

# Empirical Bayes Matrix Factorization

Matthew Stephens, Wei Wang

March 9, 2018

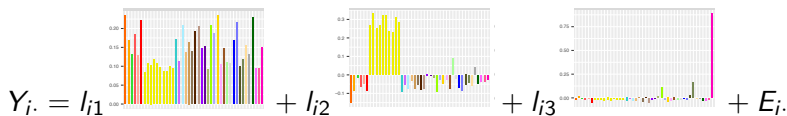
# Buzz words

- ▶ Principal Components Analysis
- ▶ Clustering
- ▶ Factor Analysis
- ▶ Dimension Reduction
- ▶ Latent Dirichlet Allocation / Admixture / Mixed Membership
- ▶ Non-negative Matrix Factorization

# Matrix Factorization

$$Y = \sum_{k=1}^K l_k f_k^T + E$$

## Example: Genotype effects across tissues



# One model, many methods (many applications)

$$Y = \sum_{k=1}^K l_k f_k^T + E$$

PCA:  $l_1, \dots, l_K$  are orthogonal; as are  $f_1, \dots, f_K$ .

NMF: elements of  $l_k$  and  $f_k$  are non-negative.

LDA, topic models, admixture:  $\sum_k l_{ki} = 1$

Sparse FA:  $l_k$  and/or  $f_k$  are sparse ...but how sparse?

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## A simpler problem: the normal means problem

Observe  $X_1, \dots, X_n$  with

$$X_j \sim N(\theta_j, s_j^2).$$

Challenge: Estimate  $\theta_1, \dots, \theta_n$ .

Key idea: Shrinkage.

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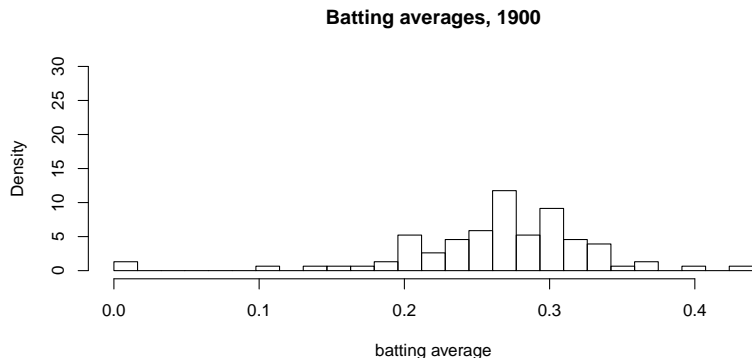
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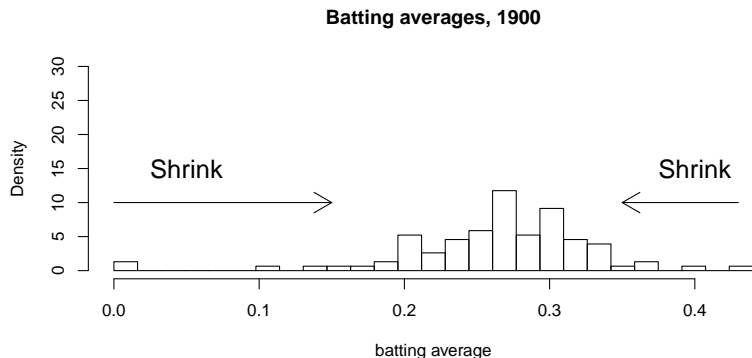
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# Shrinkage Estimation<sup>1</sup>



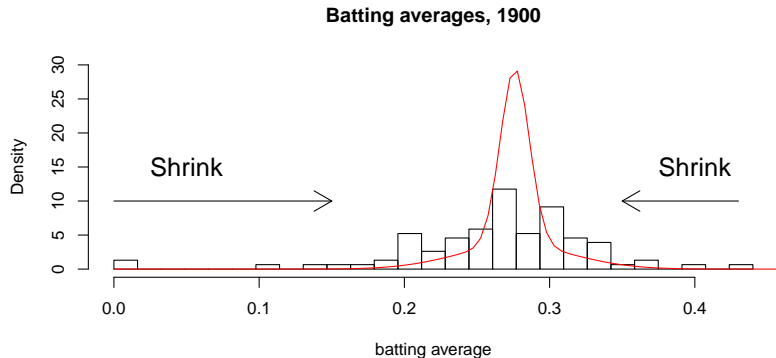
<sup>1</sup>[http://varianceexplained.org/r/empirical\\_bayes\\_baseball/](http://varianceexplained.org/r/empirical_bayes_baseball/)

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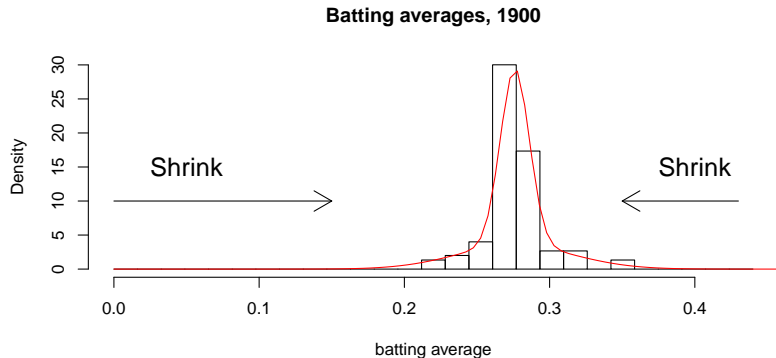
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# Empirical Bayes: learn how much to shrink from the data

$$\begin{aligned}X_j &\sim N(\theta_j, s_j^2) \\ \theta_j &\sim g(\cdot) \in \mathcal{G}\end{aligned}$$

Fit in two steps:

1. Estimate  $g$  by maximum likelihood:  $\hat{g} = \arg \max_g L(g)$
2. Estimate  $\theta_j$  using posterior distribution  $\theta_j | X_j, \hat{g}$ .

...tractable for very flexible  $\mathcal{G}$  (e.g.  $\mathcal{G}$  = distributions that are unimodal; S., 2016).



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# Empirical Bayes Factor Analysis

$$Y = \sum_{k=1}^K l_k f_k^T + E$$

$$l_{k1}, \dots, l_{kn} \sim g_k^l(\cdot) \in \mathcal{G}$$

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Harder than normal means problem...

...but approximate iterative solution based on normal means.

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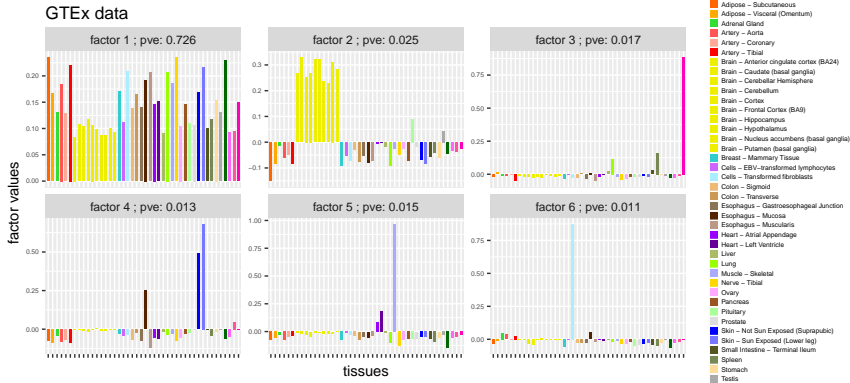
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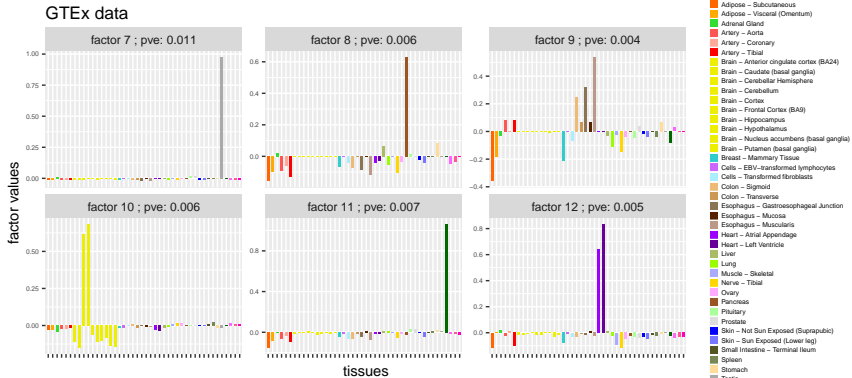
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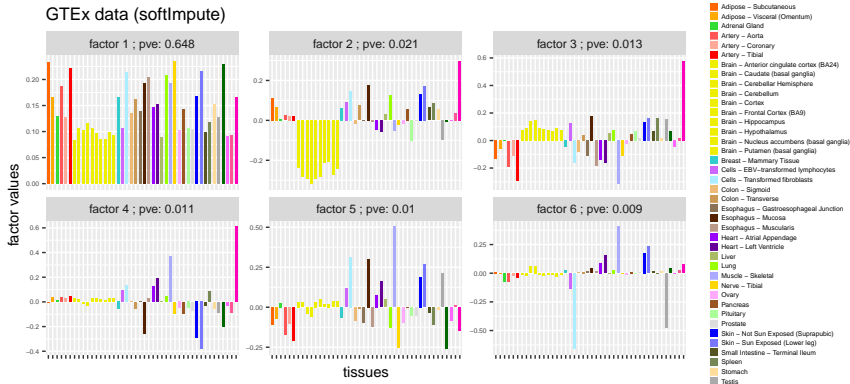
# GTEx data: first 6 factors



# GTEx data: next 6 factors



# Comparison: softImpute (nuclear norm penalty)



# What next?

- ▶ Faster
- ▶ Bigger
- ▶ Visualizing Results
- ▶ Non-negative Constraint

# Acknowledgements

- ▶ Wei Wang
- ▶ Funding: GTEX, Moore Foundation

flashr: <https://www.github.com/stephenslab/flashr>

workflowr: <https://github.com/jdblischak/workflowr>



# Rank 3 simulations

