ZHANG-WEI HONG

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EDUCATION

Massachusetts Institute of Technology

Ph.D. in Electrical Engineering and Computer Science,

start 2020 - present

Advised by Prof. Pulkit Agrawal

National Tsing Hua University

Master in Computer Science, Overall GPA: 4.22 / 4.3 start 2017 - end 2018 Advised by Prof. Chun-Yi Lee

National Tsing Hua University

Bachelor in Computer Science

Overall GPA: 3.95 / 4.3 Major GPA: 4.12 / 4.3

start 2014 - end 2017

PUBLICATIONS

Eric Chen*, Zhang-Wei Hong*, Joni Pajarinen, and Pulkit Agrawal. Reconciling Intrinsic Rewards via Constrained Policy Optimization, Accepted at Conference on Neural Information Processing Systems (NeurIPS) 2022 (* denotes co-first author)

Haokuan Luo, Albert Yue, Zhang-Wei Hong, Pulkit Agrawal. **Stubborn: A Strong Baseline for Indoor Object Navigation**, Accepted at *International Conference on Intelligent Robots and Systems* (IROS) 2022

Zhang-Wei Hong*, Ge Yang*, and Pulkit Agrawal. Bilinear Value Networks for Multi-goal Reinforcement Learning, Accepted at International Conference on Learning Representation (ICLR) 2022 (* denotes co-first author)

Zhang-Wei Hong, Tao Chen, Yen-Chen Lin, Joni Pajarinen, and Pulkit Agrawal. **Topological Experience Replay**, Accepted at *International Conference on Learning Representation (ICLR) 2022*

Chin-Jui Chang, Yu-Wei Chu, Chao-Hsien Ting, Hao-Kang Liu, Zhang-Wei Hong, and Chun-Yi Lee, Reducing the Deployment-Time Inference Control Costs of Deep Reinforcement Learning Agents via an Asymmetric Architecture, Accepted by International Conference on Robotics and Automation (ICRA) 2021

Zhang-Wei Hong, Prabhat Nagarajan, and Guilherme Maeda, **Periodic Intra-Ensemble Knowledge**Distillation for Reinforcement Learning, Accepted by European Conference on Machine Learning (ECML) 2021 and Deep Reinforcement Learning Workshop at Conference on Neural Information Processing Systems (NeurIPS) 2019

Zhang-Wei Hong, Tsu-Jui Fu, Tzu-Yun Shann, Yi-Hsiang Chang, and Chun-Yi Lee. Adversarial Active Exploration Strategy for Inverse Dynamics Model Learning, Accepted as an oral paper by Conference on Robot Learning (CoRL) 2019

Zhang-Wei Hong, Tzu-Yun Shann, Shih-Yang Su, Yi-Hsiang Chang, Tsu-Jui Fu, and Chun-Yi Lee. Diversity-driven Exploration Strategy for Deep Reinforcement Learning, Accepted as a poster paper by Conference on Neural Information Processing Systems (NeurIPS) 2018

Zhang-Wei Hong, Chen Yu-Ming, Shih-Yang Su, Tzu-Yun Shann, Yi-Hsiang Chang, Hsuan-Kung Yang, Brian Hsi-Lin Ho, Chih-Chieh Tu, Yueh-Chuan Chang, Tsu-Ching Hsiao, Hsin-Wei Hsiao, Sih-Pin Lai,

and Chun-Yi Lee Virtual-to-Real: Learning to Control in Visual Semantic Segmentation, Accepted as an oral paper by International Joint Conferences on Artificial Intelligence (IJCAI) 2018

Zhang-Wei Hong*, Shih-Yang Su*, Tzu-Yun Shann*, Yi-Hsiang Chang, and Chun-Yi Lee. **Deep Policy**Inference Q-Network for Multi-Agent Systems, Accepted as an oral paper by International
Conference on Autonomous Agents and Multiagent Systems (AAMAS) 2018

Yen-Chen Lin, Zhang-Wei Hong, Yuan-Hong Liao, Meng-Li Shih, Ming-Yu Liu, and Min Sun. **Tactics** of adversarial attack on deep reinforcement learning agents, Accepted as an oral paper by International Joint Conferences on Artificial Intelligence (IJCAI) 2017

EXPERIENCE

Research intern, Microsoft Research, Montreal	2022 Jun 2022 Aug.
Full-time research assistant, National Tsing Hua University, Taiwan	2019 Oct 2020 Mar.
Research intern, Preferred Networks, Japan	2019 Jun 2019 Sep.
Engineering intern, Appier, Taiwan	2019 Feb 2019 Jun.
Visiting researcher, Advised by Jan Peters, TU Darmstadt, Germany	2018 Jul 2018 Sep.
Graduate research assistant, National Tsing Hua University, Taiwan	2016 Oct 2019 Jan.
Engineering intern, Mediatek, Taiwan	2016 Jul 2016 Sep.
Contract engineer, Industrial Technology Research Institute, Taiwan	2015 Oct 2015 Dec.

TEACHING

6.484 - Computational Sensorimotor Learning, MIT, U.S.	2022 Feb 2022 May.
Textbook drafting	
6.S090 - Deep Learning for Control, MIT, U.S.	2021 Jan.
Lectures of off-policy reinforcement learning	
Nvidia deep learning institute, Nvidia, Taiwan	2017 Jul 2017 Oct.
Hands-on image recognition	

SERVICE

Conference on Neural Information Processing Systems, reviewer	2022
International Conference on Machine Learning, reviewer	2021, 2022
Conference on Robot Learning, reviewer	2021, 2022
International Conference on Intelligent Robots and Systems, reviewer	2019
Advanced Robotics Journal, reviewer	2019
Conference on Neural Information Processing Systems, volunteer	2018
International Joint Conferences on Artificial Intelligence, volunteer	2018

PROJECTS

Nvidia Embedded Intelligent Robot Challenge

2016 Jun. - 2016 Sep.

Develop an intelligent robot using Nvidia Jetson TX1 to solve three tasks: (i) autonomous driving, (ii) object pick-and-place, and (iii) image recognition.

SKILLS

Programming Languages and Frameworks

- C/C++/C#/Python/Java
- Message Passing Interface (MPI)/CUDA/OpenGL/Robot Operating System(ROS)

- Tensorflow/PyTorch/Chainer

- Languages
 Mandarian (Chinese)
- English

AWARDS AND SCHOLARSHIPS

DAAD & MOST Summer Institute Program Fellowship	
Ministry of Science and Technology and Deutscher Akademischer Austausch Dienst	2019
Nvidia Jetson Developer Challenge – 1st prize	
Nvidia	2018
Master scholarship	
National Tsing Hua University	2017
Nvidia Embedded Intelligent Robotics Challenge - 1st prize	
Nvidia	2017
Meichu Hackthon (Microsoft Azure group) - 3rd prize	
Microsoft	2015