

Ayudantía 3: (Guía Gauss)

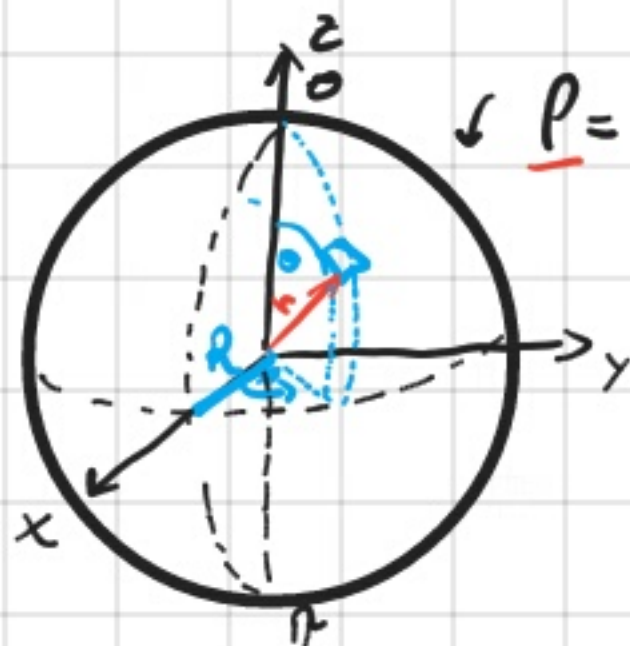
(1) Ley de Gauss: $\oint \vec{E} \cdot d\vec{S} = \frac{q_{enc}}{\epsilon_0}$

- $Q_T = ?$

- $\vec{E}(r) = ?$

- $V(r) = ?$

↓ $\rho = \rho_0 (1 - r^2/R^2)$; $r \in [0, R]$



(a)

$$dq = \rho dV$$

$$dq = \rho_0 (1 - r^2/R^2) \overset{\text{J}_\theta}{(r^2 \sin\theta)} dr d\theta d\phi \quad / \iiint$$

$$\int_0^{Q_T} dq = \int_0^R \int_0^\pi \int_0^{2\pi} \rho_0 (1 - \frac{r^2}{R^2}) r^2 \sin\theta dr d\theta d\phi$$

$$Q_T = \rho_0 \int_0^R (1 - \frac{r^2}{R^2}) r^2 dr \int_0^\pi \sin\theta d\theta \int_0^{2\pi} d\phi$$

→ $dq = \rho dV$
 $dq = \sigma dS$
 $dq = \lambda dr$

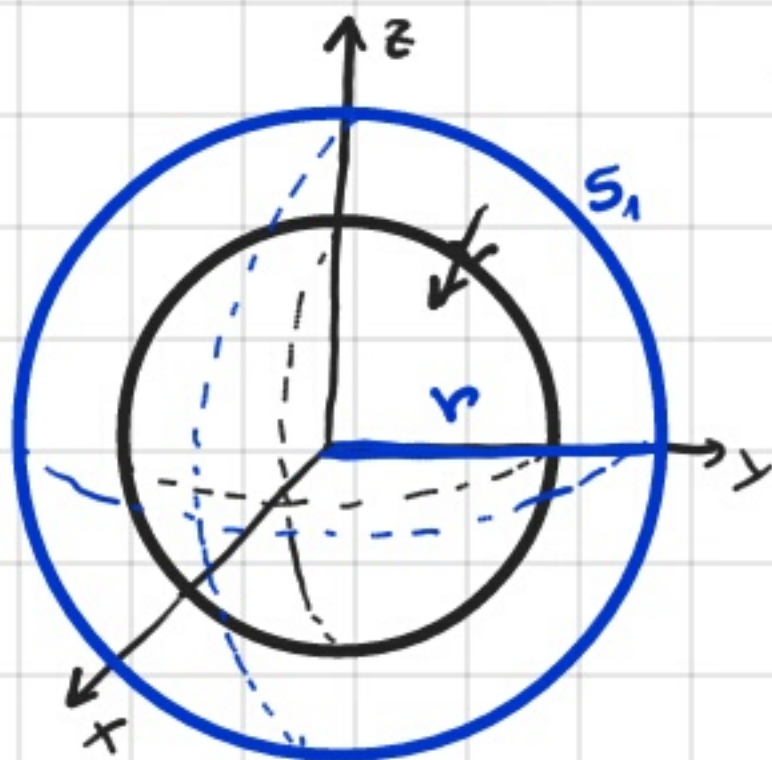
$$Q_T = \rho_0 \int_0^R \left(1 - \frac{r^2}{R^2}\right) r^2 dr (2) (2\pi)$$

$$Q_T = 4\pi\rho_0 \int_0^R \left(r^2 - \frac{r^4}{R^2}\right) dr$$

$$Q_T = 4\pi\rho_0 \left(\frac{r^3}{3} \Big|_0^R - \frac{r^5}{5} \cdot \frac{1}{R^2} \Big|_0^R \right)$$

$$Q_T = 4\pi\rho_0 \left(\frac{R^3}{3} - \frac{R^3}{5} \right)$$

$$Q_T = \frac{8\pi\rho_0 R^3}{15} \checkmark$$



• Sea la region $r \in [R, \infty[$

$$\oint \vec{E} \cdot d\vec{S} = \frac{q_{enc}}{\epsilon_0}$$

$$\int_{S_1} E \hat{r} \cdot \underline{r^2 \sin \theta d\phi d\theta \hat{r}} = \frac{q_{enc}}{\epsilon_0}$$

$$E \cdot 4\pi r^2 = \frac{Q_T}{\epsilon_0}$$

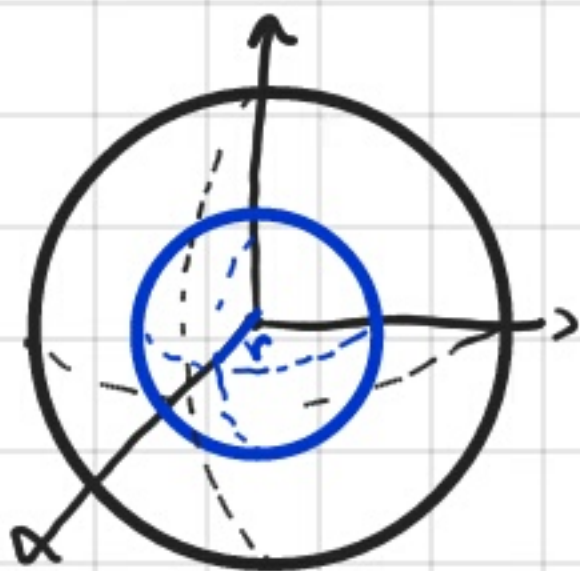
$$E = \frac{1}{4\pi r^2 \epsilon_0} \cdot \frac{8\pi \rho_0 R^3}{15}$$

$$E = \frac{2\rho_0 R^3}{15\epsilon_0 r^2}$$

$$\Rightarrow \vec{E}(r) = \frac{2\rho_0 R^3}{15\epsilon_0 r^2} \hat{r}$$

$$r \in [R, \infty[$$

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- Sea la region $r \in [0, R]$

$$\oint \vec{E}(r) \cdot d\vec{S} = \frac{q_{enc}}{\epsilon_0} \quad / \quad \begin{aligned} \vec{E}(\vec{r}) &= E \hat{r} \\ d\vec{S} &= r^2 \sin\theta \, d\phi \, d\theta \, \hat{r} \end{aligned}$$

$$E 4\pi r^2 = \frac{1}{\epsilon_0} \int_V \rho \, dV$$

$$E = \frac{1}{4\pi r^2 \epsilon_0} \int_0^r \int_0^\pi \int_0^{2\pi} \rho_0 \left(1 - \frac{r^2}{R^2}\right) r^2 \sin\theta \, d\phi \, d\theta \, dr$$

$$E = \frac{1}{4\pi r^2 \epsilon_0} \cdot 4\pi \int_0^r \rho_0 \left(1 - \frac{r^2}{R^2}\right) r^2 \, dr$$

$$= \frac{\rho_0}{r^2 \epsilon_0} \left(\frac{r^3}{3} - \frac{r^5}{5R^2} \right)$$

$$= \frac{\rho_0}{\epsilon_0} \left(\frac{r}{3} - \frac{r^3}{5R^2} \right)$$

$$\leadsto \vec{E}(r) = \frac{\rho_0}{\epsilon_0} \left(\frac{r}{3} - \frac{r^3}{5R^2} \right) \hat{r} \quad r \in [0, R]$$

$V(r)$:

- $r \in [R, \infty[$; $V(r \rightarrow \infty) \stackrel{!}{=} 0$

$$V_r = - \int_{\infty}^r \vec{E}(r) \cdot d\vec{r} + V(\cancel{r \rightarrow \infty})$$

$$= - \int_{\infty}^r \frac{2 \rho_0 R^3}{15 \epsilon_0} \frac{1}{r^2} \hat{r} \cdot d\vec{r} \hat{r}$$

$$= - \frac{2 \rho_0 R^3}{15 \epsilon_0} \int_{\infty}^r \frac{1}{r^2} dr$$

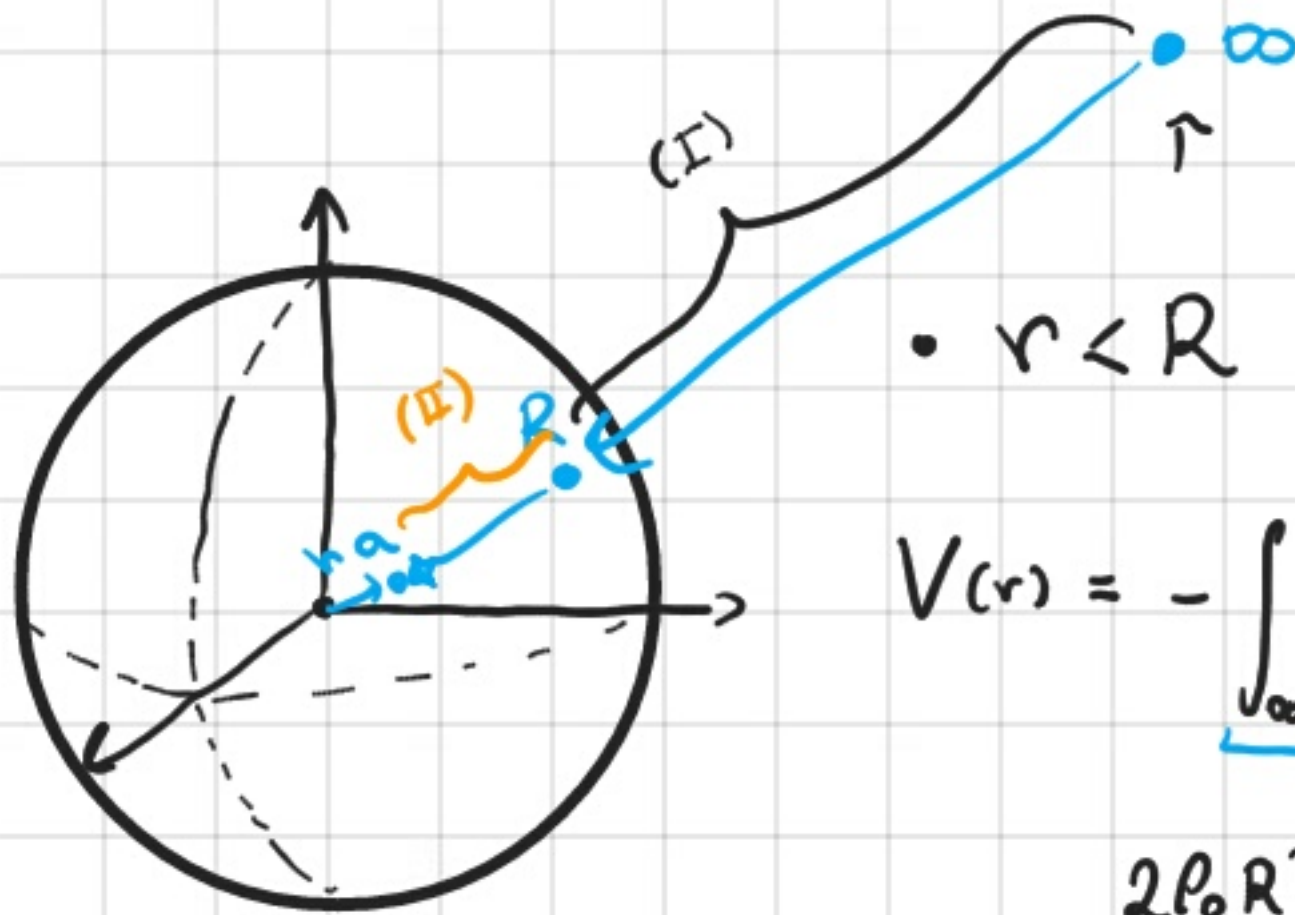
$$= - \frac{2 \rho_0 R^3}{15 \epsilon_0} \left(- \frac{1}{r} \right) \Big|_{\infty}^r$$

Nota : $\lim_{r \rightarrow \infty} \frac{1}{r} = 0$

$$V(r) = \frac{2 \rho_0 R^3}{15 \epsilon_0 r} \quad \parallel$$

$$V_a - V_b = \int_a^b \vec{E} \cdot d\vec{r}$$

$$V_a = - \int_{\text{ref}}^a \vec{E} \cdot d\vec{r} + V_{\text{ref}}$$



• $r < R$

$$V(r) = - \underbrace{\int_{\infty}^R \vec{E}(r \geq R) \cdot d\vec{r}}_{(I)} - \underbrace{\int_R^r \vec{E}(r < R) \cdot d\vec{r}}_{(II)}$$

$$\frac{2\rho_0 R^3}{15\epsilon_0 r} - \int_R^r \frac{\rho_0}{\epsilon_0} \left(\frac{r}{3} - \frac{r^3}{5R^2} \right) dr$$

$$\frac{2\rho_0 R^3}{15\epsilon_0 r} - \frac{\rho_0}{\epsilon_0} \left(\frac{1}{6} \cdot \frac{r^2}{r} - \frac{1}{20R^2} \cdot \frac{r^4}{r} \right)$$

$$V(r) = \frac{2\rho_0 R^3}{15\epsilon_0 r} - \frac{\rho_0}{\epsilon_0} \left(\frac{1}{6} (r^2 - R^2) - \frac{1}{20R^2} (r^4 - R^4) \right)$$

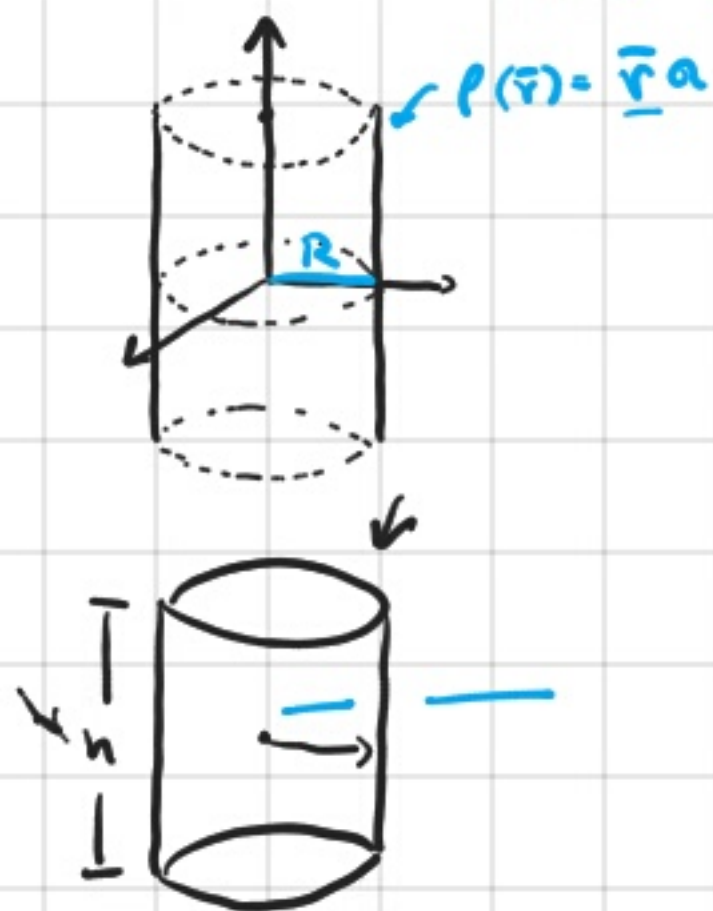
(3)

$$\bar{r} \in [0, R]$$

(a)

$$Q_T = \int_V \rho dV$$

$$(r \leq R)$$



$$Q_T = \int_0^R \int_0^{2\pi} \int_0^h (ra) r dr d\phi dz$$

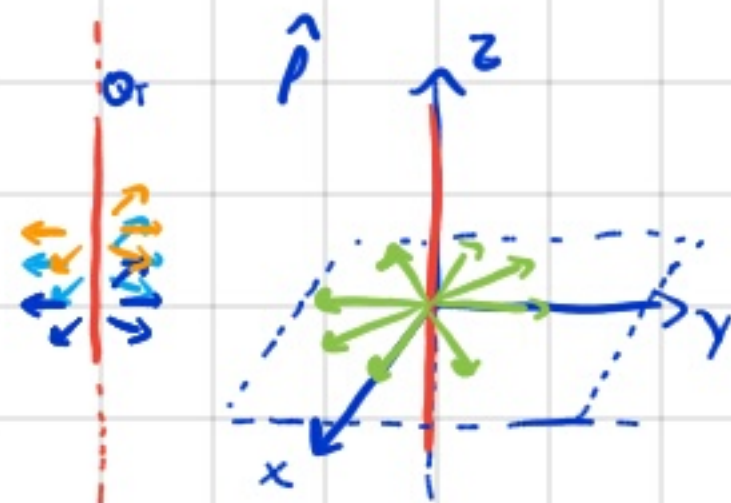
$$= a 2\pi h \int_0^R r^2 dr$$

$$= a \frac{2\pi R^3 h}{3}$$

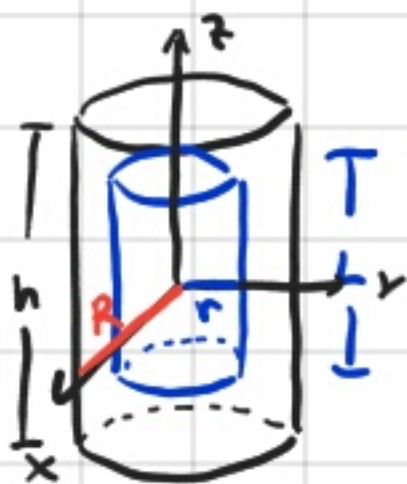
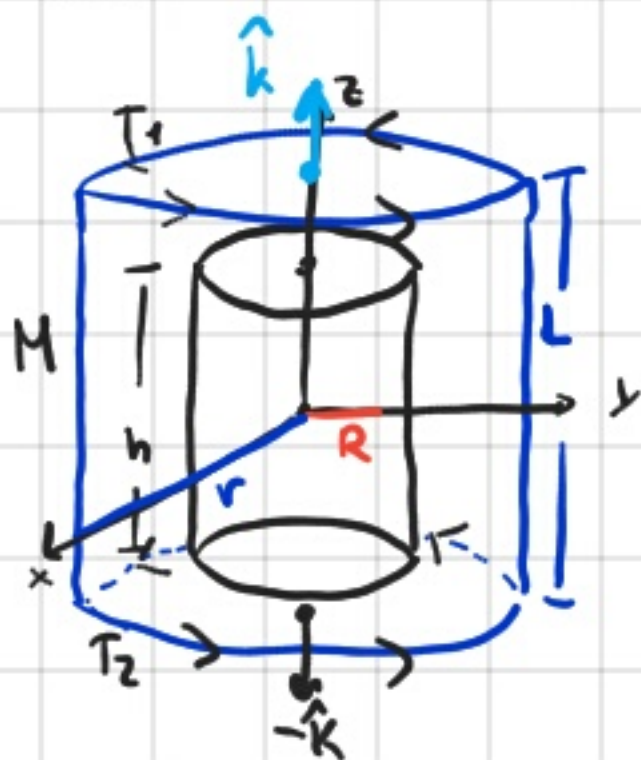
$$\vec{E}(r) = E(r) \hat{r}$$

$$Q_T : r \geq R$$

$$\begin{aligned} Q_T &= \int_V \rho dV \\ &= \int_V (0) dV \\ &= 0 \quad \text{!!} \quad \checkmark \end{aligned}$$



(b)



$$\oint \vec{E}(\vec{r}) \cdot d\vec{s} = \frac{q_{\text{enc}}}{\epsilon_0}$$

$$\int_{T_1} \vec{E}(\vec{r}) \cdot d\vec{s}_{T_1} + \int_M \vec{E}(\vec{r}) \cdot d\vec{s}_M + \int_{T_2} \vec{E}(\vec{r}) \cdot d\vec{s}_{T_2}$$

$$\int_{T_1} E(r) \hat{\rho} \cdot d\vec{s}_{T_1} \hat{k} + \int_M E(r) \hat{\rho} \cdot d\vec{s}_M \hat{\rho} - \int_{T_2} E(r) \hat{\rho} \cdot d\vec{s}_{T_2} \hat{k}$$

$$\int_M E(r) d\Omega = \frac{q_{\text{enc}}}{\epsilon_0}$$

$\vec{E}(\vec{r}) = E(r) \hat{\rho}$

$$\vec{E}(\vec{r}) \sim \begin{cases} \vec{E}(r < R) \\ \vec{E}(r > R) \end{cases} \quad \text{Torca}$$

$$V \sim \Downarrow$$