

# Approximation Algorithms

# Admin

- Assignment 9 is due on Wednesday!
  - Questions on randomized algorithms and hashing
  - Last HW you will turn in
- Deferring lecture on randomized data structures: skip lists, cuckoo hash
- Will start approximation algorithm instead so you have some examples before you attempt HW 9 problems
- CS major advising: "drop in" hours this week (no reserved slots)
  - Can go to mine or any prof's hours and discuss plans
  - Important to fill out worksheet and submit transcript before the meeting

# Approximate TSP

# Traveling Salesman Problem

- Recall the traveling salesman problem: Given  $n$  cities labeled  $v_1, \dots, v_n$ , and distance function  $d(i, j)$ , the distance from city  $v_i$  to city  $v_j$
- **TSP. (Decision Version)** Given target  $D$ , is there a tour that visits every city and returns to the starting city with total length at most  $D$ ?
- **NP complete problem.** Recall reduction from Hamiltonian cycle.
- Given directed graph  $G = (V, E)$ , define instance of TSP as:
  - City  $c_i$  for each node  $v_i$
  - $d(c_i, c_j) = 1$  if  $(v_i, v_j) \in E$
  - $d(c_i, c_j) = 2$  if  $(v_i, v_j) \notin E$

# Approximation Algorithms

- Cannot optimally solve NP hard problems like TSP efficiently
- **Goal of approximation algorithms:** design efficient algorithms that return solutions "close" to the optimal
- **(Optimization version).** Find the tour of every city with min total distance
- **(Approximation algorithm for TSP).**
  - Let OPT be the TSP tour of minimum total length, then a  $c$ -approximation algorithm finds a TSP tour of total length that is at most  $c \cdot \text{OPT}$ , for some constant  $c > 1$
  - Example: a 2-approximation for TSP always returns a tour whose cost (total distance) is never more than twice that of the optimal solution

# Bad News: Approx-TSP is hard

- **Claim.** There is no polynomial-time  $c$ -approximation algorithm for the general TSP problem, for any constant  $c \geq 1$ , unless  $\mathbf{P} = \mathbf{NP}$ .
- **Proof.** Suppose there is a poly-time  $c$ -approximation algorithm  $A$  that computes a TSP tour of total weight at most  $c \cdot \text{OPT}$
- Show that  $A$  can be used to solve the Hamiltonian cycle problem
- Modified reduction from Hamiltonian cycle instance  $G$  to TSP instance:
  - $d(c_i, c_j) = 1$  if  $(v_i, v_j) \in E$  and  $d(c_i, c_j) = cn + 1$  if  $(v_i, v_j) \notin E$
- If  $G$  has a Hamiltonian cycle: there is a tour of length exactly  $n$
- If  $G$  does not have a Hamiltonian cycle, any tour has length at least  $cn + 1$

# Bad News: Approx-TSP is hard

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- **Proof. (Cont).** If  $G$  has a Hamiltonian cycle: there is a tour of length exactly  $n$
- If  $G$  does not have a Hamiltonian cycle, any tour has length at least  $cn + 1$
- $A$  computes tour of length at most  $cn \iff G$  has a Hamiltonian cycle:
  - $A$  solves Hamiltonian cycle in polynomial time and  $P = NP$
- **[More Bad news]**  
For any function  $f(n)$  that can be computed in polynomial time in  $n$ , there is no polynomial-time  $f(n)$ -approximation for TSP on general weighted graphs, unless  $P = NP$ .

# Good News: Metric TSP is Not

- While approximating TSP on general distances is NP hard, the common special case can be approximate easily
- **Metric TSP.** TSP problem on metric distances, that is,  $d$  satisfies:
  - $d(i, j) \leq d(i, k) + d(k, j)$  for any cities  $i, j, k$  [Triangle inequality]
  - $d(i, i) = 0$  and  $d(i, j) \geq 0$  [Identity and Non-negative]
  - $d(i, j) = d(j, i)$  [Symmetric]
- Euclidean distances are an example of metric distances
- **Metric TSP** is still NP complete (reduction from undirected Ham cycle)
  - Setting  $d(c_i, c_j) = 2$  when  $(v_i, v_j) \notin E$  satisfies triangle inequality



# Approximating Metric TSP

# Approximating an NP Hard Problem

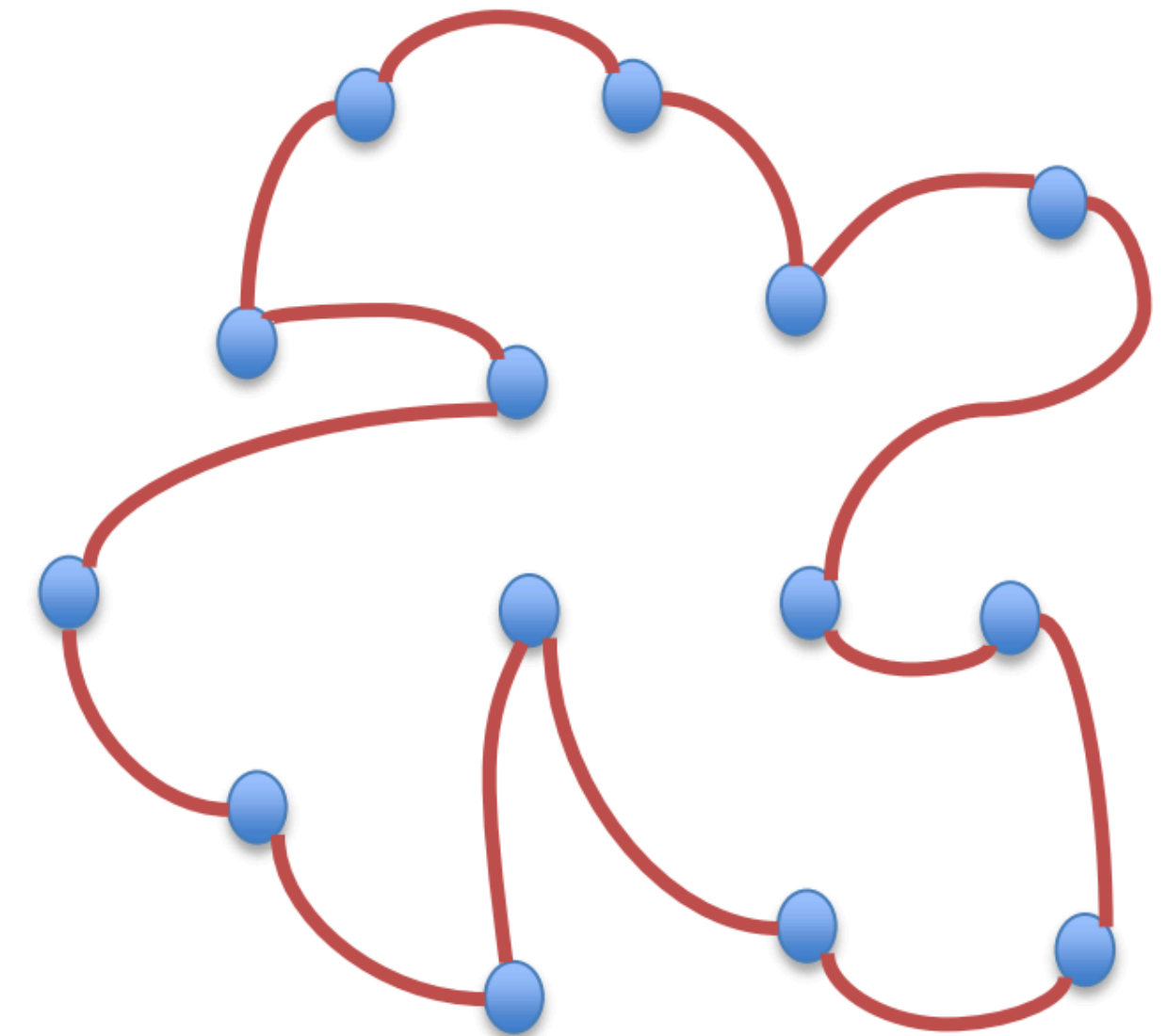
- (Metric TSP) Consider the **weighted complete graph**  $G$  where each vertex is a city, and each edge  $(i,j)$  for  $i,j \in V$  has weight equal to the distance  $d(i,j)$ , where  $d$  satisfies the triangle inequality
- **(NP hard problem)**. Find the tour of every city with min total distance
- **(Goal:  $c$ -approximation)**. Design an algorithm that finds a TSP tour of total length that is at most  $c \cdot \text{OPT}$ , for some constant  $c > 1$
- Remember, we don't actually know what the optimal algorithm or OPT actually is: we need to approximate without knowing that
- We do this by relating (upper and lower bounding) the cost of the approximation algorithm and OPT via a carefully chosen function

# Approximating Metric TSP

- Consider the weighted complete graph  $G$  where each vertex is a city, and each edge  $(i,j)$  for  $i,j \in V$  has weight equal to the distance  $d(i,j)$ , where  $d$  satisfies the triangle inequality
- **(Optimization version).** Find the tour of every city with min total distance
- Steps to follow when designing an approximation algorithm for a minimization problem
  - **Lower bound the optimal cost** by some function of input
  - Upper bound the cost of algorithm by **the same function**
- Will use MSTs to derive these upper and lower bounds for metric TSP
- We give a 2-approximation to metric-TSP using minimum spanning trees

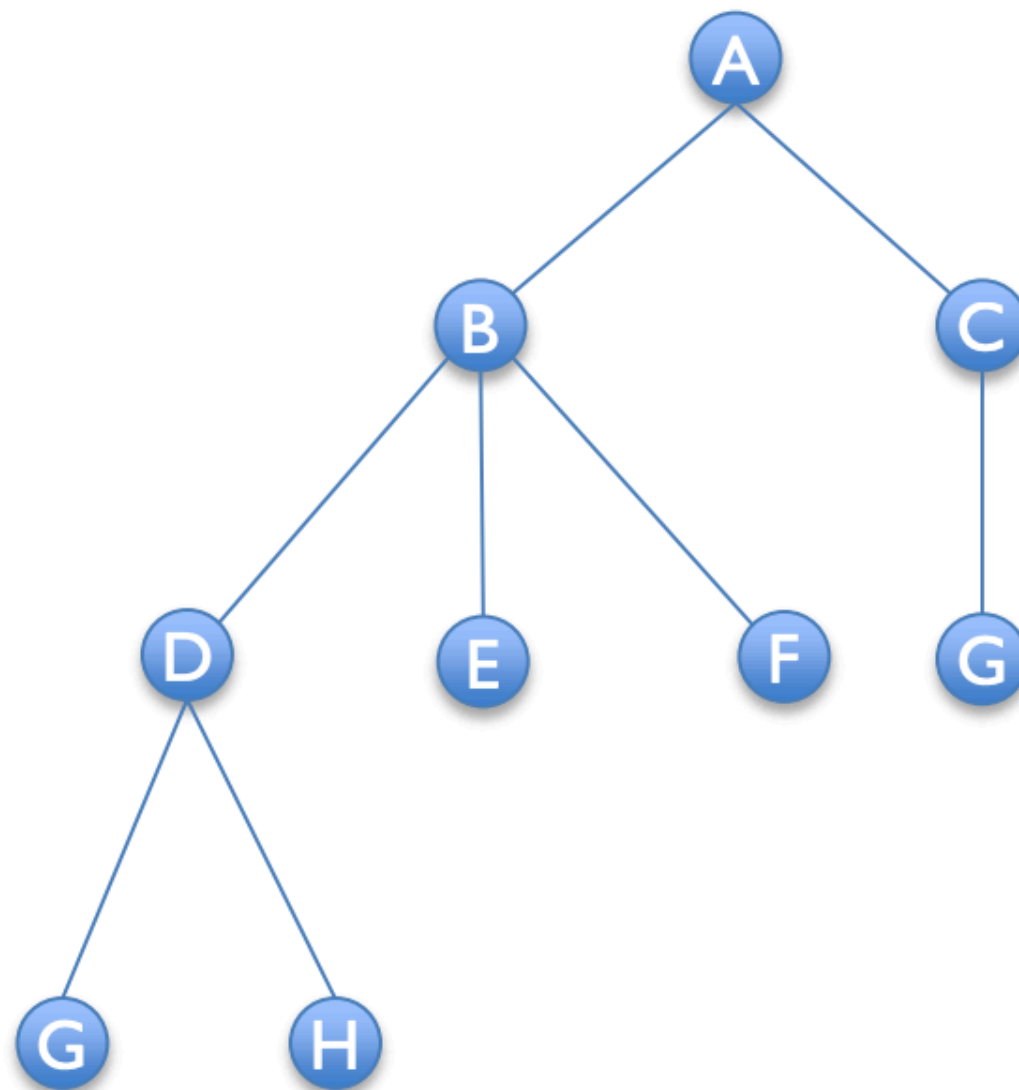
# Lower Bound on OPT

- Note that an optimal tour must not visit a city more than once:
  - Optimal tour is a simple cycle that visits all nodes
- **Claim.** Let  $T$  be the minimum spanning tree of  $G$  then length of the optimal tour  $\text{OPT} \geq w(T)$ .
- **Proof.** Take an optimal tour of length  $\text{OPT}$
- Drop an edge from it to obtain a spanning tree  $T'$
- Distances/weights are non-negative, so  $w(T') \leq \text{OPT}$
- $w(T) \leq w(T')$  ( $T$  is the MST)
- Thus  $w(T) \leq \text{OPT}$  ■



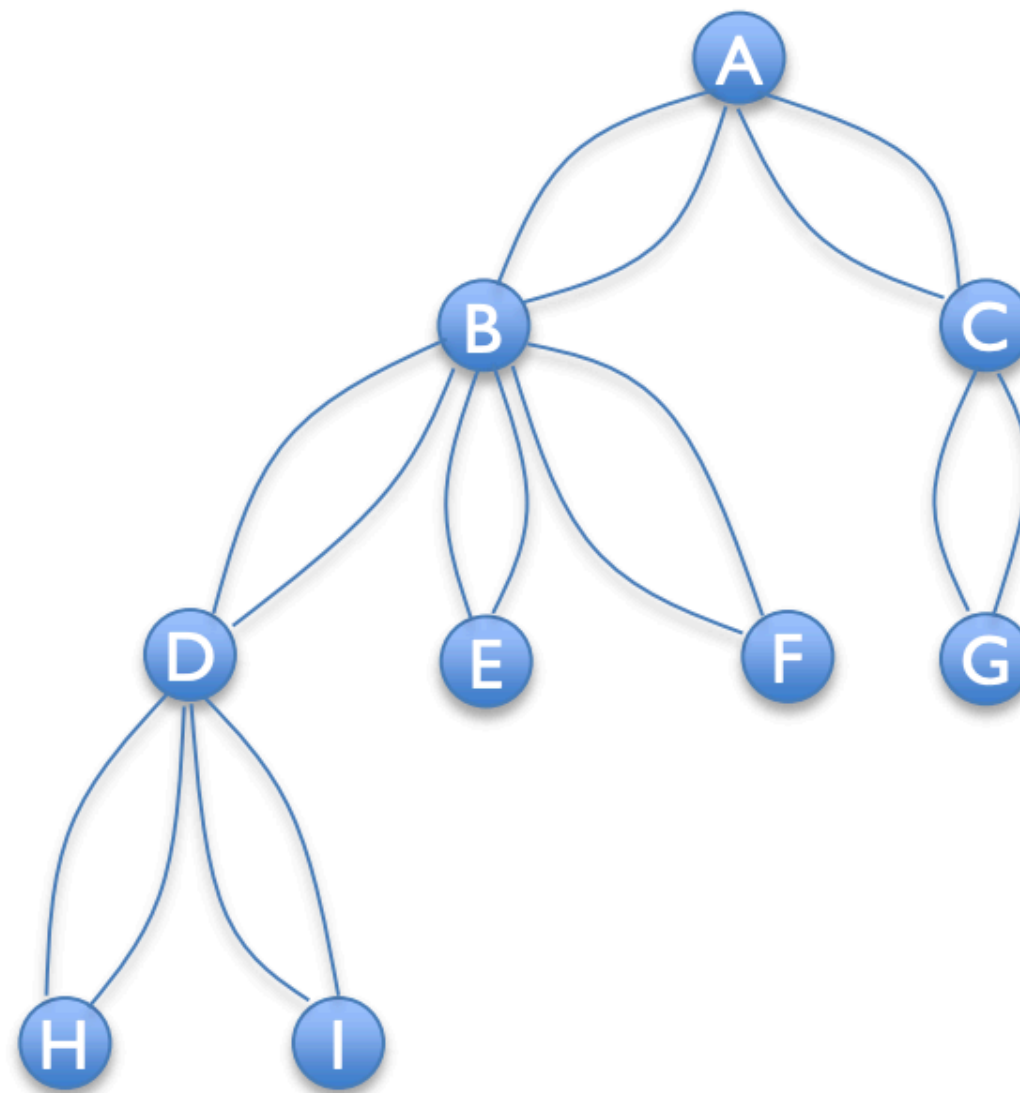
# Double Tree Algorithm

- **Find a minimum spanning tree  $T$**
- Duplicate every edge in  $T$
- Find an Eulerian tour of resulting multi-graph
- Shortcut Euler tour to avoid repeated vertices



# Double Tree Algorithm

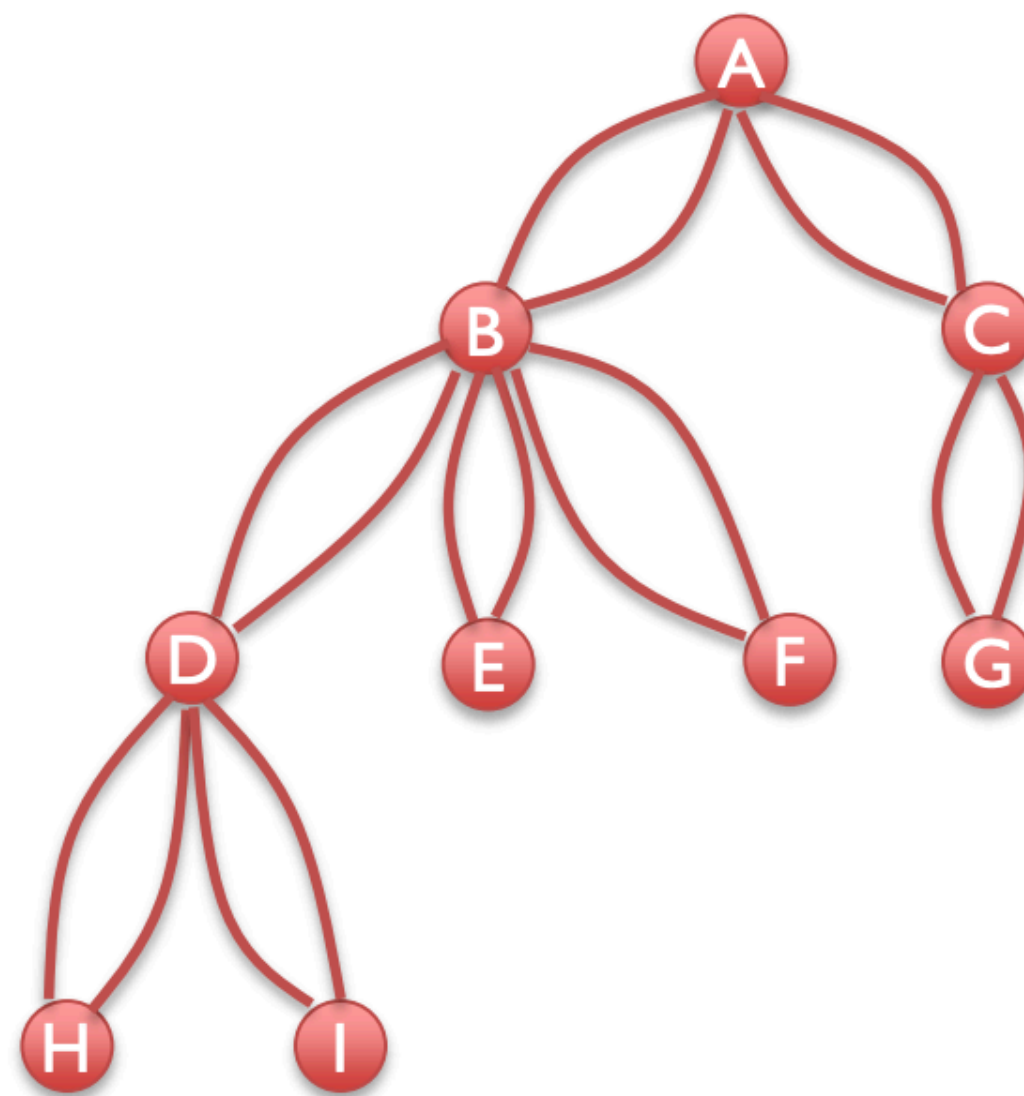
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Why must an Euler tour exist?



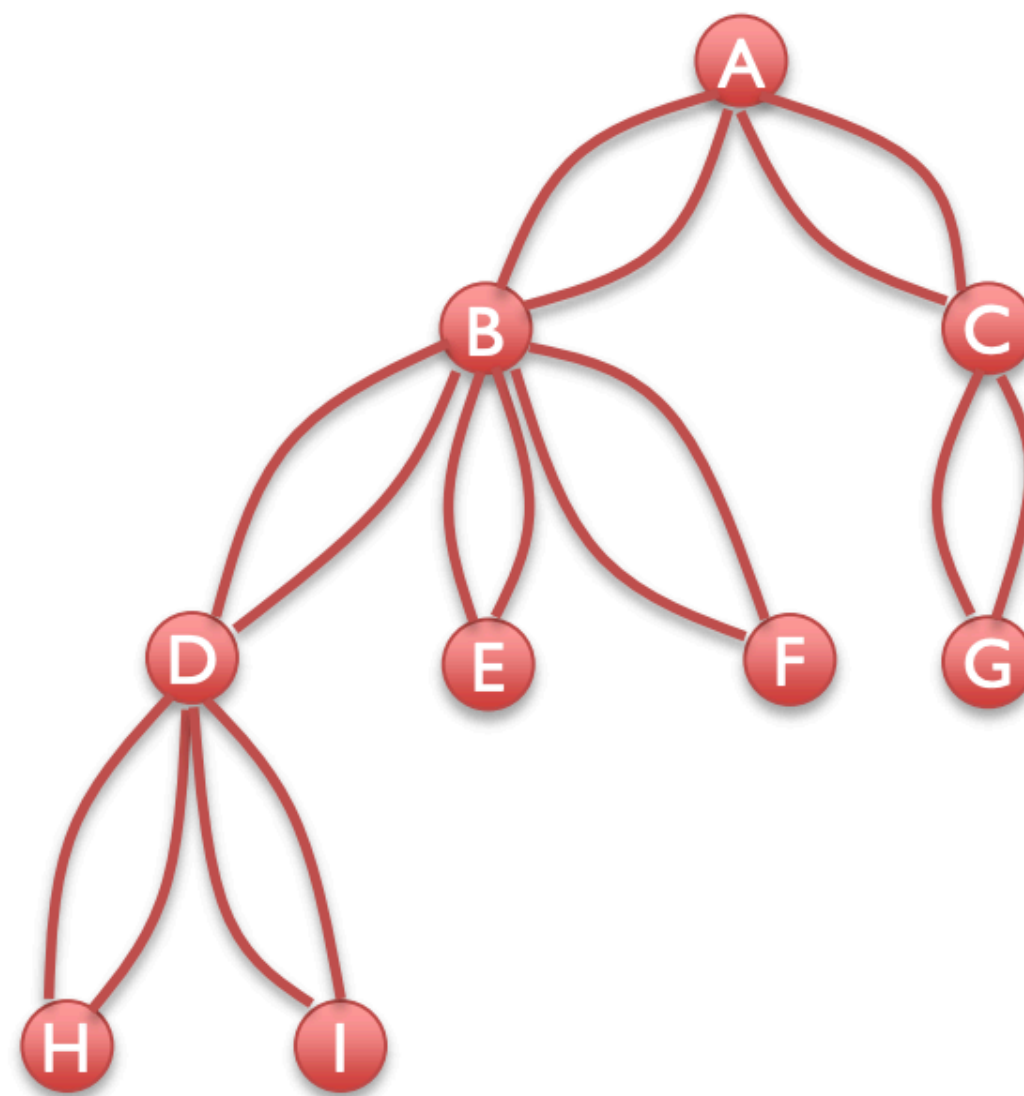
A,B,D,H,D,I,D,B,E,B,F,B,A,C,G,C,A



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A graph has an Euler tour iff all nodes have even degree

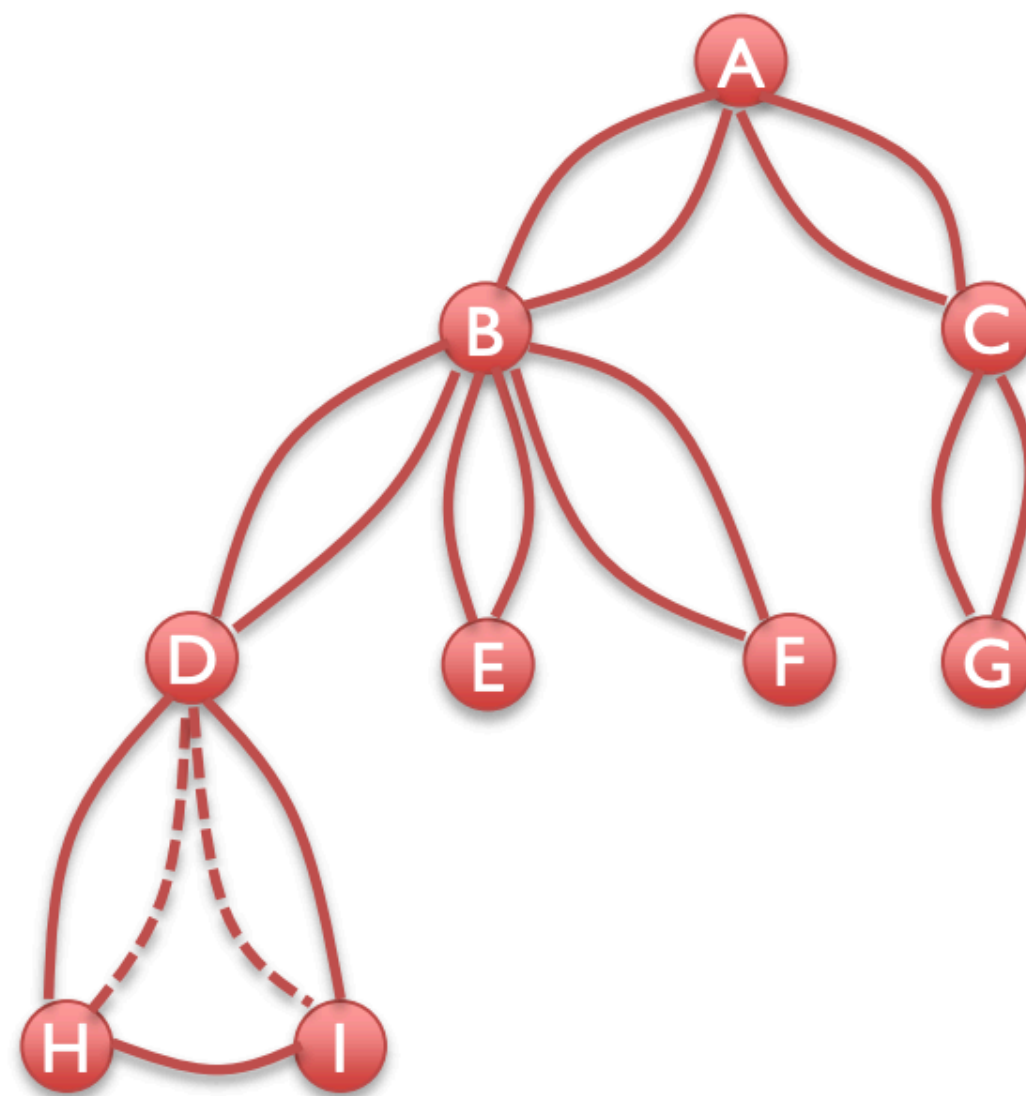


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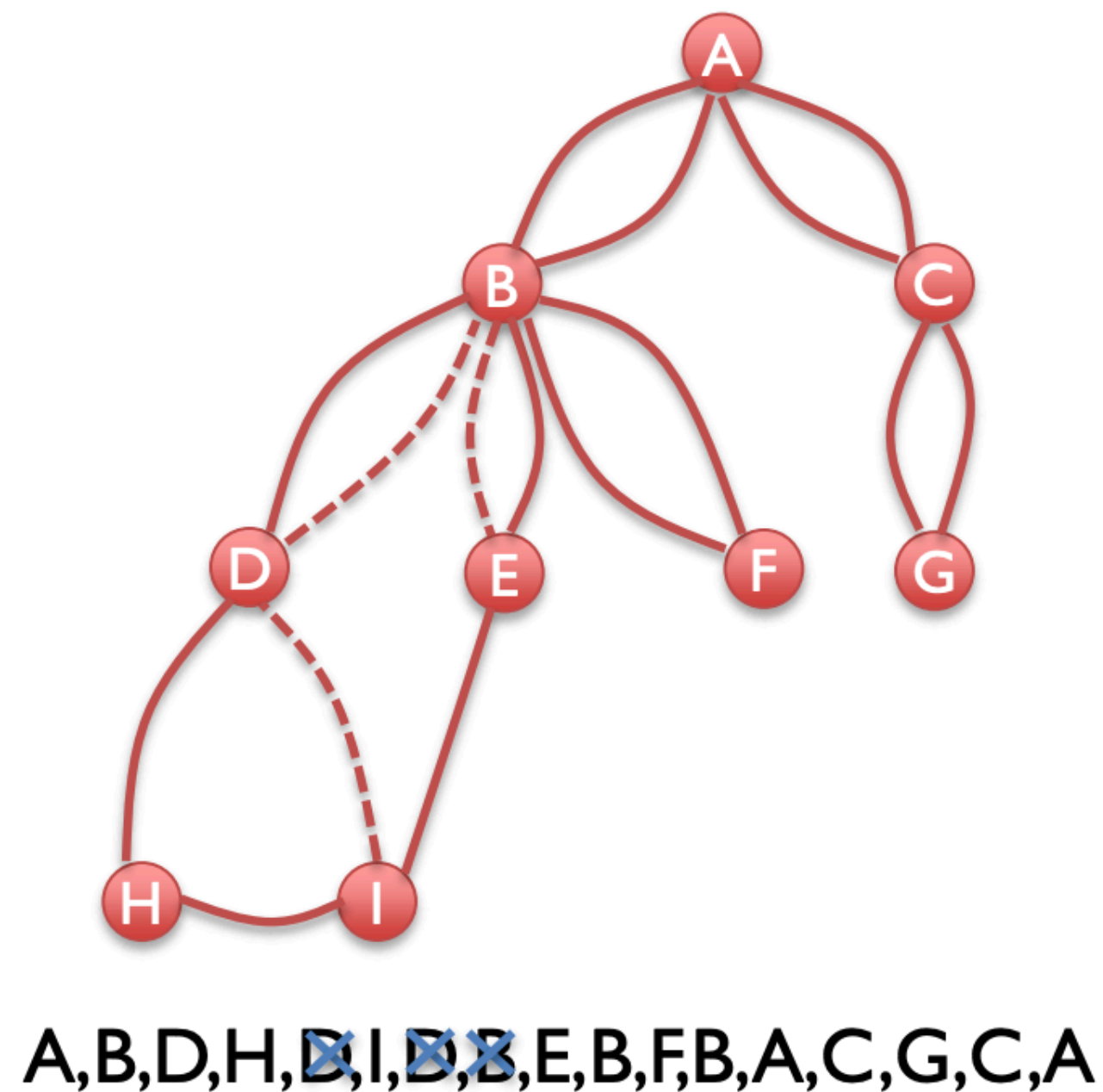
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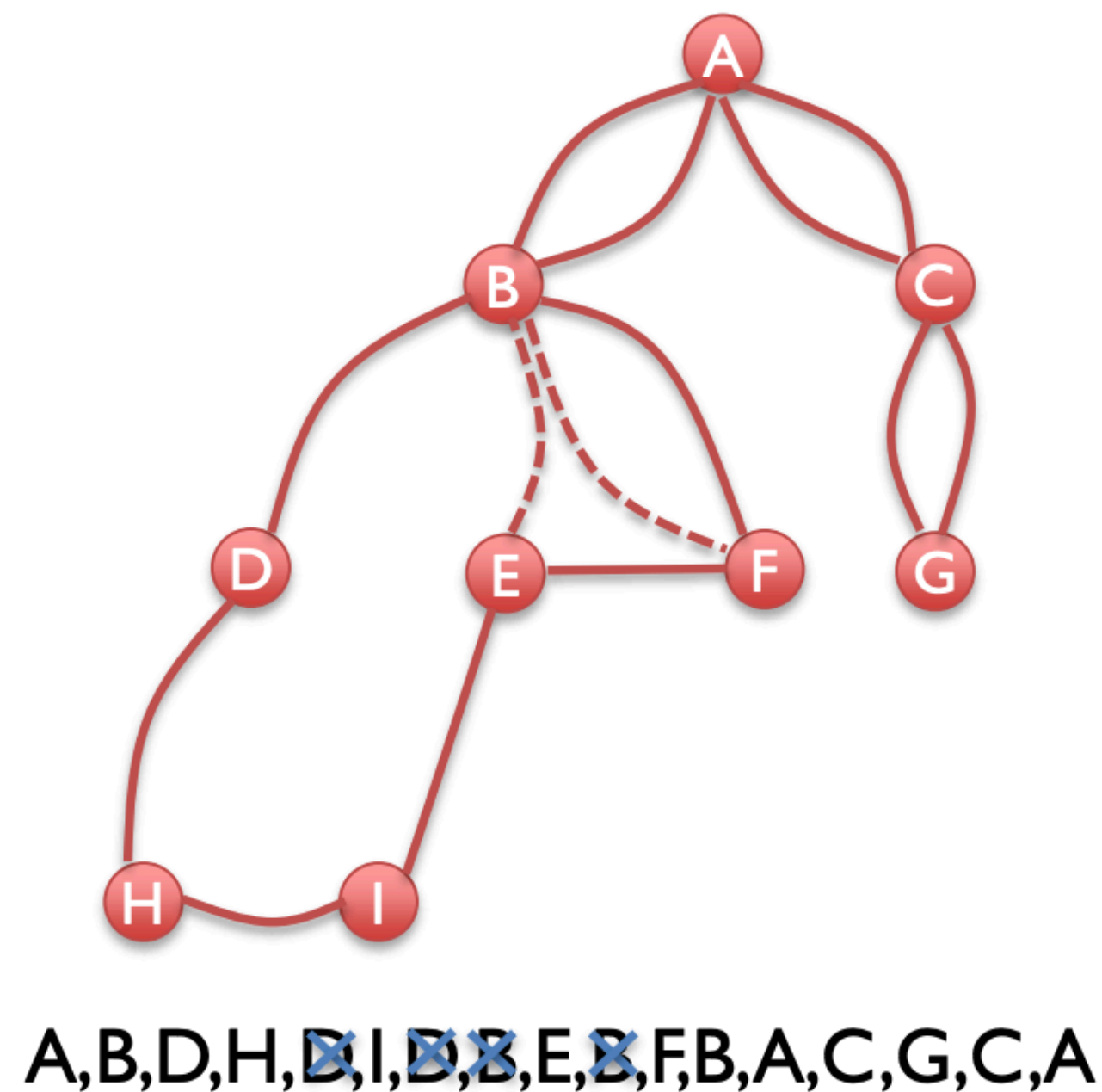
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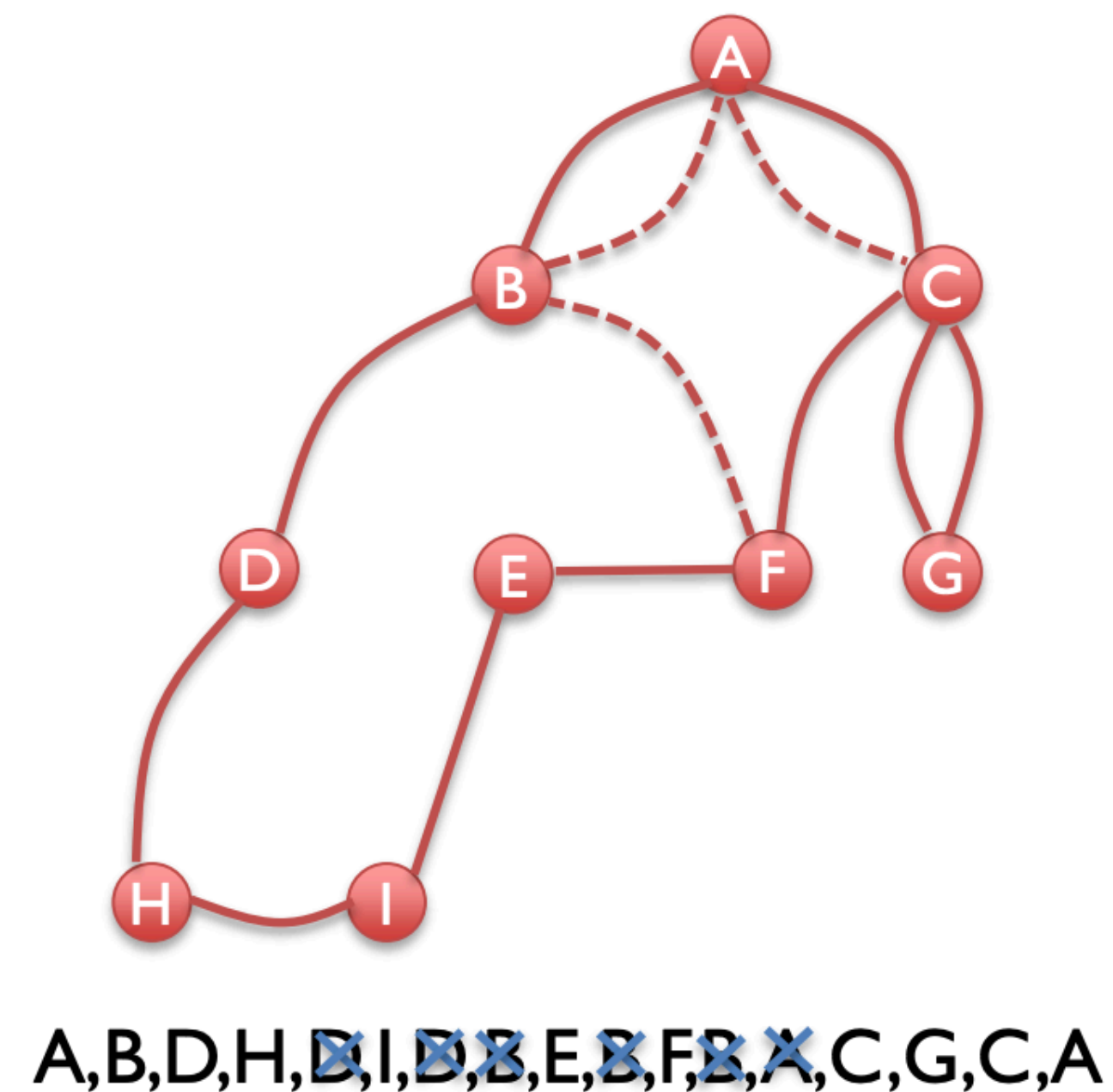
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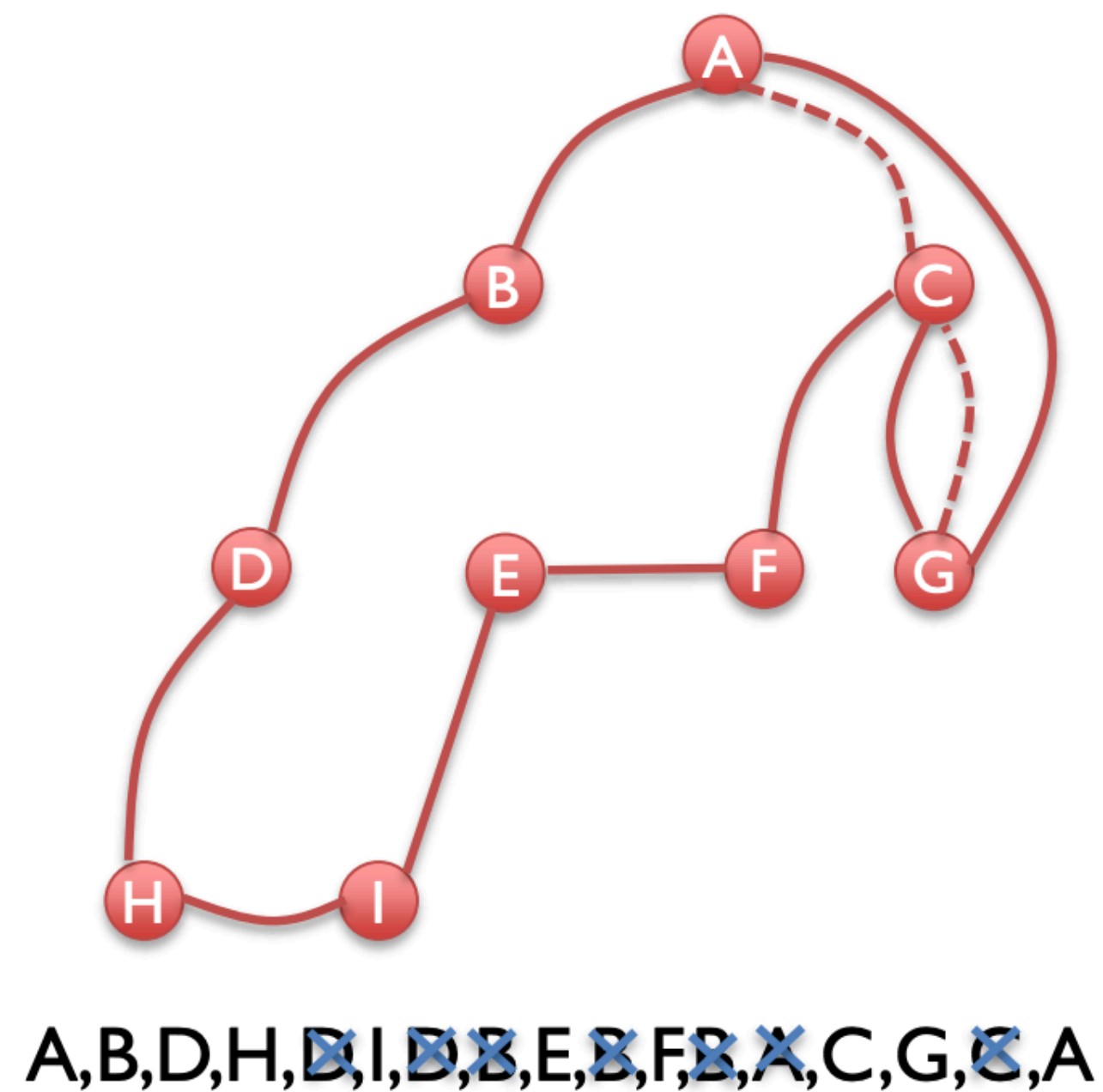
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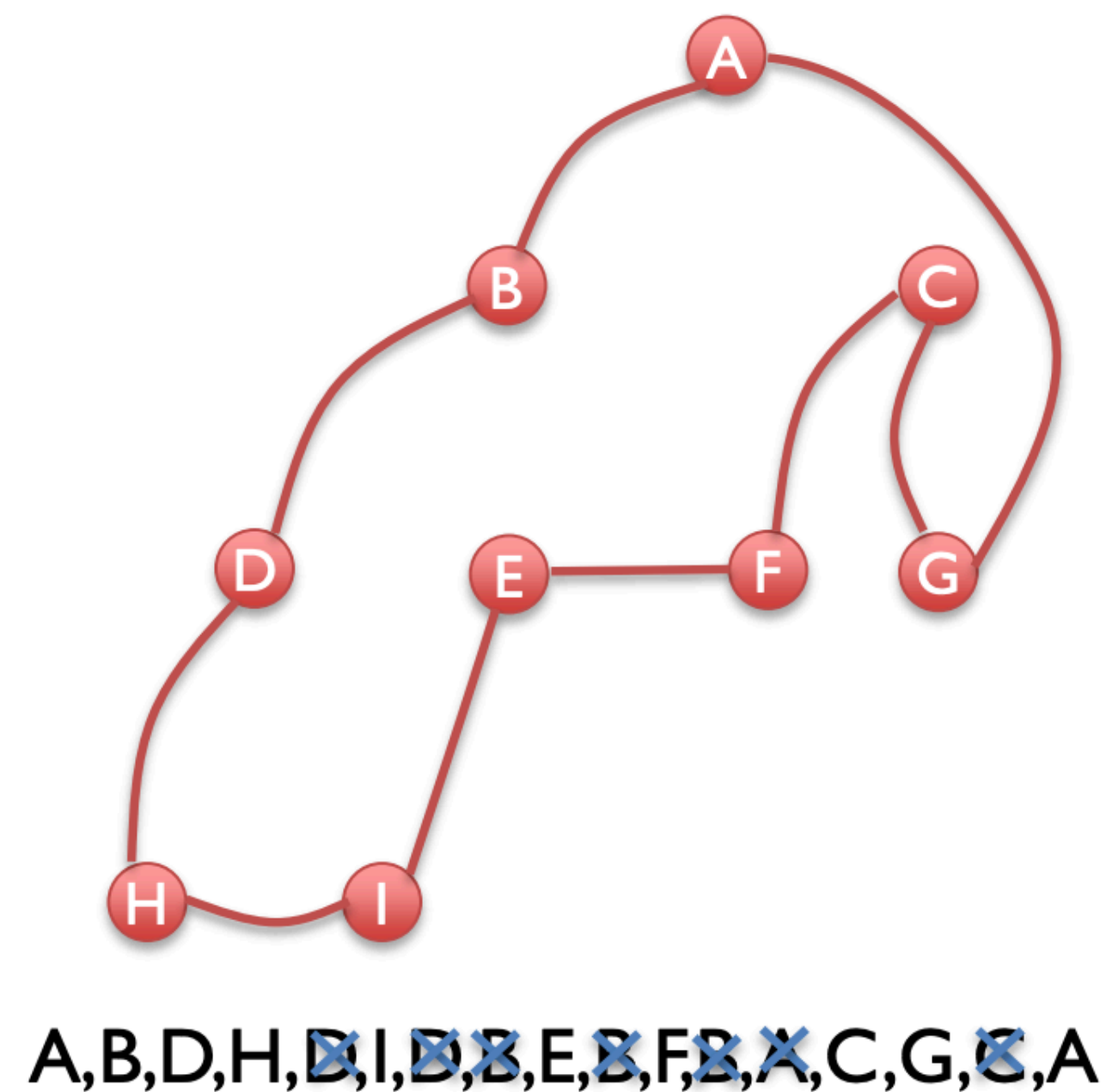
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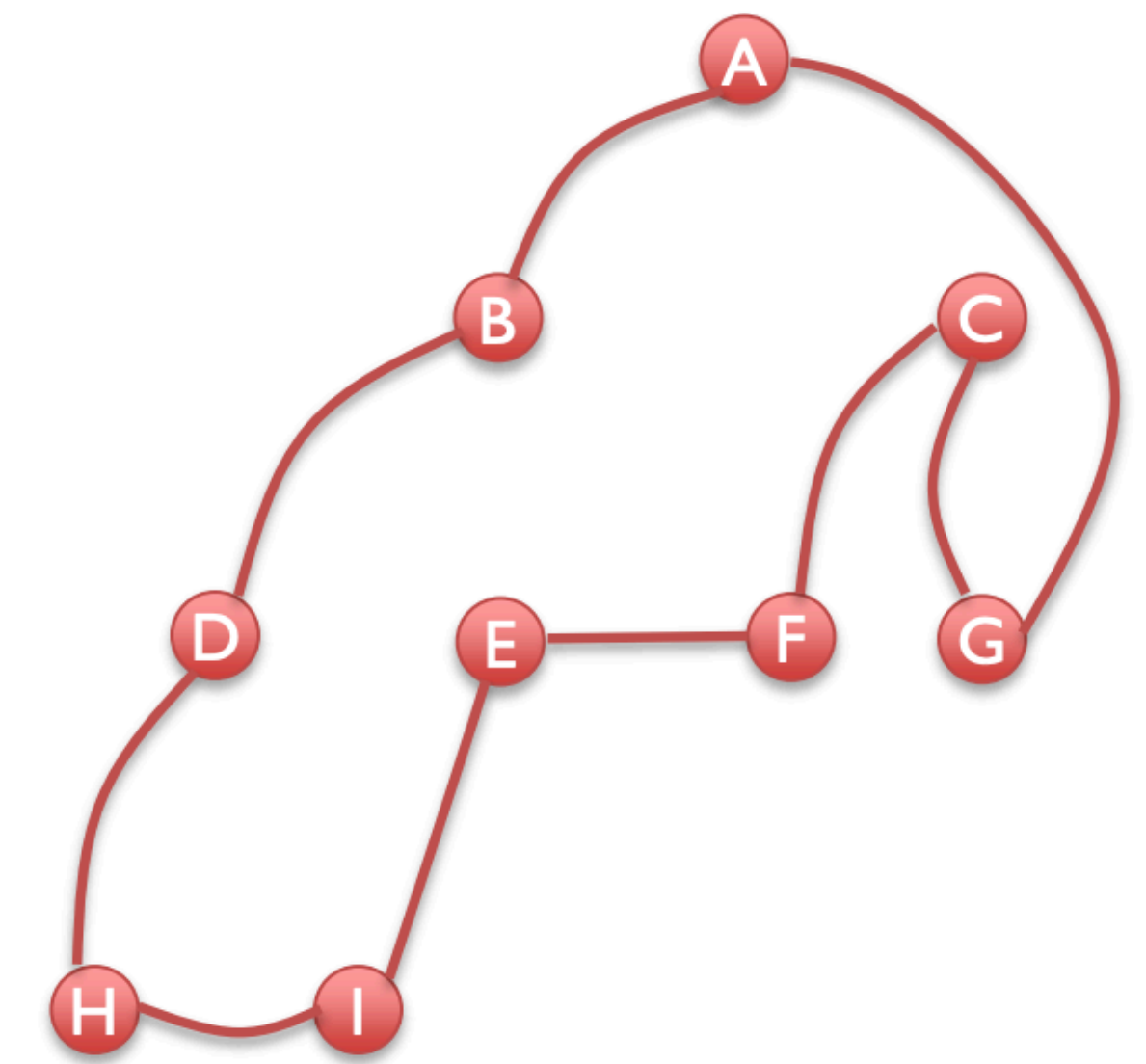
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# Double Tree Analysis

- **Claim.** Double-tree algorithm is a 2-approximation to TSP.
- **Proof.** The Euler tour visits every edge of MST  $T$  exactly twice, thus the length of tour  $= 2 \cdot w(T)$
- Due to triangle inequality, shortcutting the tour does not increase length
  - (Here is where metric distances play a role!)
- Thus length of short-circuited tour  $\leq 2 \cdot w(T)$
- Since  $w(T) \leq \text{OPT}$ , we get that our tour length is  $\leq 2 \cdot \text{OPT}$  ■



A,B,D,H,~~I~~,~~D~~,~~B~~,E,~~F~~,~~A~~,C,G,~~C~~,A

# Christofides-Serdyukov Algorithm

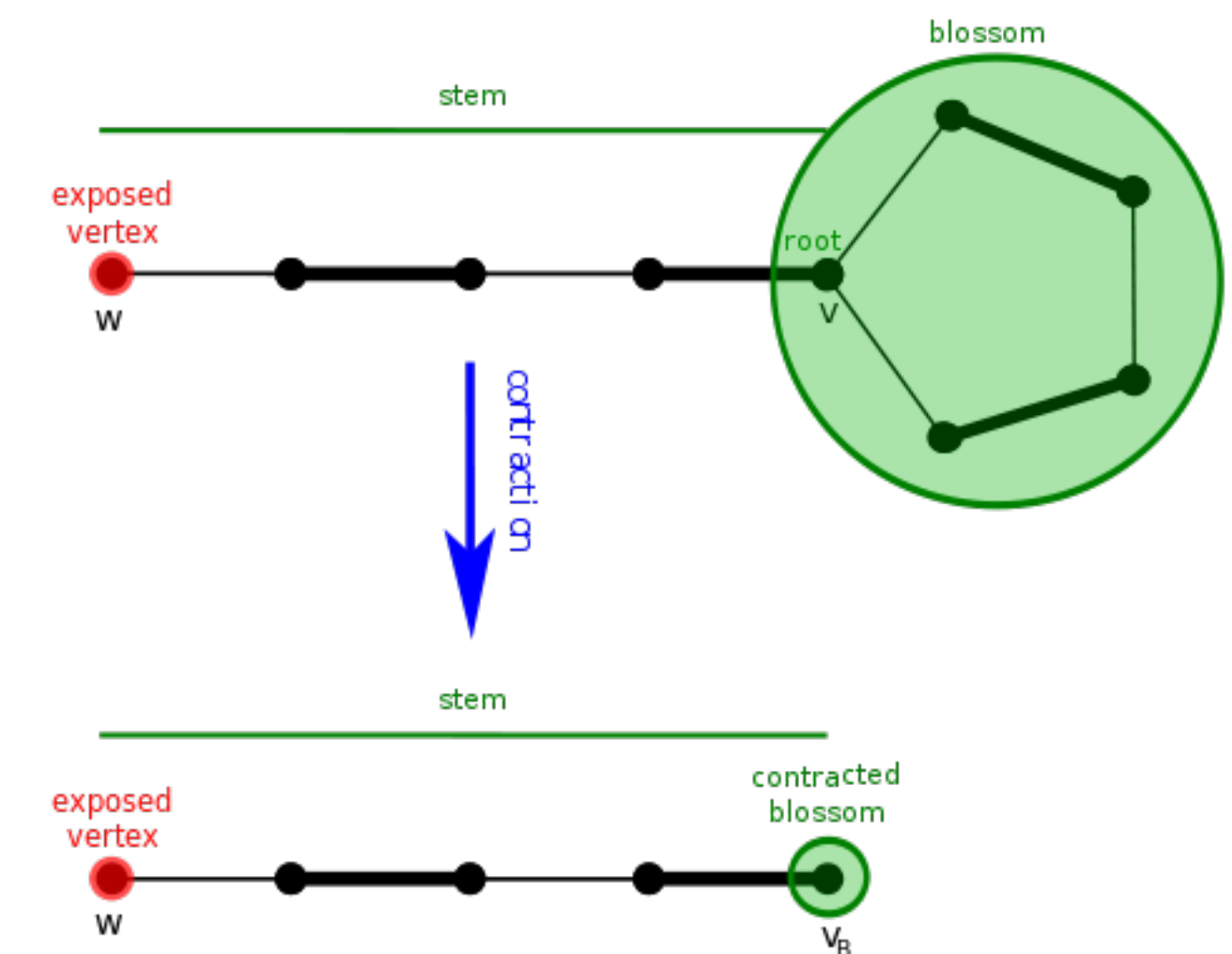
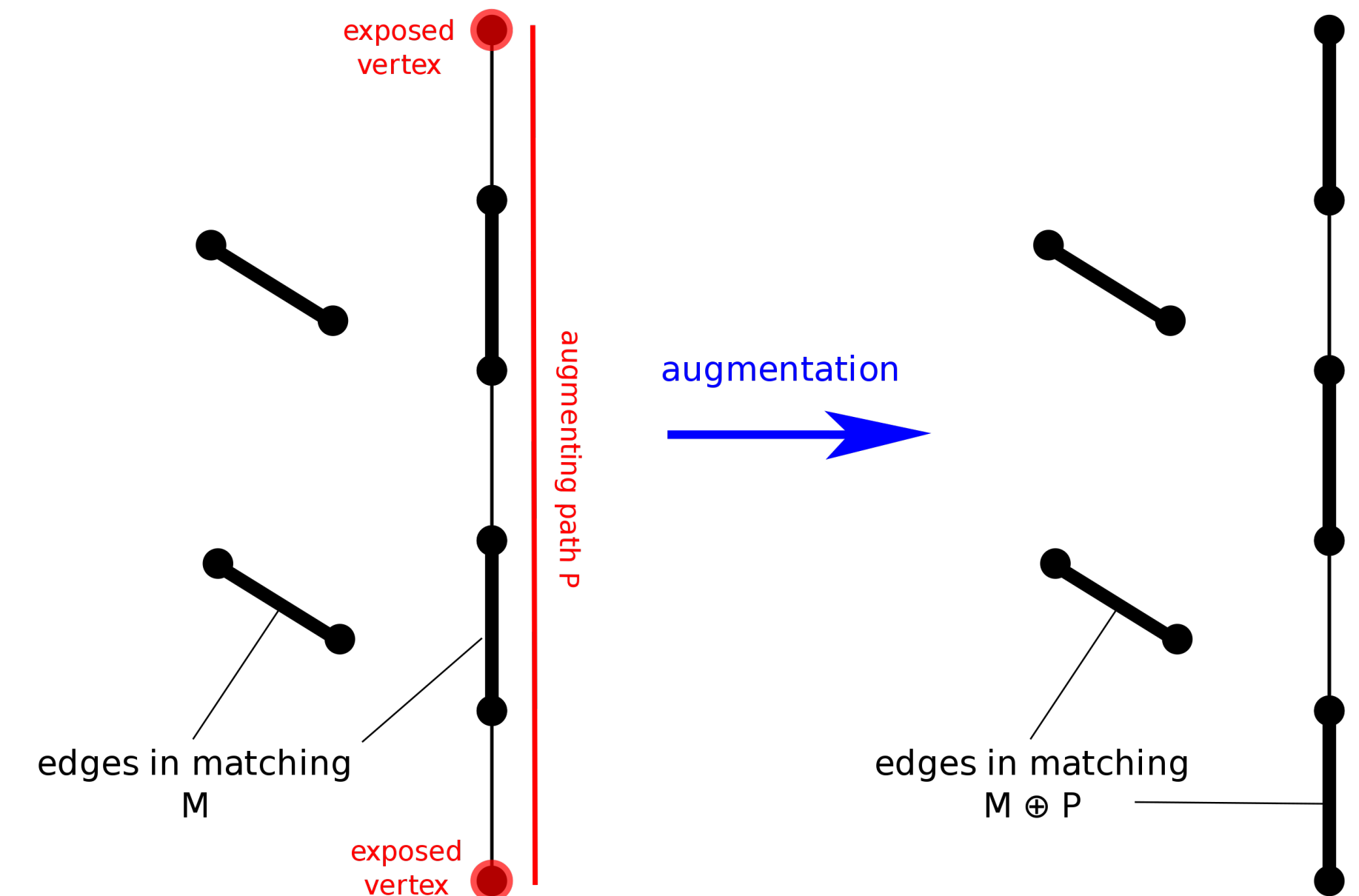


# Christofides Algorithm [Christofides 76][Serdyukov 76]

- Doubling the edges of MST is one way to achieve even degree nodes, but is there a cheaper way to augment the tree to obtain an Eulerian tour?
- What is the parity of odd degree vertices in an undirected graph?
  - Even number of odd degree vertices!
- **Christofides algorithm.** Starts with an MST, but fixes the parity of odd degree vertices by augmenting it with a matching
- **Matching.** A set of edges such that no two are adjacent
- **Perfect matching.** Every vertex is incident to exactly one edge in the matching
- **Fact We'll Use.** Minimum cost “perfect” matchings of any graph can be computed in polynomial time.

# Minimum Cost Matching

- Won't see in this class, unfortunately
- Edmond's "blossom" algorithm
- $O(|E| |V|^2)$  (slow, but much better than exponential)
- Somewhat similar to Ford-Fulkerson:
  - Use special structure to prove that we just need to find augmenting paths
  - Use data structures so that we can find augmenting paths quickly
- Tricky part: "augmenting paths" are more complicated when finding a matching

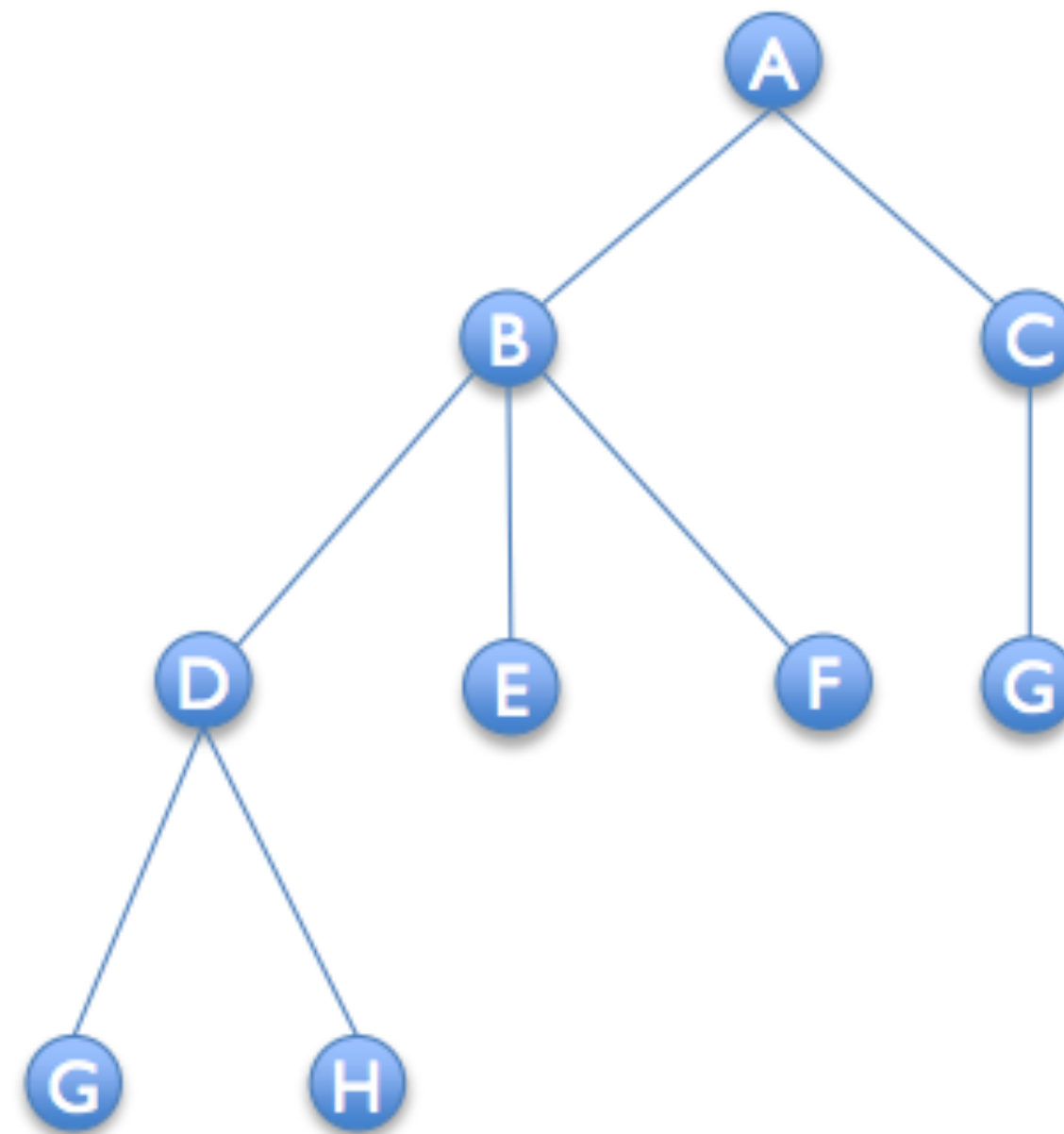


# Christofides Algorithm

- Find the minimum spanning tree  $T$
- Compute  $O$ : the set of odd degree vertices in  $T$
- Find the min-cost perfect matching  $M$  of subgraph induced by  $O$
- Return shortcut of Euler tour of  $T \cup M$

$|O|$  must be even

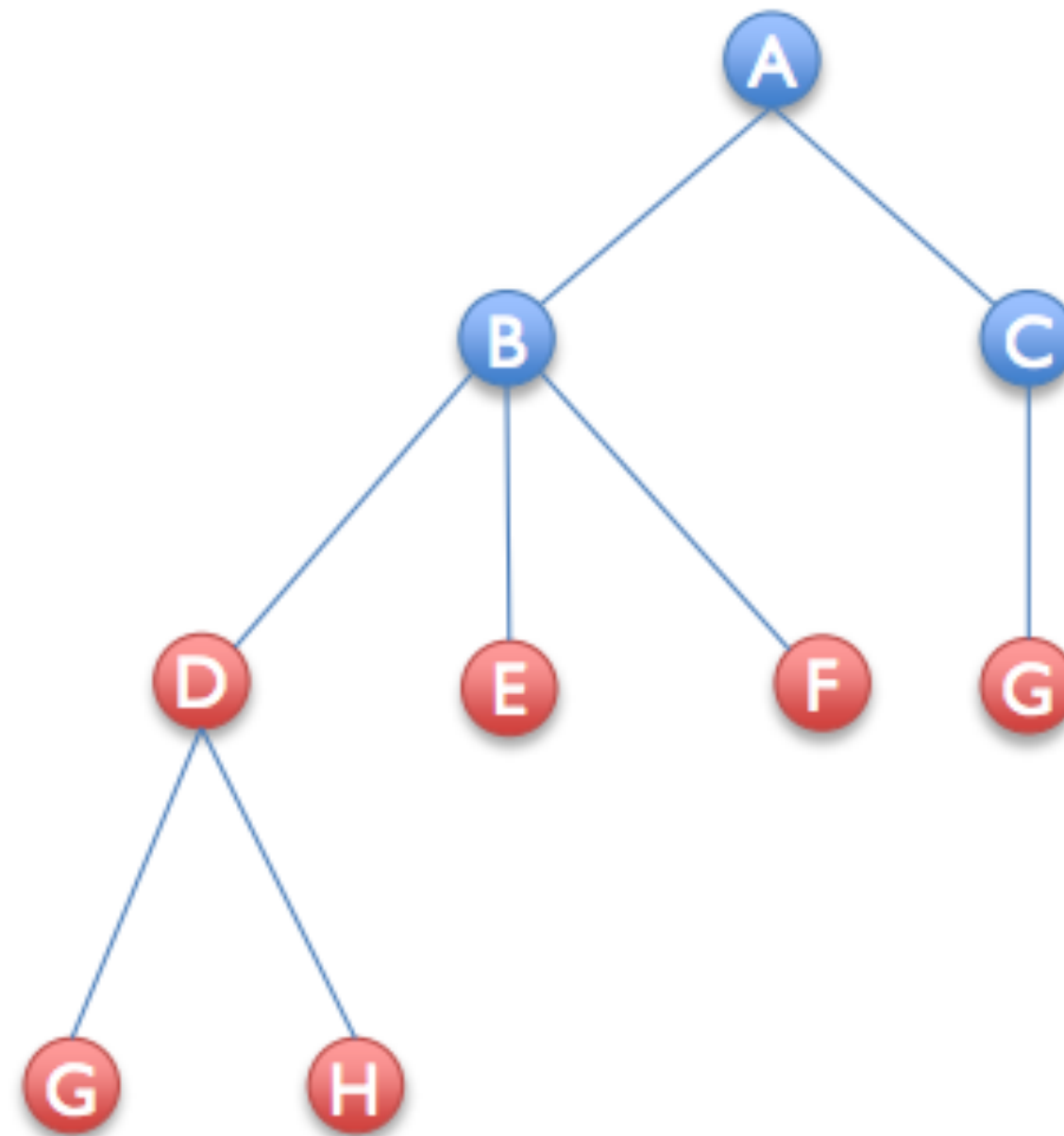
All odd-degree vertices  
and any edges  
connecting them



# Christofides Algorithm

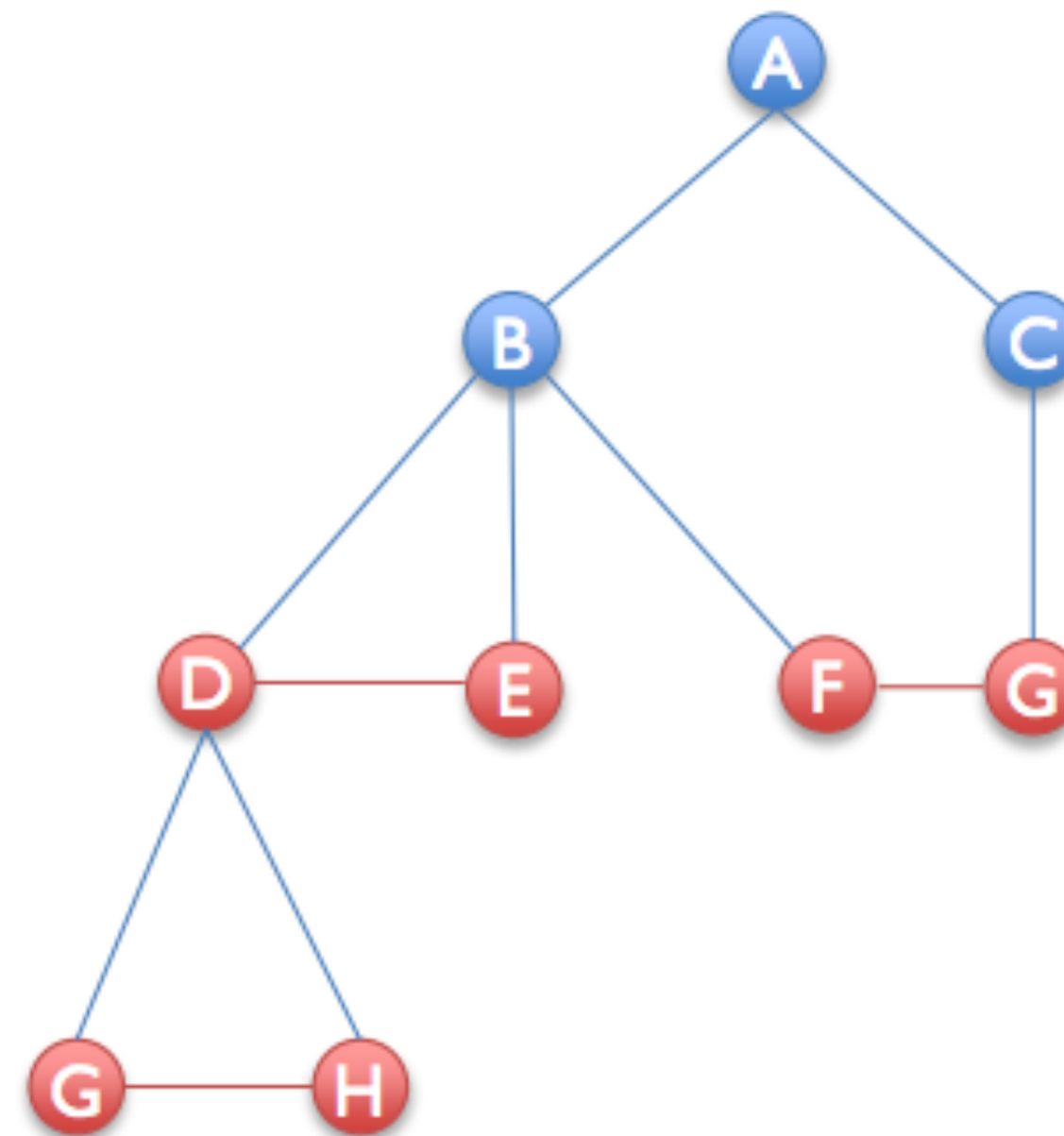
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What does adding  $M$  do to  $O$ ?



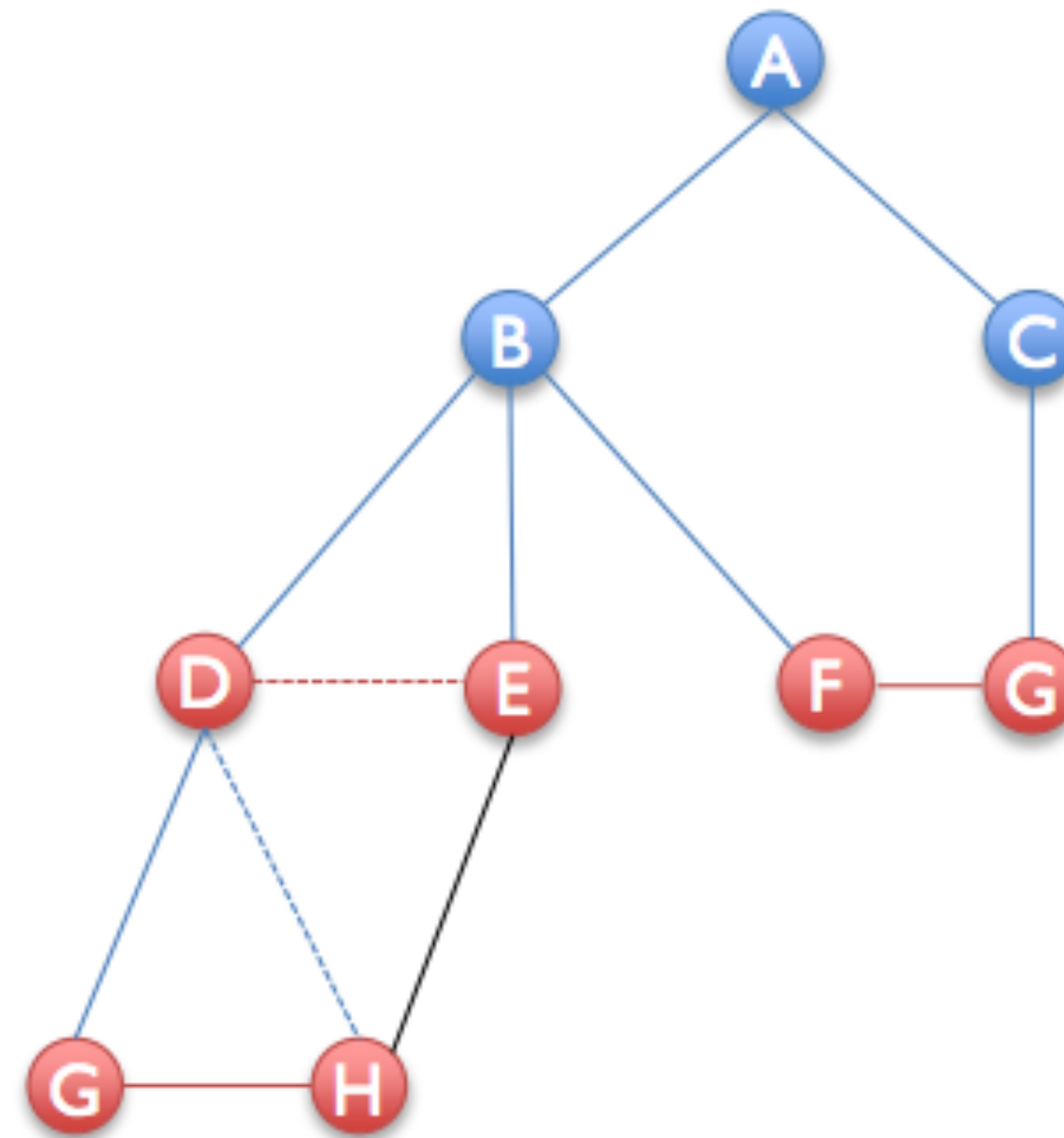
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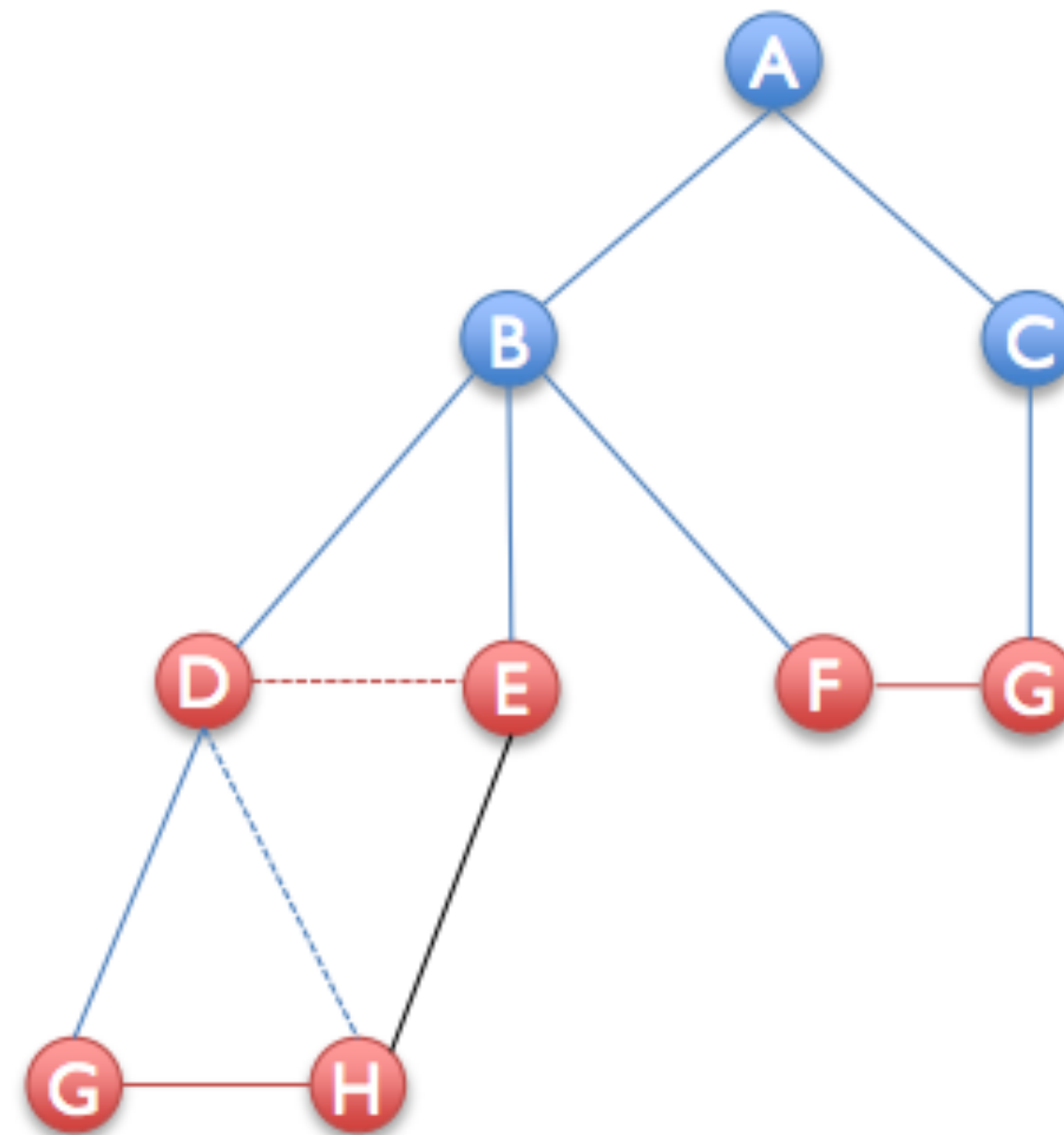
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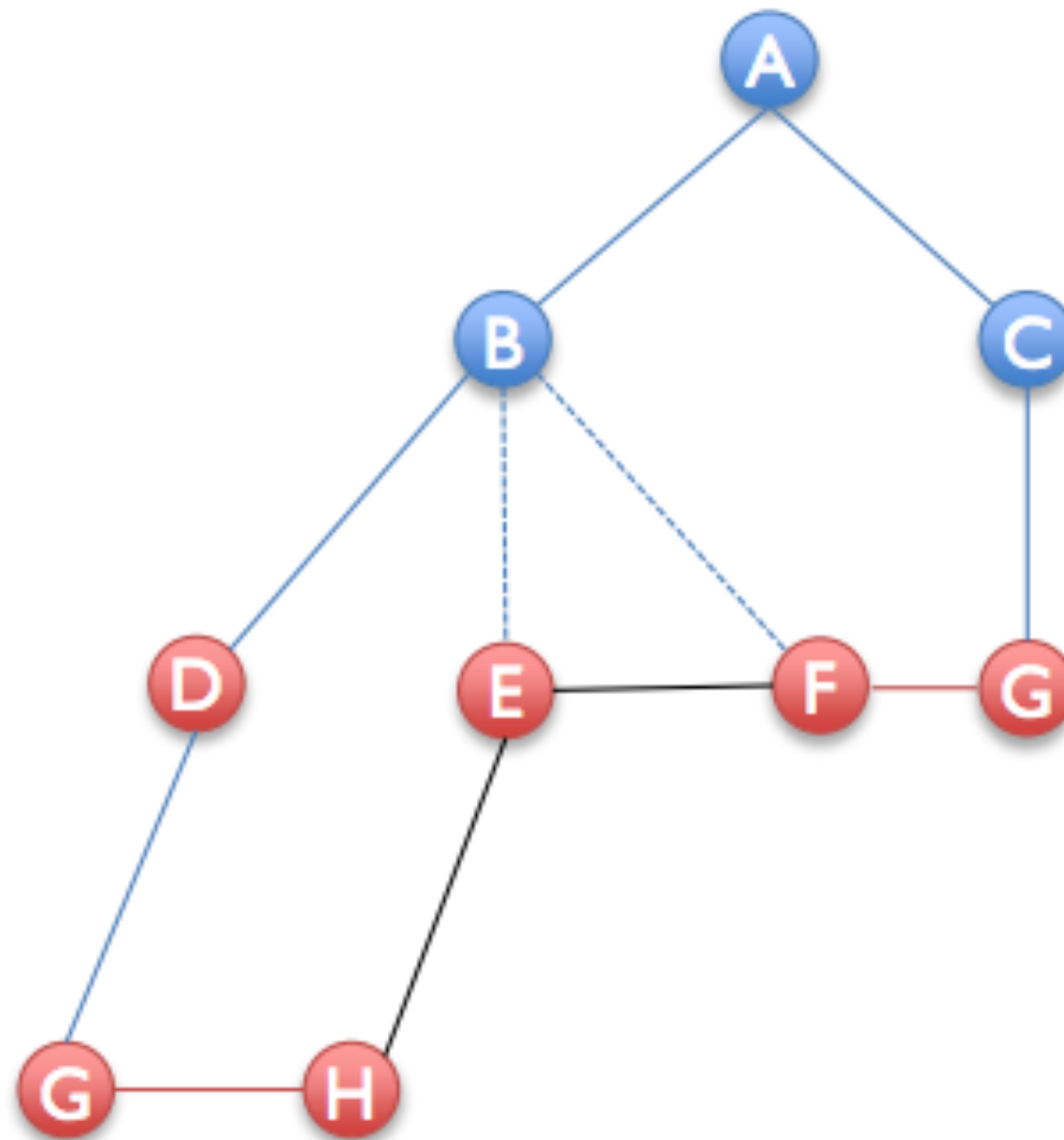
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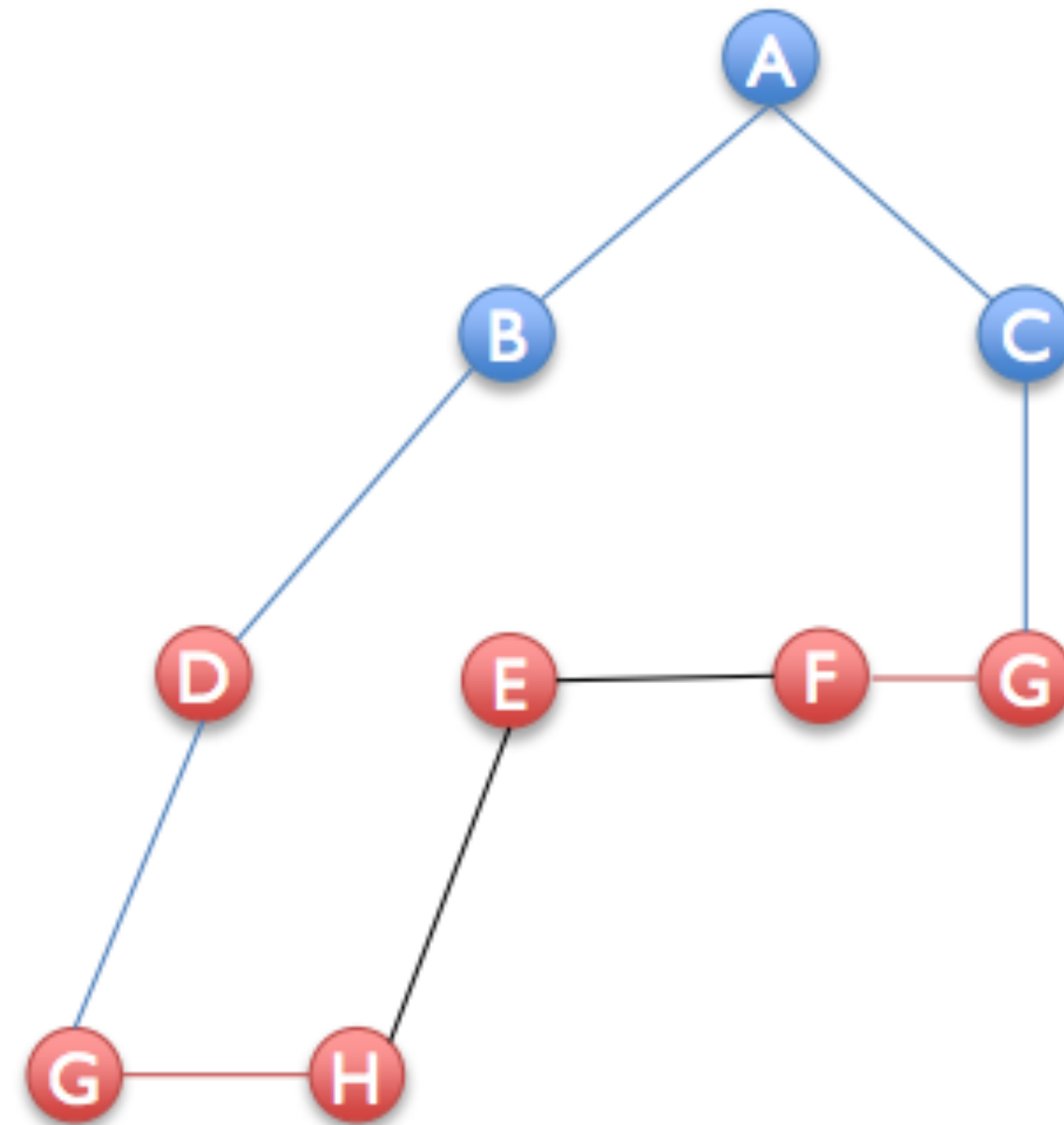
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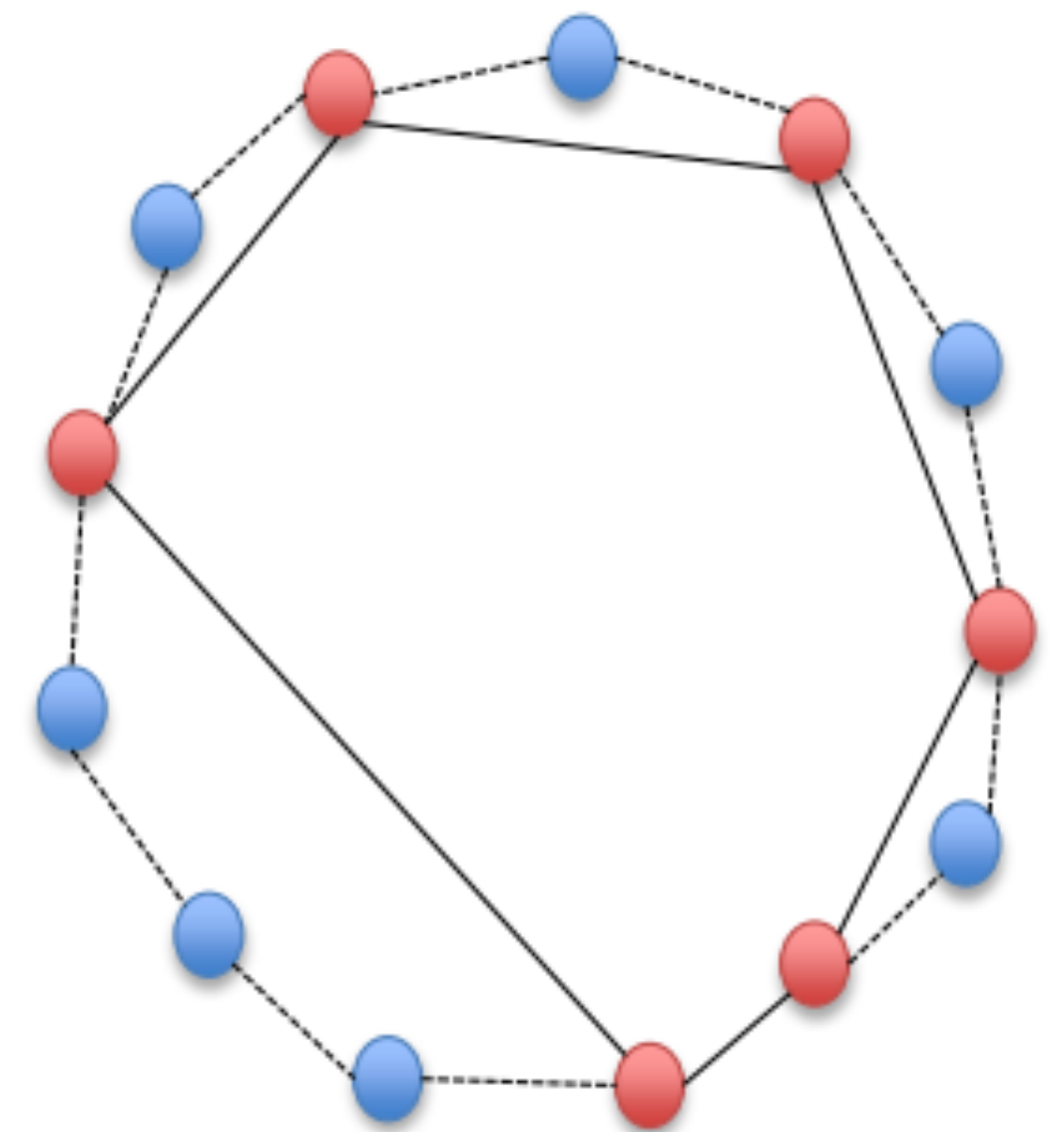
# Christofides Analysis

- Cost of TSP tour returned is at most  $w(T) + w(M)$ 
  - $T$  is the MST of the graph, and  $M$  is the minimum cost perfect matching on the subgraph induced by  $O$  (odd degree nodes in  $T$ )
- We know  $\text{OPT} \geq w(T)$
- To relate the costs, we lower bound the OPT in terms of the cost of  $M$
- **Claim.** Let OPT be the length of the optimal tour and let  $M$  be a minimum-cost perfect matching on the complete subgraph induced by  $O$ , the odd degree nodes in MST  $T$ , then

$$w(M) = \sum_{e \in M} w_e \leq \frac{1}{2} \cdot \text{OPT}$$

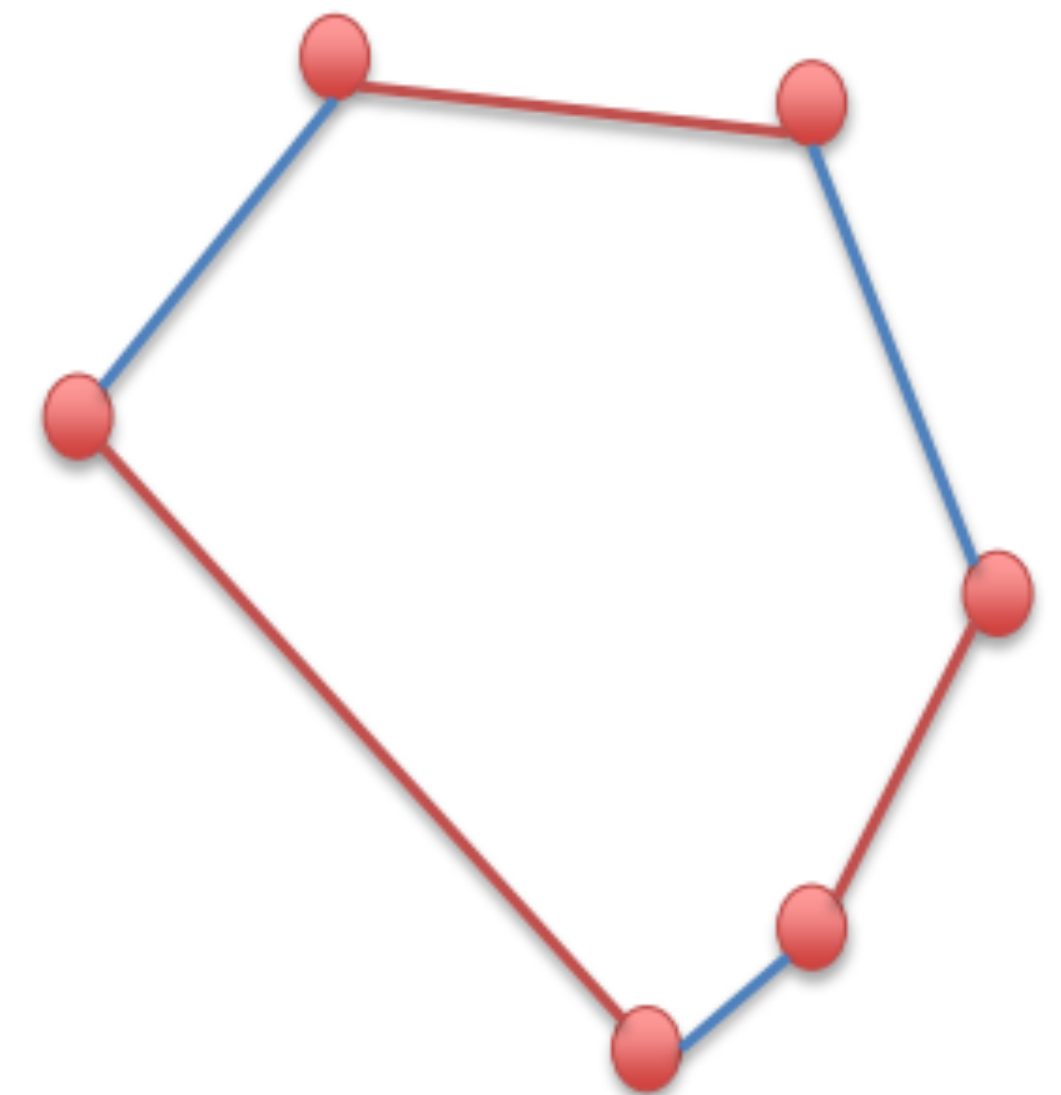
# Christofides Analysis

- **Proof of claim.** Consider an optimal tour with cost  $OPT$  and consider vertices in  $O$ , the odd-degree vertices in  $T$
- Shortcut optimal tour to obtain tour of vertices in  $O$
- By triangle inequality the cost of tour can only decrease



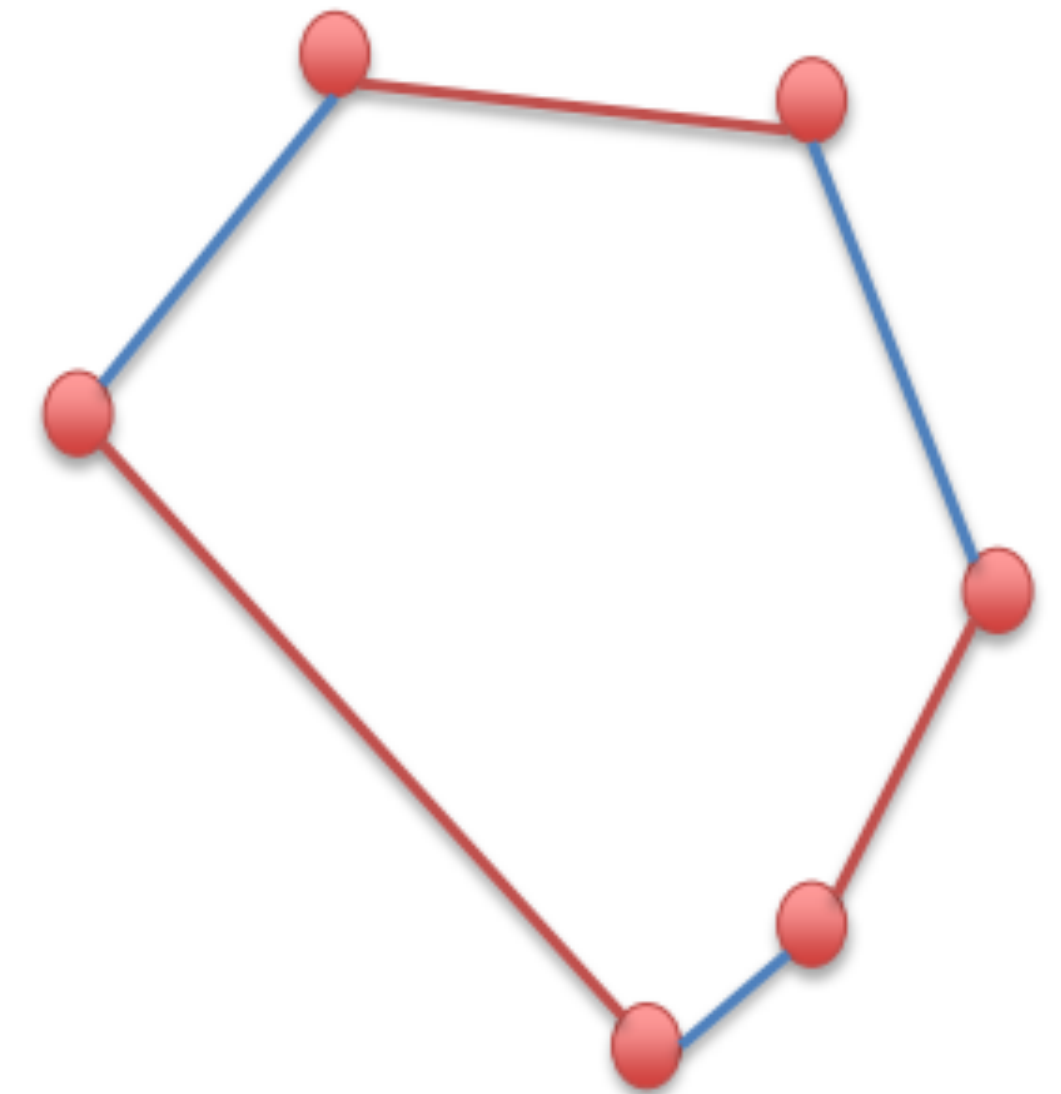
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- Shortcut optimal tour to obtain tour of vertices in  $O$
- By triangle inequality the cost of tour can only decrease
- Consider matchings  $M_1, M_2$  created by alternating edges on this tour
- $w(M_1) + w(M_2) \leq \text{OPT}$
- Then,  $\min\{w(M_1), w(M_2)\} \leq \text{OPT}/2$
- $w(M) \leq \min\{w(M_1), w(M_2)\}$ , where  $M$ : min-cost perfect matching on subgraph induced by  $O$
- Thus,  $w(M) \leq \text{OPT}/2$



# Wrapping Up

- Cost of TSP tour returned by Christofides  $\leq w(T) + w(M)$
- We showed that  $\text{OPT}$  (optimal cost)  $\geq w(T)$  and  $\text{OPT} \geq 2 \cdot w(M)$
- Thus, cost of TSP tour returned by Christofides
$$\leq \text{OPT} + \text{OPT}/2$$
$$\leq 1.5 \text{ OPT}$$
- Christofides is a 1.5 approximation to TSP



# TSP: Summary

- Held & Karp [1970s] developed a heuristic for calculating a lower bound on a TSP tour (coincides with a linear program known as Held-Karp relaxation)
  - Conjectured to give a  $4/3$ -approximation
- [Papadimitriou & Vempala, 2000's] NP-hard to approximate metric TSP within  $220/219 \sim 1.0004$ 
  - Simplified and slightly improved by Lampis'12
- “Four decades after its discovery, Christofides’ algorithm was the best approximation algorithm known for metric TSP”

No PTAS

# Last Summer

- This past summer [Karlin, Klein, Shayan] (unpublished):
  - $1.499$  approximation
- “Euclidean TSP” does have a PTAS! [Aurora 98] [Mitchell 99]
- Understanding the approximability of TSP is a major open problem in TCS

Christofide's isn't optimal!

# A (Slightly) Improved Approximation Algorithm for Metric TSP

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University of Washington

September 1, 2020

## Abstract

For some  $\epsilon > 10^{-36}$  we give a  $3/2 - \epsilon$  approximation algorithm for metric TSP.

# Acknowledgments

- Some of the material in these slides are taken from
  - Kleinberg Tardos Slides by Kevin Wayne (<https://www.cs.princeton.edu/~wayne/kleinberg-tardos/pdf/04GreedyAlgorithmsI.pdf>)
  - Jeff Erickson's Algorithms Book (<http://jeffe.cs.illinois.edu/teaching/algorithms/book/Algorithms-JeffE.pdf>)
  - Lecture slides: <https://web.stanford.edu/class/archive/cs/cs161/cs161.1138/>