

ASEN 5067: Lab 5

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Assembly program requirements

Once on startup:

- RD4, RD5, RD6, RD7 off
- "ASENS067" displayed on LCD first line
- "PW1.00ms" displayed on LCD second line
- In sequence,
 - RD5 on for $0.5s \pm 10ms$ then RD5 off
 - RD6 on for $0.5s \pm 10ms$ then RD6 off
 - RD7 on for $0.5s \pm 10ms$ then RD7 off

Loop forever

- "Alive(ED)" RD4 blinks: $200ms \pm 100\mu s$ on, $800ms \pm 10\mu s$ off
note smaller tolerance!
- PWM on RC2 begins w/ period of $20ms$ & 5% duty cycle
 - 5% duty cycle - 1ms on, 19ms off
 - Tolerances: On $\pm 100\mu s$, off $\pm 10\mu s$
- RPCh will change pulse width
 - $\frac{1}{64}^{\text{th}}$ of a turn = $\pm 0.01ms$ (clockwise = +)
 - Hard limits - 1ms, 2ms
 - LCD should update w/ pulse width

Constraints

- Timers used for base timing
 - Should not be preloaded each time

- Use CCP to generate output pulse
 - Use another CCP for "Alive LED" RD4
 - Must handle timing & CCP in ISRs
 - Updating LCD, RP6, etc. must be done in main loop
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C Program Reg's

- Blink RD4 @ 1Hz, 50% duty cycle
 - Must use Timer0 w/ ISR
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ASSEMBLY

Low Pri - Turn on

High Pri - Turn off

Low

Pseudocode

Timer 1 for high priority - turning ON

Timer 3 for low priority - turning OFF

ECCP1 for turning Alive OFF - low pri.

- Init w/ time on
- Set ECCP2 = ECCP1
- Add time off to ECCP2

ECCP2 for turning Alive ON - high pri

- Don't init
- Set ECCP1 = ECCP2
- Add time on to ECCP1

ECCP3 for turning PWM OFF - low pri

- Don't init
- Set CCP4 = ECCP3
- Add time to CCP4

CCP4 for turning PWM ON - High pri.

- Init w/ time on
- Set ECCP3 = CCP4
- Add time to ECCP3

No!!! - Timer1 = Alive, Timer3 = PWM, change low/high pri

then handling!

- High pri for turning on

Outline

- Main
- Loop
- Initial
- Lo Pr.
- Hi Pr.
- ECCP¹ Handler
- ECCP² Handler

- Timer¹ Handler
- Timer³ Handler
- RPCn checker
- LCD update V
- LCD update C
- Wait OSs

Initial

- Set up I/O
- Turn off outputs
- Output LCD stuff
- Use Timer 0 & count to 4,5s for ON & OFF
- Set Timer 1 for High Pr. interrupts
- Set Timer 3 for Low Pr. interrupts
- Configure ECCP1-3, CCPH4

Low Pr.

- Check Alive CCP bit first
 - If set, turn off alive LED, reset IF
 - Set other Alive CCP bit
- Check PWM CCP bit
 - If set, turn PWM OFF
- Handle Timer 3

High Pr.

- Check Alive CCP bit
 - If set, turn

Lo Pr: - triggered

- Check :F

Scenario: Lo Pr: for CCP1 triggered, then

Hi Pr: for CCP2 triggered

Both IF bits set, but only CCP2

is Hi Pr: - need to make sure

Hi Pr: CCPs are handled, not Lo Pr:

Hi Pr:

BITSC

Questions

1. I kept having problems getting my PWM output to work. One upload it would work fine, the next it would be stuck in a reset loop. I believe the problem is due to using Timer1 for both ECCR. This will be rectified by switching ECCP3 to Timer3 instead of Timer1.

Extra Credit

Q.2:

An Interrupt Service Routine (ISR) is a special subroutine designed and written to accomplish a specific task requested by the interrupt request. The only difference between an ISR and a regular subroutine is an ISR must use a special RETURN statement - RETFIE(). This enables interrupts!

Q.8

The only pins that can accept external interrupt sources are:

- RB0/INT0
- RB1/INT1
- RB2/INT2
- RB3/INT3
- PORTB<7:4>

Q.14

The WREG, STATUS, and BSR registers are saved onto the stack when a high-priority interrupt is triggered. This is in contrast to a low-priority interrupt, which requires those registers to be manually saved.

