

# Spinal Atomic Lambda-Calculus

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## Abstract

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**2012 ACM Subject Classification** General and reference → General literature; General and reference

**Keywords and phrases** Dummy keyword

**Digital Object Identifier** 10.4230/LIPIcs.CVIT.2016.23

## 1 Introduction

We investigate the computational meaning of the following *switch* rule of deep-inference proof theory  $[?, ?]$ :

$$\frac{(A \rightarrow B) \wedge C}{A \rightarrow (B \wedge C)}^s$$

On its own, it corresponds to an *end-of-scope* marker in  $\lambda$ -calculus. This is a special annotation of a subterm, to indicate that a given variable does not occur free, so that a substitution on that variable can be aborted early. In the above rule,  $A$  corresponds to the binding variable of an abstraction and  $C$  to the subterm of said abstraction where it doesn't occur, while  $B$  represents those subterms where it does occur.

The main thrust of our work is to incorporate this rule, and its computational interpretation as a term construct, into the *atomic  $\lambda$ -calculus*  $[?]$ . This calculus results from an investigation of the following *medial* rule:

$$\frac{(A \vee B) \rightarrow (C \wedge D)}{(A \rightarrow C) \wedge (B \rightarrow D)}^m$$

The medial rule enables duplication to proceed *atomically*: on individual constructors (abstraction and application) rather than entire subterms. The atomic  $\lambda$ -calculus implements *full laziness*, a standard notion of sharing where only the *skeleton* of a term needs to be duplicated. Given a term  $t$  which needs to be duplicated, full laziness allows to share all maximal subterms  $u_1, \dots, u_k$  of  $t$  that do not contain occurrences of a variable bound in  $t$  outside  $u_i$ . The constructors in  $t$  not in any  $u_i$  are then part of the skeleton.



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42nd Conference on Very Important Topics (CVIT 2016).

Editors: John Q. Open and Joan R. Access; Article No. 23; pp. 23:1–23:25

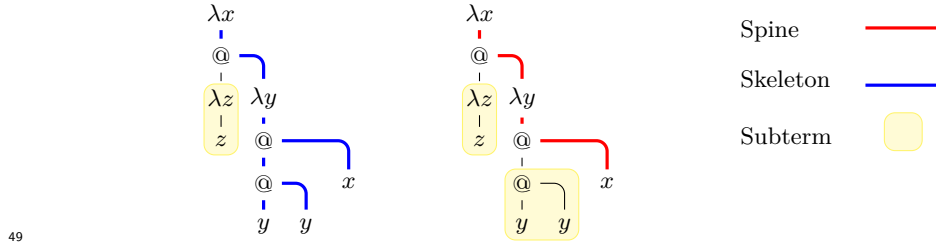
Leibniz International Proceedings in Informatics



LIPICs Schloss Dagstuhl – Leibniz-Zentrum für Informatik, Dagstuhl Publishing, Germany

## 23:2 Spinal Atomic Lambda-Calculus

Our investigation is then focused on the interaction of switch and medial. Based on this we develop the *spinal atomic*  $\lambda$ -calculus, a natural evolution of the atomic  $\lambda$ -calculus. The new calculus improves on full laziness with *spinal full laziness*, which duplicates the *spine* rather than the *skeleton*. The spine of an abstraction are the direct paths from the binder to bound variables [?]. The graph below provides an example of this for the term  $\lambda x.(\lambda z.z)\lambda y.(yy)x$ , where the spine of  $\lambda x$  is the very thick red line and the largest subterms that could be identified by an end-of-scope operator in the term calculus (or the switch rule in the proof theory) are enclosed by yellow boxes.



### 1.1 Related Work

Spine duplication has been implemented by Blanc et al. in [?], by making use of labels in a dag-implementation. The main purpose of their work is to study sharing in Wadsworth's *weak*  $\lambda$ -calculus [?] (further studied in [?]). Balabonski [?] showed that spine duplication allows for an optimal reduction in the sense of Lévy [?] for *weak reduction* i.e. where a  $\beta$ -reduction  $(\lambda x.t)s$  occurring in a subterm  $u$  can only reduce if all free variables in the redex are also free in the term  $u$ . Blleloch and Greiner [?] showed that the weak call-by-value reduction strategy can be implemented in polynomial time with respect to the size of the initial term and the number of  $\beta$  steps in said term. Given the restriction that  $u$  is a closed term, this is then the same as *closed reduction* [?, ?]. Our work generalizes spine duplication to the  $\lambda$ -calculus. It uses environments to implement sharing, and does not make use of labels, while maintaining a close intuition to dag-implementations.

End-of-scope markers in the  $\lambda$ -calculus have been seen throughout literature. *Berkling's lambda bar* [?] has shown to remove the need for variable names while maintaining correctness; improving efficiency by removing the need for alpha conversion [?]. This result was generalized by *Adbmal* (invert of "Lambda") [?]. It was shown by using multiple variables, scopes can be sequenced rather than nested which correspond closely to the boxes in MELL proof nets of linear logic [?]. This approach was studied further in [?] as graph reduction that satisfies optimality [?]. Although these approaches could identify the skeleton of a term, none however identify the spine of a term, which meant the scopes explicitly displayed may be larger than necessary from the perspective of performing substitution. This problem was solved by *director strings*, introduced by Kennaway and Sleep in [?] for combinator reduction and then generalized for any strategy by Fernández et al. in [?]. Director strings are an annotation on terms detailing the location of variable occurrences. An apt annotation on the body of an abstraction will consequently identify the spine of it. Despite being implementations that use director strings [?, ?, ?], an implementation with sharing techniques allowing for duplicating solely the spine could not be found.

Introduce the rest of the paper.

## 2 Deep Inference

Deep inference is a methodology for designing proof systems. Inference rules in deep inference, such as switch and medial, can be applied ‘deeply’ i.e. there is no concept of the main connective of a formula. The *open deduction* formalism [?] is designed around this principle, where logical connectives can be applied at the level of derivations as well as formulae. A derivation from premise  $A$  to conclusion  $C$  (over the connectives conjunction and implication) is constructed as follows,

► **Definition 1.** A derivation in open deduction is defined as follows.

$$\begin{array}{c} A \\ \Downarrow \\ C \end{array} ::= A \mid \begin{array}{c} A_1 \quad A_2 \\ \Downarrow \quad \Downarrow \\ C_1 \quad C_2 \end{array} \wedge \mid \begin{array}{c} C_1 \quad A_2 \\ \Downarrow \quad \Downarrow \\ A_1 \quad C_2 \end{array} \rightarrow \mid \begin{array}{c} A \\ \Downarrow \\ B_1 \\ \Downarrow \\ B_2 \\ \Downarrow \\ C \end{array} \begin{array}{c} r \end{array}$$

where from left to right, (1) the premise and the conclusion can be the same formula i.e.  $A = C$ . (2) We can compose derivations horizontally with a conjunction  $\wedge$ , where  $A = A_1 \wedge A_2$  and  $C = C_1 \wedge C_2$ . (3) We can compose derivations horizontally with an implication  $\rightarrow$  where  $A = A_1 \rightarrow A_2$  and  $C = C_1 \rightarrow C_2$ . Note that the derivation on the antecedent of the implication is inverted; it can be interpreted as a derivation where we treat the premise as the conclusion and the conclusion as the premise. Lastly (4) derivations can be composed vertically with an inference rule  $r$  from  $B_1$  to  $B_2$ . We work modulo symmetry, associativity, and unit laws of conjunction. Additionally the generic vertical composition of two derivations (without a mediating rule) exists as a derived operation in [?].

Open deduction was used to type the *basic calculus*, which was introduced in [?] as a basis for the atomic  $\lambda$ -calculus. We follow the same approach here; we reintroduce the basic calculus and show its typing system can be extended with the switch rule, and later expand on this to introduce the spinal atomic  $\lambda$ -calculus. We obtain a formulation of minimal logic together with the switch rule, from embedding its usual natural deduction system into open deduction. The rules are (respectively) called abstraction, switch, application and ( $n$ -ary) contraction from left to right.

$$\frac{\top}{A \rightarrow A} \lambda \quad \frac{(A \rightarrow B) \wedge C}{A \rightarrow (B \wedge C)} s \quad \frac{A \wedge (A \rightarrow B)}{B} @ \quad \frac{A}{A \wedge \dots \wedge A} \Delta$$

These rules are used to type terms of the *basic calculus*, given by the grammar

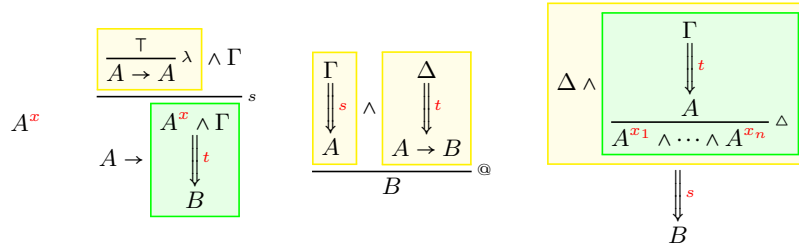
► **Definition 2.**  $s, t ::= x \mid \lambda x.t \mid st \mid s[x_1, \dots, x_n \leftarrow t]$

where the four constructors are called, from left to right, variable, abstraction, application and sharing. This is a *linear* calculus, so each variable occurs at most once, and a sharing construct is used to represent multiple occurrences of a variable (or term). The variable bound by an abstraction must occur within the body of the abstraction i.e. in the term  $\lambda x.t$ ,  $x \in (t)_{fv}$ . Lastly and similarly, each variable bound by the sharing construct must occur and become bound i.e. in the term  $s[x_1, \dots, x_n \leftarrow t]$ , each  $x_i \in (u)_{fv}$  for all  $1 \leq i \leq n$ .

For a given set  $\{a, b, c, \dots\}$  of *atomic formulae*, the following two grammars define *minimal formulae* and *conjunctive formulae* respectively.

$$A, B, C ::= a \mid A \rightarrow B \quad \Gamma, \Delta ::= A \mid \top \mid \Gamma \wedge \Delta$$

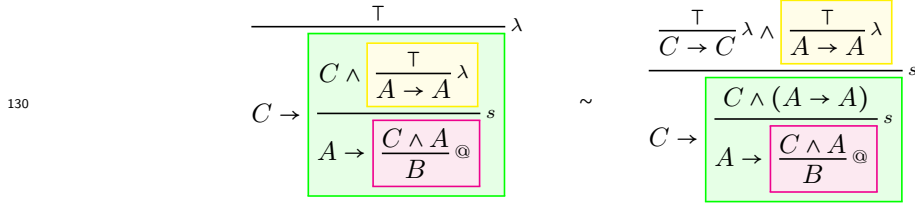
The typing derivations in open deduction for this calculus is displayed in Figure 1, where the corresponding types and derivations for terms are in red. We add the boxes to aid the reader see the horizontal composition of derivations. The colour of the box has no meaning other than to help identify derivations. A variable  $x$  may be typed by any minimal formula  $A$ , while the other constructors each correspond to inference rules, used within the context of further derivations. A term  $t$  with free variables  $x_1, \dots, x_n$  can be typed by a derivation from assumption  $A_1^{x_1} \wedge \dots \wedge A_n^{x_n}$  to conclusion  $C$ . A *typing judgement*  $t : C$  then expresses that  $t$  is typeable by a derivation with conclusion  $C$ . Note that a derivation occurring as the antecedent of an implication is always a minimal formula.



■ **Figure 1** Typing derivations for terms in the basic calculus

The semantics of the basic calculus, including the compilation and readback into the  $\lambda$ -calculus, can be found in [?] and will not be repeated here.

Although in the derivation for an abstraction in Figure 1 we place the switch rule directly after the abstraction rule, this is not always the case. Consider the term  $t = \lambda x. \lambda y. xy$ , where  $x : A \rightarrow B = C$  and  $y : A$ . The following derivations are both typing judgements of  $t : C \rightarrow A \rightarrow B$ .



The main difference between the two is that the first is *scope-balanced* while the second is *unbalanced* (terminology taken from [?]). In derivations, the *scope* of an abstraction is considered to be the subderivation found underneath the corresponding switch rule. In the scope-balanced derivation, the scope of the binder  $\lambda x$  is the whole body of the term; any scopes of any binders underneath  $\lambda x$  (such as  $\lambda y$ ) are considered nested within the scope of  $\lambda x$ . The scope of an abstraction in the scope-balanced derivation corresponds to the skeleton of the term. In the unbalanced derivation, scopes are not strictly nested but can overlap. The variable  $y$  (with type  $A$ ) is now identified by the switch rule corresponding with  $\lambda x$ , and is not considered within the scope of  $\lambda x$  in contrast to the balanced derivation where it was nested. The unbalanced scope of an abstraction corresponds with the spine of the term. Both derivations identify the application in all scope.

The atomic  $\lambda$ -calculus can be seen as using only scope-balanced derivations, and here we show that by using unbalanced derivations we can identify the spine of an abstraction, and moreover when introducing the medial rule to the typing system duplicate said spine by proof normalisation.

### 3 The Spinal Atomic $\lambda$ -Calculus

We now formally introduce the syntax of the spinal atomic  $\lambda$ -calculus ( $\Lambda_a^S$ ).

► **Definition 3** (Pre-Terms). *The pre-terms  $t \in \Lambda_a^S$  are defined by the following syntax*

$$\begin{aligned} t &::= x \mid tt \mid x\langle \vec{y} \rangle.t \mid t[\Gamma] \\ [\Gamma] &::= [\vec{x} \leftarrow t] \mid [e_1\langle \vec{x}_1 \rangle \dots e_n\langle \vec{x}_n \rangle \mid d\langle \vec{y} \rangle \overline{[\Gamma]}] \\ \overline{[\Gamma]} &::= [\Gamma] \mid \overline{[\Gamma]}[\Gamma] \end{aligned}$$

We write  $\vec{x}$  for a sequence of variables  $x_1, \dots, x_n$  for  $n \geq 0$ . An abstraction  $x\langle x \rangle.t$  and a phantom-abstraction  $x\langle \vec{y} \rangle.t$  are two instances of the same construct. We call the variables inside the brackets the *cover* of the abstraction. If the cover is the same as the preceding variable, then we consider it to be an abstraction, otherwise it is a phantom-abstraction and we call the preceding variable a *phantom-variable*. The distributor  $u[e_1\langle \vec{x}_1 \rangle \dots e_n\langle \vec{x}_n \rangle \mid d\langle \vec{y} \rangle \overline{[\Gamma]}]$  captures the phantom-variables  $e_1, \dots, e_n$  in  $u$  and the covers associated with those phantom-variables are captured by the environment  $\overline{[\Gamma]}$ , which is a collection of closures  $[\Gamma]$ . We sometimes write the distributor as  $u[\overrightarrow{e\langle x \rangle} \mid d\langle \vec{y} \rangle \overline{[\Gamma]}]$  when we are not concerned about the binding of phantom-variables. Terms are then pre-terms with sensible and correct bindings. To define terms, we first define *free* and *bound* variables and phantom variables.

► **Definition 4** (Free and Bound Variables). *The free variables  $(-)_v$  and bound variables  $(-)_b$  of a pre-term  $t$  is defined as follows*

$$\begin{aligned} (x)_{fv} &= \{x\} & (x)_{bv} &= \{\} \\ (st)_{fv} &= (s)_{fv} \cup (t)_{fv} & (st)_{bv} &= (s)_{bv} \cup (t)_{bv} \\ (x\langle x \rangle.t)_{fv} &= (t)_{fv} - \{x\} & (x\langle x \rangle.t)_{bv} &= (t)_{bv} \cup \{x\} \\ (c\langle \vec{x} \rangle.t)_{fv} &= (t)_{fv} & (c\langle \vec{x} \rangle.t)_{bv} &= (t)_{bv} \\ (u[\vec{x} \leftarrow t])_{fv} &= (u)_{fv} \cup (t)_{fv} - \{\vec{x}\} & (u[\vec{x} \leftarrow t])_{bv} &= (u)_{bv} \cup (t)_{bv} \cup \{\vec{x}\} \\ (u[\overrightarrow{e\langle x \rangle} \mid c\langle c \rangle \overline{[\Gamma]}])_{fv} &= (u[\overline{[\Gamma]}])_{fv} - \{c\} & (u[\overrightarrow{e\langle x \rangle} \mid c\langle c \rangle \overline{[\Gamma]}])_{bv} &= (u[\overline{[\Gamma]}])_{bv} \\ (u[\overrightarrow{e\langle x \rangle} \mid c\langle \vec{y} \rangle \overline{[\Gamma]}])_{fv} &= (u[\overline{[\Gamma]}])_{fv} \cup \{c\} & (u[\overrightarrow{e\langle x \rangle} \mid c\langle \vec{y} \rangle \overline{[\Gamma]}])_{bv} &= (u[\overline{[\Gamma]}])_{bv} \end{aligned}$$

► **Definition 5** (Free and Bound Phantom-Variables). *The free phantom-variables  $(-)_p$  and bound phantom-variables  $(-)_b$  of the pre-term  $t$  is defined as follows*

$$\begin{aligned} (x)_{fp} &= \{\} & (x)_{bp} &= \{\} \\ (st)_{fp} &= (s)_{fp} \cup (t)_{fp} & (st)_{bp} &= (s)_{bp} \cup (t)_{bp} \\ (x\langle x \rangle.t)_{fp} &= (t)_{fp} & (x\langle x \rangle.t)_{bp} &= (t)_{bp} \\ (c\langle \vec{x} \rangle.t)_{fp} &= (t)_{fp} \cup \{c\} & (c\langle \vec{x} \rangle.t)_{bp} &= (t)_{bp} \\ (u[\vec{x} \leftarrow t])_{fp} &= (u)_{fp} \cup (t)_{fp} & (u[\vec{x} \leftarrow t])_{bp} &= (u)_{bp} \cup (t)_{bp} \\ (u[e_1\langle \vec{x}_1 \rangle \dots e_n\langle \vec{x}_n \rangle \mid c\langle c \rangle \overline{[\Gamma]}])_{fp} &= (u[\overline{[\Gamma]}])_{fp} - \{e_1, \dots, e_n\} \\ (u[e_1\langle \vec{x}_1 \rangle \dots e_n\langle \vec{x}_n \rangle \mid c\langle c \rangle \overline{[\Gamma]}])_{bp} &= (u[\overline{[\Gamma]}])_{bp} \cup \{e_1, \dots, e_n\} \\ (u[e_1\langle \vec{x}_1 \rangle \dots e_n\langle \vec{x}_n \rangle \mid c\langle \vec{y} \rangle \overline{[\Gamma]}])_{fp} &= (u[\overline{[\Gamma]}])_{fp} \cup \{c\} - \{e_1, \dots, e_n\} \\ (u[e_1\langle \vec{x}_1 \rangle \dots e_n\langle \vec{x}_n \rangle \mid c\langle \vec{y} \rangle \overline{[\Gamma]}])_{bp} &= (u[\overline{[\Gamma]}])_{bp} \cup \{e_1, \dots, e_n\} \end{aligned}$$

Variables are bound by abstractions (not phantoms) and sharings. Phantom-variables are bound by distributors. With these definitions, we can formally define the terms of  $\Lambda_a^S$ .

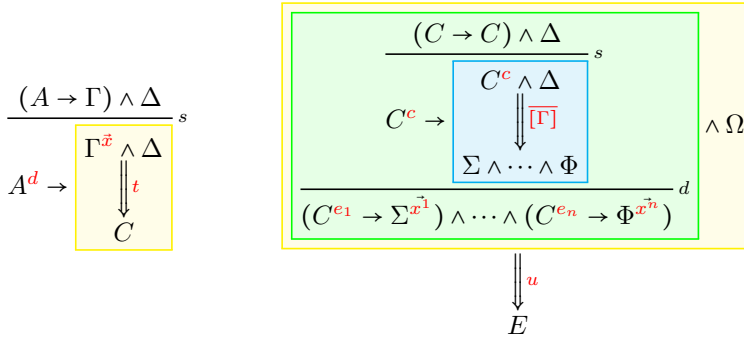
► **Definition 6 (Terms).** A term  $t \in \Lambda_a^S$  is a pre-term with the following constraints

1. Each variable may occur at most once.
2. In an abstraction  $x\langle x \rangle.t$ ,  $x \in (t)_{fv}$ .
3. In a phantom-abstraction  $c\langle x_1, \dots, x_n \rangle.t$ ,  $\{x_1, \dots, x_n\} \subset (t)_{fv}$ .
4. In a sharing  $u[x_1, \dots, x_n \leftarrow t]$ ,  $\{x_1, \dots, x_n\} \subset (u)_{fv}$ .
5. In a distributor  $u[e_1\langle w_1^1, \dots, w_{k_1}^1 \rangle \dots e_n\langle w_1^n, \dots, w_{k_n}^n \rangle | c\langle c \rangle \overline{[\Gamma]}]$ 
  - a. For all  $1 \leq i \leq n$  and  $1 \leq m \leq k_n$ ,  $w_m^i(u)_{fv}$  and becomes bound by  $\overline{[\Gamma]}$ .
  - b.  $\{e_1\langle w_1^1, \dots, w_{k_1}^1 \rangle, \dots, e_n\langle w_1^n, \dots, w_{k_n}^n \rangle\} \subset (u)_{fc}$ , and  $\{e_1, \dots, e_n\} \subset (u)_{fp}$ , and each  $e_i$  becomes bound.
  - c. The variable  $c$  occurs somewhere in the environments  $\overline{[\Gamma]}$ .
6. In a distributor  $u[e_1\langle w_1^1, \dots, w_{k_1}^1 \rangle \dots e_n\langle w_1^n, \dots, w_{k_n}^n \rangle | c\langle y_1, \dots, y_m \rangle \overline{[\Gamma]}]$ 
  - a. Both 5(a) and 5(b) hold.
  - b. For all  $1 \leq i \leq m$ ,  $y_i$  occurs in the environments  $\overline{[\Gamma]}$ .

We consider terms equal up to the congruence induced by the exchange of closures. Consider the term  $t[\Gamma_1][\Gamma_2]$  where  $[\Gamma_1]$  and  $[\Gamma_2]$  are both closures. Then  $t[\Gamma_1][\Gamma_2] \sim t[\Gamma_2][\Gamma_1]$  iff  $[\Gamma_2]$  only binds variables and phantom-variables located in  $t$ . This equivalence is essential to the rewriting theory. We also consider terms equal up to symmetry of contraction. We consider the sequence of variables  $xs$  modulo permutations. Let  $\vec{x}$  be a list of variables and let  $\vec{x}_P$  be a permutation of that list, then the following terms are considered equal.

$$u[\vec{x} \leftarrow t] \sim u[\vec{x}_P \leftarrow t] \quad c\langle \vec{x} \rangle.t \sim c\langle \vec{x}_P \rangle.t$$

### 3.1 Typing System



■ **Figure 2** Typing derivations for phantom-abstractions and distributors

The terms typed by the derivations in Figure 1 and Figure 2. Figure 2 shows the derivations for the terms  $d\langle \vec{x} \rangle.t$  and  $u[e_1\langle \vec{x}_1 \rangle \dots e_n\langle \vec{x}_n \rangle | c\langle c \rangle \overline{[\Gamma]}]$ . The distributor construct is typed using the medial rule as in [?]. Notice that the medial rule in Figure 2 does not use disjunction compared to the medial rule in the introduction. In the derivation we combine the medial rule with a co-contraction rule to form the *distribution rule* (d). Since the formula in the ante-cedent of an implication is always a minimal formula, doing this allows us to avoid introducing disjunction into the typing system.

The main difference between our calculus is the bindings. We create a new class of bindings, where phantom-variables are captured by the distributor but variables are captured

by the environment of the distributor. This shows in the derivations since the types of the variables ( $\Sigma$  and  $\Phi$ ) are not captured by the distribution rule.

## 3.2 Compilation and Readback

We now define the translations between  $\Lambda_a^S$  and the original  $\lambda$ -calculus. First we define the interpretation  $\Lambda \rightarrow \Lambda_a^S$  (*compilation*). Intuitively, it replaces each abstraction  $\lambda x. -$  with the term  $x\langle x \rangle. - [x_1, \dots, x_n \leftarrow x]$  where  $x_1, \dots, x_n$  replace the occurrences of  $x$ . Actual substitutions are denoted as  $\{t/x\}$ . Let  $|M|_x$  denote the number of occurrences of  $x$  in  $M$ , and if  $|M|_x = n$  let  $M \frac{n}{x}$  denote  $M$  with the occurrences of  $x$  by fresh, distinct variables  $x^1, \dots, x^n$ . First, the translation of a *closed* term  $M$  is  $\llbracket M \rrbracket'$ , defined below

► **Definition 7** (Compilation). *The interpretation for closed lambda terms,  $\llbracket \cdot \rrbracket' : \Lambda \rightarrow \Lambda_a^S$  is defined below*

$$\begin{aligned} \llbracket x \rrbracket' &= x \\ \llbracket M N \rrbracket' &= \llbracket M \rrbracket' \llbracket N \rrbracket' \\ \llbracket \lambda x. M \rrbracket' &= \begin{cases} x\langle x \rangle. \llbracket M \rrbracket' & \text{if } |M|_x = 1 \\ x\langle x \rangle. \llbracket M \frac{n}{x} \rrbracket' [x^1, \dots, x^n \leftarrow x] & \text{if } |M|_x = n \neq 1 \end{cases} \end{aligned}$$

For an arbitrary term  $M$ , if  $x_1, \dots, x_k$  are the free variables of  $M$  such that  $|M|_{x_i} = n_i > 1$ , the translation  $\llbracket M \rrbracket$  is

$$\llbracket M \frac{n_1}{x_1} \dots \frac{n_k}{x_k} \rrbracket' [x_1^1, \dots, x_1^{n_1} \leftarrow x_1] \dots [x_k^1, \dots, x_k^{n_k} \leftarrow x_k]$$

The readback into the  $\lambda$ -calculus is slightly more complicated, specifically due to the bindings induced by the distributor. Interpreting a distributor  $\llbracket u[e_1\langle \vec{x}_1 \rangle \dots e_n\langle \vec{x}_n \rangle | c\langle c \rangle \overline{[\Gamma]}] \rrbracket$  construct as a  $\lambda$ -term requires (1) converting the phantom-abstractions it binds in  $u$  into abstractions (2) collapsing the environment (3) maintaining the bindings between the converted abstractions and the intended variables located in the environment.

► **Definition 8.** *Given a total function  $\sigma$  with domain  $D$  and codomain  $C$ , we overwrite the function with case  $x \mapsto V$  where  $x \in D$  and  $V \in C$  such that*

$$\sigma[x \mapsto V](z) = \begin{cases} V & z = x \\ \sigma(z) & \text{otherwise} \end{cases}$$

When using the map  $\sigma$  as part of the translation, the intuition is that for all bound variables  $x$  in the term we are translating, it should be that  $\sigma(x) = x$ . The map  $\gamma : V \rightarrow V$  is defined similarly, and the purpose is to keep track of the binding of phantom-variables.

► **Definition 9.** *The interpretation  $\llbracket - | - | - \rrbracket : \Lambda_a^S \times (V \rightarrow \Lambda) \times (V \rightarrow V) \rightarrow \Lambda$  is defined as*

$$\begin{aligned} \llbracket x | \sigma | \gamma \rrbracket &= \sigma(x) \\ \llbracket st | \sigma | \gamma \rrbracket &= \llbracket s | \sigma | \gamma \rrbracket \llbracket t | \sigma | \gamma \rrbracket \\ \llbracket c\langle c \rangle. t | \sigma | \gamma \rrbracket &= \lambda c. \llbracket t | \sigma[c \mapsto c] | \gamma \rrbracket \\ \llbracket c\langle x_1, \dots, x_n \rangle. t | \sigma | \gamma \rrbracket &= \lambda c. \llbracket t | \sigma[x_i \mapsto \sigma(x_i)\{c/\gamma(c)\}]_{i \in [n]} | \gamma \rrbracket \\ \llbracket u[x_1, \dots, x_n \leftarrow t] | \sigma | \gamma \rrbracket &= \llbracket u | \sigma[x_i \mapsto \llbracket t | \sigma | \gamma \rrbracket]_{i \in [n]} | \gamma \rrbracket \end{aligned}$$

$$\begin{aligned}
253 \quad & \llbracket u[e_1\langle \vec{w}_1 \rangle, \dots, e_n\langle \vec{w}_n \rangle \mid c\langle c \rangle \overline{[\Gamma]}] \mid \sigma \mid \gamma \rrbracket = \llbracket u\overline{[\Gamma]} \mid \sigma \mid \gamma[e_i \mapsto c]_{i \in [n]} \rrbracket \\
254 \quad & \llbracket u[e_1\langle \vec{w}_1 \rangle, \dots, e_n\langle \vec{w}_n \rangle \mid c\langle x_1, \dots, x_m \rangle \overline{[\Gamma]}] \mid \sigma \mid \gamma \rrbracket = \llbracket u\overline{[\Gamma]} \mid \sigma' \mid \gamma[e_i \mapsto c]_{i \in [n]} \rrbracket \\
255 \quad & \text{where } \sigma' = \sigma[x_i \mapsto \sigma(x_i)\{c/\gamma(c)\}]_{i \in [n]}
\end{aligned}$$

256

257

258 ► **Lemma 10.** For  $s, t \in \Lambda_a^S$ , if  $s \sim t$  then  $\llbracket s \rrbracket = \llbracket t \rrbracket$

► **Lemma 11.** For a closed  $t \in \Lambda_a^S$ , where  $t$  has no distributor constructs and only variables are shared, and a closed  $N \in \Lambda$ . the following

$$\llbracket (N) \rrbracket' = N \quad \llbracket (t) \rrbracket' = t \quad \exists_{M \in \Lambda}. t = (M) \rrbracket'$$

### 259 3.3 Rewrite Rules

260 Both the spinal atomic  $\lambda$ -calculus and the atomic  $\lambda$ -calculus of [?] follow atomic reduction  
 261 steps, i.e. they apply on individual constructors. The biggest difference is that our calculus  
 262 is capable of duplicating not only the skeleton but also the spine. The rewrite rules in our  
 263 calculus make use of 3 operations, *substitution*, *book-keeping*, and *exorcism*.

264 The operation *substitution*  $t\{s/x\}$  propagates through the term  $t$ , and replaces the free  
 265 occurrences of the variable  $x$  with the term  $s$ . Moreover, if  $x$  occurs in the cover of a phantom-  
 266 variable  $e\langle \vec{y} \cdot x \rangle$ , then substitution replaces the  $x$  in the cover with  $(s)_{fv}$ ,  $e\langle \vec{y} \cdot (s)_{fv} \rangle$ .

267 Although substitution performs some book-keeping on phantom-abstractions, we define  
 268 an explicit notion of book-keeping  $\{\vec{y}/e\}_b$  that updates the variables stored in a free cover i.e.  
 269 for a term  $t$ ,  $e\langle \vec{x} \rangle \in (t)_{fc}$  then  $e\langle \vec{y} \rangle \in (t\{\vec{y}/e\}_b)_{fc}$ .

270 The last operation we introduce is called *exorcism*  $\{c\langle \vec{x} \rangle\}_e$ . We perform exorcisms on  
 271 phantom-abstractions to convert them to abstractions. Intuitively, this will be performed on  
 272 phantom-abstractions with phantom-variables bound to a distributor when said distributor is  
 273 eliminated. It converts phantom-abstractions to abstractions by introducing a sharing of the  
 274 phantom-variable that captures the variables in the cover, i.e.  $c\langle \vec{x} \rangle.t\{c\langle \vec{x} \rangle\}_e = c\langle c \rangle.t[\vec{x} \leftarrow c]$ .

275 ► **Proposition 12.** Given  $M \in \Lambda$  such that for all  $v \in V$ ,  $\gamma(v) \notin (M)_{fv}$  and  $\sigma(x) = x$ , the  
 276 translation  $\llbracket u \mid \sigma \mid \gamma \rrbracket$  commutes with substitution  $\{M/x\}$  in the following way

$$\llbracket u\{t/x\} \mid \sigma \mid \gamma \rrbracket = \llbracket u \mid \sigma[x \mapsto \llbracket t \mid \sigma \mid \gamma \rrbracket] \mid \gamma \rrbracket$$

277 ► **Proposition 13.** Book-keeping commutes with the translation in the following way

278 if  $c\langle y_1, \dots, y_m \rangle \in (u)_{fc}$  such that  $\{x_1, \dots, x_n\} \subset \{y_1, \dots, y_m\}$   
 279 and for those  $z \in \{y_1, \dots, y_m\} \setminus \{x_1, \dots, x_n\}$ ,  $\gamma(c) \notin (\sigma(z))_{fv}$   
 280 or if simply  $\{x_1, \dots, x_n\} \cap (u)_{fv} = \{\}$

$$\llbracket u\{x_1, \dots, x_n/c\}_b \mid \sigma \mid \gamma \rrbracket = \llbracket u \mid \sigma \mid \gamma \rrbracket$$

281 ► **Proposition 14.** Exorcisms commute with the translation in the following way

282 if  $c\langle x_1, \dots, x_n \rangle \in (u)_{fc}$  or  $\{x_1, \dots, x_n\} \cap (u)_{fv} = \{\}$

$$\llbracket u\{c\langle x_1, \dots, x_n \rangle\}_e \mid \sigma \mid \gamma \rrbracket = \llbracket u \mid \sigma[x_i \mapsto c]_{i \in [n]} \mid \gamma \rrbracket$$

283 Using these operations, we define the rewrite rules that allow for spinal duplication. Firstly  
 284 we have beta reduction ( $\rightsquigarrow_\beta$ ), which requires an abstraction and not a phantom-abstraction.

$$285 \quad (x\langle x \rangle.t) s \rightsquigarrow_\beta t\{s/x\} \quad (\beta)$$



However, its effect is very different: here  $\beta$ -reduction is a linear operation, since the bound variable  $x$  occurs exactly once in the body  $t$ . Any duplication of the term  $t$  in the atomic lambda-calculus proceeds via the sharing reductions, which we define next. The first set of sharing reduction rules move closures towards the outside of a term. Most of these rewrite rules only change the typing derivations in the way that subderivations are composed, with the exception of moving a closure out of scope of a distributor.

$$s[\Gamma]t \rightsquigarrow_L (st)[\Gamma] \quad (l_1)$$

$$st[\Gamma] \rightsquigarrow_L (st)[\Gamma] \quad (l_2)$$

$$d\langle \vec{x} \rangle.t[\Gamma] \rightsquigarrow_L (d\langle \vec{x} \rangle.t)[\Gamma] \text{ if } \{\vec{x}\} \cap (t)_{fv} = \{\vec{x}\} \quad (l_3)$$

$$u[x_1, \dots, x_n \leftarrow t[\Gamma]] \rightsquigarrow_L u[x_1, \dots, x_n \leftarrow t][\Gamma] \quad (l_4)$$

For the case of lifting a closure outside a distributor, we use a notation  $\|\Gamma\|$  to identify the variables captured by a closure, i.e.  $\|\vec{x} \leftarrow t\| = \{\vec{x}\}$  and  $\|[e_1\langle \vec{x}_1 \rangle, \dots, e_n\langle \vec{x}_n \rangle | c\langle c \rangle[\Gamma]]\| = \{\vec{x}_1, \dots, \vec{x}_n\}$ . Then let  $\{\vec{z}\} = \|\Gamma\|$  in the following rewrite rule, that can only occur if  $\{\vec{x}\} \cap (\|\Gamma\|)_{fv} = \{\}$ .

$$\begin{aligned} & u[e_1\langle \vec{w}_1 \rangle \dots e_n\langle \vec{w}_n \rangle | c\langle \vec{x} \rangle[\overline{\Gamma}][\Gamma]] \\ & \rightsquigarrow_L u\{(\vec{w}_i/\vec{z})/e_i\}_{b_i \in [n]}[e_1\langle \vec{w}_1/\vec{z} \rangle \dots e_n\langle \vec{w}_n/\vec{z} \rangle | c\langle \vec{x} \rangle[\overline{\Gamma}][\Gamma]] \end{aligned} \quad (l_5)$$

The proof rewrite rule corresponding with the rewrite rule  $l_5$  can be broken down into two parts. The first part is readjusting how the derivations compose as shown below.

$$\begin{array}{c} \frac{(C \rightarrow \Gamma) \wedge \Delta \wedge \Omega}{s} \\ \frac{C^c \rightarrow \left[ \frac{\Gamma^{\vec{x}} \wedge \Delta \wedge \left[ \frac{\Omega}{\downarrow t} \right]}{A \wedge \dots \wedge A} \right] \downarrow [\Gamma]}{\Sigma_1^{\vec{w}_1} \dots \Sigma_n^{\vec{w}_n}}}{d} \\ \frac{(C \rightarrow \Sigma_1) \wedge \dots \wedge (C \rightarrow \Sigma_n)}{d} \end{array} \rightsquigarrow_L \begin{array}{c} \frac{(C \rightarrow \Gamma) \wedge \Delta \wedge \left[ \frac{\Omega}{\downarrow t} \right]}{A \wedge \dots \wedge A} \downarrow s \\ \frac{C^c \rightarrow \left[ \frac{\Gamma^{\vec{x}} \wedge \Delta \wedge A \dots A}{\downarrow [\Gamma]} \right]}{\Sigma_1^{\vec{w}_1} \dots \Sigma_n^{\vec{w}_n}}}{d} \\ \frac{(C \rightarrow \Sigma_1) \wedge \dots \wedge (C \rightarrow \Sigma_n)}{d} \end{array}$$

The second part of the rewrite rule justifies the need for the book-keeping operation. In the rewrite below, let  $A$  be the type of a variable  $z$  where  $z \in \vec{z}$ . After lifting, we want to remove the variable from the cover as to ensure correctness since the variables in the cover denote the variables captured by the environment. Book-keeping allows us to remove these variables simultaneously.

$$\begin{array}{c} \frac{(C \rightarrow \Gamma^{\vec{x}}) \wedge \Delta \wedge A}{s} \\ \frac{C^c \rightarrow \left[ \frac{\Gamma \wedge \Delta}{\downarrow [\Gamma]} \right] \wedge A^z}{\Sigma_1 \wedge \dots \wedge \Sigma_n \wedge A \wedge \dots \wedge \Sigma_n} \downarrow d \\ \dots \wedge (C^{e_i} \rightarrow \Sigma_i^{\vec{w}} \wedge A) \wedge \dots \end{array} \rightsquigarrow \begin{array}{c} \frac{(C \rightarrow \Gamma^{\vec{x}}) \wedge \Delta}{s} \\ \frac{C^c \rightarrow \left[ \frac{\Gamma \wedge \Delta}{\downarrow [\Gamma]} \right]}{\Sigma_1 \wedge \dots \wedge \Sigma_i \wedge \dots \wedge \Sigma_n} \downarrow d \\ \dots \wedge (C \rightarrow \Sigma_i) \wedge \dots \\ \dots \wedge \left[ \frac{(C^{e_i} \rightarrow \Sigma_i^{\vec{w}}) \wedge A}{C \rightarrow \Sigma_i \wedge A} \right] \downarrow s \wedge \dots \end{array}$$

The lifting rules ( $l_i$ ) are justified by the need to lift closures out of the distributor, as opposed to duplicating them. The second set of rewrite rules, consecutive sharings are compounded and unary sharings are applied as substitutions.

$$u[w_1, \dots, w_m \leftarrow y_i][y_1, \dots, y_n \leftarrow t] \rightsquigarrow_C u[y_1, \dots, y_{i-1}, w_1, \dots, w_m, y_{i+1}, \dots, y_n \leftarrow t] \quad (c_1)$$

$$u[x \leftarrow t] \rightsquigarrow_C u\{t/x\} \quad (c_2)$$

The atomic steps for duplicating are given in the third and final set of rewrite rules. The first being the atomic duplication step of an application, which is the same rule used in [?]. The proof rewrite steps for each rule are also provided. For simplicity, we only show the binary case for each rule.

$$u[x_1 \dots x_n \leftarrow st] \rightsquigarrow_D u\{z_1 y_1/x_1\} \dots \{z_n y_n/x_n\}[z_1 \dots z_n \leftarrow s][y_1 \dots y_n \leftarrow t] \quad (d_1)$$

$$\frac{(A \rightarrow B) \wedge A}{\frac{B}{B \wedge B} \Delta} @ \quad \frac{\frac{(A \rightarrow B)}{(A \rightarrow B) \wedge (A \rightarrow B)} \Delta \wedge \frac{B}{B \wedge B} \Delta}{\frac{(A \rightarrow B) \wedge A}{B} @ \wedge \frac{(A \rightarrow B) \wedge A}{B} @} \Delta$$

$$u[x_1, \dots, x_n \leftarrow c(\bar{y}).t] \rightsquigarrow_D u\{e_i\langle w_1^i \rangle . w_1^i/x_i\}_{1 \leq i \leq n}[e_1\langle w_1^1 \rangle \dots e_n\langle w_1^n \rangle | c(\bar{y})[w_1^1, \dots, w_1^n \leftarrow t]] \quad (d_2)$$

$$\frac{\frac{(A \rightarrow B) \wedge \Gamma}{B \wedge \Gamma} s}{A \rightarrow \boxed{\begin{array}{c} B \wedge \Gamma \\ \Downarrow \\ C \end{array}}} \Delta \quad \frac{\frac{(A \rightarrow B) \wedge \Gamma}{B \wedge \Gamma} s}{A \rightarrow \boxed{\begin{array}{c} B \wedge \Gamma \\ \Downarrow \\ C \\ \hline C \wedge C \end{array}}} \Delta \quad \frac{}{(A \rightarrow C) \wedge (A \rightarrow C)} d$$

$$u[e_1\langle \vec{w}_1 \rangle \dots e_n\langle \vec{w}_n \rangle | c\langle c \rangle [\vec{w}_1, \dots, \vec{w}_n \leftarrow c]] \rightsquigarrow_D u\{e_1\langle \vec{w}_1 \rangle\}_e \dots \{e_n\langle \vec{w}_n \rangle\}_e \quad (d_3)$$

$$\frac{\frac{A \rightarrow \frac{A}{A \wedge A} \Delta}{(A \rightarrow A) \wedge (A \rightarrow A)} d}{\frac{}{A \rightarrow A} \lambda} \wedge \frac{}{A \rightarrow A} \lambda$$

► **Proposition 15.** If  $s \rightsquigarrow_{L,C,D} t$  and  $s : C$ , then  $t : C$

► **Lemma 16** (Sharing reduction preserves denotation). If  $s \rightsquigarrow_{L,D,C} t$  then  $\llbracket s | \sigma | \gamma \rrbracket = \llbracket t | \sigma | \gamma \rrbracket$

## 4 Strong Normalisation of Sharing Reductions

In order to show our calculus is strongly normalising, we first show that the sharing reduction rules are strongly normalising. To do this, we make use of an ‘intermediate calculus’ called the weakening calculus. Following the approaches of [?, ?], we indite a measure on terms based on its connection with the weakening calculus. We show that this measure strictly decreases as sharing reduction progresses.

► **Definition 17.** The  $w$ -terms and the weakening calculus ( $\Lambda_w$ ) are

$$T, U, V ::= x \mid \lambda x. T^* \mid UV \mid T[\leftarrow U] \mid \bullet \quad (*) \text{ where } x \in (T)_{fv}$$

The terms are variable, abstraction, application, weakening, and a bullet. In the weakening  $T[\leftarrow U]$ , the subterm  $U$  is *weakened*. The interpretation of atomic terms to weakening terms  $\llbracket - | - | - \rrbracket_w$  can be seen as an extension of the translation into the  $\lambda$ -calculus (Definition 9)

► **Definition 18.** The interpretation  $\llbracket - \mid - \mid - \rrbracket_w : \Lambda_a^S \times (V \rightarrow \Lambda_w) \times (V \rightarrow V) \rightarrow \Lambda_w$  with maps  $\sigma : V \rightarrow \Lambda_w$  and  $\gamma : V \rightarrow V$  is defined as an extension of the translation in (Definition 9) with the following additional special cases.

$$\begin{aligned} \llbracket u[\leftarrow t] \mid \sigma \mid \gamma \rrbracket_w &= \llbracket u \mid \sigma \mid \gamma \rrbracket_w [\leftarrow \llbracket t \mid \sigma \mid \gamma \rrbracket_w] \\ \llbracket u[\mid c(c) \mid \overline{\Gamma}] \mid \sigma \mid \gamma \rrbracket_w &= \llbracket u[\overline{\Gamma}] \mid \sigma[c \mapsto \bullet] \mid \gamma \rrbracket_w \\ \llbracket u[\mid c(x_1, \dots, x_n) \mid \overline{\Gamma}] \mid \sigma \mid \gamma \rrbracket_w &= \llbracket u[\overline{\Gamma}] \mid \sigma' \mid \gamma \rrbracket_w \\ \text{where } \sigma'(z) &= \begin{cases} \sigma(z)\{\bullet/\gamma(c)\} & z \in \{x_1, \dots, x_n\} \\ \sigma(z) & \text{otherwise} \end{cases} \end{aligned}$$

We also have translations of the weakening calculus to and from the lambda calculus. Both of these translations have been provided in [?]. The interpretation  $\llbracket - \rrbracket$  from weakening terms to  $\lambda$ -terms discards all weakenings. The interpretation  $\llbracket - \rrbracket^w : \Lambda \rightarrow \Lambda_w$  is defined below.

► **Definition 19.** The interpretation  $M \in \Lambda$ ,  $\llbracket - \rrbracket^w : \Lambda \rightarrow \Lambda_w$  is defined by

$$\begin{aligned} \llbracket x \rrbracket^w &= x \\ \llbracket M N \rrbracket^w &= \llbracket M \rrbracket^w \llbracket N \rrbracket^w \\ \llbracket \lambda x. N \rrbracket^w &= \begin{cases} \lambda x. \llbracket N \rrbracket^w & \text{if } x \in (N)_{fv} \\ \lambda x. \llbracket N \rrbracket^w [\leftarrow x] & \text{otherwise} \end{cases} \end{aligned}$$

The following equalities can be observed, where  $\sigma^\Lambda(z) = \lfloor \sigma^w(z) \rfloor$ .

► **Proposition 20.** For  $N \in \Lambda$  and  $t \in \Lambda_a^S$  the following properties hold

$$\lfloor \llbracket t \mid \sigma^w \mid \gamma \rrbracket_w \rfloor = \llbracket t \mid \sigma^\Lambda \mid \gamma \rrbracket \quad \llbracket \llbracket N \rrbracket \rrbracket^w = \llbracket N \rrbracket^w \quad \lfloor \llbracket N \rrbracket^w \rfloor = N$$

Here we can take advantage that preservation of strong normalisation has been proven for this weakening calculus already in [?], providing the proof for Proposition 22. Additionally, similar ideas and results can be found elsewhere, i.e. with memory in [?], the  $\lambda$ -I calculus in [?], the  $\lambda$ -void calculus [?], and the weakening  $\lambda\mu$ -calculus [?].

► **Definition 21.** In the weakening calculus,  $\beta$ -reduction is defined as follows, where  $\overline{\Gamma}$  are weakening constructs.

$$((\lambda x. T) \overline{\Gamma}) U \rightarrow_\beta T\{U/x\} \overline{\Gamma} \quad (w_\beta)$$

► **Proposition 22.** If  $N \in \Lambda$  is strongly normalising, then so is  $\llbracket N \rrbracket^w$

When translating from the spinal atomic  $\lambda$ -calculus to the weakening calculus, weakenings are maintained whilst sharings are interpreted through duplication via substitution. Thus the reduction rules in the weakening calculus cover the spinal reductions for nullary distributors and weakenings.

► **Definition 23.** The weakening reductions  $(\rightarrow_w)$  proceeds as follows.

$$\begin{aligned} \lambda x. T[\leftarrow U] &\rightarrow_w (\lambda x. T)[\leftarrow U] \quad \text{if } x \notin (U)_{fv} & (w_1) \\ U[\leftarrow T] V &\rightarrow_w (UV)[\leftarrow T] & (w_2) \\ U V[\leftarrow T] &\rightarrow_w (UV)[\leftarrow T] & (w_3) \end{aligned}$$

$$\begin{aligned}
376 \quad T[\leftarrow U[\leftarrow V]] &\rightarrow_w T[\leftarrow U][\leftarrow V] & (w_4) \\
377 \quad T[\leftarrow \lambda x.U] &\rightarrow_w T[\leftarrow U\{\bullet/x\}] & (w_5) \\
378 \quad T[\leftarrow UV] &\rightarrow_w T[\leftarrow U][\leftarrow V] & (w_6) \\
379 \quad T[\leftarrow \bullet] &\rightarrow_w T & (w_7) \\
380 \quad T[\leftarrow U] &\rightarrow_w T \quad \text{if } U \text{ is a subterm of } T & (w_8)
\end{aligned}$$

It is easy to see that these rules correspond to special cases of the sharing reduction rules for  $\Lambda_a^S$ . Lifting a closure relates  $(w_1)$  and  $(l_3)$ ,  $(w_2)$  and  $(l_1)$ ,  $(w_3)$  and  $(l_2)$ ,  $(w_4)$  and  $(l_4)$ ,  $(w_5)$  and  $(d_2)$ , and duplicating a term relates  $(w_6)$  and  $(d_1)$ , and  $(w_7)$  and  $(d_3)$ . It is not so obvious to see what the case  $(w_8)$  corresponds to. If  $U$  is a subterm of  $T$ , then in the corresponding  $\Lambda_a^S$ -term this term would be shared and one of the copies would be in a weakening. Thus this reduction relates to the case  $(c_1)$ , where we remove the weakening. We demonstrate by considering  $t[\leftarrow y][\tilde{x} \cdot y \cdot \tilde{z} \leftarrow u] \rightsquigarrow_C t[\tilde{x} \cdot \tilde{z} \leftarrow u]$ . On the left hand side, the corresponding weakening-term (obtained by  $(-)^w$ ) would have the weakening  $[\leftarrow U]$  where  $U = (u)^w$ . This is because  $U$  is substituted into  $[\leftarrow y]$ , but on the right hand side this would be gone. This situation can only occur if there are other copies of  $U$  substituted into the term. This corresponds to if only the corresponding  $(c_1)$  reduction rule can occur. This resemblance is confirmed by the following Lemmas.

► **Lemma 24.** *If  $t \rightsquigarrow_\beta u$  then  $\llbracket t \rrbracket^w \rightarrow_\beta^+ \llbracket u \rrbracket^w$*

► **Lemma 25.** *If  $t \rightsquigarrow_{(C,D,L)} u$  and for any  $x \in (t)_{bv} \cup (t)_{fp}$  and for all  $z, x \notin (\sigma(z))_{fv}$ .*

$$\llbracket t \mid \sigma \mid \gamma \rrbracket_w \rightarrow_w^* \llbracket u \mid \sigma \mid \gamma \rrbracket_w$$

We now define the components that we use for our measure on spinal atomic  $\lambda$ -terms that we will use to prove strong normalisation of sharing reductions. The *height* of a term is intuitively a multiset of integers that record the distance of each sharing. The distance is measured by the number of constructors from the sharing node to the root of the term in its graphical notation. The height is defined on terms as  $\mathcal{H}^i(-)$ , where  $i$  is an integer. We say  $\mathcal{H}(t)$  for  $\mathcal{H}^1(t)$ . We use  $\cup$  to denote the disjoint union of two multisets. We denote  $\mathcal{H}^i([\Gamma_1]) \cup \dots \cup \mathcal{H}^i([\Gamma_n])$  as  $\mathcal{H}^i(\overline{[\Gamma]})$  for the environment  $\overline{[\Gamma]} = [\Gamma_1], \dots, [\Gamma_n]$ .

► **Definition 26 (Sharing Height).** *The sharing height  $\mathcal{H}^i(t)$  of a term  $t$  is given by*

$$\begin{aligned}
395 \quad \mathcal{H}^i(x) &= \{\} \\
396 \quad \mathcal{H}^i(st) &= \mathcal{H}^{i+1}(s) \cup \mathcal{H}^{i+1}(t) \\
397 \quad \mathcal{H}^i(c\langle \tilde{x} \rangle.t) &= \mathcal{H}^{i+1}(t) \\
398 \quad \mathcal{H}^i(t[\Gamma]) &= \mathcal{H}^i(t) \cup \mathcal{H}^i([\Gamma]) \cup \{i^1\} \\
399 \quad \mathcal{H}^i([x_1, \dots, x_n \leftarrow t]) &= \mathcal{H}^{i+1}(t) \\
400 \quad \mathcal{H}^i(\overrightarrow{[e\langle \vec{w} \rangle \mid c\langle \tilde{x} \rangle \overline{[\Gamma]}]}) &= \mathcal{H}^{i+1}(\overline{[\Gamma]}) \cup \{(i+1)^n\} \text{ where } n \text{ is the number of closures in } \overline{[\Gamma]}
\end{aligned}$$

This measure then strictly decreases for the rewrite rules  $l_1, l_2, l_3, l_4$  and  $l_5$ .

► **Lemma 27.** *If  $t \rightsquigarrow_{(L)} u$  then  $\mathcal{H}^i(t) > \mathcal{H}^i(u)$*

The other measure we consider is the *weight* of a term. Intuitively this quantifies the remaining duplications, which are performed with  $\rightsquigarrow_D$  reductions. Calculating the weight of a term requires an auxiliary function from variables to integers. This function is defined by assigning integer weights to the variables of a term. This auxiliary function is defined on

terms  $\mathcal{V}^i(-)$ , where  $i$  is an integer. To measure variables independently of binders is vital. It allows to measure distributors, which duplicate  $\lambda$ 's but not the bound variable. Also, only bound variables for abstractions are measured since variables bound by sharings are substituted in the interpretation.

► **Definition 28** (Variable Weights). *The function  $\mathcal{V}^i(t)$  returns a function that assigns integer weights to the free variables of  $t$ . It is defined by the following*

$$\begin{aligned}
 \mathcal{V}^i(x) &= \{x \mapsto i\} \\
 \mathcal{V}^i(st) &= \mathcal{V}^i(s) \cup \mathcal{V}^i(t) \\
 \mathcal{V}^i(c\langle c \rangle.t) &= \mathcal{V}^i(t) / \{c\} \\
 \mathcal{V}^i(c\langle \vec{x} \rangle.t) &= \mathcal{V}^i(t) \cup \{c \mapsto i\} \\
 \mathcal{V}^i(t[\leftarrow s]) &= \mathcal{V}^i(t) \cup \mathcal{V}^1(s) \\
 \mathcal{V}^i(t[x_1, \dots, x_n \leftarrow s]) &= \mathcal{V}^i(t) / \{x_1, \dots, x_n\} \cup \mathcal{V}^{f(x_1) + \dots + f(x_n)}(s) \text{ where } f = \mathcal{V}^i(t) \\
 \mathcal{V}^i(t[e_1\langle \vec{w}_1 \rangle \dots e_n\langle \vec{w}_n \rangle | c\langle c \rangle [\overline{\Gamma}]]]) &= \mathcal{V}^i(t[\overline{\Gamma}]) / \{c, e_1, \dots, e_n\} \\
 \mathcal{V}^i(t[e_1\langle \vec{w}_1 \rangle \dots e_n\langle \vec{w}_n \rangle | c\langle \vec{x} \rangle [\overline{\Gamma}]]]) &= \mathcal{V}^i(t[\overline{\Gamma}]) / \{e_1, \dots, e_n\} \cup \{c \mapsto i\}
 \end{aligned}$$

The weight of a term can then be defined via the use of this auxiliary function. The auxiliary function is used when calculating the weight of a sharing, where the sharing weight of the variables bound by the sharing play a significant role in calculating the weight of the shared term. In the case of a weakening, we assign an initial weight of 1 to indicate that the constructor is not duplicated by appears at least once in the weakening calculus. Again we say  $\mathcal{W}(t) = \mathcal{W}^1(t)$ .

► **Definition 29** (Sharing Weight). *The sharing weight  $\mathcal{W}^i(t)$  of a term  $t$  is a multiset of integers computed by the function defined below*

$$\begin{aligned}
 \mathcal{W}^i(x) &= \{\} \\
 \mathcal{W}^i(st) &= \mathcal{W}^i(s) \cup \mathcal{W}^i(t) \cup \{i\} \\
 \mathcal{W}^i(c\langle c \rangle.t) &= \mathcal{W}^i(t) \cup \{i\} \cup \{\mathcal{V}^i(t)(c)\} \\
 \mathcal{W}^i(c\langle \vec{x} \rangle.t) &= \mathcal{W}^i(t) \cup \{i\} \\
 \mathcal{W}^i(t[\leftarrow s]) &= \mathcal{W}^i(t) \cup \mathcal{W}^1(s) \\
 \mathcal{W}^i(t[x_1, \dots, x_n \leftarrow s]) &= \mathcal{W}^i(t) \cup \mathcal{W}^{f(x_1) + \dots + f(x_n)}(s) \text{ where } f = \mathcal{V}^i(t) \\
 \mathcal{W}^i(t[e_1\langle \vec{w}_1 \rangle \dots e_n\langle \vec{w}_n \rangle | c\langle c \rangle [\overline{\Gamma}]]]) &= \mathcal{W}^i(t[\overline{\Gamma}]) \cup \{\mathcal{V}^i(t[\overline{\Gamma}]) (c)\} \\
 \mathcal{W}^i(t[e_1\langle \vec{w}_1 \rangle \dots e_n\langle \vec{w}_n \rangle | c\langle \vec{x} \rangle [\overline{\Gamma}]]]) &= \mathcal{W}^i(t[\overline{\Gamma}])
 \end{aligned}$$

We show that this measure then strictly decreases on the rewrite rules  $d_1$ ,  $d_2$ ,  $d_3$  and is unaffected by all the other sharing reduction rules.

► **Lemma 30.** *If  $t \rightsquigarrow_D u$  then  $\mathcal{W}^i(t) > \mathcal{W}^i(u)$*

► **Lemma 31.** *If  $t \rightsquigarrow_{(L,C)} u$  then  $\mathcal{W}^i(t) = \mathcal{W}^i(u)$*

The last measure we consider is the number of closures in the term, where it can be easily observed that the rewrite rules  $c_1$  and  $c_2$  strictly decrease this measure, and that the  $\rightsquigarrow_L$  rules do not alter the number of closures. We then use this along with height and weight to define a *sharing measure* on terms.

► **Definition 32.** The sharing measure of a  $\Lambda_a^S$ -term  $t$  is a triple  $(\mathcal{W}(t), C, \mathcal{H}(t))$  where  $C$  is the number of closures in  $t$ . We can compare two different sharing measures by considering the lexicographical preferences according to  $\text{weight} > \text{number of closures} > \text{height}$ .

► **Theorem 33.** Sharing reduction  $\rightsquigarrow_{(D,L,C)}$  is strongly normalising

**Proof.** From Lemma 30, Lemma 31, and Lemma 27, it follows that the sharing measure of a term is strictly decreasing under  $\rightsquigarrow_{(D,L,C)}$ , proving the statement. ◀

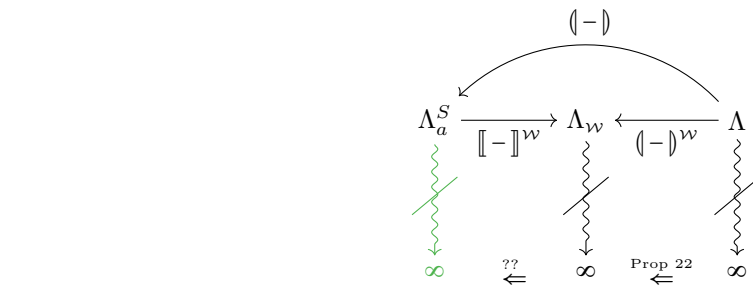
Now that we have proven the sharing reductions are strongly normalising, we can prove that they are confluent for closed terms.

► **Theorem 34.** The sharing reduction relation  $\rightsquigarrow_{(R,D,L,C)}$  is confluent

**Proof.** Lemma 10 tells us that the preservation is preserved under reduction i.e. for  $s \rightsquigarrow_{(R,D,L,C)} t$ ,  $\llbracket s \rrbracket = \llbracket t \rrbracket$ . Therefore given  $t \rightsquigarrow_{(R,D,L,C)}^* s_1$  and  $t \rightsquigarrow_{(R,D,L,C)}^* s_2$ ,  $\llbracket t \rrbracket = \llbracket s_1 \rrbracket = \llbracket s_2 \rrbracket$ . Since we know that sharing reductions are strongly normalising, we know there exists terms  $u_1$  and  $u_2$  in sharing normal form such that  $s_1 \rightsquigarrow_{(R,D,L,C)}^* u_1$  and  $s_2 \rightsquigarrow_{(R,D,L,C)}^* u_2$ . Lemma 11 tells us that terms in closed terms in sharing normal form are in correspondence with their denotations i.e.  $\llbracket \llbracket t \rrbracket \rrbracket' = t$ . Since by Lemma 10 we know  $\llbracket u_1 \rrbracket = \llbracket s_1 \rrbracket = \llbracket s_2 \rrbracket = \llbracket u_2 \rrbracket$ , and by Lemma 11  $\llbracket \llbracket u_1 \rrbracket \rrbracket' = u_1$  and  $\llbracket \llbracket u_2 \rrbracket \rrbracket' = u_2$ , we can conclude  $u_1 = u_2$ . Hence, we prove confluence. ◀

## 5 Preservation of Strong Normalisation

Here we show how  $\Lambda_a^S$  preserves strong normalisation with respect to the  $\lambda$ -calculus. Recall that by Proposition 20 that for all  $N \in \Lambda$ ,  $\llbracket \llbracket N \rrbracket \rrbracket^w = \llbracket N \rrbracket^w$ , and that Proposition 22 states if a term  $N \in \Lambda$  is strongly normalising then so is  $\llbracket N \rrbracket^w$ . Observe that the statement ‘if term  $M$  has an infinite reduction sequence then term  $N$  has an infinite reduction sequence’ is equivalent to ‘if term  $N$  is strongly normalising then term  $M$  is strongly normalising’ by contraposition. Therefore, given a strongly normalising term  $N \in \Lambda$ , we know that its corresponding weakening term is also strongly normalising. Furthermore, since  $\llbracket \llbracket N \rrbracket \rrbracket^w = \llbracket N \rrbracket^w$ , we know that  $\llbracket \llbracket N \rrbracket \rrbracket^w$  is also strongly normalising.



We prove that the spinal atomic  $\lambda$ -calculus preserves strong normalisation with the following.

► **Lemma 35.** For  $t \in \Lambda_a^S$  has an infinite reduction path, then  $\llbracket t \rrbracket^w$  also has an infinite reduction path.

**Proof.** Due to Theorem 34, we know that the infinite reduction path contains an infinite  $\beta$ -reduction. This means in the reduction sequence, between each  $\beta$ -reduction, there are finite many  $\rightsquigarrow_{(D,L,C)}$  reduction steps. Lemma 25 says each  $\rightsquigarrow_{(D,L,C)}$  step in  $\Lambda_a^S$  corresponds

489 to zero or more weakening reductions ( $\rightsquigarrow_{\mathcal{W}}^*$ ). Lemma 24 says that each beta reduction in  $\Lambda_a^S$   
 490 corresponds to one or more  $\beta$ -steps in  $\Lambda_{\mathcal{W}}$ . Therefore, it is inevitable that  $\llbracket t \rrbracket^{\mathcal{W}}$  also has an  
 491 infinite reduction path.  $\blacktriangleleft$

492 **► Theorem 36.** *If  $N \in \Lambda$  is strongly normalising, then so is  $\langle N \rangle$ .*

493 **Proof.** For a given  $N \in \Lambda$  that is strongly normalising, we know by Lemma 22 that  $\langle N \rangle^{\mathcal{W}}$  is  
 494 strongly normalising. Then  $\llbracket \langle N \rangle \rrbracket^{\mathcal{W}}$  is strongly normalising, since Proposition 20 states that  
 495  $\langle N \rangle^{\mathcal{W}} = \llbracket \langle N \rangle \rrbracket^{\mathcal{W}}$ . Then by Lemma 35, which states that if  $\llbracket t \rrbracket^{\mathcal{W}}$  is strongly normalising,  
 496 then  $t$  is strongly normalising, proves that  $\langle N \rangle$  is strongly normalising.  $\blacktriangleleft$

## 497 **6 Conclusion and Further Remarks**

## 498 **A** The Spinal Atomic $\lambda$ -Calculus

### 499 **A.1** Compilation and Readback

500 In this section we provide the proof for Proposition 11: For  $s, t \in \Lambda_a^S$ , if  $s \sim t$  then  $\llbracket s \rrbracket = \llbracket t \rrbracket$ .

501 **Proof.** Let us consider the cases.

$$502 \quad t[\Gamma_1][\Gamma_2] \sim t[\Gamma_2][\Gamma_1]$$

503 Consider  $\llbracket t[\Gamma_1][\Gamma_2] \mid \sigma \mid \gamma \rrbracket = \llbracket t[\Gamma_1] \mid \sigma' \mid \gamma' \rrbracket = \llbracket t \mid \sigma'' \mid \gamma'' \rrbracket$ . Since due to conditions any variable  $x \in \llbracket \Gamma_2 \rrbracket$  cannot occur in  $\llbracket \Gamma_1 \rrbracket$ , for all subterms  $s$  located in  $\llbracket \Gamma_1 \rrbracket$ ,  $\llbracket s \mid \sigma' \mid \gamma' \rrbracket = \llbracket s \mid \sigma \mid \gamma \rrbracket$ .  
 504 Therefore  $\llbracket t \mid \sigma'' \mid \gamma'' \rrbracket = \llbracket t[\Gamma_2] \mid \sigma''' \mid \gamma''' \rrbracket = \llbracket t[\Gamma_2][\Gamma_1] \mid \sigma \mid \gamma \rrbracket$ .  
 505  
 506

507 The remaining cases discuss permutations of variables in sharings and phantom-abstractions.  
 508 In both these cases, we overwrite  $\sigma$  for the cases of the variables in said sharing or phantom-  
 509 abstractions. The order in which they appear do not influence the translation since we do  
 510 this for all variables regardless.  $\blacktriangleleft$

We also provide the proof for Lemma 11: For a closed  $t \in \Lambda_a^S$ , where  $t$  has no distributor constructs and only variables are shared, and a closed  $N \in \Lambda$ . the following

$$\llbracket \langle N \rangle' \rrbracket = N \quad \langle \llbracket t \rrbracket \rangle' = t \quad \exists_{M \in \Lambda}. t = \langle M \rangle'$$

512 **Proof.** We prove  $\llbracket \langle N \rangle' \rrbracket = N$  by induction on  $N$

513 Base Case: Variable

$$514 \quad \llbracket \langle x \rangle' \rrbracket = \llbracket x \rrbracket = x$$

515 Inductive Case: Application

$$516 \quad \llbracket \langle M N \rangle' \rrbracket = \llbracket \langle M \rangle' \rrbracket \llbracket \langle N \rangle' \rrbracket = M N$$

517 Inductive Case: Abstraction

$$518 \quad \llbracket \langle \lambda x. M \rangle' \rrbracket$$

$$519 \quad \text{Case: } |M|_x = 1 \\ 520 \quad = \lambda x. \llbracket \langle M \rangle' \rrbracket = \lambda x. M$$

$$521 \quad \text{Case: } |M|_x = n \\ 522 \quad = \lambda x. \llbracket \langle M_x^n \rangle' [x_1, \dots, x_n \leftarrow x] \rrbracket = \lambda x. \llbracket \langle M_x^n \rangle' \mid \sigma \mid I \rrbracket = \lambda x. \llbracket \langle M_x^n \rangle' \rrbracket \{x/x_i\}_{1 \leq i \leq n} \\ 523 \quad \stackrel{\text{I.H.}}{=} \lambda x. M_x^n \{x/x_i\}_{1 \leq i \leq n} = \lambda x. M$$

524 We prove  $\langle \llbracket t \rrbracket \rangle' = t$  by induction on  $t$

525 Base Case: Variable

$$526 \quad \langle \llbracket x \rrbracket \rangle' = \langle x \rangle' = x$$

527 Inductive Case: Application

$$528 \quad \langle \llbracket s t \rrbracket \rangle' = \langle \llbracket s \rrbracket \rangle' \langle \llbracket t \rrbracket \rangle' \stackrel{\text{I.H.}}{=} s t$$

529 Inductive Case: Abstraction



539 Case:  $\llbracket x \langle x \rangle . t \rrbracket' = x \langle x \rangle . \llbracket t \rrbracket' \stackrel{\text{I.H.}}{=} x \langle x \rangle . t$

540

541 Case:  $\llbracket x \langle x \rangle . t[x_1, \dots, x_n \leftarrow x] \rrbracket' = \llbracket \lambda x. \llbracket t \mid \sigma \mid I \rrbracket' \rrbracket'$   
 542  $= \llbracket \lambda x. \llbracket t \rrbracket' \{x/x_i\}_{1 \leq i \leq n} \rrbracket' = x \langle x \rangle . \llbracket t \rrbracket' [x_1, \dots, x_n \leftarrow x]$   
 543  $\stackrel{\text{I.H.}}{=} x \langle x \rangle . t[x_1, \dots, x_n \leftarrow x]$

544

545 The proof for  $\exists_{M \in \Lambda}. t = \llbracket M \rrbracket'$  is the same as in [?]. ◀

## 546 A.2 Rewrite Rules

547 In this section we provide the proof for Proposition 37: Given  $M \in \Lambda$  such that for all  $v \in V$ ,  
 548  $\gamma(v) \notin (M)_{fv}$  and  $\sigma(x) = x$ , the translation  $\llbracket u \mid \sigma \mid \gamma \rrbracket$  commutes with substitution  $\{M/x\}$  in  
 549 the following way

$$\llbracket u \{t/x\} \mid \sigma \mid \gamma \rrbracket = \llbracket u \mid \sigma[x \mapsto \llbracket t \mid \sigma \mid \gamma \rrbracket] \mid \gamma \rrbracket$$

550 **Proof.** We prove this by induction on  $u$

551

552 Base Case: Variable

553  $\llbracket x \{t/x\} \mid \sigma \mid \gamma \rrbracket = \llbracket t \mid \sigma \mid \gamma \rrbracket = \llbracket x \mid \sigma' \mid \gamma \rrbracket$

554

555  $\llbracket y \mid \sigma \mid \gamma \rrbracket = \sigma(y) = \sigma'(y) = \llbracket y \mid \sigma' \mid \gamma \rrbracket$

556

557 Inductive Case: Application

558  $\llbracket u s \{t/x\} \mid \sigma \mid \gamma \rrbracket = \llbracket u \{t/x\} \mid \sigma \mid \gamma \rrbracket \llbracket s \{t/x\} \mid \sigma \mid \gamma \rrbracket \stackrel{\text{I.H.}}{=} \llbracket u \mid \sigma' \mid \gamma \rrbracket \llbracket s \mid \sigma' \mid \gamma \rrbracket = \llbracket u s \mid \sigma' \mid \gamma \rrbracket$

559

560 Inductive Case: Abstraction

561  $\llbracket (c \langle c \rangle . s) \{t/x\} \mid \sigma \mid \gamma \rrbracket = \lambda c. \llbracket s \{t/x\} \mid \sigma \mid \gamma \rrbracket \stackrel{\text{I.H.}}{=} \lambda c. \llbracket s \mid \sigma' \mid \gamma \rrbracket = \llbracket c \langle c \rangle . s \mid \sigma' \mid \gamma \rrbracket$

562

563 Inductive Case: Phantom-Abstraction

564  $\llbracket (c \langle x_1, \dots, x_n \rangle . s) \{t/x\} \mid \sigma \mid \gamma \rrbracket$

565 Case:  $x \in \{x_1, \dots, x_n\}$

566  $= \llbracket (c \langle x_1, \dots, x_n, x \rangle . s) \{t/x\} \mid \sigma \mid \gamma \rrbracket = \llbracket c \langle x_1, \dots, x_n, y_1, \dots, y_m \rangle . s \{t/x\} \mid \sigma \mid \gamma \rrbracket$

567 where  $\{y_1, \dots, y_m\} = (t)_{fv}$

568  $= \lambda c. \llbracket s \{t/x\} \mid \sigma'' \mid \gamma \rrbracket \stackrel{\text{I.H.}}{=} \lambda c. \llbracket s \mid \sigma_1''' \mid \gamma \rrbracket = \lambda c. \llbracket s \mid \sigma_2''' \mid \gamma \rrbracket = \llbracket c \langle x_1, \dots, x_n, x \rangle . s \mid \sigma' \mid \gamma \rrbracket$

569 where  $\sigma''(z) = \begin{cases} \sigma(z) \{c/\gamma(c)\} & \text{if } z \in \{x_1, \dots, x_n, y_1, \dots, y_m\} \\ \sigma(z) & \text{otherwise} \end{cases}$

570  $\sigma_1''' = \sigma''[x \mapsto \llbracket t \mid \sigma'' \mid \gamma \rrbracket]$

571  $\sigma_2'''(z) = \begin{cases} \llbracket t \mid \sigma'' \mid \gamma \rrbracket \{c/\gamma(c)\} & z = x \\ \sigma(z) \{c/\gamma(c)\} & z \in \{x_1, \dots, x_n\} \\ \sigma(z) & \text{otherwise} \end{cases}$

572

573 Case:  $x \notin \{x_1, \dots, x_n\}$

574  $= \llbracket c \langle x_1, \dots, x_n \rangle . s \{t/x\} \mid \sigma \mid \gamma \rrbracket = \lambda c. \llbracket s \{t/x\} \mid \sigma'' \mid \gamma \rrbracket \stackrel{\text{I.H.}}{=} \lambda c. \llbracket t \mid \sigma''[x \mapsto \llbracket t \mid \sigma'' \mid \gamma \rrbracket] \mid \gamma \rrbracket =$

575  $\lambda c. \llbracket t \mid \sigma''[x \mapsto \llbracket t \mid \sigma \mid \gamma \rrbracket] \mid \gamma \rrbracket = \llbracket c \langle x_1, \dots, x_n \rangle . s \mid \sigma[x \mapsto \llbracket t \mid \sigma \mid \gamma \rrbracket] \mid \gamma \rrbracket$

576 where

577  $\sigma'' = \sigma[x_i \mapsto \sigma(x_i) \{c/\gamma(c)\}]_{i \in [n]}$

578

579 Inductive Case: Sharing

$$\begin{aligned} & \llbracket u[z_1, \dots, z_n \leftarrow s]\{t/x\} \mid \sigma \mid \gamma \rrbracket = \llbracket u\{t/x\}[z_1, \dots, z_n \leftarrow s\{t/x\}] \mid \sigma \mid \gamma \rrbracket = \llbracket u\{t/x\} \mid \sigma'' \mid \gamma \rrbracket \\ & \stackrel{\text{I.H.}}{=} \llbracket u \mid \sigma''' \mid \gamma \rrbracket = \llbracket u[z_1, \dots, z_n \leftarrow s] \mid \sigma' \mid \gamma \rrbracket \end{aligned}$$

where

$$\begin{aligned} \sigma'' &= \sigma[z_1 \mapsto \llbracket s\{t/x\} \mid \sigma \mid \gamma \rrbracket, \dots, z_n \mapsto \llbracket s\{t/x\} \mid \sigma \mid \gamma \rrbracket] \\ \sigma''' &= \sigma'[z_1 \mapsto \llbracket s \mid \sigma' \mid \gamma \rrbracket, \dots, z_n \mapsto \llbracket s \mid \sigma' \mid \gamma \rrbracket] \end{aligned}$$

Inductive Case: Distributor 1

$$\begin{aligned} & \llbracket u[e_1 \langle \vec{w}_1 \rangle, \dots, e_n \langle \vec{w}_n \rangle \mid c \langle \vec{c} \rangle [\overline{\Gamma}]]\{t/x\} \mid \sigma \mid \gamma \rrbracket \\ &= \llbracket u[\overline{\Gamma}]\{t/x\} \mid \sigma \mid \gamma' \rrbracket \stackrel{\text{I.H.}}{=} \llbracket u[\overline{\Gamma}] \mid \sigma' \mid \gamma' \rrbracket \\ &= \llbracket u[e_1 \langle \vec{w}_1 \rangle, \dots, e_n \langle \vec{w}_n \rangle \mid c \langle \vec{x} \rangle [\overline{\Gamma}]] \mid \sigma' \mid \gamma \rrbracket \end{aligned}$$

where

$$\gamma' = \gamma[e_1 \mapsto c, \dots, e_n \mapsto c]$$

Inductive Case: Distributor 2

$$\begin{aligned} & \llbracket u[e_1 \langle \vec{w}_1 \rangle, \dots, e_n \langle \vec{w}_n \rangle \mid c \langle \vec{x} \rangle [\overline{\Gamma}]]\{t/x\} \mid \sigma \mid \gamma \rrbracket \\ &= \llbracket u[\overline{\Gamma}]\{t/x\} \mid \sigma'' \mid \gamma' \rrbracket \stackrel{\text{I.H.}}{=} \llbracket u[\overline{\Gamma}] \mid \sigma''' \mid \gamma' \rrbracket \\ &= \llbracket u[e_1 \langle \vec{w}_1 \rangle, \dots, e_n \langle \vec{w}_n \rangle \mid c \langle \vec{x} \rangle [\overline{\Gamma}]] \mid \sigma' \mid \gamma \rrbracket \end{aligned}$$

where

$$\gamma' = \gamma[e_1 \mapsto c, \dots, e_n \mapsto c]$$

The proof for Proposition 13 (repeated here) is shown below. Book-keeping commutes with the translation in the following way

if  $c \langle y_1, \dots, y_m \rangle \in (u)_{fc}$  such that  $\{x_1, \dots, x_n\} \subset \{y_1, \dots, y_m\}$   
 and for those  $z \in \{y_1, \dots, y_m\} \setminus \{x_1, \dots, x_n\}$ ,  $\gamma(c) \notin (\sigma(z))_{fv}$   
 or if simply  $\{x_1, \dots, x_n\} \cap (u)_{fv} = \{\}$

$$\llbracket u\{x_1, \dots, x_n/c\}_b \mid \sigma \mid \gamma \rrbracket = \llbracket u \mid \sigma \mid \gamma \rrbracket$$

**Proof.** We prove this by induction on  $u$

Base Case: Variable

$$\begin{aligned} & \llbracket x\{x_1, \dots, x_n/c\}_b \mid \sigma \mid \gamma \rrbracket = \llbracket x \mid \sigma \mid \gamma \rrbracket = \sigma(x) = \sigma'(x) = \llbracket x \mid \sigma' \mid \gamma' \rrbracket \\ & \text{Since it cannot be that } x \in \{x_1, \dots, x_n\} \end{aligned}$$

Base Case: Phantom-Abstraction

$$\begin{aligned} & \llbracket (c \langle y_1, \dots, y_m \rangle . t) \{x_1, \dots, x_n/c\}_b \mid \sigma \mid \gamma \rrbracket = \llbracket c \langle x_1, \dots, x_n \rangle . t \mid \sigma \mid \gamma \rrbracket \\ &= \lambda c. \llbracket t \mid \sigma'' \mid \gamma \rrbracket = \lambda c. \llbracket t \mid \sigma'' \mid \gamma' \rrbracket = \llbracket c \langle y_1, \dots, y_m \rangle . t \mid \sigma' \mid \gamma' \rrbracket \end{aligned}$$

where

$$\begin{aligned} \sigma &= \sigma_1[x_1 \mapsto M_1, \dots, x_n \mapsto M_n] \\ \sigma'' &= \sigma_1[x_1 \mapsto M_1\{c/d\}, \dots, x_n \mapsto M_n\{c/d\}] \\ \gamma(c) &= d \end{aligned}$$

Note: due to condition of Proposition any  $\{y_i \mapsto M_i\{c/d\}\} = \{y_i \mapsto M_i\}$

Base Case: Distributor

$$\begin{aligned} & \llbracket u[e_1 \langle \vec{w}_1 \rangle, \dots, e_n \langle \vec{w}_n \rangle \mid c \langle y_1, \dots, y_m \rangle [\overline{\Gamma}]]\{x_1, \dots, x_n/c\}_b \mid \sigma \mid \gamma \rrbracket \\ &= \llbracket u[e_1 \langle \vec{w}_1 \rangle, \dots, e_n \langle \vec{w}_n \rangle \mid c \langle x_1, \dots, x_n \rangle [\overline{\Gamma}]] \mid \sigma \mid \gamma \rrbracket = \llbracket u[\overline{\Gamma}] \mid \sigma' \mid \gamma' \rrbracket \\ &= \llbracket u[e_1 \langle \vec{w}_1 \rangle, \dots, e_n \langle \vec{w}_n \rangle \mid c \langle y_1, \dots, y_m \rangle [\overline{\Gamma}]] \mid \sigma \mid \gamma \rrbracket \\ & \text{where } \gamma' = \gamma[e_1 \mapsto c, \dots, e_n \mapsto c] \\ & \sigma = \sigma_1[x_1 \mapsto M_1, \dots, x_n \mapsto M_n] \end{aligned}$$

625  $\sigma' = \sigma_1[x_1 \mapsto M_1\{c/\gamma(c)\}, \dots, x_n \mapsto M_n\{c/\gamma(c)\}]$   
 626  
 627 Inductive Case: Application  
 628  $\llbracket (st)\{x_1, \dots, x_n/c\}_b \mid \sigma \mid \gamma \rrbracket = \llbracket s\{x_1, \dots, x_n/c\}_b \mid \sigma \mid \gamma \rrbracket \llbracket t\{x_1, \dots, x_n/c\}_b \mid \sigma \mid \gamma \rrbracket$   
 629  $\stackrel{\text{I.H.}}{=} \llbracket s \mid \sigma \mid \gamma \rrbracket \llbracket t \mid \sigma \mid \gamma \rrbracket = \llbracket st \mid \sigma \mid \gamma \rrbracket$   
 630  
 631 Inductive Case: Abstraction  
 632  $\llbracket (z\langle z \rangle.t)\{x_1, \dots, x_n/c\}_b \mid \sigma \mid \gamma \rrbracket = \lambda z. \llbracket t\{x_1, \dots, x_n/c\}_b \mid \sigma \mid \gamma \rrbracket \stackrel{\text{I.H.}}{=} \lambda z. \llbracket t \mid \sigma \mid \gamma \rrbracket = \llbracket z\langle z \rangle.t \mid \sigma \mid \gamma \rrbracket$   
 633  
 634 Inductive Case: Phantom-Abstraction  
 635  $\llbracket (d\langle z_1, \dots, z_m \rangle.t)\{x_1, \dots, x_n/c\}_b \mid \sigma \mid \gamma \rrbracket = \lambda d. \llbracket t\{x_1, \dots, x_n/c\}_b \mid \sigma' \mid \gamma \rrbracket$   
 636  $\stackrel{\text{I.H.}}{=} \lambda d. \llbracket t \mid \sigma' \mid \gamma \rrbracket = \llbracket d\langle z_1, \dots, z_m \rangle.t \mid \sigma \mid \gamma \rrbracket$   
 637  
 638 Inductive Case: Sharing  
 639  $\llbracket u[z_1, \dots, z_m \leftarrow t]\{x_1, \dots, x_n/c\}_b \mid \sigma \mid \gamma \rrbracket$   
 640  $= \llbracket u\{x_1, \dots, x_n/c\}_b[z_1, \dots, z_m \leftarrow t\{x_1, \dots, x_n/c\}_b] \mid \sigma \mid \gamma \rrbracket$   
 641  $= \llbracket u\{x_1, \dots, x_n/c\}_b \mid \sigma' \mid \gamma \rrbracket \stackrel{\text{I.H.}}{=} \llbracket u \mid \sigma'' \mid \gamma \rrbracket = \llbracket u[z_1, \dots, z_m \leftarrow t] \mid \sigma \mid \gamma \rrbracket$   
 642  
 643 Inductive Case: Distributor  
 644  $\llbracket u[e_1\langle \vec{w}_1 \rangle, \dots, e_m\langle \vec{w}_m \rangle \mid d\langle d \rangle \overline{[\Gamma]}]\{x_1, \dots, x_n/c\}_b \mid \sigma \mid \gamma \rrbracket$   
 645  $= \llbracket u[e_1\langle \vec{w}_1 \rangle, \dots, e_m\langle \vec{w}_m \rangle \mid d\langle d \rangle \overline{[\Gamma]}\{x_1, \dots, x_n/c\}_b] \mid \sigma \mid \gamma \rrbracket$   
 646  $= \llbracket u[\overline{[\Gamma]}\{x_1, \dots, x_n/c\}_b \mid \sigma \mid \gamma' \rrbracket \stackrel{\text{I.H.}}{=} \llbracket u[\overline{[\Gamma]}\{x_1, \dots, x_n/c\}_b \mid \sigma \mid \gamma' \rrbracket$   
 647  $= \llbracket u[e_1\langle \vec{w}_1 \rangle, \dots, e_m\langle \vec{w}_m \rangle \mid d\langle d \rangle \overline{[\Gamma]}] \mid \sigma \mid \gamma \rrbracket$  ◀

648 The proof for 14 (repeated here) is below. Exorcisms commute with the translation in  
 649 the following way  
 650 if  $c\langle x_1, \dots, x_n \rangle. \in (u)_{fc}$  or  $\{x_1, \dots, x_n\} \cap (u)_{fv} = \{\}$

$$\llbracket u\{c\langle x_1, \dots, x_n \rangle\}_e \mid \sigma \mid \gamma \rrbracket = \llbracket u \mid \sigma[x_i \mapsto c]_{i \in [n]} \mid \gamma \rrbracket$$

651 **Proof.** We prove this by induction on  $u$

652  
653 Base Case: Variable

$$654 \llbracket z\{c\langle x_1, \dots, x_n \rangle\}_e \mid \sigma \mid \gamma \rrbracket = \llbracket z \mid \sigma \mid \gamma \rrbracket = \sigma(z) = \sigma'(z) = \llbracket z \mid \sigma' \mid \gamma \rrbracket$$

655  
656 Base Case: Phantom-Abstraction

$$657 \llbracket (c\langle x_1, \dots, x_n \rangle.t)\{c\langle x_1, \dots, x_n \rangle\}_e \mid \sigma \mid \gamma \rrbracket = \llbracket c\langle c \rangle.t[x_1, \dots, x_n \leftarrow c] \mid \sigma \mid \gamma \rrbracket$$

$$658 = \lambda c. \llbracket t[x_1, \dots, x_n \leftarrow c] \mid \sigma \mid \gamma \rrbracket = \lambda c. \llbracket t \mid \sigma' \mid \gamma \rrbracket = \llbracket c\langle x_1, \dots, x_n \rangle.t \mid \sigma' \mid \gamma \rrbracket$$

659  
660 Base Case: Distributor

$$661 \llbracket u[e_1\langle \vec{w}_1 \rangle, \dots, e_m\langle \vec{w}_m \rangle \mid c\langle x_1, \dots, x_n \rangle \overline{[\Gamma]}]\{c\langle x_1, \dots, x_n \rangle\}_e \mid \sigma \mid \gamma \rrbracket$$

$$662 = \llbracket u[e_1\langle \vec{w}_1 \rangle, \dots, e_m\langle \vec{w}_m \rangle \mid c\langle c \rangle \overline{[\Gamma]}[x_1, \dots, x_n \leftarrow c]] \mid \sigma \mid \gamma \rrbracket$$

$$663 = \llbracket u[\overline{[\Gamma]}[x_1, \dots, x_n \leftarrow c] \mid \sigma \mid \gamma' \rrbracket = \llbracket u[\overline{[\Gamma]}] \mid \sigma' \mid \gamma' \rrbracket$$

$$664 = \llbracket u[e_1\langle \vec{w}_1 \rangle, \dots, e_m\langle \vec{w}_m \rangle \mid c\langle x_1, \dots, x_n \rangle \overline{[\Gamma]}] \mid \sigma' \mid \gamma \rrbracket$$

665  
666 Inductive Case: Application

$$667 \llbracket (st)\{c\langle x_1, \dots, x_n \rangle\}_e \mid \sigma \mid \gamma \rrbracket = \llbracket s\{c\langle x_1, \dots, x_n \rangle\}_e \mid \sigma \mid \gamma \rrbracket \llbracket t\{c\langle x_1, \dots, x_n \rangle\}_e \mid \sigma \mid \gamma \rrbracket$$

$$668 \stackrel{\text{I.H.}}{=} \llbracket s \mid \sigma' \mid \gamma \rrbracket \llbracket t \mid \sigma' \mid \gamma \rrbracket = \llbracket st \mid \sigma' \mid \gamma \rrbracket$$

669

670 Inductive Case: Abstraction

$$\begin{aligned} 671 & \llbracket (z\langle z \rangle.t)\{c\langle x_1, \dots, x_n \rangle\}_e | \sigma | \gamma \rrbracket = \lambda z. \llbracket t\{c\langle x_1, \dots, x_n \rangle\}_e | \sigma | \gamma \rrbracket \\ 672 & \stackrel{\text{I.H.}}{=} \lambda z. \llbracket t | \sigma' | \gamma \rrbracket = \llbracket z\langle z \rangle.t | \sigma' | \gamma \rrbracket \end{aligned}$$

673

674 Inductive Case: Phantom-Abstraction

$$\begin{aligned} 675 & \llbracket (d\langle z_1, \dots, z_m \rangle.t)\{c\langle x_1, \dots, x_n \rangle\}_e | \sigma | \gamma \rrbracket = \lambda d. \llbracket t\{c\langle x_1, \dots, x_n \rangle\}_e | \sigma'' | \gamma \rrbracket \\ 676 & \stackrel{\text{I.H.}}{=} \lambda d. \llbracket t | \sigma''' | \gamma \rrbracket = \llbracket d\langle z_1, \dots, z_m \rangle.t | \sigma' | \gamma \rrbracket \end{aligned}$$

677

678 Inductive Case: Sharing

$$\begin{aligned} 679 & \llbracket u[z_1, \dots, z_m \leftarrow t]\{c\langle x_1, \dots, x_n \rangle\}_e | \sigma | \gamma \rrbracket \\ 680 & = \llbracket u\{c\langle x_1, \dots, x_n \rangle\}_e[z_1, \dots, z_m \leftarrow t\{c\langle x_1, \dots, x_n \rangle\}_e] | \sigma | \gamma \rrbracket \\ 681 & = \llbracket u\{c\langle x_1, \dots, x_n \rangle\}_e | \sigma'' | \gamma \rrbracket \stackrel{\text{I.H.}}{=} \llbracket u | \sigma''' | \gamma \rrbracket = \llbracket u[z_1, \dots, z_m \leftarrow t] | \sigma' | \gamma \rrbracket \end{aligned}$$

682

683 Inductive Case: Distributor

$$\begin{aligned} 684 & \llbracket u[e_1\langle \vec{w}_1 \rangle, \dots, e_m\langle \vec{w}_m \rangle | d\langle d \rangle \overline{[\Gamma]}]\{c\langle x_1, \dots, x_n \rangle\}_e | \sigma | \gamma \rrbracket \\ 685 & = \llbracket u[e_1\langle \vec{w}_1 \rangle, \dots, e_m\langle \vec{w}_m \rangle | d\langle d \rangle \overline{[\Gamma]}]\{c\langle x_1, \dots, x_n \rangle\}_e | \sigma | \gamma \rrbracket \\ 686 & = \llbracket u[\overline{[\Gamma]}\{c\langle x_1, \dots, x_n \rangle\}_e | \sigma | \gamma'] \rrbracket \stackrel{\text{I.H.}}{=} \llbracket u[\overline{[\Gamma]}\{c\langle x_1, \dots, x_n \rangle\}_e | \sigma' | \gamma'] \rrbracket \\ 687 & = \llbracket u[e_1\langle \vec{w}_1 \rangle, \dots, e_m\langle \vec{w}_m \rangle | d\langle d \rangle \overline{[\Gamma]}] | \sigma | \gamma \rrbracket \end{aligned}$$

688 We prove Lemma 16 on a case by case basis. If  $s \rightsquigarrow_{L,D,C} t$  then  $\llbracket s | \sigma | \gamma \rrbracket = \llbracket t | \sigma | \gamma \rrbracket$

**Proof.** We prove this by induction. First we to a case-by-case basis for the base case.

Case:  $(c_1)$

$$u[\vec{w} \leftarrow y][\vec{x} \cdot y \leftarrow t] \rightsquigarrow_C u[\vec{x} \cdot \vec{w} \leftarrow t]$$

$$\llbracket u[\vec{w} \leftarrow y][\vec{x} \cdot y \leftarrow t] | \sigma | \gamma \rrbracket = \llbracket u[\vec{w} \leftarrow y] | \sigma' | \gamma \rrbracket = \llbracket u | \sigma'' | \gamma \rrbracket = \llbracket u[\vec{x} \cdot \vec{w} \leftarrow t] | \sigma | \gamma \rrbracket$$

where

$$\sigma' = \sigma[x \mapsto \llbracket t | \sigma | \gamma \rrbracket]_{\forall x \in \vec{x}}[y \mapsto \llbracket t | \sigma | \gamma \rrbracket]$$

$$\sigma'' = \sigma'[w \mapsto \llbracket t | \sigma | \gamma \rrbracket]_{\forall w \in \vec{w}}$$

Case:  $(c_2)$

$$u[x \leftarrow t] \rightsquigarrow_C u\{t/x\}$$

$$\llbracket u[x \leftarrow t] | \sigma | \gamma \rrbracket = \llbracket u | \sigma[x \mapsto \llbracket t | \sigma | \gamma \rrbracket] | \gamma \rrbracket = \llbracket u\{t/x\} | \sigma | \gamma \rrbracket$$

Case:  $(d_1)$

$$u[x_1 \dots x_n \leftarrow st] \rightsquigarrow_D u\{z_1 y_1/x_1\} \dots \{z_n y_n/x_n\}[z_1 \dots z_n \leftarrow s][y_1 \dots y_n \leftarrow t]$$

$$\llbracket u[x_1 \dots x_n \leftarrow st] | \sigma | \gamma \rrbracket = \llbracket u | \sigma' | \gamma \rrbracket$$

where

$$\sigma' = \sigma[x_i \mapsto \llbracket st | \sigma | \gamma \rrbracket]_{1 \leq i \leq n} = \sigma[x_i \mapsto \llbracket s | \sigma | \gamma \rrbracket \llbracket t | \sigma | \gamma \rrbracket]_{1 \leq i \leq n}$$

$$\begin{aligned} & \llbracket u\{z_1 y_1/x_1\} \dots \{z_n y_n/x_n\}[z_1 \dots z_n \leftarrow s][y_1 \dots y_n \leftarrow t] | \sigma | \gamma \rrbracket \\ & = \llbracket u\{z_1 y_1/x_1\} \dots \{z_n y_n/x_n\} | \sigma'' | \gamma \rrbracket \end{aligned}$$

where

$$\sigma'' = \sigma[z_i \mapsto \llbracket s | \sigma | \gamma \rrbracket]_{1 \leq i \leq n}[y_i \mapsto \llbracket t | \sigma | \gamma \rrbracket]_{1 \leq i \leq n} \text{ since } y_i \notin (s)_{fv}$$

$$= \llbracket u | \sigma''' | \gamma \rrbracket$$

where

$\sigma''' = \sigma''[x_i \mapsto \llbracket z_i y_i \mid \sigma'' \mid \gamma \rrbracket]_{1 \leq i \leq n} = \sigma[x_i \mapsto \llbracket s \mid \sigma \mid \gamma \rrbracket \llbracket t \mid \sigma \mid \gamma \rrbracket]_{1 \leq i \leq n}$   
 since  $z_i$  and  $y_i \notin (u)_{fv}$

Case:  $(d_2)$

$$u[x_1, \dots, x_n \leftarrow c\langle \vec{y} \rangle.t] \rightsquigarrow_D u\{e_i\langle w_1^i \rangle.w_1^i/x_i\}_{1 \leq i \leq n}[e_1\langle w_1^1 \rangle \dots e_n\langle w_1^n \rangle \mid c\langle \vec{y} \rangle][w_1^1, \dots, w_1^n \leftarrow t]$$

SubCase:  $\vec{y} = c$

$$\llbracket u[x_1, \dots, x_n \leftarrow c\langle c \rangle.t] \mid \sigma \mid \gamma \rrbracket = \llbracket u \mid \sigma' \mid \gamma \rrbracket$$

$$\text{where } \sigma' = \sigma[x_i \mapsto \llbracket c\langle c \rangle.t \mid \sigma \mid \gamma \rrbracket]_{1 \leq i \leq n} = \sigma[x_i \mapsto \lambda c. \llbracket t \mid \sigma \mid \gamma \rrbracket]_{1 \leq i \leq n}$$

$$\begin{aligned} & \llbracket u\{e_i\langle w_1^i \rangle.w_1^i/x_i\}_{1 \leq i \leq n}[e_1\langle w_1^1 \rangle \dots e_n\langle w_1^n \rangle \mid c\langle c \rangle][w_1^1, \dots, w_1^n \leftarrow t] \mid \sigma \mid \gamma \rrbracket \\ & \llbracket u\{e_i\langle w_1^i \rangle.w_1^i/x_i\}_{1 \leq i \leq n}[w_1^1, \dots, w_1^n \leftarrow t] \mid \sigma \mid \gamma' \rrbracket \\ & = \llbracket u\{e_i\langle w_1^i \rangle.w_1^i/x_i\}_{1 \leq i \leq n} \mid \sigma' \mid \gamma' \rrbracket \end{aligned}$$

where

$$\gamma' = \gamma[e_1 \mapsto c, \dots, e_n \mapsto c]$$

$$\sigma' = \sigma[w_1^i \mapsto \llbracket t \mid \sigma \mid \gamma' \rrbracket]_{1 \leq i \leq n} = \sigma[w_1^i \mapsto \llbracket t \mid \sigma \mid \gamma \rrbracket]_{1 \leq i \leq n}$$

$$= \llbracket u \mid \sigma'' \mid \gamma' \rrbracket = \llbracket u \mid \sigma'' \mid \gamma \rrbracket$$

where

$$\begin{aligned} \sigma'' &= \sigma'[x_i \mapsto \llbracket e_i\langle w_1^i \rangle.w_1^i \mid \sigma' \mid \gamma' \rrbracket]_{1 \leq i \leq n} = \sigma'[x_i \mapsto \lambda e_i. \llbracket w_1^i \mid \sigma' \mid \gamma' \rrbracket]_{1 \leq i \leq n} \\ &= \sigma'[x_i \mapsto \lambda e_i. \llbracket t \mid \sigma \mid \gamma \rrbracket \{e_i/c\}]_{1 \leq i \leq n} =_{\alpha} \sigma'[x_i \mapsto \lambda c. \llbracket t \mid \sigma \mid \gamma \rrbracket]_{1 \leq i \leq n} \\ &= \sigma[x_i \mapsto \lambda c. \llbracket t \mid \sigma \mid \gamma \rrbracket]_{1 \leq i \leq n} \text{ since } w_1^i \notin (u)_{fv} \end{aligned}$$

SubCase:  $\vec{y} = \{y_1, \dots, y_m\}$

$$\llbracket u[x_1, \dots, x_n \leftarrow c\langle y_1, \dots, y_m \rangle.t] \mid \sigma \mid \gamma \rrbracket = \llbracket u \mid \sigma' \mid \gamma \rrbracket$$

where

$$\sigma' = \sigma[x_i \mapsto \llbracket c\langle y_1, \dots, y_m \rangle.t \mid \sigma \mid \gamma \rrbracket]_{1 \leq i \leq n} = \sigma[x_i \mapsto \lambda c. \llbracket t \mid \sigma'' \mid \gamma \rrbracket]_{1 \leq i \leq n}$$

$$\sigma = \sigma_1[y_1 \mapsto M_1, \dots, y_m \mapsto M_m]$$

$$\sigma'' = \sigma_1[y_1 \mapsto M_1\{c/\gamma(c)\}, \dots, y_m \mapsto M_m\{c/\gamma(c)\}]$$

$$\begin{aligned} & \llbracket u\{e_i\langle w_1^i \rangle.w_1^i/x_i\}_{1 \leq i \leq n}[e_1\langle w_1^1 \rangle \dots e_n\langle w_1^n \rangle \mid c\langle y_1, \dots, y_m \rangle][w_1^1, \dots, w_1^n \leftarrow t] \mid \sigma \mid \gamma \rrbracket \\ & \llbracket u\{e_i\langle w_1^i \rangle.w_1^i/x_i\}_{1 \leq i \leq n}[w_1^1, \dots, w_1^n \leftarrow t] \mid \sigma'' \mid \gamma' \rrbracket \end{aligned}$$

$$\text{where } \gamma' = \gamma[e_1 \mapsto c, \dots, e_n \mapsto c]$$

$$= \llbracket u\{e_i\langle w_1^i \rangle.w_1^i/x_i\}_{1 \leq i \leq n} \mid \sigma''' \mid \gamma' \rrbracket$$

$$\text{where } \sigma''' = \sigma''[w_1^i \mapsto \llbracket t \mid \sigma'' \mid \gamma' \rrbracket]_{1 \leq i \leq n} = \sigma''[w_1^i \mapsto \llbracket t \mid \sigma'' \mid \gamma \rrbracket]_{1 \leq i \leq n}$$

$$= \llbracket u \mid \sigma'''' \mid \gamma' \rrbracket = \llbracket u \mid \sigma'''' \mid \gamma \rrbracket = \llbracket u \mid \sigma'' \mid \gamma \rrbracket$$

$$\begin{aligned} \text{where } \sigma'''' &= \sigma'''[x_i \mapsto \llbracket e_i\langle w_1^i \rangle.w_1^i \mid \sigma''' \mid \gamma' \rrbracket]_{1 \leq i \leq n} = \sigma'''[x_i \mapsto \lambda e_i. \llbracket w_1^i \mid \sigma''' \mid \gamma' \rrbracket]_{1 \leq i \leq n} \\ &= \sigma'''[x_i \mapsto \lambda e_i. \llbracket t \mid \sigma'' \mid \gamma \rrbracket \{e_i/\gamma'(e_i)\}]_{1 \leq i \leq n} =_{\alpha} \sigma'''[x_i \mapsto \lambda c. \llbracket t \mid \sigma'' \mid \gamma \rrbracket]_{1 \leq i \leq n} \end{aligned}$$

Case:  $(d_3)$

$$u[e_1\langle \vec{w}_1 \rangle \dots e_n\langle \vec{w}_n \rangle \mid c\langle c \rangle][\vec{w}_1, \dots, \vec{w}_n \leftarrow c] \rightsquigarrow_D u\{e_1\langle \vec{w}_1 \rangle\}_e \dots \{e_n\langle \vec{w}_n \rangle\}_e$$

$$\llbracket u[e_1\langle \vec{w}_1 \rangle \dots e_n\langle \vec{w}_n \rangle \mid c\langle c \rangle][\vec{w}_1, \dots, \vec{w}_n \leftarrow c] \mid \sigma \mid \gamma \rrbracket$$

$$= \llbracket u[\vec{w}_1, \dots, \vec{w}_n \leftarrow c] \mid \sigma \mid \gamma' \rrbracket = \llbracket u \mid \sigma' \mid \gamma' \rrbracket$$

$$= \llbracket u\{e_1\langle \vec{w}_1 \rangle\}_e \dots \{e_n\langle \vec{w}_n \rangle\}_e \mid \sigma \mid \gamma' \rrbracket = \llbracket u\{e_1\langle \vec{w}_1 \rangle\}_e \dots \{e_n\langle \vec{w}_n \rangle\}_e \mid \sigma \mid \gamma \rrbracket$$

For the remaining cases, we say  $\llbracket t[\Gamma] \mid \sigma \mid \gamma \rrbracket$  produces  $\llbracket t \mid \sigma_{\Gamma} \mid \gamma_{\Gamma} \rrbracket$  where  $\sigma_{\Gamma}$  and  $\gamma_{\Gamma}$  are

the resulting maps from interpreting the closure  $[\Gamma]$

Case:  $(l_1)$

$$s[\Gamma] t \rightsquigarrow_L (st)[\Gamma]$$

$$\llbracket s[\Gamma] t \mid \sigma \mid \gamma \rrbracket = \llbracket s \mid \sigma_\Gamma \mid \gamma_\Gamma \rrbracket \llbracket t \mid \sigma \mid \gamma \rrbracket = \llbracket s \mid \sigma_\Gamma \mid \gamma_\Gamma \rrbracket \llbracket t \mid \sigma_\Gamma \mid \gamma_\Gamma \rrbracket = \llbracket (st)[\Gamma] \mid \sigma \mid \gamma \rrbracket$$

Case:  $(l_2)$

$$s[\Gamma] t \rightsquigarrow_L (st)[\Gamma]$$

$$\llbracket s(t[\Gamma]) \mid \sigma \mid \gamma \rrbracket = \llbracket s \mid \sigma \mid \gamma \rrbracket \llbracket t \mid \sigma_\Gamma \mid \gamma_\Gamma \rrbracket = \llbracket s \mid \sigma_\Gamma \mid \gamma_\Gamma \rrbracket \llbracket t \mid \sigma_\Gamma \mid \gamma_\Gamma \rrbracket = \llbracket (st)[\Gamma] \mid \sigma \mid \gamma \rrbracket$$

Case:  $(l_3)$

$$d\langle \vec{x} \rangle . t[\Gamma] \rightsquigarrow_L (d\langle \vec{x} \rangle . t)[\Gamma]$$

SubCase:  $\vec{x} = d$

$$\llbracket d\langle d \rangle . t[\Gamma] \mid \sigma \mid \gamma \rrbracket = \lambda d. \llbracket t[\Gamma] \mid \sigma \mid \gamma \rrbracket = \lambda d. \llbracket t \mid \sigma_\Gamma \mid \gamma_\Gamma \rrbracket = \llbracket d\langle d \rangle . t \mid \sigma_\Gamma \mid \gamma_\Gamma \rrbracket = \llbracket (d\langle d \rangle . t)[\Gamma] \mid \sigma \mid \gamma \rrbracket$$

SubCase:  $\vec{x} = x_1, \dots, x_n$

$$\begin{aligned} \llbracket d\langle x_1, \dots, x_n \rangle . t[\Gamma] \mid \sigma \mid \gamma \rrbracket &= \lambda d. \llbracket t[\Gamma] \mid \sigma' \mid \gamma \rrbracket = \lambda d. \llbracket t \mid \sigma'_\Gamma \mid \gamma_\Gamma \rrbracket = \llbracket d\langle x_1, \dots, x_n \rangle . t \mid \sigma_\Gamma \mid \gamma_\Gamma \rrbracket \\ &= \llbracket (d\langle x_1, \dots, x_n \rangle . t)[\Gamma] \mid \sigma \mid \gamma \rrbracket \end{aligned}$$

since we know  $x_1, \dots, x_n \notin ([\Gamma])_{fv}$

Case:  $(l_4)$

$$u[\vec{x} \leftarrow t[\Gamma]] \rightsquigarrow_L u[\vec{x} \leftarrow t][\Gamma]$$

$$\llbracket u[\vec{x} \leftarrow t[\Gamma]] \mid \sigma \mid \gamma \rrbracket = \llbracket u \mid \sigma' \mid \gamma \rrbracket = \llbracket u \mid \sigma'' \mid \gamma_\Gamma \rrbracket = \llbracket u[\vec{x} \leftarrow t] \mid \sigma_\Gamma \mid \gamma_\Gamma \rrbracket = \llbracket u[\vec{x} \leftarrow t][\Gamma] \mid \sigma \mid \gamma \rrbracket$$

where

$$\sigma' = \sigma[x \mapsto \llbracket t[\Gamma] \mid \sigma \mid \gamma \rrbracket]_{\forall x \in \vec{x}} = \sigma[x \mapsto \llbracket t \mid \sigma_\Gamma \mid \gamma_\Gamma \rrbracket]_{\forall x \in \vec{x}}$$

$$\sigma'' = \sigma_\Gamma[x \mapsto \llbracket t \mid \sigma_\Gamma \mid \gamma_\Gamma \rrbracket]_{\forall x \in \vec{x}}$$

Cases:  $(l_5)$

$$u[e_1\langle \vec{w}_1 \rangle \dots e_n\langle \vec{w}_n \rangle \mid c\langle \vec{x} \rangle \overline{[\Gamma]}[\Gamma]] \rightsquigarrow_L$$

$$u\{(\vec{w}_i/\vec{z})/e_i\}_{b \in [n]}[e_1\langle \vec{w}_1/\vec{z} \rangle \dots e_n\langle \vec{w}_n/\vec{z} \rangle \mid c\langle \vec{x} \rangle \overline{[\Gamma]}[\Gamma]]$$

689 SubCase:  $\vec{x} = c$

690  $\llbracket u[e_1\langle \vec{w}_1 \rangle \dots e_n\langle \vec{w}_n \rangle \mid c\langle c \rangle \overline{[\Gamma]}[\Gamma]] \mid \sigma \mid \gamma \rrbracket = \llbracket u[\overline{[\Gamma]}[\Gamma]] \mid \sigma \mid \gamma' \rrbracket = \llbracket u[\overline{[\Gamma]}] \mid \sigma_\Gamma \mid \gamma'_\Gamma \rrbracket$

691  $= \llbracket u[\overline{[\Gamma]}]\{\vec{z}_1/e_1\}_b \dots \{\vec{z}_n/e_n\}_b \mid \sigma_\Gamma \mid \gamma'_\Gamma \rrbracket = \llbracket u\{\vec{z}_1/e_1\}_b \dots \{\vec{z}_n/e_n\}_b \overline{[\Gamma]} \mid \sigma_\Gamma \mid \gamma'_\Gamma \rrbracket$

692  $= \llbracket u\{\vec{z}_1/e_1\}_b \dots \{\vec{z}_n/e_n\}_b [e_1\langle \vec{z}_1 \rangle \dots e_n\langle \vec{z}_n \rangle \mid c\langle c \rangle \overline{[\Gamma]}] \mid \sigma_\Gamma \mid \gamma_\Gamma \rrbracket$

693  $= \llbracket u\{\vec{z}_1/e_1\}_b \dots \{\vec{z}_n/e_n\}_b [e_1\langle \vec{z}_1 \rangle \dots e_n\langle \vec{z}_n \rangle \mid c\langle c \rangle \overline{[\Gamma]}][\Gamma] \mid \sigma \mid \gamma \rrbracket$

694

695 SubCase:  $\vec{x} = x_1, \dots, x_m$

696  $\llbracket u[e_1\langle \vec{w}_1 \rangle \dots e_n\langle \vec{w}_n \rangle \mid c\langle x_1, \dots, x_m \rangle \overline{[\Gamma]}[\Gamma]] \mid \sigma \mid \gamma \rrbracket$

697  $= \llbracket u[\overline{[\Gamma]}][\Gamma] \mid \sigma' \mid \gamma' \rrbracket = \llbracket u[\overline{[\Gamma]}] \mid \sigma'_\Gamma \mid \gamma'_\Gamma \rrbracket = \llbracket u[\overline{[\Gamma]}\{\vec{z}_1/e_1\}_b \dots \{\vec{z}_n/e_n\}_b \mid \sigma_\Gamma \mid \gamma'_\Gamma \rrbracket$

698  $= \llbracket u\{\vec{z}_1/e_1\}_b \dots \{\vec{z}_n/e_n\}_b \overline{[\Gamma]} \mid \sigma_\Gamma \mid \gamma'_\Gamma \rrbracket$

699  $= \llbracket u\{\vec{z}_1/e_1\}_b \dots \{\vec{z}_n/e_n\}_b [e_1\langle \vec{z}_1 \rangle \dots e_n\langle \vec{z}_n \rangle \mid c\langle x_1, \dots, x_m \rangle \overline{[\Gamma]}] \mid \sigma_\Gamma \mid \gamma_\Gamma \rrbracket$

700  $= \llbracket u\{\vec{z}_1/e_1\}_b \dots \{\vec{z}_n/e_n\}_b [e_1\langle \vec{z}_1 \rangle \dots e_n\langle \vec{z}_n \rangle \mid c\langle x_1, \dots, x_m \rangle \overline{[\Gamma]}][\Gamma] \mid \sigma \mid \gamma \rrbracket$

701

702 Inductive Case: Application  $t \rightsquigarrow_{(C,D,L)} t'$

703  $\llbracket t s \mid \sigma \mid \gamma \rrbracket = \llbracket t \mid \sigma \mid \gamma \rrbracket \llbracket s \mid \sigma \mid \gamma \rrbracket \stackrel{1.H.}{=} \llbracket t' \mid \sigma \mid \gamma \rrbracket \llbracket s \mid \sigma \mid \gamma \rrbracket = \llbracket t' s \mid \sigma \mid \gamma \rrbracket$

◀

## B Strong Normalisation of Sharing Reductions

The weakening calculus is used to show preservation of strong normalisation with respect to the  $\lambda$ -calculus. A  $\beta$ -step in our calculus may occur within a weakening, and therefore is simulated by zero  $\beta$ -steps in the  $\lambda$ -calculus. Therefore if there is an infinite reduction path located inside a weakening in  $\Lambda_a^S$ , then the reduction path is not preserved in the corresponding  $\lambda$ -term as there are no weakenings. To deal with this, just as done in [?, ?, ?], we make use of the weakening calculus. A  $\beta$ -step is non-deleting precisely because of the weakening construct. If a  $\beta$ -step would be deleting in the  $\lambda$ -calculus, then the weakening calculus would instead keep the deleted term around as ‘garbage’, which can continue to reduce unless explicitly ‘garbage-collected’ by extra (non- $\beta$ ) reduction steps. The weakening calculus has already been shown to preserve strong normalisation through the use of a perpetual strategy in [?]. A part of proving PSN is then using the weakening calculus to prove that if  $t \in \Lambda_a^S$  has a infinite reduction path, then its translation into the weakening calculus also has an infinite reduction path.

First we demonstrate that our readback translation (Definition 18) is truly an extension of the translation into the  $\lambda$ -calculus (Definition 9). We therefore demonstrate that our operations (substitution, book-keeping, and exorcisms) commute with the two translation functions in the same way.

► **Proposition 37.** *Given  $M \in \Lambda$  such that for all  $v \in V$ ,  $\gamma(v) \notin (M)_{fv}$  and  $\sigma(x) = x$ , the translation  $\llbracket u \mid \sigma \mid \gamma \rrbracket_w$  commutes with substitution  $\{M/x\}$  in the following way*

$$\llbracket u\{t/x\} \mid \sigma \mid \gamma \rrbracket_w = \llbracket u \mid \sigma[x \mapsto \llbracket t \mid \sigma \mid \gamma \rrbracket_w] \mid \gamma \rrbracket_w$$

**Proof.** We prove this by induction on  $u$ . The argument is similar to the proof of Proposition 37. We only discuss here to cases involving the three special cases defined in Definition 18.

Inductive Case: Weakening

$$\begin{aligned} \llbracket u[\leftarrow s]\{t/x\} \mid \sigma \mid \gamma \rrbracket_w &= \llbracket u\{t/x\} \mid \sigma \mid \gamma \rrbracket_w [\leftarrow \llbracket s\{t/x\} \mid \sigma \mid \gamma \rrbracket_w] \\ &\stackrel{\text{I.H.}}{=} \llbracket u \mid \sigma' \mid \gamma \rrbracket_w [\leftarrow \llbracket s \mid \sigma' \mid \gamma \rrbracket_w] = \llbracket u[\leftarrow s] \mid \sigma' \mid \gamma \rrbracket_w \end{aligned}$$

Inductive Case: Distributor

$$\llbracket u[c\langle \vec{x} \rangle \overline{[\Gamma]}]\{t/x\} \mid \sigma \mid \gamma \rrbracket_w$$

SubCase:  $\vec{x} = c$

$$\begin{aligned} \llbracket u[c\langle c \rangle \overline{[\Gamma]}]\{t/x\} \mid \sigma \mid \gamma \rrbracket_w &= \llbracket u[c\langle c \rangle \overline{[\Gamma]}\{t/x\}] \mid \sigma \mid \gamma \rrbracket_w \\ &= \llbracket u[\overline{[\Gamma]}\{t/x\}] \mid \sigma'' \mid \gamma' \rrbracket_w \stackrel{\text{I.H.}}{=} \llbracket u[\overline{[\Gamma]}\{t/x\}] \mid \sigma''' \mid \gamma' \rrbracket_w = \llbracket u[c\langle c \rangle \overline{[\Gamma]}] \mid \sigma' \mid \gamma \rrbracket_w \end{aligned}$$

where

$$\sigma'' = \sigma \cup \{c \mapsto \bullet\}$$

$$\sigma''' = \sigma \cup \{c \mapsto \bullet\} \cup \{x \mapsto \llbracket t \mid \sigma'' \mid \gamma' \rrbracket_w\} = \sigma \cup \{c \mapsto \bullet\} \cup \{x \mapsto \llbracket t \mid \sigma \mid \gamma \rrbracket_w\}$$

SubCase:  $\vec{x} = x_1, \dots, x_n$

$$\llbracket u[c\langle x_1, \dots, x_n \rangle \overline{[\Gamma]}]\{t/x\} \mid \sigma \mid \gamma \rrbracket_w$$

SubSubCase:  $\vec{x} = x_1, \dots, x_n, x$

$$\begin{aligned} \llbracket u[c\langle x_1, \dots, x_n, x \rangle \overline{[\Gamma]}]\{t/x\} \mid \sigma \mid \gamma \rrbracket_w \\ \llbracket u[c\langle x_1, \dots, x_n, y_1, \dots, y_m \rangle \overline{[\Gamma]}\{t/x\}] \mid \sigma \mid \gamma \rrbracket_w \end{aligned}$$

where  $\{y_1, \dots, y_m\} = (t)_{fv}$

$$= \llbracket u[\overline{[\Gamma]}\{t/x\}] \mid \sigma'' \mid \gamma \rrbracket_w$$

749 where

$$\begin{aligned}
 750 \quad \sigma &= \sigma_1 \cup \{x_1 \mapsto M_1, \dots, x_n \mapsto M_n, y_1 \mapsto N_1, \dots, y_m \mapsto N_m\} \\
 751 \quad \sigma'' &= \sigma_1 \cup \{x_1 \mapsto M_1\{\bullet/\gamma(c)\}, \\
 752 \quad &\dots, x_n \mapsto M_n\{\bullet/\gamma(c)\}, y_1 \mapsto N_1\{\bullet/\gamma(c)\}, \dots, y_m \mapsto N_m\{\bullet/\gamma(c)\}\} \\
 753 \quad &\stackrel{\text{I.H.}}{=} \llbracket u[\overline{\Gamma}] \mid \sigma'' \mid \gamma \rrbracket_w = \llbracket u[\mid c\langle x_1, \dots, x_n, x \rangle \overline{\Gamma} \mid] \mid \sigma' \mid \gamma \rrbracket_w \\
 754 \quad \text{where } \sigma''' &= \sigma'' \cup \{x \mapsto \llbracket t \mid \sigma'' \mid \gamma \rrbracket_w\} = \sigma'' \cup \{x \mapsto \llbracket t \mid \sigma' \mid \gamma \rrbracket_w\{\bullet/\gamma(c)\}\} \\
 755 \quad \text{since } \{y_1, \dots, y_m\} &= (t)_{fv}
 \end{aligned}$$

756 SubSubCase:  $\vec{x} = x_1, \dots, x_n$

$$\begin{aligned}
 757 \quad &\llbracket u[\mid c\langle x_1, \dots, x_n \rangle \overline{\Gamma} \mid] \{t/x\} \mid \sigma \mid \gamma \rrbracket_w = \llbracket u[\mid c\langle x_1, \dots, x_n \rangle \overline{\Gamma} \mid] \{t/x\} \mid \sigma \mid \gamma \rrbracket_w \\
 758 \quad &\llbracket u[\overline{\Gamma}] \{t/x\} \mid \sigma'' \mid \gamma \rrbracket_w \stackrel{\text{I.H.}}{=} \llbracket u[\overline{\Gamma}] \mid \sigma''' \mid \gamma \rrbracket_w = \llbracket u[\mid c\langle x_1, \dots, x_n \rangle \overline{\Gamma} \mid] \mid \sigma' \mid \gamma \rrbracket_w \\
 759 \quad \sigma &= \sigma_1 \cup \{x_1 \mapsto M_1, \dots, x_n \mapsto M_n\} \\
 760 \quad \sigma'' &= \sigma_1 \cup \{x_1 \mapsto M_1\{\bullet/\gamma(c)\}, \dots, x_n \mapsto M_n\{\bullet/\gamma(c)\}\} \\
 761 \quad \sigma''' &= \sigma'' \cup \{x \mapsto \llbracket t \mid \sigma'' \mid \gamma \rrbracket_w\} = \sigma'' \cup \{x \mapsto \llbracket t \mid \sigma \mid \gamma \rrbracket_w\} \\
 762 \quad \text{since } \{x_1, \dots, x_n\} \cap (t)_{fv} &= \{\}
 \end{aligned}$$

764 Below we repeat Proposition 20.

765 For  $N \in \Lambda$  and  $t \in \Lambda_a^S$  the following properties hold

$$\begin{array}{ccc}
 \begin{array}{c} \Lambda_a^S \xrightarrow{\llbracket - \mid \sigma^w \mid \gamma \rrbracket_w} \Lambda_w \\ \searrow \llbracket - \mid \sigma^\Lambda \mid \gamma \rrbracket \quad \swarrow \llbracket - \mid \rrbracket \\ \Lambda \end{array} & \begin{array}{c} \Lambda_a^S \xrightarrow{\llbracket - \rrbracket^w} \Lambda_w \\ \searrow \llbracket - \rrbracket \quad \swarrow \llbracket - \rrbracket^w \\ \Lambda \end{array} & \begin{array}{c} \Lambda_w \\ \swarrow \llbracket - \rrbracket^w \quad \searrow \llbracket - \rrbracket \\ \Lambda \xrightarrow{=} \Lambda \end{array} \\
 \llbracket \llbracket t \mid \sigma^w \mid \gamma \rrbracket_w \rrbracket = \llbracket t \mid \sigma^\Lambda \mid \gamma \rrbracket & \llbracket \llbracket N \rrbracket \rrbracket^w = \llbracket N \rrbracket^w & \llbracket \llbracket N \rrbracket \rrbracket^w = N
 \end{array}$$

767 where  $\sigma^\Lambda(z) = \llbracket \sigma^w(z) \rrbracket$ .

768 **Proof.** We prove  $\llbracket \llbracket u \mid \sigma^w \mid \gamma \rrbracket_w \rrbracket = \llbracket u \mid \sigma^\Lambda \mid \gamma \rrbracket$  by induction on  $u$ .

769 Base Case: Variable

$$771 \quad \llbracket \llbracket x \mid \sigma^w \mid \gamma \rrbracket_w \rrbracket = \llbracket \sigma^w(x) \rrbracket = \llbracket x \mid \sigma^\Lambda \mid \gamma \rrbracket$$

772 Inductive Case: Application

$$774 \quad \llbracket \llbracket st \mid \sigma^w \mid \gamma \rrbracket_w \rrbracket = \llbracket \llbracket s \mid \sigma^w \mid \gamma \rrbracket_w \rrbracket \llbracket \llbracket t \mid \sigma^w \mid \gamma \rrbracket_w \rrbracket \stackrel{\text{I.H.}}{=} \llbracket s \mid \sigma^\Lambda \mid \gamma \rrbracket \llbracket t \mid \sigma^\Lambda \mid \gamma \rrbracket = \llbracket st \mid \sigma^\Lambda \mid \gamma \rrbracket$$

775 Inductive Case: Abstraction

$$777 \quad \llbracket \llbracket x \langle x \rangle . t \mid \sigma^w \mid \gamma \rrbracket_w \rrbracket = \lambda x. \llbracket \llbracket t \mid \sigma^w \mid \gamma \rrbracket_w \rrbracket \stackrel{\text{I.H.}}{=} \lambda x. \llbracket \llbracket t \mid \sigma^\Lambda \mid \gamma \rrbracket \rrbracket = \llbracket x \langle x \rangle . t \mid \sigma^\Lambda \mid \gamma \rrbracket$$

778 Inductive Case: Phantom-Abstraction

$$780 \quad \llbracket \llbracket c\langle x_1, \dots, x_n \rangle . t \mid \sigma^w \mid \gamma \rrbracket_w \rrbracket = \lambda c. \llbracket \llbracket t \mid \sigma_1^w \mid \gamma \rrbracket_w \rrbracket \stackrel{\text{I.H.}}{=} \lambda c. \llbracket \llbracket x \mid \sigma_1^\Lambda \mid \gamma \rrbracket \rrbracket = \llbracket c\langle x_1, \dots, x_n \rangle . t \mid \sigma^\Lambda \mid \gamma \rrbracket$$

781 where

$$\begin{aligned}
 782 \quad \sigma_1^w &= \sigma[x_1 \mapsto \sigma(x_1)\{c/\gamma(c)\}, \dots, x_n \mapsto \sigma(x_n)\{c/\gamma(c)\}] \\
 783 \quad \sigma_1^\Lambda &= \sigma[x_1 \mapsto \llbracket \sigma(x_1) \rrbracket\{c/\gamma(c)\}, \dots, x_n \mapsto \llbracket \sigma(x_n) \rrbracket\{c/\gamma(c)\}]
 \end{aligned}$$

784 Inductive Case: Weakening

$$786 \quad \llbracket \llbracket u[\leftarrow t] \mid \sigma^w \mid \gamma \rrbracket_w \rrbracket = \llbracket \llbracket u \mid \sigma^w \mid \gamma \rrbracket_w \rrbracket \stackrel{\text{I.H.}}{=} \llbracket u \mid \sigma^\Lambda \mid \gamma \rrbracket = \llbracket u[\leftarrow t] \mid \sigma^\Lambda \mid \gamma \rrbracket$$

787 Inductive Case: Sharing



$$\llbracket \llbracket u[x_1, \dots, x_n \leftarrow t] \mid \sigma^\omega \mid \gamma \rrbracket_\omega \rrbracket = \llbracket \llbracket u \mid \sigma_1^\omega \mid \gamma \rrbracket_\omega \rrbracket \stackrel{\text{I.H.}}{=} \llbracket u \mid \sigma_1^\Lambda \mid \gamma \rrbracket = \llbracket u[x_1, \dots, x_n \leftarrow t] \mid \sigma^\Lambda \mid \gamma \rrbracket$$

where

$$\sigma_1^\omega = \sigma^\omega[x_i \mapsto \llbracket t \mid \sigma^\omega \mid \gamma \rrbracket_\omega]_{1 \leq i \leq n}$$

$$\sigma_1^\Lambda = \sigma^\Lambda[x_i \mapsto \llbracket t \mid \sigma^\omega \mid \gamma \rrbracket_\omega]_{1 \leq i \leq n} \stackrel{\text{I.H.}}{=} \sigma^\Lambda[x_i \mapsto \llbracket t \mid \sigma^\Lambda \mid \gamma \rrbracket]_{1 \leq i \leq n}$$

Inductive Case: Distributor

$$\llbracket \llbracket u[e_1 \langle \vec{w}_1 \rangle, \dots, e_m \langle \vec{w}_m \rangle \mid c \langle \vec{x} \rangle \overline{[\Gamma]}] \mid \sigma^\omega \mid \gamma \rrbracket_\omega \rrbracket$$

SubCase:  $\vec{x} = c$

$$\llbracket \llbracket u[e_1 \langle \vec{w}_1 \rangle, \dots, e_m \langle \vec{w}_m \rangle \mid c \langle c \rangle \overline{[\Gamma]}] \mid \sigma^\omega \mid \gamma \rrbracket_\omega \rrbracket$$

$$= \llbracket \llbracket u[\overline{[\Gamma]}] \mid \sigma \mid \gamma' \rrbracket_\omega \rrbracket \stackrel{\text{I.H.}}{=} \llbracket u[\overline{[\Gamma]}] \mid \sigma^\Lambda \mid \gamma' \rrbracket$$

$$= \llbracket u[e_1 \langle \vec{w}_1 \rangle, \dots, e_m \langle \vec{w}_m \rangle \mid c \langle c \rangle \overline{[\Gamma]}] \mid \sigma^\Lambda \mid \gamma \rrbracket$$

SubCase:  $\vec{x} = x_1, \dots, x_n$

$$\llbracket \llbracket u[e_1 \langle \vec{w}_1 \rangle, \dots, e_m \langle \vec{w}_m \rangle \mid c \langle x_1, \dots, x_n \rangle \overline{[\Gamma]}] \mid \sigma^\omega \mid \gamma \rrbracket_\omega \rrbracket$$

$$\llbracket \llbracket u[\overline{[\Gamma]}] \mid \sigma_1^\omega \mid \gamma' \rrbracket_\omega \rrbracket \stackrel{\text{I.H.}}{=} \llbracket u[\overline{[\Gamma]}] \mid \sigma_1^\Lambda \mid \gamma' \rrbracket$$

$$= \llbracket u[e_1 \langle \vec{w}_1 \rangle, \dots, e_m \langle \vec{w}_m \rangle \mid c \langle x_1, \dots, x_n \rangle \overline{[\Gamma]}] \mid \sigma^\Lambda \mid \gamma \rrbracket$$

where

$$\sigma_1^\omega = \sigma[x_1 \mapsto \sigma(x_1)\{c/\gamma(c)\}, \dots, x_n \mapsto \sigma(x_n)\{c/\gamma(c)\}]$$

$$\sigma_1^\Lambda = \sigma[x_1 \mapsto \llbracket \sigma(x_1) \rrbracket \{c/\gamma(c)\}, \dots, x_n \mapsto \llbracket \sigma(x_n) \rrbracket \{c/\gamma(c)\}]$$

We prove  $\llbracket \llbracket N \rrbracket \rrbracket^\omega = \llbracket N \rrbracket^\omega$  by induction on  $N$ . We prove this statement by first proving it for closed terms.

Base Case: Variable

$$\llbracket \llbracket x \rrbracket' \rrbracket^\omega = \llbracket x \rrbracket^\omega = x = \llbracket x \rrbracket^\omega$$

Inductive Case: Application

$$\llbracket \llbracket M N \rrbracket' \rrbracket^\omega = \llbracket \llbracket M \rrbracket' \rrbracket^\omega \llbracket \llbracket N \rrbracket' \rrbracket^\omega \stackrel{\text{I.H.}}{=} \llbracket M \rrbracket^\omega \llbracket N \rrbracket^\omega = \llbracket M N \rrbracket^\omega$$

Inductive Case: Abstraction

$$\llbracket \llbracket \lambda x. M \rrbracket' \rrbracket^\omega$$

SubCase:  $|M|_x = 0$

$$= \lambda x. \llbracket \llbracket M \rrbracket' \rrbracket^\omega[\leftarrow x] = \lambda x. \llbracket \llbracket M \rrbracket' \rrbracket^\omega[\leftarrow x] \stackrel{\text{I.H.}}{=} \lambda x. \llbracket M \rrbracket^\omega[\leftarrow x] = \llbracket \lambda x. M \rrbracket^\omega$$

SubCase:  $|M|_x = 1$

$$= \lambda x. \llbracket \llbracket M \rrbracket' \rrbracket^\omega \stackrel{\text{I.H.}}{=} \lambda x. \llbracket M \rrbracket^\omega = \llbracket \lambda x. M \rrbracket^\omega$$

SubCase:  $|M|_x = n > 1$

$$= \llbracket \llbracket M_x^n \rrbracket' [x^1, \dots, x^n \leftarrow x] \rrbracket^\omega = \llbracket \llbracket M_x^n \rrbracket' \mid \sigma \mid I \rrbracket_\omega \stackrel{\text{prop ??}}{=} \llbracket \llbracket M_x^n \rrbracket' \rrbracket^\omega \{x/x_i\}_{1 \leq i \leq n}$$

$$\stackrel{\text{I.H.}}{=} \llbracket M_x^n \rrbracket^\omega \{x/x_i\}_{1 \leq i \leq n} = \llbracket M \rrbracket^\omega$$

Now that we have proven it works for closed terms, we can show the statement  $\llbracket \llbracket N \rrbracket \rrbracket^\omega = \llbracket N \rrbracket^\omega$  holds

$$\llbracket \llbracket N \rrbracket \rrbracket^\omega = \llbracket \llbracket N_{x_1}^{n_1} \dots \llbracket N_{x_k}^{n_k} \rrbracket' [x_1^1, \dots, x_1^{n_1} \leftarrow x_1] \dots [x_k^1, \dots, x_k^{n_k} \leftarrow x_k] \rrbracket^\omega$$

$$\stackrel{\text{prop ??}}{=} \llbracket \llbracket N_{x_1}^{n_1} \dots \llbracket N_{x_k}^{n_k} \rrbracket' \rrbracket^\omega \{x_i/x_i^j\}_{1 \leq i \leq k, 1 \leq j \leq n_i} = \llbracket N_{x_1}^{n_1} \dots \llbracket N_{x_k}^{n_k} \rrbracket^\omega \{x_i/x_i^j\}_{1 \leq i \leq k, 1 \leq j \leq n_i} = \llbracket N \rrbracket^\omega \quad \blacktriangleleft$$