

Going beyond stuck trackers: how well do your trackers work?

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PREPRINT



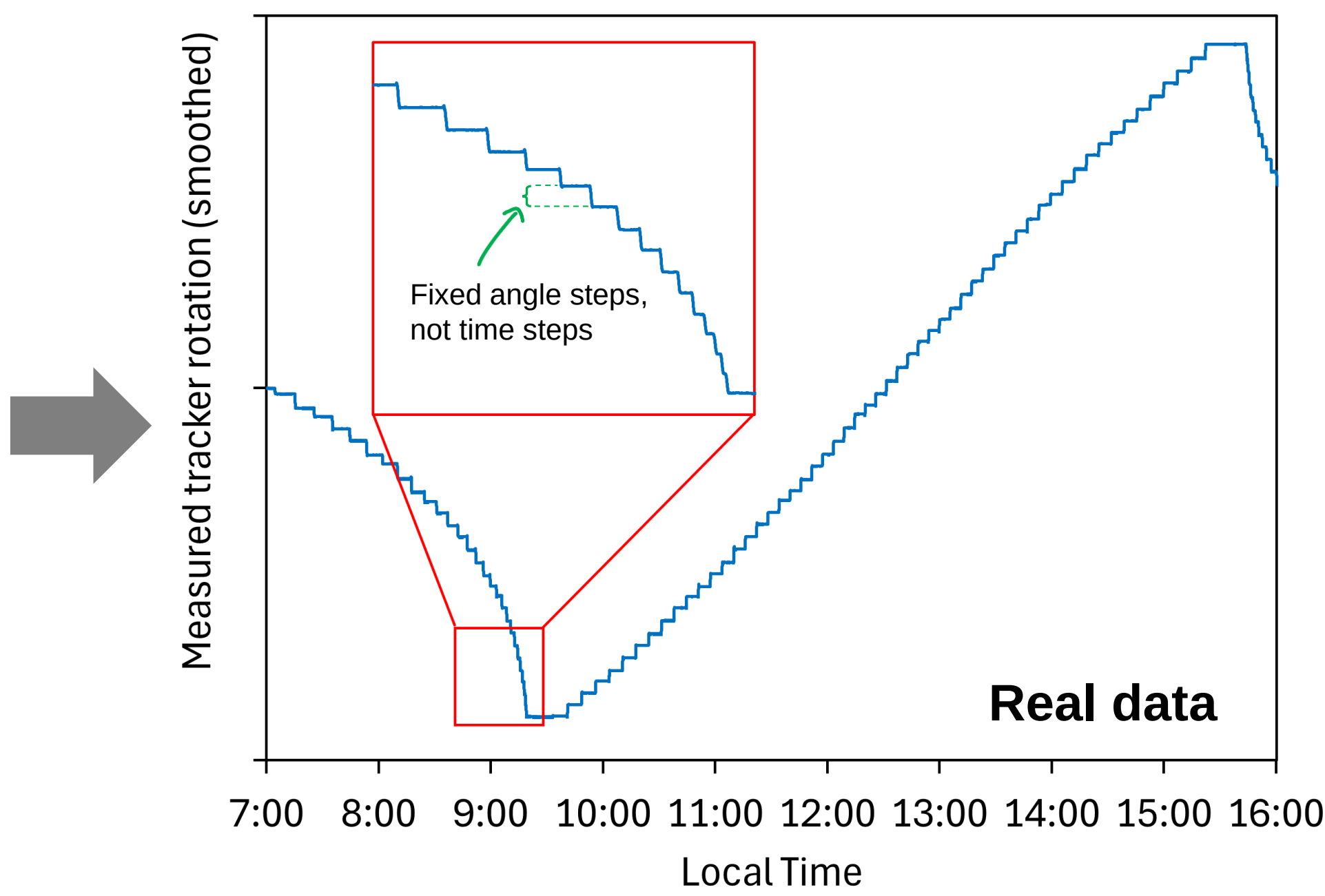
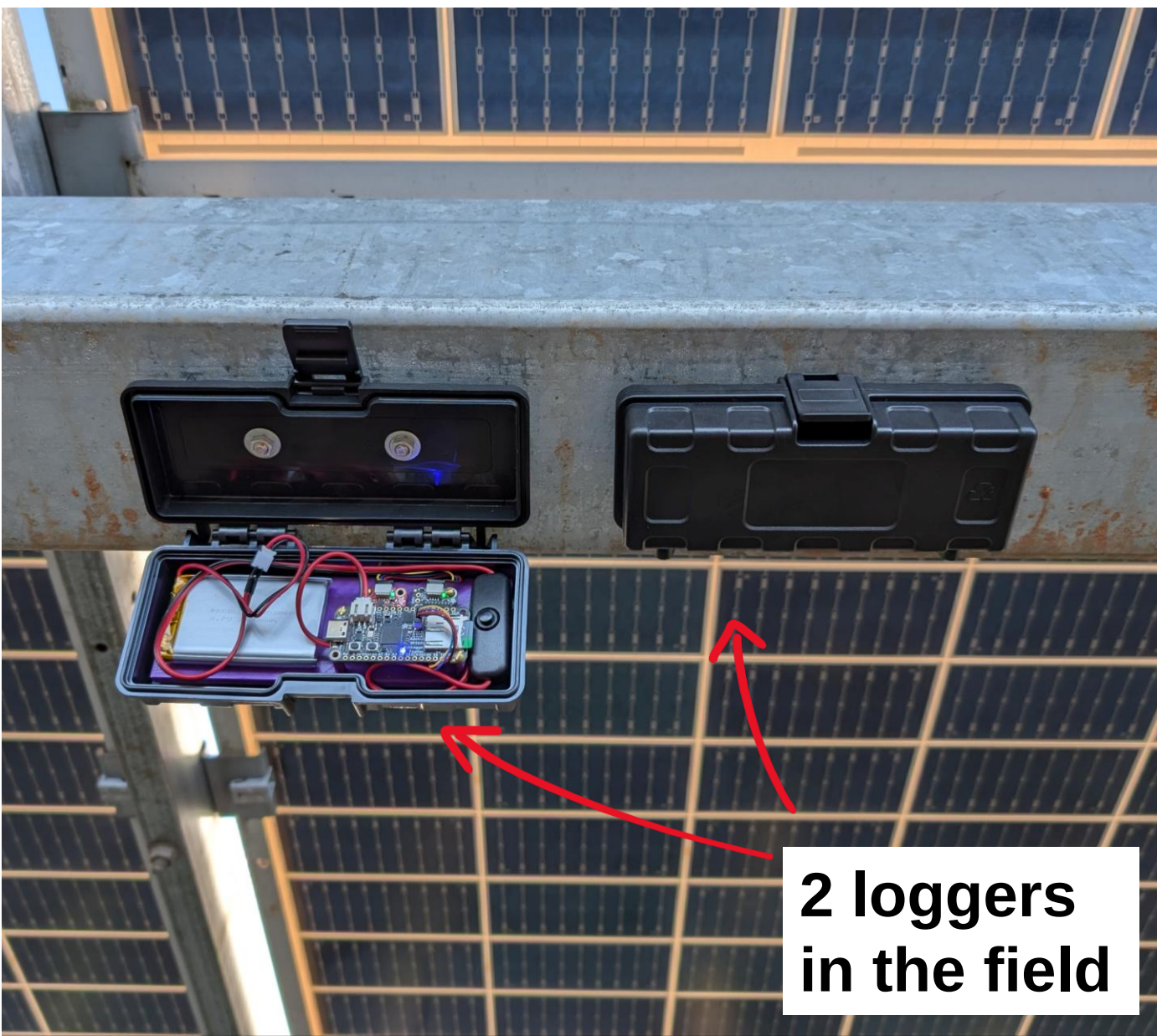
Stuck & broken trackers get attention in the industry, but there are additional **issues beyond binary “working/not working”** that can **impact performance**.

We are working on a cheap temporary datalogger to **measure actual position**, and models to **estimate impacts of “non-idealities.”**

“Where are my trackers actually pointed?”

Non-idealities that can’t be measured with existing **plant data**: torque-tube twist, torque-tube sag, actuator position calibration error.

Solution: cheap, mailable, magnet-mount 3-axis tilt data loggers. Measurements every 1-sec, compare to expected/modeled/ideal positions. Eventually open-source.



Mail to plant → stick on trackers for a few days → mail back.

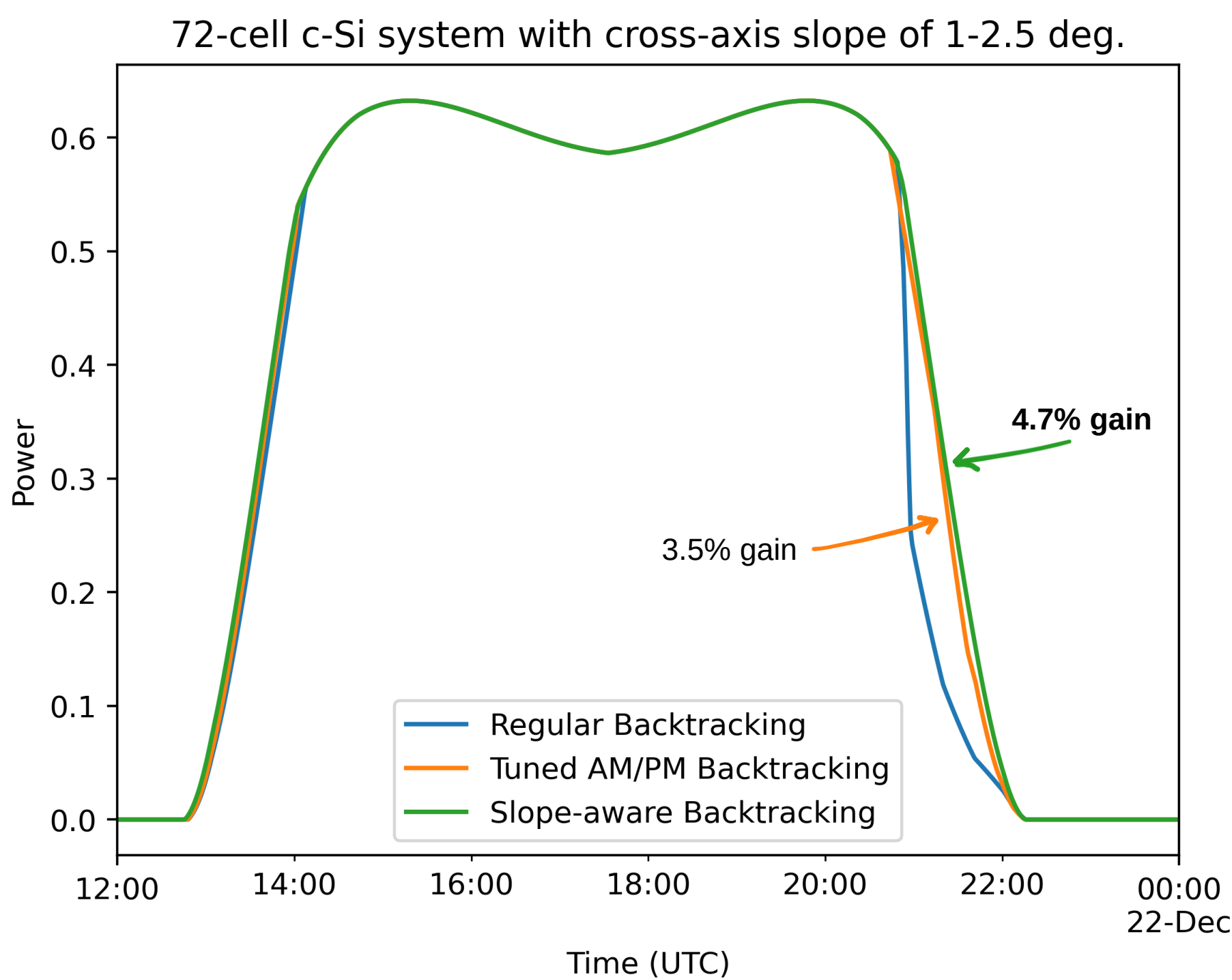
Goal: assess plant-specific and industry-wide **non-idealities**. *Contact us if you might want to participate!*

“How much am I losing?”

Modeling **non-idealities** isn’t always easy, so how much are you losing?

- We presented some self-shade and tracker fault examples/methods in [2].
- Functions in [2] have been **expanded**: now allow cross-axis slope, independent AM/PM backtracking, clock-drift, fixed-tilt shade, others.

<https://github.com/williamhobbs/pv-system-model>, with examples in <https://github.com/williamhobbs/2025-pvrw-trackers>.



References:

[1] Anderson, Kevin S., and Clifford W. Hansen. "Simulated Performance Effect of Torque Tube Twisting in Single-Axis Tracking PV Arrays." 2024 IEEE 52nd Photovoltaic Specialist Conference (PVSC). <http://dx.doi.org/10.1109/PVSC57443.2024.10749340>
[2] Hobbs, W., Anderson, K., Mikofski, M., and Ghiz, M. "An approach to modeling linear and non-linear self-shading losses with pvlib." 2024 PV Performance Modeling Collaborative (PVPMP). https://github.com/williamhobbs/2024_pvpmp_self_shade



Acknowledgements:

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