McMullen's_example_by_McMullen_algo

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```
[386]: __author__="William Huanshan Chuang"
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       #define elementary functions
       import math
       import statistics
       def Cartesian complex mul(numb1,numb2):
           #numb1 a+bi, [a,b], numb2 c+di, [c,d]
           x=numb1[0]*numb2[0]-numb1[1]*numb2[1]
           y=numb1[0]*numb2[1]+numb1[1]*numb2[0]
           return [x,y]
       def Cartesian_complex_scalar_mul(alpha,numb1):
           \#numb1 \ a+bi, [a,b], numb2 \ c+di, [c,d]
           x=numb1[0]*alpha
           y=numb1[1]*alpha
           return [x,y]
       def Cartesian_complex_add(numb1,numb2):
           \#numb1 \ a+bi, [a,b], numb2 \ c+di, [c,d]
           x=numb1[0]+numb2[0]
           y=numb1[1]+numb2[1]
           return [x,y]
       def Cartesian_complex_divide(numb1,numb2):
           #numb1\ u+vi, [u,v], numb2\ x+yi, [x,y]
           d=numb2[0]*numb2[0]+numb2[1]*numb2[1]
           nx=numb1[0]*numb2[0]+numb1[1]*numb2[1]
           ny=numb1[1]*numb2[0]-numb1[0]*numb2[1]
           X=float(nx/d)
           Y=float(ny/d)
           return[X,Y]
       def Cartesian_complex_modulus(numb):
           return math.sqrt(numb[0]*numb[0]+numb[1]*numb[1])
```

```
def Cartesian_complex_complex_conjugate(numb):
    return [numb[0],-numb[1]]
def Cartesian_complex_complex_to_polar(numb):
    r=Cartesian_complex_modulus(numb)
    if numb[0]>0:
        t=math.atan(float(numb[1]/numb[0]))
    elif numb[0]<0:</pre>
        t=math.atan(float(numb[1]/numb[0]))+math.pi
    else:
        if numb[1]>0:
            t=float(math.pi/2)
        elif numb[1]<0:</pre>
            t=float(-math.pi/2)
        else:
            t="null"
    return [r,t]
def Polar_complex_complex_to_Cartesian(numb):
    return [numb[0]*math.cos(numb[1]),numb[0]*math.sin(numb[1])]
def Polar_complex_conjugate(numb):
    return [numb[0],-numb[1]]
def Polar_complex_mul(numb1,numb2):
    #numb1 r_1e^{(it_1)}, [r_1,t_1], numb2 r_2e^{(it_2)}, [r_2,t_2]
    r=numb1[0]*numb2[0]
    t=numb1[1]+numb2[1]
    return [r,t]
def Polar_complex_divide(numb1,numb2):
    #numb1 r_1e^{(it_1)}, [r_1,t_1], numb2 r_2e^{(it_2)}, [r_2,t_2]
    r=float(numb1[0]/numb2[0])
    t=numb1[1]-numb2[1]
    return [r,t]
def Polar_complex_add(numb1,numb2):
    N1=Polar_complex_complex_to_Cartesian(numb1)
    N2=Polar complex complex to Cartesian(numb2)
    tot=Cartesian_complex_add(N1,N2)
    return Cartesian_complex_complex_to_polar(tot)
def real matrix addition(m1,m2):
    #m1=[[M11,M12],[M21,M22]]
    a=m1[0][0]+m2[0][0]
    b=m1[0][1]+m2[0][1]
    c=m1[1][0]+m2[1][0]
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```
d=m1[1][1]+m2[1][1]
    11=[a,b]
    12=[c,d]
    1=[]
    1.append(11)
    1.append(12)
    return 1
def Cartesian_complex_matrix_addition(m1,m2):
    #m1=[[M11,M12],[M21,M22]]
    \#M11 = \Gamma a.b7
    a1=m1[0][0][0]+m2[0][0][0]
    a2=m1[0][0][1]+m2[0][0][1]
    b1=m1[0][1][0]+m2[0][1][0]
    b2=m1[0][1][1]+m2[0][1][1]
    c1=m1[1][0][0]+m2[1][0][0]
    c2=m1[1][0][1]+m2[1][0][1]
    d1=m1[1][1][0]+m2[1][1][0]
    d2=m1[1][1][1]+m2[1][1][1]
    a = [a1, a2]
    b=[b1,b2]
    c = [c1, c2]
    d = [d1, d2]
    11=[a,b]
    12=[c,d]
    1=[]
    1.append(11)
    1.append(12)
    return 1
def real_matrix_multiplication(m1,m2):
    #m1=[[M11,M12],[M21,M22]]
    a=m1[0][0]*m2[0][0]+m1[0][1]*m2[1][0]
    b=m1[0][0]*m2[0][1]+m1[0][1]*m2[1][1]
    c=m1[1][0]*m2[0][0]+m1[1][1]*m2[1][0]
    d=m1[1][0]*m2[0][1]+m1[1][1]*m2[1][1]
    11=[a,b]
    12=[c,d]
    1=[]
    1.append(11)
    1.append(12)
    return 1
def Cartesian_complex_matrix_multiplication(m1,m2):
    #m1=[[M11,M12],[M21,M22]]
    \#M11=[a,b]
```

```
-a=Cartesian_complex_add(Cartesian_complex_mul(m1[0][0],m2[0][0]),Cartesian_complex_mul(m1[0
 b=Cartesian_complex_add(Cartesian_complex_mul(m1[0][0],m2[0][1]),Cartesian_complex_mul(m1[0
 →c=Cartesian_complex_add(Cartesian_complex_mul(m1[1][0],m2[0][0]),Cartesian_complex_mul(m1[1
 -d=Cartesian_complex_add(Cartesian_complex_mul(m1[1][0],m2[0][1]),Cartesian_complex_mul(m1[1
    11=[a,b]
    12 = [c,d]
    1=[]
    1.append(11)
    1.append(12)
    return 1
def real_matrix_inverse(m1):
    #m1=[[M11,M12],[M21,M22]]
    det=m1[0][0]*m1[1][1]-m1[0][1]*m1[1][0]
    a=float(m1[1][1]/det)
    b=float(-m1[0][1]/det)
    c=float(-m1[1][0]/det)
    d=float(m1[0][0]/det)
    11=[a,b]
    12=[c,d]
    1=[]
    1.append(11)
    1.append(12)
    return 1
def Cartesian_complex_matrix_inverse(m1):
    #m1=[[M11,M12],[M21,M22]]
    \#M11 = [a, b]
 -det=Cartesian_complex_add(Cartesian_complex_mul(m1[0][0],m1[1][1]),Cartesian_complex_scalar
    inverse_det=Cartesian_complex_divide([1,0],det)
    a=Cartesian_complex_mul(m1[1][1],inverse_det)
 b=Cartesian_complex_mul(Cartesian_complex_scalar_mul(-1,m1[0][1]),inverse_det)
 →c=Cartesian_complex_mul(Cartesian_complex_scalar_mul(-1,m1[1][0]),inverse_det)
    d=Cartesian_complex_mul(m1[0][0],inverse_det)
    11=[a,b]
    12 = [c,d]
    1=[]
    1.append(11)
    1.append(12)
```

```
return 1
def Cartesian_radial_hyperbolic_distance(z):
    r=float(Cartesian_complex_modulus(z))
    return math.log(float((1+r)/(1-r)))
def operator_T(Lambda):
    a1=(-Lambda-float(1/Lambda))*float(-0.5)
    a2=0
    b1 = 0
    b2=(-Lambda+float(1/Lambda))*float(-0.5)
    c1=0
    c2=(Lambda-float(1/Lambda))*float(-0.5)
    d1=(-Lambda-float(1/Lambda))*float(-0.5)
    d2=0
    l1=[[a1,a2],[b1,b2]]
    12=[[c1,c2],[d1,d2]]
    1=[]
    1.append(11)
    1.append(12)
    return 1
def operator_R(theta):
    a=Polar_complex_complex_to_Cartesian([1,float(0.5*theta)])
    b = [0, 0]
    c = [0, 0]
    d=Polar_complex_complex_to_Cartesian([1,float(-0.5*theta)])
    11=[a,b]
    12=[c,d]
    1=[]
    1.append(11)
    1.append(12)
    return 1
def classification_point(Lambda):
    return [float((2*Lambda**2)/(Lambda**4+1)),float((Lambda**4-1)/
 →(Lambda**4+1))]
def check_T_generate_a_Schottky(Lambda,m):
    t=float(-math.pi/2)+float(math.pi/(2*m))
    K=Polar_complex_complex_to_Cartesian([1,t])
    B=classification_point(Lambda)
    T=operator_T(Lambda)
    T0=Cartesian_complex_divide(T[0][1],T[1][1])
```

```
-discriminant=float(Cartesian_complex_modulus(Cartesian_complex_add(K,Cartesian_complex_scal
    print(discriminant)
    if discriminant>0:
        return True
    else:
        return False
def Tz(T,z):
    a=T[0][0]
    b=T[0][1]
    c=T[1][0]
    d=T[1][1]
    return _
 -Cartesian_complex_divide(Cartesian_complex_add(Cartesian_complex_mul(a,z),b),Cartesian_comp
#Generate the orbit Gamma(0)
def GammaO(Lambda,m,N):
    T=operator_T(Lambda)
    theta=float(math.pi/m)
    R=operator_R(theta)
    L=[Tz(T,[0,0])]
    tmp1=[]
    tmp2=[]
    nodes_in_DT=[[0,0]]
    j=1
    while j<=N:
        #N=1
        if j==1:
            z=L[0]
            tmp1=[]
            tmp2=[]
            for i in range(2*m-1):
                z=Tz(R,z)
                tmp1.append(z)
                if i!=m-1:
                    tmp2.append(z)
                else:
                    tmp2.append(L[0])
            for k in tmp2:
                L.append(k)
            nodes_in_DT=[Tz(T,[0,0])]
```

```
#N>1
        else:
            nodes_in_DT=[]
            tmp1=[]
            tmp2=[]
            tmp3=[]
            for k in L:
                z=Tz(T,k)
                nodes_in_DT.append(z)
                tmp1.append(z)
                tmp2.append(z)
            for i in range(2*m-1):
                if i!=m-1:
                    for k in tmp1:
                         tmp3.append(Tz(R,k))
                     tmp1=[]
                     for k in tmp3:
                         tmp1.append(k)
                         L.append(k)
                    tmp3=[]
                elif i==m-1:
                     for k in tmp1:
                         tmp3.append(Tz(R,k))
                    tmp1=[]
                     for k in tmp3:
                         tmp1.append(k)
                    tmp3=[]
                     for k in tmp2:
                         L.append(k)
        j+=1
   return nodes_in_DT
# measuring hyperbolic distance
def Hyperbolic_Distance_Gamma0(Lambda,m,N):
    T=operator_T(Lambda)
    theta=float(math.pi/m)
    R=operator_R(theta)
    L=[Tz(T,[0,0])]
    tmp1=[]
    tmp2=[]
    nodes_in_DT=[[0,0]]
    j=1
    while j \le N:
        #N=1
        if j==1:
            z=L[0]
```

```
tmp1=[]
        tmp2=[]
        for i in range(2*m-1):
            z=Tz(R,z)
            tmp1.append(z)
            if i!=m-1:
                tmp2.append(z)
            else:
                tmp2.append(L[0])
        L=[]
        for k in tmp2:
            L.append(k)
        nodes_in_DT=[Tz(T,[0,0])]
    #N>1
    else:
        nodes_in_DT=[]
        tmp1=[]
        tmp2=[]
        tmp3=[]
        for k in L:
            z=Tz(T,k)
            nodes_in_DT.append(z)
            tmp1.append(z)
            tmp2.append(z)
        L=[]
        for i in range(2*m-1):
            if i!=m-1:
                for k in tmp1:
                     tmp3.append(Tz(R,k))
                tmp1=[]
                for k in tmp3:
                     tmp1.append(k)
                     L.append(k)
                tmp3=[]
            elif i==m-1:
                for k in tmp1:
                     tmp3.append(Tz(R,k))
                tmp1=[]
                for k in tmp3:
                     tmp1.append(k)
                tmp3=[]
                for k in tmp2:
                    L.append(k)
    j+=1
Hyperbolic_distance=[]
```

```
for k in nodes_in_DT:
        Hyperbolic_distance.append(Cartesian_radial_hyperbolic_distance(k))
    return Hyperbolic_distance
# measuring Exp(-hyperbolic distance)
def Exp_negative_Hyperbolic_Distance_Gamma0(Lambda,m,N):
    T=operator_T(Lambda)
    theta=float(math.pi/m)
    R=operator_R(theta)
    L=[Tz(T,[0,0])]
    tmp1=[]
    tmp2=[]
    nodes_in_DT=[[0,0]]
    j=1
    while j \le N:
        #N=1
        if j==1:
            z=L[0]
            tmp1=[]
            tmp2=[]
            for i in range(2*m-1):
                z=Tz(R,z)
                tmp1.append(z)
                if i!=m-1:
                    tmp2.append(z)
                else:
                    tmp2.append(L[0])
            L=[]
            for k in tmp2:
                L.append(k)
            nodes_in_DT=[Tz(T,[0,0])]
        #N>1
        else:
            nodes_in_DT=[]
            tmp1=[]
            tmp2=[]
            tmp3=[]
            for k in L:
                z=Tz(T,k)
                nodes_in_DT.append(z)
                tmp1.append(z)
                tmp2.append(z)
            L=[]
            for i in range(2*m-1):
                if i!=m-1:
                    for k in tmp1:
```

```
tmp3.append(Tz(R,k))
                    tmp1=[]
                    for k in tmp3:
                        tmp1.append(k)
                        L.append(k)
                    tmp3=[]
                elif i==m-1:
                    for k in tmp1:
                        tmp3.append(Tz(R,k))
                    tmp1=[]
                    for k in tmp3:
                        tmp1.append(k)
                    tmp3=[]
                    for k in tmp2:
                        L.append(k)
        j+=1
    Hyperbolic_distance=[]
    for k in nodes_in_DT:
        Hyperbolic_distance.append(math.
 →exp(-Cartesian_radial_hyperbolic_distance(k)))
    return Hyperbolic_distance
# measuring Exp(-hyperbolic distance)
def Exp_negative_Hyperbolic_Distance_GammaO_with_t(Lambda,m,N,t):
    T=operator_T(Lambda)
    theta=float(math.pi/m)
    R=operator_R(theta)
    L=[Tz(T,[0,0])]
    tmp1=[]
    tmp2=[]
    nodes_in_DT=[[0,0]]
    j=1
    while j<=N:
        #N=1
        if j==1:
            z=L[0]
            tmp1=[]
            tmp2=[]
            for i in range(2*m-1):
                z=Tz(R,z)
                tmp1.append(z)
                if i!=m-1:
                    tmp2.append(z)
                else:
                    tmp2.append(L[0])
            L=[]
```

```
for k in tmp2:
                L.append(k)
            nodes_in_DT=[Tz(T,[0,0])]
        #N>1
        else:
            nodes_in_DT=[]
            tmp1=[]
            tmp2=[]
            tmp3=[]
            for k in L:
                z=Tz(T,k)
                nodes_in_DT.append(z)
                tmp1.append(z)
                tmp2.append(z)
            L=[]
            for i in range(2*m-1):
                if i!=m-1:
                    for k in tmp1:
                        tmp3.append(Tz(R,k))
                    tmp1=[]
                    for k in tmp3:
                        tmp1.append(k)
                        L.append(k)
                    tmp3=[]
                elif i==m-1:
                    for k in tmp1:
                        tmp3.append(Tz(R,k))
                    tmp1=[]
                    for k in tmp3:
                        tmp1.append(k)
                    tmp3=[]
                    for k in tmp2:
                        L.append(k)
        j+=1
    Hyperbolic_distance=[]
    for k in nodes_in_DT:
        Hyperbolic_distance.append(math.
 →exp(-t*Cartesian_radial_hyperbolic_distance(k)))
    return Hyperbolic_distance
# measuring Exp(-t*(hyperbolic distance))
def Improved_Exp_negative_Hyperbolic_Distance_GammaO_with_t(Lambda,m,N,L,t):
    T=operator_T(Lambda)
    theta=float(math.pi/m)
```

```
R=operator_R(theta)
if len(L)==0:
    L=[Tz(T,[0,0])]
    j=1
else:
    j=N
tmp1=[]
tmp2=[]
nodes_in_DT=[[0,0]]
while j \le N:
    #N=1
    if j==1:
        z=L[0]
        tmp1=[]
        tmp2=[]
        for i in range(2*m-1):
            z=Tz(R,z)
            tmp1.append(z)
            if i!=m-1:
                tmp2.append(z)
            else:
                 tmp2.append(L[0])
        L=[]
        for k in tmp2:
            L.append(k)
        nodes_in_DT=[Tz(T,[0,0])]
    #N>1
    else:
        nodes_in_DT=[]
        tmp1=[]
        tmp2=[]
        tmp3=[]
        for k in L:
            z=Tz(T,k)
            nodes_in_DT.append(z)
            tmp1.append(z)
            tmp2.append(z)
        L=[]
        for i in range(2*m-1):
            if i!=m-1:
                for k in tmp1:
                     tmp3.append(Tz(R,k))
                tmp1=[]
                 for k in tmp3:
                     tmp1.append(k)
```

```
L.append(k)
                    tmp3=[]
                elif i==m-1:
                    for k in tmp1:
                        tmp3.append(Tz(R,k))
                    tmp1=[]
                    for k in tmp3:
                        tmp1.append(k)
                    tmp3=[]
                    for k in tmp2:
                        L.append(k)
        j+=1
    Hyperbolic_distance=[]
    for k in nodes_in_DT:
        Hyperbolic_distance.append(math.
 →exp(-t*Cartesian_radial_hyperbolic_distance(k)))
    return [Hyperbolic_distance,L]
# measuring Exp(-hyperbolic distance)
def Improved_Exp_negative_Hyperbolic_Distance_Gamma0(Lambda,m,N,L):
    T=operator_T(Lambda)
    theta=float(math.pi/m)
    R=operator_R(theta)
    if len(L)==0:
        L=[Tz(T,[0,0])]
    else:
        j=N
    tmp1=[]
    tmp2=[]
    nodes_in_DT=[[0,0]]
    while j<=N:
        #N=1
        if j==1:
            z=L[0]
            tmp1=[]
            tmp2=[]
            for i in range(2*m-1):
                z=Tz(R,z)
                tmp1.append(z)
                if i!=m-1:
                    tmp2.append(z)
```

```
else:
                   tmp2.append(L[0])
           L=[]
           for k in tmp2:
               L.append(k)
           nodes_in_DT = [Tz(T,[0,0])]
       #N>1
       else:
           nodes_in_DT=[]
           tmp1=[]
           tmp2=[]
           tmp3=[]
           for k in L:
               z=Tz(T,k)
               nodes_in_DT.append(z)
               tmp1.append(z)
               tmp2.append(z)
           L=[]
           for i in range(2*m-1):
               if i!=m-1:
                   for k in tmp1:
                       tmp3.append(Tz(R,k))
                   tmp1=[]
                   for k in tmp3:
                       tmp1.append(k)
                       L.append(k)
                   tmp3=[]
               elif i==m-1:
                   for k in tmp1:
                       tmp3.append(Tz(R,k))
                   tmp1=[]
                   for k in tmp3:
                       tmp1.append(k)
                   tmp3=[]
                   for k in tmp2:
                       L.append(k)
       j+=1
  Hyperbolic_distance=[]
  for k in nodes_in_DT:
      Hyperbolic_distance.append(math.
→exp(-Cartesian_radial_hyperbolic_distance(k)))
  return [Hyperbolic_distance,L]
```

```
def examples_of_10000(initial, increment):
   counter=initial
   useful_example=0
   while counter < initial+10000*increment:
       print("***********"+str(counter)+"**********")
       out=[]
       if check_T_generate_a_Schottky(Lambda=counter,m=2):
          try:
              rho=[]
              for i in range(15):
                 sum1=0
                 sum2=0
 -test=Exp_negative_Hyperbolic_Distance_Gamma0(Lambda=counter,m=2,N=i)
                 ave_of_all_exp_of_negative_rho_of_this_level=statistics.
 →mean(test)
                 occurence=0
                 tmp=[]
                 for node in test:
                     if node < ave_of_all_exp_of_negative_rho_of_this_level:</pre>
                         occurence+=1
                     else:
                        tmp.append(node)
                 print("N="+str(i))
                 print("occurence="+str(occurence))
                 if len(tmp)!=0:
 →ave_of_all_large_exp_of_negative_rho_of_this_level=statistics.mean(tmp)
                     rho.
 append(ave_of_all_large_exp_of_negative_rho_of_this_level)
 →print("ave_of_all_large_exp_of_negative_rho_of_this_level:
 print("ave_of_all_exp_of_negative_rho_of_this_level:
 if ave_of_all_large_exp_of_negative_rho_of_this_level!
 ⇒=0:
 →append(ave_of_all_large_exp_of_negative_rho_of_this_level/
 →ave_of_all_exp_of_negative_rho_of_this_level)

¬print("ave_of_all_short_exp_of_negative_rho_of_this_level/
 →ave_of_all_exp_of_negative_rho_of_this_level:
 ave_of_all_exp_of_negative_rho_of_this_level))
```

```
except:
               print("---")
       if len(rho)>2:
           if rho[-1]>1:
               useful_example+=1
       counter+=increment
       print("counter:"+str(counter))
       print("useful_example:"+str(useful_example))
def examples of 10000 with t(initial, increment,t0):
   counter=initial
   useful example=0
   while counter < initial+10000*increment:</pre>
       print("************"+str(counter)+"**********")
       out=[]
       if check_T_generate_a_Schottky(Lambda=counter,m=2):
           try:
               rho=[]
               for i in range(15):
                   sum1=0
                   sum 2 = 0
 stest=Exp_negative_Hyperbolic_Distance_GammaO_with_t(Lambda=counter, m=2, N=i, t=t0)
 #test=Exp negative Hyperbolic Distance GammaO with t(Lambda=0.3, m=2, N=i, t=t0)
                   ave of all exp of negative rho of this level=statistics.
 →mean(test)
                   occurence=0
                   tmp=[]
                   for node in test:
                       if node < ave_of_all_exp_of_negative_rho_of_this_level:</pre>
                           occurence+=1
                       else:
                           tmp.append(node)
                   print("N="+str(i))
                   print("occurence="+str(occurence))
                   if len(tmp)!=0:
 ave_of_all_large_exp_of_negative_rho_of_this_level=statistics.mean(tmp)
 append(ave_of_all_large_exp_of_negative_rho_of_this_level)

¬print("ave_of_all_large_exp_of_negative_rho_of_this_level:
```

```
print("ave_of_all_exp_of_negative_rho_of_this_level:
 if ave_of_all_large_exp_of_negative_rho_of_this_level!
 ⇒=0:
                           rho.
 -append(ave_of_all_large_exp_of_negative_rho_of_this_level/
 ave_of_all_exp_of_negative_rho_of_this_level)

¬print("ave_of_all_large_exp_of_negative_rho_of_this_level/
 →ave_of_all_exp_of_negative_rho_of_this_level:
 →"+str(ave_of_all_large_exp_of_negative_rho_of_this_level/
 →ave_of_all_exp_of_negative_rho_of_this_level))
           except:
               print("---")
       if len(rho)>2:
           if rho[-1]>1:
               useful_example+=1
       counter+=increment
       print("counter:"+str(counter))
       print("useful example:"+str(useful example))
# measuring hyperbolic distance
def Gamma(Lambda,m,N):
   T=operator_T(Lambda) # T is a 2 by 2 matrix.
   theta=float(math.pi/m)
   ID=[[[1, 0], [0, 0]], [[0, 0], [1, 0]]]
   R=operator_R(theta) # R is a 2 by 2 matrix.
   L=[T]
   tmp1=[]
   tmp2=[]
   model=[]
   component=[]
   nodes_in_DT=[ [[[1, 0], [0, 0]], [[0, 0], [1, 0]]] ]
   j=1
   while j<=N:
       #N=1
       if j==1:
           z=L[0]
           tmp1=[]
           tmp2=[]
           for i in range(2*m-1):
               z=Cartesian_complex_matrix_multiplication(R,z)
                                                             \#Tz(R,z)
               tmp1.append(z)
```

```
if i!=m-1:
                   tmp2.append(z)
               else:
                   tmp2.append(L[0])
          L=[]
          for k in tmp2:
               L.append(k)
          nodes_in_DT=[Cartesian_complex_matrix_multiplication(T,ID)]
      #N>1
      else:
          nodes_in_DT=[]
           tmp1=[]
          tmp2=[]
           tmp3=[]
          for k in L:
               z=Cartesian_complex_matrix_multiplication(T,k)
                                                                      \#Tz(T,k)
               nodes_in_DT.append(z)
               tmp1.append(z)
               tmp2.append(z)
          L=[]
          for i in range(2*m-1):
               if i!=m-1:
                   for k in tmp1:
                       tmp3.
-append(Cartesian_complex_matrix_multiplication(R,k))
                   tmp1=[]
                   for k in tmp3:
                       tmp1.append(k)
                       L.append(k)
                   tmp3=[]
               elif i==m-1:
                   for k in tmp1:
                       tmp3.
→append(Cartesian_complex_matrix_multiplication(R,k))
                   tmp1=[]
                   for k in tmp3:
                       tmp1.append(k)
                   tmp3=[]
                   for k in tmp2:
```

```
L.append(k)
    j+=1
    Out=[]
index=0
temp0=[]
tmp1=[]
for k in L:
    z=Cartesian_complex_matrix_multiplication(T,k)
                                                          \#Tz(T,k)
    tmp1.append(z)
N=int(math.log(len(tmp1),(2*m-1)))
print("N:"+str(N))
initial_index=(((2*m)-1)**(N-1))*(m+1)
tindex=initial_index
#print(len(tmp1))
cindex=0
counter=0
for k in tmp1:
    if counter==(2*m-1):
        counter=0
        cindex+=1
    temp=[]
    component=[]
    component.append(initial_index)
    component.append(cindex)
    initial_index+=1
    initial_index=initial_index\%((2*m)*(2*m-1)**(N-1))
    temp.append(k)
    temp.append(component)
    temp0.append(temp)
    counter+=1
model.append(temp0)
initial\_index=tindex+(2*m-1)**(N-1)
initial_index=initial_index\%((2*m)*(2*m-1)**(N-1))
tindex+=1
tindex=tindex\%((2*m)*(2*m-1)**(N-1))
temp=[]
temp1=[]
temp2=[]
print("tmp1"+str(len(tmp1)))
for i in range(2*m-1):
```

```
temp2=[]
    for k in tmp1:
        temp=[]
        temp0=[]
        if counter==(2*m-1):
            counter=0
            cindex+=1
        z=Cartesian_complex_matrix_multiplication(R,k)
        temp2.append(z)
        temp.append(z)
        component=[]
        component.append(initial_index)
        component.append(cindex)
        temp.append(component)
        initial_index+=1
        initial_index=initial_index\%((2*m)*(2*m-1)**(N-1))
        temp0.append(temp)
        counter+=1
        model.append(temp0)
    tmp1=[]
    for k in temp2:
        tmp1.append(k)
    temp2=[]
    initial_index=tindex+(2*m-1)**(N-1)
    initial\_index=initial\_index\%((2*m)*(2*m-1)**(N-1))
    tindex+=1
    tindex=tindex\%((2*m)*(2*m-1)**(N-1))
#for k in model:
# tmp1=[]
  component=[]
# for key in k:
        print("====")
#
        print(key)
# print("----")
#Hyperbolic_distance=[]
#for k in nodes_in_DT:
    Hyperbolic\_distance.append(Cartesian\_radial\_hyperbolic\_distance(k))
return model
```

```
def non_normalized_derivative(T,z):
            #T = [[[a,b],[c,-d]], [[c,d],[a,-b]]]
            #z=[x,y]
            #a1=T[0][0][0]
            #a2=T[0][0][1]
           #b1=T[0][1][0]
           #b2=T[0][1][1]
           #c1=T[1][0][0]
           #c2=T[1][0][1]
           #d1=T[1][1][0]
           #d2=T[1][1][1]
           a=T[0][0]
           b=T[0][1]
           c=T[1][0]
           d=T[1][1]
    →#NR=d1**2-d2**2+2*c1*d1*x-2*c2*d2*x+c1**2*x**2-c2**2*x**2-2*c2*d1*y-2*c1*d2*y-4*c1*c2*x*y-c
   \neg \#NI = 2*d1*d2+2*c2*d1*x+2*c1*d2*x+2*c1*c2*x**2+2*c1*d1*y-2*c2*d2*y+2*c1**2*x*y-2*c2**2*x*y-2*c2*d2*y+2*c1**2*x*y-2*c2*d2*y+2*c1*d2*x+2*x+y-2*c2*d2*y+2*c1*d2*x+2*x+y-2*c2*d2*y+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2*x+2*c1*d2
           #DR=-b1*c1+b2*c2+a1*d1-a2*d2
           #DI=-b2*c1-b1*c2+a2*d1+a1*d2
            #N1=NR*DR+NI*DI
            #N2=NI*DR-NR*DI
           #D=DR**2+DI**2
   -N=Cartesian_complex_add(Cartesian_complex_mul(a,d),Cartesian_complex_scalar_mul(-1,Cartesia
   D=D=Cartesian_complex_mul(Cartesian_complex_add(Cartesian_complex_mul(c,z),d),Cartesian_complex_mul(c,z),d)
           if Cartesian_complex_modulus(D)!=0:
                       return Cartesian_complex_divide(N,D)
           else:
                       return "null"
def derivatives(model):
           output=[]
           for i in model:
                        for j in i:
                                    tmp=[]
                                    z=Tz(j[0],[0,-1])
                                    D_of_T=derivative(j[0],z)
                                    if D_of_T!="null":
                                                Tij=float(1/Cartesian_complex_modulus(D_of_T))
                                    else:
```

```
Tij=0
    tmp.append(Tij)
    tmp.append(j[1])
    output.append(tmp)
return output
```

```
[387]: # Generate x j
       def Generate_xj(M,x_1):
           #M=number of disks in the first level
           \#x 1=[1,0]
           1=[]
           k=2
           theta=float(2*math.pi/M)
           mul=Polar_complex_complex_to_Cartesian([1,theta])
           #M=3
           tmp=x_1
           1.append(tmp)
           while k<=M:
               tmp=Cartesian_complex_mul(mul,tmp)
               1.append(tmp)
               k+=1
           return 1
       # Compute y ij
       def inverse_f1(R,z,q):
           D=Cartesian_complex_add(z,Cartesian_complex_scalar_mul(-1,q))
           numb2=Cartesian_complex_divide([R**2,0],D)
           return Cartesian_complex_add(Cartesian_complex_complex_conjugate(q),numb2)
       def inverse_f2(R,z,q):
           D=Cartesian_complex_add(z,Cartesian_complex_scalar_mul(-1,q))
           numb2=Cartesian_complex_divide([R**2,0],D)
           H2=Cartesian_complex_divide([1,-math.sqrt(3)],[1,math.sqrt(3)])
           H2bar=Cartesian_complex_complex_conjugate(H2)
           return
        -Cartesian_complex_divide(Cartesian_complex_add(Cartesian_complex_complex_conjugate(q),numb2
       def inverse_f3(R,z,q):
           D=Cartesian_complex_add(z,Cartesian_complex_scalar_mul(-1,q))
           numb2=Cartesian_complex_divide([R**2,0],D)
           H3=Cartesian_complex_divide([-1,-math.sqrt(3)],[-1,math.sqrt(3)])
           H3bar=Cartesian_complex_complex_conjugate(H3)
        -Cartesian_complex_divide(Cartesian_complex_add(Cartesian_complex_complex_conjugate(q),numb2
```

```
[519]: import numpy as np from numpy.linalg import eig
```

```
def Symmetric_pairs_of_pants(angle,tinitial,incre):
    Theta=angle#math.pi-angle#0.5*angle
    R=math.tan((Theta/2)) #math.sqrt(2-2*math.cos(Theta))
    tmpl=Generate_xj(M=3,x_1=[math.sqrt(1+R**2),0])
    tmp2=Generate_xj(M=3,x_1=[0.7320628133,0])
    t11=0
    t.22=0
    t33=0
    a=tmpl[0]
 →b=Cartesian_complex_add([R**2,0],Cartesian_complex_scalar_mul(-1,Cartesian_complex_mul(tmpl
    Cartesian_complex_complex_conjugate(tmpl[0]))))
    c = [1, 0]
 -d=Cartesian_complex_scalar_mul(-1, Cartesian_complex_complex_conjugate(tmpl[0]))
    T=[[a,b],[c,d]]
 y12=Cartesian_complex_divide(Cartesian_complex_add(Cartesian_complex_mul(a,tmp2[1]),b),
 →Cartesian_complex_add(Cartesian_complex_mul(c,tmp2[1]),d))
 -y13=Cartesian_complex_divide(Cartesian_complex_add(Cartesian_complex_mul(a,tmp2[2]),b),
 →Cartesian_complex_add(Cartesian_complex_mul(c,tmp2[2]),d))
    t12=float(1/
 -Cartesian_complex_modulus(non_normalized_derivative([[tmpl[0],b],[[1,0],
 →Cartesian_complex_scalar_mul(-1,Cartesian_complex_complex_conjugate(tmpl[0]))]],y12)))
    t13=float(1/
 -Cartesian_complex_modulus(non_normalized_derivative([[tmpl[0],b],[[1,0],
 -Cartesian complex scalar mul(-1, Cartesian complex complex conjugate(tmpl[0]))]], y13)))
    H2=Cartesian_complex_divide([1,-math.sqrt(3)],[1,math.sqrt(3)])
    H2bar=Cartesian_complex_complex_conjugate(H2)
    q2=tmpl[1]
    a=Cartesian complex mul(q2,H2bar)
 →b=Cartesian_complex_add([R**2,0],Cartesian_complex_scalar_mul(-1,Cartesian_complex_mul(tmpl
    Cartesian_complex_complex_conjugate(tmpl[1]))))
    c=H2bar
    d=Cartesian_complex_scalar_mul(-1,Cartesian_complex_complex_conjugate(q2))
    T=[[a,b],[c,d]]

¬y21=Cartesian_complex_divide(Cartesian_complex_add(Cartesian_complex_mul(a,tmp2[0]),b),
```

```
→Cartesian_complex_add(Cartesian_complex_mul(c,tmp2[0]),d))
y23=Cartesian_complex_divide(Cartesian_complex_add(Cartesian_complex_mul(a,tmp2[2]),b),
→Cartesian_complex_add(Cartesian_complex_mul(c,tmp2[2]),d))
  t21=float(1/
-Cartesian complex modulus(non normalized derivative([[a,b],[c,d]],v21)))
  t23=float(1/
-Cartesian complex modulus(non normalized derivative([[a,b],[c,d]],y23)))
  H3=Cartesian_complex_divide([-1,-math.sqrt(3)],[-1,math.sqrt(3)])
  H3bar=Cartesian_complex_complex_conjugate(H3)
  q3=tmp1[2]
  a=Cartesian_complex_mul(q3,H3bar)
→b=Cartesian_complex_add([R**2,0],Cartesian_complex_scalar_mul(-1,Cartesian_complex_mul(tmpl
  Cartesian_complex_complex_conjugate(tmpl[2]))))
  c=H3bar
  d=Cartesian_complex_scalar_mul(-1,Cartesian_complex_complex_conjugate(q3))
  T=[[a,b],[c,d]]
-y31=Cartesian_complex_divide(Cartesian_complex_add(Cartesian_complex_mul(a,tmp2[0]),b),
→Cartesian_complex_add(Cartesian_complex_mul(c,tmp2[0]),d))
-y32=Cartesian_complex_divide(Cartesian_complex_add(Cartesian_complex_mul(a,tmp2[1]),b),
→Cartesian_complex_add(Cartesian_complex_mul(c,tmp2[1]),d))
  t31=float(1/
Gartesian_complex_modulus(non_normalized_derivative([[a,b],[c,d]],y31)))
  t32=float(1/
Gartesian_complex_modulus(non_normalized_derivative([[a,b],[c,d]],y32)))
  #print(t11)
  #print(t12)
  #print(t13)
  #print(t21)
  #print(t22)
  #print(t23)
  #print(t31)
  #print(t32)
  #print(t33)
  TIJ=[[t11,t12,t13],[t21,t22,t23],[t31,t32,t33]]
  #print(TIJ)
  flag=1
  flag2=0
  while flag==1:
```

```
col=[]
               TIJ_1=[]
               for k in TIJ:
                   col=[]
                   for i in k:
                        val=i**tinitial
                        col.append(val)
                   TIJ_1.append(col)
               a = np.array(TIJ_1)
               w, v=eig(a)
               M l=-10000000000
               for k in w:
                   if k>M 1:
                        M_1=k
               #print(M_l)
               #print("tinitial:"+str(tinitial))
               if M_1>1 and flag2==0:
                   flag2=1
               if flag2==1 and M_l<1:</pre>
                   flag=0
               if M_l<1 and flag2==0:</pre>
                   flag2=-1
               if flag2==-1 and M_l>1:
                   flag=0
               tinitial+=incre
           print("delta:"+str(tinitial))
           #print("Max eigenvalue:"+str(M_l.real))
           return tinitial
[520]: import matplotlib.pyplot as plt
       mlist=[]
       for angle in range(1,121):
           print("angle:"+str(angle))
           result=Symmetric_pairs_of_pants(angle=float(angle/180)*math.pi,tinitial=0.
        →000,incre=0.00001)
           mlist.append(result)
       Xlist=[]
       angle=1
       for k in mlist:
           Xlist.append(angle)
           angle+=1
       plt.plot(Xlist, mlist)
      angle:1
```

delta:0.07776000000000255

angle:2

angle:4

delta:0.09207999999997

angle:5

delta:0.0978799999999475

angle:6

delta:0.10318999999999269

angle:7

delta:0.10815999999999076

angle:8

delta:0.1128599999998894

angle:9

delta:0.1173599999999872

angle:10

delta:0.12170999999998551

angle:11

delta:0.12591999999998515

angle:12

delta:0.13002999999998927

angle:13

delta:0.134059999999933

angle:14

delta:0.1380199999999726

angle:15

delta:0.14192000000000116

angle:16

delta:0.14578000000000502

angle:17

delta:0.14960000000000884

angle:18

delta:0.1533900000001263

angle:19

delta:0.1571600000000164

angle:20

delta:0.16090000000002014

angle:21

delta:0.16464000000002388

angle:22

delta:0.168370000000276

angle:23

delta:0.1720900000003133

angle:24

delta:0.1758200000003506

angle:25

delta:0.1795500000000388

angle:26

delta:0.18328000000004252

angle:28

delta:0.19078000000005002

angle:29

delta:0.1945500000000538

angle:30

delta:0.1983400000005758

angle:31

delta:0.2021500000000614

angle:32

delta:0.20598000000006522

angle:33

delta:0.20984000000006908

angle:34

delta:0.21372000000007296

angle:35

delta:0.21763000000007687

angle:36

delta:0.2215700000000808

angle:37

delta:0.2255500000000848

angle:38

delta:0.2295600000000888

angle:39

delta:0.23360000000009284

angle:40

delta:0.23769000000009693

angle:41

delta:0.24181000000010106

angle:42

delta:0.2459800000010523

angle:43

delta:0.2501900000010944

angle:44

delta:0.254440000001137

angle:45

delta:0.258750000000118

angle:46

delta:0.26311000000012236

angle:47

delta:0.26751000000012676

angle:48

delta:0.271970000001312

angle:49

delta:0.2764900000013574

angle:50

delta:0.281070000001403

angle:52

delta:0.2904000000014965

angle:53

delta:0.295170000001544

angle:54

delta:0.3000000000015925

angle:55

delta:0.30490000000016415

angle:56

delta:0.309870000001691

angle:57

delta:0.3149100000017416

angle:58

delta:0.320030000001793

angle:59

delta:0.325240000001845

angle:60

delta:0.330520000001898

angle:61

delta:0.3358900000019514

angle:62

delta:0.341340000002006

angle:63

delta:0.34689000000020614

angle:64

delta:0.3525200000002118

angle:65

delta:0.3582600000002175

angle:66

delta:0.36409000000022335

angle:67

delta:0.3700300000002293

angle:68

delta:0.3760700000002353

angle:69

delta:0.3822200000002415

angle:70

delta:0.38848000000024774

angle:71

delta:0.39487000000025413

angle:72

delta:0.40137000000026063

angle:73

delta:0.40799000000026725

angle:74

delta:0.414750000000274

angle:76

delta:0.42867000000028793

angle:77

delta:0.435840000002951

angle:78

delta:0.4431500000003024

angle:79

delta:0.450620000003099

angle:80

delta:0.4582500000003175

angle:81

delta:0.4660400000003253

angle:82

delta:0.4740000000033327

angle:83

delta:0.4821400000003414

angle:84

delta:0.4904600000003497

angle:85

delta:0.49896000000035823

angle:86

delta:0.5076600000003244

angle:87

delta:0.5165600000002839

angle:88

delta:0.5256700000002424

angle:89

delta:0.5350000000002

angle:90

delta:0.544550000001565

angle:91

delta:0.55434000000112

angle:92

delta:0.5643700000000663

angle:93

delta:0.5746600000000195

angle:94

delta:0.585199999999715

angle:95

delta:0.596019999999223

angle:96

delta:0.6071199999998718

angle:97

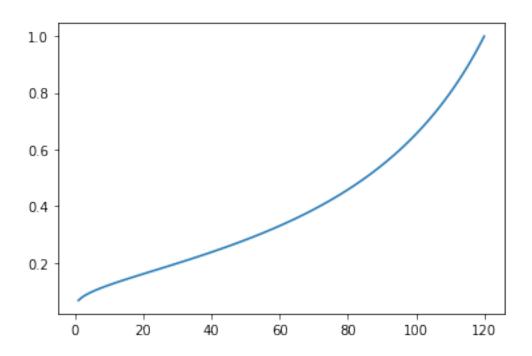
delta:0.618509999998199

angle:98

delta:0.6302099999997667

```
delta:0.64222999999712
angle:100
delta:0.654589999996557
angle:101
delta:0.667279999999598
angle:102
delta:0.680339999995385
angle:103
delta:0.6937799999994774
angle:104
delta:0.7076099999994144
angle:105
delta:0.721849999993496
angle:106
delta:0.7365099999992829
angle:107
delta:0.7516299999992141
angle:108
delta:0.767209999991432
angle:109
delta:0.78327999999907
angle:110
delta:0.799859999999946
angle:111
delta:0.8169799999989167
angle:112
delta:0.8346599999988362
angle:113
delta:0.852929999987531
angle:114
delta:0.8718199999986671
angle:115
delta:0.8913599999985782
angle:116
delta:0.9115799999984862
angle:117
delta:0.9325099999983909
angle:118
delta:0.9541999999982922
angle:119
delta:0.9766799999981899
angle:120
delta:1.0000099999980838
```

[520]: [<matplotlib.lines.Line2D at 0x1090d34f0>]



[]: