probability to 0.765



Probability of Holmes given Icy and Watson : $P(H|W, \neg I) = P(H|\neg I) = 0.1$

H and W are d-separated given I, so H and W are conditionally independent given I

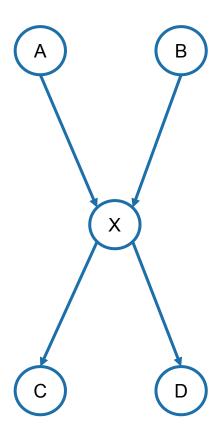
Classification using Bayesian Network

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Inteligensi Artifisial (*Artificial Intelligence*)

- X represents the fish: x1=salmon and x2=sea bass.
- X is influenced by A and B.
- A represents time of year: a1 = winter, a2 = spring, a3 = summer and a4 = autumn. Probability distribution on A in uniform.
- B represents geographical area where the fish was caught: b1 = north Atlantic and b2 = south Atlantic.
 The probabilities that any fish came from those areas are 0.6 and 0.4.
- C represents lightness with c1 = light, c2 = medium and c3 = dark
- D represents thickness with d1 = wide and d2 = thin.



The probability that the fish was caught in the <u>summer</u> in the <u>north Atlantic</u> and is a <u>sea bass</u> that is <u>dark</u> and <u>thin</u>.



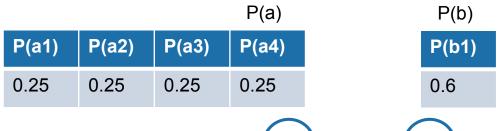
The probability that the fish was caught in the <u>summer</u> (a3) in the <u>north Atlantic</u> (b1) and is a <u>sea bass</u> (x2) that is <u>dark</u> (c3) and <u>thin</u> (d2).

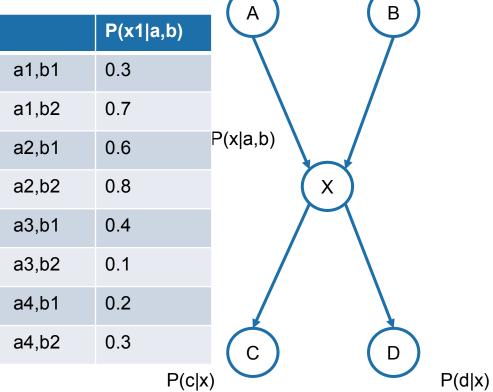


P(a3,b1,x2,c3,d2)

Inference: Example

P(a3,b1,x2,c3,d2) =P(a3)P(b1)P(x2|a3,b1)P(c3|x2)P(d2|x2)=0.012





	P(c1 x)	P(c2 x)	P(c3 x)
x1	0.6	0.2	0.2
x2	0.2	0.3	0.5

	P(d1 x)
x1	0.3
x2	0.6

Classification

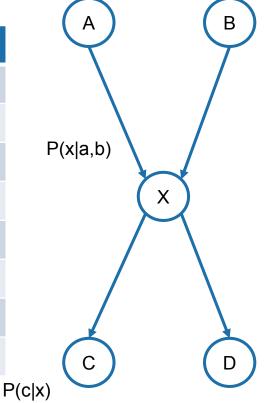
Classify the fish that is light (c1) and caught in the south Atlantic (b2), but we do not know what time of year the fish was caught nor its thickness.

Maximum a posterior probability: P(x1|c1,b2) vs P(x2|c1,b2)

P(a1)	P(a2)	P(a3)	P(a4)
0.25	0.25	0.25	0.25
			A

P(a)

	P(x1 a,b)
a1,b1	0.3
a1,b2	0.7
a2,b1	0.6
a2,b2	0.8
a3,b1	0.4
a3,b2	0.1
a4,b1	0.2
a4,b2	0.3



	P(c1 x)	P(c2 x)	P(c3 x)
x1	0.6	0.2	0.2
x2	0.2	0.3	0.5

	P(d1 x)
x1	0.3
x2	0.6

P(d|x)

P(b)

P(b1)

0.6

Classification (2)

Q: query e: evidence of all variables P(Q|**e**)=P(q,e)/P(e)=αP(Q,e)

 $P(x1|c1,b2)=P(x1,c1,b2)/P(c1,b2)\\ =\alpha\sum P(x1,a,b2,c1,d)\\ =\alpha\sum P(a).P(b2).P(x1|a,b2).\ P(c1|x1).\ P(d|x1)\\ =\alpha P(b2).P(c1|x1)\sum P(a).\ P(x1|a,b2).\ P(d|x1)\\ =\alpha P(b2).P(c1|x1)\left[\sum P(a).\ P(x1|a,b2)\right]\left[\sum P(d|x1)\right]=\alpha\\ 0.114$

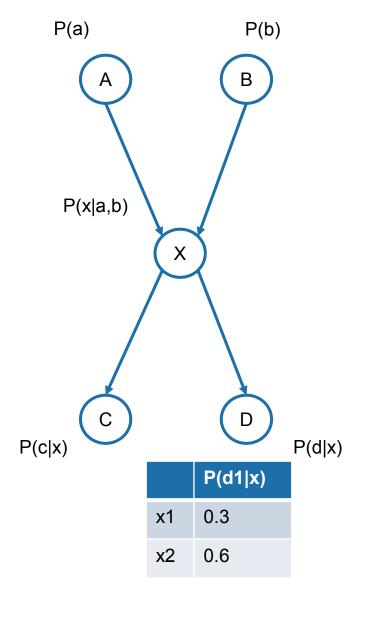
P(a1). P(x1|a1,b2)+

P(a2). P(x1|a2,b2)+

P(a3). P(x1|a3,b2)+

P(a4). P(x1|a4,b2)

P(d1|x1)+P(d2|x1)=1.0



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Classification (3)

P(x1|c1,b2)=P(x1,c1,b2)/P(c1,b2)=αP(b2).P(c1|x1).[Σ P(a).P(x1|a,b2)]. [Σ P(d|x1)]= α 0.114

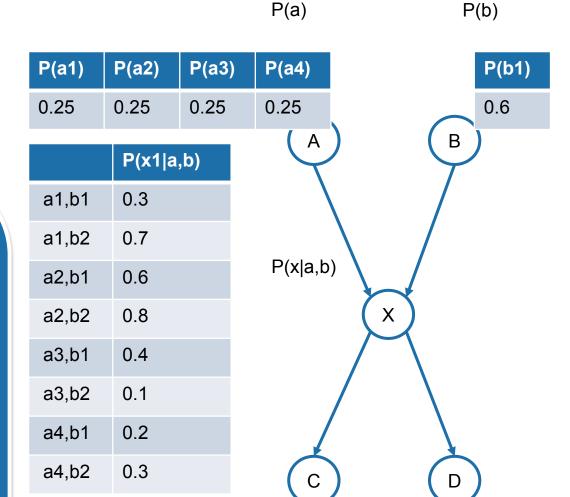
P(x2|c1,b2)=P(x2,c1,b2)/P(c1,b2) = α P(b2).P(c1|x2) [\sum P(a). P(x2|a,b2)][\sum P(d|x2)]= α 0.042

Normalize:

P(x1|c1,b2)=0.73

P(x2|c1,b2)=0.27

Decision: x1=salmon



	P(c1 x)	P(c2 x)	P(c3 x)
x1	0.6	0.2	0.2
x2	0.2	0.3	0.5

P(c|x)

x1 0.3 x2 0.6

P(d|x)

Knowledge Representation and Reasoning

Learning from Data

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KK IF – Teknik Informatika – STEI ITB

Inteligensi Buatan (*Artificial Intelligence*)

Problems in BN constructed by human expert

Knowledge acquisition bottleneck problem

Knowledge elicitation problem: slow speed, and inability of expert to express the knowledge they posses.

Very difficult in getting reliable probability estimates.

Ideally, determine probability by data distribution, experience, and assumption (subjective).

What is difference between P(a)=0.5 and P(a)=0.6?

known numerical parameters

unknown structure Knowledge from human expert

Construct structure and estimate numerical parameters

Estimate numerical parameters

known structure

Humans are good at providing structure, data is good at providing numbers

unknown numerical

parameters ling/ Edunex ITB

Parameter Estimation

Given structure with m nodes

Given a data set

$$D = \{ \langle v_1^1, ..., v_m^1 \rangle, ..., \langle v_1^k, ..., v_m^k \rangle \}$$

Count #(V_i =T), #(V_i =F), #(V_i =T, V_i =T), #(V_i =T, V_i =F)

Variable V_i with no parent $P(V_i) \approx \frac{\#(V_i = T)}{k}$

Variable
$$V_j$$
 with parent V_j

$$P(V_i|V_j) \approx \frac{\#(V_i = T, V_j = T)}{\#(V_j = T)}$$

$$P(V_i|\neg V_j) \approx \frac{\#(V_i = T, V_j = F)}{\#(V_j = F)}$$

Smoothing: Avoid Probability = 0

Variable V_i with no parent

$$P(V_i) \approx \frac{\#(V_i = T) + 1}{k + 2} \sum_{\substack{\text{runung kina n} \\ \text{nilalinya True/False} \\ \Rightarrow \text{ add } 2}}$$

Variable
$$V_i$$
 with parent V_j

$$P(V_i|V_j) \approx \frac{\#(V_i = T, V_j = T) + 1}{\#(V_j = T) + 2}$$

$$P(V_i|\neg V_j) \approx \frac{\#(V_i = T, V_j = F) + 1}{\#(V_j = F) + 2}$$

Construct BN Structure

Determine set of variables

Determine ordering of variables $X_1,...X_m$

Loop: Add X_i, and select set of parents for X_i from X₁,...,X_{i-1}

Construct BN Structure: Example

Based on causal knowledge:

- Set of variables: A,B,C,D,X
- Ordering of variables: A,B,C,D,X
- Add A: no parent.
- Add B: is A parent of B?
- Add C: parent of C?
- Add D: parent of D?
- Add X: parent of X?

Based on data:

- Set of variables: A,B,C,D,X
- Ordering of variables: A,B,C,D,X
- Add A: no parent.
- Add B: P(B|A)=P(B) ?
- Add C:
 - P(C|A)=P(C)?
 - P(C|B)=P(C)?
 - P(C|A,B)=P(C|A)?
 - P(C|A,B)=P(C|B)? P(c/B): P(c/B)
 - P(C|A,B)=P(C)?
- Etc.

```
hitung P(B|A) = P(B)

kalau iya berarni
mereka saling independen
dan A bucan parent dari B

)?

P(C|A,B): P(C,B)

A haak mempengaruhi C,
A bukan parent C

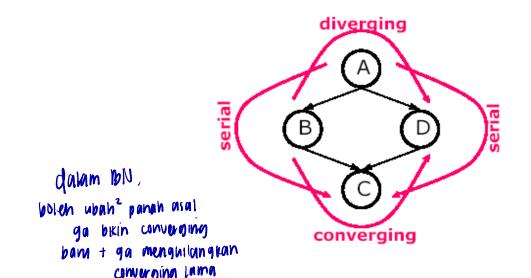
berarti parent C adalah B.
```

D Separation

Two variables A and B are d-separated iff for every path between them, there is an intermediate variable V such that either

- The connection is serial or diverging and V is known
- The connection is converging and neither V nor any descendant is instantiated

Two variables are d-connected iff they are not d-separated



- A-B-C: serial, blocked when B is known, connected otherwise
- A-D-C: serial, blocked when D is known, connected otherwise
- B-A-D: diverging, blocked when A is known, connected otherwise
- B-C-D: converging, blocked when C has no evidence, connected otherwise

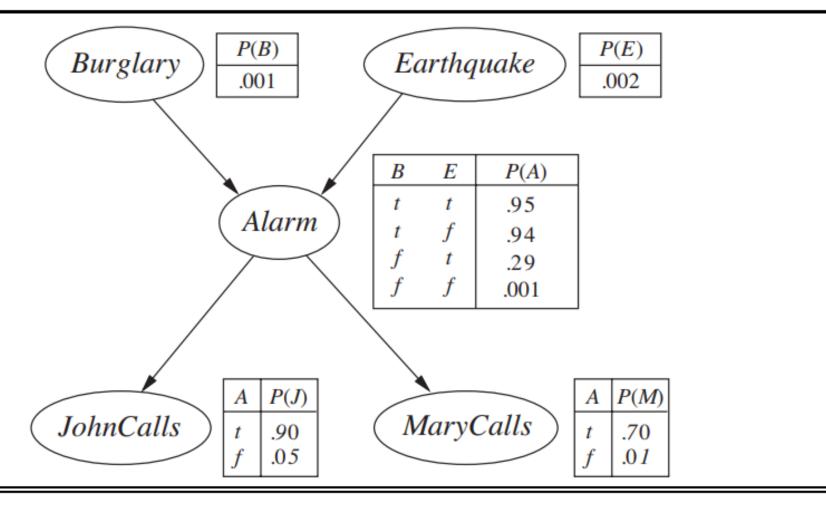


Figure 14.2 A typical Bayesian network, showing both the topology and the conditional probability tables (CPTs). In the CPTs, the letters B, E, A, J, and M stand for Burglary, Earthquake, Alarm, JohnCalls, and MaryCalls, respectively.

Variable Ordering Influences Structure

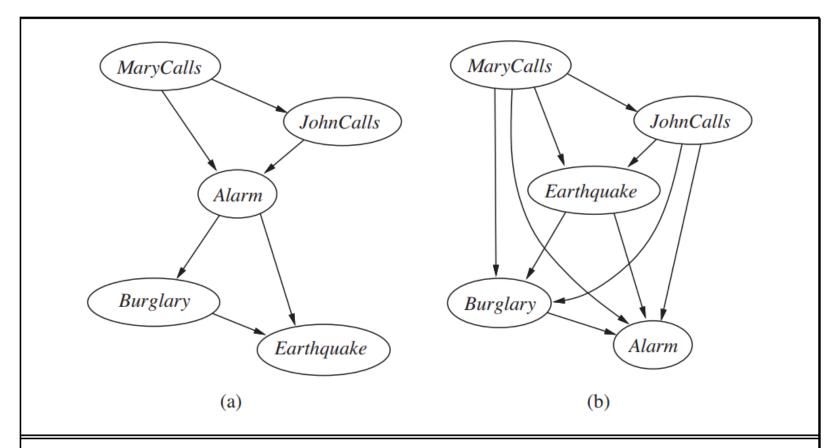
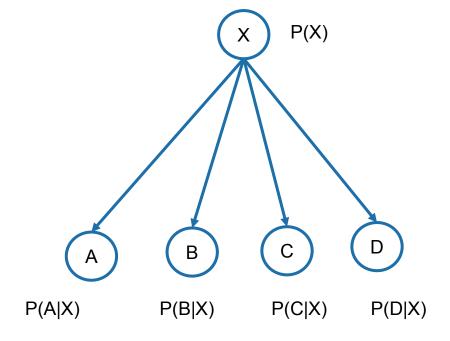


Figure 14.3 Network structure depends on order of introduction. In each network, we have introduced nodes in top-to-bottom order.

Construct BN Structure: Example 2

Based on causal knowledge:

- Set of variables: X,A,B,C,D
- Ordering of variables: X,A,B,C,D
- Add X: no parent.
- Add A: parent(A)=X.
- Add B: parent(B)=X. P(B|A,X)=P(B|X)
- Add C: parent(C)=X. P(C|A,B,X)=P(C|X)
- Add D: parent(D)=X. P(D|A,B,C,X)=P(D|X)

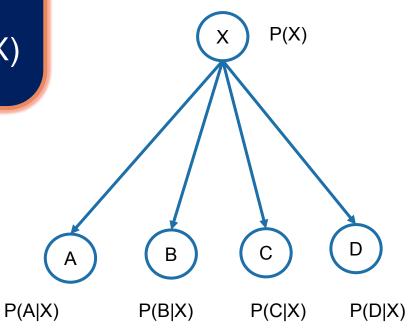


Naive Bayes as "Special" Bayesian Network

What is the Bayes Network for X1,...Xn with NO assumed conditional independencies?

Probability Model of P(X) and P($a_i|X$) P(X, A, B, C, D) = P(X). P(A|X). P(B|X). P(C|X). P(D|X)

> Classification: Find the maximum $P(X \mid A,B,C,D)$



Example: Play Tennis Dataset

outlook	temp.	humidity	windy	play
sunny	hot	high	false	no
sunny	hot	high	true	no
overcast	hot	high	false	yes
rainy	mild	high	false	yes
rainy	cool	normal	false	yes
rainy	cool	normal	true	no
overcast	cool	normal	true	yes

outlook	temp.	humidity	windy	play
sunny	mild	high	false	no
sunny	cool	normal	false	yes
rainy	mild	normal	false	yes
sunny	mild	normal	true	yes
overcast	mild	high	true	yes
overcast	hot	normal	false	yes
rainy	mild	high	true	no

Frequency of (sunny|yes) \rightarrow 2

Frequency of (overcast|yes) → 4

Frequency of (hot|yes) \rightarrow 2

Frequency of class 'yes' → 9

Frequency of $(\text{sunny}|\text{no}) \rightarrow 3$

Frequency of (overcast $| no \rangle \rightarrow 0$

ncy of Frequency of \rightarrow 0 (hot|no) \rightarrow 2 NUM&MLK&Kaelbling/ Edunex ITB

Frequency of class 'no' → 5

Example: Play Tennis Dataset

outlook	temp.	humidity	windy	play
sunny	hot	high	false	no
sunny	hot	high	true	no
overcast	hot	high	false	yes
rainy	mild	high	false	yes
rainy	cool	normal	false	yes
rainy	cool	normal	true	no
overcast	cool	normal	true	yes

outlook	temp.	humidity	windy	play
sunny	mild	high	false	no
sunny	cool	normal	false	yes
rainy	mild	normal	false	yes
sunny	mild	normal	true	yes
overcast	mild	high	true	yes
overcast	hot	normal	false	yes
rainy	mild	high	true	no

Frequency o (sunny|yes) -

Frequency o (sunny|no) ->

outlook			temperature			h	ity		win	play			
	yes	no		yes	no		yes	no		yes	no	yes	no
sunny	2	3	hot	2	2	high	3	4	false	6	2	9	5
overcast	4	0	mild	4	2	normal	6	1	true	3	3		
rainy	3	2	cool	ŊUN	Λ&MLK8	&Kaelblir	ng/ E	dunex IT	В				

Frequency of class 'yes' → 9

Frequency of class 'no' $\xrightarrow[40]{}$ 5

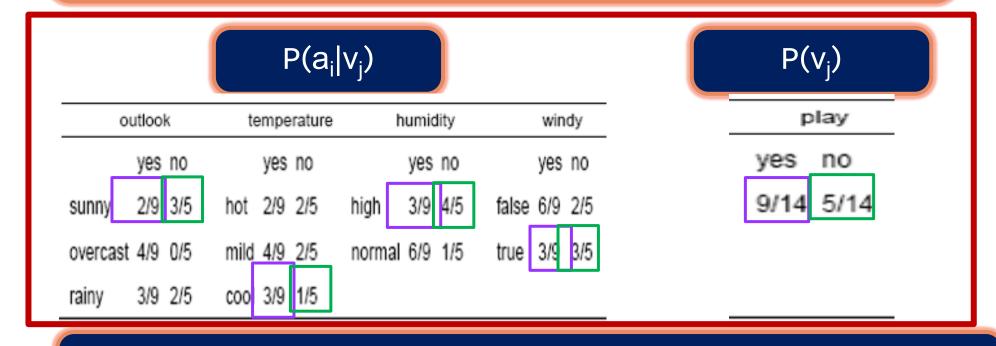
Example: Play Tennis Dataset

		OU	itlook	(te	mpe	rature	h	umid	lity		win	dy	р	lay
			yes	no		yes	no		yes	no		yes	no	yes	no
Frequency		sunny	2	3	hot	2	2	high	3	4	false	6	2	9	5
	y	overcast	4	0	mild	4	2	normal	6	1	true	3	3		
	_	rainy	3	2	cool	3	1								

$P(a_i v_j)$											P(v _j)			
01	utlool	k	te	empe	rature	h	umic	lity		win	dy		р	lay	
	yes	no		yes	no		yes	no		yes	no		yes	no	
sunny	2/9	3/5	hot	2/9	2/5	high	3/9	4/5	false	6/9	2/5		9/14	5/14	
overcast	4/9	0/5	mild	4/9	2/5	normal	6/9	1/5	true	3/9	3/5				
rainy	3/9	2/5	cool	3/9	1/5				NUM	<u>&ML</u>	K&K	aelbling/ Edune	e <u>x ITB</u>		

Probability Model

Classify New Instance: <Sunny, Cool, High, True>



$$P(v_j | a_1, a_2, ..., a_n) = P(v_j) . \prod_i P(a_i | v_j)$$

P(yes|sunny, cool, high, true)

P(no |sunny, cool, high, true)

= P(yes). P(sunny|yes).P(cool|yes).P(high|yes).P(true|yes)

= P(no). P(sunny|no).P(cool| no).P(high| no).P(true| no)

 $= 9/14 \cdot 2/9 \cdot 3/9 \cdot 3/9 \cdot 3/9 = 0.0053$

= 5/14 . 3/5 . 1/5 . 4/5 . 3/5 = 0.0206

THANK YOU