

#### UNIVERSIDAD DE PAMPLONA

Formando líderes para la construcción de un nuevo país en paz

## **Real-Time Character Animation Techniques**

### Introduction

The Techniques and problems involved in the production of realistic human synthesis and motion.

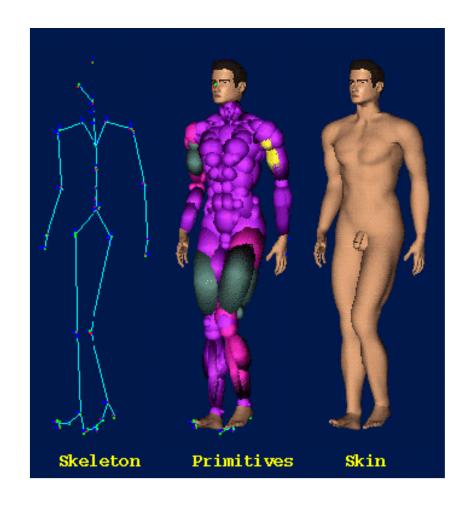
Section 2 of this paper deals with the layered modelling approach for Virtual character construction.

Section 3 presents the different techniques that are used within computer animation.



## Layared modeling

The animator divides the simulation model into a number of discrete layers, each with its own physical and geometric properties



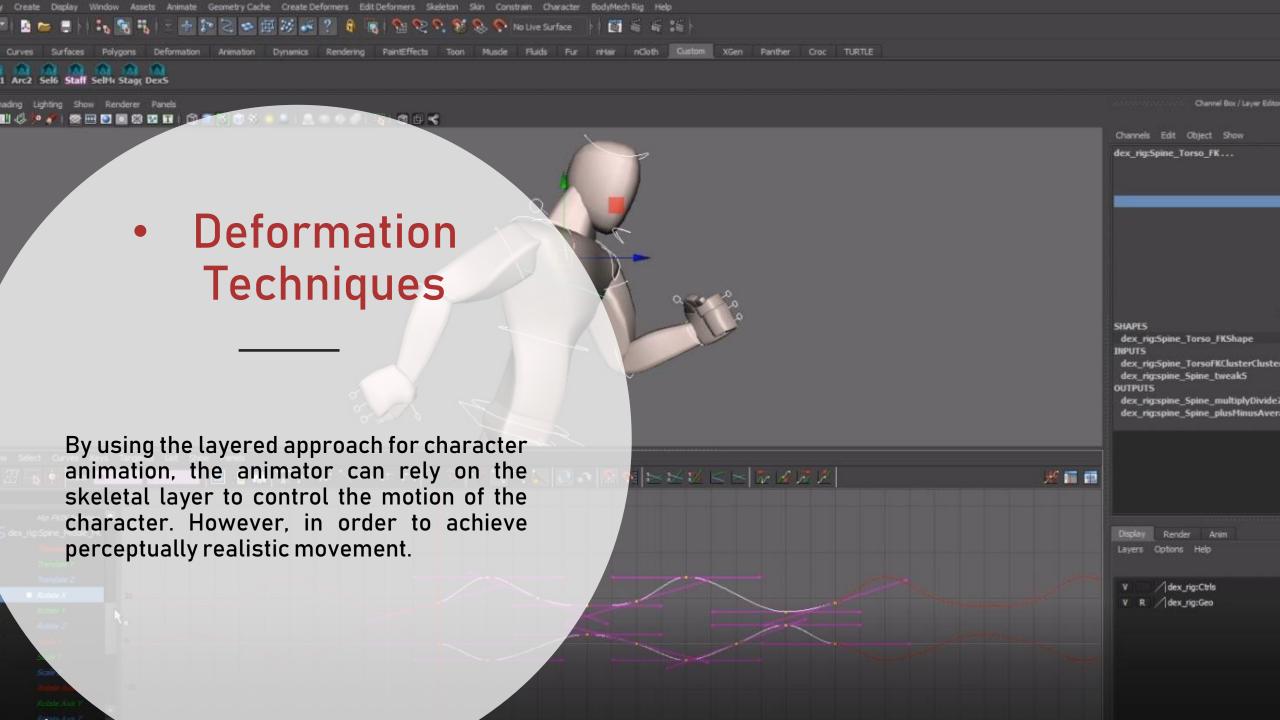


The number of layers used for real-time character animation is generally constrained by the underlying hardware's computational ability.

Where initially 2-layered (skeleton and muscle) and 3-layered (skeleton, muscle and skin) models prevailed, the ongoing improvement in processing.

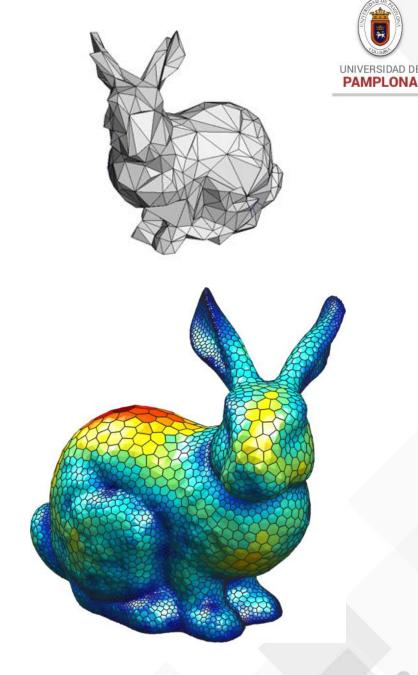


## TUTORIAL SERIES



# Joint Dependant Local Deformations (JLD)

This animation technique, which uses a polygonal mesh skin digitised from a sculpture.

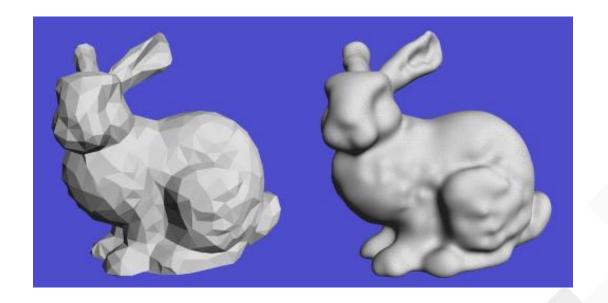


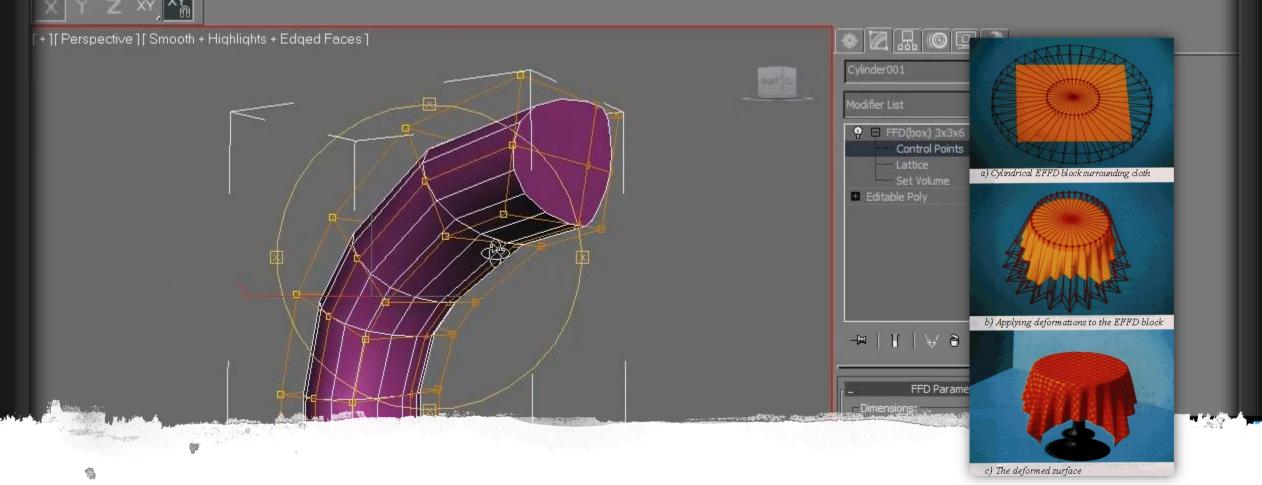


## Implicit Surfaces

#### Qualities:

- ability to represent continuous surfaces allows the virtual character to possess smooth joints, a quality which is not readily achievable using other methods
- can be used to handle collision detection and response as well as unwanted blending between the primitives in the character hierarchy.





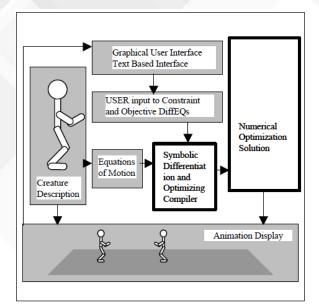
Free Form
Deformations

The unique quality of this approach is that instead of applying deformations to the object directly, the object is embedded in a space that is then deformed using Bezier theory.



Basic Techniques

The more traditional method of animating an articulated figure in computer graphics involves specifying each particular part at certain key locations in space, and then using some interpolation technique to animate the inbetween frames for the motion in question





#### Constraint Based Methods

Constraints over the entire motion are considered simultaneously in order to find the optimal motions. This essentially treats the problem of automatic motion generation as a trajectory optimisation problem.





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