# **C** Programming for Physicists

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The C programming language is introduced through a set of example programs. Programs a. New concepts will be introduced through Flowcharts, Pseudocode and example C implementation.

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### 1 Introduction

#### **Aims**

- 1. Learn to solve problems by implementing computer programming structures and designs suitable for use with any structured programming language.
- 2. Cover core aspects of the C programming language.
- 3. Introduce programming with a LINUX platform.

### **Syllabus**

- Problem Analysis Strategies
  - Flowcharts
  - Pseudocode
- ANSI C
  - Basic syntax and variable types
  - Arrays, Pointers and Functions
  - The C preprocessor
  - Input/Output Operations
  - Structures and Unions
- Introduction to LINUX Programming
  - The GNU C Compiler (gcc)
  - Building executables with Make

Material taught within the syllabus is intended to be supplemented by further reading. The recommended reference material for this course is:

• "The C Programming Language", Brian W. Kernighan and Dennis M. Ritchie, Prentice-Hall, ISBN 0-13-110362-8

Further information on the GNU C compiler can be found at [1].

### 1.1 Motivation

Computers are highly useful for data acquisition, control, statistical analyses, building simulations, numerical methods, etc. While many software packages have been written it is highly likely that during the course of research or in the working world in general, software will either need to be written or modified. Those who are able to program are

therefore in an excellent position to meet research or business goals.

### 1.2 Programming

There are a great many different computer programming languages. Thankfully once the general process of programming has been understood it does not take a great deal of effort to apply it to any one of the common languages. The C programming language was chosen for this course for several reasons: (i) the basic syntax is the same as C++ and JAVA, (ii) the structured layout is similar to many common languages, (iii) the language is simple and therefore easily understood, (iv) C is used in many modern applications.

### 1.3 Writing Programs

Before a program is written it is important to know what is actually needed. For example a program that will be used for data acquisition must be tailored to the specific hardware that will be used and provide a user interface which contains all the needed functionality. Failure to properly understand the requirements of a program may result in wasted time, redesigning or patching at a later stage. Some complicated languages such as C++ are particularly unforgiving in this respect.

Once the requirements have been listed the overall aims needed from a program can be broken down into a series of pieces which can be easily converted into a computer language. During this course Pseudocode [8] and Flowcharts [7] will be used to assist with programming design.

Flowcharts provide a high level design tool which can also be used as a form of documentation. They promote a logical thought process by following a set of construction rules. It is however very time consuming to design every corner of a program with them. Flowcharts should therefore be used either to describe the overall logic of a program or particularly difficult to understand section of a program.

Pseudocode is as the name suggests code which is not really code, but is instead a way of describing a program. Writing Pseudocode provides a quick way of breaking a problem down into component parts. There is however no fixed standard and it is therefore probably best to find a way of writing Pseudocode that feels comfortable to you. Pseudocode is more a design tool than a form of documentation although much of what is written in Pseudocode will often end up as comments within a program.

In summary the process of writing a program can be summarised in 4 steps: (i) Requirements, (ii) Design, (iii) Implementation, and (iv) Documentation. When writing a program it is a good idea to have a log book and scrap paper handy to facilitate this process.

### 1.4 Programming with LINUX

Each example that will be discussed in this document can be downloaded from

http://ppewww.physics.gla.ac.uk/~wbell/3rd\_year\_c/

After downloading a set of examples to a LINUX machine they can be unpacked by using tar:

]\$ tar xvfz 3rd\_year\_c\_lab1.tar.gz

where ]\$ refers to the Linux prompt and 3rd\_year\_c\_lab1.tar.gz is a tar file of the first laboratory examples. Within each example subdirectory there is a README file describing how to build and run the example.

When developing C it can be very helpful to use an editor that colours text according to C syntax. xemacs and emacs provide this functionality. Syntax highlighting in xemacs can be enabled by clicking on Options—Syntax Highlighting at the top of the editor window, and selecting In This Buffer, Automatic, Force Rehighlight in this Buffer, Fonts and Colors. xemacs and emacs also provide many other helpful features such as parenthesise checking and tab stops positioning according to the syntax used.

### 2 Beginning to Program with C

### 2.1 A First Program

Programming languages are commonly introduced by writing a program to print a string to the standard output. The standard output is the terminal window or screen. Therefore information printed to the standard output will appear on the terminal window or screen. Before looking at the example program let us look at its design. Figure 1 illustrates example 1 in Flowchart form, Pseudocode 1 describes the program using Pseudocode and the C implementation of example 1 is given in Listing 1.



Figure 1: A flowchart describing example 1

```
main()
Print a string
Return 0 to the operating system
```

Pseudocode 1: Example 1 in pseudocode

```
/* W. H. Bell
** A very simple C program to print one line to the standard out
*/

#include <stdio.h>
int main() {
  printf ("In the beginning...\n");
  return 0;
}
```

Listing 1: The C implementation of Example 1

The execution of every program starts from a main() function. From this function other functions can be called. The return type of main() is given by the int prefix. Within the LINUX/UNIX environment the operating system expects a program to return an exit condition. The value of the return statement from the main() function is collected by the operating system and is available to a user to query. Following the execution of the program the return value can be queried by typing

#### ]\$ echo \$?

where |\$ is the LINUX prompt.

The contents of the main() function are delimited by the brackets { }, which represent a compound statement. Inside this compound statement there may be several statements each terminated by a ';' character, together with other compound statements. In this example the main() function only contains two statements: one to print a string to the standard output and one to return the exit value to the operating system. The first of these statements prints a string to the screen by calling the standard output function printf. This string is terminated by the end of line character \n. At the top of the example, the pre-declaration of the printf function is included by including the header file stdio.h. When this program compiles the compiler reads the pre-declaration of printf from the header file and leaves a call in the machine code to be resolved at link time. Above the #include statement is a comment. Comments in C can be entered using /\* \*/ to surround the comment area.¹ When the compiler compiles the code it ignores any text surrounded by /\* \*/.

<sup>&</sup>lt;sup>1</sup>The use of // comments is a non-ANSI feature and is therefore not included in this course.

### 2.2 Loops, Conditional Statements and Functions

Example 2 introduces functions, conditional statements and loops. The example reads from the standard input and performs several checks on integers and characters provided by the user. (The standard input refers to something typed into a terminal by either the keyboard or by redirection.) A Flowchart describing the main() function is given in figure 2. A Pseudocode implementation of this program is given in Pseudocode 2.

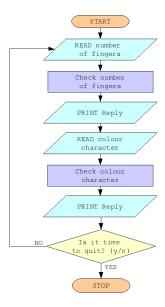


Figure 2: A flowchart describing the main() function of example 2

Functions The syntax of loops, conditional statements and functions are demonstrated by example 2. This example contains an int main() function as before. Within the main() three functions are called: numFingers, pickColour, and quitTime. Each function is pre-declared before the main() function. Each pre-declaration is a statement where the return type, and input parameter types must be given. The void type simply means that no input parameter or return value is expected. All functions must be either predeclared or declared before they are used. There are three pre-declaration statements before the main() function.

```
main()
  DO
    Check the number of fingers.
    Check the colour.
  WHILE not time to quit
numFingers()
  Print the question
  Read a number from the stdin
  Compare the number and return an answer
pickColour()
  Print the question.
  Read a character from the stdin.
  Compare the character and return an answer.
quitTime()
  Ask the user if it is time to quit (y/n)
  Collect a character from the stdin
  Compare this with y/Y and return 1 if its is time to quit
```

Pseudocode 2: Example 2 in pseudocode

```
void numFingers(void);
void pickColour(void);
bool quitTime(void);
```

The implementation of these functions is given after the main() function. Following the same syntax as the main() function the implementation of each of these three functions has a return type, a series of input types, and a compound statement enclosing the function contents. If any input parameters are present then their names must be given. These input variables are introduced with the values passed into the function when the function is called. If the implementation is not given in either the code to be compiled or libraries to be linked in a linker error will result.

It should be noted that while in this example the function pre-declarations are given before the main() and the implementation comes afterwards, the example would work just as well with the implementation before the main() and no pre-declarations. The use of pre-declarations at this point is a lead-in to the usage of header files which are later introduced in example 5.

**Conditional Statements** Common ways of writing conditional statements involve either if, if else, else or switch statements. There are other ways of construct-

ing conditional statements but these are not covered in this course. Starting with if, if else, else statements, examples of their syntax are given within the numFingers and quitTime functions of example 2. Each if statement is evaluated such that when the contents of the logic associated with an if statement inside the () brackets is true, then the code within the following compound statement is executed. if, if else, else statements operate sequentially such that each piece of logic is tested in turn. If all the logic tests fail then the statement following else is executed.

In some cases where simple sorting is needed a switch statement is a better choice than a long if, if else... else statement. An example switch statement is given in the pickColour function of example 2. While faster than an if, if else, else statement in some cases a switch statement is limited to simple cases and therefore the logic allowed can be somewhat restrictive.

Loops Several types of loops are available to C programmers. There are while, do while and for loops. Each of these loops continue to loop while a condition is true. All the logic available within an if conditional statement is also available within these conditional tests. Instances of these loop types can be found within some of the examples within this course. Within this section example 2 contains a do while loop in its main() function. This loop continues while the boolean evaluated within the while(); is true. This remains true until the function quitTime returns a true. The while loop tests on NOT quitTime return value.

### 2.3 Pointers and Arrays

Many languages use pointers implicitly such as FORTRAN and Java. In C pointers are used explicitly. This section introduces the concept of a pointer and demonstrates two basic implementations. The design of the program is given in Flowchart form in figure 3 and in Pseudocode form in Pseudocode 3.

Pointers are called pointers because they point to a memory address. A pointer can be used to access the memory address to which it points or the value contained within the memory address. The C implementation of example 3 introduces pointers. Looking at example 3 there are two distinct parts to the program: the call to the function fun and the indexing of array v[].

Functions and Pointers The function fun is declared as

```
void fun(int, int *);
```

with input parameter types int and int \*. The second input parameter is a pointer. When the function is called the memory address of p, &p is assigned to the pointer declared in fun. The importance of using a pointer in this fashion can be seen from

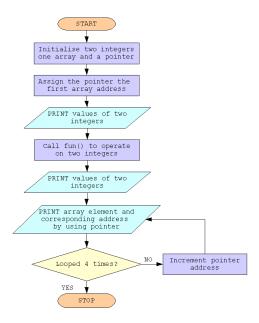


Figure 3: A flowchart describing the main() function of example 3

running the program. After calling fun, np contains the same value which it contained before the function call, while the value contained in p is the value assigned via the pointer in fun. Stepping through the program this can be explained. Both np and p are initialised in the main() with the value one.

$$int np = 1, p = 1;$$

At the point of initialisation an int sized block of memory is allocated to np and p. Then the function fun is called with the value of np (default in C) and the address of p. Within the function fun a new block of memory is allocated for the local variable np distinct from the variable contained in the main() function. This memory is given the value from the parameter np contained within main(). The value 2 is assigned to the local variable np and as the function exits, the memory of the local variable np is deleted. Therefore the value is never set within the main() function. Unlike np the value of the variable p declared within the main() is set by using a pointer. The pointer is initialised with the memory address of the variable p contained within the main() function. Then the memory address pointed to by the pointer \*p is assigned the value 2. Therefore

```
main()
    Initialise two np and p integers with 1.
    Initialise an array v with four elements.
    Initialise a pointer pv with the address of the first element of the array.

Print the values of the two integers np and p.
    CALL fun() with the value np and the address &p.
Print the values of the two integers np and p.

Iterate over the array indices using the pointer pv.
    Print the contents and address of each array element using pv.

fun(value and pointer)
    Assign a number to the local variable.
    Assign a number to the memory the pointer points to.
```

Pseudocode 3: Example 3 in pseudocode

when returning to the main() function the value contained in the memory of p is still 2.

**Arrays and Pointers** An array of type 't' is a series of memory blocks of size according to the type. Each element of the array behaves as a separate variable of the given type of the array. Array sizes are determined at compile time and therefore must be declared somewhere within a program.<sup>2</sup> In example 3 the array v is declared with four elements:

```
int v[] = \{1,2,3,4\};
```

This code is equivalent in function to:

```
int v[4];
for(int i=0;i<4;i++) v[i]=i;</pre>
```

The size of the array within example 3 is determined by the number of elements within the brackets {}.

Within example 3 the address of the first element is assigned to the pointer \*pv. It is important to note the point of declaration is the only place where the address is assigned to a pointer in this fashion. Equivalent in function but slightly longer hand, this could be written as:

```
int *pv;
pv=&v[0];
```

<sup>&</sup>lt;sup>2</sup>C does allow dynamic allocation of memory. This will be briefly demonstrated within the problem at the end of the next section.

Once the pointer has been assigned the memory address of the first element of the array v[0] it can be used to access the elements as demonstrated in the example and illustrated in figure 4. The action of incrementing the memory address of the pointer

pv++;

causes it to point at the next element of the array.

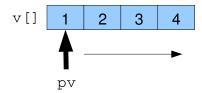


Figure 4: An illustration of a pointer being used to iterate over array elements, where the blue boxes signify the sequential sections of memory containing the values stored in the array.

### 2.4 Command Line

A C program can either receive command line input at execution time or by reading input from a file or other data source. This example demonstrates how command line arguments are passed into a C program when the program is executed. The design of the program is given as a Flowchart in figure 5 and as Pseudocode in Pseudocode 4.



Figure 5: A flowchart describing example 4

When programing C on a LINUX platform the main() function is normally implemented in one of two ways:

int main(void)

```
main(command line arguments)
  Print the number of command line arguments
  Loop over the command line inputs
    Print each command line input
```

Pseudocode 4: Example 4 in pseudocode

and

```
int main(int argc, char *argv[])
```

The second form allows command line input to be passed into the program. The operating system allocates the memory for \*argv[] and initialises it with the input command line arguments. The first element of the argv array contains the name of the executable. The second element exists only if there is a argument following the name of the executable, etc. The parameter argc is initialised by the operating system with the number of elements in the argv array. While it may seem odd to include the name of the executable in this list it can infact be very useful. For example, if a program has been written to do several tasks a symbolic link can be used to control which task it performs. The logic of this can be tested out using example 4 by typing

```
]$ ln -s command_line.exe another_cmd.exe
]$ ./another_cmd.exe
```

A simple test on the value of argv[0] could then be used to do something else.

### 2.5 File Access

Most programs will need to save or read data from disk or another input/output device. Example 5 demonstrates how some simple data can be written to and read from an ASCII file. The design of the main() is given in figure 6 and the complete program is described in Pseudocode 5 and 6.

The program starts by checking the command line arguments. Then either file\_write or file\_read is called. The functions file\_write and file\_read are pre-declared in the header file file\_io.h and implemented in file\_io.c. When this code is compiled the resultant machine code main.o contains un-defined references to these functions. Then at link time the machine code in file\_io.o and main.o is linked together to produce the final executable. The practical process of building this executable is discussed in section 2.5.1.

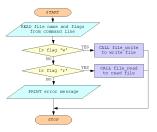


Figure 6: A flowchart describing the main() function of example 5

```
main(command line arguments)
  Check the command line arguments
   Make sure the file name is given
   Check for the input flag and if not given set the default to
   write.
```

IF the input flag is write, write the specified file. ELSE IF the input flag is read, read the specified file. ELSE report an error

Pseudocode 5: The main() function of example 5 in pseudocode

```
file_write(file name)
  Open an output file.
  IF the file was successfully openned
   LOOP from 1 to 20
      Print the value into the file.
      IF the value is a multiple of 5 then print a newline.
      ELSE print a space.
 ELSE
   Report an error.
file_read(file name)
  Open an input file.
  IF the file was successfully opened
    Get a character until the end of file or until the buffer is full.
    IF the character is not a space or a newline
      Copy character into buffer.
   ELSE IF the buffer contains something
      Add a string terminating character.
      Scan the contents into an integer.
      Print the integer.
      IF the integer is a multiple of 5 print a new line.
      Reset the buffer.
 ELSE
   Report an error.
```

Pseudocode 6: The file\_write() and file\_read() functions of example 5 in pseudocode

The file\_io.h header file of example 5 contains three pieces of precompiler syntax which surround the function pre-declarations.

```
#ifndef FILE_IO_H
#define FILE_IO_H

void file_write(char *filename);
void file_read(char *filename);
#endif
```

The purpose of these statements is to prevent the functions from being pre-declared twice. While this does not happen within this example, double declaration which can result in compiler errors is more of an issue with more complicated programs. It is therefore a good idea to adopt the use of these precompiler statements at an early stage.

The functions file\_write and file\_read are implemented in file\_io.c. The file\_write function calls fopen to open a file for writing

```
outputfile = fopen(filename, "w");
```

This command returns a *file pointer*, which is a pointer to a **struct typedef** called **FILE**. **FILE** contains information about the file which needs to be passed between the different file I/O function calls. If the file cannot be opened for writing then **null** is returned. This is logically equivalent to false and can therefore be used to check if the file was opened correctly or not.

```
if (outputfile) {
```

Once the file has been opened successfully data can be written in ASCII format by calling the fprintf function. This function follows the same syntax as the printf function with the exception of the *file pointer* as the first argument. When all the data have been written to the file fclose is called to flush any remaining data in memory to the file and to close the file. If fclose is not called, then when a program exits the file will only be partially written to disk.

Once the output file is present on disk the function file\_read is called to read the data back in and print them to the standard out. file\_read starts by opening a file for reading

```
inputfile = fopen(filename, "r");
```

Then single characters are read from the file until the End Of File (EOF) is reached or the character buffer is full.

This is much more robust than just using fscanf to read data, which can easily result in errors or crashes. If the character is not a space or a new line it is appended to

the character buffer. When a space or a new line is found then if the buffer contains something it is scanned into an int by calling

```
sscanf(str, "%d", &i);
```

where &i is the memory address of i and %d tells sscanf to treat the string as an integer. After each int is read the data are printed back to the standard output in the same form as they were saved to disk. Finally the file is closed.

### 2.5.1 Make

As the number of files involved or dependencies increases simply typing gcc would become an lengthy and complicated task. Therefore from this example onwards Make[2] is used to aid with compilation and linking of examples. The Makefile in example 5 has three targets which can be called from the command line: file\_io.exe, clean and veryclean. The default target is the first one file\_io.exe. The default target it called by typing

#### 1\$ make

The other targets are called by using the target name

### ]\$ make veryclean

Above the default target are the definition and initialisation of three variables

```
CC=gcc
TARGET=file_io
OBJECTS=main.o file_io.o
```

The last one of these is a list. When the default target is called the dependencies \$(OBJECTS) are checked. If these files are not found then Make looks through the file for a suitable target to make these files with. If there is a .c file with the correct name it calls

This target compiles the .c file into a .o file. Then when all of the \$(OBJECTS) are present on disk Make executes the rest of the default target

```
$(TARGET) . exe: $(OBJECTS)

@echo "**"
```

```
@echo "** Linking Executable"
@echo "**"
$(CC) $(OBJECTS) -o $(TARGET).exe
```

which links the object files together to make the executable.

When any of the .c files referred to in the Makefile are present but are newer than the .o file of the prefix name, Make just rebuilds the files concerned and completes the link step. When any of the \$(OBJECTS) are newer than file\_io.exe, Make just completes the link step. This can be tested out by using touch

```
]$ make
]$ touch main.c
]$ make
]$ touch file_io.o
]$ make
```

More examples of Make syntax are given in later examples.

### 2.6 Problem

While working in research it can often be the case that a piece of equipment or software produces its output in the wrong form for use as an input to another application. The program problem/generator/generator.c writes random numbers into a sample.txt file. Follow the instructions in generator/README file to produce a sample.txt. Then write a program to convert sample.txt into a Commar Separated Values file (CSV)[6] suitable for use as input to a spreadsheet. Run your program and read the resultant output into a spreadsheet and plot the Value column as a histogram.

Start by drawing a simple Flowchart outline of the program. Then write the program in Pseudocode . Finally write your program in C using code from each of this section's examples as necessary. Remember to add comments.

### 3 Data Structures and Linking with FORTRAN

In this section more complex data structures struct and union will be discussed. An example of how to interface to FORTRAN77 code will be given and the section finishes with a complicated example including much of the syntax introduced so far.

#### 3.1 Pointers and Structs

The purpose of example 6 program is to demonstrate struct syntax and to show how arrays and structs can be passed into a function. The program is described by Pseudocode 7.

```
main()
    Instantiate two ints, an array of two ints and two structs.
    Assign 1 to all data members
    Print the values contained in the ints, the array and the structs
    Call fun() to modify some of the values
    Print the values contained in the ints, the array and the structs

fun(int np, int *p, int *arr, struct st dat, struct st *dat_ptr)
    Change the value of the local variable np
    Change the value in the memory p points to.
    Change the values of the two elements of arr
    Change the data members of the local struct dat
    Change the data members of the struct dat_ptr points to.
```

Pseudocode 7: Example 6 in pseudocode

At the top of the file pointers2.c a struct is defined

```
struct st {
  int i;
  int array[2];
};
```

where st is the name of the struct. The data members of the struct are enclosed in the {} brackets. This definition can be given in a header file instead of in a source file. The definition defines the struct but does not create an instance of it. Then in the main() two st structs are instantiated

```
struct st dat, dat_p;
```

and their data members are initialised.

```
dat.i=1;
dat.array[0]=1;
```

```
dat.array[1]=1;
dat_p.i=1;
dat_p.array[0]=1;
dat_p.array[1]=1;
```

The syntax is *<instantiation>.<data member>*. Each instantiation of a struct is stored in a separate block of memory. Unlike an array the data members can have different lengths. The total memory used by a struct instantiation is determined by the sum of the memory used for the data members. The order of the struct members in the struct definition determines the order of their allocation in memory. The member types can include other structs, unions, arrays and basic variables etc.

After the structs, basic variables and the array have all been initialised the function fun() is called. This function is called with the value of np, the address of p, the array arr, the value of dat and the address of dat\_p. Notice that the name of the array arr is actually equivalent to passing an address of the first element &arr[0]. Therefore the function declaration and implementation of fun includes this as int \*. Inside the function fun each of the variables is given a different value. The syntax of accessing data members of a struct pointer is pointer name> - ><data member>

```
dat_ptr->i=5;
or (*<pointer name>).<data member>
(*dat_ptr).i=5;
```

When the function fun is called the argument struct st dat caused a new instantiation of the struct st to be made.

```
void fun(int np, int *p, int *arr, struct st dat, struct st *dat_ptr)
{
```

The memory assigned to this instantiation is local to the function fun and will go out of scope when the program leaves this function. When the function is called the data members of dat are initialised with the values of the data members of dat from the main(). The behaviour is therefore similar to the variable np.

Unlike dat, the address of dat\_p is passed into the function fun. The pointer struct st \*dat\_ptr is therefore initialised with this address. When the data members of the object that \*dat\_ptr points to are modified

```
dat_ptr->i=5; dat_ptr->array[0]=6; dat_ptr->array[1]=7;
```

then the change is still present when the execution returns to the main().

### 3.2 Binary I/O and Unions

In example 7 the data concerning several fundamental particles are written in binary form into an output file. Then the program reads these data back and prints out the

7th particle data record. The design of the program is given in Pseudocode 8.

```
main()
  Print the size of one union entry.
  Print the size of each union member.
  Write 10 records of fundemental particles to a binary file.
  Read the 7th record back from the binary file.
  Print the values of the 7th record.
status write_records()
  Create an array of 12 records.
  Initialise the array of records with fundemental particle data.
  Open a file for writing.
  Write each record element out in binary form.
  Close the file.
status find_record()
  Open an input file.
  Fast forward to the 7th record.
  Read the 7th record.
  Close the file.
```

Pseudocode 8: Example 7 in pseudocode

At the beginning of the main() a record dat is instantiated.

```
record dat;
```

record is a typedef declared in the header file data\_record.h.

```
typedef entry record [4];
```

This statement means that a record is a typedef of an array of entrys of length 4. Therefore

```
record dat;
is equivalent to
entry dat [4];
```

The type entry is itself a typedef of a union

```
typedef union {
  int id;
  double mass;
  char name[16];
  int charge;
} entry;
```

In the previous example structs were declared with the syntax:

```
struct st {
};
```

This syntax is allowed with unions and the union syntax used in this example is allowed with structs.

```
typedef struct {
} st;
```

The advantage of the typedef form used in this example is that the union prefix does not have to be carried around the code. It is therefore much more common that the typedef form of a struct or union definition is used.

A union contains a set of members which are listed within the {} brackets. The members of a union share the same memory allocation. The size of the union is therefore set by the largest member. This can easily be demonstrated by running example 7. The syntax for accessing the members of a union is the same as the syntax used for accessing the members of a struct.

In this example an array of the entry union is created with 4 elements, this is a record. The record stores a particle's id, mass, name, and charge. To make the code more readable a set of #define statements are used instead of the indices.

```
#define RECORD_ID 0
#define RECORD_MASS 1
#define RECORD_NAME 2
#define RECORD_CHARGE 3
```

When the code compiles the pre-compiler replaces each definition with its value. Then the compiler turns the result into machine code. It is a common convention that #define statements use all uppercase letters to avoid confusion with real variables. What follows the #define NAME does not have to be a simple number, the precompiler just does a find and replace.

The first use of the precompiler definitions is in write\_records. In this function an array of records is instantiated

```
record particle_data[12];
```

and each entry is filled by simple assignment.

```
particle_data[0][RECORD_ID].id = 22;
particle_data[0][RECORD_MASS].mass = 0.E+00;
strcpy(particle_data[0][RECORD_NAME].name,"gamma");
particle_data[0][RECORD_CHARGE].charge = 0;
```

This demonstrates that the array index contained in the typedef record statement comes after the array index defined by defining the particle\_data array.

Following the initialisation of the particle\_data array the data are written to a binary file. The binary file is opened in the same way as the ASCII file in example 5.

```
file_ptr = fopen(particle_file, "w");
```

This time however the error messages are handled by printing them to the standard error. To print to the standard error the **fprintf** function is used with the standard error *file pointer* stderr.

```
fprintf(stderr," Error: unable to open \'%s\' for writing.\n", particle_file);
```

The standard error is printed to the console or shell window in the same manner as the standard output but is contained in a different stream. When running a program on LINUX the standard output an be redirected to a file.

### ]\$ ./prog.exe > output

This does not redirect the standard error though, which can be left for the user to read.<sup>3</sup>

Once the file has been opened the particle\_data records are written to it in binary form.

```
fwrite(&particle_data[i][j], 16, 1, file_ptr);
```

The arguments of fwrite are the address of one union instantiation, the size of the union, the number of union instantiations to be written and the *file pointer* to which the data should be written. Since the size of the union is set by the largest member each data element is the same size. This means that the code to write out these data is very simple and only requires two loops over the fwrite statement.

After the data have been written to disk find\_record is called to find and read the 7th record. find\_record opens the binary file in the same way as the ASCII file was opened in example 5.

```
file_ptr = fopen(particle_file,"r");
```

Then after checking the file was opened successfully it fast forwards to the correct position in the file

```
if(fseek(file_ptr, (long)(sizeof(*dat)*offset), 0) != 0)
```

where fseek returns a non-zero value if the seek fails. This then leaves the file-position indicator set to point at the value given by the offset. The record is then read by calling fread.

<sup>&</sup>lt;sup>3</sup>It is possible to redirect both standard error and standard output to one file.

```
fread(dat, sizeof(*dat), 1, file_ptr);
```

Finally in the main() these data are printed to the standard out

```
printf("\t Id \t Mass \t Name \t Charge \n");
printf("\t %d \t %3.3e \t %-12s \t %d \n",
    dat [RECORD_ID].id,
    dat [RECORD_MASS]. mass,
    dat [RECORD_NAME].name,
    dat [RECORD_CHARGE].charge);
```

Throughout example 7 possible errors are caught and result in a non-zero value being returned to the operating system. When writing a program it is important to make sure the implementation is able to prevent crashes by handling error conditions properly. This means that the program should exit in a controlled manner and provide the user with a description of the error, rather than a cryptic message or nasty crash.

### 3.3 Linking with FORTRAN77

Although many modern programs have been written in C it is sometimes very useful to be able to link C code to another programming language. When the code to be linked to is compiled into machine code this can be achieved by knowing how the two compilers concerned work. For example, FORTRAN77 a programming language often used for physics and engineering applications, can be compiled by g77 into object files. These object files can be browsed with nm.

C code is also compiled into object files, which can also be browsed with nm.

```
00000000 T main
000000ed T mult_a__
U sprintf
```

All that is needed to join FORTRAN77 with C is for the undefined references in FORTRAN77 or C to be present in the object files generated from the other language. In this example call\_back\_, commons\_, forcom\_ and mult\_a\_ are linked between the two languages. The other undefined symbols can be found in the system libraries. When g77 compiles the FORTRAN code it uses a lower case version of the name and appends one underscore to the end of the name or two underscores if the name already contains an underscore.<sup>4</sup>

Example 8 demonstrates all of the features of linking C and FORTRAN77 together. The design of the program is given in Pseudocode 9.

```
main()
  Fill the FORTRAN common block with numbers and a string.
  Print the contents of the FORTRAN common block with FORTRAN code.
  Multiply a number and print a string by calling the FORTRAN code.
fill_common()
  Fill the int and float arrays of the common plot with
    sequential numbers.
  Fill the FORTRAN string with a C string.
mult_a__()
  Multiply the input value by 10 and return it.
SUBROUTINE COMMONS
  Print the contents of the common block.
FUNCTION CALL_BACK
  Print the input string.
  Call the C function to multiply the input value by 10.
  Print the resulting value and return it.
```

Pseudocode 9: Example 8 in pseudocode

There are some important differences to point out between the two languages. Firstly C strings are character arrays terminated by the '\0' character. This means that the maximum length of a string is equal to the number of elements of the character array minus one. In FORTRAN character arrays are also used to store strings but unlike C '\0' is not used. The maximum length of a string in FORTRAN is therefore set by the

<sup>&</sup>lt;sup>4</sup>This behaviour can be controlled by using compiler options.

number of elements in the character array. FORTRAN keeps track of the length of a string by implicitly passing its length with the string. When FORTRAN is compiled with g77 these implicit variables become explicit in the machine code output. Therefore when calling a FORTRAN function from C, the lengths of each of the strings must follow each of the character arrays:

```
float call_back__(float *,char *, int);
```

where the int is the implicit string length variable.

The allocation of memory to FORTRAN arrays is different to that of C. For example when a two dimensional array is declared in FORTRAN

```
INTEGER INTARRAY(3,2) REAL REALARRAY(2,3)
```

in C the array indices of the equivalent memory mapping are:

```
int intarray[2][3];
float realarray[3][2];
```

The first index of a FORTRAN array is by default 1, but C always uses 0 as the first index of an array. These differences are particularly important when dealing with common blocks. In the FORTRAN include file FORTRAN. INC a common block is declared.

```
INTEGER INTARRAY(3,2)

REAL REALARRAY(2,3)

CHARACIER*50 SOMESTRING

COMMON/FORCOM/INTARRAY, REALARRAY, SOMESTRING
```

This defines the common block and creates one global instance of the common block in memory. In a similar fashion to a struct, the order of the member variables denotes there order in memory, and the total size of the common block is just the sum of the sizes of the members. Once a common block has been declared FORTRAN or C code can access its data members. The FORTRAN common block can be included in several different FORTRAN files, but only one instance of it will be created in memory. This global memory can be accessed from C by creating a global un-resolved struct of the correct name.

```
typedef struct {
  int intarray[2][3];
  float realarray[3][2];
  char somestring[50];
} forcom;

extern forcom forcom_;
```

The extern command means that the compiler will look through the object files for the memory definition of forcom\_ and link to it, rather than allocate another block of memory. Without the extern prefix the memory allocated in the C program would be different to that of the FORTRAN common block. The order, types and sizes of the C struct must match the order, types and sizes of the FORTRAN common block.

In addition to the memory mapping and variable type name differences, FORTRAN uses pointers implicitly in function calls. A function of the form

```
FUNCTION CALLBACK (A, NAME)
IMPLICIT NONE
REAL A, C, CALLBACK, MULT-A
CHARACIER*(*) NAME
```

is therefore equivalent to

```
float call_back_-(float *,char *, int);
```

The last variable in the C version of this function is the length of the string, which is implicitly present in the FORTRAN code.

#### 3.4 Sine Wave Generator

As programs become larger the initial design becomes more important. Therefore to encourage thought about program structure the example programs given in this course will become more and more complicated. In example 9 there are 9 C files containing a total of 300 lines. When writing a program of this size it needs to be clear what the design requirements and components are.

#### Design

**Requirements** A program to either generate sine wave spectra and save them to a binary file or read the spectra from a binary file. The last spectrum either written to or read from the file should be plotted with gnuplot [3].

### Components

- main implement in main.c

  Handles the users command line arguments and selects either write or read with
  the selected number of events if this is given.
- gen\_data implement in gen\_data.c Generates the sine wave from a flat random number generator
- gen\_value implement in gen\_data.c

  A function to generate a random floating point number between two limits using

a flat random number generator.

- write\_data implement in file\_io.c
   A function to write a data sample to a binary file
- read\_data implement in file\_io.c

  A function to read a data sample from a binary file
- sample define in gen\_data.h
  A struct to contain sine wave samples.
- plot\_data implement in plot\_data.c
   A function to plot a data sample with gnuplot
- gnuplot implement in gnuplot.c

  A function to provide an interface with gnuplot by using a system call.

### Discussion of the implementation

The implementation of example 9 is described in Pseudocode 10, 11, 12 and 13.

This program uses several concepts that were introduced with previous examples. The discussion of this example therefore only covers additional points.

The program starts by checking if a binary file is to be written or read. It then checks the number of events which should be either written or read. Following this the program writes or reads sine wave data to or from the binary file and plots the last sine wave sample with gnuplot. In example 9 the each sine wave sample is stored in an instantiation of a struct typedef sample.

```
typedef struct {
  float x[MAX.PTS]; /* The x value */
  float y[MAX.PTS]; /* The y value */
  int pts; /* Number of points in the sample */
} sample;
```

In the main() an instance of sample is declared.

```
sample dat;
```

Then dat is either filled with generated data

```
gen_data(&dat);
```

or with data read from a file.

```
read_data(file_ptr , &dat);
```

While sizes of the data member arrays x and y are fixed the number of elements used varies. Therefore the data member pts is use to keep track of the number of useful elements in memory. When these data are written to file the record length of each sine wave sample varies in accordance with the value of pts. The value of pts is therefore written to the file for each sine wave sample. An illustration of the resultant file structure is given in figure 7.

ne	nevents pts			Х	у	Х	у	Х	у	Х	у	Χ	у		
X	у	Х	у	Х	у	Х	у	Х	у		pts	_	Х	у	Х
У	Х	у	Х	у	х	у	Х	у	pts		Х	у	Х	у	
X	у														

Figure 7: An illustration of the binary file structure used in example 9

The last sine wave sample that is either read from file or generated is plotted with gnuplot. The main() calls plot\_data, passing it a pointer to the last sample. plot\_data then writes a temporary file for gnuplot to read. This file has to be of the form: "<number> ". Then after plot\_data has written the file the gnuplot command is assembled.

```
sprintf(gnuplot_command, "plot \'%s\'\n", filename);
```

(sprintf follows the same syntax as printf but starts with a pointer to a string buffer.) The command assembled corresponds to what would be typed at the interactive gnuplot command line to plot these data. This command is passed to the gnuplot function to plot the data. The gnuplot function inserts another string in front of the gnuplot command

```
sprintf(syscommand, "echo \"%s\" | gnuplot -persist", gnucommand);
```

and uses a system call to execute the command in a LINUX shell.

```
system(syscommand);
```

The affect of the "-persist" is that gnuplot continues to run after the C program has exited.

```
main(commmand line inputs)
  Check the command line inputs
    IF the file name and flag are not given report an error
    IF the flag is -w check for the number of events
      IF the number of events has not been given set it to 10 events.
      ELSE read the number of events.
      Open an output file.
      Write the number of events into the file as a header.
      Generate the required number of events needed.
         Write each one to the output file.
      Plot the last event with gnuplot.
      close the output file.
    ELSE IF the flag is -r open an input file.
      Read the number of events, recorded at the start of the file.
      IF the number of events has not been given use the number at the
        top of the file.
      ELSE check if the argument is a number and if it is set the
        number of events to read to be the number given.
      IF the number of events selected is greater than the number of
        events in the file
        Set the number of events selected to be the number of events
          in the file.
      Read the events from the file.
      Plot the last event.
      Close the input file.
  ELSE return an error reporting the flag is invalid.
```

Pseudocode 10: Example 9 in pseudocode

```
gen_value(limits)

Generate a random float between two limits using a flat random distribution.

Return this value

gen_data(data sample pointer)

Set the limits for the random parameters: number of points, a, b, and c.

Generate values for: the number of points, a, b, and c.

Use the number of points to determin the step size, where the range of x is 0 to 2PI.

Use the step size, and the values for a, b, and c to generate the sine wave event.
```

Pseudocode 11: Example 9 in pseudocode

```
write_data(file pointer, data record)
  Write the number of points
  Loop over all points
    Write the x value
    Write the y value

read_data(file pointer, data record)
  Read the number of points
  Loop over all points
  Read the x value
  Read the y value
```

Pseudocode 12: Example 9 in pseudocode

```
plot_data(data record)
   Open a temporary output file.
   Loop over all points
    Write "x y" as text to the file.
   Create the gnuplot command.
   Plot the data with gnuplot.
   Remove the temporary output text file.
```

Pseudocode 13: Example 9 in pseudocode

### 3.5 Problem

Programs are often written to interface with hardware, for slow control or data acquisition. Since the LINUX lab does not contain any external hardware this problem concerns monitoring the computer itself.

A program is provided which requests more and more memory by calling malloc. After some period of time the program then frees the dynamically allocated memory by calling free. Write a program to monitor the total memory used every second for a given number of minutes. The program should finish by plotting the total memory usage as a function of time. Once the pseudocode and implementation has been finished run the monitoring program at the same time as the memory loading program:

```
]$ ./system_monitor.exe 2 &
]$ ../problem/resource_hog/resource_hog.exe
```

where 2 is the number of minutes the monitoring program should run.

#### Hints

The memory allocation status can be obtained by calling sysinfo

```
int sysinfo (struct sysinfo *info)
```

This function can be called by including

```
#include <sys/sysinfo.h>
```

This include file also includes a definition of the sysinfo struct:

```
struct sysinfo {
                              /* Seconds since boot */
  long uptime;
  unsigned long loads [3];
                             /* 1, 5, and 15 minute load averages */
  unsigned long totalram; /* Total usable main memory size */
                            /* Available memory size */
  unsigned long freeram;
  unsigned long sharedram; /* Amount of shared memory */
  unsigned long bufferram; /* Memory used by buffers */
  unsigned long totalswap; /* Total swap space size */
  {\bf unsigned\ long\ freeswap}\;;\quad /*\;\; swap\;\; space\;\; still\;\; available\;\;*/
  unsigned short procs; /* Number of current processes */
unsigned long totalhigh; /* Total high memory size */
  unsigned long freehigh; /* Available high memory size */
  unsigned int mem_unit; /* Memory unit size in bytes */
  char _f[20-2*sizeof(long)-sizeof(int)]; /* Padding for libc5 */
```

Use the sleep command used in problem/resource\_hog/main.c to sleep for 1 second between measurements. This will prevent the monitoring program from using up a lot

of CPU, which would affect the results. More information can be found in the manual page by typing

]\$ man -s 3 sleep

Use the time command used in problem/resource\_hog/main.c. More information can be found in the in the manual page by typing

]\$ man time.h

### 4 Simple Analyses

During previous sections much of the C programming language has been introduced. This section is therefore dedicated to solving more complicated problems.

### 4.1 Histogramming Data

When processing large volumes of data it is often very useful to accumulate data values in histograms. Histograms provide an important tool for observing fluctuations in a data sample. For example, a histogram could be used to find a mass peak above a flat background.

Example 10 is a program to histogram the output of two random number generators. Its design and implementation are discussed in the following sub-sections.

### Design

**Requirements** A program to histogram random numbers generated according to uniform and Gaussian distributions. The program should provide these random numbers by using the integer random number generator rand from stdlib.h. The histrogramming code should provide visual output using gnuplot.

#### Components

- main implement in main.c: create two histograms and fill them with 10000 uniform and Gaussian random numbers respectively. Display the results with gnuplot.
- Provide histogram functionality.
  - hist\_create implement in histogram.c: a function to create a histogram
  - hist\_book implement in histogram.c: a function to add a value to an existing histogram
  - hist\_plot implement in histogram.c: a function to plot a histogram's contents using gnuplot.
  - hist\_entry define in histogram.c: a struct to contain the information of each histogram.
  - gnuplot implement in gnuplot.c: A function to provide an interface with gnuplot by using a system call.
- Provide random number functionality.
  - set\_seed implement in random\_dist.c: a function to set the seed of the

random number generator.

- random\_dist\_flat implement in random\_dist.c: a function to return a floating point random number between 0. and 1.
- random\_dist\_gaus implement in random\_dist.c: a function to return a floating point random number following a Gaussian distribution with a given sigma.

### Discussion of the implementation

The implementation of example 9 is described in Pseudocode 14, 15, and 16.

```
main()
Create two histograms.
Loop for 10000
Generate a random number following a Gaussian distribution.
Histogram the Gaussian random number.
Generate a random number following a uniform distribution.
Histogram the uniform random number.
Plot both histograms using gnuplot
```

Pseudocode 14: Example 10 in pseudocode

The program starts by creating two histograms.

```
hist_create("Gaus",20,-3.0,3.0);
hist_create("Flat",20,0.0,1.0);
```

The hist\_create function assigns the histogram information to members of an element of the h\_dat array. The variable num\_hist is used to keep track of which elements of h\_dat array have been filled. Both h\_dat and num\_hist are globally available within histogram.c.

```
static int num_hist = 0;
static hist_entry h_dat[MAX_HIST];
```

The static prefix means that no function outside histogram.c is able to access these variables. Without the static prefix the variables could be accessed by a function implemented outside histogram.c provided an external instantiation was used. An example of an external instantiation is given in example 8.

The advantage of instantiating h\_dat and num\_hist globally in histogram.c is that they do not go out of scope. Therefore every time one of the histogram functions is called h\_dat and num\_hist are still in memory.

The variable h\_dat is an array of typedef struct hist\_entry, which is defined in histogram.c rather than in a header file. The reason for this is that hist\_entry is

```
hist_create(histogram name, number of bins, lower limit, upper limit)
  Fill static memory with histogram information.
  Calculate bin size and store it in static memory.
  Initialise all bins to be 0.
  RETURN this histogram's index
hist_book(histogram index, value, weight)
  IF the value is less than the lower limit increment the underflow
    bin by the weight.
  ELSE IF the value is greater or equal to the upper limit increment
    the overflow bin by the weight.
  ELSE find which bin the value is inside and increment its value by
    the weight.
hist_plot(histogram index)
  Create a temporary file for gnuplot
  Open the temporary file
  Save the data as "<value> <value>" to the file.
  Assemble a gnuplot command to plot the histogram.
  Call gnuplot.
  Remove the temporary file.
```

Pseudocode 15: Example 10 in pseudocode

intended just for storing histogram information. When writing a large program it is highly advisable to break it down into building blocks. In this program the histogram functions and the associated data are one building block.

Once the histograms have been created a Gaussian random number is generated by calling random\_dist\_gaus(). When this function is called it either generates two random numbers and returns one, or uses the spare one stored from the last time it was called. To store the spare random number random\_dist\_gaus() uses two static variables:

```
static int random_dist_gaus_status = 0;
```

and

### static double spare\_num;

The variable random\_dist\_gaus\_status is defined outside the function random\_dist\_gaus() as static. It is therefore private to the functions within random\_dist.c. The variable spare\_num is defined as static within the function random\_dist\_gaus(). Unlike normal local variables the variable spare\_num is defined once in memory and does not go out of scope when the program leaves the random\_dist\_gaus() function. The value stored in spare\_num at the end of random\_dist\_gaus() is therefore available when the function is next called.

```
random_dist_flat()
Generate an integer random number
Use the limit of the integer to calculate a floating point number
between 0 and 1.
RETURN the floating point number.

random_dist_gaus(double sigma)
IF a spare random number is not present
Generate two random numbers within the unit circle.
Use a Box-Muller transformation to get two Gaussian random
numbers.
Save one of the random numbers in static memory and RETURN the
other.
ELSE
RETURN the spare random number.
```

Pseudocode 16: Example 10 in pseudocode

There are some program operations that can cause a serious error. For example, if an array index is outside of the arrays memory allocation or if a function is passed a variable outside of the limits allowed. Wherever program structures or function calls are used that might cause such an error they should be protected. In example 10 there is a simple catch to prevent an array index from going out of bounds.

```
if(i < 0) {
   fprintf(stderr, "CRITICAL ERROR: something has gone very wrong!\n");
   exit(1);
}
h_dat[h_index].bins[i] += weight;</pre>
```

The program should not ever get inside this if statement. If it does there is a serious bug in the code. The exit(1) function call causes the program to terminate and return 1 to the operating system. This is a rather extreme case and other error prevention code may not need to cause the program to exit. For example, if a section of code is written to calculate the hypotenuse of a right angled triangle, then the code should catch the case where the sides have no length.

```
double a, b=0., c=0.;
double a_sqd; /* a squared */
a_sqd = pow(b,2.0)+pow(c,2.0); /* b^2 + c^2 */
if(a_sqd<=0) { /* Prevent a possible sqrt error */
    a = 0;
}
else {
    a = sqrt(a_sqd);
}</pre>
```

After the histograms have been filled hist\_plot is called to plot this histogram using gnuplot. In example 9 the temporary file was written in the present working directory with a fixed name. This could cause problems were the present working directory can not be written to or when two instances of the program are running in the same directory at the same time. To solve both of these issues it is common that temporary files are written in the tmp directory with unique file names. Rather than write a piece of code to produce unique file names the program calls mkstemp. This function is part of stdlib.h and creates a unique file following the supplied template. The file is left open and a file descriptor is returned. A file stream is then opened with this file descriptor.

```
tmpfile = fdopen(file_descriptor, "w");
```

Data are then written to the file and the file and file descriptor are closed with fclose. *File descriptors* are low level I/O because they are closer to the underlying operating system.

The function random\_dist\_gaus contains three mathematical functions: pow, sqrt, and log. These functions are all defined in the header file math.h and require the library libm.a to be linked in to the final executable. libm.a is a standard library and is therefore already in the search path for the linker. (If the library was not in the standard search path a -L<directory name> would have to be added to the link line.) The libm.a library is included in the link step by simply adding -lm to the link line.

### 4.2 Problem

In lab3/problem/generator is a program to produce B meson pairs using the PYTHIA[5] event generator. The program should be compiled and run as specified in the README file to generate at least 5000 events. (On the LINUX cluster the data file has already been made. Please use this data file rather than re-run the generator program.)

Write a program to read the HEPEVT event records from the binary file data/pptobbar\_hepevt.dat. Histogram the transverse momentum  $(p_T)$  of the B mesons and their proper lifetime  $\tau_{true}$  as the length  $c\tau_{true}$ . Calculate the mean value of  $c\tau_{true}$  for the data sample and compare this with the PDG[4] world averages given in table 1.

Meson	$c\tau \; (\mu \mathrm{m})$
$\mathrm{B}^{\pm}$	491.1
$ brack B^0$	458.7
$\mathbb{B}_s$	439

Table 1: A table of the mean lifetimes of B mesons expressed as  $c\tau_{true}$ , taken from the PDG.

Start by writing down a Pseudocode implementation. Then implement a solution. Remember to comment your code. Marks will be given for pseudocode and implementation.

### **Background Information**

The transverse momentum  $p_T$  is defined as

$$p_T = \sqrt{p_x^2 + p_y^2}$$

where  $p_x$  and  $p_y$  are the x and y components of the momentum respectively.

The transverse displacement of the secondary vertex with respect to the primary vertex can be calculated from

$$L_{xy} = \sqrt{v_x^2 + v_y^2}$$

where  $v_x$  and  $v_y$  are the x and y components of the vertex position respectively.

The true lifetime  $\tau_{true}$  is related to the displacement of the secondary vertex, as stated in equation 1.

$$c\tau_{true} = L_{xy}^B \frac{m_B}{p_T^B},\tag{1}$$

where  $m_B$  is the mass of the B meson,  $p_T^B$  is the transverse momentum of the B meson and  $L_{xy}^B$ , is the displacement of the secondary vertex from the primary vertex within the transverse plane.

### Hints

Start by reading over problem/generator/main.c and its associated Makefile.

The HEPEVT event record is defined in include/hepevt.h.

```
/* Maximum number of particles */
#define NMXHEP 4000

typedef struct {
   int nevhep; /* The event number */
   int nhep; /* The number of particles in the event */
   int isthep [NMXHEP]; /* Particle status code */
   int idhep [NMXHEP]; /* Particle identifier (PDG standard) */
   int jmohep [NMXHEP] [2]; /* Mother index/indices ranges */
   int jdahep [NMXHEP] [2]; /* Daughter index/indices ranges */
   double phep [NMXHEP] [5]; /* Four vector and mass */
   double vhep [NMXHEP] [4]; /* Production vertex */
} HEPEVT;
```

Documentation of the HEPEVT member variables is given in include/hepevt.h. The decay vertex of the B mesons can be obtained by using the first daughter particle's production vertex.

Use the function

```
void read_hepevt(FILE *file_ptr , HEPEVT *hepevt);
```

to read each HEPEVT event record. This function is pre-declared in include/hepevt/hepevt\_io.h and implemented in lib/libhepevt.a. To link to lib/libhepevt.a start from lab3/problem/generator/Makefile.

Use the histogram functions pre-declared in include/histo/histogram.h and implemented in lib/libhisto.a. Add -lhisto to the link line to add this library to the link step. The two histograms can be created by calling hist\_create twice.

```
hist_create("B pt", 50, 0., 50.);
hist_create("B ctau", 50, 0., 1.);
```

References References

### References

- [1] GCC, the GNU Compiler Collection. http://gcc.gnu.org/.
- [2] GNU Make. http://www.gnu.org/software/make/manual/make.html.
- [3] Gnuplot. http://www.gnuplot.info/.
- [4] Particle Data Group. http://pdg.lbl.gov/.
- [5] PYTHIA. http://www.thep.lu.se/~torbjorn/Pythia.html.
- [6] Wikipedia definition of Comma-separated values. http://en.wikipedia.org/wiki/Comma-separated\_values.
- [7] Wikipedia definition of Flowcharts. http://en.wikipedia.org/wiki/Flow\_chart.
- [8] Wikipedia definition of Pseudocode. http://en.wikipedia.org/wiki/Pseudocode.