Weakest Preconditions

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The notion of weakest precondition in program analysis derives from the work of Dijkstra [1]. He introduced the Guarded Command Language as a simple modeling language for program specification e.g.

Dijkstra introduced the Guarded Command Language (GCL) with the grammar

$$\begin{array}{lll} S &::= & \mathsf{skip} & \mid \; x := E \; \mid \; S_1; \; S_2 \\ & \mid & \mathsf{if} \; B_1 \to S_1 \mathbin{[}\negthinspace{[}\negthinspace{]}\negthinspace{[}\negthinspace{B_2} \to S_2 \mathbin{[}\negthinspace{]}\negthinspace{[}\negthinspace{]}\negthinspace{]}\negthinspace{[}\negthinspace{I}\negthinspace{[}\negthinspace{B_n} \to S_n \; \mathsf{od} \\ \\ & \mid & \mathsf{do} \; B_1 \to S_1 \mathbin{[}\negthinspace{[}\negthinspace{]}\negthinspace{B_2} \to S_2 \mathbin{[}\negthinspace{[}\negthinspace{]}\negthinspace{]}\negthinspace{[}\negthinspace{I}\negthinspace{]}\negthinspace{[}\negthinspace{B_n} \to S_n \; \mathsf{od} \end{array}$$

where the B_i are Boolean expressions. The B_i are called *guards* because they guard the corresponding statements S_i . The symbol [] is the *nondeterministic choice operator* and is not to be confused with []. In if and do statements, a clause $B_i \to S_i$ is said to be *enabled* if its guard B_i is true.

So, given a program S and a postcondition φ , we define the weakest precondition as the weakest property of the input state that guarantees that S will terminate with the postcondition φ , denoted $wp(S,\varphi)$. In the definition of GCL, we can provide definitions of how to compute the weakest precondition for various program statements. For example, for an assignment statement x:=E, we have that

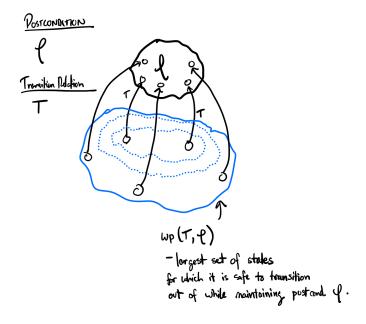
$$wp(x := E, \varphi) \equiv \varphi\{E/x\}$$

where $\varphi\{E/x\}$ represents the property φ with appearances of x in φ replaced with E. For example,

$$wp(x := x + 1, x = 3) \equiv (x = 3)\{x + 1/x\}$$

 $\equiv (x + 1) = 3$
 $\equiv x = 2$

From a more semantic perspective, we can also think about weakest preconditions in terms of symbolic transition relations. If we have a transition relation T and a postcondition φ (i.e. a state predicate), the weakest precondition of T with respect to φ is the weakest predicate P (in other words, the largest set of states) such that a transition out of any state in P will uphold the property φ .



We can also consider weakest precondition computation as a kind of *backwards symbolic execution*. That is, we start from a given postcondition predicate, and a given transition relation, and execute the transition relation backwards to compute the states contained in the weakest precondition.

References

[1] Edsger W. Dijkstra. Guarded commands, nondeterminacy and formal derivation of programs. $Commun.\ ACM,\ 18(8):453-457,\ {\rm aug}\ 1975.$