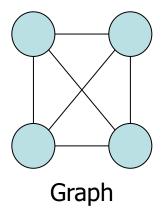
Data Structures

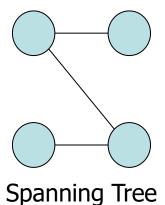
21. Minimum Spanning Tree (MST)

Spanning Trees

 A spanning tree of a graph is just a subgraph that contains all the vertices and is a tree

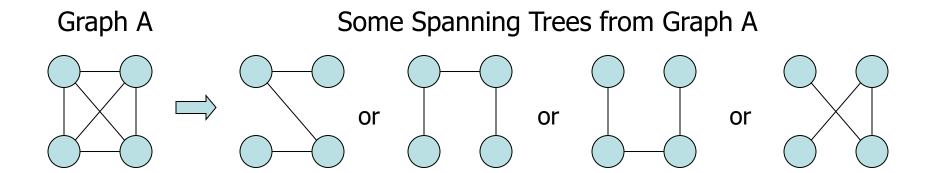
- Formal definition
 - Given a connected graph with |V| = n vertices
 - A spanning tree is defined a collection of n = 1 edges which connect all n vertices
 - The n vertices and n 1 edges define a connected sub-graph



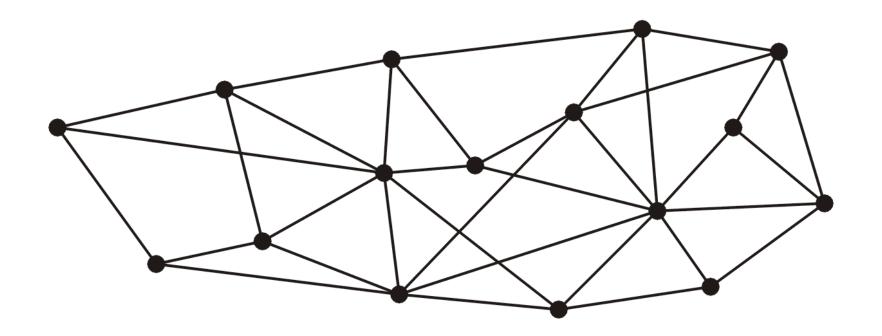


Spanning Trees

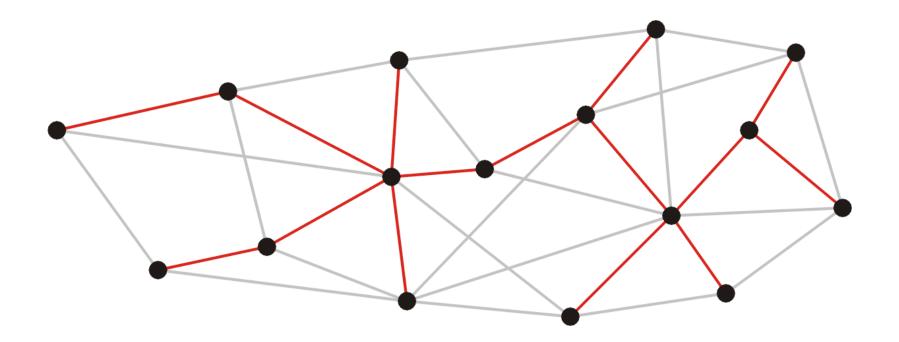
• A spanning tree is not necessarily unique



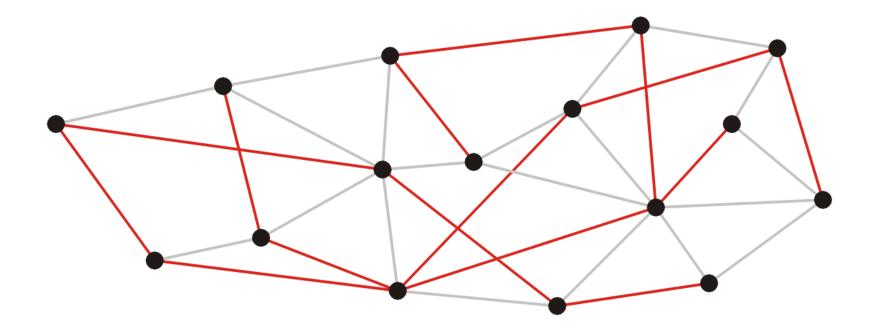
• This graph has 16 vertices and 35 edges

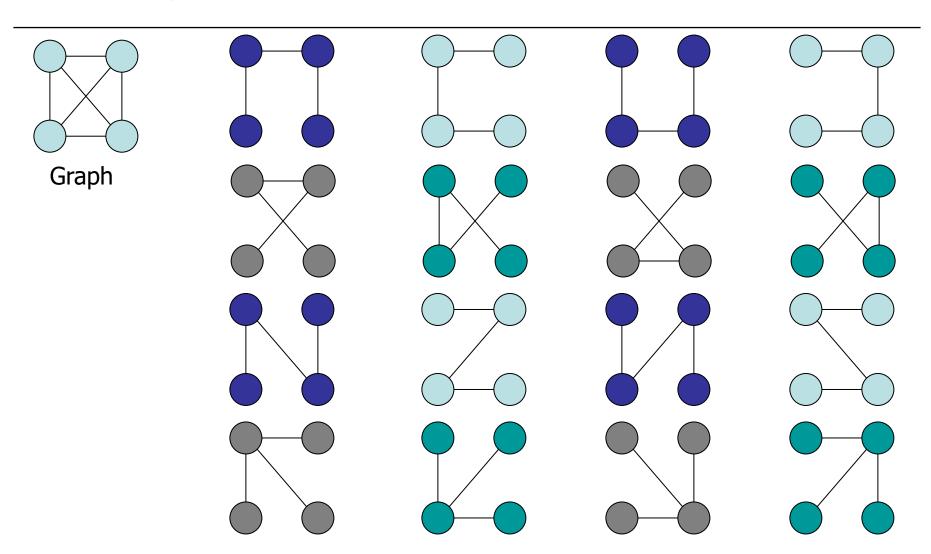


• These 15 edges form a spanning tree



• As do these 15 edges

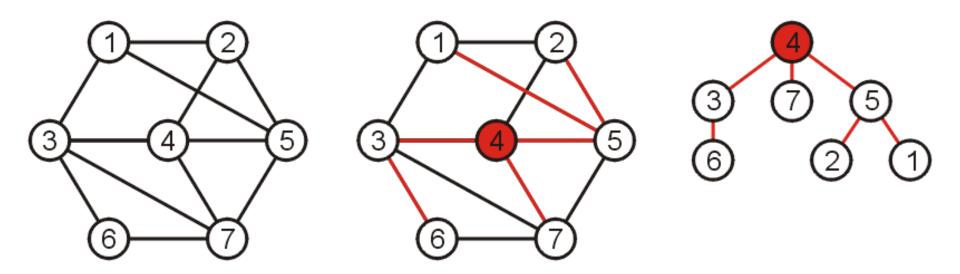




All 16 of its Spanning Trees

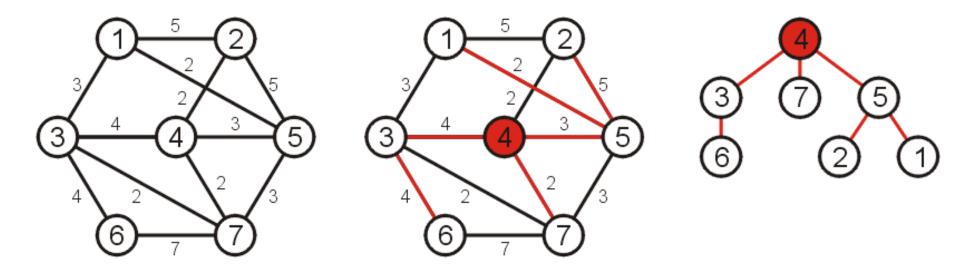
Spanning Trees

- Why such a collection of |V|-1 edges is called a tree?
 - If any vertex is taken to be the root, we form a tree by treating the adjacent vertices as children, and so on...



Spanning Tree on Weighted Graphs

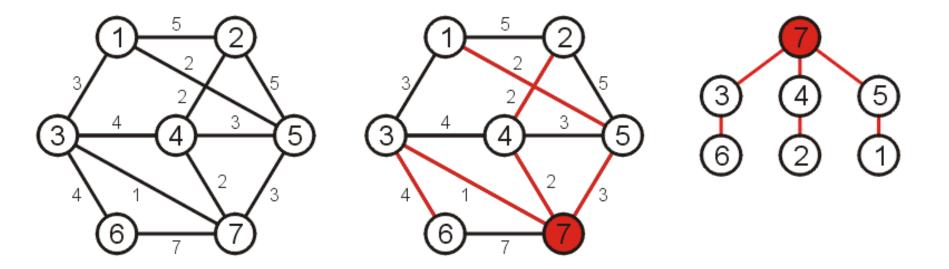
- Weight of a spanning tree
 - Sum of the weights on all the edges which comprise the spanning tree



• The weight of this spanning tree is 20

Minimum Spanning Tree (MST)

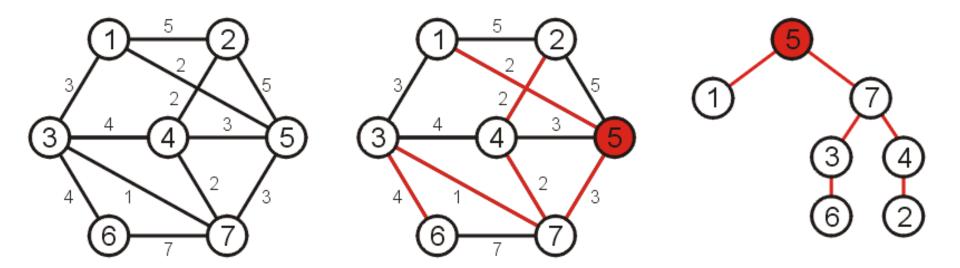
- Spanning tree that minimizes the weight
 - Such a tree is termed a minimum spanning tree



• The weight of this spanning tree is 14

Minimum Spanning Tree (MST)

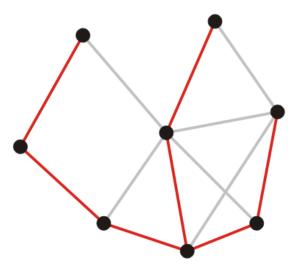
- If a different vertex is used as the root
 - A different tree is obtained
 - However, this is simply the result of one or more rotations



Spanning Forest

- Suppose that a graph is composed of N connected sub-graphs
- A spanning forest is a collection of N spanning trees
 - One for each connected sub-graph



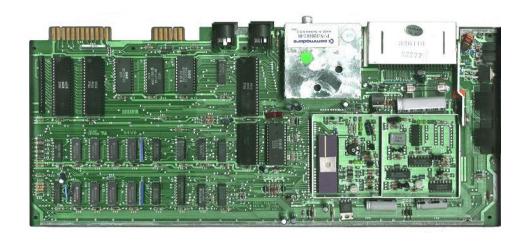




- A minimum spanning forest
 - A collection of N minimum spanning trees
 - One for each connected vertex-induced sub-graph

Applications

- Consider supplying power to
 - All circuit elements on a board
 - A number of loads within a building
- A minimum spanning tree will give the lowest-cost solution





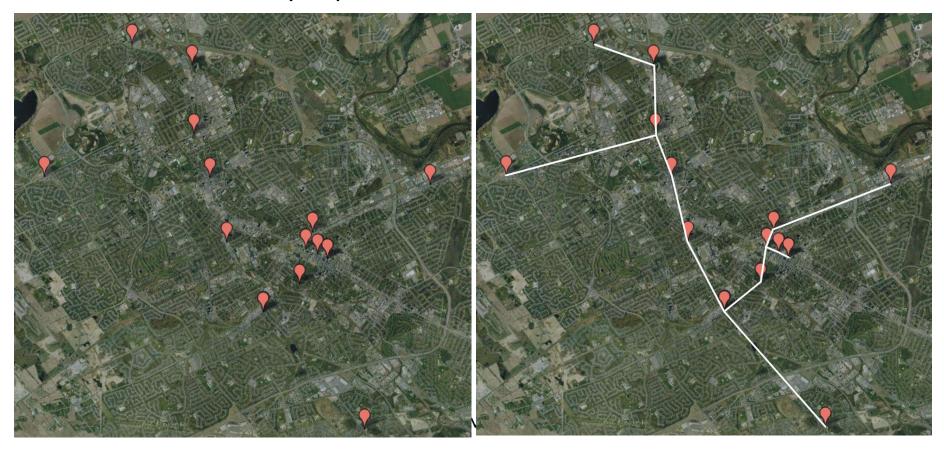
Application

- First application of a minimum spanning tree algorithm was by the Czech mathematician Otakar Borůvka
 - Designed electricity grid in Morovia in 1926



Application

- Consider attempting to find the best means of connecting a number of Local Area Networks (LANs)
 - Minimize the number of bridges
 - Costs not strictly dependent on distances



Algorithms For Obtaining MST

- Kruskal's Algorithm
- Prim's Algorithm
- Boruvka's Algorithm

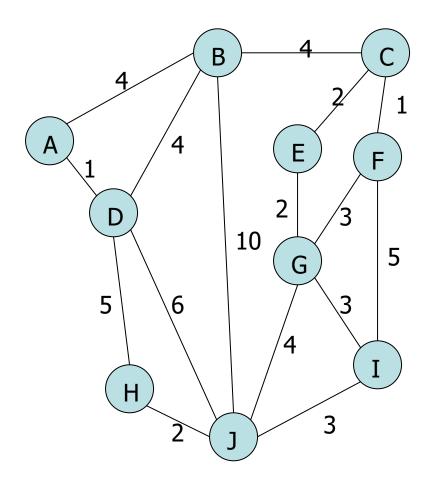
- Kruskal's algorithm creates a forest of trees
- Initially forest consists of N single node trees (and no edges)
- Sorts the edges by weight and goes through the edges from least weight to greatest weight
- At each step one edge (with least weight) is added so that it joins two trees together
 - As long as the addition does not create a cycle

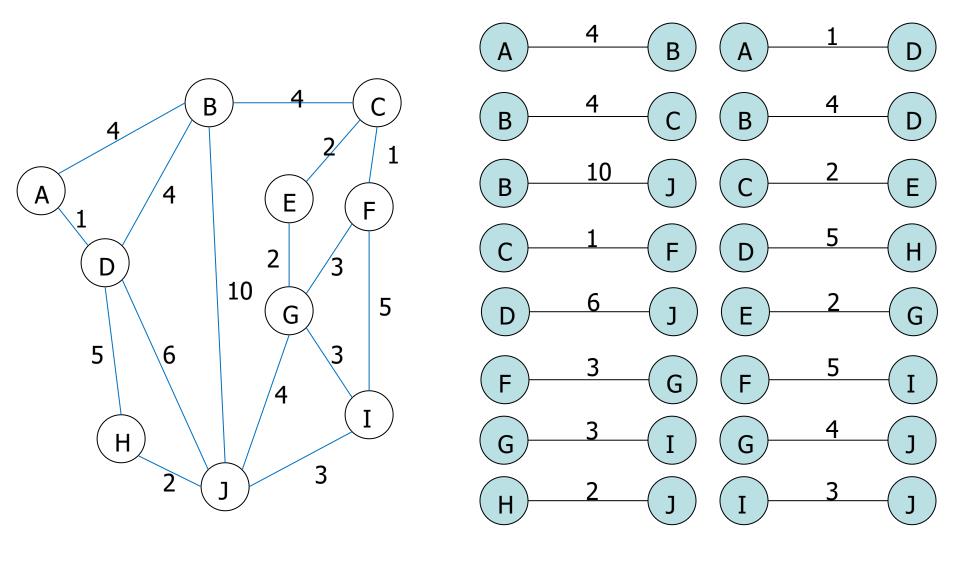
The halting conditions are as follows:

- 1. When |V| 1 edges have been added
 - In this case we have a minimum spanning tree
- 2. We have gone through all edges
 - A forest of minimum spanning trees on all connected sub-graphs

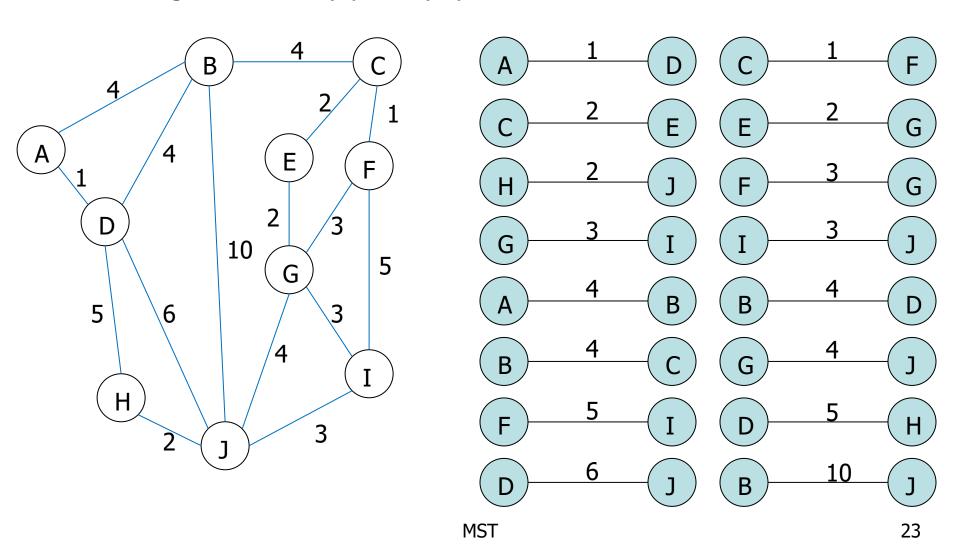
- 1. The forest is constructed with each node in a separate tree
- 2. The edges are placed in a priority queue
- 3. Until we've added n-1 edges (assumption: connected graph)
 - 1. Extract the cheapest edge from the queue
 - 2. If it forms a cycle, reject it
 - 3. Else add it to the forest. Adding it to the forest will join two trees
- Every step will have joined two trees in the forest together, so that at the end, there will only be one tree

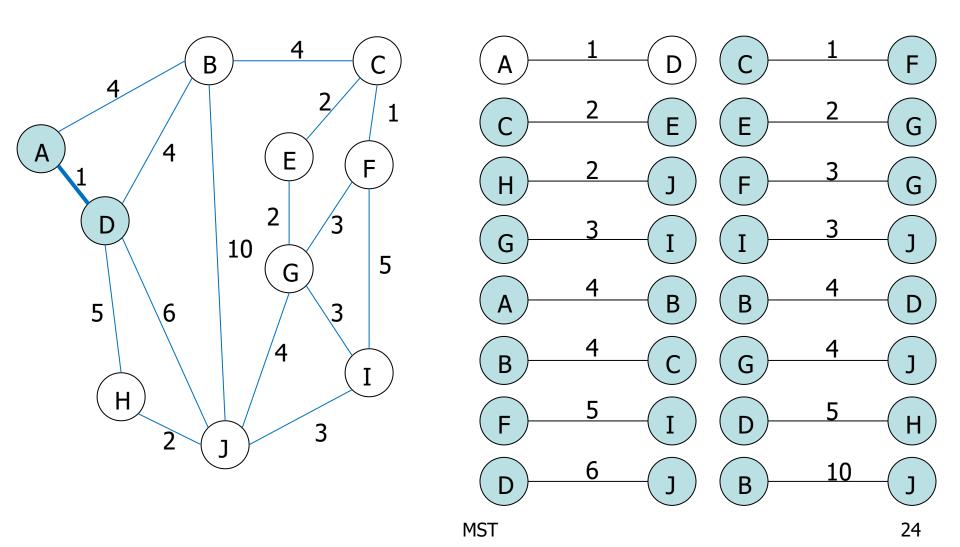
Complete Graph

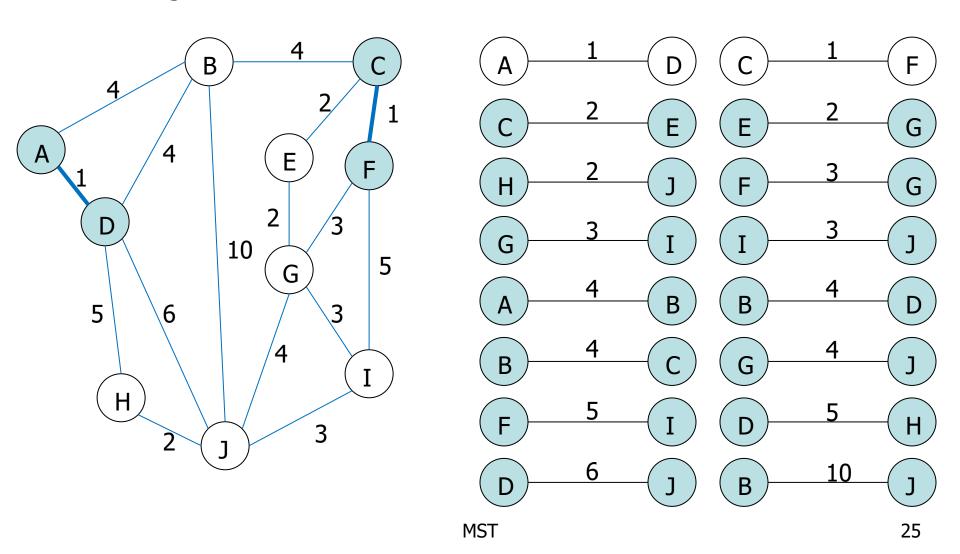


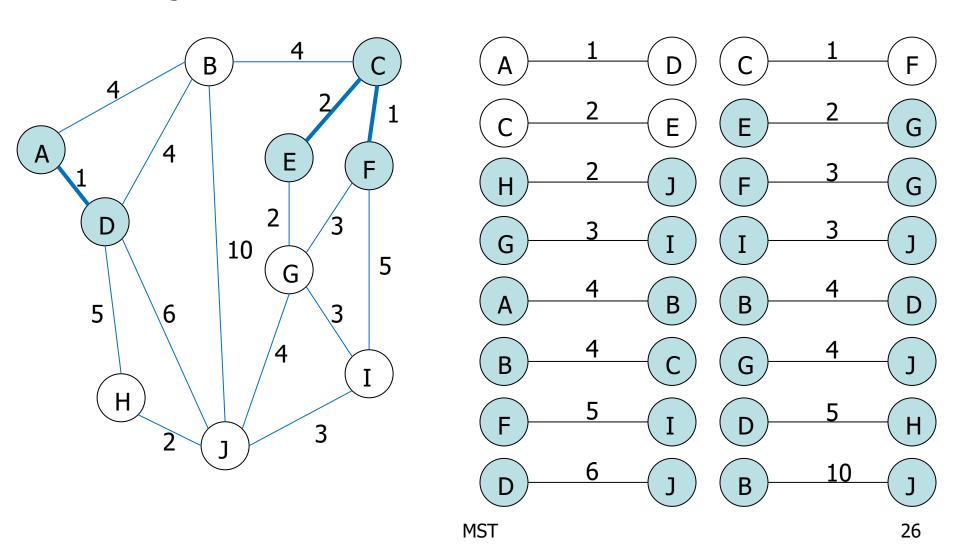


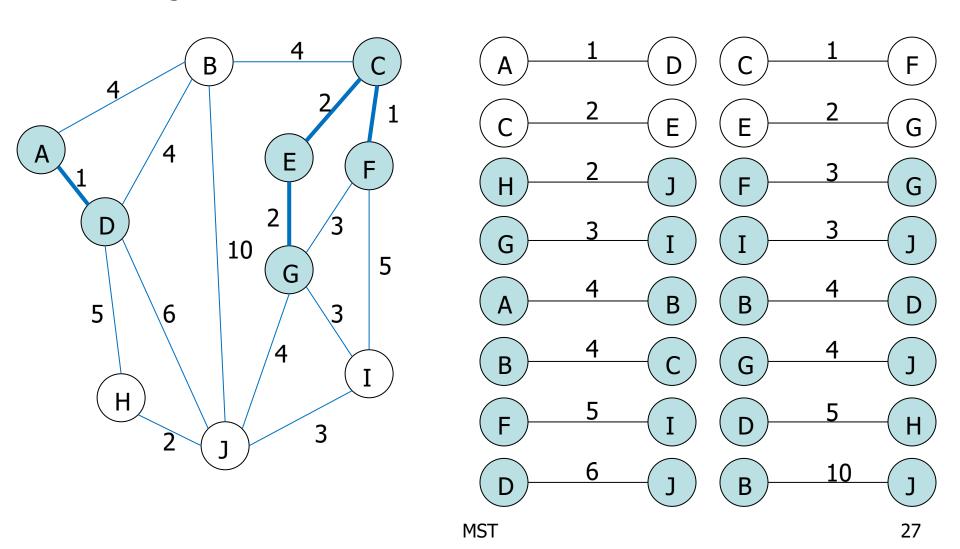
• Sort Edges: In reality priority queue is used

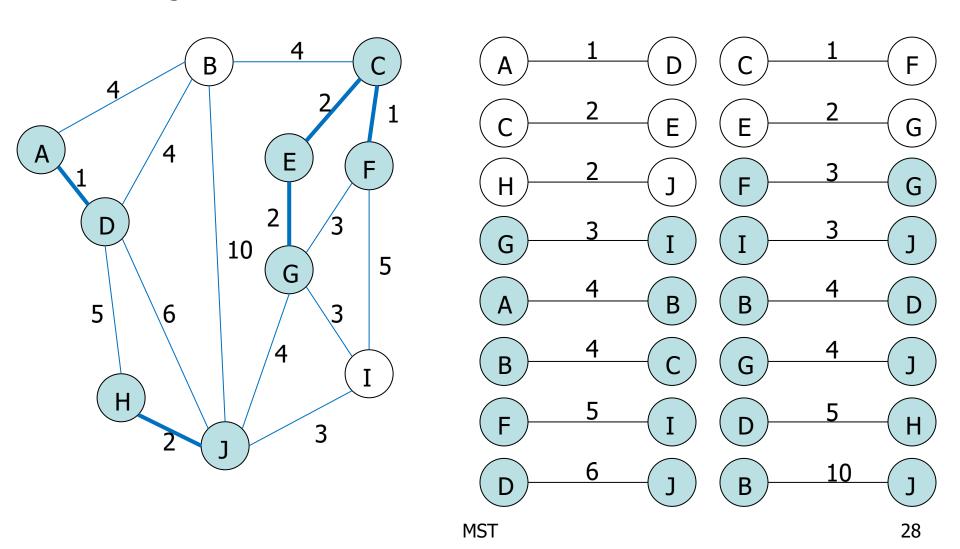


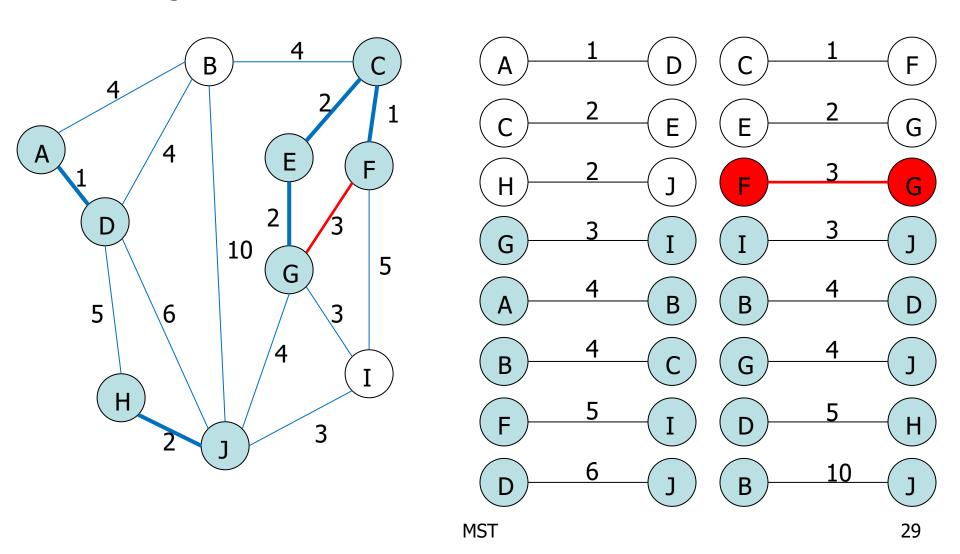


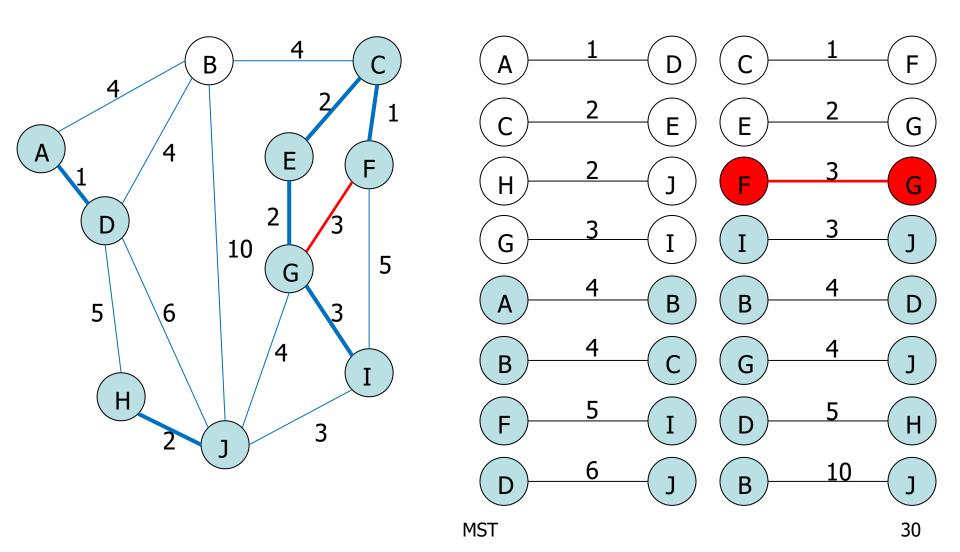


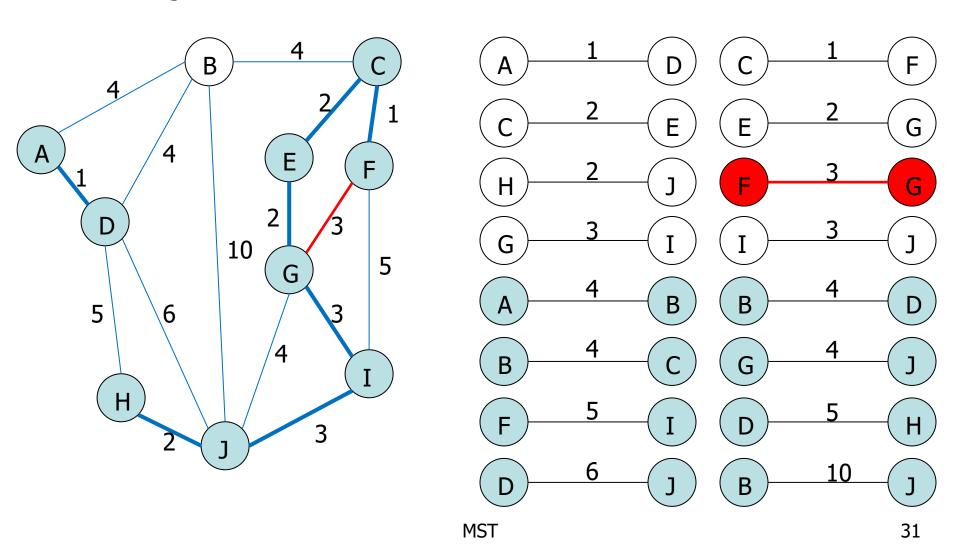


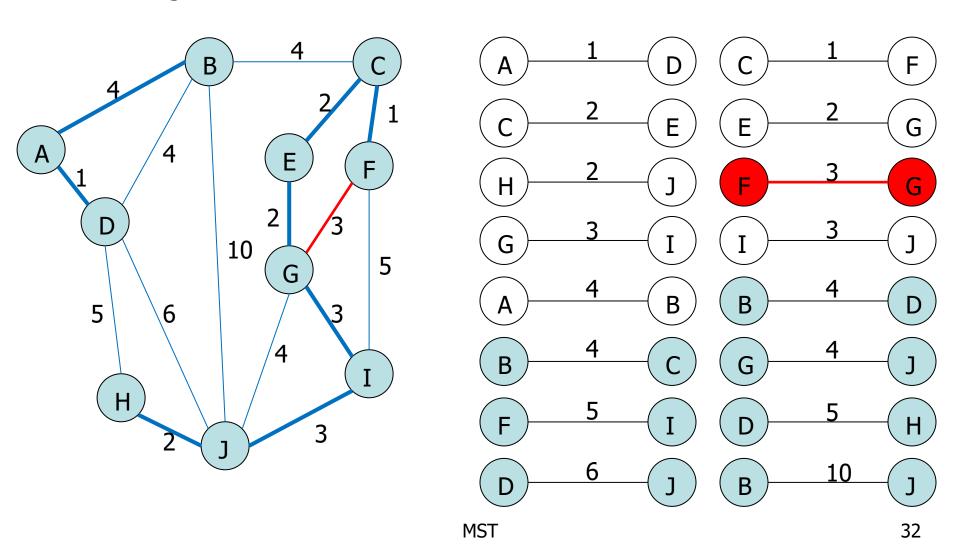


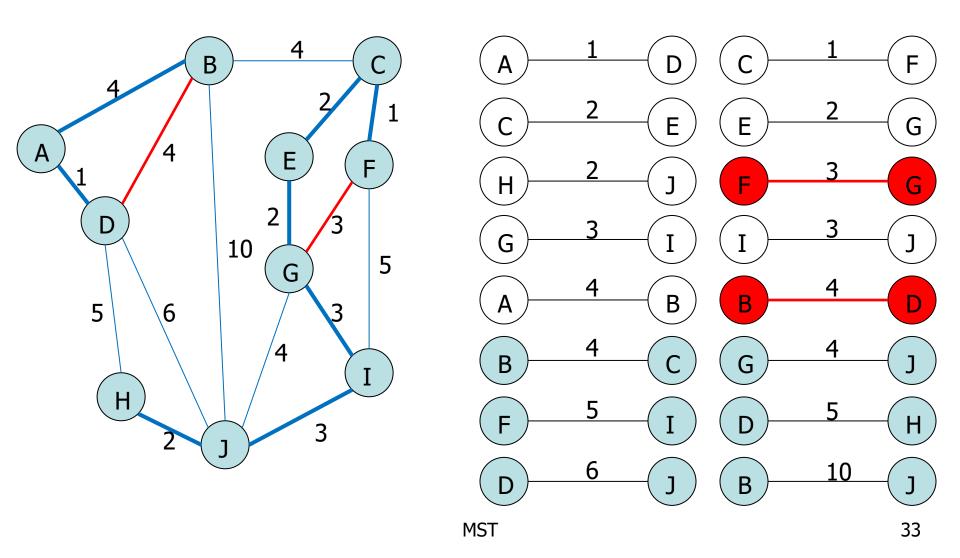


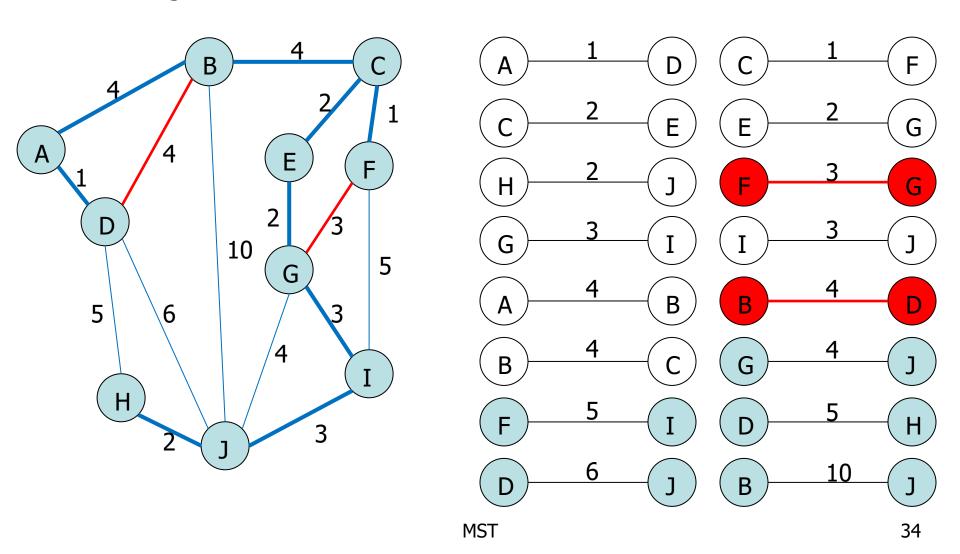




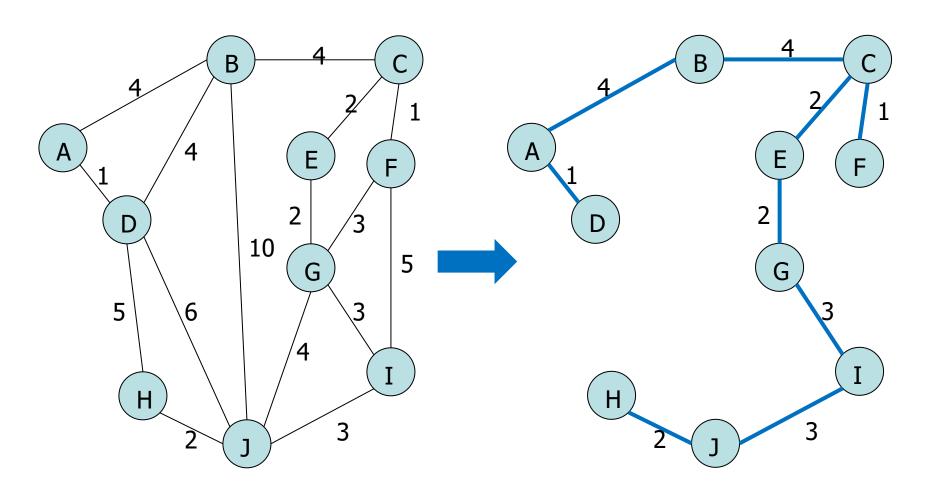




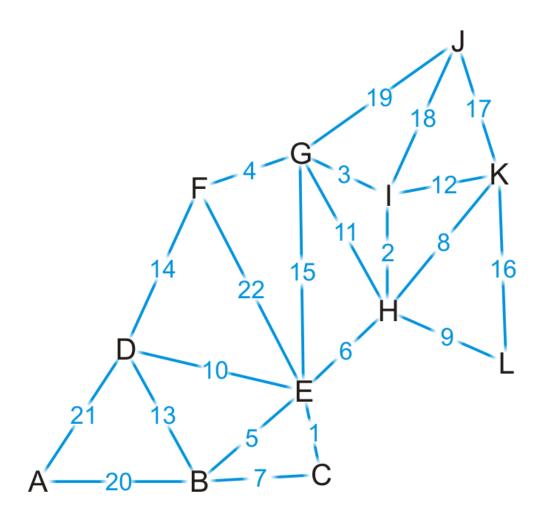




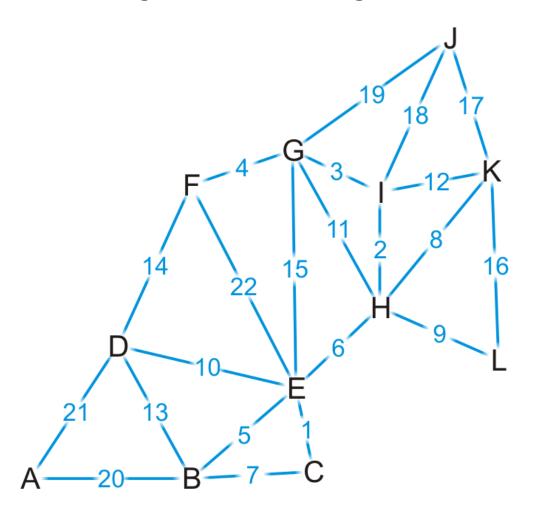
• Minimum spanning tree



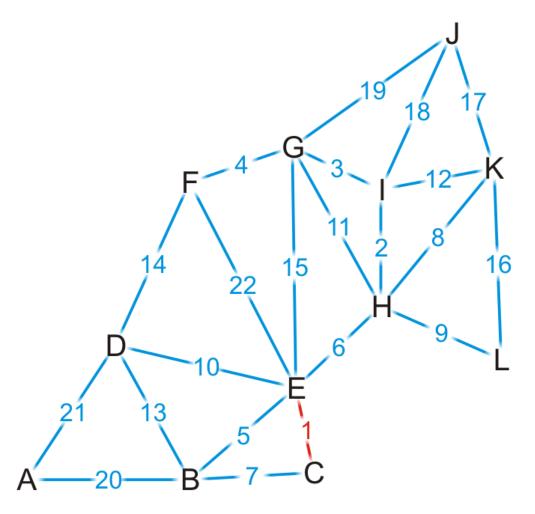
Complete graph



Sort edges based on weight



• We start by adding edge {C, E}



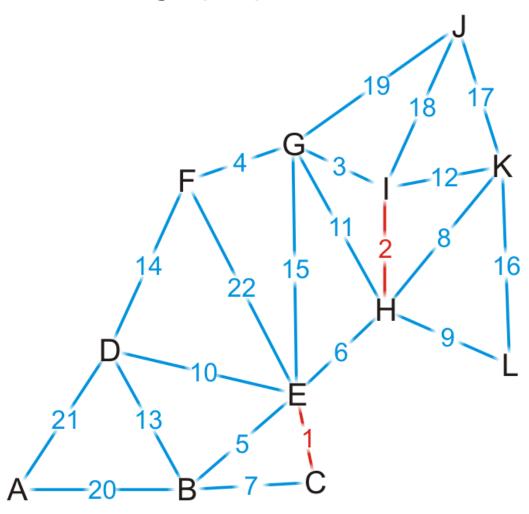
{C, E} → {H, I}

• We add edge {H, I}

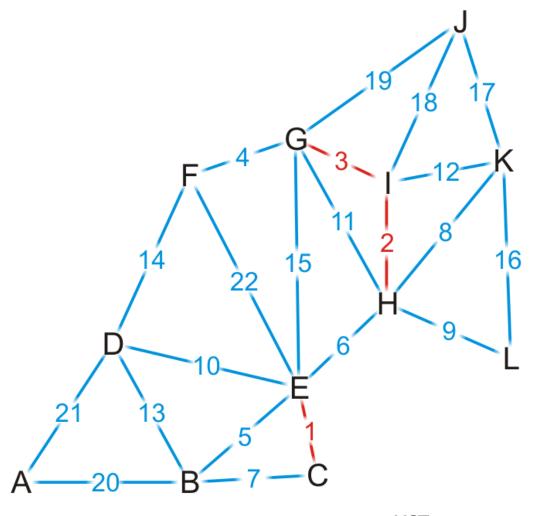


{A, D}

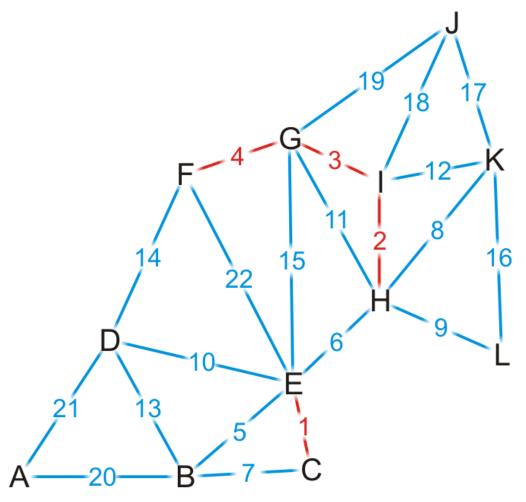
{E, F}



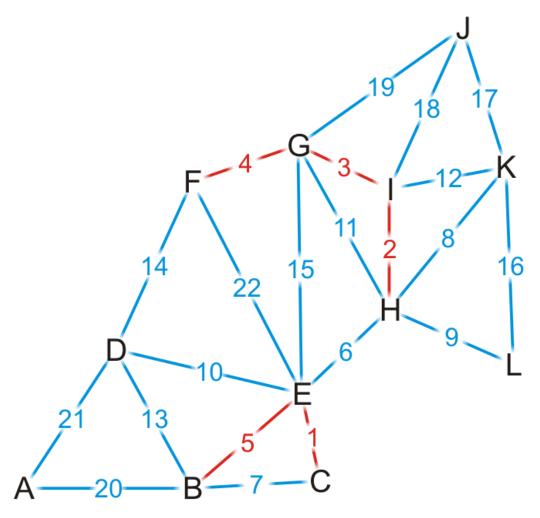
• We add edge {G, I}



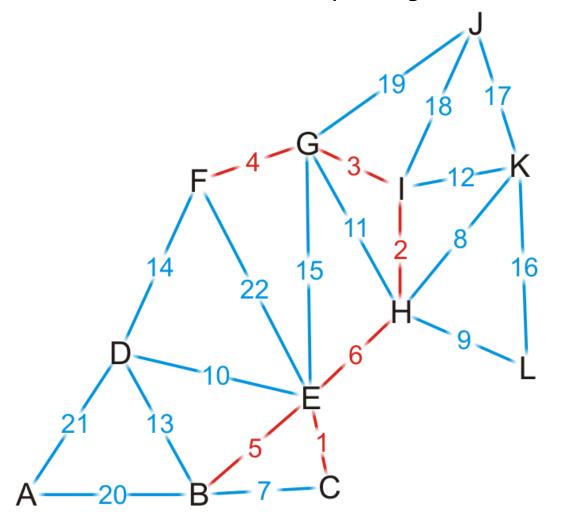
• We add edge {F, G}



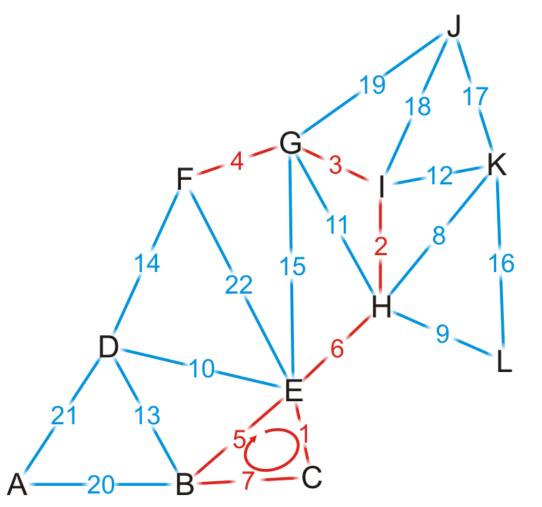
• We add edge {B, E}



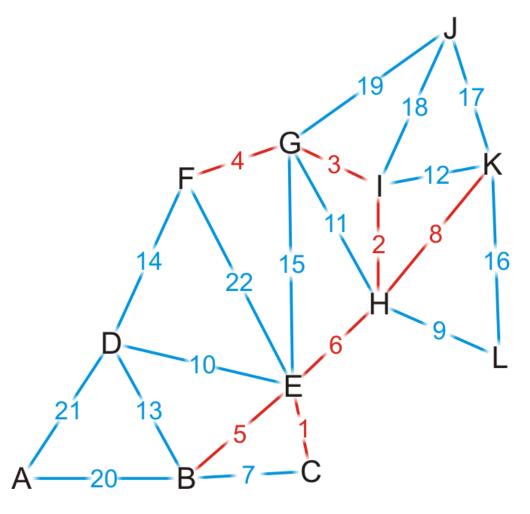
- We add edge {E, H}
 - This coalesces the two spanning sub-trees into one



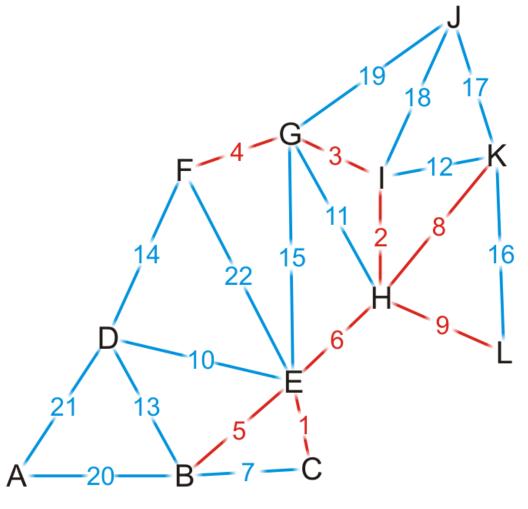
• We try adding {B, C}, but it creates a cycle



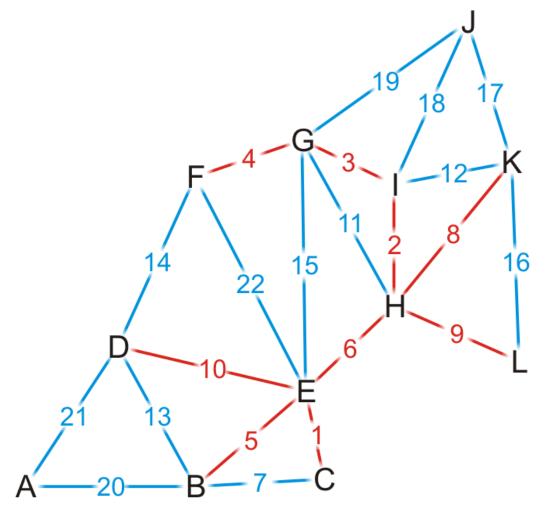
• We add edge {H, K}



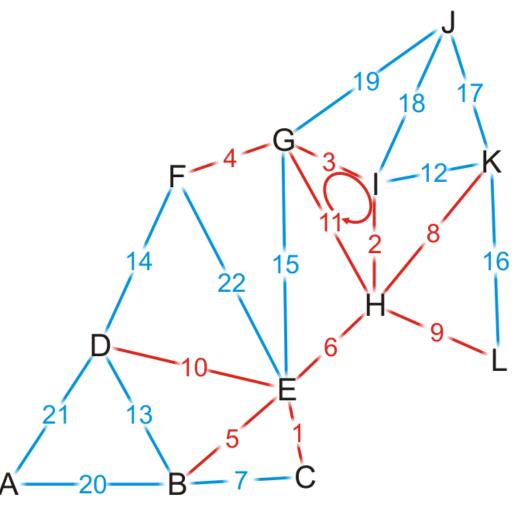
• We add edge {H, L}



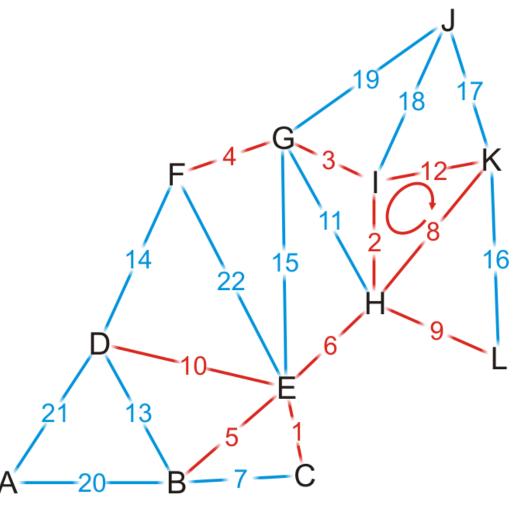
• We add edge {D, E}



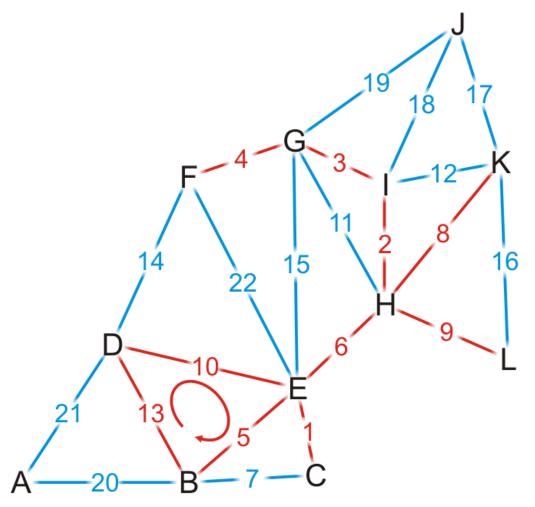
• We try adding {G, H}, but it creates a cycle



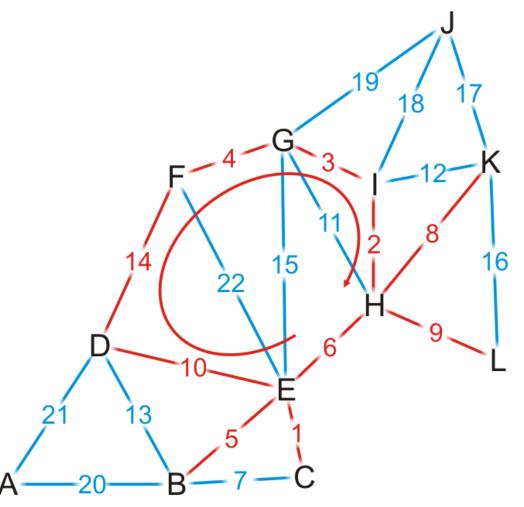
• We try adding {I, K}, but it creates a cycle



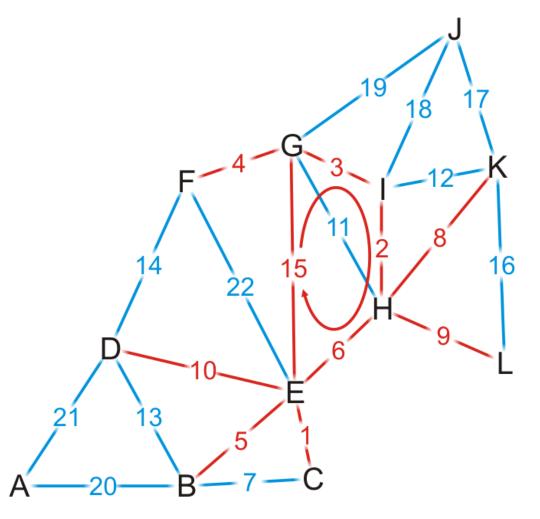
• We try adding {B, D}, but it creates a cycle



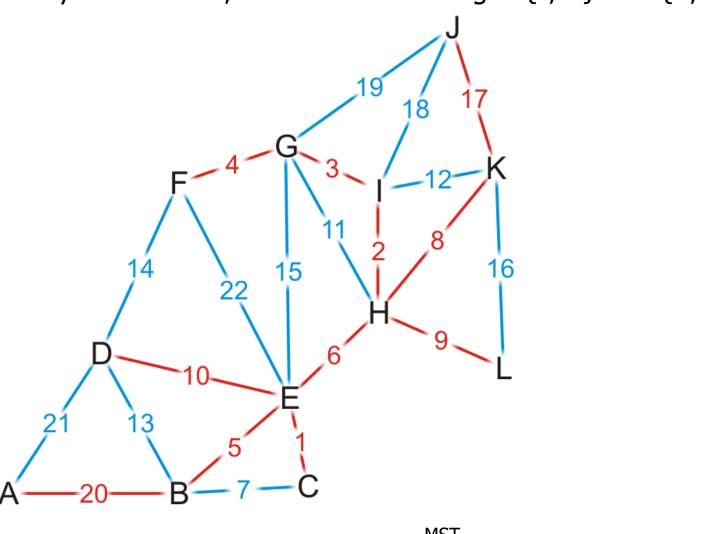
• We try adding {D, F}, but it creates a cycle



• We try adding {E, G}, but it creates a cycle



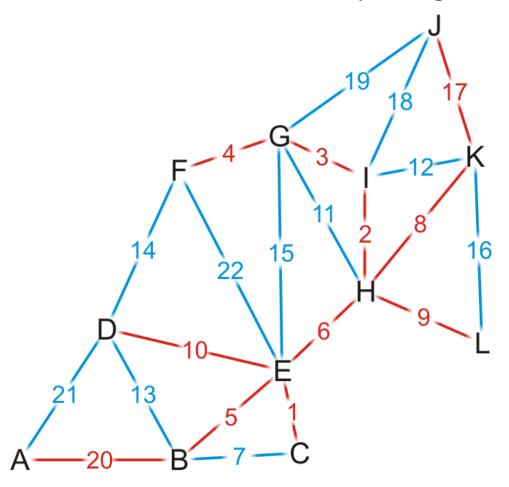
By observation, we can still add edges {J, K} and {A, B}



{H, I} {G, I} {F, G} {B, E} {E, H} {B, C} {H, K} {H, L} {D, E} {G, H} {I, K} {B, D} {D, F} {E, G} {K, L} {J, K} {A, B} {A, D} {E, F}

{C, E}

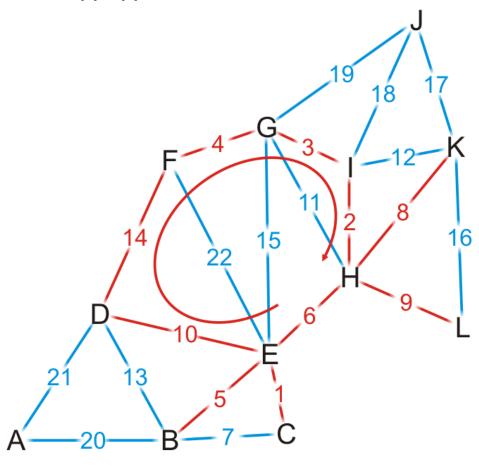
- Having added {A, B}, we now have 11 edges
 - We terminate the loop
 - We have our minimum spanning tree



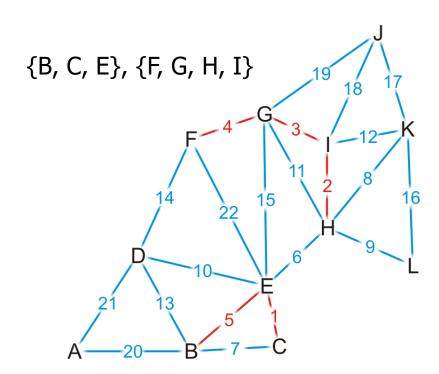
```
{C, E}
{H, I}
{G, I}
{F, G}
{B, E}
{E, H}
{B, C}
{H, K}
{H, L}
{D, E}
{G, H}
{I, K}
{B, D}
{D, F}
{E, G}
{K, L}
{J, K}
{A, B}
{A, D}
{E, F}
```

Detecting a Cycle

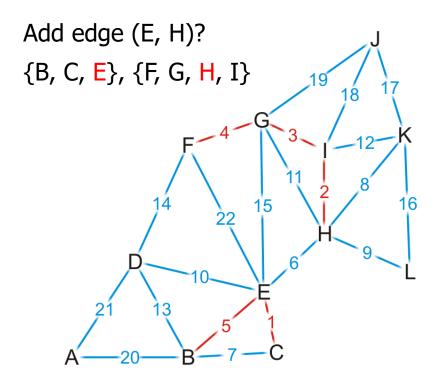
- To determine if a cycle is created, we could perform a traversal
 - A run-time of O(|V|)



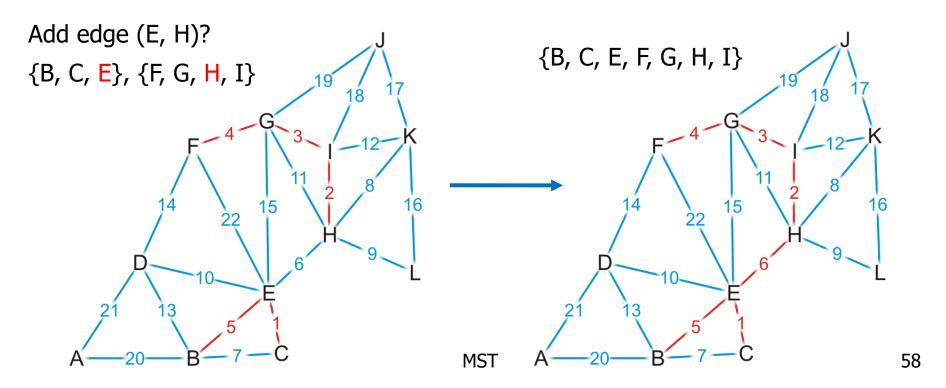
• Consider edges in the same connected sub-graph as forming a set



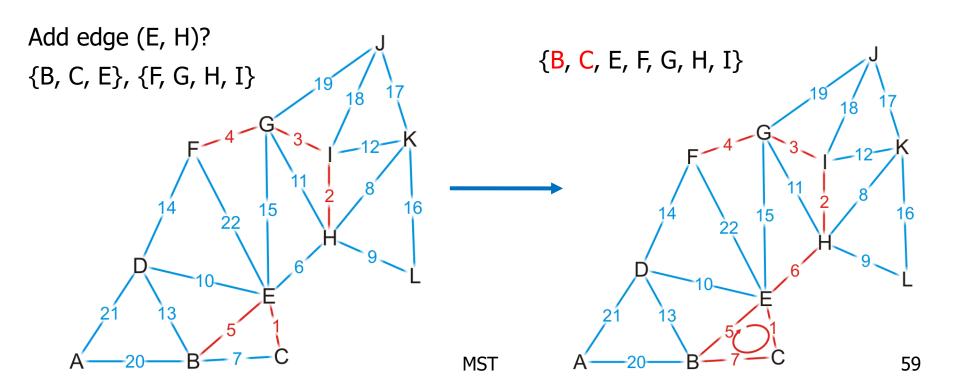
- Consider edges in the same connected sub-graph as forming a set
- If the vertices of the next edge are in different sets
 - Take the union of the two sets



- Consider edges in the same connected sub-graph as forming a set
- If the vertices of the next edge are in different sets
 - Take the union of the two sets



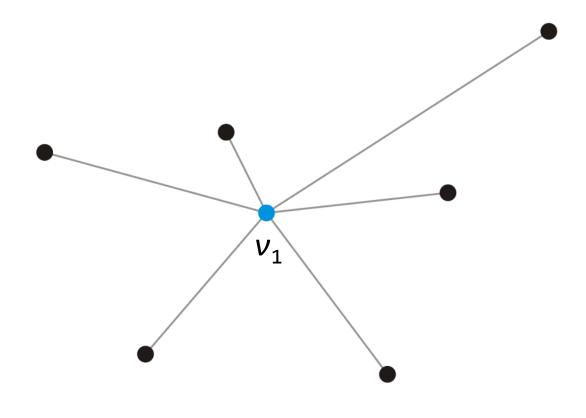
- Consider edges in the same connected sub-graph as forming a set
- If the vertices of the next edge are in different sets
 - Take the union of the two sets
- Do not add an edge if both vertices are in the same set



Prim's Algorithm

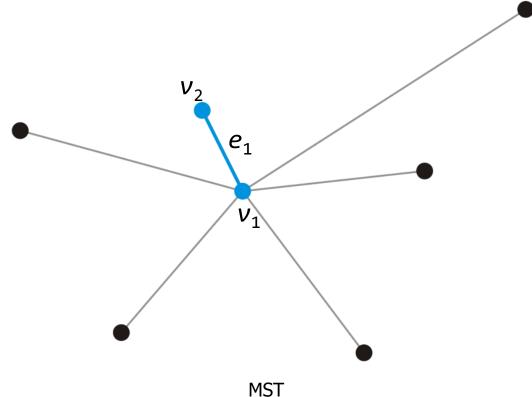
Idea

- Suppose we take a vertex v₁
 - It forms a minimum spanning tree on one vertex



Idea

- Add that adjacent vertex v_2 that has a connecting edge e_1 of minimum weight
 - This forms a minimum spanning tree on our two vertices
 - e₁ must be in any minimum spanning tree containing the vertices v₁ and v_2



62

Prim's Algorithm

- Start with an arbitrary vertex to form a minimum spanning tree on one vertex
- At each step, add a vertex v not yet in the minimum spanning tree
 - Though an edge with least weight that connects v to the existing minimum spanning sub-tree
- Continue until we have n 1 edges and n vertices

Prim's Algorithm – Pseudocode

```
MST-Prim(G, w, r) { // w is the weight matrix of edges, r is root
    Q = V[G]; // Insert graph vertices to a Queue
    for each u \in Q // Set distance of all vertices as \infty
        key[u] = \infty;
    key[r] = 0; // Distance of root is set to 0
    p[r] = NULL; // Parent of root is NULL
    while (Q not empty) {
        u = ExtractMin(Q); // Get the vertex u with min key[u]
        for each v ∈ Adj[u] { // Adj is the adjacency list
             if (v \in Q \text{ and } w(u,v) < \text{key}[v]) 
                 p[v] = u;
                 \text{key}[v] = w(u,v); // \text{ weight of an edge } (u,v)
```

Prim's Algorithm – Data Structure

- Associate with each vertex two items of data
 - The minimum distance to the partially constructed tree
 - > For a given vertex v, key[v] represent minimum distance
 - Pointer to the vertex that will form the parent node in resulting tree
 - > For a given vertex v, p[v] represent parent node

Initialization

- Set the distance of all vertices as ∞ , e.g., for all u ∈ G, key[u]= ∞
- Set all vertices to being unvisited
 - ➤ Add vertices to the Queue
- Select a root node and set its distance as 0, i.e., key[r] = 0
- Set the parent pointer of root to NULL, i.e., p[r] = NULL

```
MST-Prim(G, w, r)
    Q = V[G];
    for each u \in Q
                           14
         key[u] = \infty;
    key[r] = 0;
    p[r] = NULL;
    while (Q not empty)
                                  Run on example graph
         u = ExtractMin(Q);
         for each v \in Adj[u]
              if (v \in Q \text{ and } w(u,v) < \text{key}[v])
                   p[v] = u;
                   key[v] = w(u,v);
```

```
MST-Prim(G, w, r)
    Q = V[G];
    for each u \in Q
                          14
         key[u] = \infty;
    key[r] = 0;
    p[r] = NULL;
                                    00
    while (Q not empty)
                                  Run on example graph
         u = ExtractMin(Q);
         for each v \in Adj[u]
              if (v \in Q \text{ and } w(u,v) < \text{key}[v])
                   p[v] = u;
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```

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MST-Prim(G, w, r)
    Q = V[G];
    for each u \in Q
         key[u] = \infty;
    key[r] = 0;
     p[r] = NULL;
                                     \infty
    while (Q not empty)
                                    Pick a start vertex r
         u = ExtractMin(Q);
         for each v \in Adj[u]
              if (v \in Q \text{ and } w(u,v) < \text{key}[v])
                   p[v] = u;
                   key[v] = w(u,v);
```

```
MST-Prim(G, w, r)
    Q = V[G];
    for each u \in Q
         key[u] = \infty;
    key[r] = 0;
    p[r] = NULL;
                                     \infty
    while (Q not empty)
                                   Black vertices have been
         u = ExtractMin(Q);
                                       removed from Q
         for each v \in Adj[u]
              if (v \in Q \text{ and } w(u,v) < \text{key}[v])
                   p[v] = u;
                   key[v] = w(u,v);
```

```
MST-Prim(G, w, r)
    Q = V[G];
    for each u \in Q
         key[u] = \infty;
    key[r] = 0;
    p[r] = NULL;
                                    3
    while (Q not empty)
                                 Black arrows indicate parent
         u = ExtractMin(Q);
                                          pointers
         for each v \in Adj[u]
              if (v \in Q \text{ and } w(u,v) < \text{key}[v])
                   p[v] = u;
                   key[v] = w(u,v);
```

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MST-Prim(G, w, r)
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         u = ExtractMin(Q);
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                   p[v] = u;
                   key[v] = w(u,v);
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         u = ExtractMin(Q);
         for each v \in Adj[u]
              if (v \in Q \text{ and } w(u,v) < \text{key}[v])
                   p[v] = u;
                   key[v] = w(u,v);
```

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MST-Prim(G, w, r)
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                   p[v] = u;
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```

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         u = ExtractMin(Q);
         for each v \in Adj[u]
              if (v \in Q \text{ and } w(u,v) < \text{key}[v])
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MST-Prim(G, w, r)
    Q = V[G];
    for each u \in Q
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         key[u] = \infty;
    key[r] = 0;
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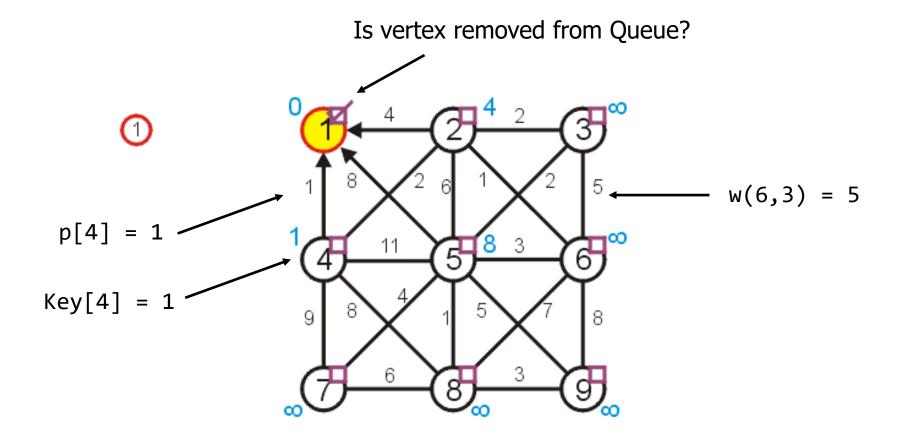
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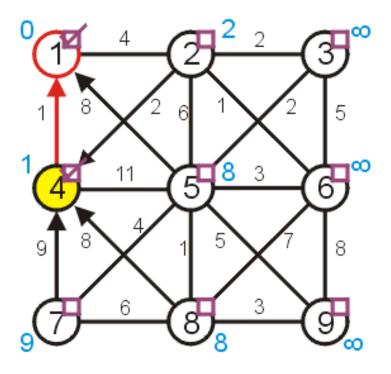
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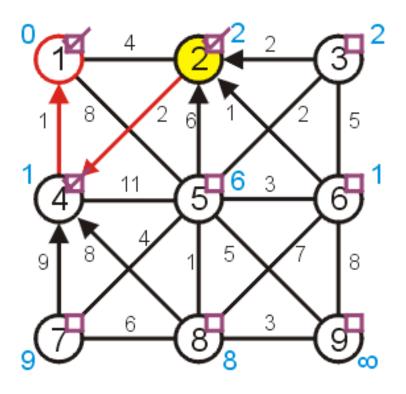
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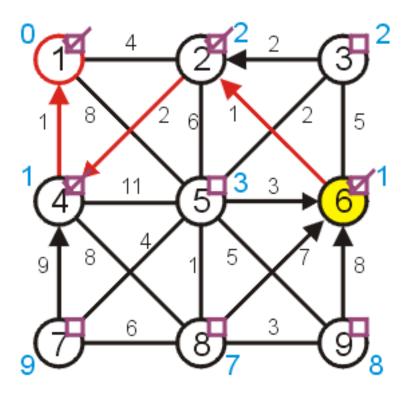


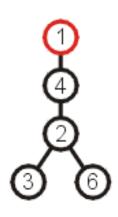


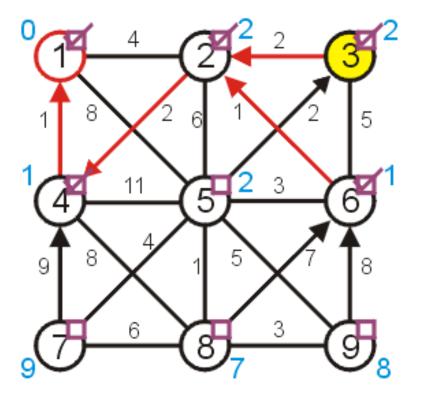


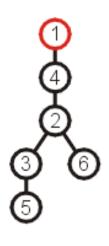


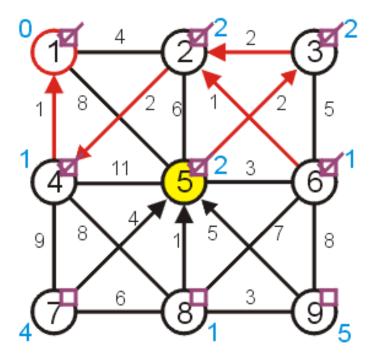


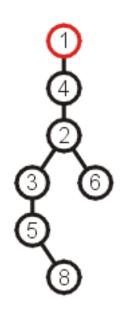


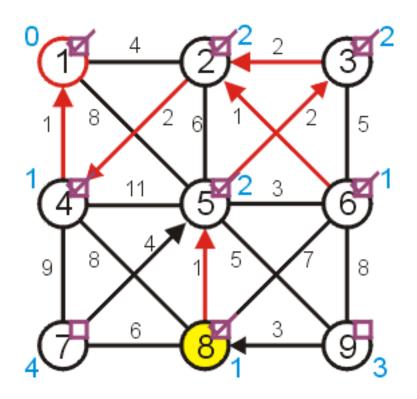


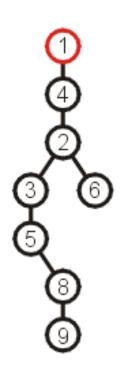


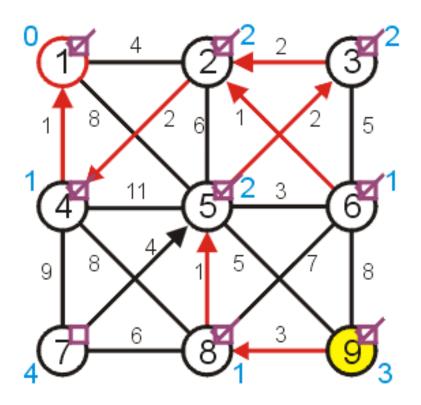


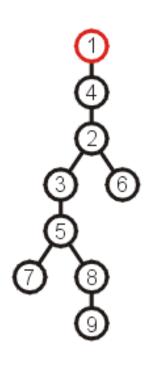


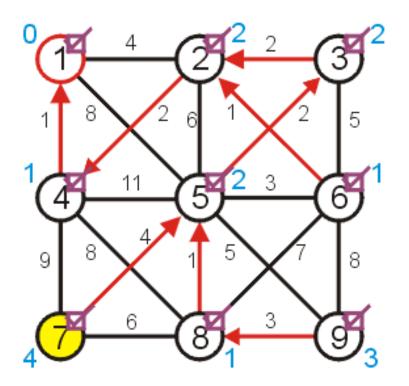


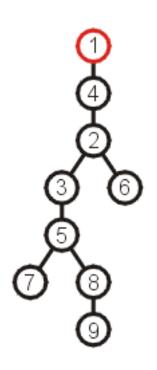


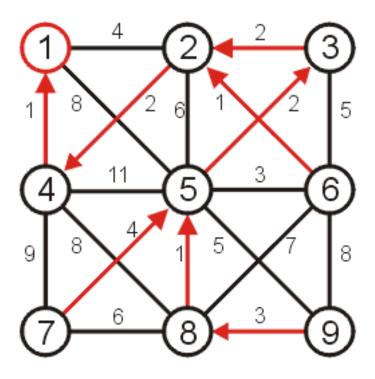












Kruskal's Algorithm vs Prim's Algorithm

- In prim's algorithm, graph must be a connected
- Kruskal's algorithm can function on disconnected graphs too
- Prim's algorithm is significantly faster for dense graphs with more number of edges than vertices
- Kruskal's algorithm runs faster in the case of sparse graphs

Any Question So Far?

