model_137_dynamic_scaling_factor

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```
[61]: # Author: William Chuang
      # Last modified: Oct 18, 2023
      # This notebook is built on the code written by Dr. Phillip Lippe.
      ## Standard libraries
      import os
      import numpy as np
      import random
      import math
      import json
      from functools import partial
      import statistics as stat
      ## PyTorch
      import torch
      import torch.nn as nn
      import torch.nn.functional as F
      import torch.utils.data as data
      import torch.optim as optim
      # PyTorch Lightning
      try:
          import pytorch_lightning as pl
      except ModuleNotFoundError: # Google Colab does not have PyTorch Lightning
       →installed by default. Hence, we do it here if necessary
          !pip install --quiet pytorch-lightning>=1.4
          import pytorch_lightning as pl
      from pytorch_lightning.callbacks import LearningRateMonitor, ModelCheckpoint
      # Path to the folder where the datasets are/should be downloaded (e.g. CIFAR10)
      DATASET PATH = "./data"
      # Path to the folder where the pretrained models are saved
      CHECKPOINT_PATH = "./saved_models/tutorial6"
      # Setting the seed
      pl.seed_everything(42)
```

```
# Ensure that all operations are deterministic on GPU (if used) for
\hookrightarrow reproducibility
torch.backends.cudnn.deterministic = True
torch.backends.cudnn.benchmark = False
device = torch.device("cuda:0") if torch.cuda.is available() else torch.

device("cpu")
print("Device:", device)
def scaled_dot_product(q, k, v, mask=None):
    d_k = q.size()[-1]
    PATH = "./tmp.pth"
    #torch.save(reverse_model.state_dict(), PATH)
    #w=torch.load(PATH)
    \#d=sigma=torch.std((w["transformer.layers.0.self_attn.qkv_proj.weight"])).
 ⇒item()
    \#print(d_k)
    attn_logits = torch.matmul(q, k.transpose(-2, -1))
    attn_logits = attn_logits*6.55 #/ (math.sqrt(d_k)) #*0.15 #math.sqrt(0.
 →005*d k) #0.005 #10 #3 #1.414 #(0.00001*d k) #(d k)**(1/100) #math.
 \hookrightarrow sqrt(d_k*2)
    #print(attn_logits)
    if mask is not None:
        attn_logits = attn_logits.masked_fill(mask == 0, -9e15)
    attention = F.softmax(attn_logits, dim=-1)
    values = torch.matmul(attention, v)
    return values, attention
class MultiheadAttention(nn.Module):
    def __init__(self, input_dim, embed_dim, num_heads):
        super().__init__()
        assert embed dim % num heads == 0, "Embedding dimension must be 011
 ⇒modulo number of heads."
        self.embed_dim = embed_dim
        self.num_heads = num_heads
        self.head_dim = embed_dim // num_heads
        # Stack all weight matrices 1...h together for efficiency
        # Note that in many implementations you see "bias=False" which is \Box
 \hookrightarrow optional
        self.qkv_proj = nn.Linear(input_dim, 3*embed_dim)
        self.o_proj = nn.Linear(embed_dim, embed dim)
```

```
self._reset_parameters()
   def _reset_parameters(self):
        # Original Transformer initialization, see PyTorch documentation
       nn.init.xavier_uniform_(self.qkv_proj.weight)
        self.qkv_proj.bias.data.fill_(0)
       nn.init.xavier_uniform_(self.o_proj.weight)
        self.o_proj.bias.data.fill_(0)
   def forward(self, x, mask=None, return_attention=False):
       batch_size, seq_length, _ = x.size()
        if mask is not None:
            mask = expand_mask(mask)
        qkv = self.qkv_proj(x)
        # Separate Q, K, V from linear output
        qkv = qkv.reshape(batch_size, seq_length, self.num_heads, 3*self.
 →head_dim)
        qkv = qkv.permute(0, 2, 1, 3) # [Batch, Head, SeqLen, Dims]
        q, k, v = qkv.chunk(3, dim=-1)
        # Determine value outputs
       values, attention = scaled_dot_product(q, k, v, mask=mask)
       values = values.permute(0, 2, 1, 3) # [Batch, SeqLen, Head, Dims]
       values = values.reshape(batch_size, seq_length, self.embed_dim)
        o = self.o_proj(values)
        if return_attention:
            return o, attention
        else:
           return o
class EncoderBlock(nn.Module):
   def __init__(self, input_dim, num_heads, dim_feedforward, dropout=0.0):
        Inputs:
            input_dim - Dimensionality of the input
            num_heads - Number of heads to use in the attention block
            dim_feedforward - Dimensionality of the hidden layer in the MLP
            dropout - Dropout probability to use in the dropout layers
        super().__init__()
        # Attention layer
        self.self_attn = MultiheadAttention(input_dim, input_dim, num_heads)
```

```
# Two-layer MLP
        self.linear_net = nn.Sequential(
            nn.Linear(input_dim, dim_feedforward),
            nn.Dropout(dropout),
            nn.ReLU(inplace=True),
            nn.Linear(dim_feedforward, input_dim)
        )
        # Layers to apply in between the main layers
        self.norm1 = nn.LayerNorm(input dim)
        self.norm2 = nn.LayerNorm(input_dim)
        self.dropout = nn.Dropout(dropout)
    def forward(self, x, mask=None):
        # Attention part
        attn_out = self.self_attn(x, mask=mask)
        x = x + self.dropout(attn_out)
        x = self.norm1(x)
        # MLP part
        linear_out = self.linear_net(x)
        x = x + self.dropout(linear_out)
        x = self.norm2(x)
        return x
class TransformerEncoder(nn.Module):
    def __init__(self, num_layers, **block_args):
        super().__init__()
        self.layers = nn.ModuleList([EncoderBlock(**block_args) for _ in_
 →range(num_layers)])
    def forward(self, x, mask=None):
        for l in self.layers:
            x = l(x, mask=mask)
        return x
    def get_attention_maps(self, x, mask=None):
        attention_maps = []
        for l in self.layers:
            _, attn_map = l.self_attn(x, mask=mask, return_attention=True)
            attention_maps.append(attn_map)
            x = 1(x)
        return attention_maps
class PositionalEncoding(nn.Module):
```

```
def __init__(self, d_model, max_len=5000):
        Inputs
            d_model - Hidden dimensionality of the input.
            max_len - Maximum length of a sequence to expect.
        super().__init__()
        # Create matrix of [SeqLen, HiddenDim] representing the positional,
 →encoding for max_len inputs
        pe = torch.zeros(max_len, d_model)
        position = torch.arange(0, max_len, dtype=torch.float).unsqueeze(1)
        div_term = torch.exp(torch.arange(0, d_model, 2).float() * (-math.
 ⇔log(10000.0) / d_model))
        pe[:, 0::2] = torch.sin(position * div_term)
        pe[:, 1::2] = torch.cos(position * div_term)
        pe = pe.unsqueeze(0)
        \# register_buffer => Tensor which is not a parameter, but should be \sqcup
 ⇔part of the modules state.
        # Used for tensors that need to be on the same device as the module.
        # persistent=False tells PyTorch to not add the buffer to the stateu
 \rightarrowdict (e.g. when we save the model)
        self.register_buffer('pe', pe, persistent=False)
    def forward(self, x):
        x = x + self.pe[:, :x.size(1)]
        return x
class TransformerPredictor(pl.LightningModule):
    def __init__(self, input_dim, model_dim, num_classes, num_heads,__
 num_layers, lr, warmup, max_iters, dropout=0.0, input_dropout=0.0):
        Inputs:
            input_dim - Hidden dimensionality of the input
            model_dim - Hidden dimensionality to use inside the Transformer
            num_classes - Number of classes to predict per sequence element
            num\_heads - Number of heads to use in the Multi-Head Attention_{\sqcup}
 \hookrightarrow blocks
            num_layers - Number of encoder blocks to use.
            lr - Learning rate in the optimizer
            warmup - Number of warmup steps. Usually between 50 and 500
            max\_iters - Number of maximum iterations the model is trained for. \sqcup
 {\scriptscriptstyle \hookrightarrow} \mathit{This} is needed for the CosineWarmup scheduler
            dropout - Dropout to apply inside the model
            input_dropout - Dropout to apply on the input features
```

```
super().__init__()
       self.save_hyperparameters()
       self._create_model()
  def _create_model(self):
      # Input dim -> Model dim
       self.input_net = nn.Sequential(
           nn.Dropout(self.hparams.input dropout),
           nn.Linear(self.hparams.input_dim, self.hparams.model_dim)
       # Positional encoding for sequences
       self.positional_encoding = PositionalEncoding(d_model=self.hparams.
→model_dim)
       # Transformer
       self.transformer = TransformerEncoder(num_layers=self.hparams.

¬num_layers,
                                              input_dim=self.hparams.model_dim,
                                              dim_feedforward=2*self.hparams.
→model_dim,
                                              num_heads=self.hparams.num_heads,
                                              dropout=self.hparams.dropout)
       # Output classifier per sequence lement
       self.output_net = nn.Sequential(
           nn.Linear(self.hparams.model dim, self.hparams.model dim),
           nn.LayerNorm(self.hparams.model_dim),
           nn.ReLU(inplace=True),
           nn.Dropout(self.hparams.dropout),
           nn.Linear(self.hparams.model_dim, self.hparams.num_classes)
       )
  def forward(self, x, mask=None, add_positional_encoding=True):
       Inputs:
           x - Input features of shape [Batch, SeqLen, input_dim]
           mask - Mask to apply on the attention outputs (optional)
           add_positional_encoding - If True, we add the positional encoding_
\hookrightarrow to the input.
                                     Might not be desired for some tasks.
       11 11 11
      x = self.input_net(x)
      if add_positional_encoding:
           x = self.positional_encoding(x)
       x = self.transformer(x, mask=mask)
       x = self.output_net(x)
       return x
```

```
@torch.no_grad()
   def get_attention_maps(self, x, mask=None, add_positional_encoding=True):
        Function for extracting the attention matrices of the whole Transformer
 ⇔for a single batch.
        Input arguments same as the forward pass.
       x = self.input_net(x)
        if add_positional_encoding:
            x = self.positional_encoding(x)
        attention_maps = self.transformer.get_attention_maps(x, mask=mask)
        return attention_maps
   def configure_optimizers(self):
        optimizer = optim.Adam(self.parameters(), lr=self.hparams.lr)
        # Apply lr scheduler per step
       lr_scheduler = CosineWarmupScheduler(optimizer,
                                             warmup=self.hparams.warmup,
                                             max_iters=self.hparams.max_iters)
        return [optimizer], [{'scheduler': lr_scheduler, 'interval': 'step'}]
   def training_step(self, batch, batch_idx):
       raise NotImplementedError
   def validation_step(self, batch, batch_idx):
       raise NotImplementedError
   def test_step(self, batch, batch_idx):
        raise NotImplementedError
class ReverseDataset(data.Dataset):
   def __init__(self, num_categories, seq_len, size):
        super(). init ()
        self.num_categories = num_categories
       self.seq len = seq len
        self.size = size
       self.data = torch.randint(self.num_categories, size=(self.size, self.
 ⇒seq_len))
        # self.data = torch.abs(torch.normal(0, 1, size=(self.size, self.
 \rightarrowseq_len)).long())
        # torch.randint(low=0, high, size, \*, generator=None, out=None,
 ⇔dtype=None,
        \# layout=torch.strided, device=None, requires_grad=False) \rightarrow Tensor
       print(self.num_categories)
```

```
print(self.seq_len)
       print(self.size)
       print(self.data)
   def __len__(self):
       return self.size
   def __getitem__(self, idx):
        inp data = self.data[idx]
        labels = torch.flip(inp_data, dims=(0,))
       return inp_data, labels
#''' Examples of torch.randint
#>>> torch.randint(3, 5, (3,))
#tensor([4, 3, 4])
#>>> torch.randint(10, (2, 2))
#tensor([[0, 2],
        [5, 5]])
#>>> torch.randint(3, 10, (2, 2))
#tensor([[4, 5],
         [6, 7]])'''
#'''>>> torch.normal(mean=0.5, std=torch.arange(1., 6.))
#tensor([-1.2793, -1.0732, -2.0687, 5.1177, -1.2303])'''
class ReversePredictor(TransformerPredictor):
   def _calculate_loss(self, batch, mode="train"):
        # Fetch data and transform categories to one-hot vectors
       inp_data, labels = batch
        inp_data = F.one_hot(inp_data, num_classes=self.hparams.num_classes).

¬float()
        # Perform prediction and calculate loss and accuracy
       preds = self.forward(inp_data, add_positional_encoding=True)
       loss = F.cross_entropy(preds.view(-1,preds.size(-1)), labels.view(-1))
        acc = (preds.argmax(dim=-1) == labels).float().mean()
        # Logging
        self.log(f"{mode}_loss", loss)
        self.log(f"{mode}_acc", acc)
       return loss, acc
   def training_step(self, batch, batch_idx):
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```
loss, _ = self._calculate_loss(batch, mode="train")
        return loss
   def validation_step(self, batch, batch_idx):
        _ = self._calculate_loss(batch, mode="val")
   def test_step(self, batch, batch_idx):
        _ = self._calculate_loss(batch, mode="test")
def train_reverse(**kwargs):
    # Create a PyTorch Lightning trainer with the generation callback
   root_dir = os.path.join(CHECKPOINT_PATH, "ReverseTask")
   os.makedirs(root_dir, exist_ok=True)
   trainer = pl.Trainer(default_root_dir=root_dir,
                         callbacks=[ModelCheckpoint(save_weights_only=True,_
 →mode="max", monitor="val_acc")],
                         accelerator="gpu" if str(device).startswith("cuda"),
 ⇔else "cpu",
                         devices=1,
                         max_epochs=10,
                         gradient_clip_val=5)
   trainer.logger._default_hp_metric = None # Optional logging argument thatu
 →we don't need
   trainer.callbacks
    # Check whether pretrained model exists. If yes, load it and skip training
   pretrained_filename = os.path.join(CHECKPOINT_PATH, "ReverseTask.ckpt")
    if os.path.isfile(pretrained filename):
        print("Found pretrained model, loading...")
       model = ReversePredictor.load_from_checkpoint(pretrained_filename)
    else:
       print("Found pretrained model does not exist, generating...")
       model = ReversePredictor(max_iters=trainer.
 max_epochs*len(train_loader), **kwargs)
        trainer.fit(model, train_loader, val_loader)
    # Test best model on validation and test set
   val_result = trainer.test(model, val_loader, verbose=False)
   test_result = trainer.test(model, test_loader, verbose=False)
   result = {"test_acc": test_result[0]["test_acc"], "val_acc":

 ⇔val_result[0]["test_acc"]}
   model = model.to(device)
   return model, result
class CosineWarmupScheduler(optim.lr_scheduler._LRScheduler):
   def __init__(self, optimizer, warmup, max_iters):
       self.warmup = warmup
```

```
self.max_num_iters = max_iters
         super().__init__(optimizer)
    def get_lr(self):
        lr_factor = self.get_lr_factor(epoch=self.last_epoch)
        return [base_lr * lr_factor for base_lr in self.base_lrs]
    def get_lr_factor(self, epoch):
        lr_factor = 0.5 * (1 + np.cos(np.pi * epoch / self.max_num_iters))
        if epoch <= self.warmup:</pre>
             lr_factor *= epoch * 1.0 / self.warmup
        return lr_factor
dataset = partial(ReverseDataset, 1000, 20)
train_loader = data.DataLoader(dataset(35000), batch_size=128, shuffle=True,__
  →drop_last=True, pin_memory=True)
val loader = data.DataLoader(dataset(1000), batch size=128)
test_loader = data.DataLoader(dataset(100000), batch_size=128)
inp_data, labels = train_loader.dataset[0]
print("Input data:", inp_data)
print("Labels:
                  ", labels)
INFO:lightning_fabric.utilities.seed:Seed set to 42
Device: cuda:0
1000
20
35000
tensor([[542, 67, 876, ..., 295, 567, 706],
        [749, 876, 73, ..., 376, 632, 10],
        [186, 822, 577, ..., 384, 978, 908],
        [414, 948,
                     2, ..., 4, 569, 745],
        [113, 734, 236, ..., 938, 85, 946],
        [963, 46, 856, ..., 424, 79, 816]])
1000
20
1000
tensor([[993, 420, 769, ..., 142, 367, 628],
        [500, 476, 945, ..., 305, 532, 851],
        [751, 480, 780, ..., 139, 14, 50],
        [540, 755, 275, ..., 15, 126, 561],
        [ 17, 758, 578, ..., 250, 116, 781],
        [435, 680, 837, ..., 262, 468, 846]])
1000
20
100000
```

```
tensor([[502, 570, 391, ..., 845, 303, 837],
            [806, 564, 631, ..., 351, 3, 528],
            [318, 935, 488, ..., 532, 800, 28],
            [896, 404, 739, ..., 494, 376, 906],
            [793, 556, 316, ..., 982, 931, 378],
            [902, 152, 152, ..., 218, 484, 66]])
     Input data: tensor([542, 67, 876, 414, 26, 335, 620, 924, 950, 113, 378, 14,
     210, 954,
            231, 572, 315, 295, 567, 706])
                tensor([706, 567, 295, 315, 572, 231, 954, 210, 14, 378, 113, 950,
     Labels:
     924, 620,
            335, 26, 414, 876, 67, 542])
[62]: reverse model, reverse_result = train_reverse(input_dim=train_loader.dataset.
      →num_categories,
                                                 model_dim=20,
                                                 num heads=1,
                                                 num_classes=train_loader.dataset.

¬num_categories,
                                                 num_layers=1,
                                                 dropout=0.0,
                                                 1r=5e-4,
                                                 warmup=50)
     INFO:pytorch_lightning.utilities.rank_zero:GPU available: True (cuda), used:
     True
     INFO:pytorch_lightning.utilities.rank_zero:TPU available: False, using: 0 TPU
     INFO:pytorch_lightning.utilities.rank_zero:IPU available: False, using: 0 IPUs
     INFO:pytorch_lightning.utilities.rank_zero:HPU available: False, using: 0 HPUs
     INFO:pytorch_lightning.accelerators.cuda:LOCAL_RANK: 0 - CUDA_VISIBLE_DEVICES:
     INFO:pytorch_lightning.callbacks.model_summary:
                                      | Params
      | Name
                   | Type
     _____
     0 | input_net
                          | Sequential
                                              | 20.0 K
     1 | positional_encoding | PositionalEncoding | 0
     2 | transformer | TransformerEncoder | 3.4 K
     3 | output_net
                      | Sequential | 21.5 K
     44.9 K
              Trainable params
              Non-trainable params
     44.9 K
              Total params
              Total estimated model params size (MB)
     0.180
     Found pretrained model does not exist, generating...
                               | 0/? [00:00<?, ?it/s]
     Sanity Checking: |
```

```
packages/pytorch_lightning/trainer/connectors/data_connector.py:441: The
     'val dataloader' does not have many workers which may be a bottleneck. Consider
     increasing the value of the `num_workers` argument` to `num_workers=1` in the
     `DataLoader` to improve performance.
     /usr/local/lib/python3.10/dist-
     packages/pytorch lightning/trainer/connectors/data connector.py:441: The
     'train_dataloader' does not have many workers which may be a bottleneck.
     Consider increasing the value of the `num workers` argument` to `num workers=1`
     in the `DataLoader` to improve performance.
                          | 0/? [00:00<?, ?it/s]
     Training: |
                            | 0/? [00:00<?, ?it/s]
     Validation: |
                           | 0/? [00:00<?, ?it/s]
     Validation: |
                           | 0/? [00:00<?, ?it/s]
     Validation: |
                           | 0/? [00:00<?, ?it/s]
     Validation: |
     Validation: |
                           | 0/? [00:00<?, ?it/s]
     Validation: |
                            | 0/? [00:00<?, ?it/s]
     Validation: |
                            | 0/? [00:00<?, ?it/s]
     Validation: |
                           | 0/? [00:00<?, ?it/s]
     Validation: |
                            | 0/? [00:00<?, ?it/s]
                            | 0/? [00:00<?, ?it/s]
     Validation: |
     INFO:pytorch_lightning.utilities.rank_zero:`Trainer.fit` stopped:
     `max epochs=10` reached.
     INFO:pytorch_lightning.accelerators.cuda:LOCAL_RANK: 0 - CUDA_VISIBLE_DEVICES:
     [0]
     /usr/local/lib/python3.10/dist-
     packages/pytorch_lightning/trainer/connectors/data_connector.py:441: The
     'test_dataloader' does not have many workers which may be a bottleneck. Consider
     increasing the value of the `num workers` argument` to `num workers=1` in the
     `DataLoader` to improve performance.
                         | 0/? [00:00<?, ?it/s]
     Testing: |
     INFO:pytorch_lightning.accelerators.cuda:LOCAL_RANK: 0 - CUDA_VISIBLE_DEVICES:
     [0]
                         | 0/? [00:00<?, ?it/s]
     Testing: |
[30]: # Ctitle the scaling factor, beta, is 1, using the algo to find dynamic scaling
       \hookrightarrow factor
      # model_134_beta=1
      print(f"Val accuracy: {(100.0 * reverse_result['val_acc']):4.2f}%")
      print(f"Test accuracy: {(100.0 * reverse_result['test_acc']):4.2f}%")
```

/usr/local/lib/python3.10/dist-

```
Val accuracy: 99.93%
     Test accuracy: 99.90%
[33]: # Otitle the scaling factor, beta, is 5, using the algo to find dynamic scaling
      \hookrightarrow factor
      # model_134_beta=5
      print(f"Val accuracy: {(100.0 * reverse_result['val_acc']):4.2f}%")
      print(f"Test accuracy: {(100.0 * reverse_result['test_acc']):4.2f}%")
     Val accuracy: 100.00%
     Test accuracy: 100.00%
[42]: # Otitle the scaling factor, beta, is 1/(d_k) 0.5, using the algo to find
      ⇔dynamic scaling factor
      \# model_134_beta=1/(d_k)^0.5
      print(f"Val accuracy: {(100.0 * reverse_result['val_acc']):4.2f}%")
      print(f"Test accuracy: {(100.0 * reverse_result['test_acc']):4.2f}%")
     Val accuracy: 10.59%
     Test accuracy: 10.68%
[39]: | # Otitle the scaling factor, beta, is 1, using the algo to find dynamic scaling
       \hookrightarrow factor
      # model 134 beta=1
      print(f"Val accuracy: {(100.0 * reverse_result['val_acc']):4.2f}%")
      print(f"Test accuracy: {(100.0 * reverse_result['test_acc']):4.2f}%")
     Val accuracy: 99.75%
     Test accuracy: 99.79%
[48]: # Ctitle the scaling factor, beta, is 1, using the algo to find dynamic scaling
       \hookrightarrow factor
      # model_134_beta=1
      print(f"Val accuracy: {(100.0 * reverse_result['val_acc']):4.2f}%")
      print(f"Test accuracy: {(100.0 * reverse_result['test_acc']):4.2f}%")
     Val accuracy: 99.47%
     Test accuracy: 99.53%
[51]: # @title the scaling factor, beta, is 1/(d_k) 0.5, using the algo to find
       ⇔dynamic scaling factor
      \# model_134_beta=1/(d_k)^0.5
      print(f"Val accuracy: {(100.0 * reverse_result['val_acc']):4.2f}%")
      print(f"Test accuracy: {(100.0 * reverse_result['test_acc']):4.2f}%")
     Val accuracy: 5.34%
     Test accuracy: 5.52%
[57]: # Otitle the scaling factor, beta, is 6, using the algo to find dynamic scaling
       \hookrightarrow factor
```