

# PMT Uniformity Measurement

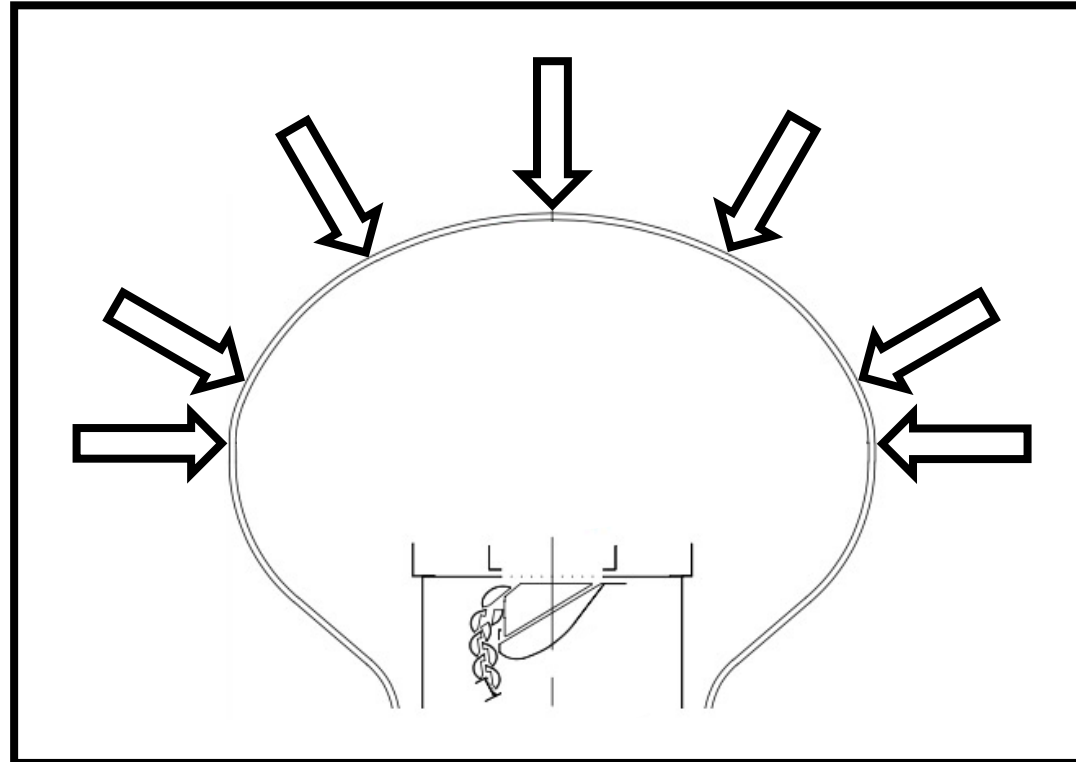
Shogo Horiuchi

# Introduction

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## ■ Uniformity of HK PMT

- HK PMT has a large photosensitive area and its shape of the B&L PMT dynode is asymmetric. Therefore, properties of PMT could depend on surface photon incident position.



# Introduction

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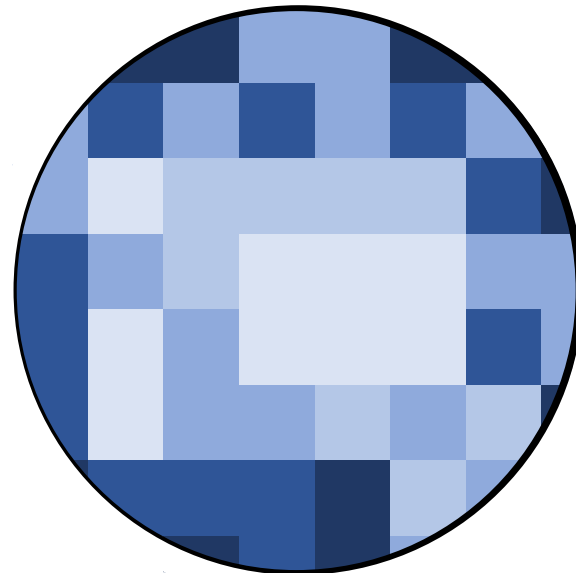
## ■ Purpose of Research

1. Make a precise response map and find area that has very different properties

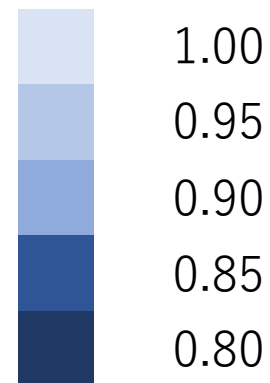
- Below is a hypothetical map of PMT demonstrated by observed gain.

Example image of potential response map

PMT seen from above



Gain /  $10^7$



# Introduction

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## ■ Purpose of Research

### 2. Identify the parameter that influence the uniformity of response

- ▶ Such as magnetic field, high voltage, tempreture, etc.
- ▶ The influential parameter will be measured at the precalibration.

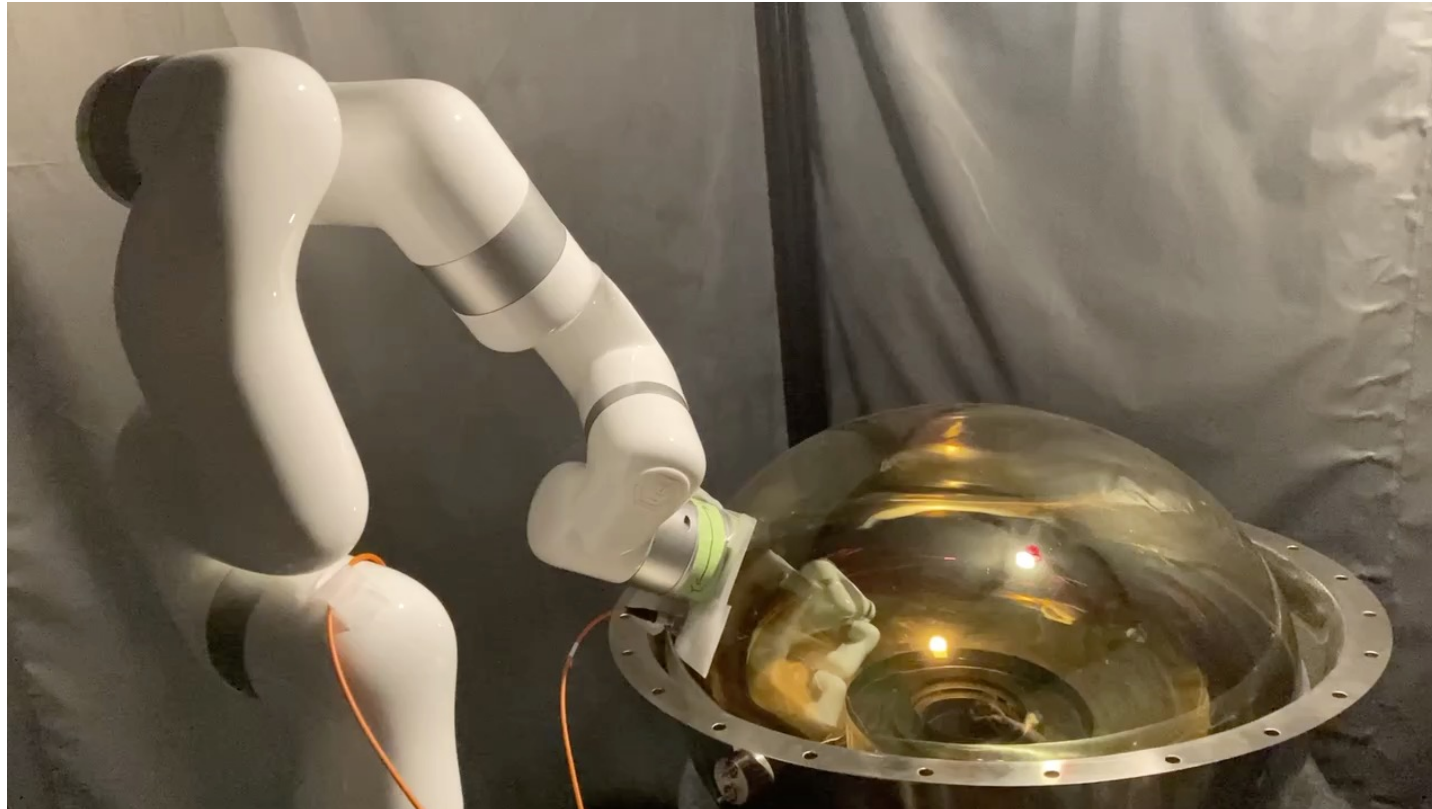
# Measurement Method

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## ■ Robot Arm

- In order to make a precise response map, photon incident position should be changed continuously.

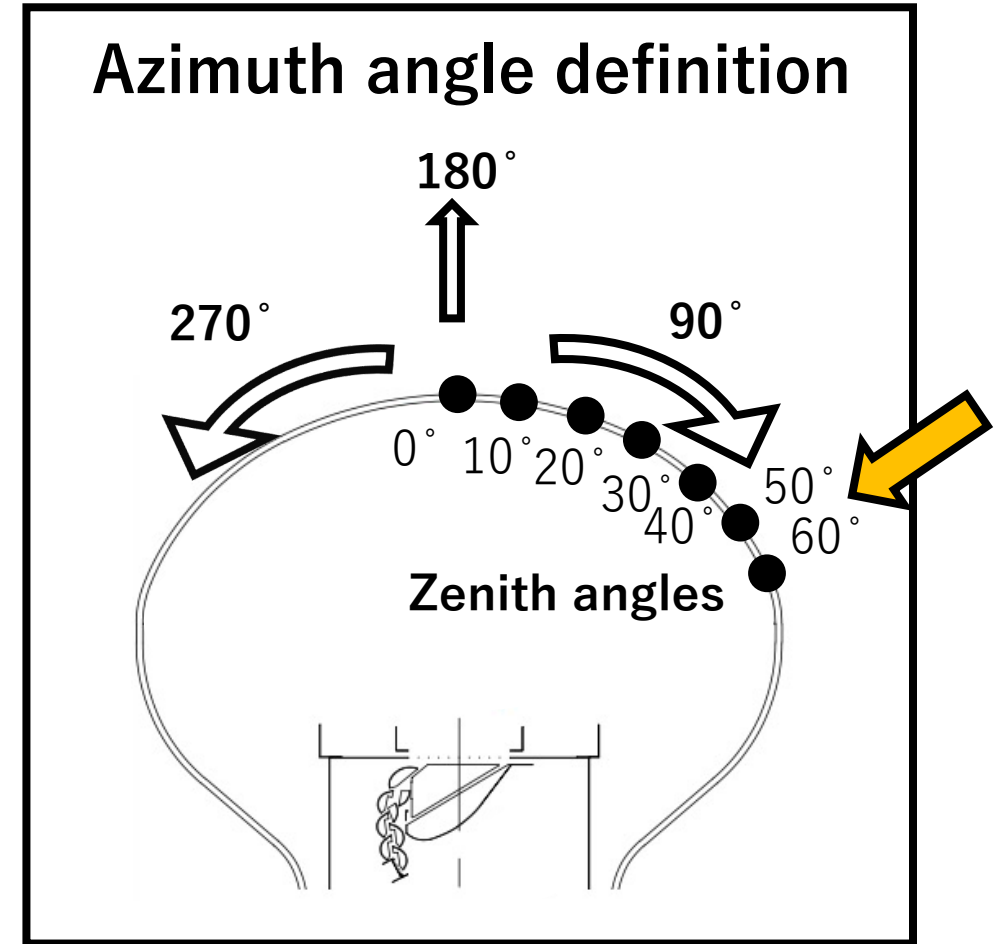
By using a robot arm, optical fiber can move smoothly.



# Measurement Method

## ■ Robot Arm

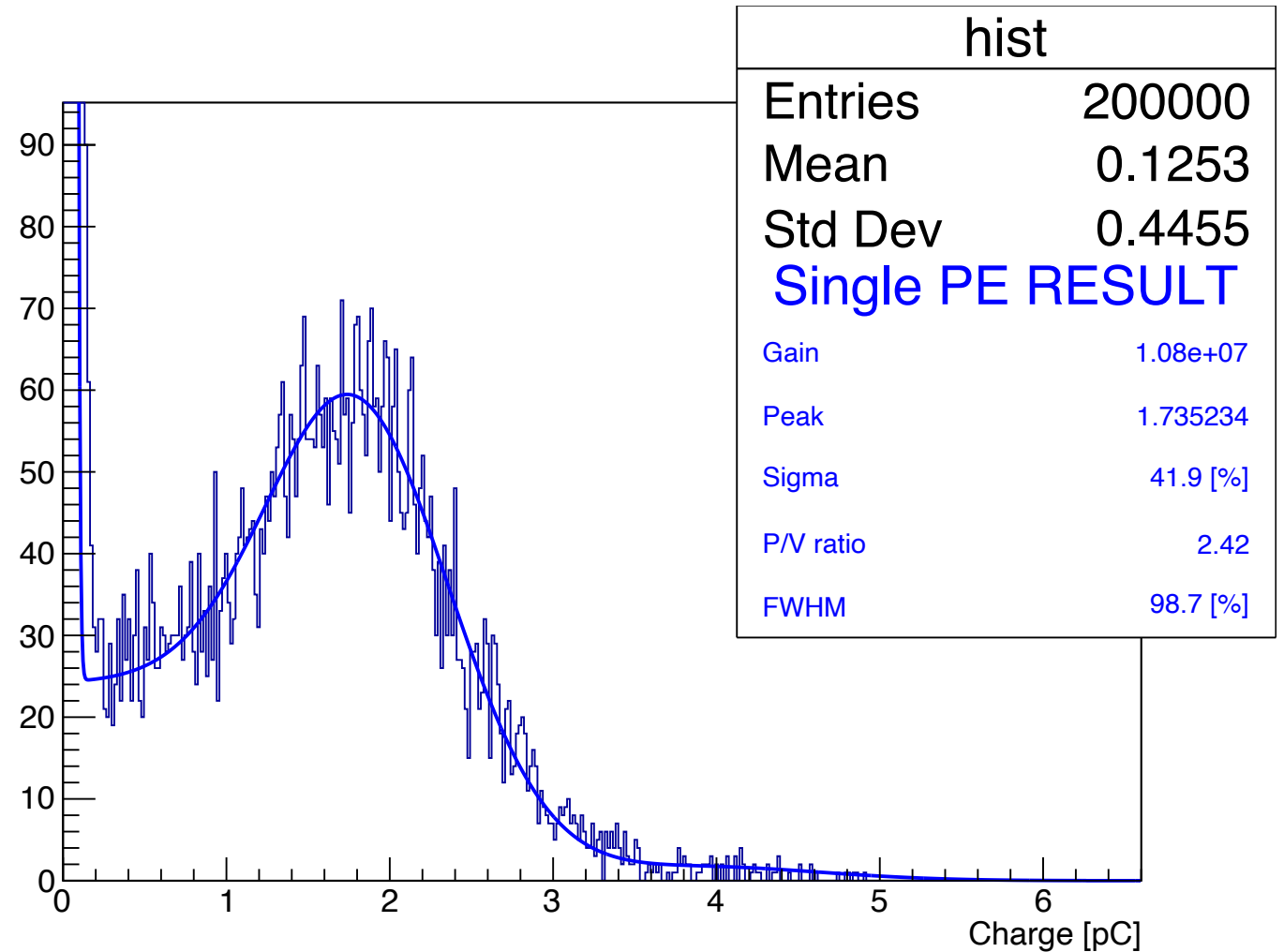
- Although the robot arm can move to any position, I measured only three azimuth angles this time.
- Photon incident angle is always vertical to the surface of the PMT.
- Zenith angle is defined by the The photon incident angle.



# Result and Analysis

## ■ Position dependency of 1 photoelectron gain

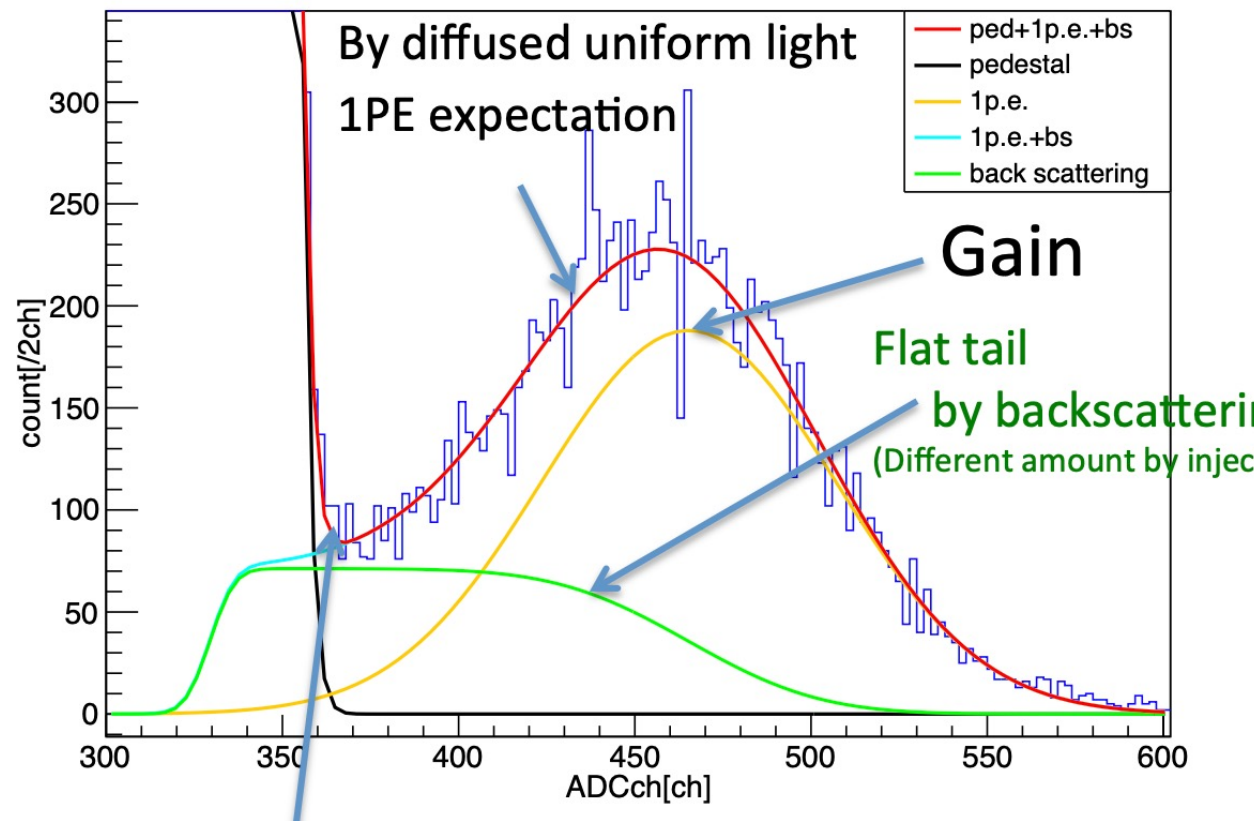
- This is the result of 1pe gain at the center of the PMT (zenith angle =  $0^\circ$ ).
- 1 p.e. gain is obtained by theoretical fit function. (next slide)



# Result and Analysis

## ■ Position dependency of 1 photoelectron gain

$$\underbrace{N_0 \exp\left(-\frac{(x - \mu_0)^2}{2\sigma_0^2}\right)}_{\text{Pedestal}} + \underbrace{N_1 \exp\left(-\frac{(x - \mu_1)^2}{2\sigma_1^2}\right)}_{\text{Gaussian}} + \underbrace{N_2 \left(\operatorname{erf}\left(\frac{x - \mu_0}{\sigma_0}\right) - \operatorname{erf}\left(\frac{x - \mu_1}{\sigma_1}\right)\right)}_{\text{Flat inelastic backscattering distribution}}$$



The fit function consists of 3 terms

- Pedestal : 0 pe peak
- **Gaussian**: 1 pe peak
- **Flat inelastic backscattering distribution** : Flat tail by backscattering, etc.

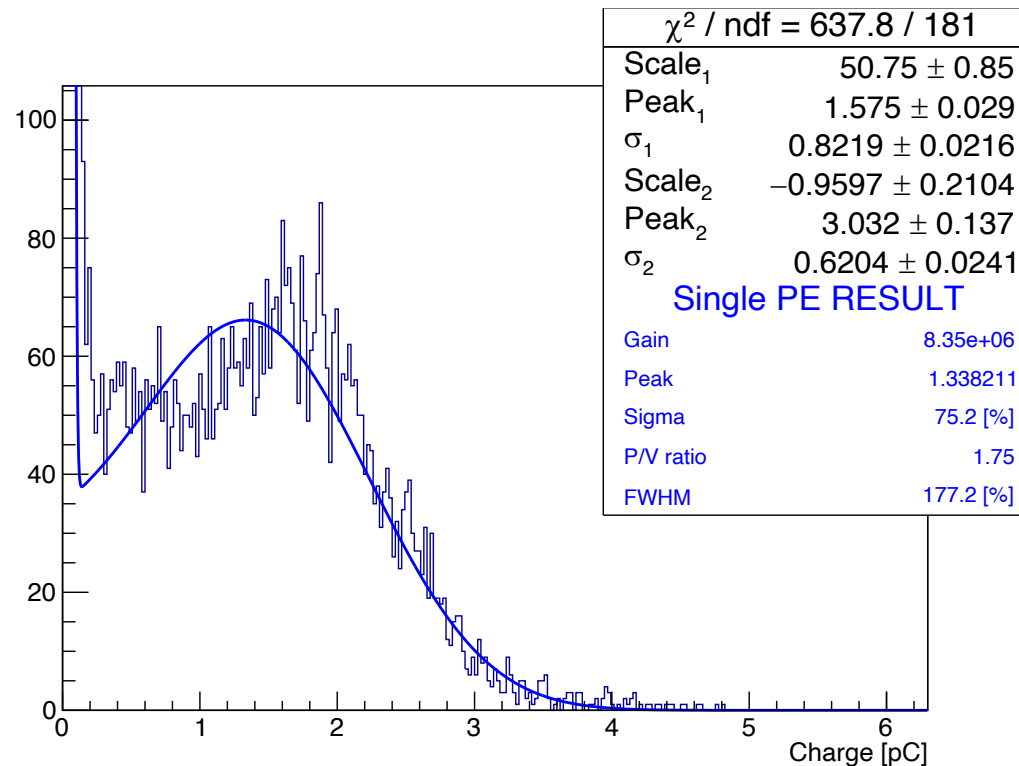
1 pe gain is obtained by **the 1 pe gaussian**



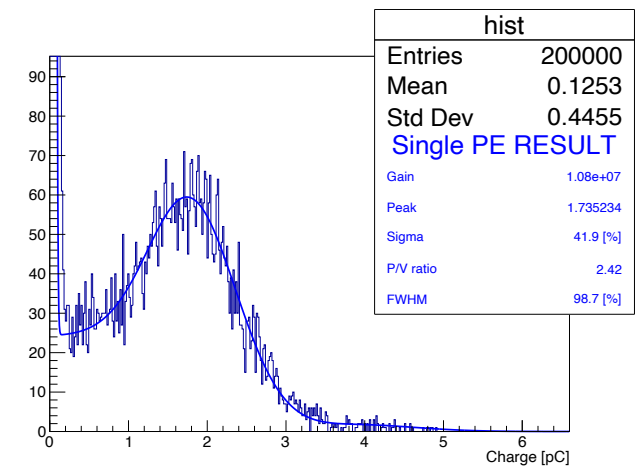
# Result and Analysis

## ■ Position dependency of 1 photoelectron gain

- When the zenith angle is large, the fitting quality get worse.
- This result has expected from the calculation of electron trajectory.



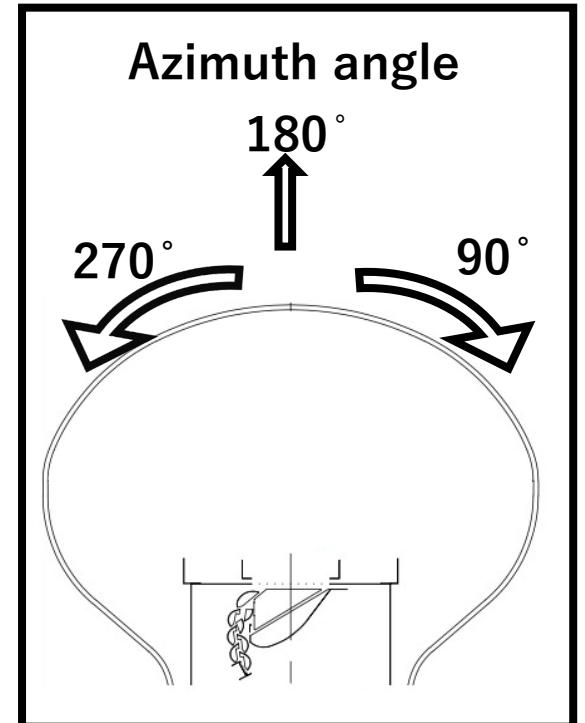
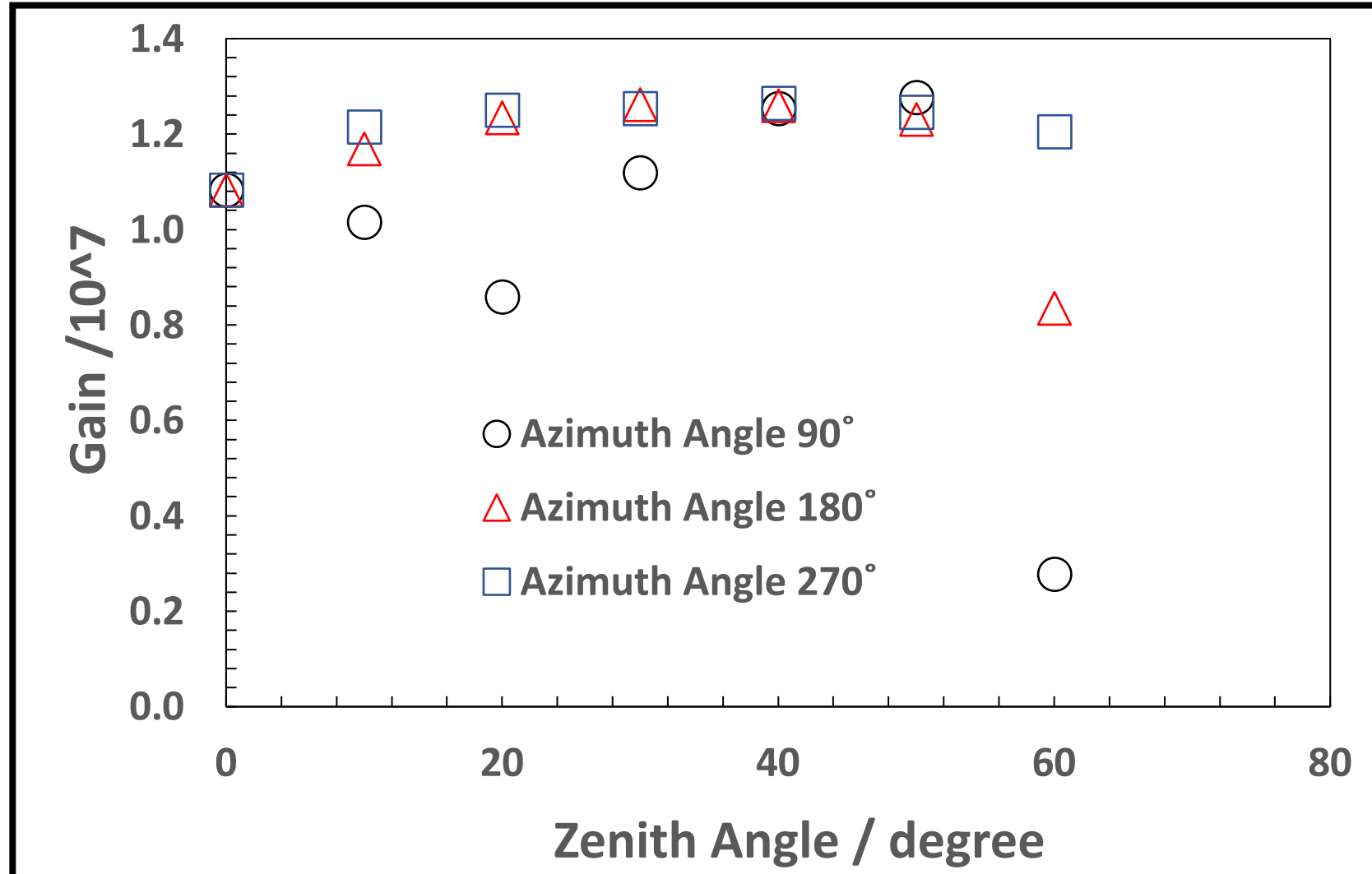
Azimuth angle: 180° zenith angle : 60°



zenith angle : 0°

# Result and Analysis

## ■ Position dependency of 1 photoelectron gain



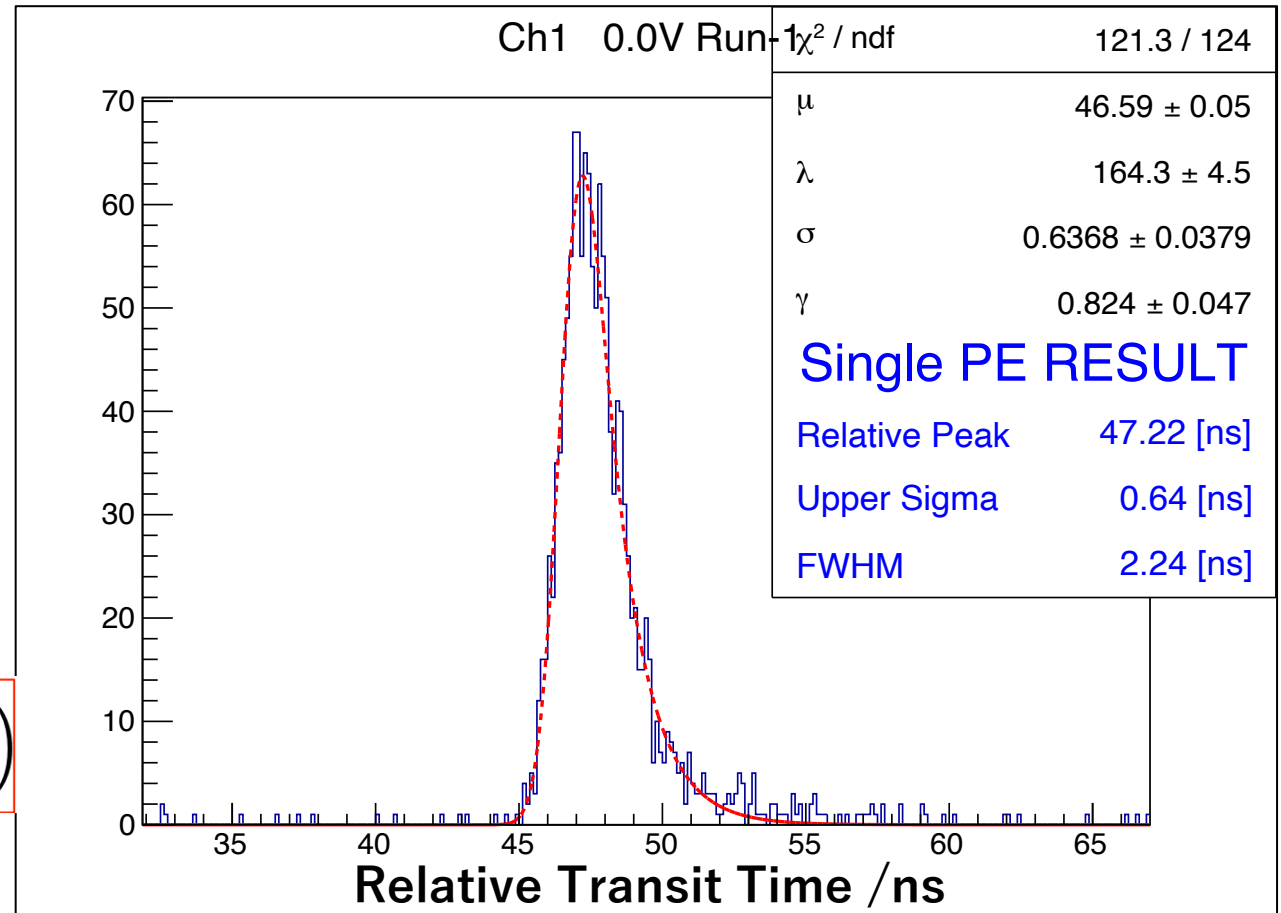
# Result and Analysis

## ■ Position dependency of 1 photoelectron T.T.S

- This is the result of T.T.S. measurement at the center of the PMT.
- Best modeling for Box&Line PMT in HK simulation is "Exponential modified gaussian":

$$f(x) = \frac{\lambda}{2} e^{\frac{\lambda}{2}(2\mu + \lambda\sigma^2 - 2x)} \operatorname{erfc}\left(\frac{\mu + \lambda\sigma^2 - x}{\sqrt{2}\sigma}\right)$$

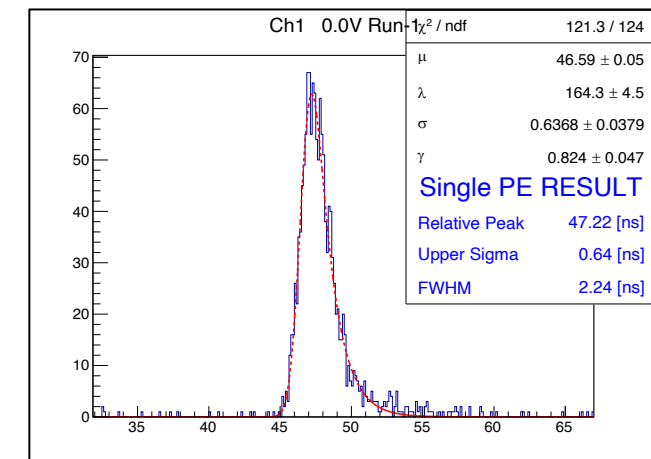
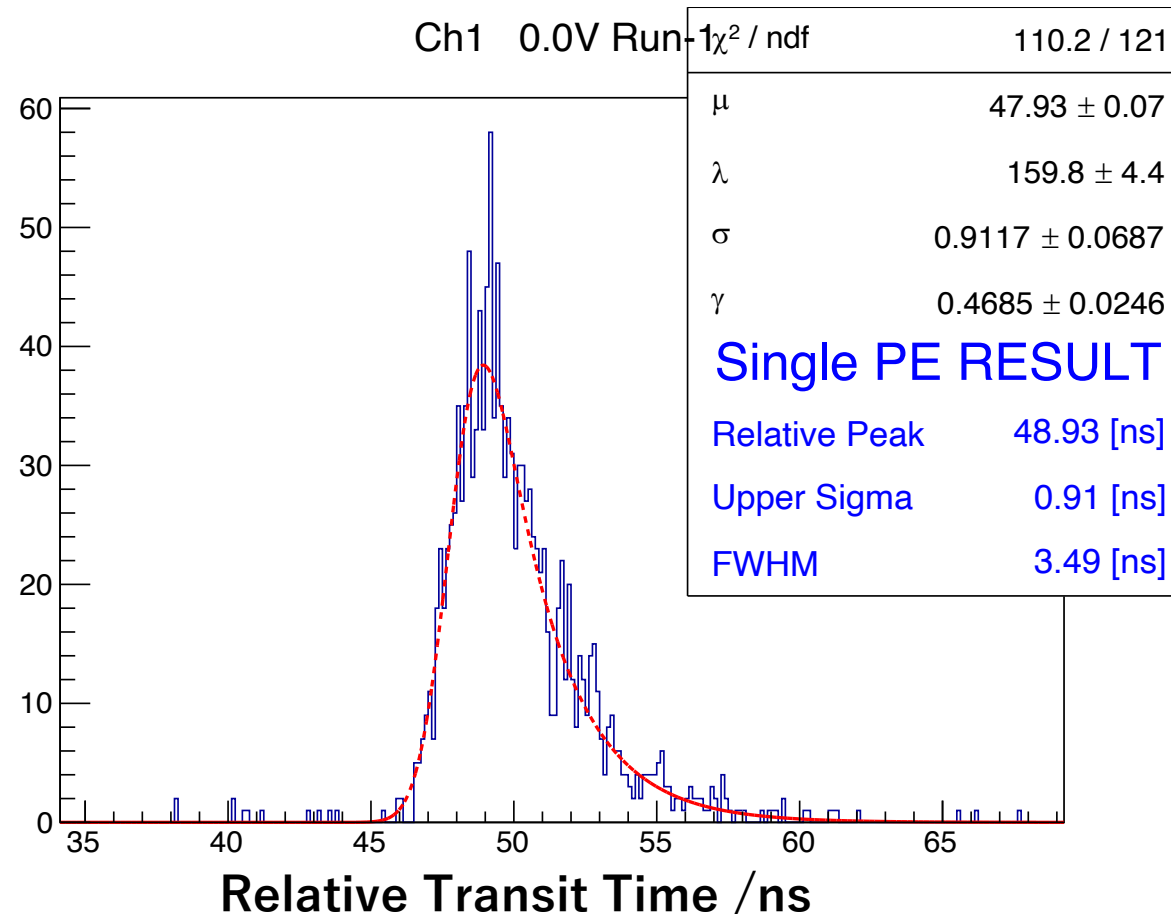
- FWHM of this fit function is used as T.T.S.



# Result and Analysis

## ■ Position dependency of 1 photoelectron T.T.S

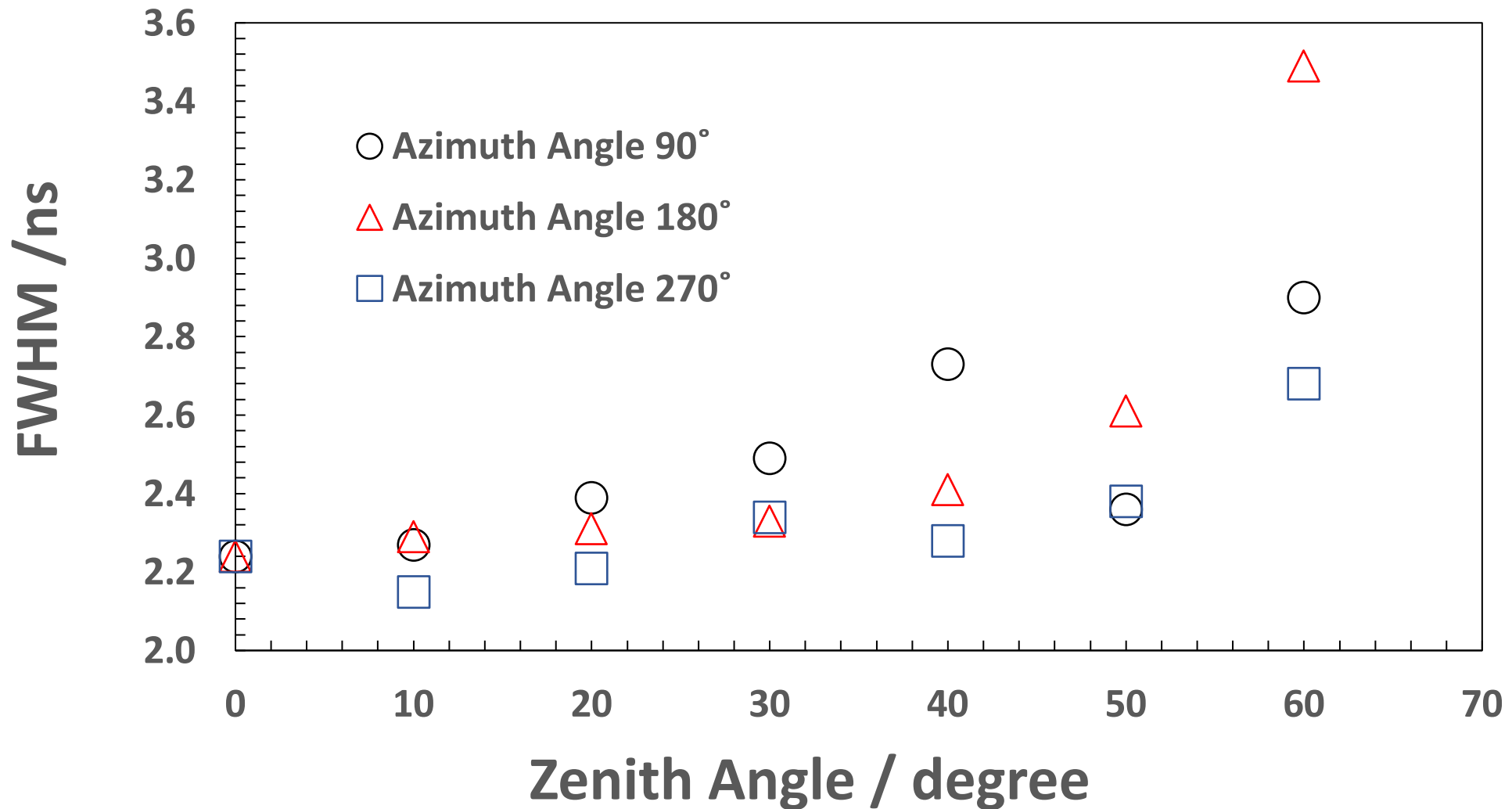
- This is the result of T.T.S. measurement when zenith angle = 60°, azimuth angle = 180°.



zenith angle : 0°

# Result and Analysis

## ■ Position dependency of 1 photoelectron T.T.S



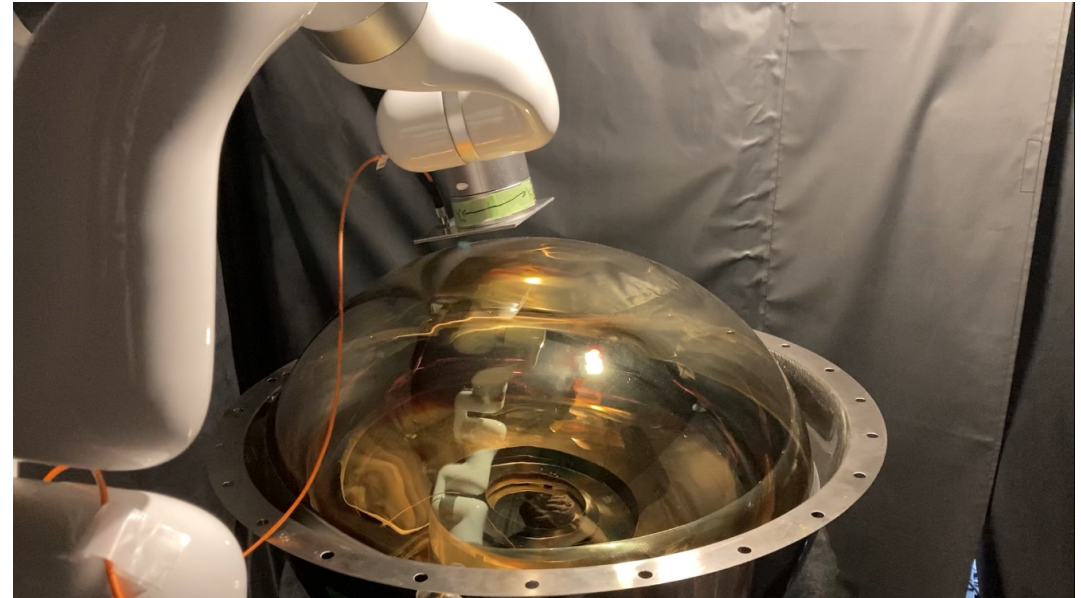
# Future prospects

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## ■ Limitations of measurement at Keio

### ● Magnetic field

- ▶ Because of the robot arm, magnetic field shield cover was removed.



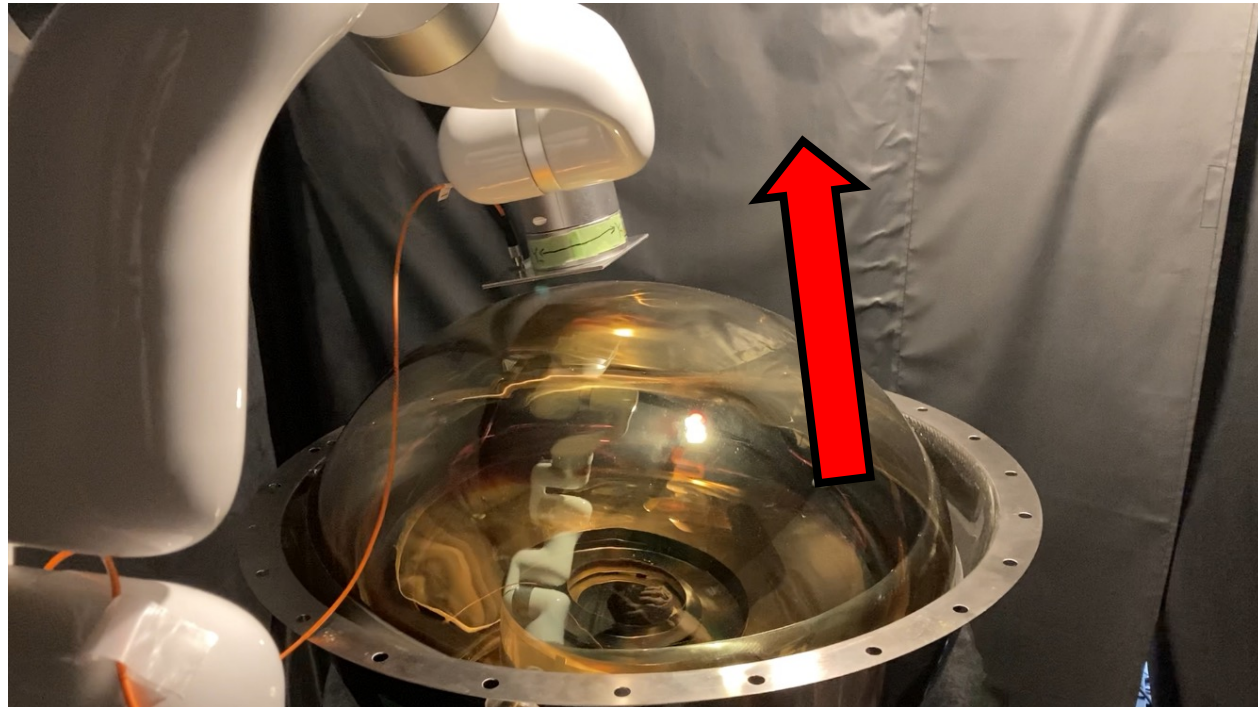
# Future prospects

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## ■ Limitations of measurement at Keio

### ● Inclination

- ▶ The PMT in our laboratoy is strapped and secured with a PMT band.
- ▶ The PMT is inclined  $7^\circ$  due to the band.





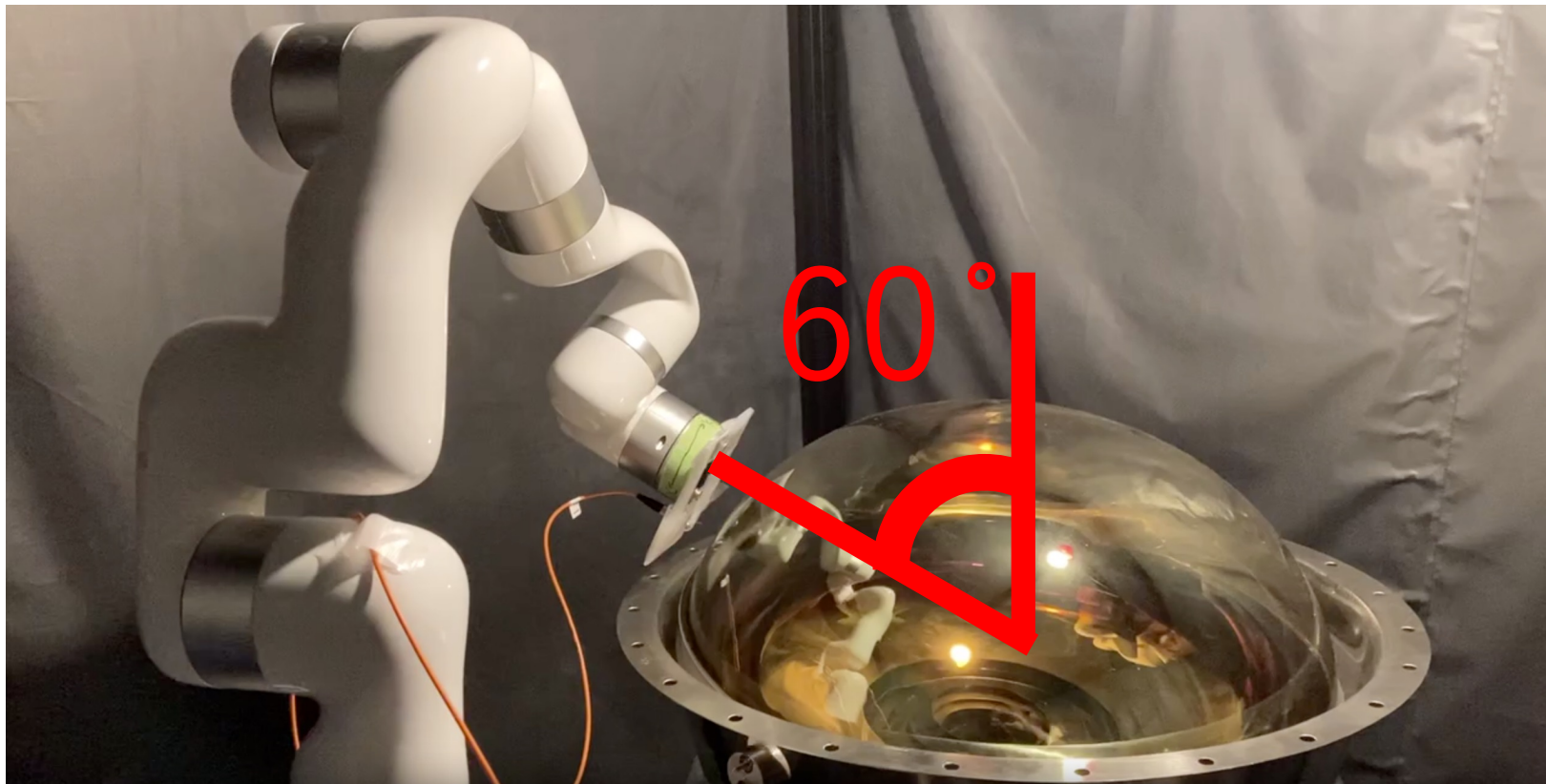
# Future prospects

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## ■ Limitations of measurement at Keio

### ● Area

- ▶ Because of the band, zenith angle is  $0^{\circ}$ - $60^{\circ}$ .





# Future prospects

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## ■ Measurement at Kamioka Lab-B

### ● Better Condition

- ▶ At Kamioka Lab-B, magnetic field can be controlled.

### ● More Parameters

- ▶ non 1pe gain
- ▶ QE

### ● Wider Area and smaller steps

- ▶ zenith and azimuth angle will be more continuous.