

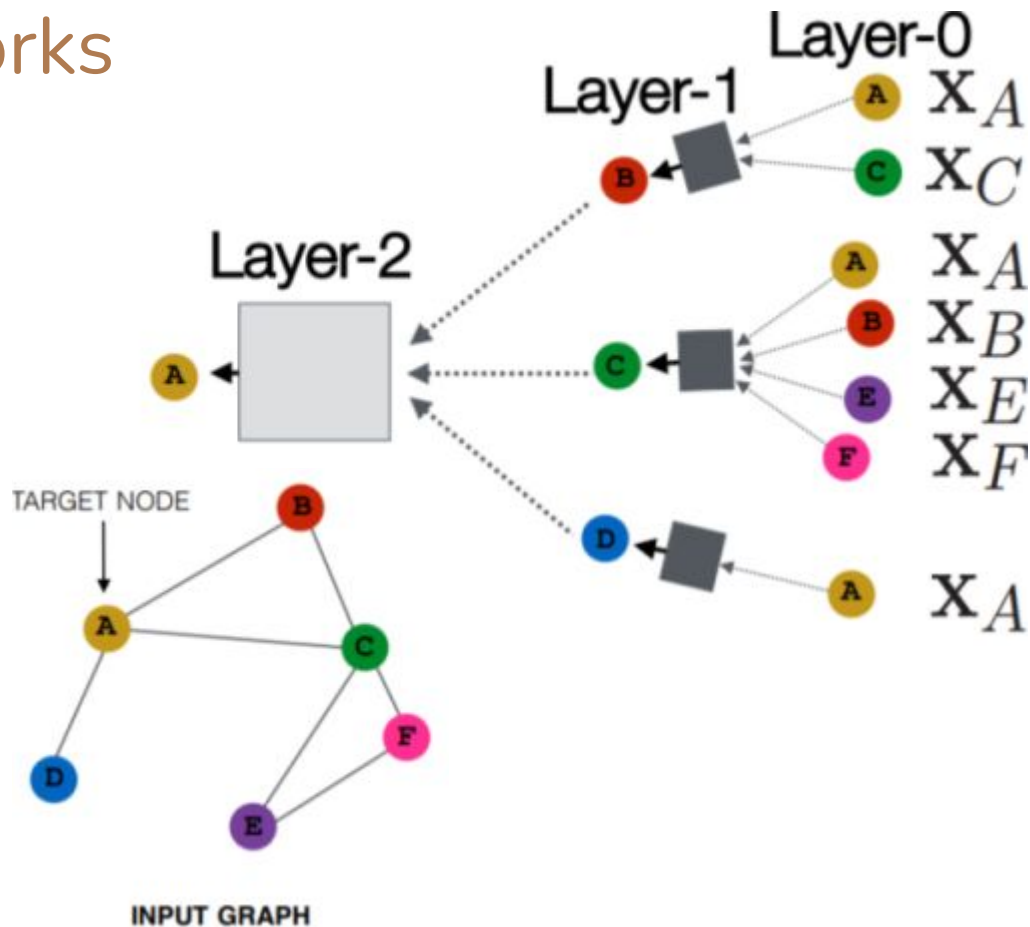
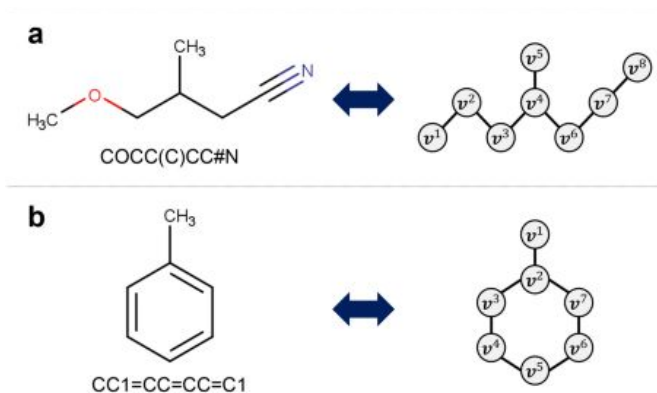
Training of Graph Neural Networks using Coarsening and Dynamic Mode Decomposition

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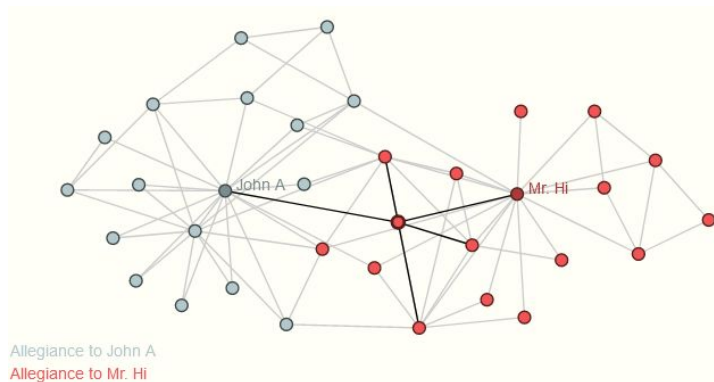
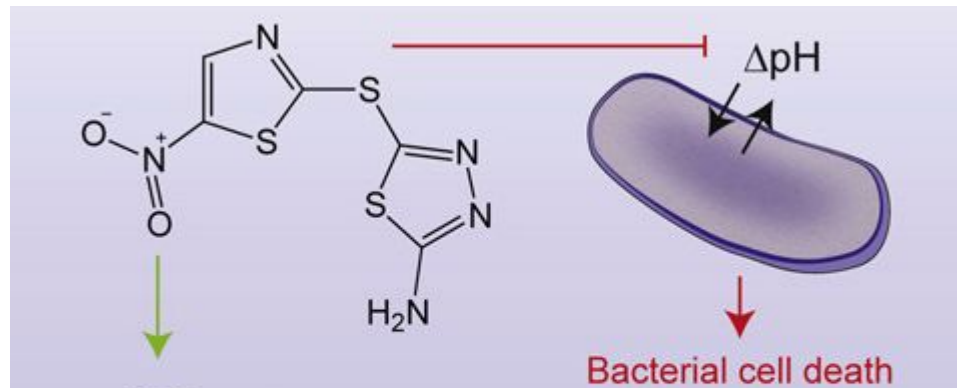
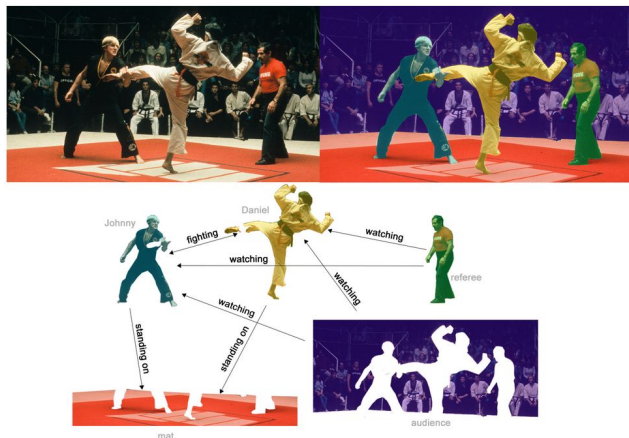
Graph Neural Networks

- Embeddings
 - Vertex Level
 - Edge Level
 - Graph Level



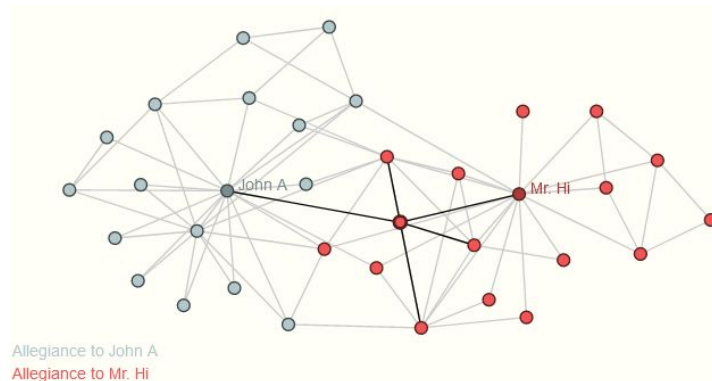
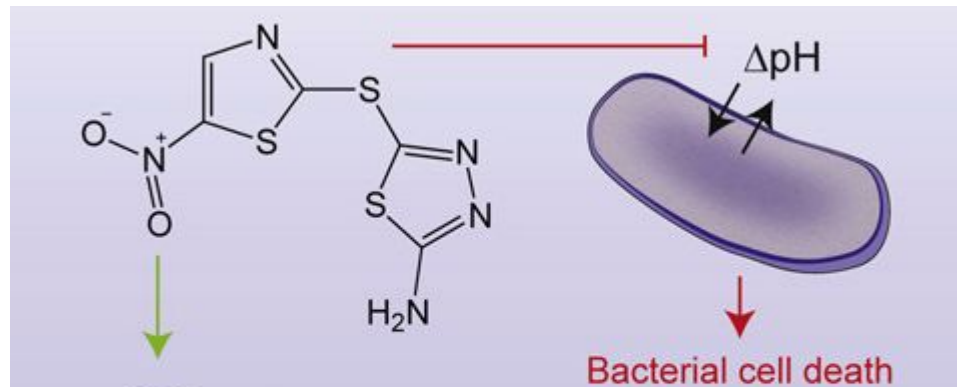
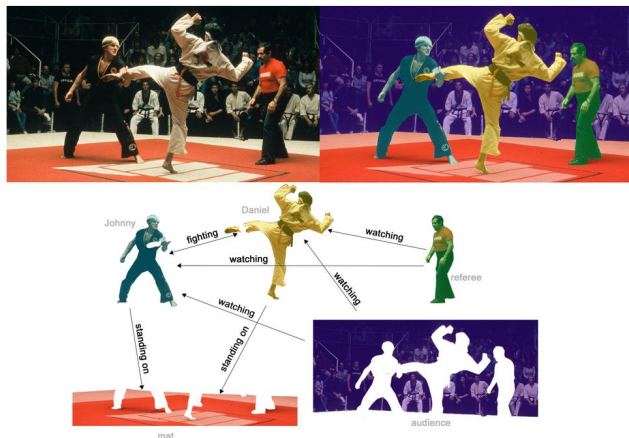
Graph Neural Network Tasks

- Graph Classification
- Vertex Classification
- Edge prediction



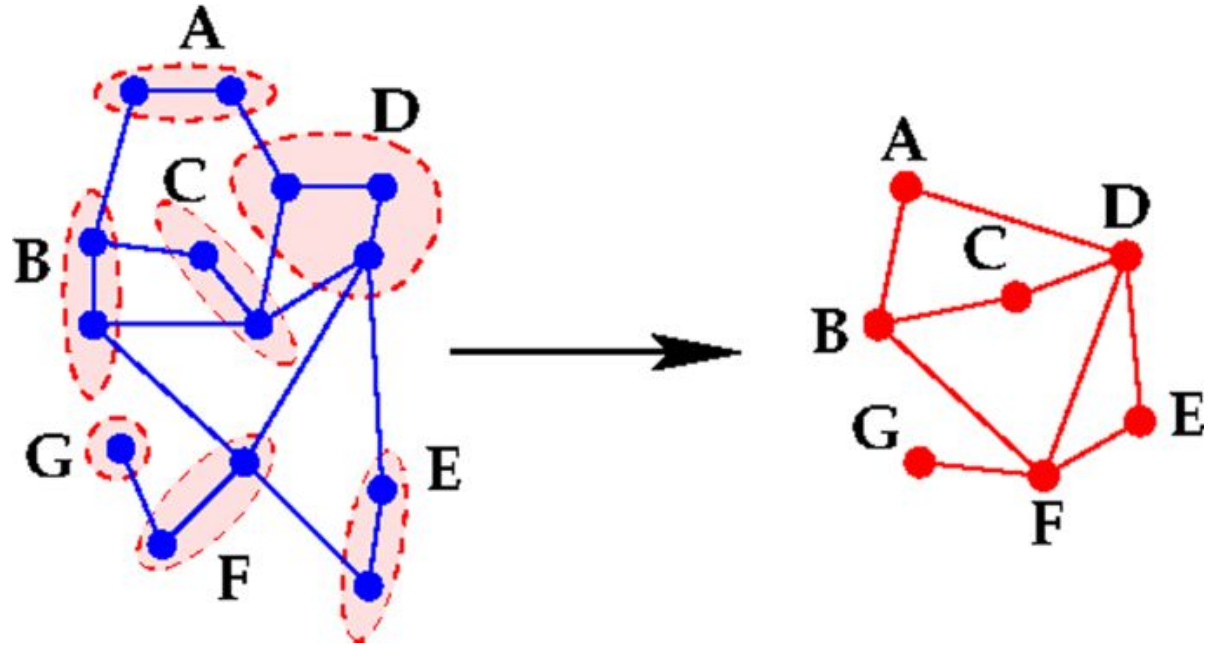
Graph Neural Network Tasks

- Graph Classification
- Vertex Classification
- Edge prediction



Coarsening

- Spectral Coarsening
- Multilevel coarsening



Dynamic Mode Decomposition

- SCHMID, P. (2010). Dynamic mode decomposition of numerical and experimental data. *Journal of Fluid Mechanics*, 656, 5-28. doi:10.1017/S0022112010001217
- Used to model the evolution of a system.
- Matrix \mathbf{W} , where rows represent the state at each timestep

Compute low-cost SVD decomposition: $\mathbf{W}^{\ell,m-} = \mathbf{U}_r^{\ell,m} \Sigma_r^{\ell,m} \mathbf{V}_r^{\ell,m T}$;

Select r modes such that $\Sigma_r^{\ell,m}[r, r] / \Sigma_r^{\ell,m}[0, 0] > \text{DMD filter tolerance}$;

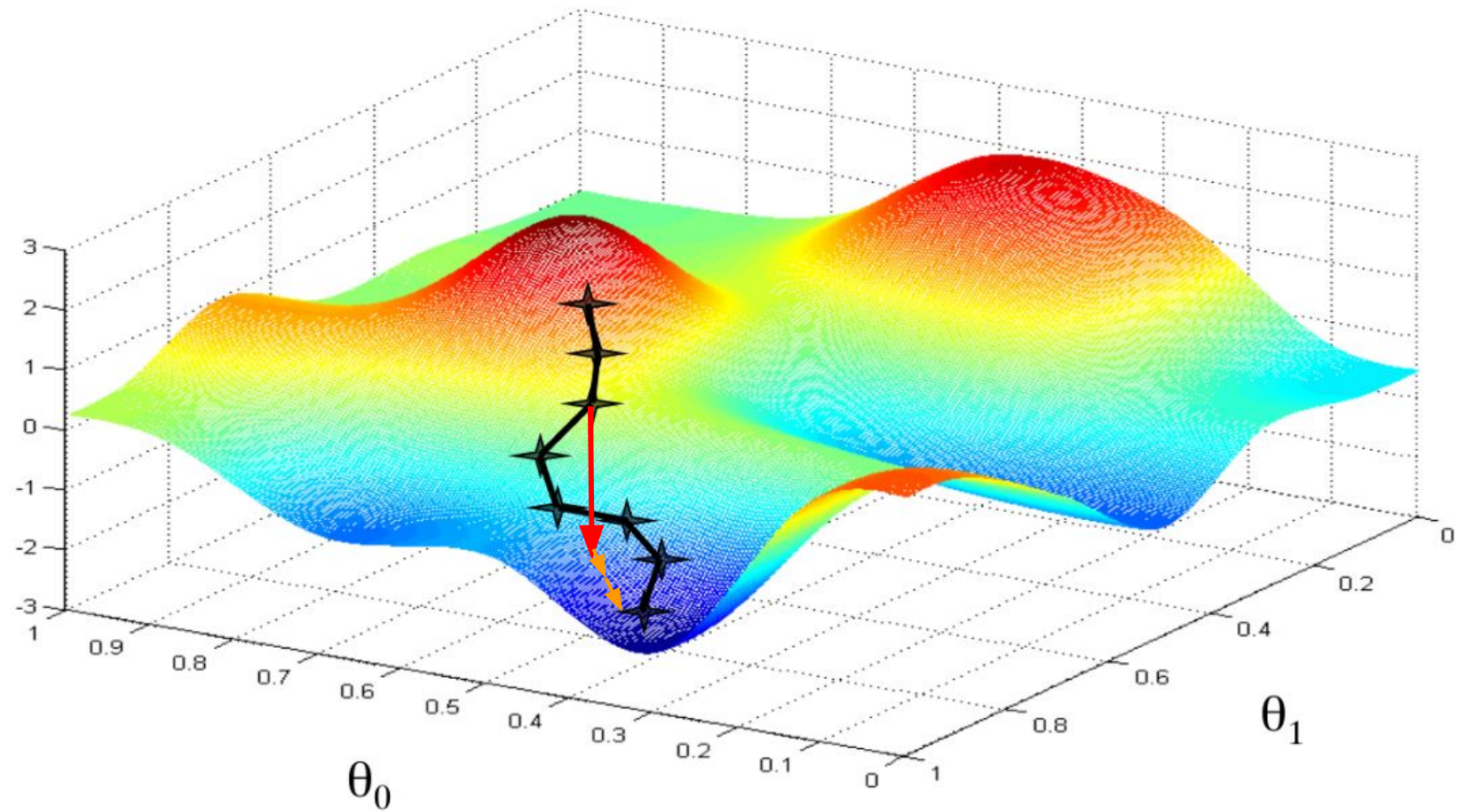
Build reduced Koopman operator with $\mathbf{A}_r^{\ell,m} = \mathbf{U}_r^{\ell,m T} \mathbf{W}^{\ell,m+} \mathbf{V}_r^{\ell,m} \Sigma_r^{\ell,m-1}$.

Perform eigendecomposition of the reduced Koopman operator with $\mathbf{A}_r^{\ell,m} \mathbf{Y}_r^{\ell,m} = \Lambda_r^{\ell,m} \mathbf{Y}_r^{\ell,m}$

Compute the matrix of weights modes: $\Phi_r^{\ell,m} = \mathbf{U}_r^{\ell,m+} \mathbf{Y}_r^{\ell,m}$ Compute initial

DMD condition: $\mathbf{b}_r^{\ell,m} = \Phi_r^{\ell,m T} \mathbf{w}^{\ell,m}$.

Evolve weights with DMD using $\mathbf{w}^{\ell,s} = \Phi_r^{\ell,m} \left[\Lambda_r^{\ell,m} \right]^{s-m} \mathbf{b}_r^{\ell,m}$



Algorithm 1: Acceleration of backpropagation with Dynamic Mode Decomposition

Input: m , DMD filter tolerance, s , Backpropagation Parameters, Total Epochs

Result: Trained weights $\mathbf{w}^\ell, \forall \ell \in \mathcal{H}_\ell$

$bp_{iter} = 0;$

while $epoch \leq Total\ Epochs$ **do**

 Do backpropagation step;

 Extract weights $\mathbf{w}^{\ell, bp_{iter}}, \forall \ell \in \mathcal{H}_\ell;$

 Store weights: $\mathbf{W}^\ell \leftarrow [\mathbf{W}^\ell \mathbf{w}^{\ell, bp_{iter}}], \forall \ell \in \mathcal{H}_\ell;$

$bp_{iter} + = 1$;

if $bp_{iter} == m$ **then**

for $\ell \in \mathcal{H}_\ell$ **do**

 Build training matrices: \mathbf{W}^{ℓ, m^-} and \mathbf{W}^{ℓ, m^+} with (1) and (2);

 Compute low-cost SVD decomposition: $\mathbf{W}^{\ell, m^-} = \mathbf{U}_r^{\ell, m} \mathbf{\Sigma}_r^{\ell, m} \mathbf{V}_r^{\ell, m^T};$

 Select r modes such that $\mathbf{\Sigma}_r^{\ell, m}[r, r] / \mathbf{\Sigma}_r^{\ell, m}[0, 0] > \text{DMD filter tolerance};$

 Build reduced Koopman operator with (3);

 Perform eigendecomposition of the reduced Koopman operator with (4) ;

 Compute the matrix of weights modes: $\mathbf{\Phi}_r^{\ell, m} = \mathbf{U}_r^{\ell, m^+} \mathbf{Y}^{\ell, m}$ Compute initial

 DMD condition: $\mathbf{b}_r^{\ell, m} = \mathbf{\Phi}_r^{\ell, m^T} \mathbf{w}^{\ell, m};$

 Evolve weights with DMD using (5) ;

 Assign updated weights to layer ℓ in the neural network;

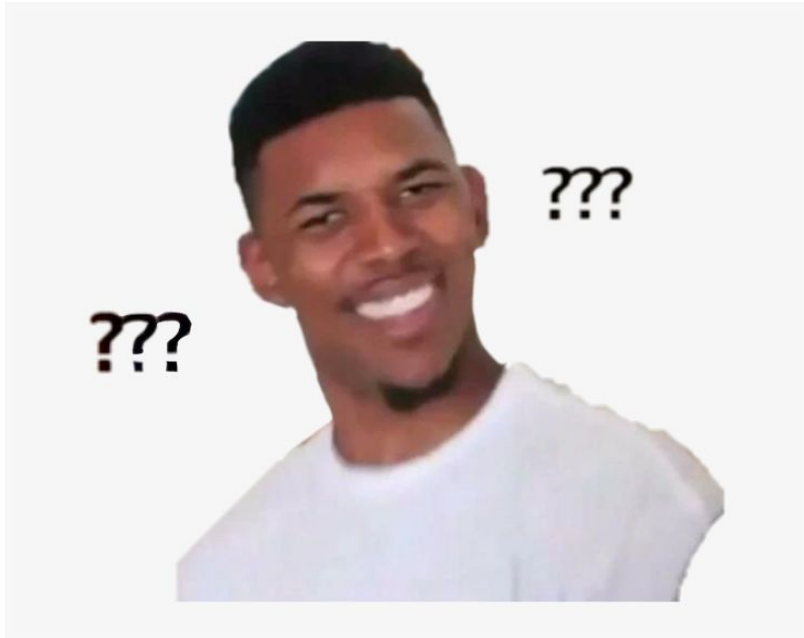
end

$bp_{iter} = 0;$

end

end

Results



Data: r/Place

- A collaborative project hosted on reddit.
- Registered users could place a single pixel on the canvas from a set of colors.
- Had to wait 5 to 10 minutes before placing another pixel.
- Alone, one user could have little impact on the canvas. Communities would need to work together to construct designs.



r/Place as a Graph

- CSV file with 1 line per placed tile
 - User ID
 - Timestamp
 - x coordinate
 - y coordinate
 - Color
- Can consider the canvas as Graph and the pixels as vertices.

Next Steps and Ideas

- Interweaving with Coarsening
- Depth vs Height
- Implement in parallel C

References

- <https://distill.pub/2021/gnn-intro/>
- <https://neptune.ai/blog/graph-neural-network-and-some-of-gnn-applications>
- [DeepMind TensorFlow ML Tech Talks Petar Veličković](#)