

# WIGVO: Real-Time Bidirectional Speech Translation over Legacy PSTN Calls via Dual-Session Echo Gating

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## Abstract

Real-time speech translation with large language models (LLMs) has become feasible in controlled settings such as mobile apps and web browsers, where developers assume wideband audio and client-side echo cancellation. However, deploying such systems over the Public Switched Telephone Network (PSTN) remains challenging due to narrowband G.711 audio, unpredictable round-trip delays, and absence of client-side signal processing. We present **WIGVO**, a server-side relay system that enables bidirectional LLM-based speech translation over ordinary telephone calls without requiring app installation or carrier integration. A central contribution is addressing what we term *echo-induced self-reinforcing translation loops*: synthesized speech echoing back through the PSTN gets re-ingested and repeatedly translated. WIGVO solves this through a dual-session architecture with deterministic silence injection and energy-based voice activity detection (VAD) gating. We evaluate WIGVO on 97 completed PSTN calls (38 fully instrumented) across three communication modes, observing 564 ms median Session A latency ( $N=148$  turns), zero echo-induced translation loops, and USD 0.42 per minute cost. WIGVO additionally supports text-to-voice and voice-to-text relay modes for users with speech anxiety or hearing impairments. The system is deployed at <https://wigvo.run> with a live demo and video walkthrough.

## 1 Introduction

Streaming speech-to-speech translation has advanced rapidly with Realtime LLM APIs, but existing work focuses on WebRTC and VoIP settings where wideband audio and client-side acoustic echo cancellation (AEC) are available (Seamless Communication et al., 2023a; Rad-

ford et al., 2023). The Public Switched Telephone Network (PSTN), however, still handles the majority of calls to restaurants, hospitals, and government offices (International Telecommunication Union, 2020). PSTN operates at 8 kHz with  $\mu$ -law companding, introduces 80–600 ms jitter, and provides no client-side AEC. For foreign residents, people with speech anxiety, or users with hearing impairments, making such calls remains a significant barrier.

We present **WIGVO**, a server-side relay that bridges a web client and a standard PSTN phone number through two concurrent LLM-backed streaming sessions. The caller speaks (or types) via a browser; the callee answers on an ordinary phone. WIGVO translates bidirectionally in real time, supporting voice-to-voice (V2V), text-to-voice (T2V), and voice-to-text (VTT) accessibility modes.

A key challenge is what we call an **echo-induced self-reinforcing translation loop**: TTS audio played to the callee echoes back through the PSTN, is re-recognized as new speech, and gets translated again—creating a runaway feedback cycle. This problem is specific to full-duplex telephony channels and cannot be solved by VAD threshold tuning alone. Our solution operates at the architectural level: (i) strict directional separation via two independent Realtime sessions, (ii) deterministic silence injection during TTS playback windows, and (iii) energy-based gating calibrated for  $\mu$ -law dynamics.

We evaluate WIGVO on 97 completed PSTN calls and report latency, echo suppression, and cost metrics. Our contributions are:

- We formalize the *echo-induced translation loop* problem in streaming speech translation over telephony.

- 084 • We propose a *dual-session gated architecture* combining directional separation, si-  
 085 lence injection, and energy-based gating  
 086 for PSTN environments.  
 087
- 088 • We deploy and evaluate a working relay  
 089 server across three communication modes,  
 090 reporting system-level metrics from real  
 091 PSTN calls.

## 092 2 Related Work

093 **Simultaneous speech translation.** Re-  
 094 cent systems such as SeamlessM4T ([Seamless Communication et al., 2023b](#)) and Se-  
 095 amless Streaming ([Seamless Communication et al., 2023a](#)) achieve real-time speech transla-  
 096 tion with expressive and multilingual models.  
 097 [ESPnet-ST-v2 \(Yan et al., 2023\)](#) provides a  
 098 comprehensive toolkit for offline and simulta-  
 099 neous translation. However, all assume wide-  
 100 band audio inputs from controlled environ-  
 101 ments and do not address PSTN-specific chal-  
 102 lenges such as G.711 codec artifacts, telephony  
 103 echo, or narrowband VAD.

106 **Telephony AI agents.** Google Duplex  
 107 ([Leviathan and Matias, 2018](#)) demonstrated  
 108 autonomous PSTN calls for restaurant reser-  
 109 vations, but performs task completion in a sin-  
 110 gle language rather than bidirectional transla-  
 111 tion. Commercial platforms such as Vapi and  
 112 Bland.ai provide LLM-powered phone agents  
 113 but focus on monolingual voice assistants.

114 **Relay services for accessibility.** Telecom-  
 115 munications Relay Services (TRS), mandated  
 116 by the FCC in the United States, provide  
 117 human operators who relay calls for deaf  
 118 and hard-of-hearing users ([Federal Communi-](#)  
 119 [cations Commission, 2024](#)). These services are  
 120 limited to specific countries, require human in-  
 121 termediaries, and do not support cross-lingual  
 122 translation.

123 **Accessibility-oriented translation.**  
 124 sign.mt ([Moryossef, 2024](#)) provides bidirec-  
 125 tional sign language translation with an  
 126 accessibility focus; our work targets telephony  
 127 and addresses echo-induced loops. Table 1  
 128 positions WIGVO against these systems.

System	PSTN	Bidir.	S2S	Echo	A11y
SeamlessM4T	✗	✓	✓	N/A	✗
Google Duplex	✓	✗	✗	Unk.	✗
FCC TRS	✓	✓	✗	Human	✓
sign.mt	✗	✓	✓	N/A	✓
Vapi / Bland	✓	✗	✗	Unk.	✗
<b>WIGVO</b>	✓	✓	✓	✓	✓

Table 1: Comparison with existing systems. PSTN: works over telephone network; Bidir.: bidirectional translation; S2S: speech-to-speech; Echo: handles telephony echo; A11y: accessibility modes (T2V/VTT).

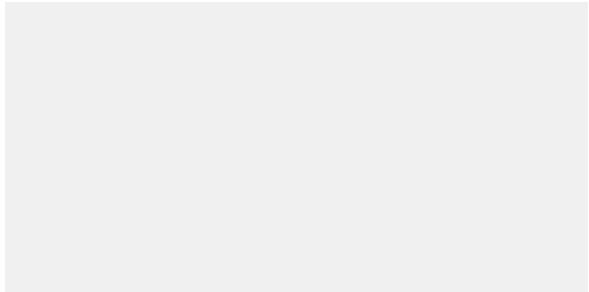


Figure 1: WIGVO architecture. The relay server manages Session A (caller→callee) and Session B (callee→caller) as independent Realtime API connections, with a telephony gateway for PSTN audio.

## 129 3 System Architecture

130 Figure 1 shows the high-level architecture.  
 131 A browser-based client connects to the relay  
 132 server via WebSocket, sending 16 kHz PCM  
 133 audio and receiving translated audio, captions,  
 134 and status events. The relay manages two in-  
 135 dependent Realtime LLM sessions and a tele-  
 136 phonny gateway connection.

137 **AudioRouter and pipelines.** An  
 138 [AudioRouter](#) implements the Strategy  
 139 pattern to dispatch events to one of four  
 140 pipeline implementations: V2V, T2V, VTT,  
 141 or Full-Agent. Each pipeline manages the  
 142 lifecycle of two Realtime sessions and cross-  
 143 cutting components (guardrails, context  
 144 window, metrics).

145 **Dual Realtime sessions.** Session A re-  
 146 ceives browser audio (PCM16) and produces  
 147 translated G.711  $\mu$ -law for the telephony gate-  
 148 way. Session B receives PSTN audio (G.711  $\mu$ -  
 149 law, 8 kHz) and produces translated audio and  
 150 captions for the browser. Each session has its  
 151 own system prompt, sliding context window (6

152 turns), and event stream, ensuring strict directional separation.  
153

154 **Communication modes.** **V2V**: both  
155 directions use streaming ASR+TTS. **T2V**: the  
156 caller types text, which is converted to TTS  
157 for the callee; the callee’s speech is trans-  
158cribed and displayed as captions. **VTT**: the  
159 caller speaks; the callee receives text captions  
160 only. **Full-Agent**: the LLM autonomously  
161 conducts the call based on collected user in-  
162 tent.

## 163 4 Echo Gating Mechanisms

### 164 4.1 The Echo Loop Problem

165 In a naive single-session design, both speak-  
166 ers’ audio feeds into one streaming session.  
167 TTS output played to the callee echoes back  
168 through the PSTN after 80–600 ms, gets re-  
169 recognized, and triggers another translation  
170 cycle. We observed this reliably in early pro-  
171 tootypes: the system would generate progres-  
172 sively distorted paraphrases of its own output  
173 until manually interrupted.

174 We initially attempted a Pearson-  
175 correlation echo detector comparing outgoing  
176 TTS buffers with incoming audio. While effec-  
177 tive in controlled tests, it failed in production  
178 due to  $\mu$ -law nonlinear quantization, variable  
179 delays, and background noise producing  
180 spurious correlations. This detector is now  
181 disabled.

182 A single-session baseline without gating pro-  
183 duced loops in the majority of test calls; a  
184 Pearson-correlation detector reduced but did  
185 not eliminate loops while introducing frequent  
186 false positives that blocked legitimate callee  
187 speech. Echo Gate v2 eliminated loops en-  
188 tirely while preserving callee interruption ca-  
189 pability.

### 190 4.2 Echo Gate v2: Silence Injection

191 Our production solution, **Echo Gate v2**, op-  
192 erates deterministically:

- 193 1. When Session A begins streaming TTS to  
194 the PSTN, an *echo window* is activated.  
195 Duration is estimated from byte length  
196 and sample rate, capped at 1.2 s.
- 197 2. During this window, incoming PSTN au-  
198 dio is replaced with  $\mu$ -law silence (0xFF)

199 before forwarding to Session B. This  
200 blocks echo at the server while allowing  
201 the Realtime API’s VAD to naturally de-  
202 tect end-of-speech.

- 203 3. A dynamic cooldown of 0.3 s accounts for  
204 PSTN jitter before resuming normal for-  
205 warding.

206 While comfort noise generation (RFC 3389;  
207 Zopf 2002) addresses perceptual continuity for  
208 human listeners in VoIP, we identify a distinct  
209 failure mode: echo-suppression-induced audio  
210 gaps cause streaming VAD state machine dead-  
211 lock in neural speech APIs. Specifically, if the  
212 relay simply *drops* audio during echo windows  
213 rather than injecting silence, the Realtime  
214 API’s server-side VAD never observes a silence-  
215 to-speech transition and remains stuck in a  
216 “speaking” state indefinitely. To our knowl-  
217 edge, this failure mode and its mitigation via  
218 silence injection have not been reported in the  
219 context of neural streaming S2ST pipelines.

220 Across 97 completed calls, Echo Gate v2  
221 produced zero echo-induced translation loops.  
222 Echo gate activated 136 times total (3.6/call  
223 on average), with 0 breakthrough incidents,  
224 confirming that silence injection effectively  
225 prevents self-reinforcing translation cycles.

### 226 4.3 Energy-Based Gating

227 RMS energy monitoring provides a secondary  
228 gate. During echo windows, only high-energy  
229 signals ( $\geq 400$  RMS) break through as genuine  
230 callee speech; typical echo energy (100–400  
231 RMS) remains suppressed. Outside echo win-  
232 dows, a lower threshold (150 RMS) filters line  
233 noise without clipping normal speech. This  
234 two-tier scheme allows callee interruptions to  
235 override the echo gate immediately. A three-  
236 level interrupt priority (callee > caller > AI)  
237 ensures callee speech immediately cancels ac-  
238 tive TTS.

## 239 5 PSTN-Aware VAD and 240 Robustness

### 241 5.1 Server VAD Failure Modes on 242 PSTN

243 OpenAI’s Realtime API provides a server-side  
244 VAD that works well for wideband WebRTC  
245 audio. On PSTN lines, however, we observed  
246 three failure modes:

247	1. Background noise misclassification.	293
248	Constant low-level PSTN noise (line hum,	294
249	codec quantization artifacts) is classified	295
250	as speech, causing the VAD to enter a	296
251	“speaking” state that never terminates.	
252	We observed stuck durations ranging from	
253	15 s to 72 s before manual intervention.	
254	2. Delayed <code>speech_stopped</code> events.	297
255	Even after genuine speech ends, the noisy	298
256	PSTN floor prevents the energy level from	299
257	dropping below the server VAD’s silence	
258	threshold, delaying end-of-utterance de-	
259	tetection by 15–72 s.	
260	3. Audio discontinuity deadlock.	300
261	When the relay drops audio frames (e.g.,	301
262	during echo suppression), the server VAD	302
263	never observes a clean silence interval and	303
264	fails to emit a <code>speech_stopped</code> event entirely.	304
265	<h2>5.2 Two-Stage Local VAD</h2>	305
266	To address these failures, WIGVO implements	306
267	a two-stage local VAD on the relay server,	307
268	applied to incoming PSTN audio before it	308
269	reaches the Realtime API.	309
270	<b>Stage 1: RMS Energy Gate.</b> A fast	310
271	energy check filters sub-speech signals. We	311
272	set the threshold at 150 RMS based on em- <td>312</td>	312
273	pirical $\mu$ -law noise distributions: back- <td>313</td>	313
274	ground noise typically falls in the 50–200 RMS range,	314
275	while speech aligns around 500–2,000+ RMS.	315
276	Frames below 150 RMS are classified as noise	316
277	and replaced with silence, preventing them	
278	from reaching Stage 2.	
279	<b>Stage 2: Silero VAD.</b> Frames passing	
280	the energy gate are processed by Silero VAD	
281	(Silero Team, 2021), a lightweight neural voice	
282	activity detector. Since Silero expects 16 kHz	
283	input but PSTN audio arrives at 8 kHz, we ap-	
284	ply zero-order hold (ZOH) upsampling before	
285	inference. Each frame is 32 ms (512 samples	
286	at 16 kHz).	
287	<b>Hysteresis state machine.</b> To avoid rapid	
288	state oscillation, we apply asymmetric hys- <td></td>	
289	teresis thresholds:	
290	• <b>SILENCE→SPEAKING:</b> probability	
291	$\geq 0.5$ for 2 consecutive frames (64 ms).	
292	Fast onset preserves responsiveness.	
	• <b>SPEAKING→SILENCE:</b> probability	293
	$< 0.35$ for 15 consecutive frames (480 ms).	294
	Slow offset avoids premature cutoff during	295
	natural pauses.	296
	This design reduces <code>speech_stopped</code> la-	297
	tency from 15–72 s (server VAD on PSTN)	298
	to a consistent 480 ms, a reduction of over 96%.	299
	<h3>5.3 Silence Injection for VAD Continuity</h3>	300
	As noted in Section 4.2, the echo gate replaces	301
	PSTN audio with $\mu$ -law silence (0xFF) rather	302
	than dropping frames. This design choice	303
	is critical for VAD continuity: if frames are	304
	dropped entirely, the Realtime API’s stream- <td>305</td>	305
	ing VAD loses its audio timeline and cannot	306
	detect speech boundaries. By injecting silence	307
	bytes, the relay maintains stream continuity	308
	while suppressing echo content. This is func-	309
	tionally distinct from comfort noise generation	310
	(RFC 3389; Zopf 2002), which synthesizes per-	311
	ceptually natural background noise for human	312
	listeners. Our silence injection instead targets	313
	the VAD state machine of neural speech APIs,	314
	preventing deadlock caused by audio gaps.	315
	<h3>5.4 STT Hallucination Blocklist</h3>	316
	A 15-pattern blocklist intercepts Korean	317
	broadcast-style hallucinations from Whisper	318
	on low-energy input; 5 outputs were blocked	319
	across 38 instrumented calls.	320
	<h2>6 Evaluation</h2>	321
	We evaluated WIGVO on 97 PSTN calls (38	322
	fully instrumented) for Korean↔English trans-	323
	lation.	324
	<h3>6.1 Latency</h3>	325
	Table 2 reports latency statistics across the 38	326
	instrumented calls.	327
	Session A achieves 564 ms median latency,	328
	within the range for interactive communica-	329
	tion. Session B, which depends on PSTN	330
	audio quality and streaming ASR, shows	331
	2,023 ms median. STT (Whisper) accounts	332
	for 74.7% of Session B mean latency across	333
	103 paired turns, with translation contribut-	334
	ing the remainder. Figure 2 shows the end-	335
	to-end latency distributions for Session A	336
	and Session B. Figure 3 shows the correlation	337
	between utterance length and Session B latency	338
		339

Stage	Avg	P50	P95	Max
Session A (ms)	618	564	1,023	2,256
Session B E2E (ms)	2,270	2,023	5,378	10,503
STT (ms)	2,263	1,979	5,065	—
Translation (ms)	757	464	2,209	—
First message (ms)	2,585	1,550	7,460	11,308

Table 2: Translation latency across 38 instrumented calls. Session A: caller→callee (ASR+translate+TTS). Session B: callee→caller, decomposed into STT (Whisper) and translation (GPT-4o) components.  $N$ : number of measured turns.

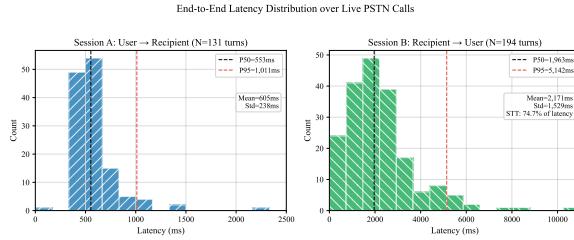


Figure 2: End-to-end latency distributions for Session A (caller→callee,  $N=148$  turns) and Session B (callee→caller,  $N=214$  turns) over live PSTN calls.

( $r = 0.529$ ,  $p < 0.001$ ), STT accounts for 74.7% of Session B mean latency.

T2V mode shows lower Session A latency (no caller-side ASR), while Agent mode shows higher Session B latency due to function-calling overhead.

## 6.2 Echo and Safety

Table 3 reports echo suppression, VAD, and guardrail statistics across the 38 instrumented calls.

The echo gate activated 3.6 times per call on average, corresponding to TTS playback events. Critically, **zero echo-induced translation loops** were observed, whereas early prototypes without gating reliably produced such loops. VAD false triggers (1.6/call) were mitigated by a minimum speech duration filter (480 ms hysteresis). The guardrail module blocked 5 hallucinated outputs (broadcast-style phrases from Whisper on low-energy input).

## 6.3 Cost

Across the 38 instrumented calls (45.5 minutes total), WIGVO consumed 638,035 tokens at a total cost of USD 19.05, yielding **USD 0.42/min** (USD 0.50/call). These costs

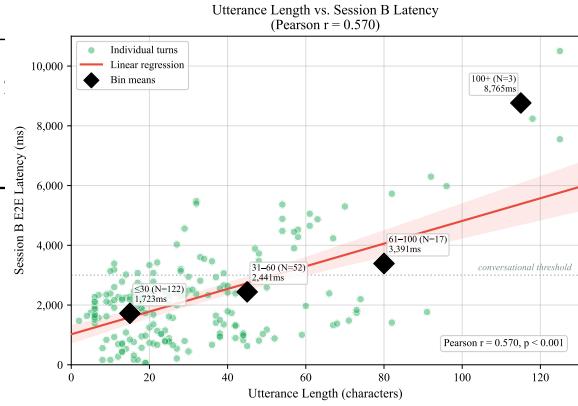


Figure 3: Utterance length (characters) vs. Session B E2E latency. Pearson  $r = 0.529$  ( $p < 0.001$ ), indicating that longer recipient utterances incur higher ASR-dominated latency.

Metric	Total	Per-call avg
Echo gate activations	136	3.6
Echo-induced loops	0	0.0
VAD false triggers	62	1.6
Guardrails blocked	5	0.13

Table 3: Echo, VAD, and guardrail statistics over 38 instrumented calls. Zero echo loops were observed.

reflect dual-session Realtime API pricing and remain an order of magnitude cheaper than human relay services (USD 1–3/min).

## 7 Demonstration

WIGVO is deployed at <https://wigvo.run> with a live demo accessible to reviewers.<sup>1</sup> The web interface supports scenario selection (restaurant, hospital, government office), real-time caption display, and mode switching. Figure 4 shows the interface during an active V2V call.

We demonstrate two scenarios:

**Restaurant reservation (V2V).** An English-speaking user calls a Korean restaurant. Session A translates caller utterances into Korean TTS for the callee; Session B returns Korean responses as English audio and captions. Across 38 instrumented calls, Session A achieved 564 ms median latency (P95: 1,023 ms) and Session B 2,023 ms median (P95: 5,378 ms;  $r=0.529$  with utterance length,  $p<0.001$ ).

<sup>1</sup>Demo video: <https://youtu.be/PLACEHOLDER>

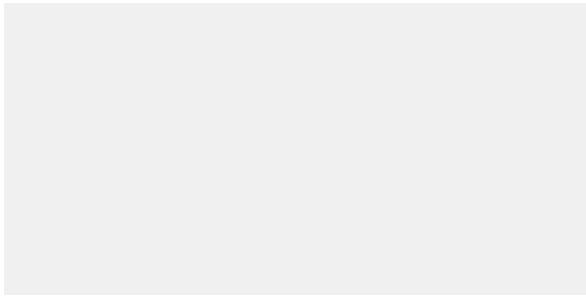


Figure 4: WIGVO web interface during a V2V call. Left: chat and caption view with bidirectional translations. Right: call status, duration, and mode indicator.

388                   **Medical appointment (T2V).** A Korean  
389 user with speech anxiety types messages that  
390 WIGVO speaks to a clinic via TTS; the clinic’s  
391 spoken responses appear as real-time captions.  
392 A typing indicator is relayed to the callee during  
393 text composition.

## 394                   8 Discussion and Limitations

395                   **Scope of contribution.** WIGVO’s contribu-  
396 tion is architectural: demonstrating that ex-  
397 isting Realtime LLM APIs can be made ro-  
398 bust for PSTN environments through dual-  
399 session separation, deterministic echo gating,  
400 and energy-based filtering. Translation quality  
401 is not independently evaluated; WIGVO inher-  
402 its the translation capabilities of GPT-4o Re-  
403 altime (OpenAI, 2024), which achieves state-  
404 of-the-art performance on Korean↔English  
405 translation. Formal translation quality evalua-  
406 tion (e.g., BLEU, chrF) is left for future work.

407                   **Limitations.** Session B latency ( $\sim 2$ s  
408 median) introduces noticeable delay in  
409 the callee→caller direction, primarily due  
410 to streaming ASR. The evaluation covers  
411 Korean↔English only; multilingual general-  
412 ization requires further study. We report  
413 system metrics but lack formal user studies; a  
414 System Usability Scale evaluation with target  
415 populations is planned. Echo gate parameters  
416 are hand-tuned; adaptive threshold learning  
417 could improve robustness.

418                   **Broader applications.** The dual-session  
419 gated architecture is applicable beyond trans-  
420 lation: multilingual call centers, voice inclu-  
421 sion services for users with disabilities, and  
422 telephony-native LLM agents that combine

task completion with cross-lingual communica-  
423 tion.

## 424                   Ethics Statement

425 All calls were initiated by the authors and  
426 collaborators for system testing. Audio was  
427 logged for debugging and aggregate metrics  
428 only, with no personally identifiable informa-  
429 tion retained beyond temporary phone num-  
430 bers. For deployment with real users, informed  
431 consent, data minimization, and compliance  
432 with privacy regulations (e.g., GDPR, PIPA)  
433 are required. The accessibility use cases (T2V  
434 for speech anxiety, VTT for hearing impair-  
435 ment) aim to reduce communication barriers  
436 but should be deployed with user agency and  
437 opt-in participation.

## 438                   Acknowledgments

439 We thank the anonymous reviewers for their  
440 feedback. WIGVO uses OpenAI’s Realtime  
441 API and Twilio Media Streams. The re-  
442 lay server is implemented in Python with  
443 FastAPI.

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