



## Robotic Class

Time Limit: 2000/1000 MS (Java/Others) Memory Limit: 262144/262144 K (Java/Others)  
Total Submission(s): 0 Accepted Submission(s): 0

### Problem Description

Baby volcano is now at a robotic class. In this class, babies are required to program a special control system of a robot. This control system has a real-valued control variable  $x$ , which captures the behavior of this robot. In addition, this control system could be abstracted as an acyclic directed graph, with  $n$  node, the nodes are indexed from 1 to  $n$ . In this graph, the node  $n$  has no output edge, termed as the output node. Moreover, for each vertex  $t$ ,  $1 \leq t < n$ , there is a number  $k_t$ , a set of *integer-valued* limits  $a_{t,0} < a_{t,1} < a_{t,2} < \dots < a_{t,k_t-1} < a_{t,k_t} := +\infty$ , and a set of *integer-valued* coefficients, bias and destinations  $c_{t,0}, b_{t,0}, d_{t,0}, c_{t,1}, b_{t,1}, d_{t,1}, c_{t,2}, b_{t,2}, d_{t,2}, \dots, c_{t,k_t}, b_{t,k_t}, d_{t,k_t}$ . For every  $t$  and  $i$ ,  $0 \leq i \leq k_t$ ,  $-1 \leq c_{t,i} \leq 1$ .

To use this system to control the robot, the user follows the steps below:

1. Choose  $x_0$  and initialize  $x := x_0$ , then choose some node  $s_0$  and set the current node  $t := s_0$
2. If  $t$  is the output node ( $t = n$ ), then output  $x_{out} := x$ , else go to step 3.
3. The user finds the smallest  $i$  such that  $a_{t,i} \geq x$  (Note that  $i$  always exists), then transform  $x := c_{t,i} \times x + b_{t,i}$ , and set  $t := d_{t,i}$ , and go back to step 2.

Note that for every fixed  $s_0$ , the output value  $x_{out}$  is a function with respect to the initial value  $x_0 \in \mathbb{R}$ , we call this function  $C_{s_0}(x_0)$ .

To precisely control the robot, it is required that for every initial node  $s_0$ ,  $C_{s_0}(x_0)$  is continuous with respect to  $x_0$ .

A function  $f(x)$ ,  $x \in \mathbb{R}$  is continuous with respect to  $x$  iff

$$\forall x \in \mathbb{R}, \forall \epsilon > 0, \exists \delta > 0, \forall x' \in \mathbb{R}, (|x - x'| \leq \delta \implies |f(x) - f(x')| \leq \epsilon)$$

You need to verify this requirement is satisfied or not. In other words, if for every initial node  $s_0$ ,  $C_{s_0}(x_0)$  is continuous with respect to  $x_0$ , you should output "YES". If there exists some node  $s^*$  such that  $C_{s^*}(x_0)$  is not continuous, you should output "NO".

### Input

In the first line there is one integer  $T$ , denotes the number of test cases.

The rest of input has  $T$  part, each part corresponds to a test case.

For each part, in the first line there is a number  $n$ , denotes the number of nodes.

In the next  $n - 1$  lines, the  $i$ -th line starts with  $k_i$ , follows with  $4k_i + 3$  integers, they are  $c_{i,0}, b_{i,0}, d_{i,0}, a_{i,0}, c_{i,1}, b_{i,1}, d_{i,1}, a_{i,1}, \dots, a_{i,k_i-1}, c_{i,k_i}, b_{i,k_i}, d_{i,k_i}$ .

It guarantees that  $1 \leq T \leq 100$ ,

and in a single test cases,

$1 \leq n \leq 500$ ,

$1 \leq \sum k_i \leq 2000$ ,

$-1 \leq c_{i,j} \leq 1$ ,

$-10^6 \leq b_{i,j} \leq 10^6$ ,

$-10^9 \leq a_{i,j} \leq 10^9$ ,

$i + 1 \leq d_{i,j} \leq n$ .

And it guarantees that  $a_{i,j-1} < a_{i,j}$  for every  $1 \leq j < k_i$ .

### Output

For each test case, you should firstly output "Case #t: " (without quotes), where  $t$  is the index of this test case, then if for every initial node  $s_0$ ,  $C_{s_0}(x_0)$  is continuous with respect to  $x_0$ , you should output "YES". If there exists some node  $s^*$  such that  $C_{s^*}(x_0)$  is not continuous, you should output "NO".

### Sample Input

```
3
4
1 1 1 2 -4 -1 -7 3
0 -1 -2 4
0 1 4 4
4
1 1 1 2 -4 -1 -7 3
0 -1 -3 4
0 1 4 4
1
```

## Sample Output

Case #1: YES  
Case #2: NO  
Case #3: YES

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