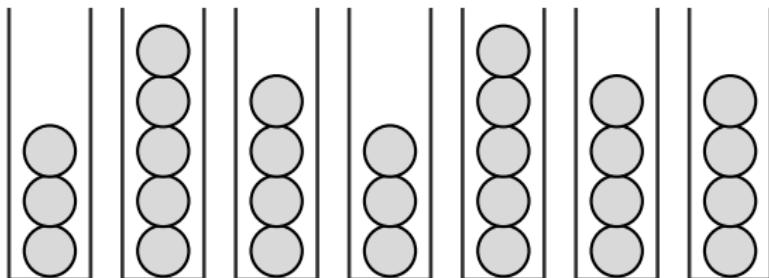


History-Independent Load Balancing



Michael A. Bender

Stony Brook University

Bill Kuszmaul

CMU

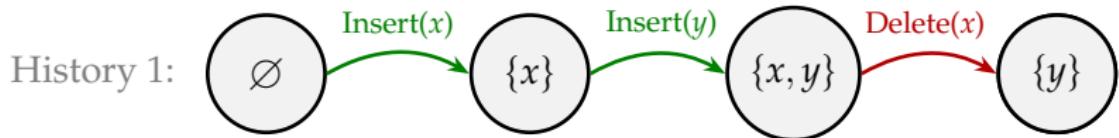
Elaine Shi

CMU

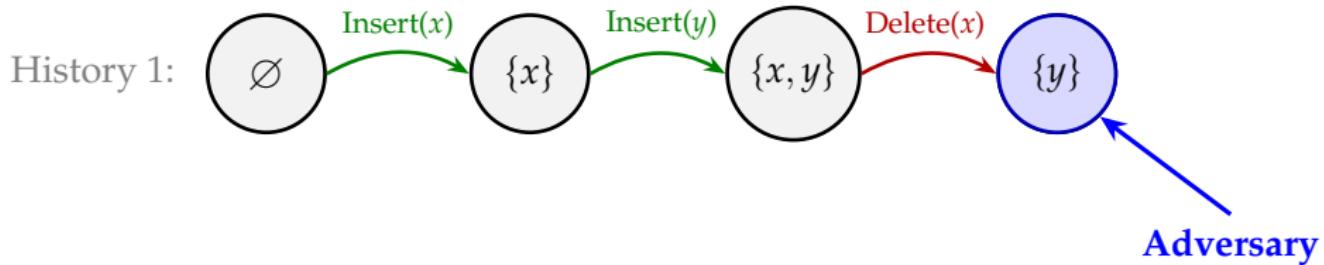
Rose Silver

CMU

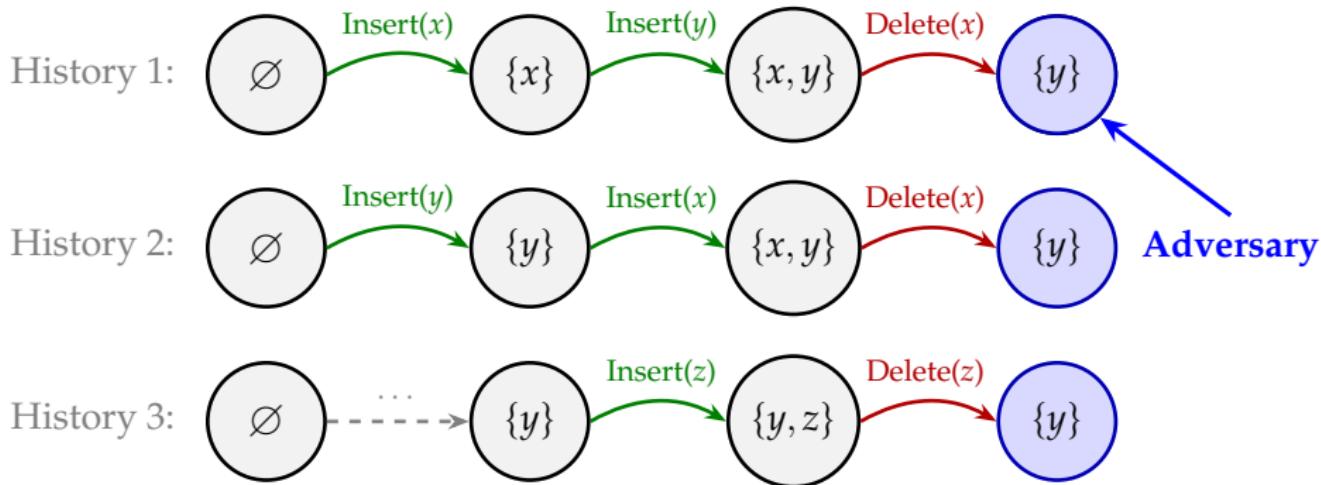
HISTORY-INDEPENDENT DATA STRUCTURES



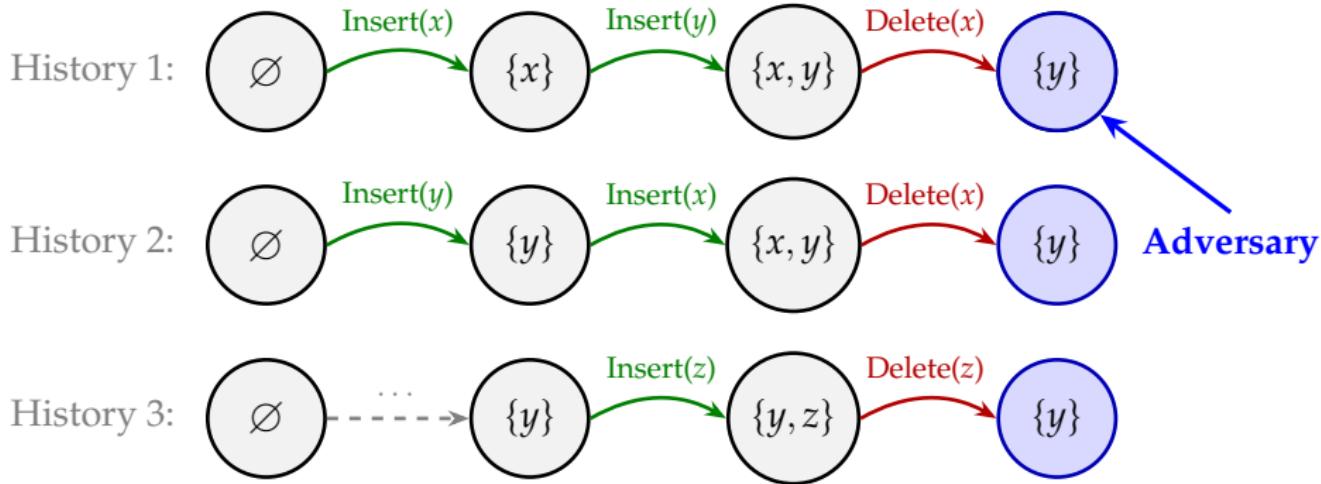
HISTORY-INDEPENDENT DATA STRUCTURES



HISTORY-INDEPENDENT DATA STRUCTURES



HISTORY-INDEPENDENT DATA STRUCTURES



History Independence (Micciancio '97, Naor & Teague '01)

- ▶ The state reveals only the current elements—not the history of operations.

HISTORY INDEPENDENT DATA STRUCTURES

A History of Applications

Hash tables, trees, memory allocation, PMAs, graph algorithms, cache-oblivious data structures, and more.

Micciancio '97, Naor & Teague '01, Buchbinder & Petrank '03, Molnar et al. '06, Blelloch & Golovin '07,
Moran et al. '07, Naor et al. '08, Golovin '08–'10, Bajaj & Sion '13, Roche et al. '15, Bender et al. '16

HISTORY INDEPENDENT DATA STRUCTURES

A History of Applications

Hash tables, trees, memory allocation, PMAs, graph algorithms, cache-oblivious data structures, and more.

Micciancio '97, Naor & Teague '01, Buchbinder & Petrank '03, Molnar et al. '06, Blelloch & Golovin '07,
Moran et al. '07, Naor et al. '08, Golovin '08–'10, Bajaj & Sion '13, Roche et al. '15, Bender et al. '16

Yet fundamental questions remain open.

HISTORY INDEPENDENT DATA STRUCTURES

A History of Applications

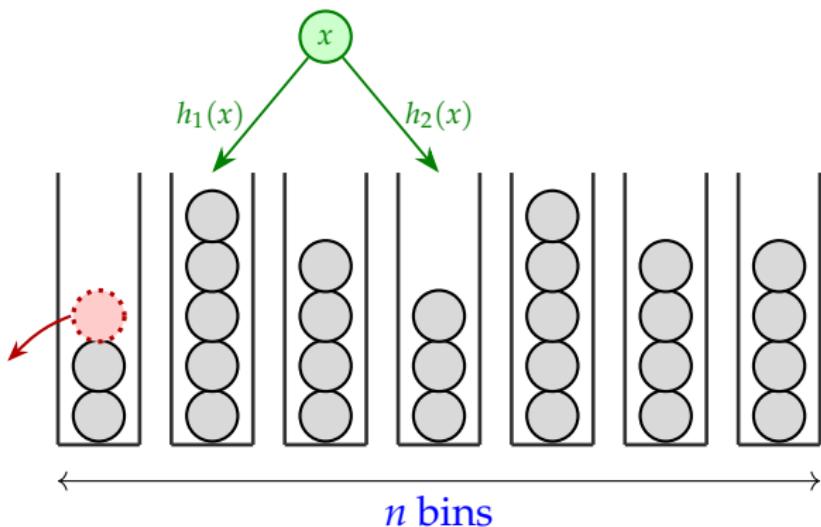
Hash tables, trees, memory allocation, PMAs, graph algorithms, cache-oblivious data structures, and more.

Micciancio '97, Naor & Teague '01, Buchbinder & Petrank '03, Molnar et al. '06, Blelloch & Golovin '07,
Moran et al. '07, Naor et al. '08, Golovin '08–'10, Bajaj & Sion '13, Roche et al. '15, Bender et al. '16

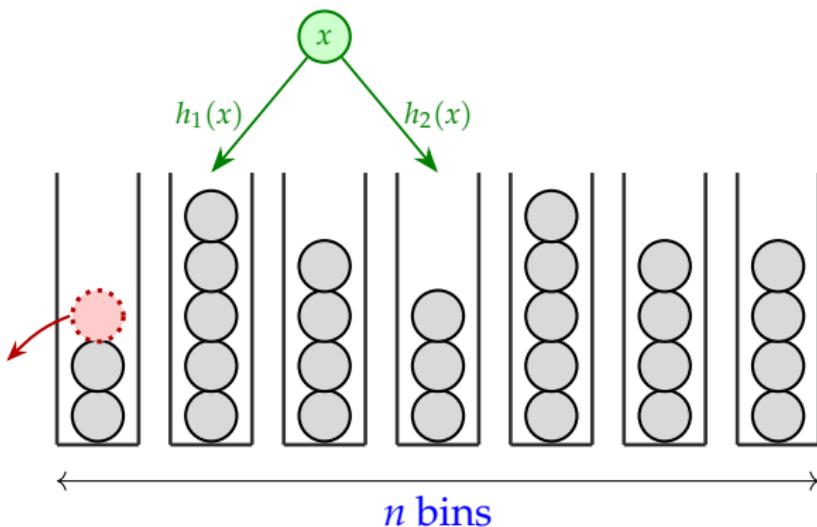
Yet fundamental questions remain open.

This work: History-Independent Load Balancing

TWO-CHOICE LOAD BALANCING

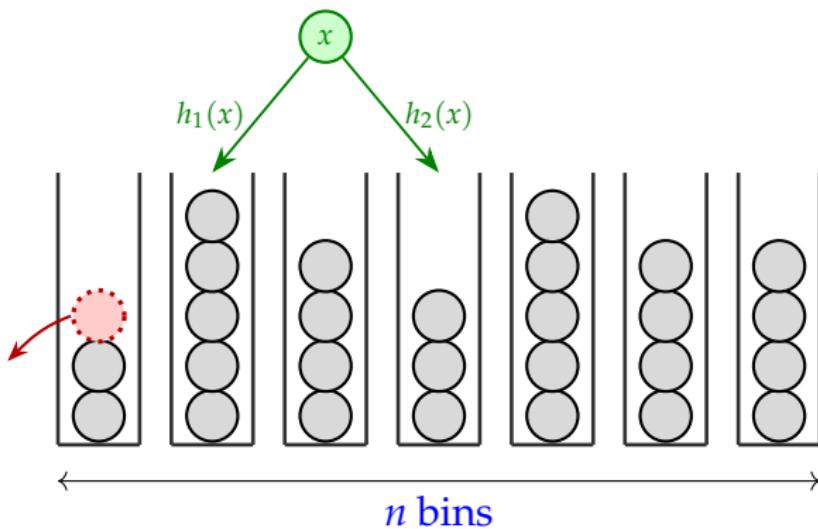


TWO-CHOICE LOAD BALANCING



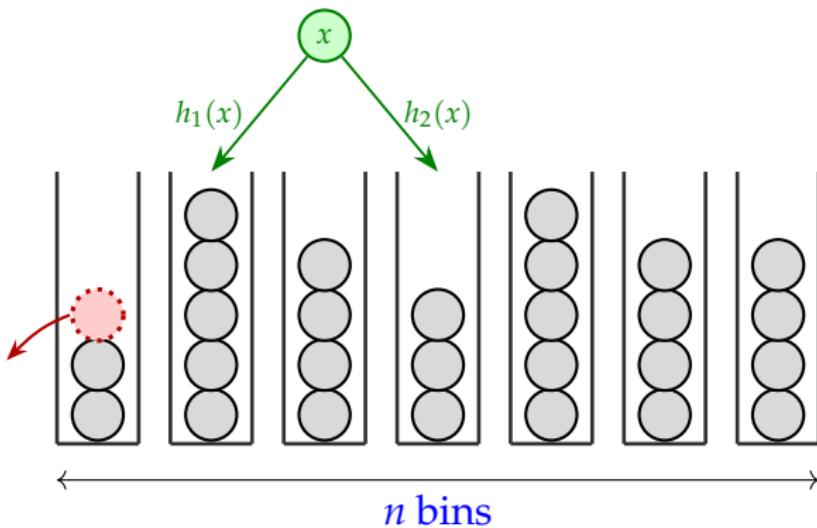
- ▶ Balls are **inserted/deleted**, with up to m present at a time.

TWO-CHOICE LOAD BALANCING



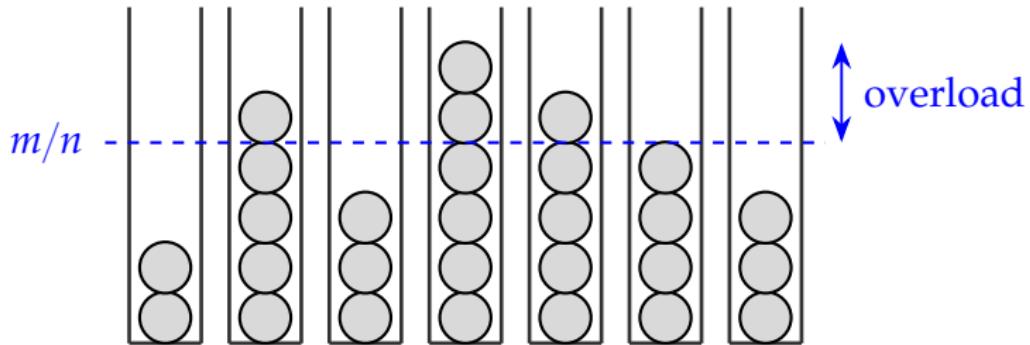
- ▶ Balls are **inserted/deleted**, with up to m present at a time.
- ▶ Each ball has two random bins where it can go.

TWO-CHOICE LOAD BALANCING



- ▶ Balls are **inserted/deleted**, with up to m present at a time.
- ▶ Each ball has two random bins where it can go.
- ▶ We must maintain a valid assignment of balls to bins.

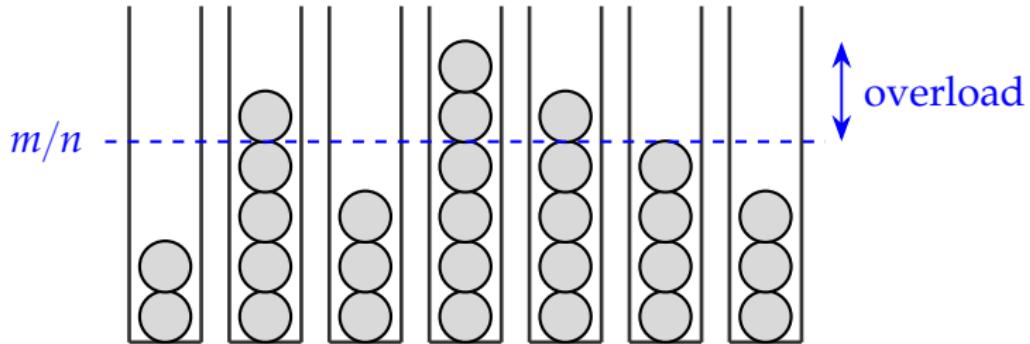
TWO GOALS



Minimize Overload:

- ▶ i.e., the amount by which the fullest bin exceeds m/n .

TWO GOALS



Minimize Overload:

- ▶ i.e., the amount by which the fullest bin exceeds m/n .

Minimize Recourse:

- ▶ i.e., the number of balls moved around on any given insertion/deletion.

PUTTING IT ALL TOGETHER

PUTTING IT ALL TOGETHER

History-Independent Load Balancing:

PUTTING IT ALL TOGETHER

History-Independent Load Balancing:

- ▶ For all sets S of balls, if the current set is S , then the assignment is always A_S .

PUTTING IT ALL TOGETHER

History-Independent Load Balancing:

- ▶ For all sets S of balls, if the current set is S , then the assignment is always A_S .

Question: Does there exist a history-independent solution with small recourse and small overload?

PUTTING IT ALL TOGETHER

History-Independent Load Balancing:

- ▶ For all sets S of balls, if the current set is S , then the assignment is always A_S .

Question: Does there exist a history-independent solution with small recourse and small overload?

Our Main Result: There exists a history-independent solution with:

- ▶ High probability overload $O(1)$
- ▶ Expected recourse $O(\log \log(m/n))$

PAST WORK (NOT HISTORY INDEPENDENT)

| Overload | Recourse | Reference | Caveats |
|-------------------------|----------------|--------------------------------|-----------------|
| $O(\log \log n)$ | 0 | [ABKU '94] [BCSV '00] | insertion-only |
| $O(1)$ | $O(\log(m/n))$ | [Dietzfelbinger, Weidling '07] | insertion-only |
| $\tilde{O}(\sqrt{m/n})$ | $O(1)$ | [Frieze, Petti '18] | insertion-only |
| $O(\log(m/n))$ | 0 | [Bansal, Kuszmaul '22] | no reinsertions |
| $O(1)$ | $O(m/n)$ | [Dietzfelbinger, Weidling '07] | |

PAST WORK (NOT HISTORY INDEPENDENT)

| Overload | Recourse | Reference | Caveats |
|-------------------------|---------------------|--------------------------------|-----------------|
| $O(\log \log n)$ | 0 | [ABKU '94] [BCSV '00] | insertion-only |
| $O(1)$ | $O(\log(m/n))$ | [Dietzfelbinger, Weidling '07] | insertion-only |
| $\tilde{O}(\sqrt{m/n})$ | $O(1)$ | [Frieze, Petti '18] | insertion-only |
| $O(\log(m/n))$ | 0 | [Bansal, Kuszmaul '22] | no reinsertions |
| $O(1)$ | $O(m/n)$ | [Dietzfelbinger, Weidling '07] | |
| $O(1)$ | $O(\log \log(m/n))$ | [This Paper] | |

PAST WORK (NOT HISTORY INDEPENDENT)

| Overload | Recourse | Reference | Caveats |
|-------------------------|---------------------|--------------------------------|-----------------|
| $O(\log \log n)$ | 0 | [ABKU '94] [BCSV '00] | insertion-only |
| $O(1)$ | $O(\log(m/n))$ | [Dietzfelbinger, Weidling '07] | insertion-only |
| $\tilde{O}(\sqrt{m/n})$ | $O(1)$ | [Frieze, Petti '18] | insertion-only |
| $O(\log(m/n))$ | 0 | [Bansal, Kuszmaul '22] | no reinsertions |
| $O(1)$ | $O(m/n)$ | [Dietzfelbinger, Weidling '07] | |
| $O(1)$ | $O(\log \log(m/n))$ | [This Paper] | |

If we want overload $O(1)$, our result is a new state of the art!

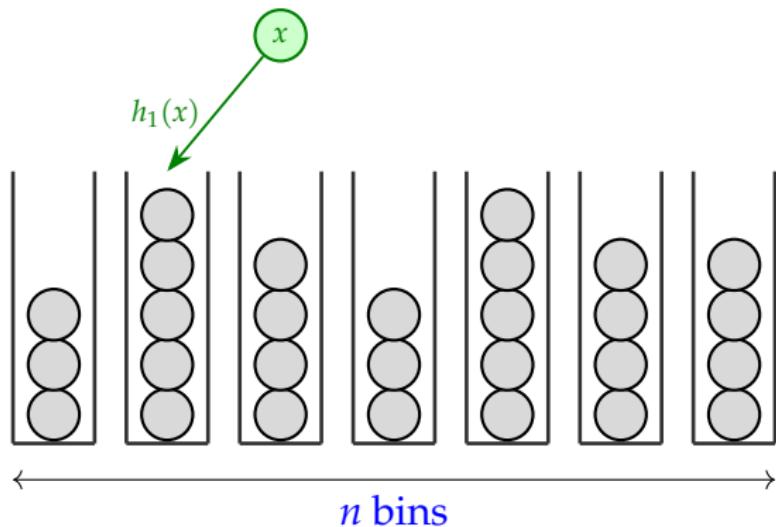
REST OF TALK: A SIMPLE WARMUP

Theorem: There exists a history-independent solution with:

- ▶ High-probability overload $\Theta(1)$ $O(\log \log n)$.
- ▶ Expected recourse $\Theta(\log \log(m/n))$ $O(m/n)$.

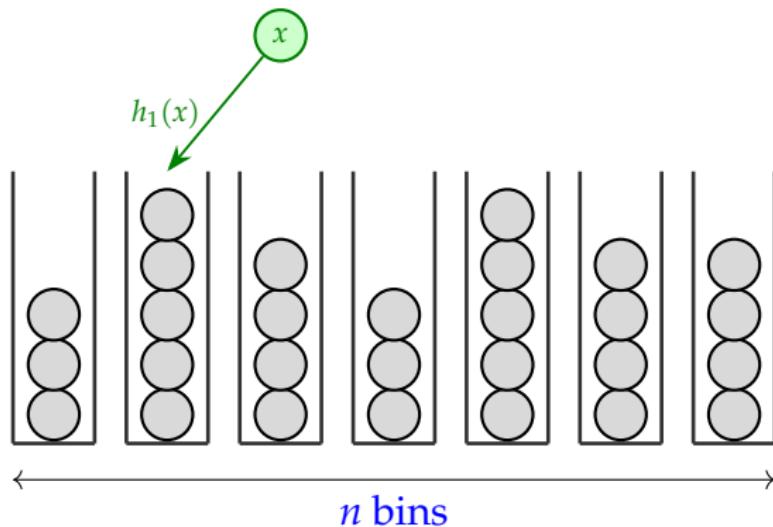
BASELINE 1: THE SINGLE-CHOICE STRATEGY

To insert a ball x , just put it in bin $h_1(x)$:



BASELINE 1: THE SINGLE-CHOICE STRATEGY

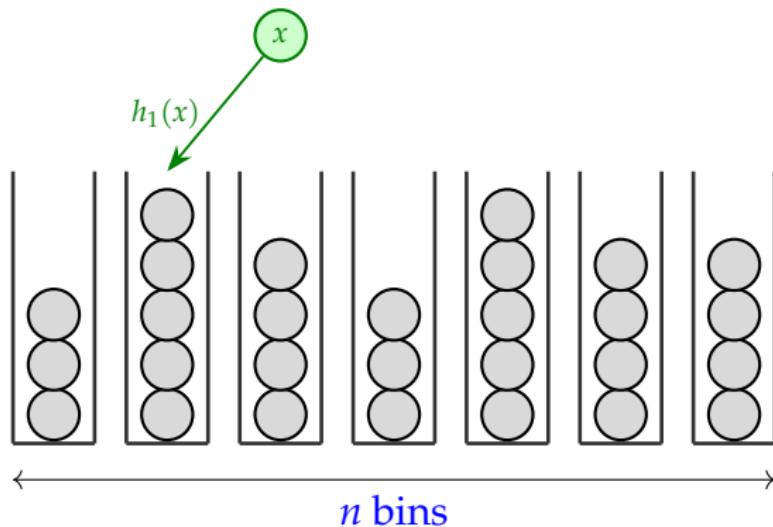
To insert a ball x , just put it in bin $h_1(x)$:



- ▶ This is history-independent ✓

BASELINE 1: THE SINGLE-CHOICE STRATEGY

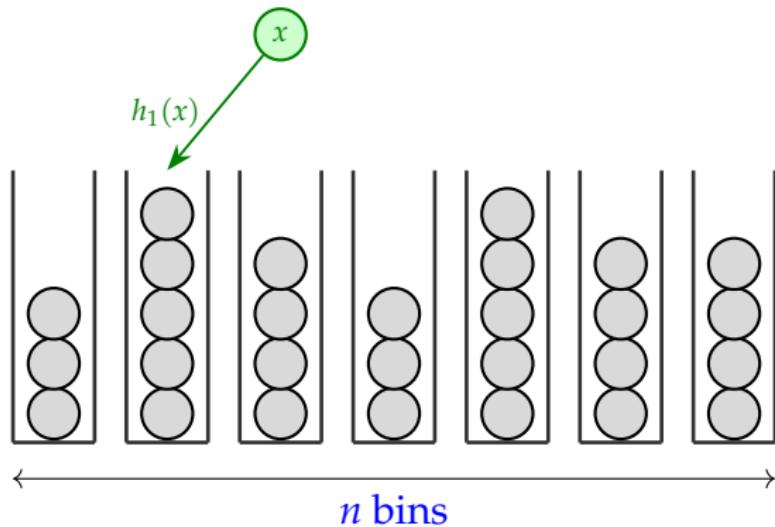
To insert a ball x , just put it in bin $h_1(x)$:



- ▶ This is history-independent ✓
- ▶ The recourse is 0 ✓

BASELINE 1: THE SINGLE-CHOICE STRATEGY

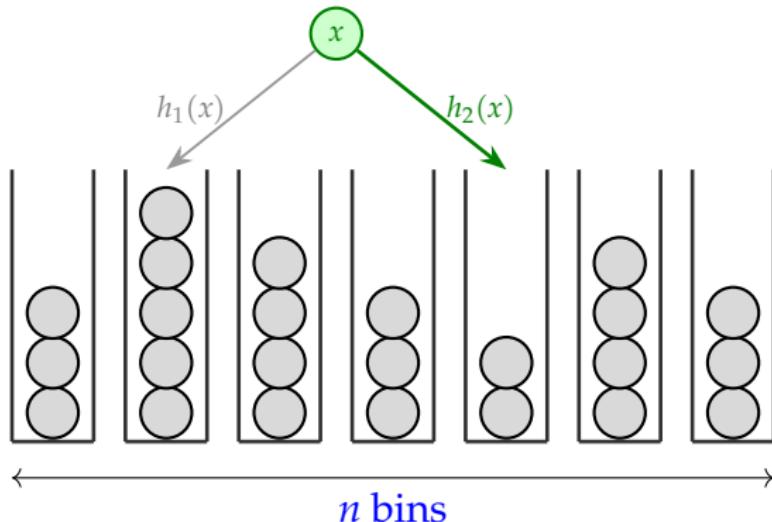
To insert a ball x , just put it in bin $h_1(x)$:



- ▶ This is history-independent ✓
- ▶ The recourse is 0 ✓
- ▶ But... the overload is huge, roughly $\sqrt{m/n}$ ✗

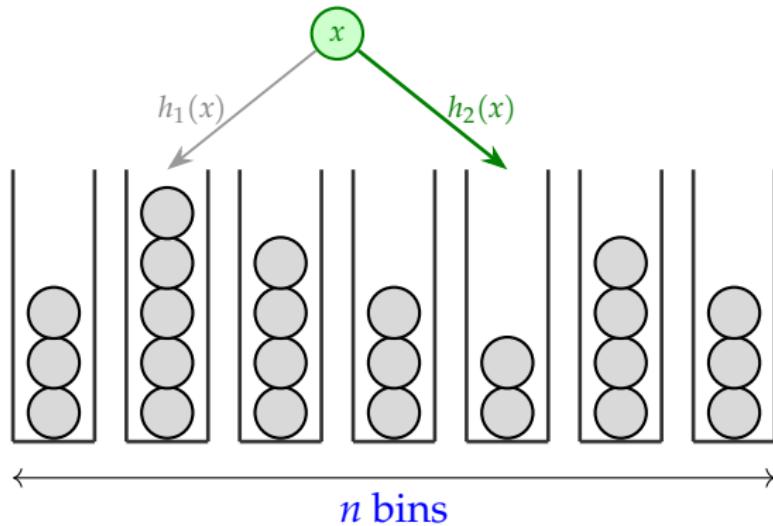
BASELINE 2: GREEDY INSERTIONS

To insert a ball x , put it in the **emptier** of its choices:



BASELINE 2: GREEDY INSERTIONS

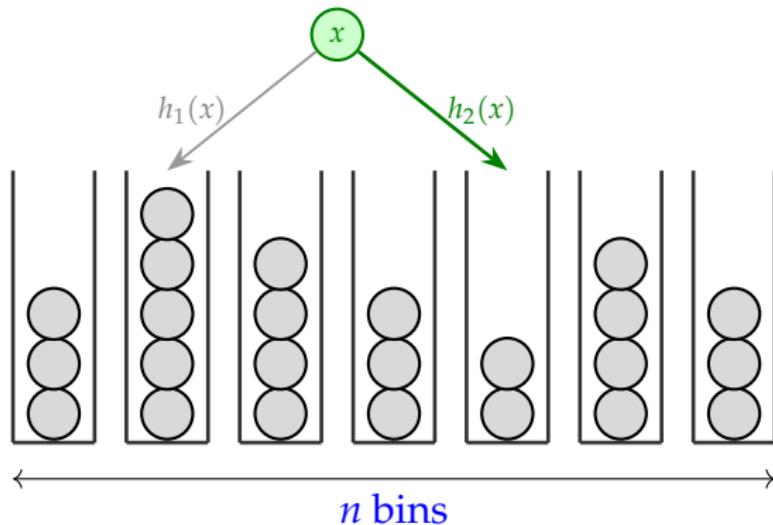
To insert a ball x , put it in the **emptier** of its choices:



- ▶ This is **not** history-independent \times

BASELINE 2: GREEDY INSERTIONS

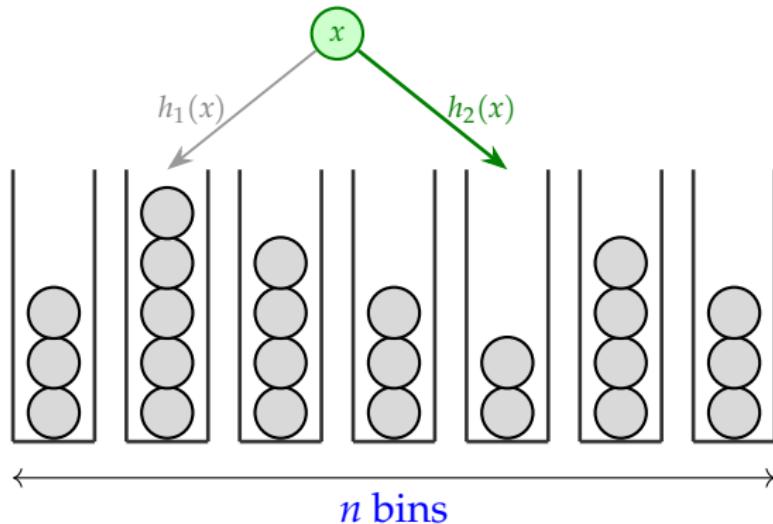
To insert a ball x , put it in the **emptier** of its choices:



- ▶ This is **not** history-independent ✗
- ▶ The recourse is 0 ✓

BASELINE 2: GREEDY INSERTIONS

To insert a ball x , put it in the **emptier** of its choices:

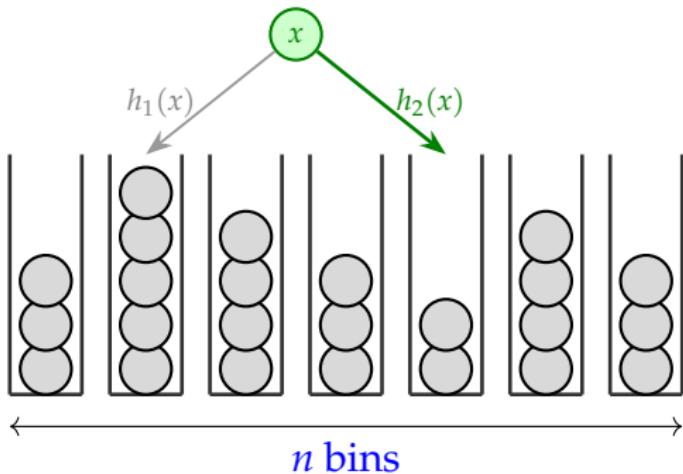


- ▶ This is **not** history-independent ✗
- ▶ The recourse is 0 ✓
- ▶ In the insertion-only case, the overload is $O(\log \log n)$ ✓

[Azar, Broder, Karlin and Upfal '94]

A SIMPLE HISTORY-INDEPENDENT ALGORITHM

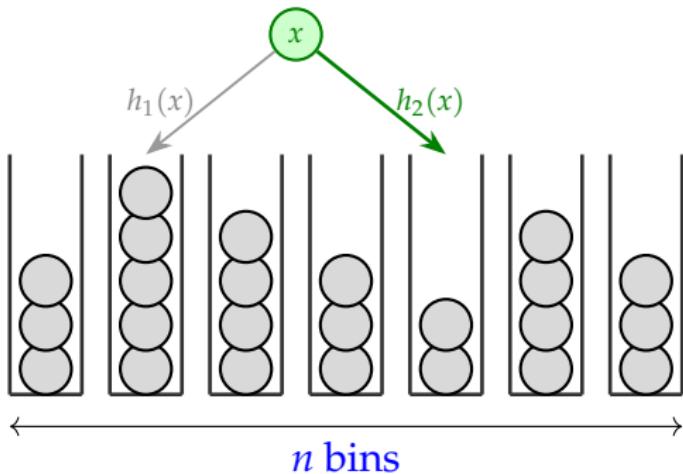
A SIMPLE HISTORY-INDEPENDENT ALGORITHM



Given a set S of balls, define $\text{Greedy}(S)$ as:

- ▶ Start with empty bins.
- ▶ Sort the balls in S to get a sequence x_1, x_2, \dots .
- ▶ Insert x_1, x_2, \dots using the greedy algorithm.

A SIMPLE HISTORY-INDEPENDENT ALGORITHM

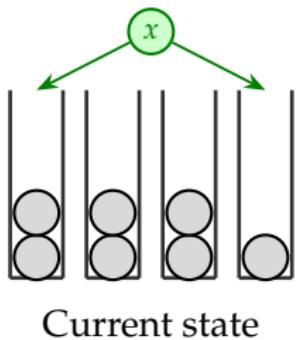


Given a set S of balls, define $\text{Greedy}(S)$ as:

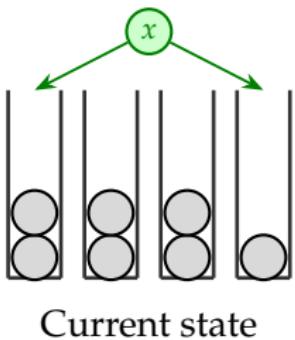
- ▶ Start with empty bins.
- ▶ Sort the balls in S to get a sequence x_1, x_2, \dots .
- ▶ Insert x_1, x_2, \dots using the greedy algorithm.

A History-Independent Algorithm: If S is the current set, use $\text{Greedy}(S)$.

A SIMPLE HISTORY-INDEPENDENT ALGORITHM



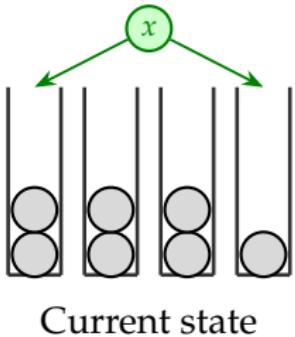
A SIMPLE HISTORY-INDEPENDENT ALGORITHM



At each time step:

1. Observe current set S
2. Compute A_S
3. Update the system to reflect A_S

A SIMPLE HISTORY-INDEPENDENT ALGORITHM



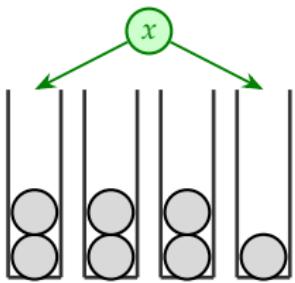
At each time step:

1. Observe current set S
2. Compute A_S ←
3. Update the system to reflect A_S

Compute A_S by simulating greedy:

- 2a. Start with empty bins
- 2b. Sort balls in S to get x_1, x_2, \dots
- 2c. Insert balls using greedy

A SIMPLE HISTORY-INDEPENDENT ALGORITHM



Current state



Computing A_S

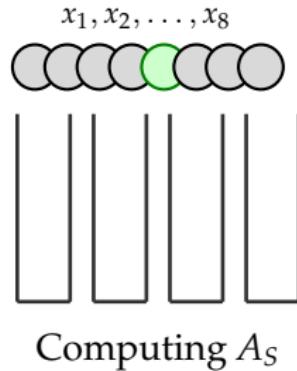
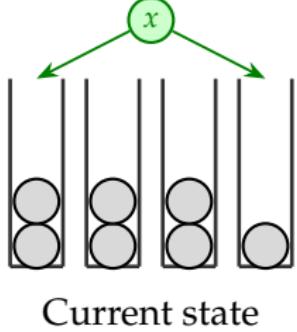
At each time step:

1. Observe current set S
2. Compute A_S
3. Update the system to reflect A_S

Compute A_S by simulating greedy:

- 2a. Start with empty bins
- 2b. Sort balls in S to get x_1, x_2, \dots
- 2c. Insert balls using greedy

A SIMPLE HISTORY-INDEPENDENT ALGORITHM



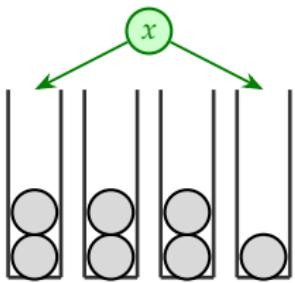
At each time step:

1. Observe current set S
2. Compute A_S
3. Update the system to reflect A_S

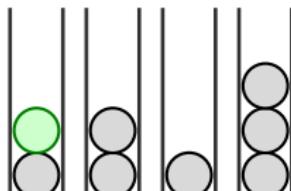
Compute A_S by simulating greedy:

- 2a. Start with empty bins
- 2b. Sort balls in S to get x_1, x_2, \dots
- 2c. Insert balls using greedy

A SIMPLE HISTORY-INDEPENDENT ALGORITHM



Current state



Computing A_S

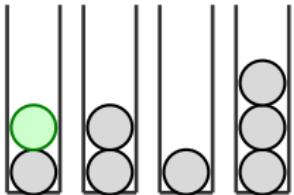
At each time step:

1. Observe current set S
2. Compute A_S
3. Update the system to reflect A_S

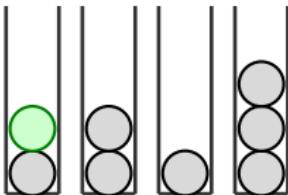
Compute A_S by simulating greedy:

- 2a. Start with empty bins
- 2b. Sort balls in S to get x_1, x_2, \dots
- 2c. Insert balls using greedy

A SIMPLE HISTORY-INDEPENDENT ALGORITHM



Updated state



Computing A_S

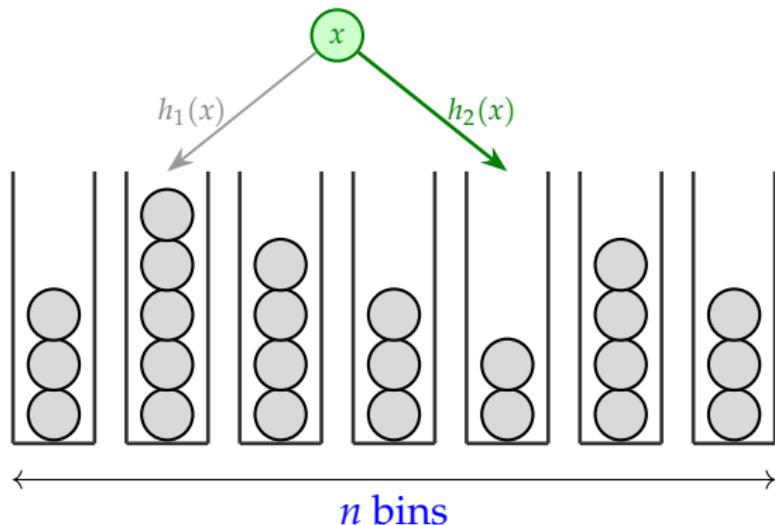
At each time step:

1. Observe current set S
2. Compute A_S
3. Update the system to reflect A_S

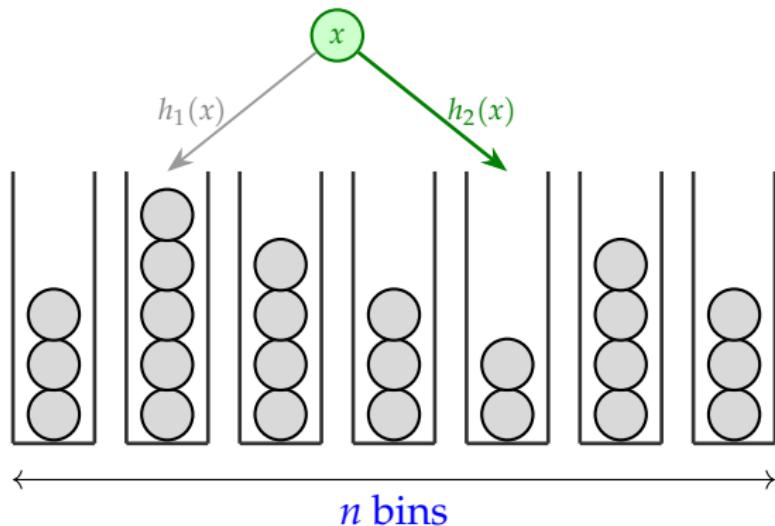
Compute A_S by simulating greedy:

- 2a. Start with empty bins
- 2b. Sort balls in S to get x_1, x_2, \dots
- 2c. Insert balls using greedy

ANALYZING HISTORY-INDEPENDENT GREEDY

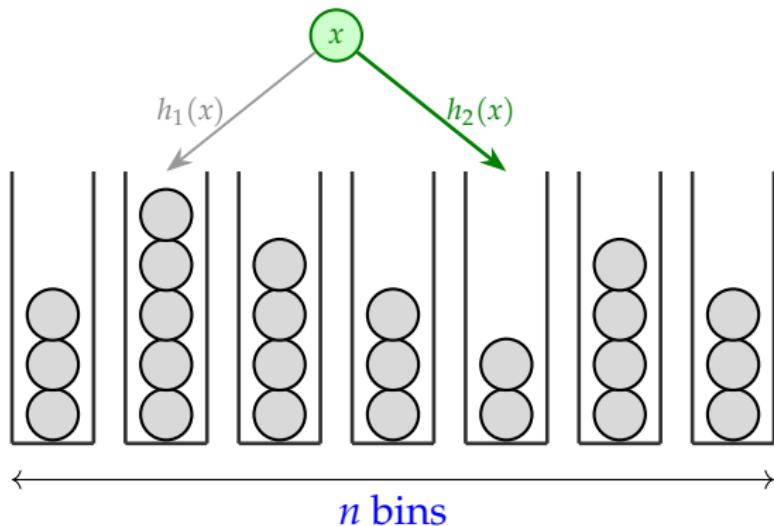


ANALYZING HISTORY-INDEPENDENT GREEDY



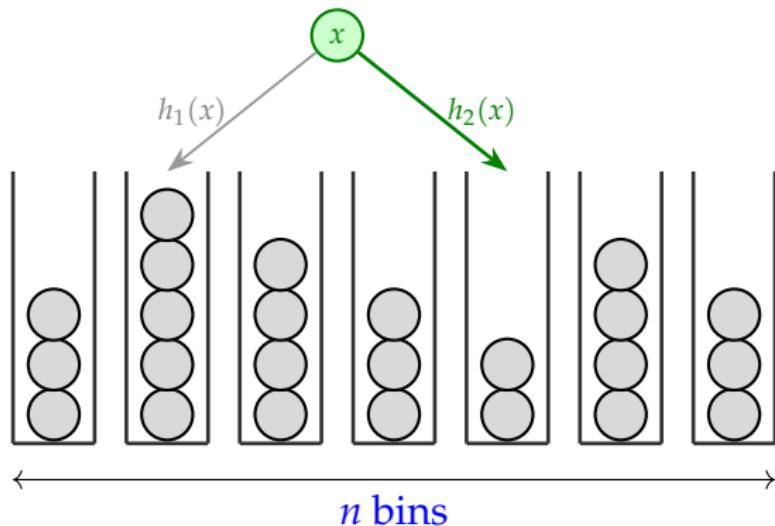
- ▶ The algorithm is history independent ✓

ANALYZING HISTORY-INDEPENDENT GREEDY



- ▶ The algorithm is history independent ✓
- ▶ The overload is $O(\log \log n)$ ✓

ANALYZING HISTORY-INDEPENDENT GREEDY



- ▶ The algorithm is history independent ✓
- ▶ The overload is $O(\log \log n)$ ✓
- ▶ What is the recourse?

ANALYZING THE RE COURSE



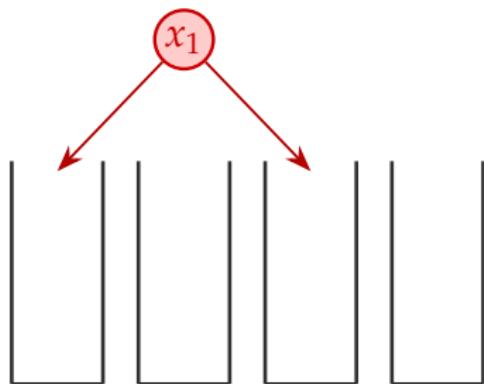
Computing **Greedy**(S)



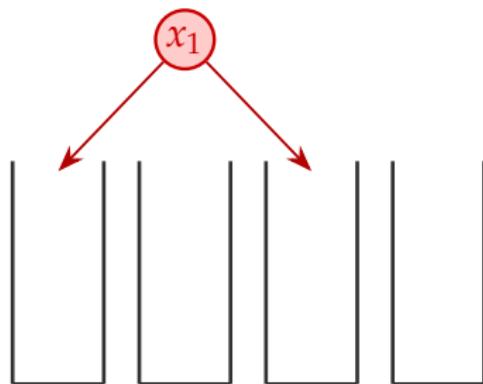
Computing **Greedy**($S \cup \{x^*\}$)

How does $\text{Greedy}(S)$ change if we add a ball x^* ?

ANALYZING THE RE COURSE



Computing **Greedy**(S)



Computing **Greedy**($S \cup \{x^*\}$)

ANALYZING THE RE COURSE

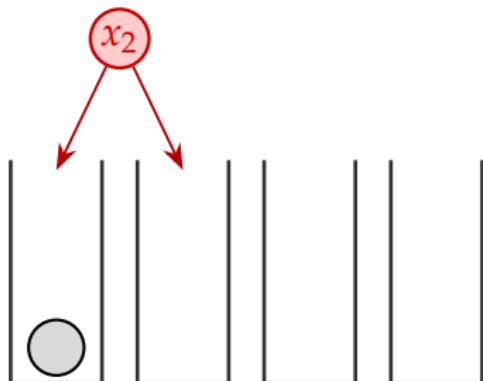


Computing **Greedy**(S)

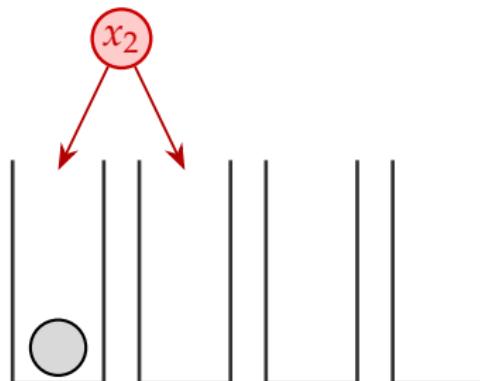


Computing **Greedy**($S \cup \{x^*\}$)

ANALYZING THE RE COURSE

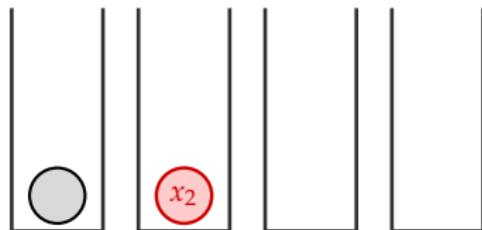


Computing **Greedy**(S)

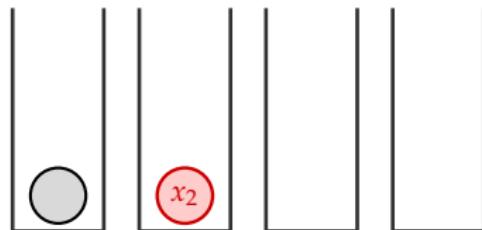


Computing **Greedy**($S \cup \{x^*\}$)

ANALYZING THE RE COURSE

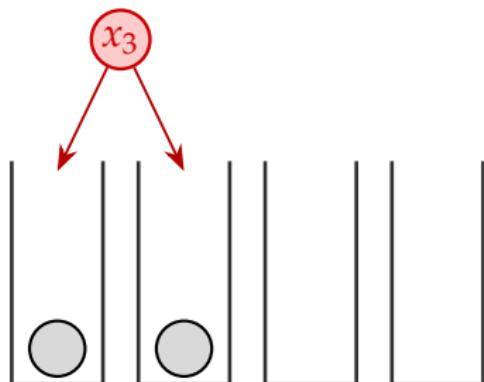


Computing **Greedy**(S)

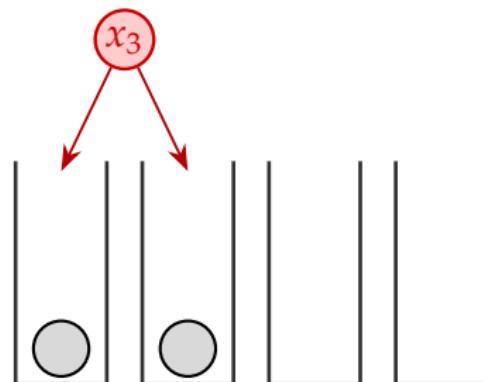


Computing **Greedy**($S \cup \{x^*\}$)

ANALYZING THE RE COURSE

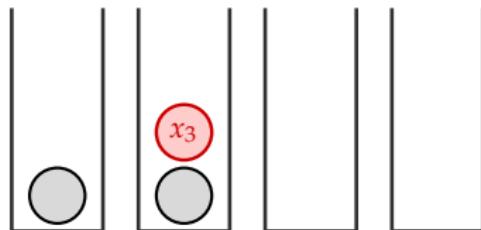


Computing $\text{Greedy}(S)$

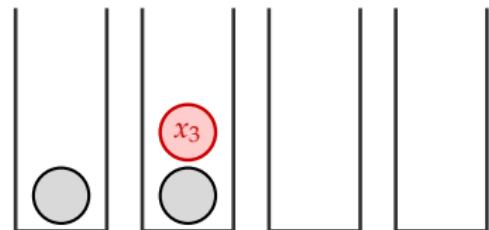


Computing $\text{Greedy}(S \cup \{x^*\})$

ANALYZING THE RE COURSE

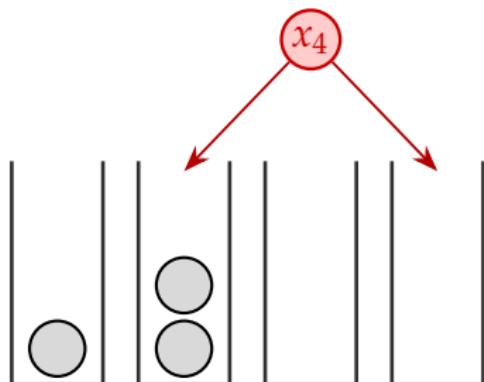


Computing **Greedy**(S)

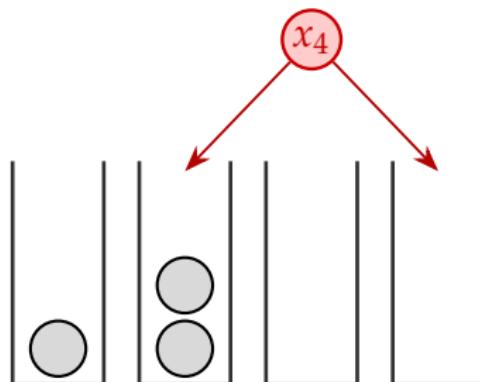


Computing **Greedy**($S \cup \{x^*\}$)

ANALYZING THE RE COURSE

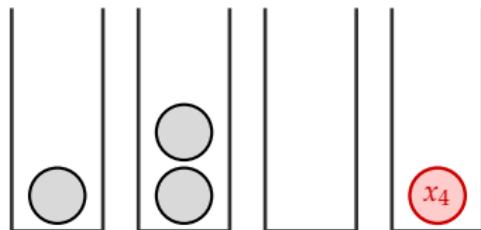


Computing **Greedy**(S)

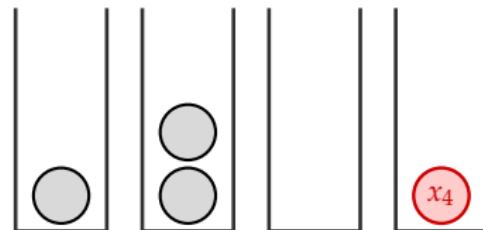


Computing **Greedy**($S \cup \{x^*\}$)

ANALYZING THE RE COURSE

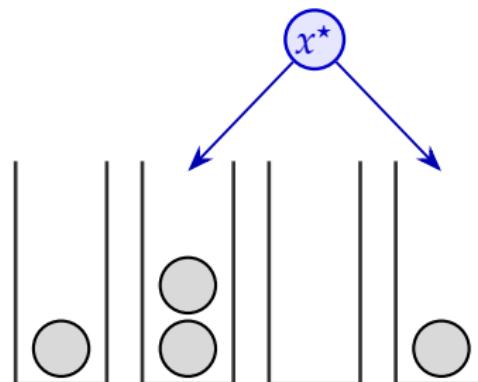
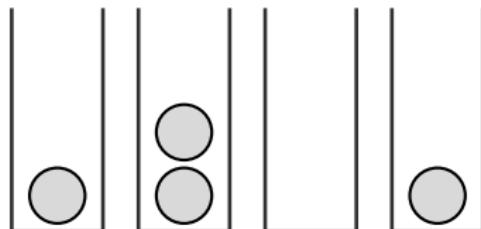


Computing **Greedy**(S)

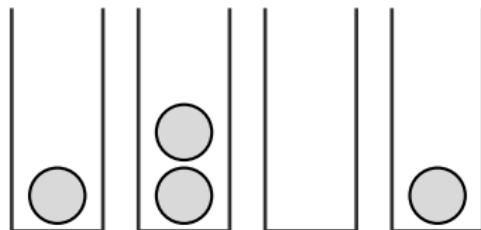


Computing **Greedy**($S \cup \{x^*\}$)

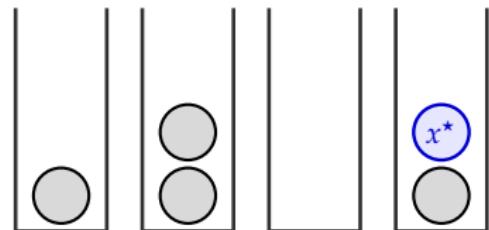
ANALYZING THE RE COURSE



ANALYZING THE RE COURSE

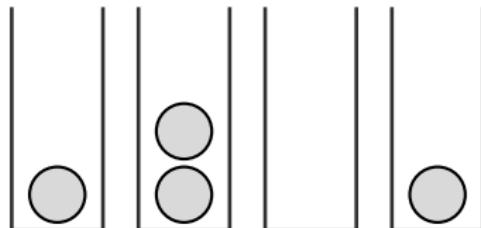


Computing **Greedy**(S)

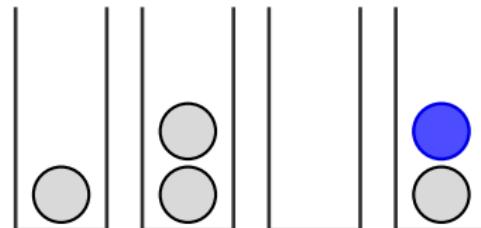


Computing **Greedy**($S \cup \{x^*\}$)

ANALYZING THE RE COURSE



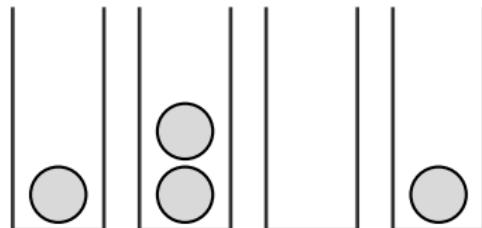
Computing **Greedy**(S)



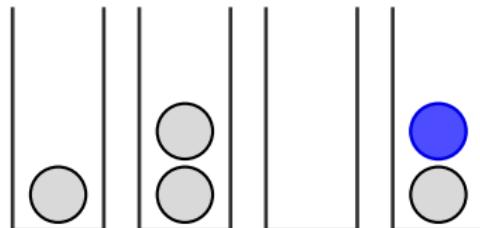
Computing **Greedy**($S \cup \{x^*\}$)

Subsequent balls will experience either:

ANALYZING THE RE COURSE



Computing Greedy(S)

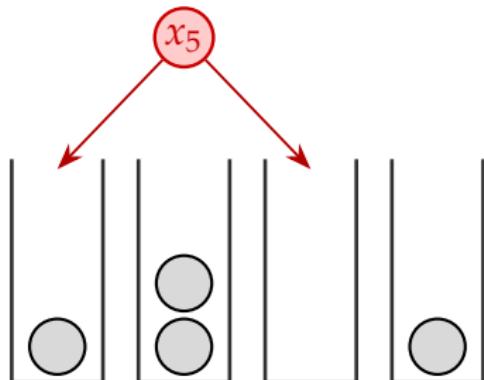


Computing Greedy($S \cup \{x^*\}$)

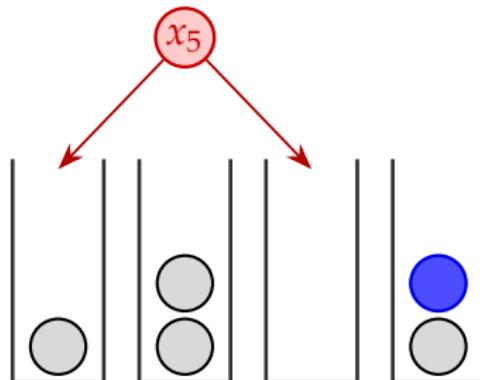
Subsequent balls will experience either:

1. No recourse

ANALYZING THE RE COURSE



Computing **Greedy**(S)

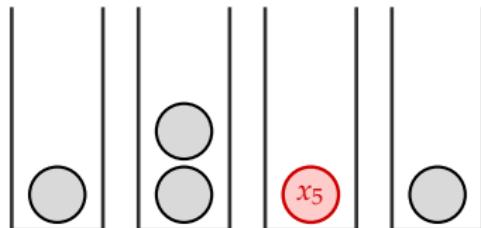


Computing **Greedy**($S \cup \{x^*\}$)

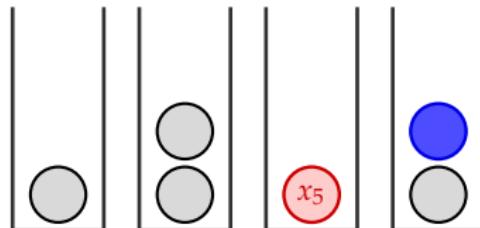
Future insertions will experience either:

1. No recourse

ANALYZING THE RE COURSE



Computing Greedy(S)

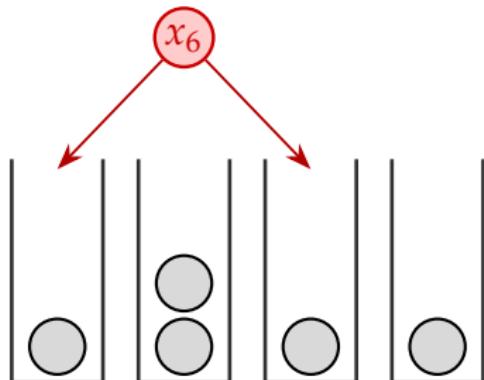


Computing Greedy($S \cup \{x^*\}$)

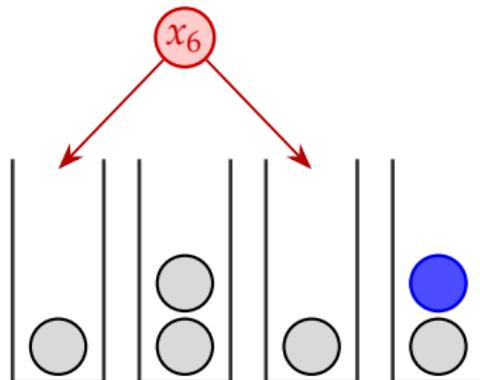
Subsequent balls will experience either:

1. No recourse

ANALYZING THE RE COURSE



Computing Greedy(S)

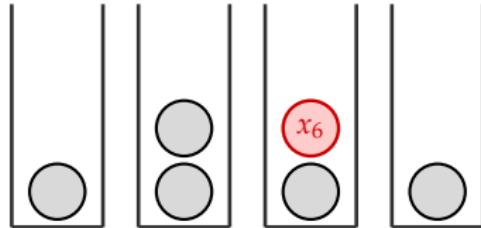


Computing Greedy($S \cup \{x^*\}$)

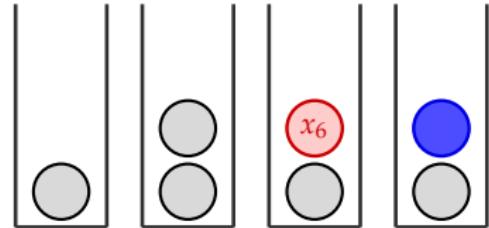
Subsequent balls will experience either:

1. No recourse

ANALYZING THE RE COURSE



Computing **Greedy**(S)

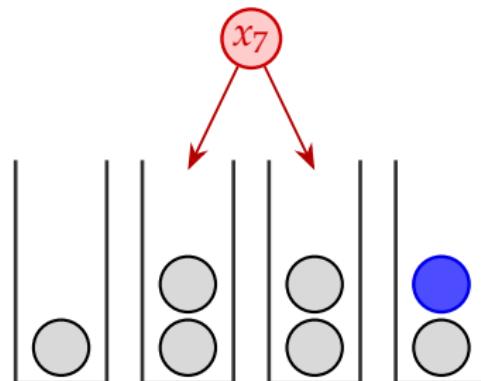
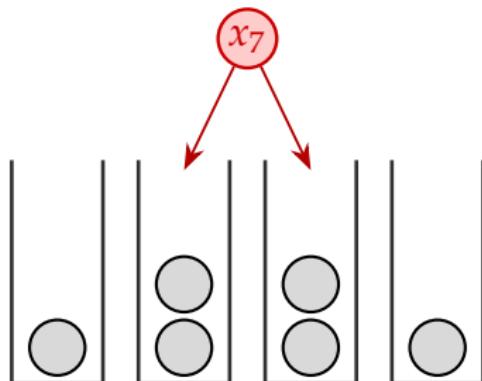


Computing **Greedy**($S \cup \{x^*\}$)

Subsequent balls will experience either:

1. No recourse

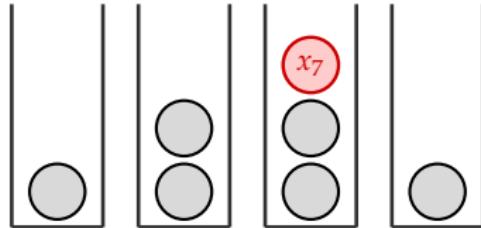
ANALYZING THE RE COURSE



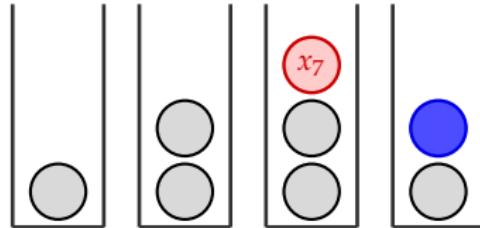
Subsequent balls will experience either:

1. No recourse

ANALYZING THE RE COURSE



Computing Greedy(S)

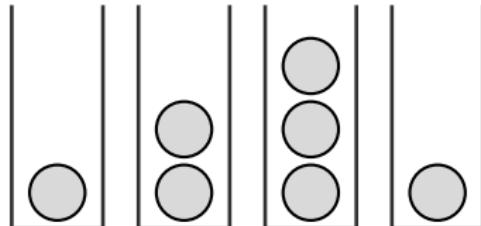


Computing Greedy($S \cup \{x^*\}$)

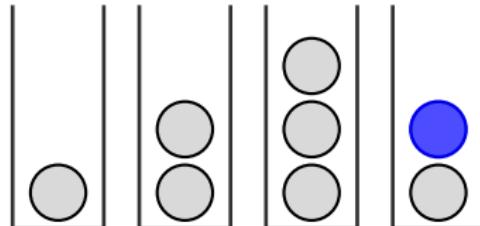
Subsequent balls will experience either:

1. No recourse

ANALYZING THE RE COURSE



Computing **Greedy**(S)

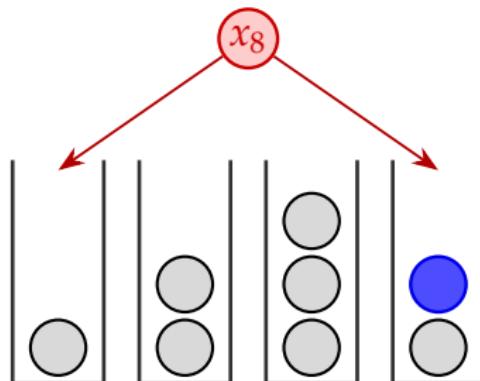
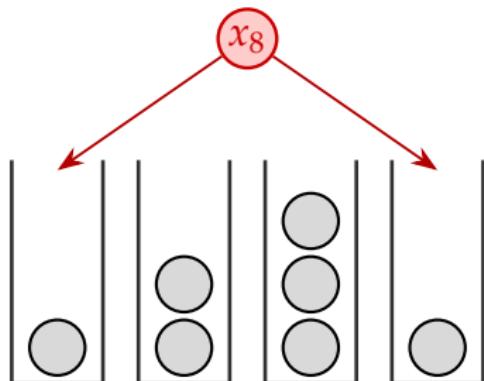


Computing **Greedy**($S \cup \{x^*\}$)

Subsequent balls will experience either:

1. No recourse
2. Recourse

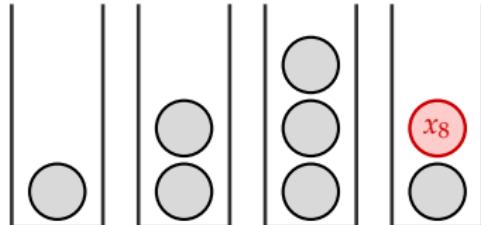
ANALYZING THE RE COURSE



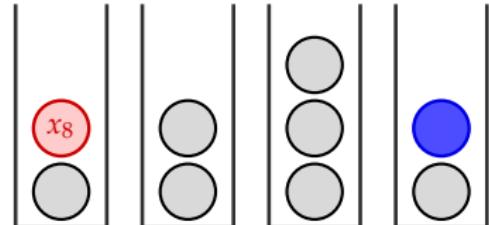
Subsequent balls will experience either:

1. No recourse
2. Recourse

ANALYZING THE RE COURSE



Computing **Greedy**(S)

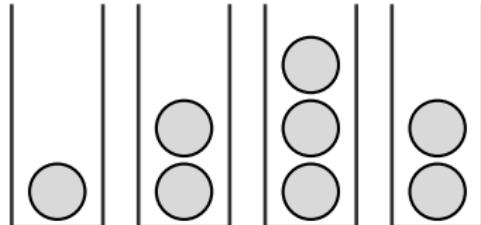


Computing **Greedy**($S \cup \{x^*\}$)

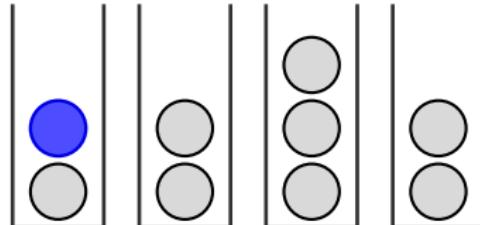
Subsequent balls will experience either:

1. No recourse
2. Recourse

ANALYZING THE RE COURSE



Computing Greedy(S)

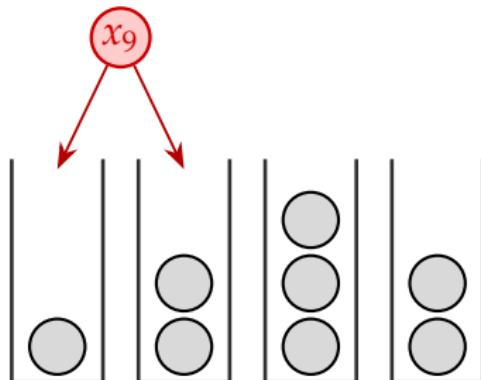


Computing Greedy($S \cup \{x^*\}$)

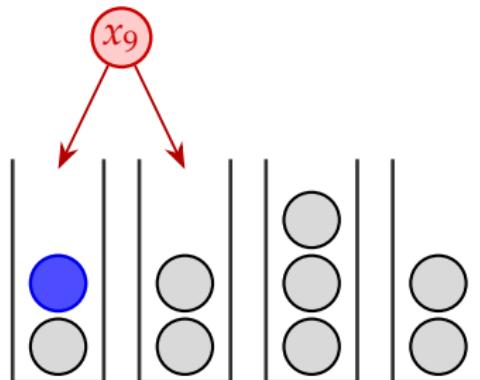
Subsequent balls will experience either:

1. No recourse
2. Recourse

ANALYZING THE RE COURSE



Computing Greedy(S)

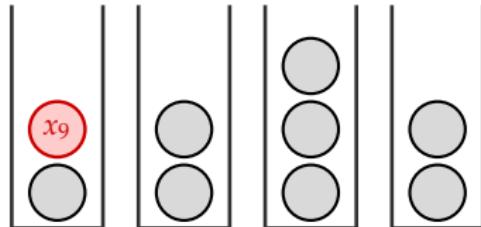


Computing Greedy($S \cup \{x^*\}$)

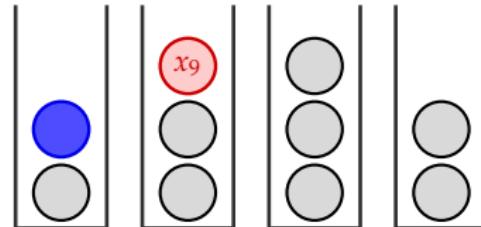
Subsequent balls will experience either:

1. No recourse
2. Recourse

ANALYZING THE RE COURSE



Computing **Greedy**(S)

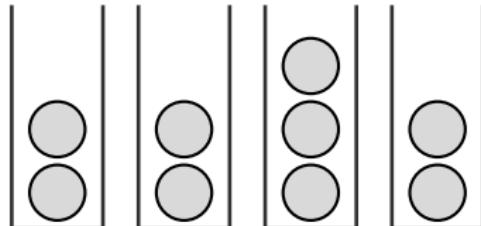


Computing **Greedy**($S \cup \{x^*\}$)

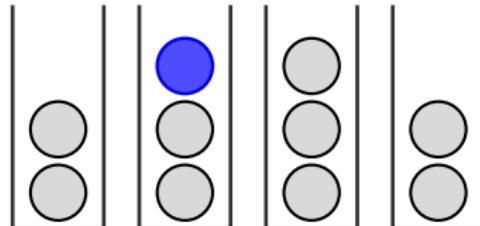
Subsequent balls will experience either:

1. No recourse
2. Recourse

ANALYZING THE RE COURSE



Computing Greedy(S)

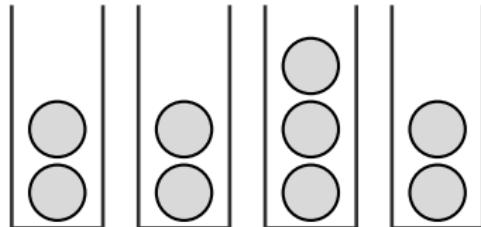


Computing Greedy($S \cup \{x^*\}$)

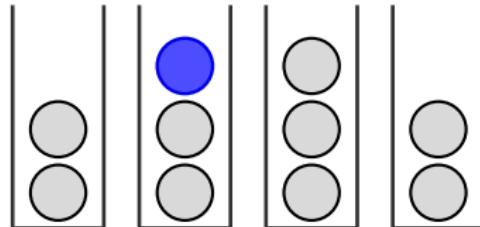
Subsequent balls will experience either:

1. No recourse
2. Recourse

ANALYZING THE RE COURSE



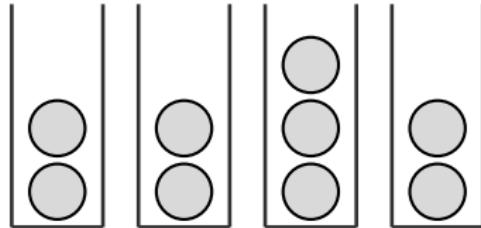
Computing Greedy(S)



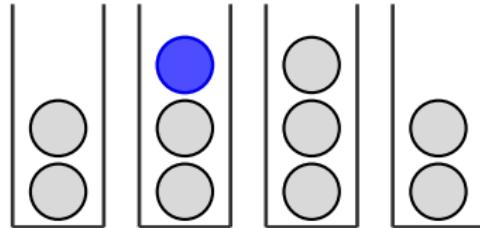
Computing Greedy($S \cup \{x^*\}$)

Two key observations:

ANALYZING THE RE COURSE



Computing **Greedy**(S)

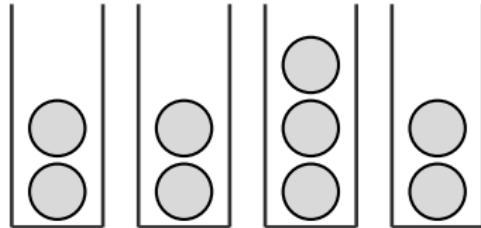


Computing **Greedy**($S \cup \{x^*\}$)

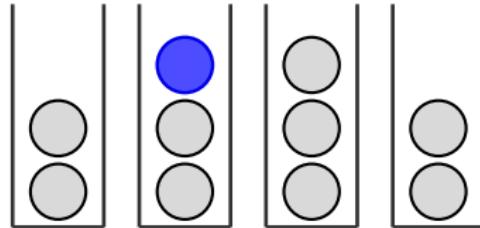
Two key observations:

1. There's always one special bin with an extra ball

ANALYZING THE RE COURSE



Computing **Greedy**(S)

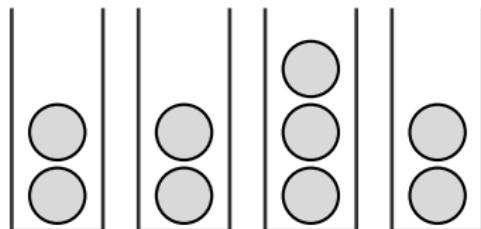


Computing **Greedy**($S \cup \{x^*\}$)

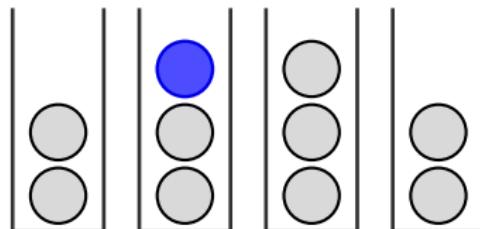
Two key observations:

1. There's always one special bin with an extra ball
2. If a ball incurs recourse, one of its choices is the special bin

ANALYZING THE RE COURSE



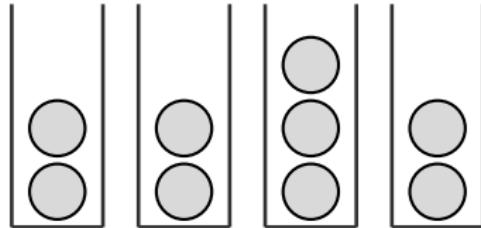
Computing **Greedy**(S)



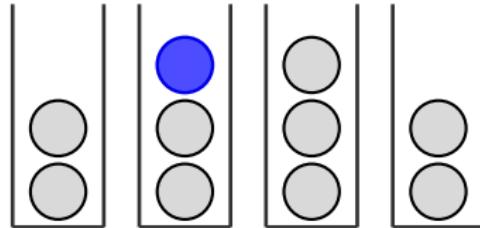
Computing **Greedy**($S \cup \{x^*\}$)

$$\Pr[\text{ball } x_i \text{ incurs recourse}] = O(1/n)$$

ANALYZING THE RECOURSE



Computing $\text{Greedy}(S)$



Computing $\text{Greedy}(S \cup \{x^*\})$

$$\Pr[\text{ball } x_i \text{ incurs recourse}] = O(1/n)$$

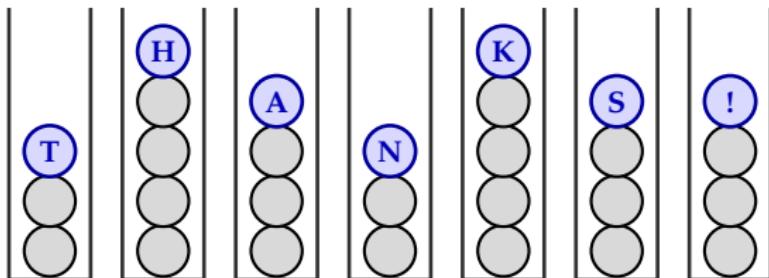
$$\implies \mathbb{E}[\text{total recourse}] = \sum_i \Pr[\text{ball } x_i \text{ incurs recourse}] = O(m/n)$$

A SIMPLE WARMUP

Theorem: There exists a history-independent solution with:

- ▶ High-probability overload $\Theta(1)$ $O(\log \log n)$.
- ▶ Expected recourse $\Theta(\log \log(m/n))$ $O(m/n)$.

History-Independent Load Balancing



Michael A. Bender

Stony Brook University

Bill Kuszmaul

CMU

Elaine Shi

CMU

Rose Silver

CMU