# dog\_app

July 8, 2020

# 1 Convolutional Neural Networks

# 1.1 Project: Write an Algorithm for a Dog Identification App

In this notebook, some template code has already been provided for you, and you will need to implement additional functionality to successfully complete this project. You will not need to modify the included code beyond what is requested. Sections that begin with '(IMPLEMENTATION)' in the header indicate that the following block of code will require additional functionality which you must provide. Instructions will be provided for each section, and the specifics of the implementation are marked in the code block with a 'TODO' statement. Please be sure to read the instructions carefully!

**Note**: Once you have completed all of the code implementations, you need to finalize your work by exporting the Jupyter Notebook as an HTML document. Before exporting the notebook to html, all of the code cells need to have been run so that reviewers can see the final implementation and output. You can then export the notebook by using the menu above and navigating to **File -> Download as -> HTML (.html)**. Include the finished document along with this notebook as your submission.

In addition to implementing code, there will be questions that you must answer which relate to the project and your implementation. Each section where you will answer a question is preceded by a 'Question X' header. Carefully read each question and provide thorough answers in the following text boxes that begin with 'Answer:'. Your project submission will be evaluated based on your answers to each of the questions and the implementation you provide.

**Note:** Code and Markdown cells can be executed using the **Shift + Enter** keyboard shortcut. Markdown cells can be edited by double-clicking the cell to enter edit mode.

The rubric contains *optional* "Stand Out Suggestions" for enhancing the project beyond the minimum requirements. If you decide to pursue the "Stand Out Suggestions", you should include the code in this Jupyter notebook.

## Step 0: Import Datasets

Make sure that you've downloaded the required human and dog datasets:

Note: if you are using the Udacity workspace, you *DO NOT* need to re-download these - they can be found in the /data folder as noted in the cell below.

- Download the dog dataset. Unzip the folder and place it in this project's home directory, at the location /dog\_images.
- Download the human dataset. Unzip the folder and place it in the home directory, at location /lfw.

Note: If you are using a Windows machine, you are encouraged to use 7zip to extract the folder. In the code cell below, we save the file paths for both the human (LFW) dataset and dog dataset in the numpy arrays human\_files and dog\_files.

## Step 1: Detect Humans

In this section, we use OpenCV's implementation of Haar feature-based cascade classifiers to detect human faces in images.

OpenCV provides many pre-trained face detectors, stored as XML files on github. We have downloaded one of these detectors and stored it in the haarcascades directory. In the next code cell, we demonstrate how to use this detector to find human faces in a sample image.

```
In [2]: import cv2
    import matplotlib.pyplot as plt
    %matplotlib inline

# extract pre-trained face detector
    face_cascade = cv2.CascadeClassifier('haarcascades/haarcascade_frontalface_alt.xml')

# load color (BGR) image
    img = cv2.imread(human_files[0])
    # convert BGR image to grayscale
    gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)

# find faces in image
    faces = face_cascade.detectMultiScale(gray)

# print number of faces detected in the image
    print('Number of faces detected:', len(faces))
```

```
# get bounding box for each detected face
for (x,y,w,h) in faces:
    # add bounding box to color image
    cv2.rectangle(img,(x,y),(x+w,y+h),(255,0,0),2)

# convert BGR image to RGB for plotting
cv_rgb = cv2.cvtColor(img, cv2.COLOR_BGR2RGB)

# display the image, along with bounding box
plt.imshow(cv_rgb)
plt.show()
```

Number of faces detected: 1



Before using any of the face detectors, it is standard procedure to convert the images to grayscale. The detectMultiScale function executes the classifier stored in face\_cascade and takes the grayscale image as a parameter.

In the above code, faces is a numpy array of detected faces, where each row corresponds to a detected face. Each detected face is a 1D array with four entries that specifies the bounding box of the detected face. The first two entries in the array (extracted in the above code as x and y) specify the horizontal and vertical positions of the top left corner of the bounding box. The last two entries in the array (extracted here as w and h) specify the width and height of the box.

### 1.1.1 Write a Human Face Detector

dog: 17.00%

We can use this procedure to write a function that returns True if a human face is detected in an image and False otherwise. This function, aptly named face\_detector, takes a string-valued file path to an image as input and appears in the code block below.

```
In [3]: # returns "True" if face is detected in image stored at img_path
    def face_detector(img_path):
        img = cv2.imread(img_path)
        gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)
        faces = face_cascade.detectMultiScale(gray)
        return len(faces) > 0
```

### 1.1.2 (IMPLEMENTATION) Assess the Human Face Detector

**Question 1:** Use the code cell below to test the performance of the face\_detector function.

- What percentage of the first 100 images in human\_files have a detected human face?
- What percentage of the first 100 images in dog\_files have a detected human face?

Ideally, we would like 100% of human images with a detected face and 0% of dog images with a detected face. You will see that our algorithm falls short of this goal, but still gives acceptable performance. We extract the file paths for the first 100 images from each of the datasets and store them in the numpy arrays human\_files\_short and dog\_files\_short.

**Answer:** Using the above implemented face\_detector function: percentage of Human faces detected in Human files: 98% percentage of Human faces detected in Dog files: 17%

```
In [4]: from tqdm import tqdm
    human_files_short = human_files[:100]
    dog_files_short = dog_files[:100]

#-#-# Do NOT modify the code above this line. #-#-#

## TODO: Test the performance of the face_detector algorithm
    ## on the images in human_files_short and dog_files_short.

def detect(detector, files):
    # np.mean(list(map(detector, files))) # Or this method
    return np.mean([detector(f) for f in files])
    print('human: {:.2%}'.format(detect(face_detector, human_files_short)))
    print('dog: {:.2%}'.format(detect(face_detector, dog_files_short)))
human: 98.00%
```

We suggest the face detector from OpenCV as a potential way to detect human images in your algorithm, but you are free to explore other approaches, especially approaches that make use of deep learning:). Please use the code cell below to design and test your own face detection

algorithm. If you decide to pursue this *optional* task, report performance on human\_files\_short and dog\_files\_short.

```
In []: ### (Optional)
     ### TODO: Test performance of anotherface detection algorithm.
     ### Feel free to use as many code cells as needed.
```

## Step 2: Detect Dogs

In this section, we use a pre-trained model to detect dogs in images.

### 1.1.3 Obtain Pre-trained VGG-16 Model

The code cell below downloads the VGG-16 model, along with weights that have been trained on ImageNet, a very large, very popular dataset used for image classification and other vision tasks. ImageNet contains over 10 million URLs, each linking to an image containing an object from one of 1000 categories.

```
In [5]: import torch
    import torchvision.models as models

# define VGG16 model
    VGG16 = models.vgg16(pretrained=True)

# check if CUDA is available
    use_cuda = torch.cuda.is_available()

# move model to GPU if CUDA is available
    if use_cuda:
        VGG16 = VGG16.cuda()
```

Downloading: "https://download.pytorch.org/models/vgg16-397923af.pth" to /root/.torch/models/vgg100%|| 553433881/553433881 [00:06<00:00, 91994498.12it/s]

Given an image, this pre-trained VGG-16 model returns a prediction (derived from the 1000 possible categories in ImageNet) for the object that is contained in the image.

## 1.1.4 (IMPLEMENTATION) Making Predictions with a Pre-trained Model

In the next code cell, you will write a function that accepts a path to an image (such as 'dogImages/train/001.Affenpinscher/Affenpinscher\_00001.jpg') as input and returns the index corresponding to the ImageNet class that is predicted by the pre-trained VGG-16 model. The output should always be an integer between 0 and 999, inclusive.

Before writing the function, make sure that you take the time to learn how to appropriately pre-process tensors for pre-trained models in the PyTorch documentation.

```
In [10]: from PIL import Image
         import torchvision.transforms as transforms
         def VGG16_predict(img_path):
             Use pre-trained VGG-16 model to obtain index corresponding to
             predicted ImageNet class for image at specified path
             Args:
                 img_path: path to an image
             Returns:
                 Index corresponding to VGG-16 model's prediction
             ## TODO: Complete the function.
             ## Load and pre-process an image from the given img_path
             ## Return the *index* of the predicted class for that image
             #transforms image to image_tensor as needed for input to VGG16 model.
             111
             As described on https://pytorch.org/hub/pytorch_vision_vgg/
             All pre-trained models expect input images normalized in the same way,
             i.e. mini-batches of 3-channel RGB images of shape (3 x H x W),
             where H and W are expected to be at least 224.
             The images have to be loaded in to a range of [0, 1] and
             then normalized using mean = [0.485, 0.456, 0.406] and std = [0.229, 0.224, 0.225].
             So used this sample code right from there.
             111
             input_image = Image.open(img_path)
             preprocess = transforms.Compose([
                 transforms.Resize(256),
                 transforms.CenterCrop(224),
                 transforms.ToTensor(),
                 transforms.Normalize(mean=[0.485, 0.456, 0.406], std=[0.229, 0.224, 0.225]),
             ])
             input_tensor = preprocess(input_image)
             input_batch = input_tensor.unsqueeze(0) # create a mini-batch as expected by the mo
             # move the input to GPU for speed if available
             if use cuda:
                 input_batch = input_batch.cuda()
             with torch.no_grad():
                 output = VGG16(input_batch)
```

```
# convert output to predicted index
_, index = torch.max(output, 1)
pred_index = np.squeeze(index.numpy()) if not use_cuda else np.squeeze(index.cpu().
return int(pred_index) # predicted class index
```

# 1.1.5 (IMPLEMENTATION) Write a Dog Detector

While looking at the dictionary, you will notice that the categories corresponding to dogs appear in an uninterrupted sequence and correspond to dictionary keys 151-268, inclusive, to include all categories from 'Chihuahua' to 'Mexican hairless'. Thus, in order to check to see if an image is predicted to contain a dog by the pre-trained VGG-16 model, we need only check if the pre-trained model predicts an index between 151 and 268 (inclusive).

Use these ideas to complete the dog\_detector function below, which returns True if a dog is detected in an image (and False if not).

## 1.1.6 (IMPLEMENTATION) Assess the Dog Detector

**Question 2:** Use the code cell below to test the performance of your dog\_detector function.

- What percentage of the images in human\_files\_short have a detected dog?
- What percentage of the images in dog\_files\_short have a detected dog?

### **Answer:**

percentage of Dog faces detected in Human files : 0% percenatge of Dog faces detected in Dog files : 100%

We suggest VGG-16 as a potential network to detect dog images in your algorithm, but you are free to explore other pre-trained networks (such as Inception-v3, ResNet-50, etc). Please use the code cell below to test other pre-trained PyTorch models. If you decide to pursue this *optional* task, report performance on human\_files\_short and dog\_files\_short.

```
In [ ]: ### (Optional)
     ### TODO: Report the performance of another pre-trained network.
     ### Feel free to use as many code cells as needed.
```

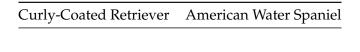
## Step 3: Create a CNN to Classify Dog Breeds (from Scratch)

Now that we have functions for detecting humans and dogs in images, we need a way to predict breed from images. In this step, you will create a CNN that classifies dog breeds. You must create your CNN *from scratch* (so, you can't use transfer learning *yet*!), and you must attain a test accuracy of at least 10%. In Step 4 of this notebook, you will have the opportunity to use transfer learning to create a CNN that attains greatly improved accuracy.

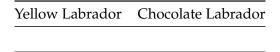
We mention that the task of assigning breed to dogs from images is considered exceptionally challenging. To see why, consider that *even a human* would have trouble distinguishing between a Brittany and a Welsh Springer Spaniel.

Brittany	Welsh Springer Spaniel

It is not difficult to find other dog breed pairs with minimal inter-class variation (for instance, Curly-Coated Retrievers and American Water Spaniels).



Likewise, recall that labradors come in yellow, chocolate, and black. Your vision-based algorithm will have to conquer this high intra-class variation to determine how to classify all of these different shades as the same breed.



We also mention that random chance presents an exceptionally low bar: setting aside the fact that the classes are slightly imabalanced, a random guess will provide a correct answer roughly 1 in 133 times, which corresponds to an accuracy of less than 1%.

Remember that the practice is far ahead of the theory in deep learning. Experiment with many different architectures, and trust your intuition. And, of course, have fun!

## 1.1.7 (IMPLEMENTATION) Specify Data Loaders for the Dog Dataset

Use the code cell below to write three separate data loaders for the training, validation, and test datasets of dog images (located at dog\_images/train, dog\_images/valid, and dog\_images/test, respectively). You may find this documentation on custom datasets to be a useful resource. If you are interested in augmenting your training and/or validation data, check out the wide variety of transforms!

```
In [13]: import os
         import random
         import requests
         import time
         import ast
         import numpy as np
         from glob import glob
         import cv2
         from tqdm import tqdm
         from PIL import Image, ImageFile
         import torch
         import torchvision
         from torchvision import datasets
         import torchvision.transforms as transforms
         import torch.optim as optim
         import torchvision.models as models
         import matplotlib.pyplot as plt
         ImageFile.LOAD_TRUNCATED_IMAGES = True
         # check if CUDA is available
         use_cuda = torch.cuda.is_available()
         ### TODO: Write data loaders for training, validation, and test sets
         ## Specify appropriate transforms, and batch_sizes
         Resource help for dataloaders and augmentation has been taken from
         https://pytorch.org/tutorials/beginner/transfer_learning_tutorial.html
         # Data augmentation for training and normalization for validation and test
         data_transforms = {
                                 'train': transforms.Compose([
                                     transforms.RandomResizedCrop(224),
                                     transforms.RandomHorizontalFlip(),
                                     transforms.RandomRotation(10),
                                     transforms.ToTensor(),
                                     transforms.Normalize([0.485, 0.456, 0.406], [0.229, 0.224,
                                 1),
                                 'valid': transforms.Compose([
                                     transforms.Resize(256),
                                     transforms.CenterCrop(224),
                                     transforms.ToTensor(),
```

```
transforms.Normalize([0.485, 0.456, 0.406], [0.229, 0.224,
                        ]),
                        'test': transforms.Compose([
                            transforms.Resize(256),
                            transforms.CenterCrop(224),
                            transforms.ToTensor(),
                            transforms.Normalize([0.485, 0.456, 0.406], [0.229, 0.224,
                        ]),
                    }
data_dir = '/data/dog_images'
image_datasets = {x: datasets.ImageFolder(os.path.join(data_dir, x),
                                          data_transforms[x])
                  for x in ['train', 'valid', 'test']}
loaders_scratch = {x: torch.utils.data.DataLoader(image_datasets[x], batch_size=16,
                                             shuffle=True, num_workers=2)
              for x in ['train', 'valid', 'test']}
dataset_sizes = {x: len(image_datasets[x]) for x in ['train', 'valid', 'test']}
```

**Question 3:** Describe your chosen procedure for preprocessing the data. - How does your code resize the images (by cropping, stretching, etc)? What size did you pick for the input tensor, and why? - Did you decide to augment the dataset? If so, how (through translations, flips, rotations, etc)? If not, why not?

### Answer:

- 1. Training set has been rescaled to 224\*224. I have used 224 as a resize value, so that it can be used in other prerained models too. Like VGG16 needs input image size to be at least 224.
- 2. Yes, I have augmented the training set through Random Flip and Rotation. Validation and test set is just normalized. This will reduce overfitting

## 1.1.8 (IMPLEMENTATION) Model Architecture

Create a CNN to classify dog breed. Use the template in the code cell below.

```
self.conv1 = nn.Conv2d(3, 64, 3, padding=1)
        self.conv2 = nn.Conv2d(64, 128, 3, padding=1)
        self.conv3 = nn.Conv2d(128, 256, 3, padding=1)
        self.conv4 = nn.Conv2d(256, 512, 3, padding=1)
        self.conv5 = nn.Conv2d(512, 1024, 3, padding=1)
        self.conv6 = nn.Conv2d(1024, 2048, 3, padding=1)
        self.conv7 = nn.Conv2d(2048, 4096, 3, padding=1)
        self.bn1 = nn.BatchNorm2d(64)
        self.bn2 = nn.BatchNorm2d(128)
        self.bn3 = nn.BatchNorm2d(256)
        self.bn4 = nn.BatchNorm2d(512)
        self.bn5 = nn.BatchNorm2d(1024)
        self.bn6 = nn.BatchNorm2d(2048)
        self.bn7 = nn.BatchNorm2d(4096)
        self.pool = nn.MaxPool2d(2, 2)
        self.fc1 = nn.Linear(4096, 2048)
        self.fc2 = nn.Linear(2048, 133)
        self.dropout = nn.Dropout(0.5)
    def forward(self, x):
        ## Define forward behavior
        x = self.bn1(self.pool(F.relu(self.conv1(x))))
        x = self.bn2(self.pool(F.relu(self.conv2(x))))
        x = self.bn3(self.pool(F.relu(self.conv3(x))))
        x = self.bn4(self.pool(F.relu(self.conv4(x))))
        x = self.bn5(self.pool(F.relu(self.conv5(x))))
        x = self.bn6(self.pool(F.relu(self.conv6(x))))
        x = self.bn7(self.pool(F.relu(self.conv7(x))))
        x = x.view(x.size(0), -1)
        x = F.relu(self.fc1(x))
        x = self.dropout(x)
        x = self.fc2(x)
        return x
#-#-# You so NOT have to modify the code below this line. #-#-#
# instantiate the CNN
model_scratch = Net()
# move tensors to GPU if CUDA is available
if use_cuda:
```

## Define layers of a CNN

```
model_scratch.cuda()
```

**Question 4:** Outline the steps you took to get to your final CNN architecture and your reasoning at each step.

## **Answer:**

Thinking of ResNet101, i tried the concept of using more stacked layers to captures fine details, so to gain a goood accuracy. Incorporating mentor suggestions ended up with having 7 conv2d layer, 1 maxpool layer, 2 fully connected layer and 1dropout layer. This can be tuned more to acheive a good accuracy.

Steps: 1. Added 7 conv2d layers with alternate BatchNormaliZation2D and dropout after each layer to overcome overfitting. 2. Added MaxPool2D layer to downsample as its best choice for this kind of classification. 3. Added FC layers to produce 133-dim output.

## 1.1.9 (IMPLEMENTATION) Specify Loss Function and Optimizer

Use the next code cell to specify a loss function and optimizer. Save the chosen loss function as criterion\_scratch, and the optimizer as optimizer\_scratch below.

## 1.1.10 (IMPLEMENTATION) Train and Validate the Model

Train and validate your model in the code cell below. Save the final model parameters at filepath 'model\_scratch.pt'.

```
if use_cuda:
        data, target = data.cuda(), target.cuda()
    ## find the loss and update the model parameters accordingly
    # clear the gradients of all optimized variables
    optimizer.zero_grad()
    # forward pass: compute predicted outputs by passing inputs to the model
    output = model(data)
    # calculate the batch loss
    loss = criterion(output, target)
    # backward pass: compute gradient of the loss with respect to model paramet
    loss.backward()
    # perform a single optimization step (parameter update)
    optimizer.step()
    ## record the average training loss, using something like
    train_loss = train_loss + ((1 / (batch_idx + 1)) * (loss.data - train_loss)
#####################
# validate the model #
######################
model.eval()
for batch_idx, (data, target) in enumerate(loaders['valid']):
    # move to GPU
    if use_cuda:
        data, target = data.cuda(), target.cuda()
    # forward pass: compute predicted outputs by passing inputs to the model
    output = model(data)
    # calculate the batch loss
    loss = criterion(output, target)
    ## update the average validation loss
    valid_loss = valid_loss + ((1 / (batch_idx + 1)) * (loss.data - valid_loss)
# print training/validation statistics
print('Epoch: {} \tTraining Loss: {:.6f} \tValidation Loss: {:.6f}'.format(
    epoch,
    train_loss,
    valid_loss
    ))
## TODO: save the model if validation loss has decreased
if valid_loss <= valid_loss_min:</pre>
    print('Validation loss decreased ({:.6f} --> {:.6f}). Saving model ...'.fo
    valid_loss_min,
    valid loss))
   torch.save(model.state_dict(), save_path)
    valid_loss_min = valid_loss
```

# # return trained model return model

# train the model

#### # load the model that got the best validation accuracy model\_scratch.load\_state\_dict(torch.load('model\_scratch.pt')) Epoch: 1 Training Loss: 4.650801 Validation Loss: 4.376101 Validation loss decreased (inf --> 4.376101). Saving model ... Training Loss: 4.399663 Validation Loss: 4.081033 Validation loss decreased (4.376101 --> 4.081033). Saving model ... Training Loss: 4.216371 Validation Loss: 3.884148 Epoch: 3 Validation loss decreased (4.081033 --> 3.884148). Saving model ... Validation Loss: 3.908316 Epoch: 5 Training Loss: 3.950665 Epoch: 6 Training Loss: 3.838559 Validation Loss: 3.459666 Validation loss decreased (3.884148 --> 3.459666). Saving model ... Epoch: 7 Training Loss: 3.724799 Validation Loss: 3.504665 Training Loss: 3.625448 Epoch: 8 Validation Loss: 3.242447 Validation loss decreased (3.459666 --> 3.242447). Saving model ... Training Loss: 3.527767 Epoch: 9 Validation Loss: 3.145574 Validation loss decreased (3.242447 --> 3.145574). Saving model ... Epoch: 10 Training Loss: 3.426196 Validation Loss: 3.834436 Epoch: 11 Training Loss: 3.308857 Validation Loss: 3.037142 Validation loss decreased (3.145574 --> 3.037142). Saving model ... Training Loss: 3.285589 Validation Loss: 2.751651 Epoch: 12 Validation loss decreased (3.037142 --> 2.751651). Saving model ... Epoch: 13 Training Loss: 3.177968 Validation Loss: 2.834353 Validation Loss: 2.577734 Epoch: 14 Training Loss: 3.087807 Validation loss decreased (2.751651 --> 2.577734). Saving model ... Epoch: 15 Training Loss: 2.989716 Validation Loss: 2.603860 Training Loss: 2.924501 Epoch: 16 Validation Loss: 2.502494 Validation loss decreased (2.577734 --> 2.502494). Saving model ... Training Loss: 2.847238 Epoch: 17 Validation Loss: 2.448747 Validation loss decreased (2.502494 --> 2.448747). Saving model ... Training Loss: 2.786272 Epoch: 18 Validation Loss: 2.333966 Validation loss decreased (2.448747 --> 2.333966). Saving model ... Epoch: 19 Training Loss: 2.737456 Validation Loss: 2.204324 Validation loss decreased (2.333966 --> 2.204324). Saving model ... Epoch: 20 Training Loss: 2.642419 Validation Loss: 2.437210

model\_scratch = train(20, loaders\_scratch, model\_scratch, optimizer\_scratch,

criterion\_scratch, use\_cuda, 'model\_scratch.pt')

### 1.1.11 (IMPLEMENTATION) Test the Model

Try out your model on the test dataset of dog images. Use the code cell below to calculate and print the test loss and accuracy. Ensure that your test accuracy is greater than 10%.

```
In [17]: def test(loaders, model, criterion, use_cuda):
             # monitor test loss and accuracy
             test_loss = 0.
             correct = 0.
             total = 0.
             model.eval()
             for batch_idx, (data, target) in enumerate(loaders['test']):
                 # move to GPU
                 if use_cuda:
                     data, target = data.cuda(), target.cuda()
                 # forward pass: compute predicted outputs by passing inputs to the model
                 output = model(data)
                 # calculate the loss
                 loss = criterion(output, target)
                 # update average test loss
                 test_loss = test_loss + ((1 / (batch_idx + 1)) * (loss.data - test_loss))
                 # convert output probabilities to predicted class
                 pred = output.data.max(1, keepdim=True)[1]
                 # compare predictions to true label
                 correct += np.sum(np.squeeze(pred.eq(target.data.view_as(pred))).cpu().numpy())
                 total += data.size(0)
             print('Test Loss: {:.6f}\n'.format(test_loss))
             print('\nTest Accuracy: %2d%% (%2d/%2d)' % (
                 100. * correct / total, correct, total))
         # call test function
         test(loaders_scratch, model_scratch, criterion_scratch, use_cuda)
Test Loss: 2.240855
Test Accuracy: 38% (325/836)
```

## Step 4: Create a CNN to Classify Dog Breeds (using Transfer Learning)

You will now use transfer learning to create a CNN that can identify dog breed from images. Your CNN must attain at least 60% accuracy on the test set.

## 1.1.12 (IMPLEMENTATION) Specify Data Loaders for the Dog Dataset

Use the code cell below to write three separate data loaders for the training, validation, and test datasets of dog images (located at dogImages/train, dogImages/valid, and dogImages/test, respectively).

If you like, **you are welcome to use the same data loaders from the previous step**, when you created a CNN from scratch.

### 1.1.13 (IMPLEMENTATION) Model Architecture

Use transfer learning to create a CNN to classify dog breed. Use the code cell below, and save your initialized model as the variable model\_transfer.

```
In [19]: import torchvision.models as models
    import torch.nn as nn

## TODO: Specify model architecture
    model_transfer = models.resnet101(pretrained=True)

for param in model_transfer.parameters():
        param.requires_grad = False

model_transfer.fc = nn.Linear(2048, 133, bias=True)
    fc_parameters = model_transfer.fc.parameters()

for param in fc_parameters:
        param.requires_grad = True

if use_cuda:
        model_transfer = model_transfer.cuda()
```

Downloading: "https://download.pytorch.org/models/resnet101-5d3b4d8f.pth" to /root/.torch/models/100%|| 178728960/178728960 [00:02<00:00, 78337779.83it/s]

**Question 5:** Outline the steps you took to get to your final CNN architecture and your reasoning at each step. Describe why you think the architecture is suitable for the current problem.

### **Answer:**

Steps: 1. import resnet101 model 2. just change its final FC layer to meet our requiremnts to output to 133 classes. 3. Used CrossEntropyLoss and SGD optimizer with learning rate of 0.001

I used resnet101 for thi task because resNet gains good accuracy with increased depths. As it has 101 layers, it capures very fine details. And it also easy to optimize. Now as its already trained on huge dataset, its an advantage of transfer learning to already have base weights. This results in good accuracy.

## 1.1.14 (IMPLEMENTATION) Specify Loss Function and Optimizer

Use the next code cell to specify a loss function and optimizer. Save the chosen loss function as criterion\_transfer, and the optimizer as optimizer\_transfer below.

### 1.1.15 (IMPLEMENTATION) Train and Validate the Model

Train and validate your model in the code cell below. Save the final model parameters at filepath 'model\_transfer.pt'.

```
In [21]: def train(n_epochs, loaders, model, optimizer, criterion, use_cuda, save_path):
             """returns trained model"""
             # initialize tracker for minimum validation loss
             valid_loss_min = np.Inf
             for epoch in range(1, n_epochs+1):
                 # initialize variables to monitor training and validation loss
                 train loss = 0.0
                 valid_loss = 0.0
                 ##################
                 # train the model #
                 ###################
                 model.train()
                 for batch_idx, (data, target) in enumerate(loaders['train']):
                     # move to GPU
                     if use_cuda:
                         data, target = data.cuda(), target.cuda()
                     ## find the loss and update the model parameters accordingly
                     # clear the gradients of all optimized variables
                     optimizer.zero_grad()
                     # forward pass: compute predicted outputs by passing inputs to the model
                     output = model(data)
                     # calculate the batch loss
                     loss = criterion(output, target)
                     # backward pass: compute gradient of the loss with respect to model paramet
                     loss.backward()
                     # perform a single optimization step (parameter update)
                     optimizer.step()
                     ## record the average training loss, using something like
                     train_loss = train_loss + ((1 / (batch_idx + 1)) * (loss.data - train_loss)
```

######################

```
model.eval()
                 for batch_idx, (data, target) in enumerate(loaders['valid']):
                     # move to GPU
                     if use_cuda:
                         data, target = data.cuda(), target.cuda()
                     # forward pass: compute predicted outputs by passing inputs to the model
                     output = model(data)
                     # calculate the batch loss
                     loss = criterion(output, target)
                     ## update the average validation loss
                     valid_loss = valid_loss + ((1 / (batch_idx + 1)) * (loss.data - valid_loss)
                 # print training/validation statistics
                 print('Epoch: {} \tTraining Loss: {:.6f} \tValidation Loss: {:.6f}'.format(
                     epoch,
                     train_loss,
                     valid_loss
                     ))
                 ## TODO: save the model if validation loss has decreased
                 if valid_loss <= valid_loss_min:</pre>
                     print('Validation loss decreased ({:.6f} --> {:.6f}). Saving model ...'.fo
                     valid_loss_min,
                     valid_loss))
                     torch.save(model.state_dict(), save_path)
                     valid_loss_min = valid_loss
             # return trained model
             return model
         # train the model
         model_transfer = train(15, loaders_transfer, model_transfer, optimizer_transfer, criter
         # load the model that got the best validation accuracy (uncomment the line below)
         model_transfer.load_state_dict(torch.load('model_transfer.pt'))
Epoch: 1
                 Training Loss: 4.799244
                                                 Validation Loss: 4.594285
Validation loss decreased (inf --> 4.594285). Saving model ...
Epoch: 2
                 Training Loss: 4.529651
                                                 Validation Loss: 4.277665
Validation loss decreased (4.594285 --> 4.277665). Saving model ...
                 Training Loss: 4.301835
                                                 Validation Loss: 3.998369
Epoch: 3
Validation loss decreased (4.277665 --> 3.998369). Saving model ...
                Training Loss: 4.089093
                                                 Validation Loss: 3.717441
Epoch: 4
Validation loss decreased (3.998369 --> 3.717441). Saving model ...
Epoch: 5
                Training Loss: 3.878784
                                               Validation Loss: 3.506076
```

```
Validation loss decreased (3.717441 --> 3.506076). Saving model ...
               Training Loss: 3.680005
Epoch: 6
                                        Validation Loss: 3.228996
Validation loss decreased (3.506076 --> 3.228996). Saving model ...
                Training Loss: 3.502679
                                               Validation Loss: 3.064612
Epoch: 7
Validation loss decreased (3.228996 --> 3.064612). Saving model ...
               Training Loss: 3.335519
Epoch: 8
                                             Validation Loss: 2.867664
Validation loss decreased (3.064612 --> 2.867664). Saving model ...
                Training Loss: 3.184310
Epoch: 9
                                             Validation Loss: 2.647885
Validation loss decreased (2.867664 --> 2.647885). Saving model ...
Epoch: 10
                 Training Loss: 3.046098
                                               Validation Loss: 2.483310
Validation loss decreased (2.647885 --> 2.483310). Saving model ...
                 Training Loss: 2.895712
                                              Validation Loss: 2.323523
Epoch: 11
Validation loss decreased (2.483310 --> 2.323523). Saving model ...
                 Training Loss: 2.786886 Validation Loss: 2.178687
Epoch: 12
Validation loss decreased (2.323523 --> 2.178687). Saving model ...
Epoch: 13
                 Training Loss: 2.679495
                                               Validation Loss: 2.135894
Validation loss decreased (2.178687 --> 2.135894). Saving model ...
                 Training Loss: 2.582039
                                                Validation Loss: 2.000326
Epoch: 14
Validation loss decreased (2.135894 --> 2.000326). Saving model ...
Epoch: 15
                 Training Loss: 2.490747 Validation Loss: 1.853126
Validation loss decreased (2.000326 --> 1.853126). Saving model ...
```

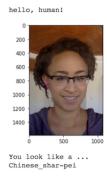
### 1.1.16 (IMPLEMENTATION) Test the Model

Try out your model on the test dataset of dog images. Use the code cell below to calculate and print the test loss and accuracy. Ensure that your test accuracy is greater than 60%.

```
In [22]: test(loaders_transfer, model_transfer, criterion_transfer, use_cuda)
Test Loss: 1.802369
Test Accuracy: 74% (626/836)
```

## 1.1.17 (IMPLEMENTATION) Predict Dog Breed with the Model

Write a function that takes an image path as input and returns the dog breed (Affenpinscher, Afghan hound, etc) that is predicted by your model.



## Sample Human Output

```
input_image = Image.open(img_path)
preprocess = transforms.Compose([
    transforms.Resize(256),
    transforms.CenterCrop(224),
    transforms.ToTensor(),
    transforms.Normalize(mean=[0.485, 0.456, 0.406], std=[0.229, 0.224, 0.225]),
])
input_tensor = preprocess(input_image)
input_batch = input_tensor.unsqueeze(0) # create a mini-batch as expected by the mo
# move the input to GPU for speed if available
if use_cuda:
    input_batch = input_batch.cuda()
with torch.no_grad():
    output = model_transfer(input_batch)
# convert output to predicted index
index = torch.max(output,1)[1].item()
return class_names[index]
```

## Step 5: Write your Algorithm

Write an algorithm that accepts a file path to an image and first determines whether the image contains a human, dog, or neither. Then, - if a **dog** is detected in the image, return the predicted breed. - if a **human** is detected in the image, return the resembling dog breed. - if **neither** is detected in the image, provide output that indicates an error.

You are welcome to write your own functions for detecting humans and dogs in images, but feel free to use the face\_detector and human\_detector functions developed above. You are required to use your CNN from Step 4 to predict dog breed.

Some sample output for our algorithm is provided below, but feel free to design your own user experience!

## 1.1.18 (IMPLEMENTATION) Write your Algorithm

```
In [24]: ### TODO: Write your algorithm.
         ### Feel free to use as many code cells as needed.
         def plot_image(img_path):
             img = Image.open(img_path)
             plt.imshow(img)
             plt.show()
         def run_app(img_path):
             ## handle cases for a human face, dog, and neither
             if face_detector(img_path):
                 print ("hello, human!")
                 predicted_breed = predict_breed_transfer(img_path)
                 plot_image(img_path)
                 print("You look like a ...: ", predicted_breed)
             elif dog_detector(img_path):
                 print ("hello, Doggie!")
                 predicted_breed = predict_breed_transfer(img_path)
                 plot_image(img_path)
                 print("You look like a ...: ", predicted_breed)
             else:
                 print ("Unable to identify...")
                 plot_image(img_path)
```

## Step 6: Test Your Algorithm

In this section, you will take your new algorithm for a spin! What kind of dog does the algorithm think that *you* look like? If you have a dog, does it predict your dog's breed accurately? If you have a cat, does it mistakenly think that your cat is a dog?

## 1.1.19 (IMPLEMENTATION) Test Your Algorithm on Sample Images!

Test your algorithm at least six images on your computer. Feel free to use any images you like. Use at least two human and two dog images.

**Question 6:** Is the output better than you expected :) ? Or worse :(? Provide at least three possible points of improvement for your algorithm.

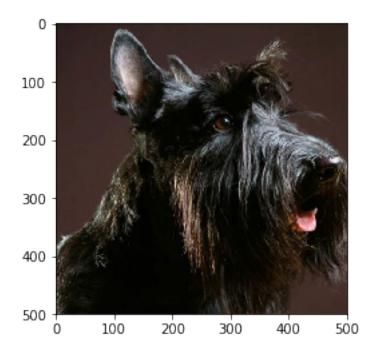
**Answer:** (Three possible points for improvement)

Improvement points: 1. proper image preprocessing needs to be done. i.e not only resizing or flip. 2. More data needs for training and validation. 3. Hyper parameter tuning. As during training i tried running with batch size 32, with learning rate 0.001, and performance decreased. Where as with batch size 16 and learning rate 0.02, it gave good result.

## Feel free to use as many code cells as needed.

```
import os
import glob
img_dir = "testImages" # Enter Directory of all images
data_path = os.path.join(img_dir,'*g')
files = glob.glob(data_path)
## suggested code, below
for file in files:
    run_app(file)
```

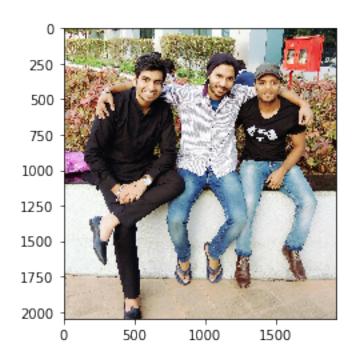
# hello, Doggie!



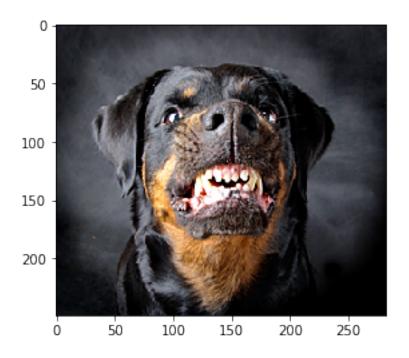
You look like a ...: Affenpinscher hello, human!



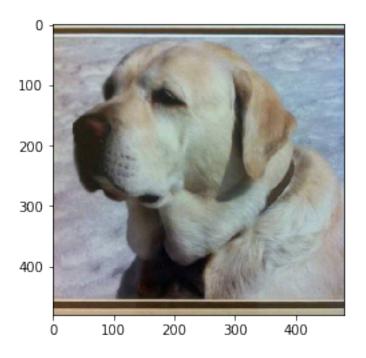
You look like a ...: Akita hello, human!



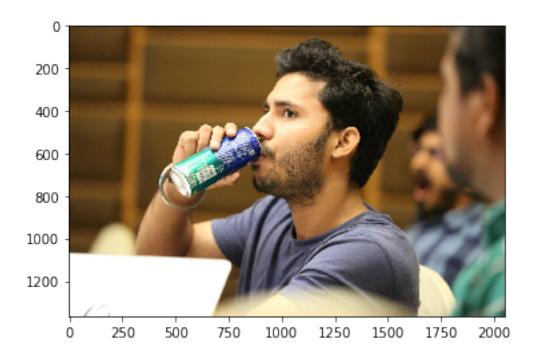
You look like a ...: Dalmatian hello, Doggie!



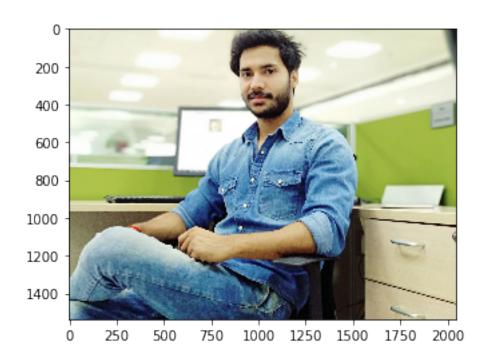
You look like a ...: Beauceron hello, Doggie!



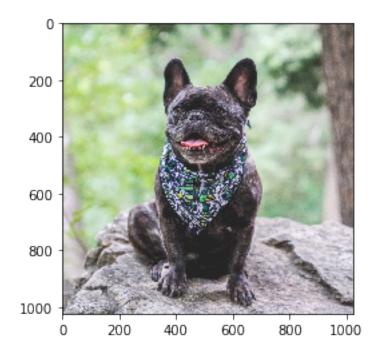
You look like a  $\ldots$ : Golden retriever Unable to identify...



hello, human!



You look like a ...: Bull terrier hello, Doggie!



```
You look like a ...: French bulldog

In [27]: """

References:

1. https://pytorch.org/tutorials/beginner/blitz/cifar10_tutorial.html
2. https://pytorch.org/tutorials/beginner/transfer_learning_tutorial.html
3. https://pytorch.org/docs/stable/nn.html#linear-layers
"""

Out[27]: '\nReferences:\n 1. https://pytorch.org/tutorials/beginner/blitz/cifar10_tutorial.html
In []:
```