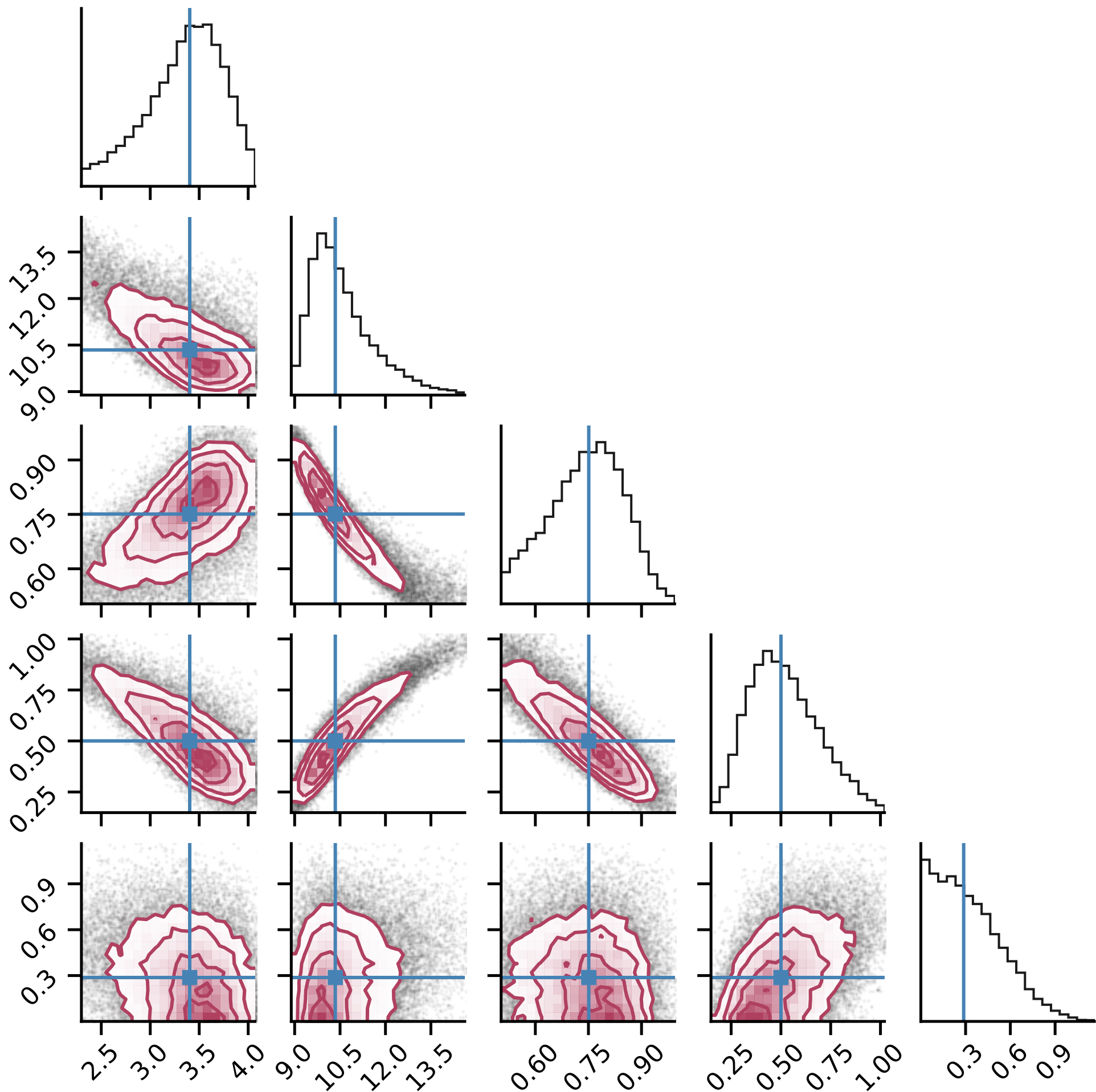


Noise:
 $[\text{km}^2 \text{ s}^{-1}]$
 RMS seeing:
 s_0 [parsec]
 Power-law
 slope: m
 Vel. variance:
 $\sigma^2 [\text{km}^2 \text{ s}^{-1}]$



Corr. length:
 r_0 [parsec]

Vel. variance:
 $\sigma^2 [\text{km}^2 \text{ s}^{-1}]$

Power-law
 slope: m

RMS seeing:
 s_0 [parsec]

Noise:
 $[\text{km}^2 \text{ s}^{-1}]$