Advanced Union-Find

Path Compression
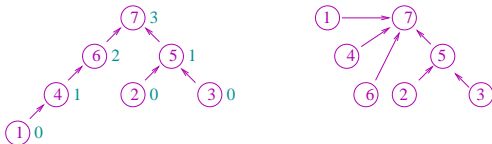
Algorithms: Design and Analysis, Part II

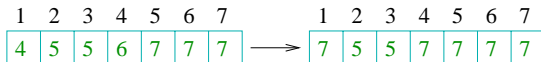# Path Compression

Idea: Why bother traversing a leaf-root path multiple times?

Path compression: After FIND(x), install shortcuts (i.e., revise parent pointers) to x's root all along the $x \to$ root path.
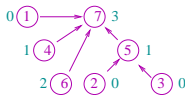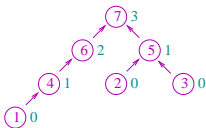

In array representation:

Con: Constant-factor overhead to FIND (from "multitasking").

Pro: Speeds up subsequent FINDs. [But by how much?]

On Ranks

Important: Maintain all rank fields EXACTLY as without path compression.

- Ranks initially all 0
- In UNION, new root = old root with bigger rank
- When merging two nodes of common rank r, reset new root's rank to $r + 1$

Bad news: Now rank[x] is only an upper bound on the maximum number of hops on a path from a leaf to x
(which could be much less)

Good news: Rank Lemma still holds ($\leq n/2^r$ objects with rank r)

Also: Still always have rank[parent[x]]>rank[x] for all non-roots x

Hopcroft-Ullman Theorem

Theorem: [Hopcroft-Ullman 73] With Union by Rank and path compression, m Union+Find operations take $O(m \log^* n)$ time, where $\log^* n =$ the number of times you need to apply log to n before the result is ≤ 1.

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Quiz on log*

Question: What is $\log^*(2^{65536})$?

A) 2
B) 5
C) 16
D) 65536

In general: $\log^*(2^{2^{\cdots^{2} \ t \ \text{times} \ \cdots^{2}}}) = t$

Measuring Progress

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