Constraint Satisfaction Problems, Graph Theory, and Universal Algebra

Cliff Bergman

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What is a CSP?

Informally, a Constraint Satisfaction Problem consists of

- a list of variables ranging over a finite domain and
- a set of constraints on those variables.

Problem: can we assign values to all the variables so that all of the constraints are satisfied?



Examples

A system of linear equations is a CSP

$$a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n = b_1$$

 $a_{21}x_1 + a_{22}x_2 + \cdots + a_{2n}x_n = b_2$
 \vdots
 $a_{m1}x_1 + a_{m2}x_2 + \cdots + a_{mn}x_n = b_m$



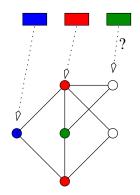
Also, a system of nonlinear equations is a CSP

$$a_{11}X_1^2X_3 + a_{12}X_2X_3X_7 + \cdots + a_{1n}X_4X_n^3 = b_1$$

 $a_{21}X_2X_5 + a_{22}X_2 + \cdots + a_{2n}X_4^3 = b_2$
 \vdots
 $a_{m1}X_3X_5X_8 + a_{m2}X_2 + \cdots + a_{mn}X_n = b_m$



For a fixed k, determining whether a graph is k-colorable is a CSP





Given a propositional formula $\phi(x_1, \ldots, x_n)$, determine whether ϕ is satisfiable

$$\phi(\mathbf{X},\mathbf{y},\mathbf{z}) = (\mathbf{X} \vee \mathbf{y} \vee \mathbf{z}') \wedge (\mathbf{X}' \vee \mathbf{y} \vee \mathbf{z}')$$

then

$$\phi(0,0,1) = 1$$



Algorithms

There is an efficient algorithm (Gaussian elimination) for solving any linear system. That is

There is an algorithm that accepts as input a linear system and decides whether that system has a solution. The running time of the algorithm is bounded above by f(s) where f is a polynomial and s is the size of the system.

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The running time of the algorithm is bounded above by f(s) where f is a polynomial and s is the size of the system.

The particular system is an instance of the problem LINEAR SYSTEM



Similarly

There is an algorithm that accepts as input a graph and decides whether the graph is 2-colorable.

The running time is bounded by f(s) where f is a polynomial and s is the size of the graph.

The graph is an instance of the problem 2-COLORABILITY.

There is an algorithm that accepts as input a formula, $\phi = \phi_1 \wedge \phi_2 \wedge \cdots \wedge \phi_k$, in which each ϕ_i is bijunctive, and decides whether ϕ is satisfiable. the running time is bounded by f(k) in which f is a polynomial

 ϕ is an instance of the problem 2-SAT.

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We say these algorithms run in polynomial time.

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Thus these problems are solvable in nondeterministic polynomial time.

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It is possible for $X \leq_p Y \leq_p X$. In that case, write $X \equiv_p Y$.



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- Both $\mathbb P$ and $\mathbb N\mathbb P$ are downsets, i.e., $Y\in\mathbb P$ & $X\leq_{\mathsf p}Y\implies X\in\mathbb P$

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- Both \mathbb{P} and \mathbb{NP} are downsets, i.e., $Y \in \mathbb{P} \& X \leq_{p} Y \implies X \in \mathbb{P}$

The maximal members of \mathbb{NP} are called \mathbb{NP} -complete.

3-COLORABILITY, NONLINEAR SYSTEM, and 3-SAT are known to be \mathbb{NP} -complete.



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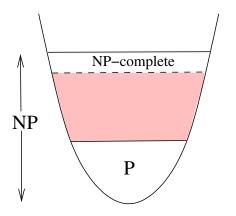
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Theorem (Ladner, 1975)

If $\mathbb{P} \neq \mathbb{NP}$ then there are problems in $\mathbb{NP} - \mathbb{P}$ that are not \mathbb{NP} -complete.





If $\mathbb{P} \neq \mathbb{NP}$ then the pink area is nonempty.

Formal Definition of CSP

Let D be a set, n a positive integer An n-ary relation on D is a subset of D^n

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 $Rel_n(D)$ denotes the set of all *n*-ary relations on *D*

$$\mathsf{Rel}(D) = \bigcup_{n>0} \mathsf{Rel}_n(D)$$



Let *D* be a finite set and $\Delta \subseteq Rel(D)$

CSP($\langle D, \Delta \rangle$) is the problem: **instance:** A finite set $V = \{v_1, \ldots, v_n\}$ of variables and a finite set $\{C_1, \ldots, C_m\}$ of constraints

Each constraint C_i is a pair $(\langle x_{i1}, \ldots, x_{ip_i} \rangle, \delta_i)$ in which $x_{i1}, \ldots, x_{ip_i} \in V$ and $\delta_i \in \Delta$



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Question: Does there exist a mapping $f: V \to D$ such that for all $i \le m$, $\langle f(x_{i1}), \ldots, f(x_{ip}) \rangle \in \delta_i$?



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 $\mathsf{CSP}(\langle D, \Delta \rangle)$ always lies in \mathbb{NP} .



Example: Linear Equations over \mathbb{F}_2

$$D = \{0, 1\}$$

Δ consists of all relations

$$\delta_{n,\mathbf{a}}^b = \left\{ \langle x_1, \dots, x_n \rangle \in D^n : a_1 x_1 + \dots + a_n x_n = b \right\}$$

Here, $\mathbf{a} = \langle a_1, a_2, \dots, a_n \rangle \in D^n$, $b \in D$.

Then $CSP(\langle D, \Delta \rangle)$ is LINEAR SYSTEM

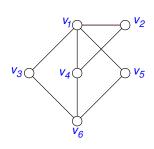


Example: 3-colorability

$$D = \{r, g, b\}, \quad \Delta = \{\kappa_3\}$$

 $\kappa_3 = \{(x, y) \in D : x \neq y\}$

Then $CSP(\langle D, \Delta \rangle)$ is the 3-colorability problem



$$V = \{v_1, \dots, v_6\}$$

$$\langle v_1, v_2 \rangle \in \kappa$$

$$\langle v_1, v_3 \rangle \in \kappa$$

$$\langle v_1, v_4 \rangle \in \kappa$$

$$\langle v_2, v_4 \rangle \in \kappa$$

$$\vdots$$

$$\langle v_5, v_6 \rangle \in \kappa$$



$$D = \{0, 1\}$$

For a bijunctive clause $\phi(x, y)$,

$$\delta_{\phi} = \left\{ \, \langle \textbf{\textit{a}}, \textbf{\textit{b}}
angle \in \textbf{\textit{D}}^{2} : \phi(\textbf{\textit{a}}, \textbf{\textit{b}}) = 1 \, \right\}$$

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| X | У | $x \vee y'$ |
|---|---|-------------|
| 0 | 0 | 1 |
| 0 | 1 | 0 |
| 1 | 0 | 1 |
| 1 | 1 | 1 |



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$$\begin{array}{c|cccc} x & y & x \vee y' \\ \hline 0 & 0 & 1 \\ & & & \\ 1 & 0 & 1 \\ 1 & 1 & 1 \end{array}$$
 So $\delta_{x\vee y'} = \{\langle 00 \rangle, \, \langle 10 \rangle, \, \langle 11 \rangle\}$

$$\Delta = \{\delta_{\mathbf{x} \vee \mathbf{y}}, \, \delta_{\mathbf{x} \vee \mathbf{y}'}, \, \delta_{\mathbf{x}' \vee \mathbf{y}}, \, \delta_{\mathbf{x}' \vee \mathbf{y}'}\}$$



Example: Horn-SAT

Horn formula:

$$(x_0 \wedge x_1 \wedge \cdots \wedge x_{i-1} \wedge x_{i+1} \wedge \cdots \wedge x_{n-1}) \rightarrow x_i$$

Equivalently:

$$\textit{X}'_0 \lor \textit{X}'_1 \lor \ldots \textit{X}'_{i-1} \lor \textit{X}_i \lor \cdots \lor \textit{X}'_{n-1}$$



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Corresponding relation $\gamma_i^n = \{0, 1\}^n - \{\langle 111 \dots 0 \dots 111 \rangle\}$



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Horn-SAT is
$$CSP\langle D, \Gamma \rangle$$

 $D = \{0, 1\}, \quad \Gamma = \{ \gamma_i^n : 0 \le i < n \}$



Schaefer's Dichotomy

Theorem (Schaefer, 1978)

Let $D = \{0, 1\}$. There are six families $\Delta_0, \dots, \Delta_5$ such that

$$\mathsf{CSP}(\langle D, \Delta \rangle) \in \mathbb{P} \iff \Delta \subseteq \Delta_i, \textit{some } i < 6$$

Otherwise $\mathsf{CSP}(\langle D, \Delta \rangle)$ is \mathbb{NP} -complete.



The six families

$$\Delta_0 = \{ \delta : \langle 0, 0, \dots, 0 \rangle \in \delta \} \text{ ("All False")}$$

$$\Delta_1 = \{ \delta : \langle 1, 1, \dots, 1 \rangle \in \delta \} \text{ ("All True")}$$

$$\Delta_2 = \{ \delta_{x \vee y}, \, \delta_{x \vee y'}, \, \delta_{x' \vee y}, \, \delta_{x' \vee y'} \} \text{ (bijunctive)}$$

$$\Delta_3 = \Gamma \text{ (Horn)}$$

$$\Delta_4 = \Gamma^{\partial} \text{ (dual-Horn)}$$

$$\Delta_5 \text{ (affine, i.e., linear system over } \mathbb{F}_2 \text{)}$$



Two Motivating Questions

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- Tractability Problem Characterize those CSPs that lie in ℙ.

Two Motivating Questions

- **Dichotomy Conjecture** Every $CSP(\langle D, \Delta \rangle)$ either lies in \mathbb{P} or is \mathbb{NP} -complete.
- Tractability Problem Characterize those CSPs that lie in P.

What would a characterization look like? What language could we use?



Why is 2-SAT tractable, but 3-SAT is not?

2-SAT:
$$\Delta_2 = \{\delta_{x \lor y}, \, \delta_{x \lor y'}, \, \delta_{x' \lor y}, \, \delta_{x' \lor y'}\}$$

3-SAT:
$$\Lambda = \{\lambda_0, \lambda_1, \dots, \lambda_7\}$$

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3-SAT:
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$$M(x,y,z)=\begin{cases}0\\1\end{cases}$$

if at least 2 of x, y, z equal 0 otherwise

"Majority Operation"



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$$\text{2-SAT: } \Delta_2 = \{\delta_{\textbf{\textit{x}} \vee \textbf{\textit{y}}}, \, \delta_{\textbf{\textit{x}} \vee \textbf{\textit{y}}'}, \, \delta_{\textbf{\textit{x}}' \vee \textbf{\textit{y}}}, \, \delta_{\textbf{\textit{x}}' \vee \textbf{\textit{y}}'}\}$$

3-SAT:
$$\Lambda = \{\lambda_0, \lambda_1, \dots, \lambda_7\}$$

$$M(x, y, z) = \begin{cases} 0 & \text{if at least 2 of } x, y, z \text{ equal 0} \\ 1 & \text{otherwise} \end{cases}$$

"Majority Operation"

M preserves each $\delta \in \Delta_2$:

$$\begin{array}{ccc} \langle a_1, & b_1 \rangle & \in \delta \\ \langle a_2, & b_2 \rangle & \in \delta \\ \langle a_3, & b_3 \rangle & \in \delta \text{ implies} \\ \langle \textit{M}(a_1, a_2, a_3), & \textit{M}(b_1, b_2, b_3) \rangle & \in \delta \end{array}$$



But *M* fails to preserve each $\lambda \in \Lambda$

For example, with
$$\lambda = \lambda_{x \vee y \vee z'} = \{0, 1\}^3 - \{\langle 001 \rangle\}$$

$$\begin{split} \langle \mathbf{1}, \mathbf{0}, \mathbf{0} \rangle &\in \lambda \\ \langle \mathbf{0}, \mathbf{0}, \mathbf{1} \rangle &\in \lambda \\ \langle \mathbf{0}, \mathbf{1}, \mathbf{1} \rangle &\in \lambda \text{ but } \\ \langle \mathbf{0}, \mathbf{0}, \mathbf{1} \rangle &\notin \lambda \end{split}$$



Polymorphisms

Definition

Let $\delta \in \operatorname{Rel}_k(D)$ and $f \colon D^n \to D$. We say f preserves δ if

$$(a_{11},\ldots,a_{1k}),\ldots,(a_{n1},\ldots,a_{nk})\in\delta\implies$$

 $(f(a_{11},\ldots,a_{n1}),\ldots,f(a_{1k},\ldots,a_{nk}))\in\delta$



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f is an n-ary operation on D.



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Let F be a set of operations on D. Then Inv(F) denotes the set of all relations preserved by all operations in F.

Important point: $\langle D, Pol(\Delta) \rangle$ is an algebraic structure

Theorem

Let $\Gamma, \Delta \subseteq Rel(D)$. Then

 $\mathsf{Pol}(\Gamma)\subseteq\mathsf{Pol}(\Delta)\implies\mathsf{CSP}(\Delta)\leq_{\mathsf{p}}\mathsf{CSP}(\Gamma).$

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$$\mathsf{Pol}(\Gamma) \subseteq \mathsf{Pol}(\Delta) \implies \mathsf{CSP}(\Delta) \leq_{\mathsf{p}} \mathsf{CSP}(\Gamma).$$

Thus, the richer the algebraic structure, the easier the corresponding CSP



Schaefer proved that on $D = \{0, 1\}$, there are 4 key polymorphisms:

$$M(x,y,z)$$
 (majority)
 $x \wedge y$
 $x \vee y$
 $P(x,y,z) = x \oplus y \oplus z = x - y + z$

 $\langle \{0,1\},\Delta\rangle$ is tractable iff one of these four is a polymorphism of Δ



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Unfortunately, things become much more complicated when $|\mathcal{D}| > 2$.



One can go back and forth between relational and algebraic structures

$$\begin{array}{cccc} \textbf{Relational} & & \textbf{Algebraic} \\ \langle D, \Delta \rangle & \longrightarrow & \langle D, \mathsf{Pol}(\Delta) \rangle \\ \langle D, \mathsf{Inv}(F) \rangle & \longleftarrow & \langle D, F \rangle \\ \end{array}$$

$$\mathsf{CSP}\langle D, \Delta \rangle \equiv_{\mathsf{p}} \mathsf{CSP}\langle D, \mathsf{Inv}(\mathsf{Pol}(\Delta)) \rangle$$



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Perhaps the expressive power of algebra can be used to classify CSPs.



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$$\phi(x_1,\ldots,x_n) = (\exists y_1)(\exists y_2)\cdots(\exists y_m)(\delta_1(z_{1_1},\ldots,z_{1_k})\wedge\ldots\wedge\delta_t(z_{t_1},\ldots,z_{t_j}))$$

Here $\delta_1 \dots, \delta_t \in \Delta$ and every $z_{i_j} \in \{x_1, \dots, x_n, y_1, \dots, y_m\}$



Algebraic Facts

Let **A** and **B** be algebras

 ${f B}$ a subalgebra of ${f A} \implies {\sf CSP}({f B}) \leq_p {\sf CSP}({f A}).$

 ${f B}$ a homomorphic image of ${f A} \implies {\sf CSP}({f B}) \leq_p {\sf CSP}({f A}).$

$$\mathsf{CSP}(\boldsymbol{\mathsf{A}}^n) \equiv_{p} \mathsf{CSP}(\boldsymbol{\mathsf{A}})$$



Theorem (Bulatov, Jeavons, Krokhin, 2000)

If $\langle D, \Delta \rangle$ is a core and every polymorphism is essentially unary, then $\mathsf{CSP}(\Delta)$ is \mathbb{NP} -complete.

f is essentially unary if $f(x_1, ..., x_n) = g(x_j)$ for some unary g and some $j \le n$.



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Corollary

3-COLORABILITY, NONLINEAR SYSTEM, and 3-SAT are \mathbb{NP} -complete.



Informal reformulation of the dichotomy conjecture If A has some kind of decent algebraic structure then $CSP(A) \in \mathbb{P}$ otherwise CSP(A) is \mathbb{NP} -complete.

Let n > 1. An n-ary operation f is called a weak near-unanimity operation if

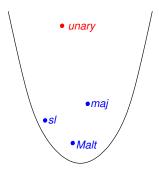
$$f(x, x, \dots, x) = x$$
 and $f(y, x, x, x, \dots, x) = f(x, y, x, x, \dots, x) = \cdots$ $= f(x, x, \dots, x, y)$

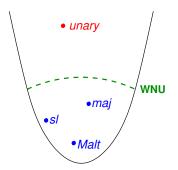
Note: no essentially unary operation is WNU

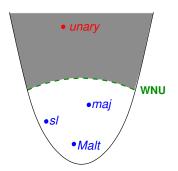


Theorem (Bulatov, Larose, Zádori, McKenzie, Maróti)

If Δ is a core and $Pol(\Delta)$ has no WNU operation then $CSP(\Delta)$ is \mathbb{NP} -complete.







Let Δ be a core. Then $\mathsf{CSP}(\Delta)$ is tractable if and only if it has a WNU polymorphism. Otherwise, it is \mathbb{NP} -complete.

Supporting Examples

 2-SAT, 2-COLARABILITY, LINEAR SYSTEM have a WNU.

Let Δ be a core. Then $\mathsf{CSP}(\Delta)$ is tractable if and only if it has a WNU polymorphism. Otherwise, it is \mathbb{NP} -complete.

Supporting Examples

- 2-SAT, 2-COLARABILITY, LINEAR SYSTEM have a WNU.
- Let **A** be an abelian group, n = |A|. Choose integers k, l with $kl \equiv 1 \pmod{n}$. Then

$$f(x_1,\ldots,x_k)=I(x_1+\cdots+x_k)$$

is a WNU operation.

Two General Techniques for Tractable Algorithms

Method 1

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Examples of cube operations:

$$P(x, y, z) = x - y + z$$

 $M(x, y, z) =$ majority

Essentially a generalization of Gaussian elimination.

Algebras with a cube operation possess "few subpowers". This algebraic property is used to prove that the algorithm terminates in polynomial time.



Method 2

If $Pol(\Delta)$ contains WNU operations v(x, y, z) and w(x, y, z, u) satisfying v(y, x, x) = w(y, x, x, x), then $CSP(\Delta) \in \mathbb{P}$.

Method 2

If Pol(Δ) contains WNU operations v(x, y, z) and w(x, y, z, u) satisfying v(y, x, x) = w(y, x, x, x), then CSP(Δ) $\in \mathbb{P}$.

Examples: majority, semilattice

Algebras with these operations have a property called "congruence meet-semidistributivity."



Current State of Affairs

The two general techniques do not cover all cases of a WNU. What to do next?

Two possible directions:

- Find a completely new algorithm.
- Combine the two existing algorithms.

I am exploring the second approach.