

# Multi-class link prediction with PyKEEN and Large Language Models

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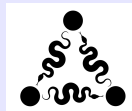
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## Knowledge Graph Completion

**Goal:** Predict missing links to complete and enhance knowledge graphs.

**Methods:** Use embedding models, LLM-based techniques, and hybrid approaches.



## Python Knowledge Embedding and Evaluation Network

**Purpose:** Knowledge graph embedding and link prediction tasks.

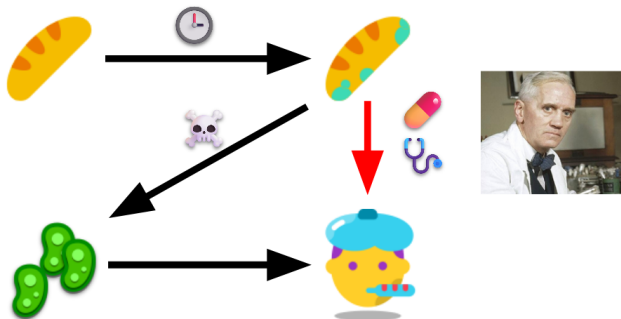


## Neo4j Desktop

**Purpose:** Neo4j is a graph database designed to store and manage connected data.

# Goal & Motivation

How to predict missing links to complete and enhance knowledge graphs with LLMs?



# Problem Statement

**Motivation:** Knowledge graphs are often incomplete, limiting applications like

- Recommendation systems
- Biomedical research
- Drug repurposing

**Objective:** Address incompleteness by

- 1 Employing PyKEEN for link prediction and relationship classification.
- 2 Exploring LLMs to complement traditional methods.

# Methodology Overview

## ① PyKEEN:

- Enables KGE models over entities and relations into vector spaces.
- Facilitates link prediction and multi-class classification.

## ② Neo4j:

- Query and manage the graph data.
- Retrieve triples (h, r, t) for PyKEEN training.

## ③ LLM Integration:

- Dual embedding architecture of RotatE with LLaMA 3.2-3B
- Future exploration on zero-shot, few-shot, and RAG techniques.

## Extract triples using Cypher query

```
MATCH (h)-[r] → (t)
RETURN id(h) AS head, type(r) AS relation, id(t) AS tail
```

## Convert triples to PyKEEN's TriplesFactory format

For example: `[("Gene_A", "causes", "Disease_X")] → [0, 0, 1]`

- These ID mappings are used during model training.

## Train using RotatE model with

- 100 epochs
- Embedding dimension = 128
- Family of KGE models tested.

# Neo4j and LLMs Integration

## Neo4j Integration

- Setup Neo4j Desktop with Hetionet Database.
- Visualize Schema using `CALL db.schema.visualization()`.

## LLMs (Dual Embedding Architecture)

### Integrating RotatE with LLaMA 3.2-3B for Knowledge Graph Embeddings

#### Key Components:

- **RotatE**: Traditional entity and relation embeddings in complex space, trained using PyKEEN.
- **LLaMA 3.2-3B (RLM-A)**: LLM embeddings, initialized with Wikidata entries for entities.

**This semantic-rich embeddings enhances link prediction.**



## Hetionet:

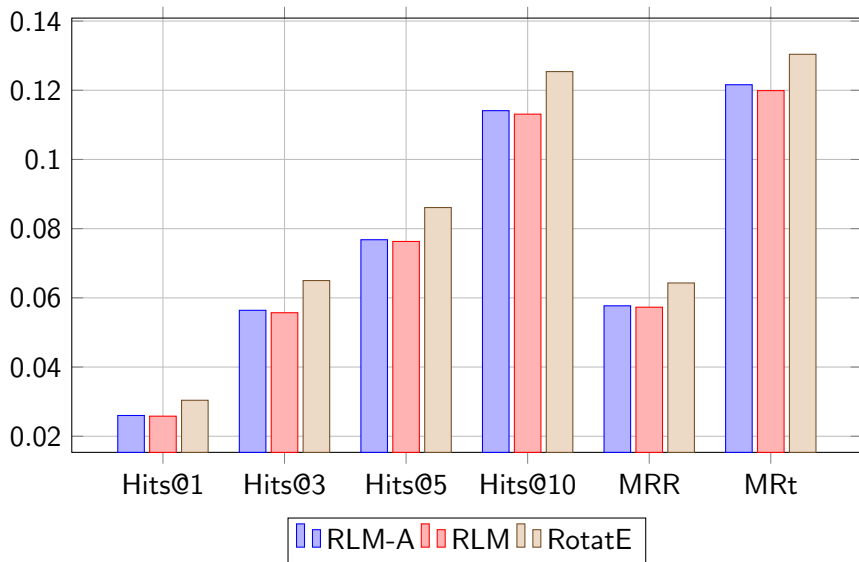
- Biomedical knowledge graph representing relationships between diseases, drugs, genes, and other biological entities.
- High edge-to-node ratio

Statistic	Value
Entities (Nodes )	22,634
Relationships (Edges)	561,721
Unique Relation Types	10
Unique Triples	561,721

## Evaluation Metrics:

- Hits@K - Fraction of correct predictions ranked in the top K.
- Mean Reciprocal Rank (MRR) - Average inverse rank of correct predictions.
- Mean Rank (MR) - Average rank of correct predictions.

# Model Comparison



## Highlights:

- Poor performance across all KGE models tested specifically Translational and Semantic Matching models, except promising result from RotatE.
- Integrating RotatE with LLaMA 3.2-3B did not yield further benefits.

## Future Improvements:

- Refine hyperparameters.
- Incorporate negative sampling strategies for better generalization.

## Challenges:

- Hetionet's biomedical heterogeneity requires models to handle complex relationships.

## Explore other embedding models:

- Rule-based models: e.g., AnyBURL for patterns missed by embeddings.
- BoxE (constraints modeling).
- CNN-based models: ConvE, R-GCN for local feature capture.
- Heterogeneous models: HoIE, AutoSF for complex datasets like Hetionet.

## Key Takeaways:

- 1 PyKEEN demonstrates potential for knowledge graph completion.
- 2 Llama 3.2:3b integration with RotatE didn't show better results.
- 3 Hetionet is a complex biomedical datasets, needs more advanced models/approaches.

## References:

1. [Ali et al., 2021] PyKEEN: A Python Library for Training and Evaluating Knowledge Graph Embeddings.
2. [Himmelstein et al., 2017] Hetionet: Systematic integration of biomedical knowledge.
3. [Neo4j, 2024] Neo4j Graph Database Documentation.