

Info

• Textbook has a free digital version

- PS 30% MIDTERM 20%
- LABS 20% FINAL 30%

• 2 for LAB GROUPS

- LABS ARE PROBABLY 3-4 hrs

How do we make actual trajectory match desired trajectory

- Nonlinear dynamics

Decentralized Control

- Separate controller for each joint
- When behavior is coupled, that will throw in complexity

Centralized Control

- Array of data rather than individual } DECOUPLING
- MAY STILL HAVE NONLINEAR COMPENSATION } MATRIX

- LYAPUNOV TECHNIQUES