

Polymorphic algebraic effects: theoretical properties and implementation

Wiktor Kuchta

Chapter 1

Introduction

A programming language needs to be more than just a lambda calculus, capable only of functional abstraction and evaluation of expressions. Programs need to have an effect on the outside world and, thinking more locally, in our programs we would like to have fragments which do not merely reduce to a value in isolation, but affect the execution of surrounding code in interesting ways. This is what we call computational effects, the typical examples of which are: input/output, mutable state, exceptions, nondeterminism, and coroutines.

Today, we are at the mercy of programming language designers to include the effects we would like to use and make sure that they all interact with each other well. In recent years, however, a new approach, called *algebraic effects*, has emerged. Algebraic effects allow programmers to express all the usual computational effects as library code and use them in the usual direct style (as opposed to eg. monadic encodings, which do not always play well with the rest of the language and do not compose easily). These implementations of effects are instances of one concept and hence interact with each other predictably.

More concretely, algebraic effects may be thought of as resumable exceptions. We can *perform* an *operation*, just as we can raise an exception in a typical high-level programming language. The operation is then handled by the nearest enclosing *handler* for the specific operation. The handler receives the value given at perform-point and also, unlike normal exception handlers, a *continuation*, a first-class functional value representing the rest of the code to execute inside the handler from the perform-point. By calling the continuation with a value we can resume at the perform-point, as if performing the operation evaluated to the value. But more interestingly, we can resume multiple times, or never, or store the continuation for later use.

This access to the continuation, while powerful, might also be a recipe for disaster. That is why languages with algebraic effects typically have *type-and-effect systems*, not only tracking the type of value an expression might evaluate to, but also what kind of effects it may perform on the way.

This work will study a particular formal language equipped with algebraic effects. Although most results in the domain of programming languages depend crucially on the exact calculus and type system used, we hope that the results, ideas, and techniques may apply elsewhere. This should not seem far-fetched, as the paper

which introduced the language [2] is exactly about interexpressibility with other systems.

Possibly the most interesting result of this work is a potentially novel use of coinduction in the method of logical relations. It allowed us to get rid of step-indexing in the definition of the logical relation and ultimately prove termination of the language. This may seem surprising, as coinduction is connotated primarily with infinite processes.

[todo other contributions]

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Chapter 2

The language

We will study the deep handler calculus and type-and-effect system formulated in [2]. It is a refreshingly minimal language—the call-by-value lambda calculus with a few extensions to be able to express the essence of algebraic effects. There is only one unnamed universal operation, performed **do** v . To be able to simulate calculi with named effects (and more), the *lift* operator, written $[e]$, is introduced. When operations are performed inside the expression e enclosed by lift, the nearest handler will be skipped and the operation will be handled by the next one instead. Naturally, the operator composes, so multiple enclosing lifts means multiple handlers skipped. In contrast to most work on algebraic effects, the effect-tracking system here is structural, we do not have any concept of predefined or user-defined (named) signatures of effects. Finally, the language features polymorphic expressions and polymorphic operations.

$$\begin{aligned} \text{TVar} &\ni \alpha, \beta, \dots \\ \text{Var} &\ni f, r, x, y, \dots \\ \text{Kind} &\ni \kappa ::= \mathbf{T} \mid \mathbf{E} \mid \mathbf{R} \\ \text{Typelike} &\ni \sigma, \tau, \varepsilon, \rho ::= \alpha \mid \tau \rightarrow_\rho \tau \mid \forall \alpha :: \kappa. \tau \mid \iota \mid \varepsilon \cdot \rho \\ \text{Val} &\ni v ::= x \mid \lambda x. t \\ \text{Exp} &\ni e ::= v \mid e e \mid [e] \mid \mathbf{do} \ v \mid \mathbf{handle} \ e \{x, r. e; x. e\} \\ \text{ECont} &\ni K ::= \square \mid K e \mid v K \mid [K] \mid \mathbf{handle} \ K \{x, r. e; x. e\} \end{aligned}$$

Figure 2.1: Syntax.

$$\begin{array}{c}
\frac{}{0\text{-free}(\square)} \qquad \frac{n\text{-free}(K)}{n\text{-free}(K \ e)} \qquad \frac{n\text{-free}(K)}{n\text{-free}(v \ K)} \qquad \frac{n\text{-free}(K)}{n + 1\text{-free}([K])} \\
\\
\frac{n + 1\text{-free}(K)}{n\text{-free}(\text{handle } K \ \{x, r. e_h; x. e_r\})}
\end{array}$$

Figure 2.2: Evaluation context freeness.

$$\begin{array}{c}
\frac{e_1 \mapsto e_2}{K[e_1] \rightarrow K[e_2]} \qquad (\lambda x. e) \ v \mapsto e\{v/x\} \qquad [v] \mapsto v \\
\\
\frac{0\text{-free}(K) \quad v_c = \lambda z. \text{handle } K[z] \ \{x, r. e_h; x. e_r\}}{\text{handle } K[\text{do } v] \ \{x, r. e_h; x. e_r\} \mapsto e_h\{v/x\}\{v_c/r\}} \\
\text{handle } v \ \{x, r. e_h; x. e_r\} \mapsto e_r\{v/x\}
\end{array}$$

Figure 2.3: Single-step reduction.

$$\begin{array}{c}
\frac{\alpha :: \kappa \in \Delta}{\Delta \vdash \alpha :: \kappa} \qquad \frac{\Delta \vdash \tau_1 :: \mathsf{T} \quad \Delta \vdash \rho :: \mathsf{R} \quad \Delta \vdash \tau_2 :: \mathsf{T}}{\Delta \vdash \tau_1 \rightarrow_{\rho} \tau_2 :: \mathsf{T}} \qquad \frac{\Delta, \alpha :: \kappa \vdash \tau :: \mathsf{T}}{\Delta \vdash \forall \alpha :: \kappa. \tau :: \mathsf{T}} \\
\\
\frac{}{\Delta \vdash \iota :: \mathsf{R}} \qquad \frac{\Delta \vdash \varepsilon :: \mathsf{E} \quad \Delta \vdash \rho :: \mathsf{R}}{\Delta \vdash \varepsilon \cdot \rho :: \mathsf{R}} \qquad \frac{\Delta, \Delta' \vdash \tau_1 :: \mathsf{T} \quad \Delta, \Delta' \vdash \tau_2 :: \mathsf{T}}{\Delta \vdash \Delta'. \tau_1 \Rightarrow \tau_2 :: \mathsf{E}} \\
\\
\Delta \vdash \delta :: \Delta' \iff \text{dom}(\delta) = \text{dom}(\Delta') \wedge \forall \alpha \in \text{dom}(\delta). \Delta \vdash \delta(\alpha) :: \Delta'(\alpha)
\end{array}$$

Figure 2.4: Well-formedness of types, rows, and type substitution.

$$\begin{array}{c}
\frac{}{\Delta \vdash \sigma <: \sigma} \qquad \frac{\Delta \vdash \tau_2^1 <: \tau_1^1 \quad \Delta \vdash \rho_1 <: \rho_2 \quad \Delta \vdash \tau_1^2 <: \tau_2^2}{\Delta \vdash \tau_1^1 \rightarrow_{\rho_1} \tau_1^2 <: \tau_2^1 \rightarrow_{\rho_2} \tau_2^2} \\
\\
\frac{\Delta, \alpha :: \kappa \vdash \tau_1 <: \tau_2}{\Delta \vdash \forall \alpha :: \kappa. \tau_1 <: \forall \alpha :: \kappa. \tau_2} \qquad \frac{\Delta \vdash \rho :: \mathsf{R}}{\Delta \vdash \iota <: \rho} \qquad \frac{\Delta \vdash \rho_1 <: \rho_2}{\Delta \vdash \varepsilon \cdot \rho_1 <: \varepsilon \cdot \rho_2}
\end{array}$$

Figure 2.5: Subtyping.

$$\begin{array}{c}
\frac{x : \tau \in \Gamma}{\Delta; \Gamma \vdash x : \tau / \iota} \qquad \frac{\Delta \vdash \tau_1 :: \mathbf{T} \quad \Delta; \Gamma, x : \tau_1 \vdash e : \tau_2 / \rho}{\Delta; \Gamma \vdash \lambda x. e : \tau_1 \rightarrow_{\rho} \tau_2 / \iota} \\
\\
\frac{\Delta; \Gamma \vdash e_1 : \tau_1 \rightarrow_{\rho} \tau_2 / \rho \quad \Delta; \Gamma \vdash e_2 : \tau_1 / \rho}{\Delta; \Gamma \vdash e_1 e_2 : \tau_2 / \rho} \qquad \frac{\Delta \vdash \varepsilon :: \mathbf{E} \quad \Delta; \Gamma \vdash e : \tau / \rho}{\Delta; \Gamma \vdash [e] : \tau / \varepsilon \cdot \rho} \\
\\
\frac{\Delta, \alpha :: \kappa; \Gamma \vdash e : \tau / \iota}{\Delta; \Gamma \vdash e : \forall \alpha :: \kappa. \tau / \iota} \qquad \frac{\Delta \vdash \sigma :: \kappa \quad \Delta; \Gamma \vdash e : \forall \alpha :: \kappa. \tau / \rho}{\Delta; \Gamma \vdash e : \tau \{ \sigma / \alpha \} / \rho} \\
\\
\frac{\Delta \vdash \tau_1 <: \tau_2 \quad \Delta \vdash \rho_1 <: \rho_2 \quad \Delta; \Gamma \vdash e : \tau_1 / \rho_1}{\Delta; \Gamma \vdash e : \tau_2 / \rho_2} \\
\\
\frac{\Delta; \Gamma \vdash v : \delta(\tau_1) / \iota \quad \Delta \vdash \delta :: \Delta' \quad \Delta \vdash \Delta'. \tau_1 \Rightarrow \tau_2 :: \mathbf{E}}{\Delta; \Gamma \vdash \mathbf{do} v : \delta(\tau_2) / (\Delta'. \tau_1 \Rightarrow \tau_2)} \\
\\
\frac{\Delta, \Delta'; \Gamma, x : \tau_1, r : \tau_2 \rightarrow_{\rho} \tau_r \vdash e_h : \tau_r / \rho \quad \Delta; \Gamma, x : \tau \vdash e_r : \tau_r / \rho}{\Delta; \Gamma \vdash \mathbf{handle} e \{ x, r. e_h; x. e_r \} : \tau_r / \rho}
\end{array}$$

Figure 2.6: Type system.

Chapter 3

The logical relation

The logical relation is adapted from [1] with a few changes: our relation is unary, we additionally have polymorphic effects, we do not have type lambdas.

3.1 Definition

First, we define the spaces of *semantic types* and *semantic effects*, which are also the interpretations of the appropriate kinds:

$$\begin{aligned}\llbracket \mathbf{T} \rrbracket &= \mathcal{P}(\text{Val}) = \text{Type}, \\ \llbracket \mathbf{E} \rrbracket = \llbracket \mathbf{R} \rrbracket &= \mathcal{P}(\text{Exp} \times \mathbb{N} \times \text{Type}) = \text{Eff}.\end{aligned}$$

Semantic types are simply sets of closed values. Semantic effects are sets of triples, which aim to describe a situation in which an expression being evaluated performs an effect. The components of such a triple are: the argument of the operation, the freeness of the enclosing context beyond which the operation can be handled, and the semantic type of values we can call the resumption with.

Logical relations can be used to establish various properties. Here, we choose termination to a value as our *observation*:

$$\text{Obs} = \{e \mid \exists v. e \rightarrow^* v\}.$$

We start with defining interpretations of types and effects. We parameterize the definitions by a mapping η from type variables to semantic types or effects.

$$\begin{aligned}\llbracket \tau_1 \rightarrow_\rho \tau_2 \rrbracket_\eta &= \{\lambda x. e \mid \forall v \in \llbracket \tau_1 \rrbracket_\eta. e\{v/x\} \in \mathcal{E}\llbracket \tau_2/\rho \rrbracket_\eta\} \\ \llbracket \forall \alpha :: \kappa. \tau \rrbracket_\eta &= \{v \mid \forall \mu \in \llbracket \kappa \rrbracket. v \in \llbracket \tau \rrbracket_{[\alpha \mapsto \mu]_\eta}\} \\ \llbracket \alpha \rrbracket_\eta &= \{v \mid \forall K. (\forall u \in \eta(\alpha). K[u] \in \text{Obs}) \implies K[v] \in \text{Obs}\} \\ \llbracket \tau_1 \Rightarrow \tau_2 \rrbracket_\eta &= \{(v, 0, \llbracket \tau_2 \rrbracket_\eta) \mid v \in \llbracket \tau_1 \rrbracket_\eta\} \\ \llbracket \forall \alpha :: \kappa. \varepsilon \rrbracket_\eta &= \{t \mid \exists \mu \in \llbracket \kappa \rrbracket. t \in \llbracket \varepsilon \rrbracket_{[\alpha \mapsto \mu]_\eta}\} \\ \llbracket \varepsilon \cdot \rho \rrbracket_\eta &= \llbracket \varepsilon \rrbracket_\eta \cup \{(v, n+1, \mu) \mid (v, n, \mu) \in \llbracket \rho \rrbracket_\eta\} \\ \llbracket \iota \rrbracket_\eta &= \emptyset\end{aligned}$$

By adapting the definitions from [1] we end up with the following equations defining the sets good expressions, contexts, and control-stuck terms:

$$\begin{aligned}\mathcal{E}[\tau/\rho]_\eta &= \{e \mid \forall K \in \mathcal{K}[\tau/\rho]_\eta. K[e] \in \text{Obs}\} \\ \mathcal{K}[\tau/\rho]_\eta &= \{K \mid \forall v \in [\tau]_\eta. K[v] \in \text{Obs} \wedge \forall s \in \mathcal{S}[\tau/\rho]_\eta. K[s] \in \text{Obs}\} \\ \mathcal{S}[\tau/\rho]_\eta &= \{K[\text{do } v] \mid \exists n, \mu. (v, n, \mu) \in [\rho]_\eta \wedge n\text{-free}(K) \wedge \forall u \in \mu. K[u] \in \mathcal{E}[\tau/\rho]_\eta\}\end{aligned}$$

This, however, does not immediately define anything yet, due to the recursive occurrence of $\mathcal{E}[\tau/\rho]_\eta$.

We untangle the recursion firstly by abstracting out the recursive occurrence as an additional parameter and secondly by noticing that we do not need the exact interpretations of types and effects, any semantic type and effect will do.

$$\begin{aligned}\mathcal{E}(\mu, \xi, X) &= \{e \mid \forall K \in \mathcal{K}(\mu, \xi, X). K[e] \in \text{Obs}\} \\ \mathcal{K}(\mu, \xi, X) &= \{K \mid \forall v \in \mu. K[v] \in \text{Obs} \wedge \forall s \in \mathcal{S}(\xi, X). K[s] \in \text{Obs}\} \\ \mathcal{S}(_, \xi, X) &= \{K[\text{do } v] \mid \exists n, \mu. (v, n, \mu) \in \xi \wedge n\text{-free}(K) \wedge \forall u \in \mu. K[u] \in X\}\end{aligned}$$

We note that $\mathcal{E}(\mu, \xi, X)$ is non-decreasing as a function of X , i.e. it is a monotone function on the complete lattice of the powerset of Exp ordered by inclusion. Hence, by the Knaster-Tarski theorem, it has a greatest fixed point, which we denote $\mathcal{E}(\mu, \xi)$. Moreover, the theorem states that this is exactly the greatest prefixpoint, i.e.

$$\mathcal{E}(\mu, \xi) = \bigcup \{X \subseteq \text{Exp} \mid X \subseteq \mathcal{E}(\mu, \xi, X)\}.$$

This is the argument X we wanted, so we plug it in and set $\mathcal{K}(\mu, \xi) = \mathcal{K}(\mu, \xi, \mathcal{E}(\mu, \xi))$ and $\mathcal{S}(\mu, \xi) = \mathcal{S}(\mu, \xi, \mathcal{E}(\mu, \xi))$.

Now, it remains to plug in the interpretations of types as the semantic types:

$$\begin{aligned}\mathcal{E}[\tau/\rho]_\eta &= \mathcal{E}([\tau]_\eta, [\rho]_\eta), \\ \mathcal{K}[\tau/\rho]_\eta &= \mathcal{K}([\tau]_\eta, [\rho]_\eta), \\ \mathcal{S}[\tau/\rho]_\eta &= \mathcal{S}([\tau]_\eta, [\rho]_\eta).\end{aligned}$$

The interpretations of types and effects are defined by structural induction (in the case of the arrow type we can treat τ_2/ρ as a subterm of $\tau_1 \rightarrow_\rho \tau_2$, just written in a different notation).

3.2 Basic properties

Lemma 1 (Coinduction principle). *If $X \subseteq \mathcal{E}(\mu, \xi, X)$ then $X \subseteq \mathcal{E}(\mu, \xi)$.*

Proof. Follows directly from the definition. \square

Lemma 2 (Monotonicity). *If $\mu_1 \subseteq \mu_2$ and $\xi_1 \subseteq \xi_2$, then $\mathcal{E}(\mu_1, \xi_1) \subseteq \mathcal{E}(\mu_2, \xi_2)$.*

Proof. It is easy to check that $\mathcal{E}(\mu, \xi, X)$ is non-decreasing as a function of μ and ξ . So if $\mu_1 \subseteq \mu_2$ and $\xi_1 \subseteq \xi_2$, then $X \subseteq \mathcal{E}(\mu_1, \xi_1, X)$ implies $X \subseteq \mathcal{E}(\mu_2, \xi_2, X)$. Therefore $\{X \subseteq \text{Exp} \mid X \subseteq \mathcal{E}(\mu_1, \xi_1, X)\} \subseteq \{X \subseteq \text{Exp} \mid X \subseteq \mathcal{E}(\mu_2, \xi_2, X)\}$ and $\bigcup \{X \subseteq \text{Exp} \mid X \subseteq \mathcal{E}(\mu_1, \xi_1, X)\} \subseteq \bigcup \{X \subseteq \text{Exp} \mid X \subseteq \mathcal{E}(\mu_2, \xi_2, X)\}$. \square

Lemma 3. *The empty context \square is in $\mathcal{K}(\mu, \emptyset)$.*

Proof. The set $\mathcal{S}(\mu, \emptyset)$ is empty and μ is contained in Obs . \square

3.3 Compatibility lemmas

We want to establish that $\vdash e : \tau / \iota$ implies $e \in \mathcal{E}[\![\tau/\iota]\!]$. Termination to a value will follow from lemma 3.

For this purpose we will prove a semantic counterpart of each typing rule. First, we need to define a counterpart to the typing judgment. Unlike typing judgments, our relations are on closed terms only, so we get around that by using substitution. We define

$$\Delta; \Gamma \models e : \tau / \rho \iff \forall \eta \in [\![\Delta]\!]. \forall \gamma \in [\![\Gamma]\!]_\eta. \gamma(e) \in \mathcal{E}[\![\tau/\rho]\!]_\eta,$$

where $[\![\Delta]\!] = \{\eta \mid \forall \alpha :: \kappa \in \Delta. \eta(\alpha) \in [\![\kappa]\!]\}$ contains type-level mappings and $[\![\Gamma]\!]_\eta = \{\gamma \mid \forall x : \tau \in \Gamma. \gamma(x) \in [\![\tau]\!]_\eta\}$ contains expression-level variable substitutions.

3.3.1 Lambda calculus core

Lemma 4 (Variable rule compatibility).

3.3.2 Effects

3.3.3 Subtyping

3.3.4 Polymorphism

Bibliography

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