

Medical Laser Control System - Architecture Overview

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Executive Summary

This document outlines the architecture for a medical laser control system designed for clinical use. The system integrates laser control, linear actuator positioning, GPIO-based safety interlocks, camera-based alignment, and comprehensive patient/session tracking.

System Purpose

Control and monitor medical laser treatments with:

- Precise power and timing control
- Adjustable ring size via linear actuator
- Real-time safety monitoring via photodiode and hotspot smoothing device
- Camera-based alignment and focus verification
- Complete treatment recording and audit trail
- Longitudinal patient tracking across multiple sessions

Technology Stack

Core Technologies

- **Language:** Python 3.10+
- **GUI Framework:** PyQt6 (modern, cross-platform, feature-rich)
- **OS Platform:** Windows 10 (Mini PC)
- **Database:** SQLite (local, single-user)

Key Libraries

```
# UI & Visualization
PyQt6           # Main GUI framework
pyqtgraph       # Real-time plotting (photodiode, power graphs)

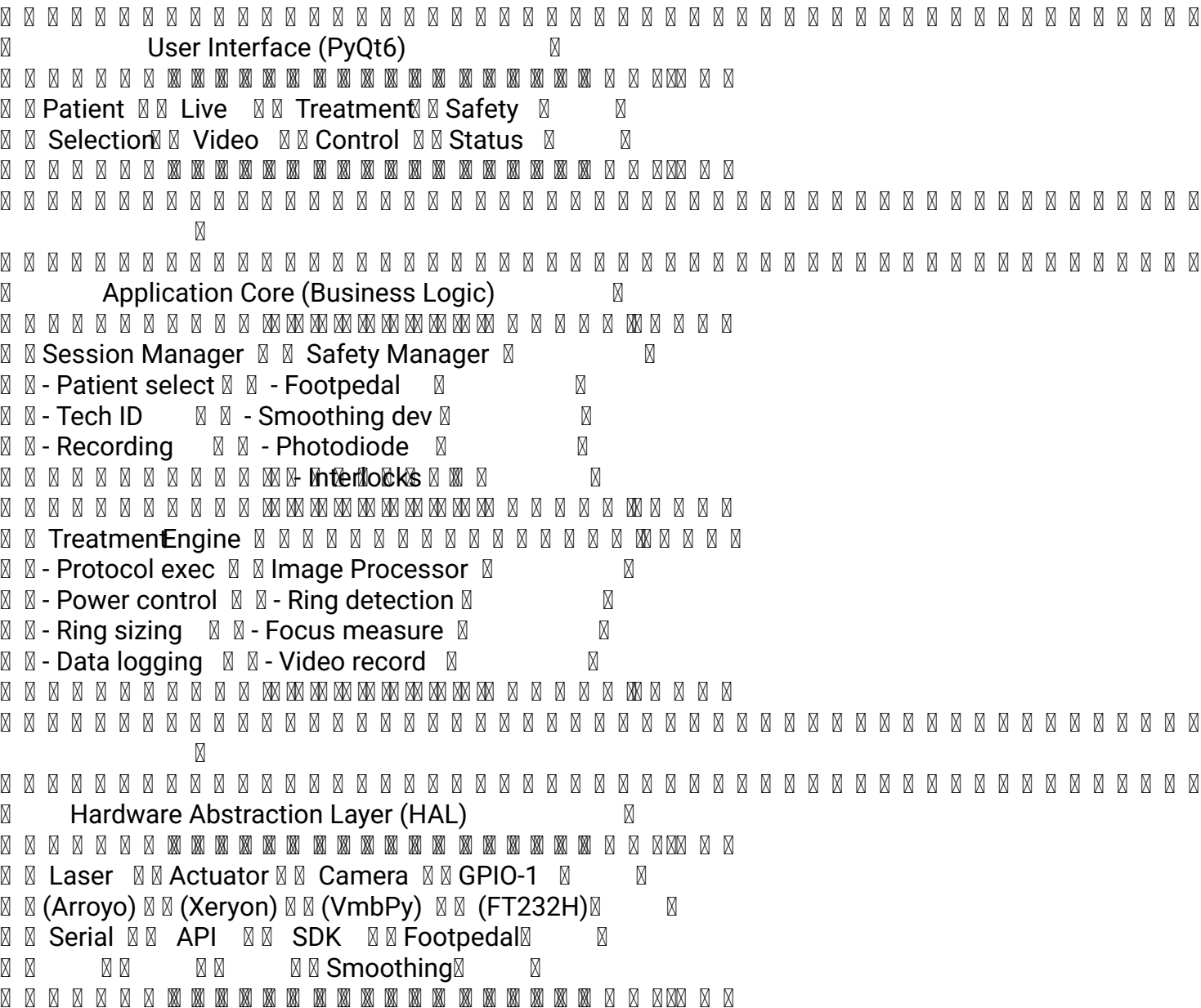
# Image Processing & Computer Vision
opencv-python (cv2) # Ring detection, focus measurement
numpy           # Image array operations
pillow          # Image saving/conversion
```

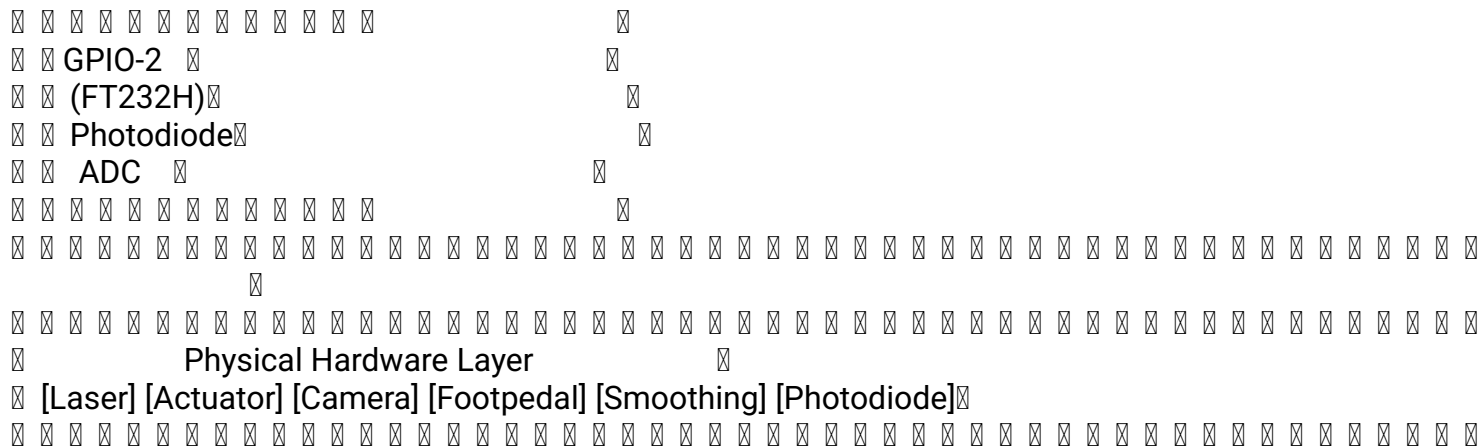
Hardware Interfaces
pyserial # Arroyo laser serial communication
adafruit-blinka # FT232H GPIO/ADC support
board, busio # Adafruit pin definitions
Xeryon library # Linear actuator control (existing)
VmbPy SDK # Allied Vision camera interface (existing)

Database & Data Management
sqlite3 # Built-in database
sqlalchemy # ORM for cleaner database code
alembic # Database migrations

Logging & Utilities
logging # Event logging
python-dateutil # Timestamp handling
pydantic # Configuration validation
jsonschema # Protocol validation

High-Level Architecture





Hardware Components

1. Laser Controller

- **Device:** Arroyo Instruments TEC Controller
- **Interface:** Serial communication (RS-232/USB)
- **Library:** Custom Python class for Arroyo serial protocol
- **Control:** Power settings, on/off, status queries

2. Linear Actuator

- **Device:** Xeryon linear stage
- **Interface:** External API library
- **Function:** Controls laser ring size by adjusting optical position
- **Control:** Position commands & Ring diameter mapping

3. Camera System

- **SDK:** VmbPy (Allied Vision Vimba Python SDK)
- **Interface:** USB/GigE
- **Functions:** - Live video feed display - Manual focus/alignment by operator - Ring detection (circle finding) - Focus quality measurement - Treatment recording

4. GPIO Controller 1 - Safety Interlocks (FT232H)

- **Device:** Adafruit FT232H Breakout (USB-C)
- **Library:** adafruit-blinka, board, busio
- **Connections:** - **Footpedal Input:** Deadman switch - MUST be depressed to enable laser firing - **Hotspot Smoothing Device:** Signal monitoring - MUST be present and healthy for laser operation

5. GPIO Controller 2 - Photodiode Monitoring (FT232H)

- **Device:** Adafruit FT232H Breakout (USB-C)

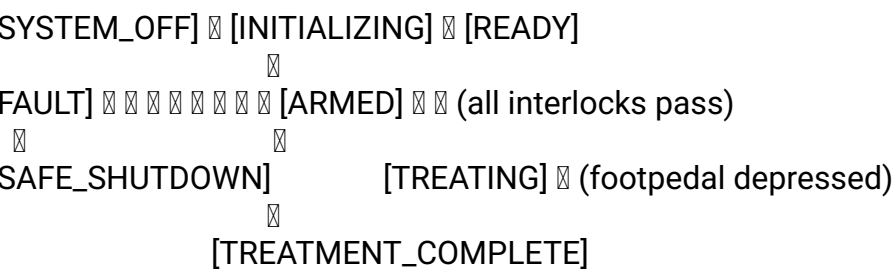
- **Function:** ADC reading of photodiode voltage
- **Purpose:** Real-time measurement of laser output via optical pickoff
- **Monitoring:** Validates expected power output, detects anomalies

Safety Architecture

Critical Safety Interlocks (All Must Pass for Laser Operation)

1. **Footpedal Deadman Switch** (GPIO-1) - Type: Active-high requirement - Behavior: Laser can only fire while footpedal is DEPRESSED - Fail-safe: Releasing pedal immediately disables laser - Poll rate: 100Hz minimum
2. **Hotspot Smoothing Device** (GPIO-1) - Type: Signal health monitoring - Behavior: Device must output valid signal - Fail-safe: Loss of signal triggers immediate laser shutdown - Validation: Signal presence + value within acceptable range
3. **Photodiode Feedback** (GPIO-2 ADC) - Type: Output power verification - Behavior: Measured power must match commanded power - Fail-safe: Deviation beyond threshold triggers shutdown - Monitoring: Continuous during treatment
4. **Software E-stop** - Type: UI button + keyboard shortcut (e.g., ESC key) - Behavior: Immediate treatment halt - Priority: Highest - bypasses all queues
5. **Session Active** - Type: Logical interlock - Behavior: Laser cannot fire outside active treatment session - Purpose: Ensures all actions are logged and attributed
6. **Image Valid** - Type: Camera feed health check - Behavior: Valid image frame received within timeout - Purpose: Ensures alignment/monitoring capability

Safety State Machine



Any interlock failure → Immediate transition to FAULT state → Safe shutdown

Session Workflow

Session Initialization

1. Application Launch
→
2. Hardware Connection & Self-Test
→
3. Tech ID Entry (required for all operations)
→

4. Patient Selection Screen

- ☒ ☒ Option A: Select Existing Patient (search by patient code)
- ☒ ☒ ☒ Load patient history
- ☒ ☒ Option B: Create New Patient
- ☒ ☒ Generate patient code, enter demographics
- ☒

5. Session Creation

- ☒ ☒ Log: Patient ID, Tech ID, Start Time

Pre-Treatment Setup

1. Display Live Camera Feed

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2. Operator Manual Actions (outside software control):

- ☒ ☒ Adjust focus (physical optics)
- ☒ ☒ Align laser ring to treatment site
- ☒ ☒ Position patient
- ☒

3. Software Assistance:

- ☒ ☒ Real-time focus quality indicator
- ☒ ☒ Ring detection overlay
- ☒ ☒ Alignment guides
- ☒

4. Operator confirms ready

Treatment Execution

1. Select Treatment Protocol

- ☒ ☒ Load saved protocol, OR
- ☒ ☒ Create/modify custom protocol
- ☒

2. Safety Pre-checks

- ☒ ☒ All hardware connected
- ☒ ☒ Interlocks in valid state
- ☒ ☒ Camera image valid
- ☒ ☒ Session active
- ☒

3. Operator initiates FIRE trigger

☒

4. System transitions to ARMED state

☒

5. Treatment Loop (while footpedal depressed):

- ☒ ☒ Execute protocol step (power, ring size)
- ☒ ☒ Monitor photodiode
- ☒ ☒ Monitor smoothing device
- ☒ ☒ Capture camera frames
- ☒ ☒ Log all parameters (timestamp, power, position, voltage)
- ☒ ☒ Check safety interlocks (every cycle)
- ☒

6. Treatment completion or pedal release

☒

7. Return to READY state

Session Recording

Continuous Recording During Treatment:

- Video: Full treatment video saved to session folder
- Event log: Every parameter change, every cycle
- Images: Periodic snapshots + key events
- Metadata: Timestamps, device states, operator actions

Data Storage Location:

```
data/
├── sessions/
│   ├── session_YYYYMMDD_HHMMSS_/
│   │   ├── video.avi
│   │   ├── events.json
│   │   ├── snapshots/
│   │   │   ├── frame_001.png
│   │   │   ├── frame_002.png
│   │   └── metadata.json
```

Session Closure

1. Operator ends treatment
 └─
2. Save final recordings
 └─
3. Add session notes
 └─
4. Mark session as complete in database
 └─
5. Update patient last_modified timestamp
 └─
6. Return to Patient Selection (for next patient)

Treatment Protocol Engine

Protocol Structure

```
{
  "protocol_name": "Standard Treatment A",
  "description": "5W constant for 60s at 3mm ring",
  "steps": [
    {
      "step_number": 1,
      "duration_seconds": 60,
      "power_start_watts": 5.0,
      "power_end_watts": 5.0, # Same as start = constant
      "ring_size_mm": 3.0,
      "ramp_type": "constant" # or "linear", "logarithmic"
    }
  ]
}
```

```
]
}
```

Protocol Types

1. **Constant Power** - Fixed power for duration - Example: 5W for 60 seconds
2. **Linear Ramp** - Power increases/decreases linearly - Example: Ramp from 2W to 6W over 90 seconds
3. **Multi-Step** - Multiple sequential steps - Example: 3W for 30s, then 5W for 30s, then 3W for 30s
4. **Custom** - In-app protocol builder - Adjust any parameter on the fly

Real-Time Protocol Adjustment

- Operator can pause treatment
- Modify power/ring size during pause
- Changes logged as protocol deviation
- Resume with modified parameters

Image Processing Pipeline

Pipeline Overview

Camera Frame

⊠

[Preprocessing]

⊠ ⊠ Grayscale conversion

⊠ ⊠ Noise reduction

⊠ ⊠ Contrast enhancement

⊠

[Ring Detection]

⊠ ⊠ Hough Circle Transform

⊠ ⊠ Edge detection refinement

⊠ ⊠ Circle parameters (center, radius)

⊠

[Focus Measurement]

⊠ ⊠ Laplacian variance (sharpness)

⊠ ⊠ Gradient magnitude

⊠ ⊠ Focus score (0-100)

⊠

[Display Overlay]

⊠ ⊠ Detected ring outline

⊠ ⊠ Focus indicator

⊠ ⊠ Alignment guides

⊠

[Recording]

⊠ ⊠ Save annotated frames

Ring Detection Algorithm

```
def detect_laser_ring(frame):
    """
    Detect circular laser ring in camera frame

    Returns:
        center (x, y), radius, confidence
    """
    # 1. Preprocess
    gray = cv2.cvtColor(frame, cv2.COLOR_BGR2GRAY)
    blurred = cv2.GaussianBlur(gray, (9, 9), 2)

    # 2. Detect circles (Hough Transform)
    circles = cv2.HoughCircles(
        blurred,
        cv2.HOUGH_GRADIENT,
        dp=1,
        minDist=100,
        param1=50,
        param2=30,
        minRadius=20,
        maxRadius=200
    )

    # 3. Select best circle (brightest, most circular)
    # ... validation logic ...

    return center, radius, confidence
```

Focus Quality Measurement

```
def calculate_focus_score(frame):
    """
    Calculate image sharpness/focus quality

    Returns:
        focus_score (0-100, higher = better focus)
    """
    gray = cv2.cvtColor(frame, cv2.COLOR_BGR2GRAY)

    # Laplacian variance method
    laplacian = cv2.Laplacian(gray, cv2.CV_64F)
    variance = laplacian.var()

    # Normalize to 0-100 scale
    focus_score = min(100, variance / 10) # Calibrate threshold

    return focus_score
```

Data Architecture

Database: SQLite

Location: data/laser_control.db

Key Tables:

- 1. `patients` - Patient records (anonymized)
- 2. `sessions` - Treatment sessions
- 3. `treatment_events` - Detailed event log (high frequency)
- 4. `protocols` - Saved treatment protocols
- 5. `calibrations` - Device calibration data
- 6. `safety_log` - Safety events and faults
- 7. `tech_users` - Technician/operator accounts

See: 02_database_schema.md for full schema

Event Logging Strategy

Two-tier logging:

- 1. **High-frequency data** (100Hz+): JSON files in session folder - Photodiode readings - Camera frame metadata - Real-time interlock states
- 2. **Event-based data**: SQLite database - Protocol steps - Power changes - Ring size adjustments - Safety triggers - User actions

Project Directory Structure

```
laser-control-system/  
├── src/  
│   ├── main.py           # Application entry point  
│   └──  
├── config/  
│   ├── settings.py       # User-configurable settings  
│   ├── safety_limits.py  # Hard-coded safety parameters  
│   └── hardware_config.py # Hardware connection parameters  
└── ui/  
    ├── main_window.py    # Main application window  
    ├── patient_selection.py # Patient selection/creation dialog  
    ├── treatment_control.py # Treatment control panel  
    ├── video_display.py   # Live camera feed widget  
    ├── protocol_builder.py # Protocol creation/editing UI  
    ├── safety_panel.py    # Safety status indicators  
    └── widgets/           # Reusable UI components  
├── core/  
│   ├── session_manager.py # Session lifecycle management  
│   ├── treatment_engine.py # Protocol execution engine  
│   ├── safety_manager.py  # Safety interlock orchestration  
│   └── recording_manager.py # Video/data recording
```

```

0 calibration_manager.py # Calibration routines
0
0 hardware/
0 base.py # Abstract hardware device class
0 laser_controller.py # Arroyo laser interface
0 actuator_controller.py # Xeryon actuator interface
0 camera_controller.py # VmbPy camera interface
0 gpio_interlocks.py # GPIO-1: Footpedal + Smoothing
0 gpio_photodiode.py # GPIO-2: Photodiode ADC
0 hardware_manager.py # Unified hardware coordination
0
0 image_processing/
0 ring_detector.py # Laser ring circle detection
0 focus_analyzer.py # Focus quality measurement
0 video_recorder.py # Video file writing
0 frame_processor.py # Image preprocessing pipeline
0
0 database/
0 models.py # SQLAlchemy ORM models
0 db_manager.py # Database operations
0 session_logger.py # High-frequency session logging
0 migrations/ # Alembic migration scripts
0
0 utils/
0 logger.py # Application logging setup
0 validators.py # Input validation functions
0 exceptions.py # Custom exception classes
0 constants.py # System-wide constants
0
0 data/
0 laser_control.db # SQLite database
0 sessions/ # Per-session data folders
0 session_/
0 video.avi
0 events.json
0 photodiode_log.csv
0 snapshots/
0 metadata.json
0 logs/ # Application logs
0 app_YYYYMMDD.log
0 errors_YYYYMMDD.log
0
0 docs/
0 architecture/
0 01_system_overview.md # This file
0 02_database_schema.md
0 03_safety_system.md
0 04_treatment_protocols.md
0 05_image_processing.md
0 user_manual.md
0 installation.md
0
0 tests/
0 test_hardware/

```

```
test_core/
test_safety/
test_integration/
requirements.txt
setup.py
README.md
```

Development Phases

Phase 1: Foundation (Hardware + Safety)

- ☐ Hardware abstraction layer for all devices
- ☐ Safety interlock system
- ☐ Basic GUI shell (PyQt6)
- ☐ Database schema and basic CRUD operations

Phase 2: Core Treatment Features

- ☐ Patient selection and session management
- ☐ Treatment protocol engine
- ☐ Manual treatment control (constant power)
- ☐ Basic event logging

Phase 3: Advanced Features

- ☐ Ring detection and focus measurement
- ☐ Video recording
- ☐ Protocol builder UI
- ☐ Advanced ramping protocols

Phase 4: Polish & Validation

- ☐ Comprehensive testing
- ☐ User manual
- ☐ Calibration procedures
- ☐ Performance optimization

Key Design Principles

- Safety First**: Multiple redundant interlocks, fail-safe design
- Audit Trail**: Every action logged, immutable records
- User Workflow**: Match clinical workflow, minimize clicks
- Hardware Abstraction**: Easy to swap/upgrade devices
- Modularity**: Loosely coupled components
- Testability**: Unit tests for critical paths
- Documentation**: Code + user docs maintained together

Next Documentation Files

1. `02_database_schema.md` - Complete SQL schema with indexes and constraints
2. `03_safety_system.md` - Detailed safety architecture and fault handling
3. `04_treatment_protocols.md` - Protocol format, execution engine, validation
4. `05_image_processing.md` - Computer vision algorithms and calibration

Document Owner: System Architect **Last Updated:** 2025-10-15 **Review Frequency:** Weekly during development