```
import numpy as np
In [ ]:
         import matplotlib.pyplot as plt
         from typing import NamedTuple
         from google.colab import output
In [ ]:
         SEED = 0
         BOARD_COL = 3
         BOARD ROW = 3
         BOARD_SIZE = BOARD_COL * BOARD_ROW
         Game board and actions are: \{q, w, e, a, s, d, z, x, c\}
         q w e
         --|---|--
         a s d
         --|---|--
         z x c
         ACTIONS_KEY_MAP = \{'q': 0, 'w': 1, 'e': 2,
                            'a': 3, 's': 4, 'd': 5,
                            'z': 6, 'x': 7, 'c': 8}
In [ ]: | np.random.seed(SEED)
```

State Defination

```
def print state(board, clear output=False):
In [ ]:
           if clear output:
             output.clear()
           for i in range(BOARD_ROW):
             print('----')
             out = ' '
             for j in range(BOARD_COL):
               if board[i, j] == 1:
                   token = 'x'
               elif board[i, j] == -1:
                   token = 'o'
               else:
                   token = ' ' # empty position
               out += token + ' '
             print(out)
           print('----')
         class State:
           def __init__(self, symbol):
             # the board is represented by an n * n array,
             # 1 represents the player who moves first,
             # -1 represents another player
             # 0 represents an empty position
             self.board = np.zeros((BOARD_ROW, BOARD_COL))
             self.symbol = symbol
             self.winner = 0
             self.end = None
```

```
@property
def hash value(self):
 hash = 0
 for x in np.nditer(self.board):
   hash = 3*hash + x + 1 # unique hash
 return hash
def next(self, action: str):
 id = ACTIONS_KEY_MAP[action]
 i, j = id // BOARD COL, id % BOARD COL
 return self.next_by_pos(i, j)
def next_by_pos(self, i: int, j: int):
 assert self.board[i, j] == 0
 new state = State(-self.symbol)
                                       # another player turn
 new_state.board = np.copy(self.board)
 new state.board[i, j] = self.symbol # current player choose to play at (i, j) pos
 return new state
@property
def possible_actions(self):
 rev_action_map = {id: key for key, id in ACTIONS_KEY_MAP.items()}
 actions = []
 for i in range(BOARD ROW):
   for j in range(BOARD COL):
     if self.board[i, j] == 0:
        actions.append(rev action map[BOARD COL*i+j])
 return actions
def is end(self):
 if self.end is not None:
   return self.end
 check = []
 # check row
 for i in range(BOARD ROW):
   check.append(sum(self.board[i, :]))
 # check col
 for i in range(BOARD_COL):
   check.append(sum(self.board[:, i]))
 # check diagonal
 diagonal = 0; reverse_diagonal = 0
 for i in range(BOARD_ROW):
   diagonal += self.board[i, i]
   reverse diagonal += self.board[BOARD ROW-i-1, i]
 check.append(diagonal)
 check.append(reverse_diagonal)
 for x in check:
   if x == 3:
      self.end = True
      self.winner = 1
                        # player 1 wins
     return self.end
   elif x == -3:
      self.end = True
      self.winner = 2
                        # player 2 wins
      return self.end
```

```
for x in np.nditer(self.board):
    if x == 0:  # play available
        self.end = False
        return self.end

self.winner = 0  # draw
self.end = True
```

Environment

```
class Env:
In [ ]:
           def __init__(self):
             self.all_states = self.get_all_states()
             self.curr_state = State(symbol=1)
           def get_all_states(self):
             all states = {} # is a dict with key as state_hash_value and value as State object
             def explore all substates(state):
               for i in range(BOARD_ROW):
                 for j in range(BOARD COL):
                   if state.board[i, j] == 0:
                     next state = state.next by pos(i, j)
                     if next_state.hash_value not in all_states:
                       all states[next state.hash value] = next state
                       if not next state.is end():
                         explore all substates(next state)
             curr_state = State(symbol=1)
             all states[curr state.hash value] = curr state
             explore all substates(curr state)
             return all states
           def reset(self):
             self.curr state = State(symbol=1)
             return self.curr_state
           def step(self, action):
             assert action in self.curr_state.possible_actions, f"Invalid {action} for the curre
             next_state_hash = self.curr_state.next(action).hash_value
             next_state = self.all_states[next_state_hash]
             self.curr_state = next_state
             reward = 0
             return self.curr_state, reward
           def is end(self):
             return self.curr_state.is_end()
           @property
           def winner(self):
             result id = self.curr state.winner
             result = 'draw'
             if result_id == 1:
               result = 'player1'
             elif result_id == 2:
               result = 'player2'
             return result
```

Policy

```
class BasePolicy:
In [ ]:
           def reset(self):
             pass
           def update_values(self, *args):
             pass
           def select action(self, state):
             raise Exception('Not Implemented Error')
         class HumanPolicy(BasePolicy):
In [ ]:
           def __init__(self, symbol):
             self.symbol = symbol
           def select action(self, state):
             assert state.symbol == self.symbol, f"Its not {self.symbol} symbol's turn"
             print_state(state.board, clear_output=True)
             key = input("Input your position: ")
             return key
         class RandomPolicy(BasePolicy):
In [ ]:
           def init (self, symbol):
             self.symbol = symbol
           def select action(self, state):
             assert state.symbol == self.symbol, f"Its not {self.symbol} symbol's turn"
             return np.random.choice(state.possible_actions)
In [ ]:
         class ActionPlayed(NamedTuple):
           hash value: str
           action: str
         class MenacePolicy(BasePolicy):
           def __init__(self, all_states, symbol, tau=5.0):
             self.all_states = all_states
             self.symbol = symbol
             self.tau = tau
             # It store the number of stones for each action for each state
             self.state action value = self.initialize()
             # variable to store the history for updating the number of stones
             self.history = []
           def initialize(self):
             state action value = {}
             for hash_value, state in self.all_states.items():
               # initially all actions have 0 stones
               state_action_value[hash_value] = {action: 0 for action in state.possible_actions}
             return state_action_value
           def reset(self):
             for action_value in self.state_action_value.values():
               for action in action value.keys():
                 action value[action] = 0
           def print_updates(self, reward):
             print(f'Player with symbol {self.symbol} updates the following history with {reward
```

```
for item in self.history:
   board = np.copy(self.all states[item.hash value].board)
    id = ACTIONS KEY MAP[item.action]
    i, j = id//BOARD_COL, id%BOARD_COL
   board[i, j] = self.symbol
    print state(board)
def update_values(self, reward, show_update=False):
 # reward: if wins receive reward of 1 stone for the chosen action
           else -1 stone.
 # reward is either 1 or -1 depending upon if the player has won or lost the game.
 if show update:
   self.print updates(reward)
 for item in self.history:
   # your code here
   self.state action value[item.hash value][item.action] = reward # update state_act
 self.history = []
def select_action(self, state): # Softmax action probability
 assert state.symbol == self.symbol, f"Its not {self.symbol} symbol's turn"
 action value = self.state action value[state.hash value]
 max value = action value[max(action value, key=action value.get)]
 exp values = {action: np.exp((v-max value) / self.tau) for action, v in action value
 normalizer = np.sum([v for v in exp values.values()])
 prob = {action: v/normalizer for action, v in exp values.items()}
 action = np.random.choice(list(prob.keys()), p=list(prob.values()))
 self.history.append(ActionPlayed(state.hash value, action))
 return action
```

Game Board

```
In [ ]:
         class Game:
           def __init__(self, env, player1, player2):
             self.env = env
             self.player1 = player1
             self.player2 = player2
             self.show_updates = False
           def alternate(self):
             while True:
               yield self.player1
               yield self.player2
           def train(self, epochs=1 00 000):
             game_results = []
             player1_reward_map = {'player1': 1, 'player2': -1, 'draw': 0}
             for _ in range(epochs):
               result = self.play()
               # if player1 wins add 1 stone for the action chosen
               player1_reward = player1_reward_map[result]
               player2_reward = -player1_reward # if player2 wins add 1 stone
               self.player1.update values(player1 reward)
               self.player2.update values(player2 reward)
           def play(self):
```

```
alternate = self.alternate()
state = self.env.reset()
while not self.env.is_end():
   player = next(alternate)
   action = player.select_action(state)
   state, _ = self.env.step(action)
result = self.env.winner
return result
```

Experiment

```
env = Env()
In [ ]:
         player1 = MenacePolicy(env.all states, symbol=1)
         player2 = MenacePolicy(env.all_states, symbol=-1)
         # player2 = RandomPolicy(symbol=-1)
         game = Game(env, player1, player2)
In [ ]:
         game.train(epochs=1 00 000)
         game with human player = Game(env, player1, HumanPolicy(symbol=-1))
In [ ]:
         game with human player.play()
         result = env.winner
         print(f"winner: {result}")
         player1_reward_map = {'player1': 1, 'player2': -1, 'draw': 0}
         player1.update values(player1 reward map[result], show update=True)
         game with human player = Game(env, player1, HumanPolicy(symbol=-1))
In [ ]:
         game with human player.play()
         result = env.winner
         print(f"winner: {result}")
         player1_reward_map = {'player1': 1, 'player2': -1, 'draw': 0}
         player1.update_values(player1_reward_map[result], show_update=True)
        ------
        | o | | x |
          | x | x |
        | | | 0 |
        Input your position: z
        winner: player1
        Player with symbol 1 updates the following history with 1 stone
          | | x |
          | o | | x |
                | x |
```

]				
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		Ī			0	
	0				х	
	x	Ī	х		х	
	0	Ī			0	

In []: