

HW3

Goal

1. Draw a sphere and apply Phong shading or Gouraud shading on it.
2. Use keyboard to control the lighting parameters.

*Use GLSL to do this homework, otherwise you'll get zero points.

Spec

Camera:

Position: $(0, 0, 5.6)$

Center: $(0, 0, 0)$

Up vector: $(0, 1, 0)$

Sphere:

Slice: 20

Stack: 10

Radius: 1

Spec

Point light source : (draw a small sphere to represent the light source)

Position : (1.1, 1.0 , 1.3)

The color of the sphere : (0.4, 0.5, 0.0)

The radius of the sphere : 0.05

Keyboard control :

“1” : The parameter “Ks” decreases from 1 to 0 ($K_s -= 0.1$)

“2” : The parameter “Ks” increases from 0 to 1 ($K_s += 0.1$)

“3” : The parameter “Kd” decreases from 1 to 0 ($K_d -= 0.1$)

“4” : The parameter “Kd” increases from 0 to 1 ($K_d += 0.1$)

Spec

Phong Shading :

$K_s = 0$ (initial value)

$K_d = 0$ (initial value)

$K_a = 0.5$

$\alpha = 3.6$

$I_a = (0.2, 0.2, 0.2)$

$I_d = (0.5, 0.5, 0.5)$

$I_s = (0.8, 0.8, 0.8)$

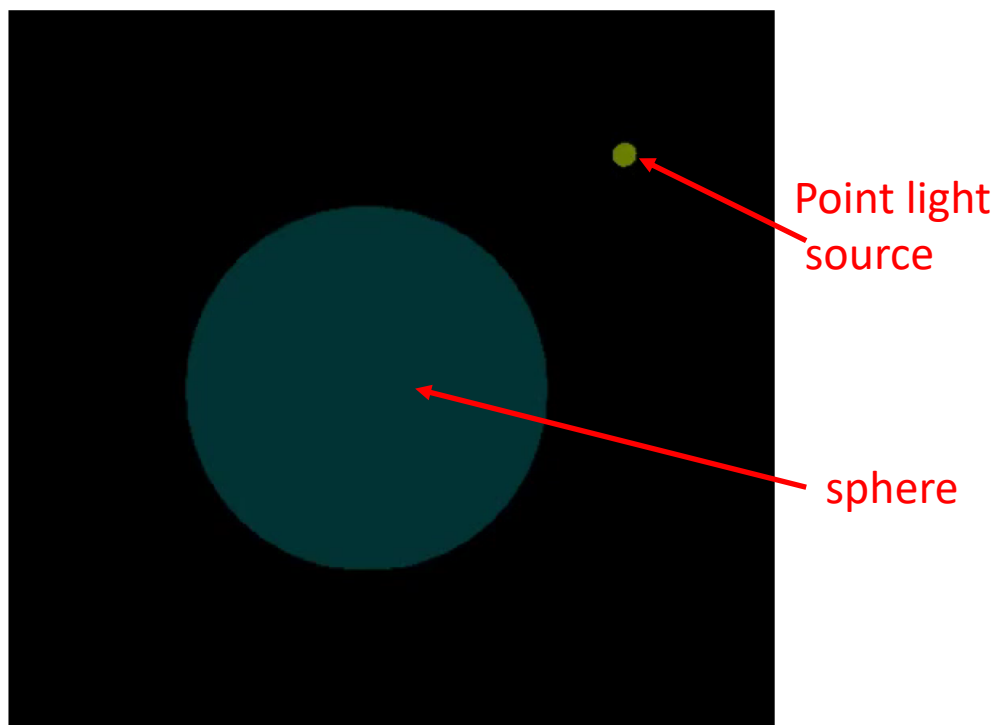
Score

- 1. Successfully draw a sphere and apply Gouraud shading on it. (70%)
- 2. Switch to Phong shading (Use keyboard “B”). (10%)
- 3. Use keyboard to control the Kd and Ks parameters. (10%)
- 4. Demo (10%)
(We will ask you some questions about this homework)
- 5. **Bonus : (10%)**
 - (1).Change to tone mapping (5%) (Use keyboard “B”)
(Set the threshold to map the color into 4 Intensity levels.)
 - (2).Add border enhancement (5%)
(Use keyboard “E” to enable and disable the border)

Example video

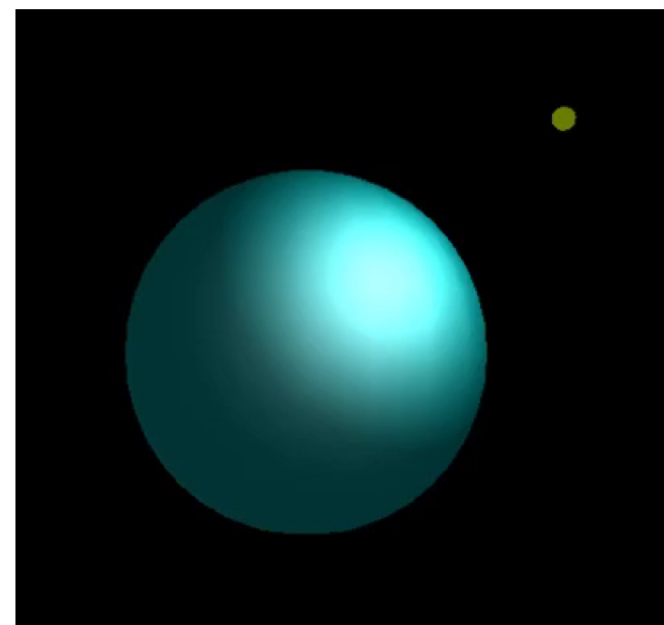
➤ Phong shading

➤ Control K_d and K_s



➤ Phong shading 、 Gouraud shading 、 Tone mapping

➤ Border enhancement



Others

1. You can do this homework based on your HW2.
2. Zip your Visual Studio project into “ StudentID_HW3.zip” , and upload it to New e3.
3. The deadline is at **11:55 pm on December 23**.
4. If you submit your homework late, the score will be discounted.

submit between (12/24 ~ 12/30) : Your final score * 0.9

submit between (12/31 ~ 1/6) : Your final score * 0.8

submit between (1/6~1/10) : Your final score * 0.7